

Application Descriptions

Shutters and Blinds

Shutters and Blinds Actuators

Supplement 1 LTE-Mode Extensions

Summary

This document specifies the Functional Blocks for actuators in the Shutters and Blinds Application Domain.

Version 01.00.02 is a KNX Approved Standard.

This document is part of the KNX Specifications v2.1.

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Document updates

Version	Date	Modifications
AN144 v03	2011.12.06	Voting comments included
7/50/2 S1 v01.00.00	2013.09.13	Publication as Chapter 7/50/2 Supplement 1 "Shutters and blinds actuators LTE extensions"
v01.00.01	2013.10.22	Editorial review in view of integration in the KNX Specifications v2.1.
v01.00.02	2013.10.22	Editorial review in view of integration in the KNX Specifications v2.1.

References

[01] Chapter 7/1/2 "Common Sensors"

[02] Chapter 7/50/1 "Shutters and Blinds Sensors"

[03] Chapter 7/50/2 "Actuators"

[04] Part 10/1 "Logical Tag Extended"

Filename: 07_50_02 Supp1 Shutters and blinds actuators LTE Extensions v01.00.02 AS.docx

Version: 01.00.02

Status: Approved Standard

Savedate: 2013.10.29

Number of pages: 77

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Abbreviations

COV Change Of Value FS FB Frost Sensor

IR LTE-Mode InfoReport serviceLTE-Mode Logical Tag Extended easy mode

RS FB Rain Sensor

SAB FB Sunblind Actuator Basic

SCS FB Scene Sensor

SSSB FB Shutters and Blinds Sunblind Sensor Basic

W LTE-Mode Write service

WS FB Wind Sensor

Shutters and Blinds

1 FB Sunblind Actuator Basic (SAB)

1.1 Aims and objectives

The definitions in this document for FB Sunblind Actuator Basic (SAB) are an extension of the existing Specification in [03] to describe the standardized LTE-Mode runtime interface and LTE-Mode specific parameters of FB SAB.

The FB SAB is used in the Application Domain of Shutters and Sunblind control:

- to exchange control commands and status information with Shutters and Sunblind Sensors (FB SSSB, traditional direct sensor actuator communication) where the control functionality, command arbitration and priority handling is located in the actuator
 - \Rightarrow see also [02]
- to be connected and controlled by a **Shutters and Blinds Controller** (sensor controller actuator communication)

1.2 Functional specification

1.2.1 Overview

This functional specification focuses on LTE-Mode specific runtime process data exchange and LTE-Mode specific parameters. SAB functionality, state machines and standardized SAB parameters are already specified in [03] and are therefore only referenced in this document.

Runtime interworking and binding of SAB is based on LTE-Mode zoning concepts. Control commands and status feedback information are exchanged according to LTE-Mode mechanisms in a common BlindsGroup.

In the LTE-Mode runtime system BlindsGroup is mapped to existing LTE-Mode Geographical zones. Runtime process communication of SAB is disabled if BlindsGroup is 'OutOfService'

If the SAB is connected to a Shutters and Blinds Controller, the LTE-Mode runtime data interface of the SAB is partially different from the runtime interworking between SAB and shutters and sunblind sensors SSSB. The different mechanisms are outlined in the following clauses.

The connection type (Sensor- or Controller-Connection) of the SAB is configurable via parameter ActuatorMode.

1.2.2 Application model for direct sensor – actuator binding

1.2.2.1 Illustrations

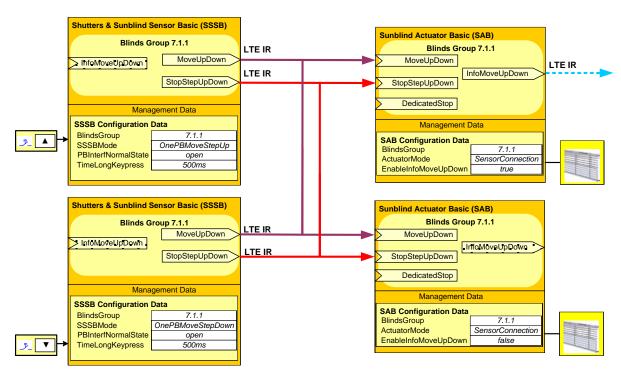


Figure 1 – Example of direct SSSB – SAB connection: manual blinds control, basic interworking

Figure 1 illustrates direct binding of two SSSB with two parallel blinds actuators SAB. Runtime interworking covers basic functionality to manually control blinds height and slats position. Both SSSB are configured to be operated via 1 push-button or binary input.

- one SSSB to provide control commands to move up / step up / stop movement only
- one SSSB to provide control commands to move down / step down / stop movement only

Control command **MoveUpDown** is provided by the SSSB to trigger up/down movement.

Control command StopStepUpDown is provided by the SSSB to trigger

- a stop command if actuator is moving
- a gradual up/down movement of its slats if actuator is not moving

Both control commands are sent by the SSSB using LTE-Mode InfoReport Service and are received and processed by both SAB in the same BlindsGroup.

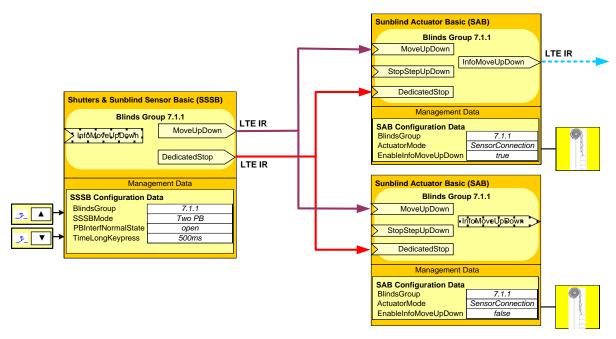


Figure 2 – Example of direct SSSB – SAB connection: manual shutter control, basic interworking

Figure 2 illustrates direct binding of one SSSB with two parallel actuators SAB. Runtime interworking covers basic functionality to manually control the shutter position.

SSSB is configured to be operated via 2 push-buttons or binary inputs.

- one push-button / binary input to provide control commands to move up / stop movement
- one push-button / binary input to provide control commands to move down / stop movement

Control command **MoveUpDown** is provided by the SSSB to trigger up/down movement of the shutter.

Specific control command **DedicatedStop** is provided by the SSSB instead of **StopStepUpDown** to trigger a stop command if the shutter is moving. DedicatedStop command is sent by the SSSB using LTE-Mode InfoReport Service and is received and processed by both SAB in the same BlindsGroup.

In the examples in Figure 1 and Figure 2 actuator feedback information **InfoMoveUpDown** is provided by one SAB (configured as group-speaker) to indicate the last moving direction. InfoMoveUpDown may be used to support e.g. the toggle functionality in the SSSB (1 push-button operation) or for any other purpose. However, in the examples above InfoMoveUpDown is in principle not needed on the SSSB.

Transmission of InfoMoveUpDown status information may be enabled or disabled via SAB configuration parameter EnableInfoMoveUpDown.

NOTE 1 Since both actuators are controlled together, InfoMoveUpDown could in principle be provided by both SAB. InfoMoveUpDown value of both actuator feedback messages would normally be identical (\Rightarrow last wins principle on the input in the SSSB). Redundant InfoMoveUpDown messages create unnecessary traffic and should be avoided.

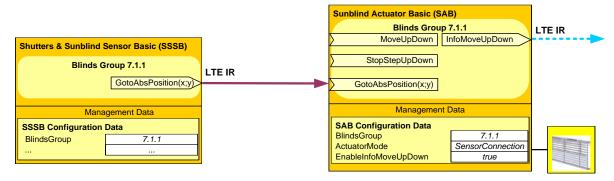


Figure 3 – SSSB providing combined absolute positioning command

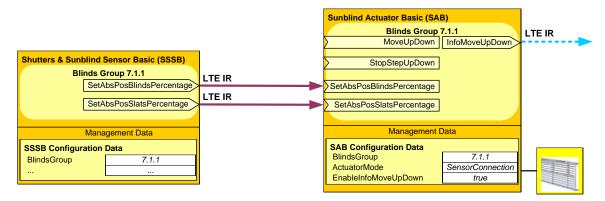


Figure 4 – SSSB providing separate height and slats positioning commands

Figure 3 and Figure 4 illustrate extended runtime interworking mechanisms between a SSSB and a SAB with the purpose to start moving the blinds towards an absolute position specified by the HeightPosition (%) and SlatsPosition (%).

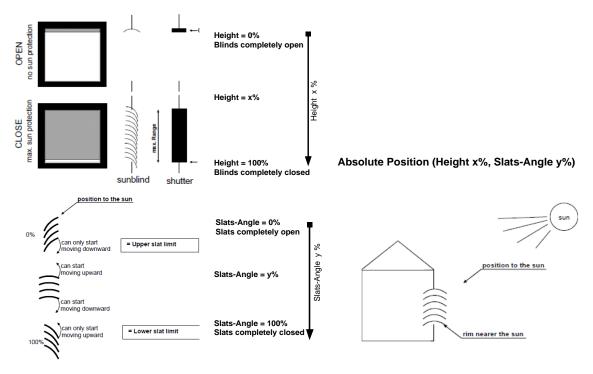


Figure 5 – Representation of height and slats position in percent

Control command **GotoAbsPosition(x;y)** according to Figure 3 contains both HeightPosition(x) and SlatsPosition(y) and validity attributes for both position fields. Combination of both position fields in one message ensures consistency of the target position. The actuator will usually move the blinds to the target HeightPosition first and will then move the slats to the target SlatsPosition.

Usage of combined control command GotoAbsPosition is recommended if the actuator supports control of height- and slats-angle position (e.g. for Venetian sunblind)

Control commands **SetAbsPosBlindsPercentage** and **SetAbsPosSlatsPercentage** according to Figure 4 are used to control HeightPosition(x) and SlatsPosition(y) independently. Usage of separate control commands SetAbsPosBlindsPercentage and SetAbsPosSlatsPercentage is recommended if either height – or slats-angle position can be controlled (e.g. for shutters or vertical jalousies).

Absolute positioning control commands are provided by the SSSB using LTE-Mode InfoReport Service and are received and processed by the SAB in the same BlindsGroup.

Absolute positioning control commands have the same priority as inputs MoveUpDown, StopStepUpDown or DedicatedStop (last wins principle).

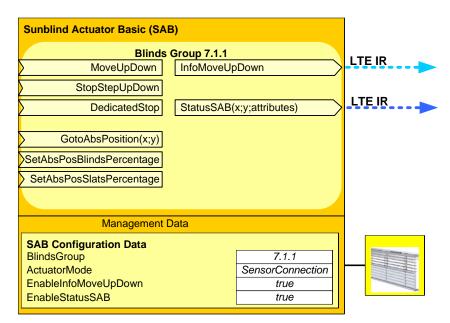


Figure 6 – Actuator status information

Figure 6 illustrates extended actuator status information **StatusSAB** that may be provided by the SAB in addition to InfoMoveUpDown signal. StatusSAB contains the current Height- and Slats-Position and additional status attributes in one message with the goal to ensure consistent status actuator information.

NOTE 2 Actuator status information should be provided by one group-speaker only if multiple actuators are controlled together in one BlindsGroup.

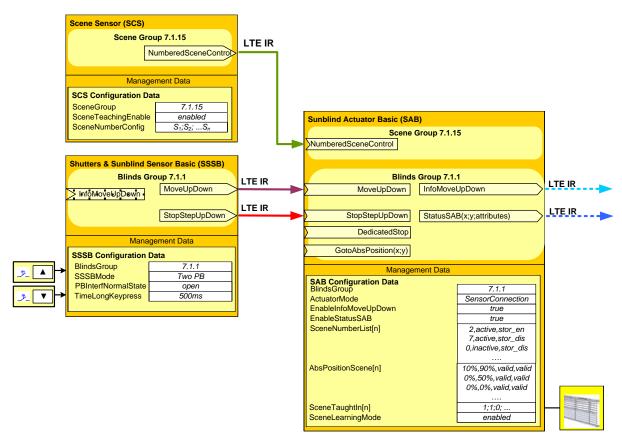


Figure 7 – Example Scene Control

Figure 7 illustrates the binding of a SAB with a SSSB and a Scene Sensor SCS (see [01]).

SCS provides **NumberedSceneControl** information to recall or teach-in a scene. NumberedSceneControl message is distributed using LTE-Mode InfoReport mechanisms in a dedicated SceneGroup.

In the LTE-Mode runtime system SceneGroup is mapped to existing LTE-Mode Geographical zones.

On SAB the NumberedSceneControl input has the same priority as MoveUpDown, StopStepUpDown, DedicatedStop, GotoAbsPosition etc. inputs (last wins principle).

NumberedSceneControl command is received and processed by the SABs belonging to a SceneGroup. After the execution of a scene recall command the SAB group-speaker will provide updated actuator feedback information.

Execution of the scene command by the SAB depends on various local scene configuration parameters. Therefore multiple SAB in the same BlindsGroup may react differently. In this case actuator status information of the group-speaker will not represent the current state of all SAB in the BlindsGroup!

It is highly recommended that pre-engineered scene configuration (storage function disabled) shall be identical for all SAB in the same BlindsGroup. The problem of inconsistent scene execution does not occur if scene learning feature is enabled on all SAB for a given scene number.

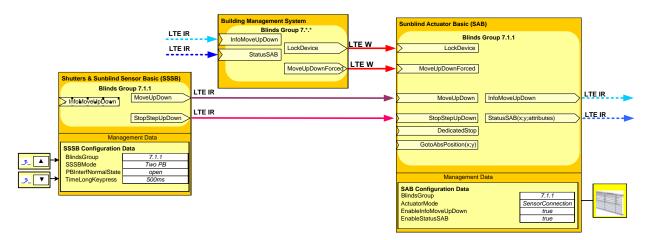


Figure 8 – Example of Building Management System overriding local SSSB commands

Figure 8 illustrates direct sensor actuator binding in combination with a Building Management System that may control the actuator with highest priority.

A Building Management System may trigger a forced up or down movement of the sunblind via prioritized control command **MoveUpDownForced** using LTE-Mode Write. Lower priority control command inputs on the SAB are overruled as long as the 'forced' attribute in MoveUpDownForced is set. If the 'forced' attribute is reset, the sunblind actuator can be controlled via lower priority inputs again.

A Building Management System may freeze the actual state of the actuator via control command **LockDevice** using LTE-Mode Write Service. The specific behaviour related to lock and unlock states and transitions can be controlled with additional SAB configuration parameters.

LTE-Mode wildcard features may be used to control all actuators in the same BuildingZone (e.g. 7.*.*).

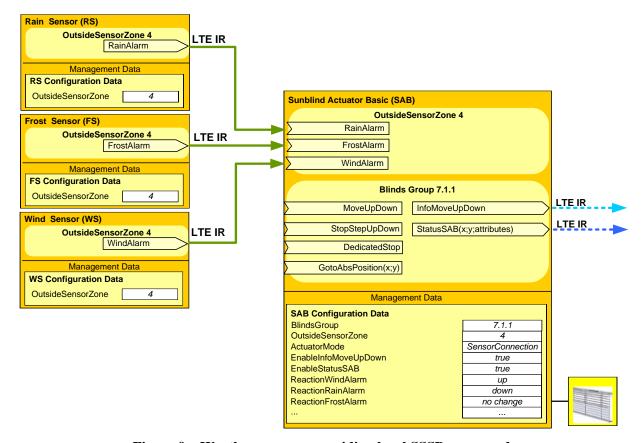


Figure 9 – Weather sensors overriding local SSSB commands

Weather sensors may be connected to the actuator to move the sunblind to a secure position in case of wind / frost / rain alarm and to block it for any further manual control. Weather alarm signals are provided by the corresponding sensor Functional Block using LTE-Mode InfoReport mechanisms in a dedicated OutsideSensorZone.

The behaviour of the actuator in case of a weather alarm is manufacturer specific or may be defined by additional parameters ReactionWindAlarm, ReactionRainAlarm, ReactionFrostAlarm.

