

# Pre-training and fine-tuning neural networks to interpolate Sea Surface Height field from multi-variate satellite observations

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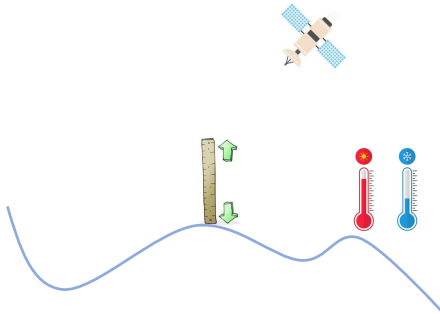
24 avril 2024

# Summary

1. Multi-Variate satellite surface observations of the ocean
2. Problem Statement
3. Proposed Method
4. Results on synthetic data
5. Results on observations
6. Conclusion and perspectives

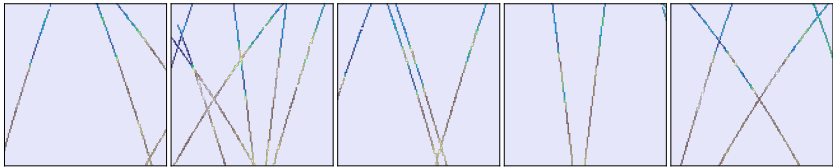
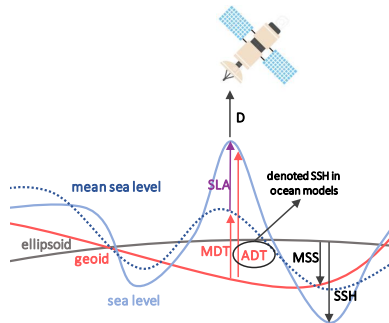
# Multi-Variate satellite surface observations of the ocean

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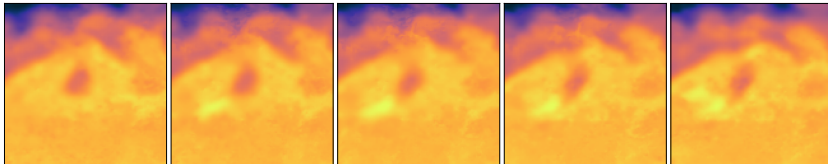
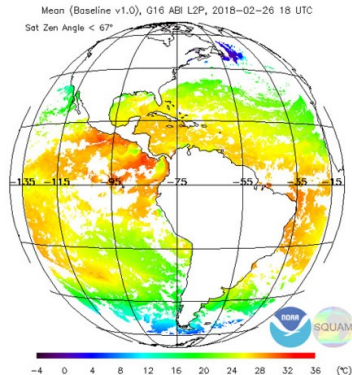
# Sea Surface Height

- Used to derive surface currents to geostrophic approximation
- Measurement principle : return time of a radar pulse
- Nadir-pointing altimeters : only measure data along their ground tracks



# Sea Surface Temperature

- Measurement principle : Direct infra-red image with high resolution ( $1/25^\circ$ )
- Sensible to cloud cover
- Combining several satellites through interpolation
- Physically linked to SSH as currents advect heat



# Problem Statement

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# Inverse Problem Formulation

*Let  $\mathbf{X}_a$ ,  $\mathbf{X}_b$  be the ocean state of the target and contextual variables, respectively. Let  $\mathbf{Y}_a$ ,  $\mathbf{Y}_b$  be their associated observations obtained through  $\mathcal{H}_a$ ,  $\mathcal{H}_b$  as follows :*

$$\begin{cases} \mathbf{Y}_a &= \mathcal{H}_a(\mathbf{X}_a) + \varepsilon_a \\ \mathbf{Y}_b &= \mathcal{H}_b(\mathbf{X}_b) + \varepsilon_b \end{cases}$$

$\mathcal{H}_a$  can be seen as a forward operator that we aim to inverse. Therefore, in our application, the SSH is the target variable ( $\mathbf{X}_a$ ), and SST is the contextual information ( $\mathbf{X}_b$ ).

