Lab - 12

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Implement a CBIR system that uses features derived from HOG Features.

CODE:

getHOGFeatures.m

```
function [feature] = getHOGFeatures(im)
if size(im,3)==3
im=rgb2gray(im);
end
im=double(im);
rows=size(im,1);
cols=size(im,2);
Ix=im; %Basic Matrix assignment
Iy=im; %Basic Matrix assignment
% Gradients in X and Y direction. Iy is the gradient in X direction and Iy
% is the gradient in Y direction
for i=1:rows-2
```

```
Iy(i,:) = (im(i,:) - im(i+2,:));
end
for i=1:cols-2
Ix(:,i) = (im(:,i)-im(:,i+2));
end
gauss=fspecial('gaussian',8); %% Initialized a gaussian filter with
sigma=0.5 * block width.
angle=atand(Ix./Iy); % Matrix containing the angles of each edge
gradient
angle=imadd(angle,90); %Angles in range (0,180)
magnitude=sqrt(Ix.^2 + Iy.^2);
% figure,imshow(uint8(angle));
% figure,imshow(uint8(magnitude));
% Remove redundant pixels in an image.
angle(isnan(angle))=0;
magnitude(isnan(magnitude))=0;
feature=[]; %initialized the feature vector
```

```
% Iterations for Blocks
for i = 0: rows/8 - 2
for j = 0: cols/8 - 2
     %disp([i,j])
     mag patch = magnitude(8*i+1 : 8*i+16, 8*j+1 : 8*j+16);
     %mag_patch = imfilter(mag_patch,gauss);
     ang_patch = angle(8*i+1 : 8*i+16, 8*j+1 : 8*j+16);
     block_feature=[];
     %Iterations for cells in a block
     for x=0:1
          for y=0:1
                angleA = ang patch(8*x+1:8*x+8, 8*y+1:8*y+8);
                       =mag_patch(8*x+1:8*x+8, 8*y+1:8*y+8);
                magA
                histr = zeros(1,9);
                %Iterations for pixels in one cell
                for p=1:8
```

```
for q=1:8
응
                       alpha= angleA(p,q);
                       % Binning Process (Bi-Linear Interpolation)
                       if alpha>10 && alpha<=30
                            histr(1) = histr(1) +
magA(p,q)*(30-alpha)/20;
                            histr(2) = histr(2) +
magA(p,q) * (alpha-10)/20;
                       elseif alpha>30 && alpha<=50
                            histr(2) = histr(2) +
magA(p,q)*(50-alpha)/20;
                            histr(3) = histr(3) +
magA(p,q) * (alpha-30)/20;
                       elseif alpha>50 && alpha<=70
                            histr(3) = histr(3) +
magA(p,q)*(70-alpha)/20;
                            histr(4) = histr(4) +
magA(p,q)*(alpha-50)/20;
                       elseif alpha>70 && alpha<=90
                            histr(4) = histr(4) +
magA(p,q)*(90-alpha)/20;
```

```
histr(5) = histr(5) +
magA(p,q)*(alpha-70)/20;
                       elseif alpha>90 && alpha<=110
                             histr(5) = histr(5) +
magA(p,q)*(110-alpha)/20;
                             histr(6) = histr(6) +
magA(p,q)*(alpha-90)/20;
                       elseif alpha>110 && alpha<=130
                             histr(6) = histr(6) +
magA(p,q)*(130-alpha)/20;
                             histr(7) = histr(7) +
magA(p,q)*(alpha-110)/20;
                       elseif alpha>130 && alpha<=150
                             histr(7) = histr(7) +
magA(p,q) * (150-alpha) / 20;
                             histr(8) = histr(8) +
magA(p,q)*(alpha-130)/20;
                       elseif alpha>150 && alpha<=170
                             histr(8) = histr(8) +
magA(p,q)*(170-alpha)/20;
                             histr(9) = histr(9) +
magA(p,q)*(alpha-150)/20;
                       elseif alpha>=0 && alpha<=10
                             histr(1) = histr(1) +
magA(p,q)*(alpha+10)/20;
```

```
histr(9) = histr(9) +
magA(p,q)*(10-alpha)/20;
                       elseif alpha>170 && alpha<=180
                            histr(9) = histr(9) +
magA(p,q)*(190-alpha)/20;
                            histr(1) = histr(1) +
magA(p,q) * (alpha-170) / 20;
                       end
                 end
                 end
                 block_feature=[block_feature histr]; % Concatenation
of Four histograms to form one block feature
           end
     end
     \mbox{\%} Normalize the values in the block using L1-Norm
     block feature=block feature/sqrt(norm(block feature)^2+.01);
     feature=[feature block_feature]; %Features concatenation
end
end
```

```
feature(isnan(feature))=0; %Removing Infinitiy values
\mbox{\%} Normalization of the feature vector using L2-Norm
feature=feature/sqrt(norm(feature)^2+.001);
for z=1:length(feature)
if feature(z)>0.2
     feature(z)=0.2;
end
end
feature=feature/sqrt(norm(feature)^2+.001);
% toc;
Main.m
clc
clear all
close all
tic;
% Reading in the query image and extracting it's LBP features
query_image = imread('./Faces/angry20.jpg');
query_image_features = getHOGFeatures(query_image);
```

```
% Initializing the path of the image base and getting the directory
listing
D = './Faces';
S = dir(fullfile(D, '*.jpg'));
%Column Names
CNames = {'file name'};
for i = 1:900
CNames{end+1} = sprintf('%d',i);
end
CNames{end+1} = 'Euclidean Distance';
info table = cell2table(cell(0, size(CNames,2)),
'VariableNames', CNames);
% Calculating the euclidean distance between every image in the image
base and the query image
for k=1:numel(S)
F = fullfile(D, S(k).name);
I = imread(F);
image_features = getHOGFeatures(I);
if size(image_features, 2) == size(query_image_features, 2)
     euclidean_distance = sqrt(sum((image_features -
query_image_features).^2));
```

```
imageFeatures={S(k).name};
     for i=1:900
           imageFeatures{end+1}=image features(i);
     end
     imageFeatures{end+1} = euclidean distance;
     info table = [info table; imageFeatures];
end
end
% Sorting the entries of the table based on ascending order of
% euclidean_distance
info_table = sortrows(info_table, 'Euclidean Distance');
writetable(info_table, 'lab12.xlsx','Sheet',1);
% Displaying the first 4 nearest image
subplot(3, 3, 2);
imshow(query_image);
title('Query image');
file_names = info_table(:, 'file_name').file_name; % Extracting the
filenames of the images
for i = 1:6
```

```
F = fullfile(D, char(file_names(i)));
I = imread(F);
subplot(3, 3, i+3);
imshow(I);
title(char(file_names(i)));
end
toc;
```