In case of wind or frost or rain alarm, all other control commands with lower priority shall not be executed

However weather alarms can be overruled by a prioritized MoveUpDownForced control command, see Figure 8

1.2.2.2 SAB input signals

The Functional Block SAB receives sunblind control commands primarily from FB SSSB and optionally from various other sensor FBs. In addition the sunblind position may be locked or overruled by a Management Station. SAB moves the sunblind accordingly up, down or to a predefined position as well as stops the sunblind movement and steps the slats up/down.

The following SAB control command inputs are used in case of direct sensor-actuator connection:

- **MoveUpDown**: mandatory, low priority LTE-Mode IR input to receive control commands from FB SSSB to move the sunblind up or down
- StopStepUpDown: mandatory, low priority LTE-Mode IR input to receive stop/step control commands from FB SSSB. Depending on the received command this control signal triggers:
 - either a stop command if the sunblind is moving
 - or a gradual up/down movement of its slats if the sunblind is not moving
- **DedicatedStop**: optional, low priority LTE-Mode IR input to receive a dedicated control command from FB SSSB to stop movement of the sunblind. This command does not trigger a step to change the position of the slats
- **GotoAbsPosition**: optional, low priority LTE-Mode IR input to receive a dedicated control command from FB SSSB to start moving the sunblind towards the absolute target position specified by the combined command fields HeightPosition (%) and SlatsPosition(%).
 - Validity of HeightPosition and SlatsPosition fields is indicated by two dedicated attributes.
 - Field SlatsPosition shall be ignored if the actuator is only able to control the height position (e.g. in case of shutter control).
 - Field HeightPosition shall be ignored if the actuator is only able to control the angle position of the slats (e.g. control of vertical sunblinds).
- **SetAbsPosBlindsPercentage**: optional, low priority LTE-Mode IR input to receive a dedicated control command from FB SSSB to start moving the blinds towards a target height position (%).
 - NOTE 3 In the LTE-Mode implementation control signal SetAbsPosBlindsLength is not supported.
- **SetAbsPosSlatsPercentage**: optional, low priority LTE-Mode IR input to receive a dedicated control command from FB SSSB to move the slats to the target slats-angle position (%).
 - NOTE 4 In the LTE-Mode implementation control signal SetAbsPosSlatsDegrees is not supported.
- **NumberedSceneControl**: optional, low priority LTE-Mode IR input to receive numbered scene commands from a scene sensor SCS. This trigger input is used to call and store a maximum of 64 different sunblind positions in the SAB. NumberedSceneControl message is distributed by FB Scene Sensor SCS in a dedicated SceneGroup.

The number of scenes supported by the actuator can be lower than 64. It is optionally allowed that the functionality of the actuator is solely limited to recalling scenes without teaching.

Scene configuration parameters:

- SceneLearningModeEnable defines globally for all scenes if teach-in function is enabled or not
- SceneNumbers defines a list of Scene Numbers that are supported by FB SAB.

Each element of the list defines for a dedicated scene:

- the corresponding SceneNumber (0 to 63)
- scene active/inactive
- storage function enable/disable
- AbsPositionSceneNumber defines the absolute height- and angle- position of the slats for a dedicated scene

NOTE 5 In the LTE-Mode implementation the Datapoints for binary scene control as well as SceneNumber to recall numbered scenes are not supported.

- WindAlarm: optional, medium priority LTE-Mode IR input to receive wind alarm information from FB Wind Sensor WS to start moving the blinds to a secure position and to block it for any further manual control towards as long as the wind alarm is active.
 - WindAlarm message is distributed by FB WS in a dedicated OutsideSensorZone
- **RainAlarm**: optional, medium priority LTE-Mode IR input to receive rain alarm information from FB Rain Sensor RS to start moving the blinds to a secure position and to block it for any further manual control towards as long as the rain alarm is active.
 - RainAlarm message is distributed by FB RS in a dedicated OutsideSensorZone
- **FrostAlarm**: optional, medium priority LTE-Mode IR input to receive frost alarm information from FB Frost Sensor FS to start moving the blinds to a secure position and to block it for any further manual control towards as long as the frost alarm is active.
 - FrostAlarm message is distributed by FB FS in a dedicated OutsideSensorZone
- **MoveUpDownForced**: optional. high priority LTE-Mode W input to be written by e.g. a Building Management Station.
- This control command is used to overrule lower priority inputs by a management client according to the following rules:

Value of MoveUpDownForced	Mandatory behaviour of the actuator
00b, 01b	MoveUpDownForced is inactive.
	Low priority inputs are active.
10b	high priority forced move up
11b	high priority forced move down

- **LockDevice**: optional, high priority LTE-Mode W input to be written by e.g. a Building Management Station. This control command is used to freeze the actual position of the sunblind by a management client. The specific behaviour related to lock and unlock states and transitions can be controlled with additional parameters.
- ControlModeUser: optional LTE-Mode IR input to receive a control command from FB SSSB to indicate whether automatic control or manual control is requested by the room occupant. This process signal is usually intended for the runtime communication between a SSSB and a Shutters & Blinds Controller, see specification of FB SSSB and illustration in clause 1.2.3.1.
- However, from the perspective of the SSSB the Controller behaves like a SAB actuator proxy to emulate traditional direct Sensor Actuator communication. Therefore input 'ControlModeUser' is listed in this document as process signal of actuator proxy FB SAB.
 - In case of sophisticated actuators with built in controller functionality this input signal may also be useful on the SAB for direct Sensor Actuator communication.

In case of direct sensor – actuator connection, the following SAB inputs are generally disabled:

- MoveUpDownCmd,
- StopStepUpDownCmd
- DedicatedStopCmd
- AbsPositionSetp
- AbsHeightPositionSetp
- AbsSlatsPositionSetp

The behaviour is controlled by SAB configuration parameter ActuatorMode

1.2.2.3 Input priority handling

High priority input MoveUpDownForced having the value 'high priority forced move up' or 'high priority forced move down' shall override the following low priority inputs:

- MoveUpDown,
- StopStepUpDown
- DedicatedStop
- GotoAbsPosition
- SetAbsPosBlindsPercentage
- SetAbsPosSlatsPercentage
- NumberedSceneControl

and the following medium priority inputs:

- WindAlarm
- RainAlarm
- FrostAlarm.

Groups of inputs with the same priority shall be processed independently from each other, i.e. the last message notification to an input shall be executed.

Medium priority alarm states from weather sensors shall inhibit lower priority control commands, see above.

High priority input LockDevice shall inhibit all low and medium priority inputs.

Priority of input LockDevice vs. input MoveUpDownForced: the behaviour is manufacturer specific.

1.2.2.4 SAB output signals

- InfoMoveUpDown: optional LTE-Mode IR output to indicate the last moving direction of the sunblind actuator. Transmission of this output signal is triggered by COV only (no heartbeat). This information can be used solely for visualization purposes or for implementing the toggle functionality in the SSSB. Spontaneous transmission of InfoMoveUpDown in the LTE-Mode runtime system may be enabled or disabled via configuration parameter EnableInfoMoveUpDown. However the value of InfoMoveUpDown is always accessible via Property Read service.
- **StatusSAB:** mandatory LTE-Mode IR output to indicate the current status of the sunblind actuator.

- HeightPosition: actual height position represented as percentage value

- SlatsPosition: actual slats-angle represented as percentage value

- Attributes (bitset):

ValidHeightPos: to indicate the reliability of field HeightPosition
 ValidSlatsPos: to indicate the reliability of field SlatsPosition

UpperEndPos: to indicate if the sunblind has reached the upper end position
 LowerEndPos: to indicate if the sunblind has reached the lower end position

• LowerPredefPos: to indicate if the sunblind has reached the lower predefined position (typically height 100 %, slats-angle <100 %)

• DriveState: to indicate if the sunblind has reached the target position or if it is moving

- TargetHPosRestrict to indicate that the target height position cannot be reached due to some limitation of the moving range
- TargetSPosRestrict to indicate that the target slats-angle position cannot be reached due to some limitation of the moving range

• WeatherAlarm: to indicate if at least one of the inputs Wind-/Rain-/Frost-Alarm is 'in alarm'

Forced: to indicate if up/down position is forced by MoveUpDownForced input

Locked: to indicate if movement is locked, e.g. by DeviceLocked input

• LocalOverride: to indicate if the actuator setvalue is locally overridden, e.g. via a local user interface

• Failure to indicate a general failure of the actuator or the connected drive

StatusSAB shall be transmitted when the drive has stopped a movement. SAB may optionally transmit intermediate updates of StatusSAB while moving. StatusSAB is cyclically repeated (heartbeat).

This information can be used solely for visualization purposes or for any other purpose.

Spontaneous transmission of StatusSAB in the LTE-Mode runtime system may be enabled or disabled via configuration parameter EnableStatusSAB. However the value of StatusSAB is always accessible via Property Read service.

• **ControlModeEff:** optional LTE-Mode IR output to indicate if manual or automatic control is currently active in the BlindsGroup. This process signal is usually intended for the runtime communication between a SSSB and a Shutters & Blinds Controller, see specification of FB SSSB and illustration in clause 1.2.3.1.

However, from the perspective of the SSSB the Controller behaves like a SAB actuator proxy to emulate traditional direct Sensor – Actuator communication. Therefore output 'ControlModeEff' is listed in this document as process signal of actuator proxy FB SAB.

In case of sophisticated actuators with built in controller functionality this signal may also be useful on the SAB for direct Sensor - Actuator communication.

1.2.3 Application model for sensor – controller – actuator binding

1.2.3.1 Illustrations

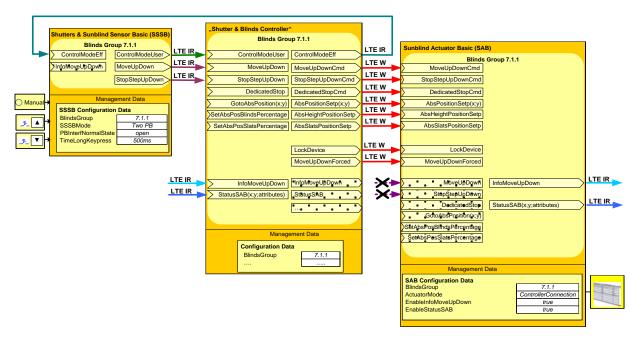


Figure 10 - Sunblind sensor - controller - actuator model: basic features

Figure 10 illustrates the basic application model for indirect binding of Sunblind Sensor SSSB with a Sunblind Actuator SAB via a Shutter & Blinds Controller.

The application model supports binding of SSSB – Controller - SAB in the same LTE-Mode BlindsGroup. However it is possible to configure separate BlindsGroups for SSSB - Controller and Controller-SAB bindings.

Runtime interworking SSSB – Controller

The LTE-Mode Shutter & Blinds application model does not define a dedicated 'Shutter & Blinds Controller' FB. The design and runtime interface of the Shutter & Blinds Controller is manufacturer specific. However in the runtime system, the Shutter & Blinds Controller shall emulate a Sunblind Actuator 'proxy SAB' as the counterpart for the Sunblind Sensors SSSB.

Sunblind Sensors SSSB are connected to the Controller to notify direct control commands requested by the room occupant (manual control). The runtime interface between SSSB and the Controller is the same as for sensor – actuator binding \Rightarrow see 1.2.2.

Inputs **MoveUpDown**, **StopStepUpDown**, **DedicatedStop** etc. on the Controller are usually processed with the same priority (last wins principle).

In addition the SSSB may provide the optional signal **ControlModeUser** representing a request by the user to change from manual to automatic control mode (and vice versa). The Controller provides the current control mode **ControlModeEff** (automatic/manual) as optional feedback information for the SSSB. For further details: see specification of FB SSSB and the statements in 1.2.2.2 and 1.2.2.4

The Controller determines the resulting control command to change the setpoint of the connected SAB according to control commands from SSSB and other criteria (e.g. scheduler, room occupancy etc.).

Runtime interworking Controller- SAB:

Direct control commands MoveUpDownCmd, StopStepUpDownCmd, DedicatedStopCmd are introduced on the SAB

- to trigger up/down movement of the sunblind
- to stop movement
- to perform a gradual up/down movement of the slats

The commands are sent to the SAB using LTE-Mode Write Service ¹⁾ and are executed by the actuator with the same low priority (last wins principle).

SAB inputs AbsPositionSetp(x;y), AbsHeightPositionSetp, AbsSlatsPositionSetp are introduced with the purpose to move the sunblind towards an absolute position specified by the HeightPosition (%) and SlatsPosition (%)

The commands are sent to the SAB using LTE-Mode Write Service ¹⁾ and are executed by the actuator with the same low priority (last wins principle)

The Controller may trigger a forced up or down movement of the sunblind via prioritized control command **MoveUpDownForced** using LTE-Mode Write Service; \Rightarrow see 1.2.2, Figure 8 Lower priority control command inputs on the SAB are overruled as long as the 'forced' attribute in MoveUpDownForced is set. If the 'forced' attribute is reset, the sunblind actuator can be controlled via lower priority inputs again.

The Controller may freeze the actual state of the actuator via control command **LockDevice** using LTE-Mode Write Service \Rightarrow see 1.2.2, Figure 8

The following SAB inputs are generally disabled to inhibit all direct control commands from SSSB:

- MoveUpDown
- StopStepUpDown
- DedicatedStop
- GotoAbsPosition
- SetAbsPosBlindsPercentage
- SetAbsPosSlatsPercentage

These inputs are disabled on the SAB via configuration parameter ActuatorMode.

SAB status information:

Same behaviour as for SSSB – SAB binding

 \Rightarrow see 1.2.2, Figure 6

Usually actuator status information is provided by one SAB only (configured to act as group-speaker).

SAB status information may be received by the Controller and the SSSB as well, if SSSB – Controller - SAB are connected via the same LTE-Mode BlindsGroup. Otherwise the Controller may act as an actuator proxy to route SAB status information to the SSSB in a different BlindsGroup; see example in Figure 11.

¹⁾ Please note that LTE Mode Write Service addresses the destination FB of the receiver (in this example the SAB) whereas LTE-Mode InfoReport Service contains the source FB of the sender.

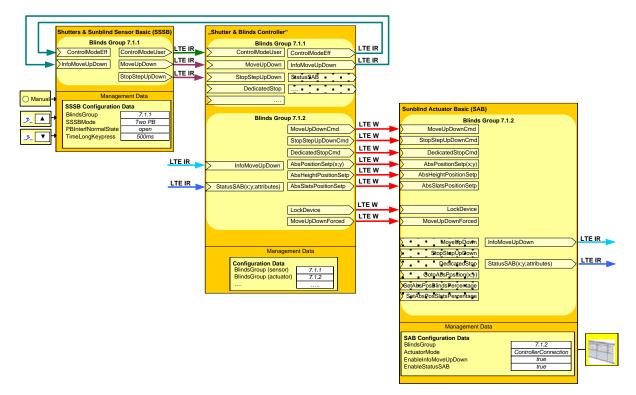


Figure 11 – Example with separate BlindsGroups for sensors and actuators

Figure 11 illustrates binding of sensors and actuators with the Controller via separate BlindsGroups.

- SSSB is connected to the Controller via in BlindsGroup 7.1.1.
- SAB is connected to the Controller via in BlindsGroup 7.1.2.

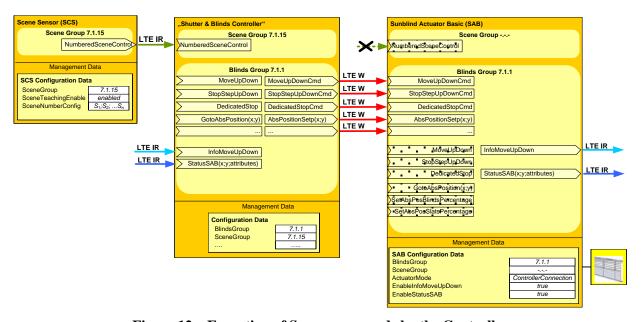


Figure 12 – Execution of Scene commands by the Controller

Figure 12 illustrates the binding of the Controller with a Scene Sensor SCS (see [01]).