# The operational inversion method : DUACS

Data Unification and Altimeter Combination System (DUACS) :

- Optimal linear interpolation of the satellite along-tracks measures from multiple satellites.
- Uses covariances matrices tuned on 25 years of data and not publicly available
- Low effective resolution
- Misses mesoscale structures and eddies

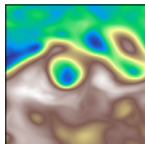
**Our goal** : enhance DUACS's interpolation using a neural network and SST information.



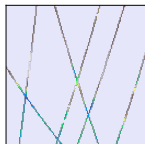
# Observing System Simulation Experiment

*We use the Global Physical Reanalysis (GLORYS) as simulated ground truth. We take 7194 days of data in the north stream area (Latitude 33 to 43, longitude -65 to -55)*

- We simulate  $\mathcal{H}_a$  as the trilinear interpolation of this ground truth on the path of the satellite. We use the support from real-world observations.



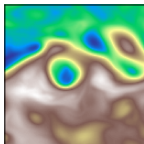
$\mathcal{H}_a$   
→



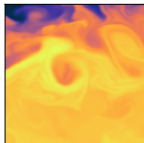
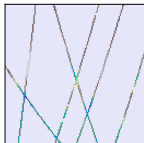
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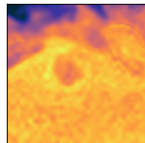
- We simulate  $\mathcal{H}_a$  as the trilinear interpolation of this ground truth on the path of the satellite. We use the support from real-world observations.
- To simulate  $\mathcal{H}_b$  we first add a white additive noise, and we use a real world cloud cover to select areas where we smooth the image using a gaussian blur.



$\mathcal{H}_a$   
→



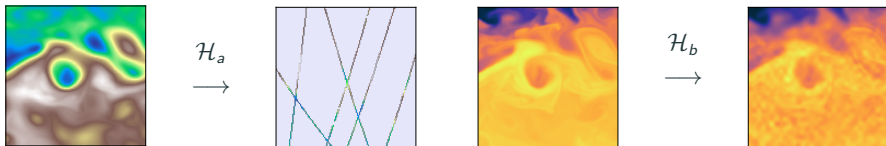
$\mathcal{H}_b$   
→



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Doing so we have access to :

- Gappy and noisy SSH measures which emulates SSH along tracks measures
- Noisy and blurred SST maps which emulates the interpolation process, and unequal noise resolutions

## Proposed Method

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## Neural inversion

We perform the interpolation using a neural network  $f_\theta$  estimating the SSH field from 21 days on data.

$$\hat{\mathbf{X}}_a = f_\theta(\mathbf{Y}_a, \mathbf{Y}_b) \quad \text{with } \hat{\mathbf{X}}_a, \mathbf{Y}_a, \mathbf{Y}_b \in \mathbb{R}^{T \times H \times W}$$

The network is trained using a loss function  $\mathcal{L}$  in our case the Mean Squared Error.

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- **Supervised Learning** : If we have access to  $\mathbf{X}_a$ 
  - Requires a realistic twin experiment on a simulation
  - Domain gap issues

# Neural inversion

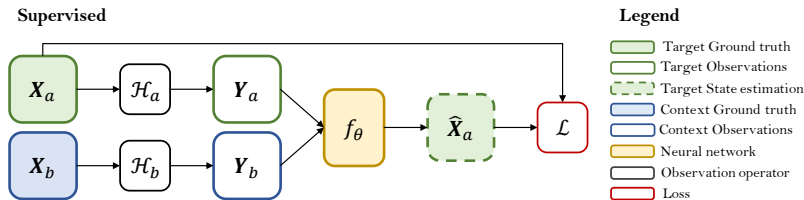
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- **Supervised Learning** : If we have access to  $\mathbf{X}_a$ 
  - Requires a realistic twin experiment on a simulation
  - Domain gap issues
- **Unsupervised learning** : If we only have access to observations
  - With observations only, learning the relationship between data is harder

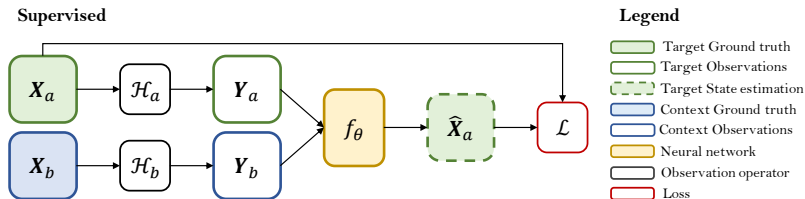
# Learning method



- Apply observing operators to  $\mathbf{X}_a, \mathbf{X}_b$  and estimates the state from observations.