OUTPUT

Query 1



Precision = 5/(5+5) = 0.5

Recall = 5/(5+(25-5)) = 5/25 = 0.2

Query 2

Query image



happy20.jpg



happy8.jpg



angry2.jpg



happy18.jpg



happy4.jpg



happy2.jpg





angry3.jpg



happy23.jpg



happy5.jpg



Precision = 7/(7+3) = 0.7

Query 3

Query image



angry11.jpg



angry21.jpg



angry17.jpg



angry25.jpg



happy14.jpg



happy7.jpg



happy12.jpg



angry20.jpg



angry22.jpg



angry19.jpg



Precision = 7/(7+3) = 0.7

Recall =
$$7/(7+(25-7) = 0.28$$

Query 4

happy11.jpg happy2.jpg angry17.jpg angry20.jpg angry14.jpg

happy9.jpg angry22.jpg angry13.jpg angry1.jpg happy10.jpg

Precision = 4/(4+6) = 0.4

Recall = 4/25 = 0.16

Query 5

Query image



happy1.jpg



happy23.jpg



happy13.jpg



happy18.jpg



happy21.jpg



angry13.jpg









angry10.jpg



Precision = 7/(7+3) = 0.7

Recall = 7/25 = 0.28

Table

Query	Precision	Recall
angry20.jpg	0.5	0.2
happy20.jpg	0.7	0.28
angry11.jpg	0.7	0.28
happy4.jpg	0.4	0.16
happy1.jpg	0.7	0.28

Average Precision = 0.6

Average Recall = 0.24