SCS provides NumberedSceneControl information to recall or teach-in a scene. NumberedSceneControl message is distributed using LTE-Mode InfoReport mechanisms in a dedicated SceneGroup. In the LTE-Mode runtime system SceneGroup is mapped to existing LTE-Mode Geographical zones.

NumberedSceneControl command is received and processed by the Controller. Mapping of NumberedSceneControl command to scene number specific actuator states is handled by the Controller. The corresponding control commands are sent to the sunblind actuators that are affected by the scene command.

Input NumberedSceneControl on the SAB shall be disabled via SceneGroup to be configured with the value 'OutOfService'

This is the preferred model to handle scenes by the Controller. Parallel SAB in a BlindsGroup are controlled in the same way and therefore actuator feedback information of the group-speaker represents the state of all actuators in the BlindsGroup.

Alternative scene control model:

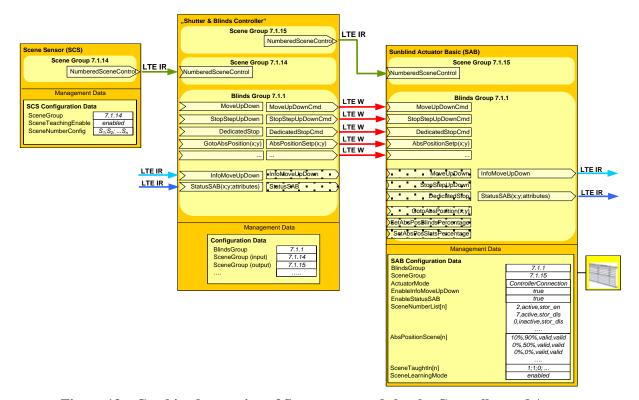


Figure 13 – Combined execution of Scene commands by the Controller and Actuator

Figure 13 illustrates an alternative solution to handle scenes by the Controller and the Actuator in a combined way.

Scene Sensor SCS and Sunblind Actuators shall belong to separate SceneGroups to inhibit direct communication between the SCS and the SAB.

NumberedSceneControl command from the SCS is received by the Controller and may be further processed and propagated to specific Sunblind Actuators. Transformation of the NumberedSceneControl command by the Controller includes a mapping of scene numbers and scene groups.

The Controller acts as a proxy SCS and generates corresponding NumberedSceneControl command using LTE-Mode InfoReport Service.

NumberedSceneControl command is received and processed by the SABs belonging to that SceneGroup; See description of Figure 7.

Execution of the scene command by the SAB depends on local scene configuration parameters. Therefore multiple SAB in the same BlindsGroup may react differently. In this case actuator status information of the group-speaker will not represent the state of all SAB in the BlindsGroup.

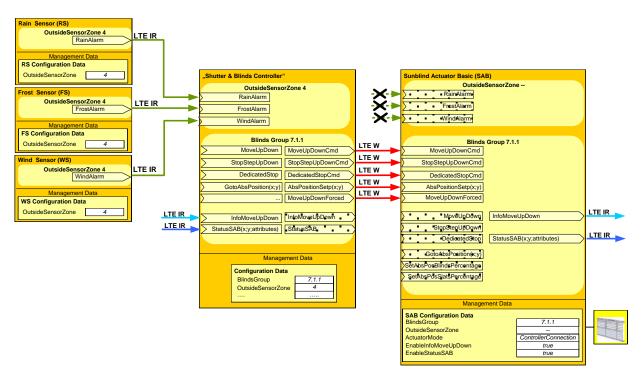


Figure 14 - Connection of weather sensors

Weather sensors may be connected to the Controller to indicate that the sunblind should be moved to a secure position in case of wind / frost / rain alarm and to block it for any further manual control. Weather alarm signals are provided by the corresponding sensor Functional Block using LTE-Mode InfoReport mechanisms in a dedicated OutsideSensorZone.

The Controller determines the resulting control command (e.g. MoveUpDownForced) to move the sunblind to a secure position. The behaviour of the Controller in case of a weather alarm is manufacturer specific.

Weather alarm inputs on the SAB shall be disabled via OutsideSensorZone to be configured with the value 'OutOfService'

1.2.3.2 SAB input signals

SAB provides various inputs to control the position of the sunblind and the angle of the slats by the connected Controller. The application program of the actuator prioritizes the different inputs to determine the resulting actuator setpoint.

- **MoveUpDownCmd**: mandatory, low priority LTE-Mode W input to trigger up or down movement of the sunblind
 - ⇒ same behaviour as MoveUpDown LTE-Mode IR command from SSSB.
- **StopStepUpDownCmd**: mandatory, low priority LTE-Mode W input. Depending on the received command this control signal triggers:
 - either a stop command if the sunblind is moving
 - or a gradual up/down movement of its slats if the sunblind is not moving
 - ⇒ same behaviour as StopStepUpDown LTE-Mode IR command from SSSB
- **DedicatedStopCmd**: optional, low priority LTE-Mode W to stop movement of the sunblind. This command does not trigger a step to change the position of the slats.
 - ⇒ same behaviour as DedicatedStop LTE-Mode IR command from SSSB
- **AbsPositionSetp**: optional, low priority LTE-Mode W input to set the absolute target position of the sunblind and the slats specified by the combined command fields HeightPosition (%) and SlatsPosition (%). Validity of HeightPosition and SlatsPosition fields is indicated by two dedicated attributes.
 - ⇒ same behaviour as GotoAbsPosition LTE-Mode IR input from SSSB
- **AbsHeightPositionSetp**: optional, low priority LTE-Mode W input to control the HeightPosition (%) of the sunblind only
 - ⇒ same behaviour as SetAbsPosBlindsPercentage LTE-Mode IR input from SSSB
- **AbsSlatsPositionSetp**: optional, low priority LTE-Mode W input to control the SlatsPosition (%) only
 - ⇒ same behaviour as SetAbsPosSlatsPercentage LTE-Mode IR input from SSSB
- **LockDevice**: same functionality as described in clause 1.2.2.2
- **MoveUpDownForced**: same functionality as described in clause 1.2.2.2
- **NumberedSceneControl**: optional, low priority LTE-Mode IR input to receive numbered scene commands from the Controller emulating a scene sensor SCS
 - \Rightarrow same functionality as described in clause 1.2.2.2
 - \Rightarrow execution of numbered scene commands is not recommended if the SAB is connected to a Controller

If the SAB is connected to a Controller, the following SAB LTE-Mode IR inputs are generally disabled via parameter ActuatorMode:

- MoveUpDown
- StopStepUpDown
- DedicatedStop
- GotoAbsPosition
- SetAbsPosBlindsPercentage
- SetAbsPosSlatsPercentage
- ControlModeUser

It is highly recommended to connect weather alarm sensors to the Controller only and to disable the corresponding inputs WindAlarm, RainAlarm, FrostAlarm on the SAB by setting the parameter OutsideSensorZone to the value 'OutOfService'

1.2.3.3 Input priority handling

Groups of inputs with the same priority shall be processed independently from each other, i.e. the last message notification to an input shall be executed. The actuator drive model calculates the resulting TargetPosition of the sunblind which may be represented and accessible via an optional local Property.

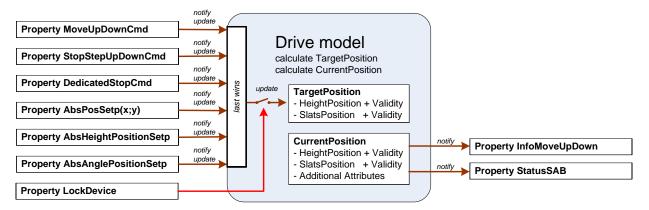


Figure 15 – Example of input priority handling

High priority input MoveUpDownForced having the value 'high priority forced move up' or 'high priority forced move down' shall overrule the following low priority LTE-Mode W inputs:

- MoveUpDownCmd,
- StopStepUpDownCmd
- DedicatedStopCmd
- AbsPositionSetp
- AbsHeightPositionSetp
- AbsSlatsPositionSetp

Priority of inputs LockDevice vs. input MoveUpDownForced: the behaviour is manufacturer specific.

1.2.3.4 SAB Output signals

Same functionality as specified in 1.2.2.4

1.3 Functional Block diagram

FB Sunblind A	Actuator Basic (SAB) 800
Inputs	Outputs
	BlindsGroup (Geographical)
IR: SSSB.MoveUpDown	IR: InfoMoveUpDown
IR: SSSB.StopStepUpDown	IR: StatusSAE
IR: SSSB.DedicatedStop	IR: ControlModeEf
IR: SSSB.SetAbsPosBlindsPercentage	
IR: SSSB.SetAbsPosSlatsPercentage	
IR: SSSB.GotoAbsPosition	
IR: SSSB.ControlModeUser	
W: MoveUpDownCmd	
W: StopStepUpDownCmd W: DedicatedStopCmd	
W: LockDevice	
W: MoveUpDownForced	
W: AbsHeightPositionSetp	
W: AbsSlatsPositionSetp	
W: AbsPositionSetp	
	1
Binding Grp.: S	SceneGroup (Geographical)
IR: SCS.NumberedSceneControl	
Pinding Cr	rn : OutoidoSonoor7ono
	p.: OutsideSensorZone
IR: WS.WindAlarm IR: RS.RainAlarm	
IR: FS.FrostAlarm	
additional I/Os	Parameters
-	BlindsGroup (Geographical)
	SceneGroup
	OutsideSensorZone
	ActuatorMode
	EnableInfoMoveUpDown
	EnableStatusSAB
	MoveDownTime + MoveUpTime
	AdditionalMoveTime ReversionPauseTime
	SlatStepTime
	MaximumSlatMoveTime + NumberOfSlatSteps
	PowerReturnMode + PowerReturnValue
	BusFailureMode + BusFailureValue
	BusReturnMode + BusReturnValue
	PowerFailureMode
	BehaviourAtLocking + LockSetvalue
	BehaviourAtUnlocking + UnlockSetvalue
	SceneLearningModeEnable SceneNumberList[n]
	SceneTaughtIn[n]
	AbsPositionScene[n]
	EnableBlindsMode
	ReactionWindAlarm
	ReactionRainAlarm
	ReactionFrostAlarm
	TimeoutWindAlarm
	TimeoutRainAlarm
	TimeoutFrostAlarm
mondatory	nol ID. LTC Mode InfoDenced - W. LTC Mede W. C.
mandatory option	nal IR: LTE-Mode InfoReport W: LTE-Mode Write

Figure 16 – Functional Block Diagram for FB Shutters and blinds sunblind Sensor Basic

NOTE 6 The LTE-Mode Write Service addresses the destination FB of the receiver (i.e. SAB for the MoveUpDownCmd input) whereas LTE-Mode InfoReport Service contains the source FB of the sender (i.e. SCS for the NumberedSceneControl input). Therefore all LTE-Mode W inputs are directly addressing local properties of the SAB. For further details: see LTE-Mode Specification in [04].

1.4 Datapoints

Datapoint	Description	Datapoint Type	SAB PID
Inputs			
SSSB.MoveUpDown	Request from a Sunblind Sensor SSSB to move the blinds up (=0) or down (=1)	DPT_UpDown (1.008)	SSSB PID 61
SSSB.StopStepUpDown	Request from a Sunblind Sensor SSSB to stop movement of the sunblind or to perform a step Up/Down	DPT_Step (1.007)	SSSB PID 62
SSSB.DedicatedStop	Request from a Sunblind Sensor SSSB to stop movement of the shutter	DPT_Trigger (1.017)	SSSB PID 63
SSSB.SetAbsPosBlinds Percentage	Request from a Sunblind Sensor SSSB to set the absolute position of the blinds in percentage.	DPT_Scaling (5.001)	SSSB PID 65
SSSB.SetAbsPos SlatsPercentage	Request from a Sunblind Sensor SSSB to set the absolute position of the slats in percentage.	DPT_Scaling (5.001)	SSSB PID 66
SSSB.GotoAbsPosition	Request from a Sunblind Sensor SSSB to start moving the blinds towards the absolute position specified by the combined command fields HeightPosition (%) and SlatsPosition (%) Validity of the individual command fields is indicated by two additional attributes	DPT_CombinedPositi on (240.800)	SSSB PID 67
SSSB.ControlModeUser	Request from a Sunblind Sensor SSSB to select automatic or manual control of the sunblind	DPT_BlindsControlM ode (20.804)	SSSB PID 64
SCS.NumberedSceneCo ntrol	Trigger form a Scene Sensor or a Controller (sender FB SCS) to recall or learn the output state related to the encoded scene number	DPT_SceneControl (18.001)	SCS PID 51
WS.WindAlarm	Indication from a Wind Sensor to move the sunblind to a secure position in case of strong wind and to block it for any further control. The secure position can be controlled by an additional parameter	DPT_Alarm (1.005)	WS PID 51
FS.FrostAlarm	Indication from a Frost Sensor to move the sunblind to a secure position in case of frost alarm and to block it for any further control. The secure position can be controlled by an additional parameter	DPT_Alarm (1.005)	FS PID 51
RS.RainAlarm	Indication from a Rain Sensor to move the sunblind to a secure position in case of rain alarm and to block it for any further control. The secure position can be controlled by an additional parameter	DPT_Alarm (1.005)	RS PID 51
MoveUpDownCmd	Input to be written by a Controller to trigger up (=0) or down (=1) movement of the sunblind	DPT_UpDown (1.008)	PID 61
StopStepUpDownCmd	Input to be written by a Controller to stop movement of the sunblind or to perform a step up/down	DPT_Step (1.007)	PID 62

Datapoint	Description	Datapoint Type	SAB PID
Inputs			
DedicatedStopCmd	Input to be written by a Controller to stop movement of the shutter	DPT_Trigger (1.017)	PID 63
MoveUpDownForced	Input to be written by a Controller or by a BMS to move the sunblind to a forced up or down position and to block it for any further control	DPT_Direction1_Cont rol (2.008)	PID 65
AbsHeightPositionSetp	Input to be written by a Controller to control the HeightPosition (%) of the sunblind.	DPT_Scaling (5.001)	PID 66
AbsSlatsPositionSetp	Input to be written by a Controller to control the angle position (%) of the slats	DPT_Scaling (5.001)	PID 67
AbsPositionSetp	Input to be written by a Controller to start moving the blinds towards the absolute position specified by the combined command fields HeightPosition (%) and SlatsPosition (%) Validity of the individual command fields is indicated by two additional attributes	DPT_CombinedPositi on (240.800)	PID 68
LockDevice	Input to freeze the actual setpoint of the actuator e.g. by a Controller or by a BMS. The specific behaviour related to lock and unlock states and transitions can be controlled with additional parameters	DPT_Enable (1.003)	PID 69

Datapoint	Description	Datapoint Type	SAB PID
Outputs			
InfoMoveUpDown	Feedback information from the actuator to indicate the last moving direction	DPT_UpDown (1.008)	PID 51
StatusSAB	Feedback information from the actuator to indicate - current HeightPosition - current SlatsPosition - various attributes	DPT_StatusSAB (241.800)	PID 52
ControlModeEff	Feedback information from the actuator to indicate if manual or automatic control is currently active in the BlindsGroup	DPT_BlindsControlMo de (20.804)	PID 54

Datapoint	Description	Datapoint Type	SAB PID
Parameters			
BlindsGroup (3 Properties)	LTE-Mode Geographical Zone - Building zone like Floor, Apartment - Room within the Building zone - Subzone within the Room	- DPT_UcountValue8_Z (202.002) - DPT_UcountValue8_Z (202.002) - DPT_UcountValue8_Z (202.002)	PID 101-103
SceneGroup (3 Properties)	LTE-Mode Geographical Zone - Building zone like Floor, Apartment - Room within the Building zone - Subzone within the Room	- DPT_UcountValue8_Z (202.002) - DPT_UcountValue8_Z (202.002) - DPT_UcountValue8_Z	PID 104-106

