Dijkstra Worksheet

Name: NetID:

Signature:

1. What is the defining characteristic of a Max Heap? How can the characteristics of Heaps be used to implement a Priority Queue?

Ans: Parents must have larger values than their children, and the root node has the biggest value. In a Min Heap, parents must always have a smaller value than the child, so the root node is always the node with the smallest value.

2. Suppose we have an array representation of a Binary Heap. Find the parent, left child, and right child of an element i.

```
Ans: Parent → Floor((i-1)/2)

Left Child → 2*i+1

Right Child → 2*i+2
```

3. How can you insert into a Heap? Assume the Heap is implemented as an array. Write some code!

```
def HeapInsert(Heap,key):
    Heap.size = Heap.size + 1
    i = Heap.size
    while ((i > 0) and (Heap[parent(i)] > key)):
        Heap[i] = Heap[parent(i)]
        i = parent(i)
    Heap[i] = key
```

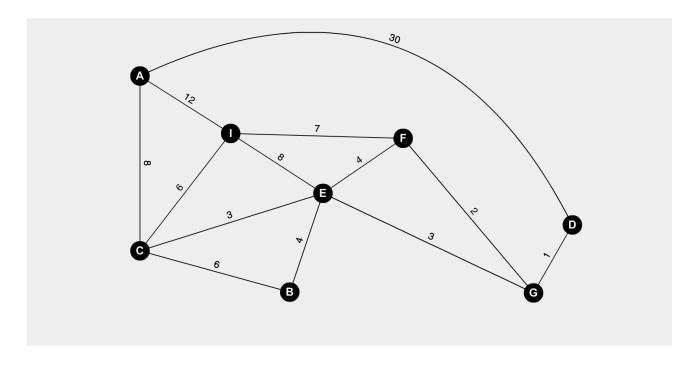
4. Let's say you have a very important packet to send from your computer to another computer, find the shortest path from your computer to all other nodes in the computer network.

Here is Dijkstra:

```
def Dijkstra(Graph, start, end):
    PQ = Queue.PriorityQueue()
```

```
foreach node in Graph:
  node.cost = infinity
start.cost = 0
foreach node in Graph:
  PQ.insert(n,node.cost)
while not(PQ.empty()):
  u = PQ.extract()
  if u == end:
    break
  foreach neighbor v in u.neighbors:
    w = cost from v to u
    newCost = u.cost + w
    if (newCost < v.cost):</pre>
      PQ.decreasekey(v,newcost)
      v.cost = newCost
      v.predecessor = u
```

Here is a graph. Use Dijkstra to find the shortest path from A to all nodes in the graph. Go through iteration by iteration, update the costs, as well as u from the psuedocode. ∞



	и	A	В	С	D	Е	F	G	Ι
1	A	0	inf	8	30	inf	inf	inf	12
2	AC	0	14	8	30	11	inf	inf	12
3	ACE	0	14	8	30	11	15	14	12
4	ACEI	0	14	8	30	11	15	14	12
5	ACEIG	0	14	8	15	11	15	14	12
6	ACEIGB	0	14	8	15	11	15	14	12