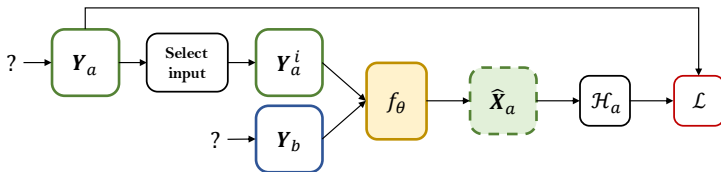


# Learning method



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## Unsupervised

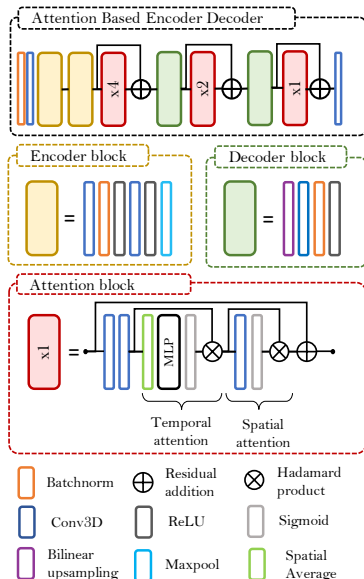


- Subset input data  $\mathbf{Y}_a^i$ , and estimates  $\hat{\mathbf{X}}_a$  from  $(\mathbf{Y}_a^i, \mathbf{Y}_b)$
- Apply  $\mathcal{H}_a$  to  $\hat{\mathbf{X}}_a$  before computing the loss.

# Architecture

We propose an attention-based encoder-decoder (ABED) using a time series of along-track SSH and SST to estimate the gridded SSH time-series.

- Two encoding blocks reducing spatial dimensions
- Spatio-Temporal Attention modules
  - Temporal attention : performs channel and temporal attention together
  - Spatial attention
- Decoding blocks to increase spatial dimensions

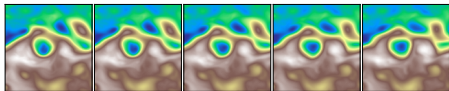


# Results on synthetic data

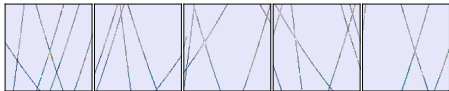
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Sea Surface Height

$X_a$

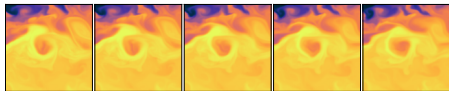


$Y_a$

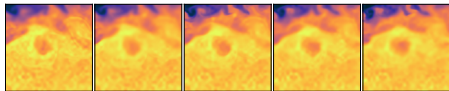


Sea Surface Temperature

$X_b$



$Y_b$



*On the OSSE framework, we want to assess :*

## **Learning strategies :**

- Supervised learning
- Unsupervised learning
- Unsupervised learning with regularization

# Experiment

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## **Impact of SST data :**

- SSH-only interpolation
- SSH and noised SST
- SSH and model SST (to give an upper bound performance)

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## **Impact of SST data :**

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- SSH and model SST (to give an upper bound performance)

We validate the results using the following metrics :

- SSH reconstruction : RMSE
- Structures analysis : we perform an automatic eddy detection on ground truth and estimation, compare the physical properties of the eddies
- State-of-the-art interpolations methods on a similar OSSE