Datapoint	Description	Datapoint Type	SAB PID
Parameters			
		(202.002)	
OutsideSensorZone	LTE-Mode Zone for Wind, Rain, Frost Alarm sensors	- DPT_UcountValue8_Z (202.002)	PID 107
ActuatorMode	Parameter to define whether the Actuator is connected to a Sensor (SSSB) or to a Controller 1: SensorConnection 2: ControllerConnection	DPT_ActuatorConnectType (20.020)	PID 110
EnableInfoMoveUpDown	Parameter to enable or disable transmission of actuator state InfoMoveUpDown	DPT_Enable (1.003)	PID 111
EnableStatusSAB	Parameter to enable or disable transmission of actuator state StatusSAB	DPT_Enable (1.003)	PID 112
MoveDownTime	Time to move the sunblind from the final upper to the final lower position.	DPT_TimePeriodSec (7.005)	PID 113
MoveUpTime	Time to move the sunblind from the final lower to the final upper position.	DPT_TimePeriodSec (7.005)	PID 114
AdditionalMoveTime	Additional time to move the sunblind from the upper/lower position to the end- switch position	DPT_TimePeriodSec (7.005)	PID 115
ReversionPauseTime	Stop Time before changing the moving direction	DPT_TimePeriodMsec (7.002)	PID 116
SlatStepTime	Time to move the slat for one step.	DPT_TimePeriodMsec (7.002)	PID 117
NumberOfSlatSteps	Number of steps to move the slats from the final upper 0 % to the final lower 100 % position	DPT_Value_1_Ucount (5.010)	PID 118
MaximumSlatMoveTime	Time to move the slats from the final upper 0 % to the final lower 100 % position	DPT_TimePeriodMsec (7.002)	PID 119
PowerReturnMode	Parameter to define the behaviour of the actuator after return of the supply power or after a restart of the application: - 0 = up - 1 = down - 2 = no change - 3 = value according additional parameter ⇒ PowerReturnValue - 4 = stop	DPT_SABExceptBehaviour (20.801)	PID 120
PowerReturnValue	Parameter in addition to parameter PowerReturnMode = 3; to define the HeightPosition (%) and SlatsPosition (%)after power return	DPT_CombinedPosition (240.800)	PID 121
BusFailureMode	Parameter to define the behaviour of the actuator in case of a bus failure: - 0 = up - 1 = down - 2 = no change - 3 = value according additional parameter ⇒ BusFailureValue - 4 = stop	DPT_SABExceptBehaviour (20.801)	PID 122

Datapoint	Description	Datapoint Type	SAB PID
Parameters			
BusFailureValue	Parameter in addition to parameter BusFailureMode = 3; to define the behaviour in case of a bus failure	DPT_CombinedPosition (240.800)	PID 123
BusReturnMode	Parameter to define the behaviour of the actuator in case of a recovery of the bus: - 0 = up - 1 = down - 2 = no change - 3 = value according additional parameter ⇒ BusReturnValue - 4 = stop	DPT_SABExceptBehaviour (20.801)	PID 124
BusReturnValue	Parameter in addition to parameter BusReturnMode = 3; to define the behaviour after a recovery of the bus.	DPT_CombinedPosition (240.800)	PID 125
PowerFailureMode	Parameter to define the behaviour of the actuator in case of the supply power failure, to switch e.g. a bistable relay before power down of the device: - 0 = up - 1 = down - 2 = no change - 4 = stop	DPT_SABExceptBehaviour (20.801)	PID 126
BehaviourAtLocking	Parameter to define the behaviour of the actuator in case of input LockDevice changing from false -> true: - 0 = up - 1 = down - 2 = no change - 3 = value according to parameter LockSetvalue - 4 = stop	DPT_SABBehaviour_Lock_ Unlock (20.802)	PID 127
LockSetvalue	Parameter in addition to parameter BehaviourAtLocking = 3; to define the behaviour at the beginning of the lock state	DPT_CombinedPosition (240.800)	PID 128
BehaviourAtUnlocking	Parameter to define the behaviour of the actuator in case of input LockDevice changing from true -> false: - 0 = up - 1 = down - 2 = no change - 3 = value according to parameter UnlockSetvalue - 5 = updated value - 6 = value before locking	DPT_SABBehaviour_Lock_ Unlock (20.802)	PID 129
UnlockSetvalue	Parameter in addition to parameter BehaviourAtUnlocking = 3; to define the behaviour at the end of the lock state	DPT_CombinedPosition (240.800)	PID 130
SceneLearningModeEna		DPT_Enable (1.003)	PID 131

Datapoint	Description	Datapoint Type	SAB PID
Parameters			
ble	scene numbers the learning of new scenes, regardless of the value of any field Storage Function of the Scene Index in the Parameter SceneNumbers.		
SceneNumberList[n]	List of Scene Numbers that are supported by this FB SAB. This parameter is implemented as an array property with n (up to 64) elements. This list shall allow linking a Scene Number to a Scene Index within the FB. Each array element defines for a dedicated scene: SceneNumber (0 to 63) activation/inactivation storage function enable/disable	DPT_SceneConfig (238.001)	PID 132
SceneTaughtIn[n]	This parameter is implemented as an array property with n (up to 64) elements. Each element indicates for a dedicated scene, whether the scene n has been taught in or not	DPT_BOOL	PID 133
AbsPositionScene[n]	This parameter is implemented as an array property with n (up to 64) elements. Each element defines the height and slats-angle position and validity attributes for a dedicated scene	DPT_CombinedPosition (240.800)	PID 134
EnableBlindsMode	Determines whether the actuator functions as a blinds actuator (with slats) or only as a shutter actuator (no slats -> step command is interpreted as stop)	DPT_Enable (1.003)	PID 135
ReactionWindAlarm	Defines the behaviour of the actuator in case of a wind alarm whether to move the sunblind to final upper or final lower position or no reaction	DPT_Alarm_Reaction (23.002)	PID 140
ReactionRainAlarm	Defines the behaviour of the actuator in case of a rain alarm whether to move the sunblind to final upper or final lower position or no reaction	DPT_Alarm_Reaction (23.002)	PID 141
ReactionFrostAlarm	Defines the behaviour of the actuator in case of a frost alarm whether to move the sunblind to final upper or final lower position or no reaction	DPT_Alarm_Reaction (23.002)	PID 142
TimeoutWindAlarm	Defines the timeout period for receiving a message on input WindAlarm.	DPT_TimePeriodMin (7.006)	PID 143
TimeoutRainAlarm	Defines the timeout period for receiving a message on input RainAlarm.	DPT_TimePeriodMin (7.006)	PID 144
TimeoutFrostAlarm	Defines the timeout period for receiving a message on input FrostAlarm.	DPT_TimePeriodMin (7.006)	PID 145

Table 1 - support of LTE-Mode runtime process data

		ActuatorMode			
		SensorConnection	ControllerConnection		
Inputs	SSSB.MoveUpDown	М	NA		
	SSSB.StopStepUpDown	М	NA		
	SSSB.DedicatedStop	0	NA		
	SSSB.SetAbsPosBlindsPercentage	0	NA		
	SSSB.SetAbsPosSlatsPercentage	0	NA		
	SSSB.GotoAbsPosition	0	NA		
	SSSB.ControlModeUser ²⁾	0	NA		
	SCS.NumberedSceneControl	0	0		
	WS.WindAlarm	0	0		
	RS.RainAlarm	0	0		
	FS.FrostAlarm	0	0		
	MoveUpDownCmd	NA	M		
	StopStepUpDownCmd	NA	M		
	DedicatedStopCmd	NA	0		
	LockDevice	0	0		
	MoveUpDownForced	0	0		
	AbsHeightPositionSetp	NA	0		
	AbsSlatsPositionSetp	NA	0		
	AbsPositionSetp	NA	0		
Outputs	InfoMoveUpDown	0	0		
	StatusSAB	М	M		
	ControlModeEff ²⁾	0	0		

functionality these signals may also be useful on the SAB for direct Sensor - Actuator communication. In case of Sensor - Controller – Actuator communication, the SAB in the Actuator shall disable these process signals.

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Process signals 'ControlModeUser' and 'ControlModeEff' are usually intended for the runtime communication between a SSSB and a Shutters & Blinds Controller, see specification of FB SSSB. However, from the perspective of the SSSB the Controller behaves like a SAB actuator proxy to emulate traditional direct Sensor – Actuator communication. Therefore input 'ControlModeUser' and output 'ControlModeEff' are listed in this document as process signals of actuator proxy FB SAB. In case of sophisticated actuators with built in controller

Table 2 - LTE-Mode specific Properties

		Support
Parameter	BlindsGroup	М
	SceneGroup	0
	OutsideSensorZone	0
	ActuatorMode	М
	EnableInfoMoveUpDown	0
	EnableStatusSAB	М

Table 3 - Standard Properties of Interface Object

_		Support
Parameter	MoveDownTime	0
	MoveUpTime	0
	AdditionalMoveTime	0
	ReversionPauseTime	0
	SlatStepTime	0
	NumberOfSlatSteps	0
	MaximumSlatMoveTime	0
	PowerReturnMode	0
	PowerReturnValue	0
	BusFailureMode	0
	BusFailureValue	0
	BusReturnMode	0
	BusReturnValue	0
	PowerFailureMode	0
	BehaviourAtLocking	0
	LockSetvalue	0
	BehaviourAtUnlocking	0
	UnlockSetvalue	0
	SceneLearningModeEnable	0
	SceneNumberList[n]	0
	SceneTaughtIn[n]	0
	AbsPositionScene[n]	0
	EnableBlindsMode	0
	ReactionWindAlarm	0
	ReactionRainAlarm	0
	ReactionFrostAlarm	0
	TimeoutWindAlarm	0
	TimeoutRainAlarm	0
	TimeoutFrostAlarm	0
Diagnostic Data		

1.5 Detailed specification of the Datapoints

1.5.1 Output InfoMoveUpDown

FB: SAB	LTE	E-Mode	e Server Output Nan	ne: InfoM	loveUpE	Down	Mar	ndatory <u>L</u>	<u> </u>	nal 🖂
Description:										
The output InfoMoveUpDown provides feedback information from the actuator to indicate the last moving direction.										
	e shall	he sen	t when the sunblind s	tarts movin	a and n	ot wh	en ente	ring in the	e state s	tenning
			ed solely for visualiza							
in the SSSB				anon parpoc	00 01 10	,r	3101110111	ng mo to;	, g.o . u c	, in or idinty
DPT: Name DPT_UpDown DPT ID 1.008 Datatype format B ₁										
Field			ription		Sup.	Ran		Unit	COV	Default
b			ield shall indicate the	moving	M	{0, '		-	-	-
			ion up (0) or down (1			,	,			
Communica	ation:		. , ,	,			*		-	
Binding Gr	oup:									
Class			Туре			Defa	ault			
Geographic	cal	\boxtimes	BuildingZone.Room	.Subzone		cs (see para	ameter Bl	indsGro	lb)
Application		с 🗌								
Unassigned			Broadcast Configurable							
DP Addres	s:		IO Type(ID): 800 (SAB) Property ID:			:	51			
LTE-Mode	-Servic	es	COV MinRepTime: sec			sec	Heartbeat: min			
(event):			Output per default communicating					oup Wild	card allo	wed 🗌
InfoReport		\boxtimes	Tx Prio: High \(\square\) Normal \(\square\) Lo				Low			
(LTE-Mode										
Response			Transm after Powerup: Stored Value ☐ Act Value ☐ Default Value ☐					due 🗆		
the output s		vays	Transm alter rewer	up. Otorcu	value _E	<u> </u>	riot vaic		ciadit ve	
be supporte										
Property-Service (individual access): Read only Read/Write										
Exception F	Exception Handling: Save at Powerdown							own 🛛		
Special Fea										
- If multiple actuators are in the same zone, each actuator may send its own InfoMoveUpDown										
message. Since all actuators in the same zone are controlled together, subsequent InfoMoveUpDown										
			m parallel actuators v							
- Group speaker: in order to reduce network traffic, one group speaker out of all SAB in the same										
BlindsGroup can be nominated by SAB configuration via parameter EnableInfoMoveUpDown.										

1.5.2 Output StatusSAB

FB:	SAB	LTE-Mode Server Output Name:	StatusSAB	Mandatory 🛛 2)	Optional
_					

Description:

Output StatusSAB indicates provides feedback information from the actuator to indicate the current HeightPosition, SlatsPosition and various status attributes.

StatusSAB shall be transmitted:

- when the drive has completed a motion (State MOVING -> STOPPED)
- if one of the Attributes changes its value in State STOPPED

StatusSAB may be transmitted

- when the sunblind starts moving (transition to State MOVING) with an allowed latency (e.g. few hundreds of ms)
- It is additionally allowed to transmit intermediate updates of StatusSAB during a motion in State MOVING, however, at maximum once per minute.

StatusSAB must not be transmitted when entering the State STEPPING

This information can be useful for the application program of the Controller or it may be used solely for visualization or for other purposes

DPT : Name DPT_	Status	StatusSAB DPT ID 241			.800	Datatype format U ₈ U ₈ B ₁₆			3 ₁₆
Field	Descri	iption			Sup	Range	Unit	CO V	Default
HeightPosition	Current height position in %			М	0 % to 100 %	%	cs	CS	
SlatsPosition	Current slats-angle position %			М	0 % to 100 %	%	cs	CS	
Attributes	Bit #				0				
- UpperEndPos	0	Upper end position reached			O 3)	{0, 1}		Υ	0
- LowerEndPos	1	Lower end position reached			O 3)	{0, 1}		Υ	0
- LowerPredefPos	2	Lower predefined position reached; typically height 100 %, slats-angle <100 %			O 3)	{0, 1}		Y	0
- DriveState	3	Indicates wheth position is reactorive is moving	hed (1) or t		M	{0, 1}		Y	1
- TargetHPosRestrict	4	Restriction of target height position. Position cannot be reached			0	{0, 1}		Y	0
- TargetSPosRestrict	5	Restriction of ta position. Position reached		е	0	{0, 1}		Y	0
- WeatherAlarm	6	At least one of Wind-/Rain-/Fro		S	0	{0, 1}		Y	0
- Forced	7	up/down position by MoveUpDow input	vnForced	l	0	{0, 1}		Y	0
- Locked	8	Movement is lo DeviceLocked i			0	{0, 1}		Υ	0
- LocalOverride	9	indicates if the setvalue is loca overridden, e.g. user interface	illy . via a loca	I	0	{0, 1}		Y	0
- Failure	10	General actuate	or failure		0	{0, 1}		Υ	0
- reserved	11 12 13				NA	0			0
- ValidHeightPos	14	Validity of field HeightPosition			М	{0, 1}			cs
- ValidSlatsPos	15	Validity of field	SlatsPositi	on	М	{0, 1}			CS

Communication:								
Binding Group:								
Class	Type	Default						
Geographical 🖂	BuildingZone.Room.Subzone	cs (see parameter BlindsGroup)						
Application Specific								
Unassigned	Broadcast Configurable							
DP Address:	IO Type(ID): 800 (SAB)	Property ID: 52						
LTE-Mode-Services	COV MinRepTime: 10	s ¹⁾ sec Heartbeat: 15 min						
(event):	Output per default communicating	Binding Group Wildcard allowed						
InfoReport 🖂	Tx Prio: High 🗌	Normal \(\sumber \) Low \(\superstandarrow\)						
(LTE-Mode Read-	•							
Response polling of	Transm after Powerup: : Stored Value	☐ Act Value ☑ Default Value ☐						
the output shall always	Transifi after Fowerup Stored value	☐ Act value ☑ Delauit value ☐						
be supported)								
Property-Service	Read only X Read/W	/rite □						
(individual access):								
Exception Handling:		Save at Powerdown						
Special Features:								
in State MOVING Status	SAB may be updated at maximum once	per minute						
²⁾ Spontaneous transmission	on of StatusSAB in the LTE-Mode runtin	ne system may be enabled or disabled						
	r EnableStatusSAB. However the value							
Property Read service.								
Group speaker: in order to reduce network traffic, one group speaker out of all SAB in the same								
BlindsGroup can be nominated by SAB configuration via parameter EnableStatusSAB. If transmission of								
StatusSAB is disabled, this signal can't be used for life-check and supervisory functions for individual								
actuators anymore								
3) StatusSAB does not contain information whether or not the actuator has the ability to detect such								
positions. As long as the position attributes are 0, the client of this information does not know if the								
position is not reached or if the information is not supported by the SAB.								
The client of StatusSAB may test and learn autonomously during commissioning if the position attributes								

are supported by moving the blinds to the upper end lower end positions. The corresponding position

flags will temporarily change to 1 during that test if the position can be detected, e.g. via end switches. An alternative solution would be that the client of StatusSAB is informed via configuration if the SAB supports the position flags.

