## M607 - First programming Project Iterative Methods

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Due Oct 5

Hand in code, pictures and comments as requested. Please try to format for minimum use of paper!

## 1 Gauss-Seidel/SOR

• Using the code from your first homework, write a function with the first line

that performs at most itmax iterations of SOR with relaxation parameter omega. The iteration should stop when the maximum norm of the residual is less than tol. The other parameters are as follows:

p0	The initial guess with the boundary data loaded around the edges of the matrix.
rhs	the right hand side matrix (i.e. $rhs(i,j) =_{i,j}$ )
dx	the mesh size in $x$
dy	the mesh size in $y$

Run your code using omega=1, itmax=500 and tol=1.e-04 to solve  $\Delta p = 0$  in the unit square using 10 mesh intervals in the x and y directions (so dx=1/10). The boundary data should be p = 0 on x = 1 and y = 1 together with

$$p(x,0) = \sinh(\pi(1-x)/2)/\sinh(\pi/2), \quad 0 \le x \le 1,$$

and

$$p(0,y) = \cos(\pi y/2), \quad 0 \le y \le 1.$$

Draw a plot of the result using the matlab command mesh. You should see the result in Fig. 1 (perhaps after rotating the picture). The exact solution is known in this case

$$u_{exact}(x,y) = \cos(\pi y/2) \sinh(\pi (1-x)/2) / \sinh(\pi/2)$$

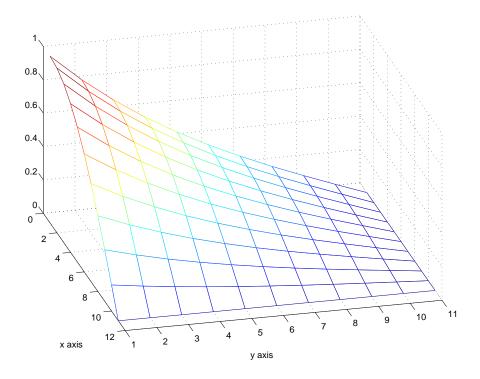


Figure 1: Example using 10 mesh intervals

Compute the maximum error at the mesh points in your SOR solution. You should find it to be  $2.18 \times 10^{-4}$  (this will help you check your code is right)! Rerun the code with omega=1.7 and observe the decrease in number of iterations needed (how many iterations are needed in each case?). For a smooth solution (i.e. one have four bounded derivatives in x and y) we expect that the truncation error (i.e. error due to finite differences) should behave like

$$e_{trunc} \approx C(dx)^2$$
, so  $\log(e_{trunc}) \approx 2\log(dx) + \log(C)$ .

This power law is said to be second order convergence.

Use your SOR function to compute the solution for 5, 10, 15, 20 subintervals and plot the maximum error in each case against dx using a log-log plot. What is the slope of the line? Does it support theory? The total error in the calculation is  $e_{trunc} + e_{it}$  where  $e_{it}$  is the error due to stopping SOR. Make sure that you have set a tolerance low enough that  $e_{it}$  is small compared to  $e_{trunc}$  (in real calculations you want to choose the tolerance so that the two errors are roughly the same so that you do as little work as possible....).

• Now change the boundary data to p = 0 at y = 0, y = 1 and x = 1, but keep the cos boundary condition at x = 0. Compute the finite difference solution using 12 subintervals and plot the result. You should see that the solution varies very rapidly near x = y = 0 and in fact the derivative is unbounded as you approach the corner.

The exact solution is given by

$$p(x,y) = \sum_{n=1}^{\infty} \frac{2n}{\pi(n^2 - 1/4)\sinh(n\pi)} \sin(n\pi y) \sinh(n\pi (1-x))$$

Write a function with the first line

function pe=exact(x,y,N)

where N is the number of terms in the series to be added. Experiment with N until you find a reasonable choice that computes the solution at x = 1/2, y = 1/2 to an error of at most 1.e-4. Now solve the finite difference equation for 4,8,12,16,20,24,28,32 subintervals and plot a log-log error graph using the absolute value of error at x = 1/2, y = 1/2 only. Is the convergence consistent with power law as before? Are we seeing the same convergence rate as before?

## 2 GMRES

Here is a small exercise that demonstrates some properties of GMRES (use the matlab gmres function) from the book of Trefethen and Bau.

• Create a random matrix A using

m=200; A=2\*eye(m)+0.5\*randn(m)/sqrt(m);

Compute the eigenvalues of A using the matlab command eig and plot each eigenvalue as a \* in the complex plane (you will need the commands real and imag). Note that the eigenvalues are clustered in circle of radius 1/2 around z=2. Hand in a plot of the eigenvalues. Now run GMRES using (in matlab notation) b=ones(m,1). Plot the norm of the residual at each step (using semilogy). What is the slope of the line? This is an example of rapid convergence (without even a preconditioner) since the eigenvalues are well clustered.

• Modify the matrix A in the previous example by computing  $\theta_k = k\pi/(m-1)$ ,  $\leq k \leq m$  and defining the diagonal matrix D with  $d_{k,k} = (-2+2\sin(\theta_k))+i\cos(\theta_k)$ . Then setting B = A + D. Now as before, plot the eigenvalues of B (they are no longer clustered) and solve  $B\vec{x} = \vec{b}$  using GMRES. Increase the allowed number of iterations to 40 and plot the residual. Convergence of GMRES critically depends on clustering eigenvalues and that can be accomplished by using a good preconditioner (its not easy to say what is a good preconditioner in thus case because the matrix is random).