# SSH reconstruction

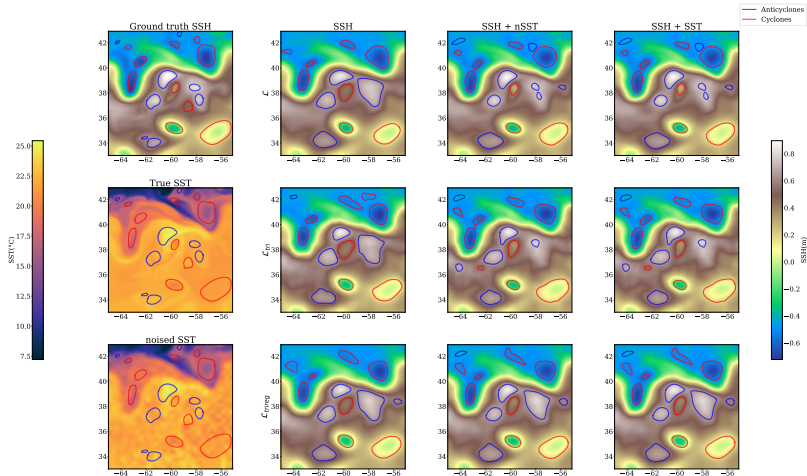
Loss	SSH	SSH+nSST	SSH+SST
supervised	4.18 — 3.85	3.23 — 2.93	<b>2.92 — 2.59</b>
unsupervised	4.52 — 4.16	3.86 — 3.51	3.62 — 3.24
unsupervised+regul	4.38 — 4.13	3.73 — 3.48	3.48 — 3.20

**Table 1:** SSH reconstruction RMSE in centimeters. For each method, the first score is the one of the mean RMSE of 3 neural networks, while the second one is the one of its ensemble estimation.

- SST improves reconstruction
- It is possible to train a neural network in an unsupervised way, although with a performance drop.
- Ensemble estimation improves reconstruction

# Structures analysis

We perform an automatic eddy detection (AMEDA) on the generated maps and compare the eddies of the interpolations to the ones of the ground truth.





# Structures analysis

Loss	SSH			SSH+nSST			SSH+SST		
	$F_1$	recall	precision	$F_1$	recall	precision	$F_1$	recall	precision
supervised	0.719	0.617	0.86	0.765	0.685	0.866	<b>0.785</b>	<b>0.728</b>	0.852
unsupervised	0.704	0.647	0.771	0.727	0.672	0.79	0.739	0.692	0.793
unsupervised+regul	0.714	0.609	0.863	0.725	0.623	0.865	0.742	0.644	<b>0.877</b>

**Table 2:** Detection scores

- Better eddy detection of SST using methods (similar precision but increased recall)
- Performance drop of the unsupervised methods

# State-of-the-art comparison

We use the interpolations benchmark of the Ocean Data Challenge 2020 to compare our methods. The considered metrics are the following :

- $\mu$  and  $\sigma_t$  (in cm) are respectively RMSE and its temporal standard deviation
- $\lambda_x(^{\circ})$  and  $\lambda_t(\text{days})$  are respectively the smallest half resolved spatial and the temporal wavelength
- $\mu_u$  and  $\mu_v$  are the RMSE on northward and eastward surface currents

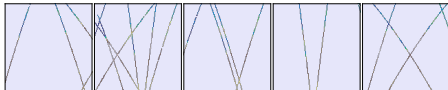
Method	SST	SUP	$\mu$	$\sigma_t$	$\lambda_x$	$\lambda_t$	$\mu_u$	$\mu_v$
DUACS	✗	✗	4.89	3.02	1.42	12.08	16.8	16.2
DYMOST	✗	✗	5.18	3.05	1.35	11.87	16.8	16.8
MIOST	✗	✗	4.21	2.5	1.34	10.34	14.9	14.5
BFN	✗	✗	4.7	2.73	1.23	10.64	15.1	15.3
4DVarNet	✗	✓	3.26	1.73	<b>0.84</b>	7.95	13.1	12.8
MUSTI	✓	✗	3.12	1.32	1.23	<b>4.14</b>	12.2	14.2
ABED-SSH	✗	✓	3.75	2.0	1.21	8.74	13.3	13.5
ABED-SSH	✗	✗	4.06	2.19	1.32	9.29	13.7	15.1
ABED-SSH-SST	✓	✓	<b>2.88</b>	<b>1.24</b>	0.95	4.51	<b>11.4</b>	<b>11.4</b>
ABED-SSH-SST	✓	✗	3.08	1.41	1.18	5.18	11.8	12.8

# Results on observations

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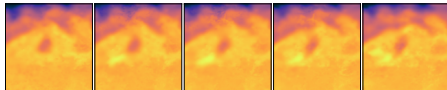
Sea Surface Height

$Y_a$



Sea Surface Temperature

$Y_b$



## Comparing training strategies

Given the supervised and the unsupervised learning, we derive 3 strategies ;

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- **Observations only** : unsupervised training on real-world observations.