1.5.3 Output ControlModeEff

FB: SAB LTE-MC	ode Server Output Nan	ne: Con	trolMode	eEff	Mandatory [Optio	nal $oximes^{1)}$
Description:							
Output ControlModeEff indicates if manual or automatic control is currently active in the BlindsGroup. This information can be used solely for visualization purposes, or to synchronize ControlModeUser values of multiple SSSB in the same zone, or for other purposes							
DPT: Name DPT_BlindsControlMode DPT ID 20.804 Datatype format N ₈							
	escription		Sup.	Range	Unit	COV	Default
	nis field shall indicate wh		M	0, 1 *)	-	Υ	cs
	tomatic control (0) or m						
со	ntrol (1) is currently acti	ive					
	l 0 (. 055						
	llues 2 to 255 are reserv	/ea for					
Communication:	ture extensions						
Binding Group:							
Class	Туре			Default			
Geographical X		Subzone			parameter Bl	indsGro	(au
Application Specific]			10 (000	<u> </u>		
Unassigned	Broadcast C	onfigurable					
DP Address:	IO Type(ID):	800 (SAB))	Proper	rty ID:	54	
LTE-Mode-Services		/linRepTim		se			15 min
(event):	Output per default c	ommunica	ting 🖂	Bindir	ng Group Wilde	card allo	wed 🛛
InfoReport	Tx Prio:	High 🗌		Norn	nal 🛚	Low	
(LTE-Mode Read-							
Response polling of	Transm after Power	up: : Store	d Value	☐ Act	Value D	efault Va	alue 🖂
the output shall always							<u></u>
be supported)							
Property-Service (individual access):							
Exception Handling: Save at Powerdown					own 🗆		
	Save at Powerdown						
Special Features:							
1) Usually this output may only implemented in a Controller which emulates a SAB actuator proxy, see							
comments in clause 1.2.2.4 and 1.2.3.4							
This output is disabled if the SAB is controlled by a Controller (⇒ see parameter ActuatorMode)							

1.5.4 Input MoveUpDown

FB: S	SAB	L	TE-	Mod	e Client Input Nam	ie:	Move	eUpDow	/n	Ма	ndatory [☑ ¹⁾ Opti	onal 🗌
Descrip	ption:												
					ndicates the reques								t of the
					 The behaviour of 								
MoveU	pDown :	sh	all d	omp	ly with the actuator	state m	achin	e descri	ption :	as spec	cified in [C)3].	
DPT:	Name	!	DP	T_{U}	Down	DPT	ĪD	1.008		atatype	e format	B ₁	
Field					Description						Sup.	Unit	Default
b					This field shall inc	licate w	/hethe	r the su	nblind	ls	M		none
					actuator will move	e up (0)	or do	wn (1)					
Commi	unicatio	on	:										
Bindin	Binding Group:												
Class					Type				Defa	ult			
Geogra	aphical			\boxtimes	BuildingZone.Roo	m.Sub	zone		cs (s	ee par	ameter Bl	indsGrou	p)
Applica	ation Sp	ec	cific										
Unassi					Broadcast	Confi	igurab	le 🗌					
DP Ad	dress:				IO Type(ID):	801	(SSSE	3)	Pro	perty ID) :	61	
LTE-M	lode-Se	rv	ice		InfoReport Sniffe	r on Bi	nding	Group:					
(event	,				Timeout:				Min				
InfoRe				\boxtimes	Timeout.				IVIIII				
	lode-Se	rv	ice										
(pollin					Read Wildcard / F	Resp Sr	niffer o	on Bindi	ng Gro	oup:			
Read -	 Respo 	ns	se										
Value a	Value after Powerup: Default Value □ Stored Value □												
Exception Handling: Save at Powerdown													
1													
Specia	l Featur	re	s:										
This lov	w priority	y i	npu	t on t	he actuator can be	overrule	ed by	other in	puts. S	See pri	ority hand	lling in cla	ause
1.2.2.3	.2.2.3												
¹⁾ This i	input is o	dis	sabl	ed if	the SAB is controlle	d by a	Contro	oller (⇒	see p	arame	ter Actuat	orMode)	

1.5.5 Input StopStepUpDown

FB: SAB	LTE	-Mode	e Client Input Name	: Stop	StepUpl	Dow	n Ma	andatory [☑ ¹⁾ Opti	onal 🗌
Description:										
			n indicates the requ							
			ep Up/Down. The be							input
			mply with the actuate		chine de	escri	ption as	specified i		
DPT: Name	DF	T_Ste	ер	DPT ID	1.007		Datatyp	e format	B ₁	
Field			Description					Sup.	Unit	Default
b			Indicates a request	to perform	a gradu	al		M		none
			movement							
			0: step up or stop							
			1: step down or sto	op						
	Communication:									
Binding Group:										
Class Type Default										
Geographical			BuildingZone.Roon	n.Subzone		cs	(see par	ameter Bl	indsGrou	p)
Application Sp	pecific									
Unassigned			Broadcast	Configurat						
DP Address:			IO Type(ID):	801 (SSS		Р	roperty II) :	62	
LTE-Mode-Se	ervice		InfoReport Sniffer	on Binding	Group:					
(event):		_	Timeout:			Mi	n			
InfoReport		\boxtimes	Timeout.			IVII	11			
LTE-Mode-Se	ervice					_	_			
(polling):		_	Read Wildcard / Re	esp Sniffer	on Bindii	ng G	3roup:			
Read – Respo		Ш								
Value after Powerup: Default Value Stored Value										
Exception Handling: Save at Powerdown										
Special Featu	res:									
	y inpu	t on th	ne actuator can be o	verruled by	other in	puts	s. See pri	ority hand	ling in cla	ause
1.2.2.3	.2.2.3									
¹⁾ This input is	disab	led if t	he SAB is controlled	by a Contr	oller (⇒	see	e parame	ter Actuat	orMode)	

1.5.6 Input DedicatedStop

FB:	SAB	LTE-Mod	e Client Input Name	e: Dedi	catedSt	ор	Mai	ndatory [Option	ıal 🛛 1)
Desc	ription:									
of the	shutter /	sunblind.	ndicates the request							vement
			used instead of Sto							
			applications for realiz							
			on the reception of		input De	edicateds	stop :	shall com	iply with t	.ne
			scription as specified		4.047	Date	. 4	£ t		
DPT:	Name	DPT_Tri		DPT ID	1.017	Data	atype	format	B ₁	Datault
Field b			Description 0, 1: Requests to s	ton movem	ont			Sup. M	Unit	Default
	municatio	\n.	0, 1. Requests to s	top moveme	eni			IVI	<u> </u>	none
	Communication: Binding Group:									
	Class Type Default Geographical BuildingZone.Room.Subzone cs (see parameter BlindsGroup)									
	cation Sp		Building Zono. (Con	11.00020110		000)000	puic	intotor Bi	macorca	Ρ)
	signed		Broadcast	Configurab	le 🗌					
	\ddress:		IO Type(ID):	801 (SSSE		Proper	ty ID	:	63	
LTE-	Mode-Se	rvice	InfoReport Sniffer	on Binding	Group:		-	-		
(eve	nt): Report	\bowtie	Timeout:			Min				
	Mode-Se	rvice								
(poll	ing):		Read Wildcard / Re	esp Sniffer o	n Bindii	ng Group):			
Read	d – Respo	nse 🗌								
Value	Value after Powerup: Default Value □ Stored Value □									
Exception Handling: Save at Powerdown										
Spec	Special Features:									
	This low priority input on the actuator can be overruled by other inputs. See priority handling in clause									
1.2.2.										
¹⁾ This	s input is	disabled if t	he SAB is controlled	by a Contro	oller (⇒	see para	amet	er Actuat	orMode)	

1.5.7 Input SetAbsPosBlindsPercentage

FB:	SAB	LTE-Mod	le Client Input Name:		PosBlind	IsPerce	Mandatory	Optio	nal ⊠ ¹⁾	
<u> </u>				ntage						
	ription:									
			sPosBlindsPercentage							
			wards the target heigh	nt position	(%) betv	veen 0 %	(fully open) a	and 100 $^{\circ}$	% (fully	
	d). See F									
			B on the reception of d			tAbsPosE	BlindsPercen	tage sha	I comply	
with t	he actuat	tor state m	achine description as s	specified in	n [03].					
DPT:	Name	DPT_S		DPT ID	5.001	Data	type format	U ₈		
Field			Description				Sup.	Unit	Default	
Unsig	ned valu	е	Target height position	n of the su	ınblind in	percentag	ge M	%	none	
Comi	municati	on:	-				-			
Bind	Binding Group:									
Class	Class Type Default									
Geog	Geographical BuildingZone.Room.Subzone cs (see parameter BlindsGroup)									
Appli	cation Sp	pecific 🗌								
Unas	signed		Broadcast	Configura	ble 🗌					
DP A	ddress:		IO Type(ID):	801 (SSS		Propert	y ID:	65		
	Mode-Se	ervice	InfoReport Sniffer	on Binding	g Group:					
(eve	•		Timeout:			Min				
	Report	\boxtimes	Timeout.			IVIIII				
	Mode-Se	ervice								
(poll			Read Wildcard / Re	sp Sniffer	on Bindi	ng Group:				
	l – Respo									
Value	Value after Powerup: Default Value □ Stored Value □									
Exception Handling: Save at Powerdown										
Spec	ial Featu	res:								
		ty input on	the actuator can be ov	erruled by	other in	puts. See	priority hand	lling in cla	ause	
1.2.2.	-									
¹⁾ This	s input is	disabled i	the SAB is controlled	by a Cont	roller (⇒	see para	meter Actuat	orMode)		

1.5.8 Input SetAbsPosSlatsPercentage

FB:	Perce					sPosS ntage	lats-	Mai	ndatory [Optio	nal ⊠ ¹⁾
Desc	ription:			-				-			
			PosSlatsPercentage								SB to
		e slats towa	ards the target slats-a	angle po	sitio	n (%) k	etween	0 %	and 100 '	%.	
	igure 5.										
			on the reception of c				tAbsPos	Slats	Percenta	ige shall	comply
			chine description as								
DPT:	Name	DPT_Sc		DPT II)	5.001	Dat	atype	format	U ₈	
Field			Description		_	_			Sup.	Unit	Default
,	ned value		Target angle position	on of the	slat	s in pe	rcentage)	M	%	none
	Communication:										
	Binding Group:										
	Class Type Default										
	graphical		BuildingZone.Room	n.Subzoi	ne		cs (see	para	meter Bli	ndsGrou	p)
	ication Sp	ecific	_								
	ssigned		Broadcast	Configu							
	Address:		IO Type(ID):	801 (S			Prope	rty ID		66	
	·Mode-Se	rvice	InfoReport Sniffer	on Bind	ling (Group:		-	.=		
(eve	•	5 -7	Timeout:				Min				
	Report	🗵	111100011								
	·Mode-Se	rvice		0		<u> </u>	_				
	ing):		Read Wildcard / Re	esp Sniff	er or	n Bindir	ng Grou	p:			
	d – Respo		5 (1/)						-		
	Value after Powerup: Default Value Stored Value										
Exception Handling: Save at Powerdown											
•	Special Features:										
		y input on th	ne actuator can be ov	verruled	by c	ther in	outs. Se	e pric	rity hand	ling in cla	ause
1.2.2											
¹⁾ Thi	s input is	disabled if t	he SAB is controlled	by a Co	ntro	ler (⇒	see par	amet	er Actuate	orMode)	

1.5.9 Input GotoAbsPosition

FB: SAB	LTE-N	/lode	Client	Input Na	me:	Got	oAbs	Posi	tior	n M	landatory [Optio	nal ⊠¹)
Description:													
	n update of input GotoAbsPosition indicates the request from a Sunblind Sensor SSSB to start moving e blinds towards the absolute position specified by the combined command fields HeightPosition (%) and SlatsPosition (%). See Figure 5.												
and SlatsPositi	on (%)	. Se	e Figure	• 5.		•					_		, ,
Validity of the i													
The behaviour							inpu	t Go	toA	bsPosit	ion shall co	mply wit	h the
actuator state													
Field SlatsPosi		all be	e ignore	d if the ac	ctuato	or is only	able	to co	ontr	ol the h	eight positi	on (e.g. i	n case
of shutter contr				1.16.41									
Field HeightPo				ed if the a	actua	itor is oni	y abi	e to	con	itroi the	angle posit	tion of the	siats
(e.g. control of				D '('		DDT ID	0.46	2 000		Datat	(
DPT: Name	DPT	Co		Position		DPT ID	240	0.800)	Dataty	oe format	U ₈ U ₈ B ₈	
Field			Descri		:4:		1:				Sup.	Unit	Default
HeightPosition				height po						entage	M	%	none
SlatsPosition Attributes			Bit #	slats-ang	gie po	osition in	perce	entag	ge		M	%	none
- ValidHeightPo	20		0 Bit #	\/alidity/	of fiel	ld Height	Dooit	ion:			M		nono
- validheightei	JS		U			e of Heig			n ic	woid	IVI		none
				- true:		e of Heig							
- ValidSlatsPos			1			ld SlatsP			11 13	valiu	М		none
- valiusiaisrus	•		'	- false:		e of Slats			ie v	void	IVI		Hone
				- true:		e of Slats							
- reserved			2-7			shall be			13 V	and			
Communication	n.			10001700	2 0110	oriali bo	igiioi	<u> </u>					-
Binding Grou													
Class	.		Type						De	efault			
Geographical				gZone.R	oom.	Subzone					rameter Bl	indsGrou	(a)
Application Sp			Danan	ig=onon t	0011111	00020110				(000 pa			Ρ)
Unassigned			Broado	cast \square	С	Configura	ble [1					
DP Address:			IO Typ			301 (SSS			Р	roperty	ID:	67	
LTE-Mode-Se	rvice			port Snif				up:					
(event):									N 4:	_			
InfoReport		\boxtimes	Timeo	ut:					Mi	n			
LTE-Mode-Se	rvice												
(polling):			Read \	Wildcard /	/ Res	p Sniffer	on B	indir	ng C	Group:			
Read – Respo	nse [
Value after Po	werup:	•		Defau	ılt Va	lue 🗌					S	tored Val	ue 🗌
Exception Handling: Save at Powerdown													
	-												
	pecial Features:												
This low priority	y input	on th	ne actua	tor can be	e ove	erruled by	othe	er inp	outs	s. See p	riority hand	lling in cla	ause
1.2.2.3													
1) This input is	<u>disabl</u> e	d if th	he SAB	is control	lled b	y a Cont	<u>rolle</u> r	(⇒	see	e param	eter Actuat	orMode)	
			· · · · · · · · · · · · · · · · · · ·										

