

## \* Depth First Search:

- runs on directed/undirected graphs and ignores any weight
- we assume an underlying adjacency list representation
- exploring the graph within.

## \* Simple Implementation

DFS( $G$ , startVertex).

ResetGraph( $G$ ).

DFSVertex(startVertex).

ResetGraph( $G$ )

for  $v \in V$

$v$ .discovered = false

DFSVertex( $u$ )

$u$ .discovered = True

for each  $v$  s.t.  $u \rightarrow v$

if (not  $v$ .discovered)

DFSVertex( $v$ )

- recursive calls
- storing parents is less interesting here. In case of BFS path is always shortest possible but not in case of DFS.
- storing distance/length is also not interesting here due to same reason.
- Instead we use time stamps, finish time and discovery time to do some interesting tasks

## \* Implementation:

```
DFS(G, startVertex)
    ResetGraph(G)
    DFSVertex(startVertex)

ResetGraph(G)
    for v in V
        v.π = nil
        v.discovery = -1
        v.finishing = -1
    time = 1
```

DFSVertex(u)

```
    u.discovery = time++
    for each v s.t. u → v
        if (v.discovery < 0)
            v.π = u
```

DFSVertex(v)

```
    u.finishing = time++
```

- \* One problem here is when we apply DFS from a vertex, there may be vertex which may remain undiscovered.
- if you want to explore the whole graph then.



DFS (G)

ResetGraph (G)

for  $u \in V$

if ( $u.\text{discovery} < 0$ )

DFSVertex (u)

\* This everything can be visualized in terms of balanced parenthesis. -- where  $( \rightarrow$  signifies when a DFS call is made on a vertex and  $) \rightarrow$  when the call exits

- A child will be nested in its parent

ex: A D B G G B F C C F D A (counting parentheses from the beginning will match discovery/finished times)

\* Another approach to time stamps is color vertex colors -- white (undiscovered), grey (discovered, unfinished) and black (finished)

\* Edge classification:

(i) Tree Edge:

- parent to a child.
- go to an undiscovered vertex.

## (ii) Back Edges:

- to an ancestor
- to a discovered but unfinished vertex
- every back edge makes a cycle, and removing back edges will remove all cycles. (also self loops are included).

## (iii) Forward Edges:

- to a non-child descendant / not a direct child!
- to a finished vertex discovered after the current vertex

## (iv) Cross Edges:

- any other edge can go to one branch to another or also from one tree to another tree.
- no ancestor-descendant relationship between the vertices it links.
- to a vertex finished before the current vertex's discovery.

## \* Undirected Graphs:

- no forward / cross edges

## \* Analysis:

- we call DFS on every vertex (once) and explore each edge
- On a graph
- taking time  $\Theta(|V| + |E|)$



• on a single vertex with  $G' = (V', E')$  reachable from that vertex, takes time  $\Theta(|V'| + |E'|)$

all vertices are initialized.

\* Deep Trees may cause Stack Overflow  
hence we may use our own stack  
implementation for DFS:

DFS ( $G$ )

ResetGraph( $G$ )

$S = \text{new stack}()$

for ( $u \in V$ )

$S.\text{push}(u);$

while(not  $S.\text{isEmpty}()$ )

$x = S.\text{pop}();$

if( $x.\text{isVertex}()$ )

ExploreVertex( $x, S$ )

else

ExploreEdge( $x, S$ )

ExploreVertex( $u, S$ )

if ( $u.\text{discovery} < 0$ )

$u.\text{discovery} = \text{time}++$

$S.\text{push}(u)$

for each  $v$  such that  $u \rightarrow v$

$S.\text{push}(u \rightarrow v)$

else if ( $u.\text{finishing} < 0$ )

$u.\text{finishing} = \text{time}++$

ExploreEdge( $u \rightarrow v, S$ )

if ( $v.\text{discovery} < 0$ )

$(u \rightarrow v).\text{label} = \text{"tree Edge"}$

$v.\pi = u$

ExploreVertex( $v, S$ )

else if ( $v.\text{finishing} < 0$ )

$(u \rightarrow v).\text{label} = \text{"back Edge"}$

else if ( $v.\text{discovery} > u.\text{discovery}$ )

$(u \rightarrow v).\text{label} = \text{"forward Edge"}$

else  $(u \rightarrow v).\text{label} = \text{"cross Edge"}$