Input data	SSH			SSH+nSST			SSH+SST		
Learning method	$\mu$	$\sigma_t$	$\lambda_x$	$\mu$	$\sigma_t$	$\lambda_x$	$\mu$	$\sigma_t$	$\lambda_x$
Observation	6.52	1.95	111	6.13	1.84	104	—	—	—

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Given the supervised and the unsupervised learning, we derive 3 strategies ;

- **Observations only** : unsupervised training on real-world observations.
- **Simulation only** : supervised training on simulation and direct inference on real-world data.

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Observation	6.52	1.95	111	6.13	1.84	104	—	—	—
Simulation	6.35	1.9	112	6.2	1.87	108	6.85	2.22	111

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- **Observations only** : unsupervised training on real-world observations.
- **Simulation only** : supervised training on simulation and direct inference on real-world data.
- **Both** : Supervised pre-training on simulation and unsupervised fine-tuning on real-world observations

Input data	SSH			SSH+nSST			SSH+SST		
Learning method	$\mu$	$\sigma_t$	$\lambda_x$	$\mu$	$\sigma_t$	$\lambda_x$	$\mu$	$\sigma_t$	$\lambda_x$
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Simulation	6.35	1.9	112	6.2	1.87	108	6.85	2.22	111
Both	6.27	1.85	110	<b>5.77</b>	1.64	<b>102</b>	<b>5.77</b>	<b>1.6</b>	103

**Table 3:**  $\mu$  and  $\sigma_t$  :RMSE and RMSE temporal standard deviation (in cm),  $\lambda_x$  : first half-resolved spatial wavelength (in km).

# Comparing training strategies

We compare the methods on real-world observations : on the noisy measurements of a left aside satellite.

Input data	SSH			SSH+nSST			SSH+SST		
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SST enhances the reconstruction :

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- Once fine-tuned it leads to a very high improvement

Interest of the SST OSSE :

- Leads to better reconstruction on the training from simulation only
- Once fine-tuned, pre-training on noisy SST or not makes no difference

## State-of-the-art comparison

Method	SST	NN	Learning	$\mu(cm)$	$\sigma_t(cm)$	$\lambda_x(km)$
DUACS	$\times$	$\times$	$\times$	7.66	2.66	138
DYMOST	$\times$	$\times$	$\times$	6.75	2.00	121
MIOST	$\times$	$\times$	$\times$	6.75	2.00	121
BFN	$\times$	$\times$	$\times$	7.46	2.59	114
4DVarNet	$\times$	$\checkmark$	simulation	6.56	1.84	104
MUSTI	$\checkmark$	$\checkmark$	observation	6.26	1.96	107
CONVLSTM	$\times$	$\checkmark$	observation	6.82	1.86	108
CONVLSTM	$\checkmark$	$\checkmark$	observation	6.29	<b>1.60</b>	<b>102</b>
ABED-SSH	$\times$	$\checkmark$	both	6.27	1.85	110
ABED-SSH-SST	$\checkmark$	$\checkmark$	both	<b>5.74</b>	1.61	<b>102</b>

## Conclusion and perspectives

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- SST is a key contextual information
- It is possible to learn a neural inversion from observations only
  - But it leads to a drop of performances
- Pre-training and fine-tuning neural networks leads to better reconstructions.
  - Especially for SST using networks.

Currently working on

- Forecast
- Simultaneous forecast and gridding

Other ideas

- Toward a global product : how to adapt this methods in the context of wider geographical areas ?
- Application of the method to other variables as well as contextual information or target data. (CHL)