1.5.10 Input ControlModeUser

FB:	SAB	LTE-Mode	e Client Input Name	e: Con	trolMode	eUser	Mandatory	/ 🗌 Opti	onal 🛚
Desc	ription:			-			-		
			ModeUser indicates	the reques	t from a	Sunblind	Sensor SSS	B to requ	est
			ol of the sunblinds						
DPT:	Name	DPT_BI	indsControlMode	DPT ID	20.804	Data	type format	N ₈	
Field			Description				Sup.	Unit	Default
Contr	olMode		This field shall indi				ol M		CS
			(0) or manual conti						
			values 2 to 255 are	e reserved t	or future	extensio	ns		
	municatio								
	ling Grou	ıp:	T =			D. (- 1)			
Class Type Default Geographical BuildingZone.Room.Subzone cs (see parameter BlindsGroup)									
								p)	
	Application Specific Unassigned Broadcast Configurable								
	Address:		IO Type(ID):	801 (SSSI		Propert	v ID:	64	
	-Mode-Se	rvice	InfoReport Sniffer		,	Flopen	.y ID.	04	
(eve		VICC		on binding	Отоир.				
•	Report	\boxtimes	Timeout:			Min			
LTE	-Mode-Se								
(poll	ing):		Read Wildcard / Ro	esp Sniffer o	on Bindii	ng Group	:		
Read	d – Respo	nse 🗌							
Value	after Po	werup:	Default \	/alue 🛚			Sto	red Value	
Exce	ption Har	ndling:					Save at Po	owerdown	⊠ ²⁾
Spec	Special Features:								
1) Usu	ıally this ir	nput may o	nly implemented in a	Controller	which er	mulates a	SAB actuat	or proxy,	see
comn	nents in cl	ause 1.2.2.	2						
			SAB is controlled b						
	Initialization of this input after power return is implementation specific. Persistent storage is an optional								
featu		-	*	-	•				

1.5.11 Input NumberedSceneControl

FB:	SAB	LTE-Mod	e Client Input Name	1	Num Cont	beredSo trol	cene-	Man	datory [Optio	nal 🛚
Desc	ription:							-			
The in	nput Num	beredScen	eControl indicates th	e requ	ıest fr	om a Sc	ene Se	nsor SC	CS or fro	m a Sce	ne
			er to recall or learn a							number (0 to 63).
The n	naximum	scene num	ber that is supported	by th	e actu	uator is c	compan	y specit	ic.		
DPT:	Name	DPT_S	ceneControl	DPT	「ID	18.001	Da	tatype f	ormat	B ₁ r ₁ U ₆	
Field			Description						Sup.	Unit	Default
С			Control information	to en	code	recall/le	arning o	of the	M	-	-
			scene control infor								
			0: recall the scene			ling					
			to the field Scer								
	1: teach-in the scene corresponding										
	to the field SceneNumber										
Scen	SceneNumber Selects the number of the scene to be controlled M								-		
	(063)										
	munication										
	ling Grou	ıp:									
Clas			Туре				Defau				
	graphical		BuildingZone.Roon	n.Sub	zone		cs (se	e paran	neter Sc	eneGrou	ıp)
	ication Sp	ecific									
	ssigned		Broadcast	Confi							
	Address:		IO Type(ID):		SCS)		Prop	erty ID:	!	51	
	-Mode-Se	rvice	InfoReport Sniffer	on Bi	nding	Group:					
(eve		_	Timeout:				Min				
	Report		Tillioodt.								
	Mode-Se	ervice		_			_				
	ing):		Read Wildcard / Re	esp Sr	niffer	on Bindii	ng Grou	ıb:			
	Read – Response										
	Value after Powerup: Default Value Stored Value										
	ption Hai									erdown	
			rt less than the maxi					. If a sco	ene is ca	alled/lear	ned with
			t supported, then the	devic	e sha	all not re	act.				
	Special Features:										
		y input on t	he actuator can be o	verrule	ed by	other in	puts. S	ee priori	ity hand	ling in cla	ause
1.2.2.	nis low priority input on the actuator can be overruled by other inputs. See priority handling in clause 2.2.3										

1.5.12 Input WindAlarm

FB:	SAB	LTE-Mode	Client Input Nam	e: Wind	dAlarm		Mai	ndatory [Opti	onal 🛚
Desc	dication from a Wind Sensor to move the sunblind to a secure position in case of strong wind and to book it for any further control. The secure position can be controlled by an additional parameter									
										and to
			rol. The secure pos	sition can be	controll	ed by ar	n addi	tional pai	ameter	
	tionWind <i>P</i>						_			
			r control command							
	_		Il be cleared if the r							
DPT:	Name	DPT_Ala		DPT ID	1.005	Dat	tatype	format	B ₁	D : (- 1)
Field			Description		41 :			Sup.	Unit	Default
b			This field shall ind 'alarm' (1) or 'no a		er there i	s a wind	ו	М		cs ²⁾
Comi	munication	n.	alaini (1) or no a	ilaiiii (0)						
	ing Grou									
	Class Type Default									
Geog	Geographical									
	Application Specific ☐ OutsideSensorZone cs									
Unas	Unassigned									
	Address:		IO Type(ID):	802 (WS)		Prope	rty ID	:	51	
	Mode-Se	rvice	InfoReport Sniffer	r on Binding	Group:		-	· -		
(eve	•		Timeout: 1)		21	Min				
	Report		Timoodt.							
	Mode-Se	rvice				_				
(poll		5 7 2)	Read Wildcard / R	Resp Sniffer o	on Bindi	ng Grou	p:			
	d – Respo							-		
	after Po	•	Default Va	alue 🗌 ²⁾			_		tored Va	
	ption Har							e at Pow		
			es, the actuator sha	all react in th	e same	way as	if Win	dAlarm =	: 'alarm'	•
-	ial Featu									
	This medium priority input on the actuator can be overruled by high priority inputs. See priority handling in									
	clause 1.2.2.3 Timeout is either fixed or defined by parameter TimeoutWindAlarm									
2) — :	eout is ei	tner fixed oi	r defined by parame	eter I imeout	vvindAla	ırm				
-, The	internal v	wind alarm :	state after power re	turn is manu	ıtacturer	specific	. The	actuator	may be	•
	locked until an update of the sensor value = 'no alarm' is received. The actuator may actively read WindAlarm from the remote sensor to shorten the latency caused by the heartbeat period of the									
			note sensor to short	ten the laten	cy cause	ed by the	e hea	rtbeat pe	riod of th	ne
pro	cess sign	idi								

1.5.13 Input FrostAlarm

FB: SAB LTE-	Mode	Client Input Name	e: Fro	stAlarm		Ma	indatory [Opti	onal 🛚
Description:						-			
Indication from a Fro									
any further control. T								actionFi	ostAlarm.
During frost alarm, al									
The frost alarm statu					alue			1	
	T_Ala		DPT ID	1.005		Datatyp	e format	B ₁	
Field		Description					Sup.	Unit	Default
b		This field shall ind		er there i	s a	frost	M		cs ²⁾
		'alarm' (1) or 'no a	ılarm' (0)				<u> </u>	<u> </u>	
Communication:									
Binding Group:									
Class		Туре			De	fault			
Geographical		0.1.1.0							
Application Specific		OutsideSensorZor			CS				
Unassigned Broadcast Configurable Property ID: 51									
DP Address: IO Type(ID): 804 (FS) Property ID: 51 LTE-Mode-Service InfoReport Sniffer on Binding Group:									
LTE-Mode-Service		,	r on Binding	g Group:					
(event): InfoReport	\boxtimes	Timeout: 1)		21	Mi	n			
LTE-Mode-Service									
(polling):		Read Wildcard / R	een Sniffer	on Rindi	na C	Proup.			
Read – Response	₫ 2)	rtead Wildcard / It	cop offilier	on bindi	iig C	Jioup.			
Value after Poweru		Default Va	alue 🔲 2)				S	tored Va	alue 🗌
Exception Handling] :					Sa	ve at Pow	erdown	
If the receive timeout	expir	es, the actuator sha	all react in th	ne same	way	as if Fro	stAlarm =	: 'alarm'	
Special Features:	•								
This medium priority input on the actuator can be overruled by high priority inputs. See priority handling in									
clause 1.2.2.3									
1) Timeout is either fix	xed or	defined by parame	eter Timeou	tFrostAla	ırm				
2) The internal frost a	larm s	state after power ret	turn is manı	ufacturer	spe	cific. The	actuator	may be	
locked until an upo	date o	f the sensor value =	= 'no alarm'	is receive	ed. ˈ	The actu	ator may a	actively	read
FrostAlarm from the remote sensor to shorten the latency caused by the heartbeat period of the									
process signal									

1.5.14 Input RainAlarm

FB: SAB LTE-	Mode	Client Input Nam	e: Rair	nAlarm		Ма	ndatory [Opti	onal 🛚
Description:			-			5			
Indication from a Rain									d to block
it for any further conti	rol. Ti	he secure position (can be contro	olled by	an add	itional	paramete	er	
ReactionRainAlarm.									
During rain alarm, all									
The rain alarm status				•					
	T_Ala		DPT ID	1.005	Da	atatype	format	B ₁	
Field		Description					Sup.	Unit	Default
b		This field shall ind		er there i	is a rair	า	М		cs 2)
		'alarm' (1) or 'no a	alarm' (0)						
Communication:									
Binding Group:									
Class Type Default									
Geographical Out it is a second of the secon									
Application Specific OutsideSensorZone cs									
Unassigned Broadcast Configurable									
DP Address:		IO Type(ID):	803 (RS)			erty ID	:	51	
LTE-Mode-Service		InfoReport Sniffe	r on Binding	Group:			-		
(event):		Timeout: 1)		21	Min				
InfoReport LTE-Mode-Service									
		Deed Wilderd / F) O - :#	an Dia di	0				
(polling):	7 2)	Read Wildcard / F	kesp Sniffer (on Bindi	ng Gro	up:			
Read – Response 🗵	7		alua 🗆 2)						
Value after Powerup		Default Va	alue 🔲 🛂					ored Va	
Exception Handling							e at Pow		
If the receive timeout	expir	es, the actuator sh	all react in th	e same	way as	if Rai	nAlarm =	'alarm'.	
Special Features:									
This medium priority input on the actuator can be overruled by high priority inputs. See priority handling in									
clause 1.2.2.3									
	Timeout is either fixed or defined by parameter TimeoutRainAlarm The internal rain alarm state after power return is manufacturer specific. The actuator may be								
locked until an update of the sensor value = 'no alarm' is received. The actuator may actively read									
	e rem	ote sensor to short	en the latend	cy cause	ed by th	e hear	tbeat per	iod of th	ie
process signal									

1.5.15 Input MoveUpDownCmd

FB: SAB	L	TE-Mod	de Server Input Na	me: Mo	veUpDo	wnCmd	Man	datory [⊠ ¹⁾ Opti	onal 🗌
Description	1:			-			-			
The input Mo	ovel	lpDown(Cmd is written by a	Controller to t	rigger u	o (=0) or	down	(=1) mo	vement o	of the
sunblind.										
			3 on the reception o							
for input Mov	veUp	Down a	nd shall comply witl	<u>h the actuator</u>	state m	achine de	escript	tion as s	specified	in [03].
DPT : Nar	me	DPT_L	JpDown	DPT ID	1.008	Data	type f	ormat	B ₁	
Field			Description					Sup.	Unit	Default
b			This field indicate					M		none
			direction of the s	unblind up (0)	or dow	n (1)				
Communica	ation	:								
Binding Group:										
Class Type Default										
Geographical BuildingZone.Room.Subzone cs (see parameter BlindsGroup)										
	Application Specific									
Unassigned			Broadcast	Configurat						
DP Address	s:		IO Type(ID):	800 (SAB)	Proper	ty ID:		61	
LTE-Mode-	Serv	ice								
(event):		_	Timeout:			Min				
Write										
Property-Se			Read only		Read/W	Vrite	\boxtimes			
(individual			,	<u> </u>	11000,1					
Value after			Defaul	t Value 🗌				St	ored Val	ue 🔃
Exception F		<u></u>							ver-down	
			ctionality of a trigge							
			alue of this property		n updat	e of this i	nput a	t runtim	ie by a re	mote
Controller triggers movement of the actuator.										
Special Features:										
			ed by high priority in	nputs MoveUp	DownF	orced or I	LockD	evice. S	See priori	ty
handling in o										
	If the SAB is directly connected to sensor FB SSSB, MoveUpDownCmd input is disabled. The									
behaviour is	cont	rolled by	/ configuration para	meter Actuate	orMode.					

1.5.16 Input StopStepUpDownCmd

FB:	SAB	LTE-Mode	e Server Input Nam	ne:	Stop	StepUp I	Down-	Man	datory [⊠ ¹⁾ Opti	onal 🗌		
Desc	ription:							-					
			vnCmd is written by										
			viour of the SAB on										
			put StopStepUpDov	wn and	shall	comply	with th	ne actuat	tor state	machine)		
		specified in											
DPT:	Name	DPT_St		DPT	ĪD	1.007	D	atatype f		B ₁			
Field			Description						Sup.	Unit	Default		
b			This field indicates	a requ	uest to	o perforr	m a gr	adual	М		none		
			movement										
			0: step up or stop										
			1: step down or st	юр									
	Communication:												
Bind	Binding Group:												
	Class Type Default												
	graphical		BuildingZone.Roo	m.Sub	zone		cs (s	ee paran	neter Bli	ndsGrou	p)		
	ication Sp	ecific											
	ssigned		Broadcast	Confi									
	Address:		IO Type(ID):	800	(SAB)	1	Prop	perty ID:		62			
	Mode-Se	rvice											
(eve	•	_	Timeout:				Min						
Write													
	erty-Serv vidual ac		Read only]		Read/W	/rite	\boxtimes					
•	e after Po		Default '	Value [St	ored Val	ue 🗌		
	ption Har	.						Save	e at Pov	ver-down			
This	property h	as the func	tionality of a trigger	input, i	.e. af	er powe	er-retu	rn or a re	start of	the appli	cation		
			lue of this property										
			top or a step.	Ü				•		•			
	ial Featu		•										
This i	nput can	be overrule	d by high priority inp	uts Mo	veUp	DownFo	orced	or LockD	evice. S	See priori	ty		
handl	ling in clau	use 1.2.3.3									•		
1) If th	ie SAB is	directly con	nected to sensor Fl	SSSE	3, Sto	pStepU	pDowr	Cmd inp	out is dis	abled. T	he		
behav	viour is co	ntrolled by	configuration param	eter A	ctuato	rMode.	•	•					

1.5.17 Input DedicatedStopCmd

FB:	SAB	L	LTE-Mode Server Input Name: DedicatedStopCmd Mandatory □ Optional □ 1)										
Desc	ription:												
					Cmd is written by a								
					the reception of da								
	_	_	_		shall comply with	the acti	uator st	ate macl	hine	descripti	on as spe	ecified in	[03].
DPT:	Name)	DF	<u>'T_T</u>	rigger	D	PT ID	1.017		Datatype	format	B ₁	
Field					Description						Sup.	Unit	Default
b					0, 1: Requests t	o stop	movem	ent			M		none
Com	municatio	on	:		_								-
Bind	Binding Group:												
Class	Class Type Default												
	Geographical BuildingZone.Room.Subzone cs (see parameter BlindsGroup)												
Appli	Application Specific												
Unas	Unassigned Broadcast Configurable												
	\ddress:				IO Type(ID):	80	0 (SAB)	Р	roperty ID	:	63	
	Mode-Se	rv	ice										
(eve	•			_	Timeout:				Mi	n			
Write				\boxtimes									
	erty-Serv				Read only			Read/W	/rite				
	vidual ac												
	after Po				Defau	lt Valu	e 🔲				S	tored Val	ue 🔃
	ption Har											ver-down	
					ctionality of a trigg								
					alue of this propert	y is igr	nored. A	n update	e of	this input	at runtin	ne by a re	mote
Contr	oller trigg	ers	sa	stop	<u> </u>								
_	ial Featui												
					ed by high priority	inputs I	MoveUp	DownFo	orce	ed or Lock	Device.	See priori	ty
	ing in clau												
					nnected to sensor					Cmd inpu	t is disab	led. The	
beha	viour is co	ont	rolle	ed b∮	y configuration para	ameter	Actuate	orMode.					

1.5.18 Input LockDevice

FB:	SAB	L٦	ГЕ-Мос	e Server Input Nar	ne:	Lock	Device		Ma	andatory	Opti	onal 🛚	
Desc	ription:	=				<u>-</u>			<u>-</u>				
Input	to freeze	the	actual	setpoint of the actua	ator	e.g. by a	Control	ler o	or by a Bu	ilding Ma	ınagemer	nt	
				viour related to lock									
additi	onal para	me	ters Be	naviourAtLocking / L	_ocl	kSetvalue	and Bel	hav	iourAtUnk	ocking / l	JnlockSet 4 6 1	tvalue	
DPT:	Name)	DPT_E	nable		DPT ID	1.003		Datatype	format	B ₁		
Field				Description						Sup.	Unit	Default	
b				1: shall lock the a	ctua	ator on its	current	sta	te	М		CS	
				0: shall unlock the	e ac	ctuator							
Comi	nunicati	on:											
Bind	ding Gro	up:											
Clas	Class Type Default Geographical ☒ BuildingZone.Room.Subzone cs (see parameter BlindsGroup)												
Geo	graphical		\boxtimes	BuildingZone.Roo	m.S	Subzone		CS	(see para	meter Bl	indsGrou	p)	
App	Application Specific												
Una	ssigned			Broadcast	С	Configurat	ole 🗌						
DP A	Address:	:		IO Type(ID):	8	300 (SAB)	Р	roperty ID	:	69		
LTE	-Mode-S	ervi	ice										
(eve	ent):			Timeout:				Mi	n				
Write	<u> </u>		\boxtimes										
	perty-Ser			Read only	7		Read/W	/rite					
	ividual a			rtcad offig			rtcau, vi	viite	, 🖂				
Value	after Po	we	r-up:	Default	Va	lue 🗌				S	tored Val	ue 🗌	
Exce	ption Ha	ndli	ing:						Sa	ave at Po	wer-dowr	<u> </u>	
				urn: either persister								default	
value	is allowe	d. T	The me	chanism is product s	spec	cific and r	nay be d	lefir	ned by par	ameters			
				the default value is	se	t to unloc	ked (0)						
•	ial Featu												
This h	nigh priori	ity ir	nput on	the actuator can ov	erru	ule other l	lower pri	ority	y inputs. S	ee priori	ty handlin	ig in	
claus	e 1.2.2.3	and	1.2.3.3	3									

1.5.19 Input MoveUpDownForced

FB:	SAB	LTE-Mode	Server Input Na	me: Move	UpDowr	Forced	Mano	datory [Optio	nal 🛚				
Descri						-								
			md is written by a		y a BMS	S to move	the s	unblind	to a forc	ed up or				
			t it for any further o											
			ed if the value '00b			and the s	unblin	id actua	ator can b	e				
			ts of low and medi											
			on the reception o			veUpDov	wnFor	ced sha	all comply	/ with				
	_		description as spe											
DPT:	Name	DPT_Di	rection1_Control	DPT ID	2.008	Data	type fo		B ₁					
Field			Description					Sup.	Unit	Default				
С			0: MoveUpDown					М		cs				
			Lower priority in											
	1: MoveUpDownForced is active. Forced up/down movement according v field													
	Forced up/down movement according v field													
	Lower priority inputs are overruled.													
V														
	If c=1:													
			- v=0: forced-mov											
			- v=1: forced-mov	ve down			<u> </u>							
	nunicatio													
	ng Grou	p:				D. (- 1)								
Class		<u> </u>	Type	0		Default		- (D)	1.0	- \				
	aphical		BuildingZone.Ro	om.Subzone		cs (see	param	eter Bi	indsGrou	p)				
	ation Sp	ecific	D	0 - 6	. 🗆									
Unass			Broadcast (ID)	Configurat		ъ .			0.5					
	dress:		IO Type(ID):	800 (SAB)	Propert	y ID:		65					
	/lode-Se	rvice	T '			N 42 -								
(even	t):	∇	Timeout:			Min								
Write	erty-Serv	wiese 🔲												
	idual ac		Read only		Read/W	/rite	\boxtimes							
		wer-up:	Default	Value 🗌				St	ored Val	ue 🗌				
Excep	tion Har	ndling:					Save	at Pov	ver-down					
			ırn: either persiste	nt storage of	MoveUpl	DownFor								
	Behaviour after power-return: either persistent storage of MoveUpDownForced value or initialization with a default value is allowed. The mechanism is product specific and may be defined by parameters.													
	al Featu													
			he actuator can ov	errule other	ower pri	ority input	ts. Se	e priorit	y handlin	ig in				
clause	1.2.2.3	and 1.2.3.3												

1.5.20 Input AbsHeightPositionSetp

FB:	SAB	LT	E-Mod	e Server Input Nar	ne:	AbsHe Setp	ightPosi	tion-	Man	datory [Option	nal 🛚 1)
Desc	ription:											
The in	nput Absh	Heig	htPosit	ionSetp is written by	y a C	ontrolle	or to co	ontrol the	Heigh	tPositio	n (%) of	the
				lly open) and 100 %								
				on the reception of								
			lindsPe	rcentage and shall	comp	oly with t	he actua	ator state	mach	ine des	cription a	IS
	fied in [03	_									r	
DPT:	Name	}	DPT_S		D	PT ID	5.001	Data	atype f		U ₈	
Field				Description						Sup.	Unit	Default
	ned value			Target height pos	ition	of the s	unblind i	n percen	tage	M	%	none
	munication											
Binding Group:												
Class Type Default												
	graphical			BuildingZone.Roo	m.S	ubzone		cs (see	paran	neter Bl	indsGrou	p)
	cation Sp	ecif	ic 📙									
	signed			Broadcast		onfigurat						
	ddress:			IO Type(ID):	80	00 (SAB)	Proper	ty ID:		66	
	Mode-Se	rvic	e									
(eve	•			Timeout:				Min				
Write												
	erty-Serv vidual ac			Read only			Read/W	Vrite				
Value	after Po	we	r-up:	Default	Valu	ıe 🗌				St	tored Val	ue 🗌
Exce	ption Har	ndli	ng:						Save	at Pov	ver-down	
After	power-ret	urn	or a re	start of the applicati	on p	rogram t	he local	initial va	lue of	this pro	perty is ig	gnored.
An up	date of th	nis ii	nput at	runtime by a remote	e Coi	ntroller t	riggers n	novemen	t to the	e target	position.	i
Spec	ial Featui	res:										
This i	nput can l	be o	overrule	ed by high priority in	puts	MoveUp	DownFo	orced or	LockD	evice. S	See priori	ty
	ing in clau											
1) If th	e SAB is	dire	ctly co	nnected to sensor F	BSS	SSB, Ab	sHeightF	PositionS	etp inp	out is di	sabled. T	he
behav	viour is co	ontro	olled by	configuration parar	nete	r Actuate	orMode					

1.5.21 Input AbsSlatsPositionSetp

FB:	SAB	LTI	E-Mo	de	Server Input Nam	e: Al	osSl	atsPositi	onSetp	Man	datory [Option	nal 🛚 1)
Descri	iption:					-				-			
				itio	nSetp is written by	a Conti	olle	or to co	ntrol th	ne angle	positio	า (%) of	the
	See Figu												
					on the reception of								
•			atsPe	rce	entage and shall co	mply wi	th th	e actuat	or state	e machii	ne desc	ription as	;
	<u>ed in [03</u>												
DPT:	Name		PT_S			DPT	ID	5.001	Da	atatype f		U ₈	
Field					Description						Sup.	Unit	Default
	ned value				Target angle posit	ion of th	e sla	ats in pe	rcentaç	ge	M	%	none
	unicatio												
Binding Group: Class Default													
Class Type Default													
	Geographical BuildingZone.Room.Subzone cs (see parameter BlindsGroup)												
	ation Sp	ecifi	<u>с Ц</u>										
Unass				_	Broadcast	Config							
	dress:				IO Type(ID):	800 (SAB)	Prop	erty ID:		67	
	lode-Se	rvic	е										
(event	t):		<u> </u>		Timeout:				Min				
Write													
•	rty-Serv				Read only	1		Read/W	/rite	\boxtimes			
_	idual ac					·							
	after Po				Default \	√alue <u></u>				T _		tored Val	
	tion Har											ver-down	
					art of the application								
		nis in	put a	t ru	intime by a remote	Control	ller ti	riggers n	novem	ent of th	e slats t	o the tar	get
positio													
	al Featur				1 1 1 1 1 1 1 1 1			<u> </u>					
					by high priority inp	outs Mov	veUp	DOWNF	orced c	or LockD	evice. S	see priori	ty
	ng in clau					0000	Λ.	- Ol-4- D :	:4:	Na. 4	.4 !a al! - :		_
If the	SAB IS	aire	Ctly Co	onn	ected to sensor FE	3 333B	, Abs	sSiatsPc	sitions	etp inpu	it is aisa	ablea. Th	е
benavi	our is co	ntro	nea b	ус	onfiguration param	ieter AC	เนสเ	ועוטמפ					

1.5.22 Input AbsPositionSetp

FB: SAB	LTE-Mc	ode	Serve	r Input Na	me: A	bsPosition	Setp	Man	datory [Option	nal 🖂 '′		
Description:								-					
The input AbsP specified by the Validity of the creception of dat with the actuator Field SlatsPosit of shutter control Field HeightPosit (e.g. control of Validity Processing Control of Validity Processing Pro	The input AbsPositionSetp is written by a Controller to start moving the blinds towards the position specified by the combined command fields HeightPosition(%) and SlatsPosition(%). See Figure 5. Validity of the command fields is indicated by 2 additional attributes. The behaviour of the SAB on the reception of data on the input AbsPositionSetp is the same as for input GotoAbsPosition and shall comply with the actuator state machine description as specified in [03]. Field SlatsPosition shall be ignored if the actuator is only able to control the height position (e.g. in case of shutter control). Field HeightPosition shall be ignored if the actuator is only able to control the angle position of the slats (e.g. control of vertical sunblinds). DPT: Name DPT_CombinedPosition DPT ID 240.800 Datatype format U8U8B8 Field Description Sup. Unit Default HeightPosition Target height position of the blinds in percentage M % none												
	DF I_				וואטן	D 240.00	Date	atype i					
HeightPosition					sition of th	e blinds in r	percentac	ne er	M	%	none		
SlatsPosition						in percenta		J O	M	%	none		
Attributes			Bit #	olato arigi	io pooition	прогостко	igo		141	70	110110		
- ValidHeightPos 0 Validity of field HeightPosition: M none - false: value of HeightPosition is void - true: value of HeightPosition is valid													
ValidSlatsPos 1 Validity of field SlatsPosition: - false: value of SlatsPosition is void - true: value of SlatsPosition is valid reserved 2-7 reserved bits shall be ignored													
			2-1	reserved	DILS SHAIL	be ignored					<u> </u>		
Communication Binding Group													
Class	J	1	Туре				Default						
Geographical	\triangleright	1		gZone.Ro	om Subzo	ne			neter Bli	indsGrou	n)		
Application Spe		<u> </u> 	Dallall	igzonc.rto	0111.00020	110	03 (300	paran	icter Di	ilasoloa	Ρ)		
Unassigned		1	Broado	cast 🗆	Configu	ırable 🗍							
DP Address:			IO Typ		800 (S		Proper	tv ID:		68			
LTE-Mode-Ser	vice		, , ,		333 (3	,,	1 1000	·, · ·					
(event): Write			Timeo	ut:			Min						
Property-Serv (individual acc			Read	only		Read/V	Vrite						
Value after Pov				Defaul	t Value 🗌				St	tored Val	ue 🗌		
Exception Han										ver-down			
After power-return An update of the position.	urn or a i	res at r	tart of thuntime	ne applicat by a remot	tion progra te Controll	im the local er triggers r	initial va novemer	lue of nt of th	this pro e sunbli	perty is ig ind to the	nored. target		
Special Featur													
This input can be handling in clau 1) If the SAB is costrolled by	ise 1.2.3 directly c	.3 on	nected	to sensor l	· FB SSSB,	AbsPosition				·			

1.5.23 Parameter-set BlindsGroup

BlindsGroup is implemented using the LTE-Mode Geographical zone concept. It consists of 3 properties belonging together.

1.5.23.1 Parameter BuildingZone

FB: SA	\B P	roperty N	lame (<u>Server</u>):	В	lindsGroup	.Building	Zon	ne	Mandatory	/ 🛛 Opti	onal 🗌
Descripti	ion:										
			neter set mapped			Geograp	hic	al zo	ne:		
-> Buildin	gEntity		oartment, Buildin	g se							
	Name	DPT_Uc	ountValue8_Z		DPT ID	202.002			atype format	U_8Z_8	
Field			Description				Sı	up.	Range	Unit	Default
CounterV	/alue		Number of the	Build	dingZone		N	M	1 to 126		CS
Status										bitset	
- OutOfSe			zone active /ina		~		(0	true/false		cs
- all other	flags		not supported,		Ν	ΙA					
Command	-							enum			
- NormalV							-	M			
- SetOSV			set zone inactiv	/e / a	active			0			
- all other			not supported				N	ΙA			
Commun		1:									
DP Add			IO Type(ID):	80	00 (SAB)				ty ID:	101	
(in the s			Start-Index:	1			N	° of e	elements	1	
Propert		ss:	Read only			Read/W	/rite)	\boxtimes		
Protect	ion		Read level				W	rite I	evel		
Exception Handling: Value after Powerup: Stored Value ☐ Act Value ☐ Default Value ☐											
Special F	eature	s:									
			except Numbere								
			er BuildingZone		OutOfServio	ce' also th	ne c	corre	sponding Ro	om and Su	ıbzone
paramete	ers are '	OutOfSer	vice' (common fl	ag)							

1.5.23.2 Parameter Room

FB:	SAB	Property	Name (Serve	<u>r</u>): Bl	lindsGroup	.Room			Mandatory	y 🛛 Optic	onal 🗌
Desc	ription:										
			ameter set map	ped to	LTE-Mode	Geograp	hical	zor	ne:		
-> Ro	om withi	n BuildingZ	<u>Zone</u>								
DPT:	Name	e DPT_L	JcountValue8_	Z	DPT ID	202.002	2 [Data	atype format	U ₈ Z ₈	
Field			Description				Su	p.	Range	Unit	Default
Count	terValue		Room numb	er			М	1	1 to 63		CS
Status	3									bitset	
	OfService		zone active /				0)	true/false		CS
- all o	ther flags	8	not supporte		N/	4					
Comn	nand									enum	
- Norr	nalWrite						M	1			
- SetC)SV & R	esetOSV	set zone ina	ctive / a	ctive		0)			
- all o	ther com	mands	not supporte	d			N/	4			
Comr	nunicati	on:									
DP .	Address	: :	IO Type(ID):	800 (SAB	5)	Pro	oper	ty ID:	102	
(in t	he serve	er)	Start-Index		1		N°	of e	lements	1	
Pro	perty ac	cess:	Read only			Read/W	rite'		\boxtimes		
Prof	tection		Read level				Wr	ite l	evel		
Exce	otion Ha	ndling:	Value after P	owerup:	Stored	Value 🛚	Act	Val	ue 🗌 🛮 Def	fault Value	
-											
Speci	ial Featu	ıres:									
SAB r	untime [Datapoints	(except Numb	eredSce	eneControl) are not	LTE-	-Mo	de communi	cating if zo	ne is
'OutO	fService	'. If parame	eter BuildingZo	ne is 'C	OutOfService	e' also th	ie co	rres	ponding Ro	om and Su	ıbzone
paran	neters ar	e 'OutOfSe	ervice' (commo	n flag)							

1.5.23.3 Parameter Subzone

FB:	SAB	Property	Name (<u>Server</u>):	Bli	indsGroup.	Subzone)		Mandator	y 🛛 Opti	ional 🗌
Desc	ription:								-		
			meter set mapped	to L	_TE-Mode	Geograp	hic	al zo	ne:		
-> Su	bzone w	ithin Buildin	igZone.Room								
DPT:	Name	DPT_U	countValue8_Z		DPT ID	202.002	2	Dat	atype format	U_8Z_8	
Field			Description				S	up.	Range	Unit	Default
Coun	terValue		Subzone number	r				M	1 to 15		CS
Statu	S									bitset	
	OfService		zone active /inact					0	true/false		CS
- all o	ther flags	3	not supported, fix	ced	to '0'		١	۱A			
	mand									enum	
	malWrite							M			
		esetOSV	set zone inactive	/ a	ctive			0			
	ther com		not supported					۱A			
	municati		_								
	Address	· -	IO Type(ID):		800 (SAB)			rty ID:	103	
(in	the serve	er)	Start-Index:		1		Ν	l° of	elements	1	
	perty ac	cess:	Read only			Read/W	rite)	\boxtimes		
Pro	tection		Read level				٧	Vrite	level		
Exce	ption Ha	ndling:	up:	Stored \	√alue 🛚	A	ct Va	lue 🗌 De	fault Value	e 🗌	
Spec	ial Featu	ires:									
SAB	runtime [Datapoints ((except Numbered	Sce	neControl)	are not	LTI	E-Mc	de commun	icating if z	one is
'OutC)fService	'. If parame	eter BuildingZone is	s 'O	utOfServic	e' also th	e c	corre	sponding Ro	om and Si	ubzone
parar	neters ar	e 'OutOfSe	rvice' (common fla	a)							

1.5.24 Parameter-set SceneGroup

SceneGroup is implemented using the LTE-Mode Geographical zone concept. It consists of 3 properties belonging together.

1.5.24.1 Parameter BuildingZone

FB:	SAB	Property	Name (<u>Server</u>):	Sc	eneGroup.	.Building2	Zon	e	Mandatory	<u>/ 🔲 </u>	Optio	onal 🖂
Desc	ription:											
			meter set mapped			Geograp	hic	al zo	ne:			
-> Bu	ildingEnt	ity (Floor, A	Apartment, Building	se	ction etc.)							
DPT:	Name	DPT_U	countValue8_Z		DPT ID	202.002	2	Data	atype format	U	J_8Z_8	
Field			Description				S	up.	Range	Un	it	Default
Coun	terValue		Number of the Bu	ıildi	ngZone			M	1 to 126			CS
Statu	S									bits	set	
- Out	OfServic	е	zone active /inact	ive			(0	true/false			CS
- all o	ther flag	S	not supported, fix	ed	to '0'		N	ΙA				
Comr							eni	um				
	malWrite						ı	M				
		esetOSV	set zone inactive	/ac	ctive			0				
- all o	ther com	mands	not supported				N	IA.				
Com	municati	ion:										
DP	Address	::	IO Type(ID):		800 (SAB))			rty ID:	104	ļ	
(in t	the serv	er)	Start-Index:		1		Ν	° of e	elements	1		
Pro	perty ac	cess:	Read only			Read/W	rite	!	\boxtimes			
Pro	tection		Read level				W	/rite l	evel			
Exception Handling: Value after Powerup: Stored Value								t Va	lue 🗌 Def	ault	Value	
Spec	ial Featu	ıres:										
SAB	runtime [Datapoint N	umberedSceneCo	ntro	ol is not LTI	E-Mode c	om	mun	icating if zon	e is		
'OutC)fService	'. If parame	ter BuildingZone is	G,	utOfServic	e' also th	ес	orres	sponding Roo	om a	nd Su	bzone
paran	neters ar	e 'OutOfSe	rvice' (common flag	g)								

1.5.24.2 Parameter Room

FB:	SAB	Property	Name (Server): SceneGroup.Room Mandatory ☐ Optional ☐										
Descri	ption:												
		Group para	λM	neter set mapped to	Ľ	TE-Mode	Geograp	ohic	al zo	one: -> Room	within		
Building	gZone												
DPT:	Name	DPT_L	Jc	ountValue8_Z		DPT ID	202.00	2	Dat	atype format	U_8Z_8		
Field				Description				S	up.	Range	Unit		Default
Counte	rValue			Room number					М	1 to 63			CS
Status											bitset		
- OutO	fService)		zone active /inactive	,				0	true/false			CS
- all oth	er flags	;		not supported, fixed	to	o '0'		1	NΑ				
Comma	and										enum		
- Norm	alWrite								M				
- SetOS	SV & Re	esetOSV	1	set zone inactive / ad	ct	tive			0				
- all oth	er com	mands	L	not supported				1	NΑ				
Comm	unicati	on:								-		_	
DP A	ddress	:		IO Type(ID):		800 (SAB))	Р	rope	rty ID:	105		
(in th	e serve	er)		Start-Index:		1		Ν	l° of	elements	1		
Prop	erty acc	cess:		Read only			Read/V	√rite)	\boxtimes			
Prote	ection			Read level				٧	Vrite	level			
Except	tion Ha	ndling:	١	/alue after Powerup:	:	Stored \	/alue 🛚	Α	ct Va	lue 🔲 🏻 De	fault Val	ue [
Specia	I Featu	res:											
SAB ru	ntime D	atapoint N	۱u	mberedSceneContro	ol	I is not LTI	E-Mode	con	nmur	nicating if zor	ne is		
'OutOf	Service'	. If parame	eto	er BuildingZone is 'O)ι	utOfServic	e' also tl	ne d	corre	sponding Ro	om and	Sub	zone
parame	eters are	e 'OutOfSe	эr۱	vice' (common flag)									

1.5.24.3 Parameter Subzone

FB:	SAB	AB Property Name (Server): SceneGroup.Subzone Mandatory									
Desc	ription:		-						9		
Part of	of Scene	Group paran	neter set mapped to) L	TE-Mode	Geograp	hica	al zo	ne:		
-> Su	bzone w	ithin Building	gZone.Room								
DPT:	Name	e DPT_Uc	countValue8_Z		DPT ID	202.002	2	Dat	atype forma	U_8Z_8	
Field			Description				Su	ıp.	Range	Unit	Default
Coun	terValue		Subzone number				N	1	1 to 15		CS
Statu	S									bitset	
- OutOfService zone active /inactive						C)	true/false		CS	
- all c	ther flags	S	not supported, fixe	ed	to '0'		N.	Α			
Comi	mand									enum	
	malWrite						N	-			
		esetOSV	set zone inactive / active			C	1				
- all c	ther com	mands	not supported				N.	A			
Com	municati	ion:									
	Address	- -	IO Type(ID):		800 (SAB))	Pr	ope	rty ID:	106	
(in	the serve	er)	Start-Index:		1			of e	elements	1	
	perty ac	cess:	Read only			Read/W	rite		\boxtimes		
Pro	tection		Read level				W	rite	level		
Exce	ption Ha	ndling:	Value after Powerup	o:	Stored \	/alue 🛚	Act	t Va	lue 🗌 De	fault Valu	e 🗌
Spec	Special Features:										
SAB	SAB runtime Datapoint NumberedSceneControl is not LTE-Mode communicating if zone is										
		•	er BuildingZone is '		utOfServic	e' also th	e co	orre	sponding Ro	om and S	ubzone
parar	arameters are 'OutOfService' (common flag)										

1.5.25 Parameter OutsideSensorZone

FB:	SAB	Property	Name (Server):	ame (Server): OutsideSensorZone Mandatory ☐ Optional ☐						onal 🛚	
Desc	ription:								_		
Numb	er of the	Outside S	ensor Zone to be u	ised	for the bir	nding of s	sen	sors	providing Wi	ndAlarm,	
Frost	Alarm ar	ıd RainAlar	m information in the	e L	TE-Mode re	untime sy	yste	em.			
DPT:	Nam	e DPT_U	JcountValue8_Z		DPT ID	202.002	2	Dat	atype format	U_8Z_8	
Field			Description				S	up.	Range	Unit	Default
Sens	orZone		Number of the se	ensc	or zone			M	1 to 31		CS
Statu	S									bitset	
- OutOfService zone active /inactive						0	true/false		CS		
- all o	- all other flags not supported, fixed to '0'						١	NA			
Comr										enum	
- NormalWrite							M				
		esetOSV	set zone inactive	/ a	ctive			0			
- all o	ther com	ımands	not supported				١	۱A			
Com	municat	ion:									
DP	Address	5:	IO Type(ID):		800 (SAB))	Р	rope	rty ID:	107	
(in t	the serv	er)	Start-Index:		1		Ν	l° of e	elements	1	
Pro	perty ac	cess:	Read only			Read/W	/rite)	\boxtimes		
Pro	tection		Read level				٧	Vrite	level		
Exce	ption Ha	andling:	Value after Power	up:	Stored \	Value 🛚	A	ct Va	lue 🗌 Def	fault Value	<u>,</u>
Spec	Special Features:										
SAB	runtime i	nput Datap	oints WindAlarm, F	ros	tAlarm and	RainAla	ırm	are	not LTE-Mod	le commur	nicating if
zone	AB runtime input Datapoints WindAlarm, FrostAlarm and RainAlarm are not LTE-Mode communicating if one is 'OutOfService'.										

1.5.26 Parameter ActuatorMode

FB:	SAB	Proper	ty Name (<u>Server</u>):	ActuatorMo	ode		Mandator	y 🛛 Opt	tional 🗌
Desc	ription:								
This	parameter i	s only us	ed in the LTE-Mode ru	untime syst	em to de	fine wl	nether the SA	B is conne	ected to a
SSSI	B Sensor or	to a Cor	ntroller.						
DPT:	: Name	DPT_A	ctuatorConnectType	DPT ID	20.020	Da	tatype format	t N ₈	
Field			Description			Sup.	Range	Unit	Default
1: SensorConnection [1, 2] cs								CS	
	2: ControllerConnection								
Com	munication	1 :			•		-		
DP	Address:		IO Type(ID):	800(SAB)		Prop	erty ID:	110	
(in	the server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	rite	\boxtimes		
Pro	tection		Read level			Write	elevel		
Exce	ption Hand	dling:	Value after Powerup:	Stored V	′alue ⊠	Act V	alue 🔲 Def	fault Value	, 🗌
Spec	ial Feature	s:		_	•		-		

1.5.27 Parameter EnableInfoMoveUpDown

FB:	SAB	Proper	ty Name (<u>Server</u>):	Name (Server): EnableInfoMoveUpDown Mandatory Optional						
Desc	ription:	-	•				-			
			ed in the LTE-Mode r	untime syst	tem to er	nable or	disable trans	smission o	f	
actua	tor state In	foMoveU	pDown							
DPT:	Name	DPT_E	nable	DPT ID	1.003	Dat	tatype format	B ₁		
Field			Description			Sup.	Range	Unit	Default	
0: disable disable										
	1: enable									
Comi	municatior	າ:				3	-	-		
DP	Address:		IO Type(ID):	800(SAB)		Prope	erty ID:	111		
(in t	the server)		Start-Index:	1		N° of	elements	1		
Pro	perty acce	ss:	Read only		Read/W	rite	\boxtimes			
Pro	tection		Read level			Write	level			
Exce	ption Hand	dling:	Value after Powerup:	Stored \	/alue 🛚	Act Va	alue 🗌 🛮 Def	ault Value	<u> </u>	
Spec	ial Feature	s:								
This	his parameter shall be implemented if LTE-Mode output InfoMoveUpDown is implemented.									

1.5.28 Parameter EnableStatusSAB

FB:	SAB	Proper	ty Name (<u>Server</u>):	<u>er</u>): EnableStatusSAB Mandatory ⊠ Optional □						
Desc	ription:	3	-				-			
This p	oarameter i	s only us	sed in the LTE-Mode r	untime syst	em to en	able or	disable trans	mission o	f	
actua	tor state St	atusSAE	}							
DPT:	Name	DPT_E	nable	DPT ID	1.003	Dat	atype format	B ₁		
Field Description Sup. Range Unit							Unit	Default		
			0: disable						disable	
			1: enable							
Com	municatior	1:			•		-			
DP .	Address:		IO Type(ID):	800(SAB)		Prope	rty ID:	112		
(in t	he server)		Start-Index:	1		N° of	elements	1		
Pro	perty acce	ss:	Read only		Read/W	rite	\boxtimes			
Pro	tection		Read level			Write	level			
Exce	ption Hand	lling:	Value after Powerup	Stored \	/alue 🛚	Act Va	ılue 🗌 🛮 Def	ault Value	:	
Spec	Special Features:									

1.5.29 Parameter MoveDownTime

FB:	SAB	Proper	Property Name (Server): MoveDownTime Mandatory ☐ Optional ☒						
Desc	ription:	-	-				-		
			ne time in the drive mo	odel of the	SAB to m	nove the	e sunblind fro	m the fina	l upper
to the	final lower	position	•						
DPT:	Name	DPT_T	imePeriodSec	DPT ID	7.005	Da	tatype format	U ₁₆	
Field			Description			Sup.	Range	Unit	Default
TimePeriodSec See above M cs s cs									
Com	munication	า :							
DP	Address:		IO Type(ID):	800(SAB)		Prope	erty ID:	113	
(in t	he server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	/rite	\boxtimes		
Pro	tection		Read level			Write	level		
Exce	ption Hand	dling:	Value after Powerup:	Stored \	/alue 🛚	Act Va	alue 🔲 Def	fault Value	- 🗌
Spec	Special Features:								
If a se	ensor (hard	wired) is	implemented that det	ects that th	e upper	or lowe	r position is re	eached, th	is
paran	parameter may not be needed.								

1.5.30 Parameter MoveUpTime

FB:	SAB	Proper	ty Name (<u>Server</u>):	er): MoveUpTime Mandatory Optional					
Desc	ription:	-	-				-		
This p	oarameter o	defines th	ne time in the drive mo	del of the	SAB to m	ove the	sunblind fro	m the fina	l lower to
the fir	nal upper p	osition.							
DPT:	Name	DPT_T	imePeriodSec	DPT ID	7.005	Dat	atype format	U ₁₆	
Field			Description			Sup.	Range	Unit	Default
Timel	PeriodSec		See above			М	CS	S	CS
Com	municatior	1 :							
DP	Address:		IO Type(ID):	800(SAB)		Prope	rty ID:	114	
(in t	he server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	rite	\boxtimes		
Pro	tection		Read level			Write	level		
Exce	ption Hand	dling:	Value after Powerup:	Stored \	/alue 🛚	Act Va	lue 🗌 Def	ault Value	-
Spec	Special Features:								
If a se	ensor (hard	wired) is	implemented that det	ects that th	e upper o	or lowe	r position is re	eached, th	is
paran	parameter may not be needed.								

1.5.31 Parameter Additional Move Time

FB:	SAB	Proper	ty Name (Server): AdditionalMoveTime Mandatory Optional						
Desc	ription:	-	-			-			
This	parameter o	defines th	ne additional time in th	e drive model of the	e SAB t	to move the s	unblind fro	m the	
uppei	r/lower posi	tion to th	e end- switch position	1					
DPT:	Name	DPT_T	mePeriodSec	DPT ID 7.005	Da	tatype format	U ₁₆		
Field			Description		Sup.	Range	Unit	Default	
TimePeriodSec See above M cs s cs						CS			
Com	municatior	า :							
DP	Address:		IO Type(ID):	800(SAB)	Prop	erty ID:	115		
(in t	the server)		Start-Index:	1	N° of	elements	1		
Pro	perty acce	ss:	Read only	Read/W	/rite	\boxtimes			
Pro	tection		Read level		Write	level			
Exce	ption Hand	lling:	Value after Powerup:	Stored Value 🛛	Act V	alue 🔲 De	fault Value	· 🔲	
									
Spec	Special Features:								
This	his parameter is only useful if end-switch sensor (hardwired) is implemented								

1.5.32 Parameter ReversionPauseTime

FB: SAB F	ropert	erty Name (<u>Server</u>): ReversionPauseTime Mandatory ☐ Optional 🗵								
Description:										
This parameter def	fines the	e wait time in the driv	e model of	the SAB	to avoi	d destruction	of the driv	ve as a		
result of too fast ch	nange o	f moving direction. A	Ithough this	parame	ter is op	otional, the fu	inctionality	/ shall		
always be ensured	via ap	oropriate hardware.								
DPT: Name D	PT_Tir	mePeriodMsec	DPT ID	7.002	Dat	atype format	U ₁₆			
Field		Description			Sup.	Range	Unit	Default		
TimePeriodMSec		See above			М	cs	ms	CS		
Communication:	-						-	_		
DP Address:		IO Type(ID):	800(SAB)		Prope	rty ID:	116			
(in the server)		Start-Index:	1		N° of	elements	1			
Property access	s:	Read only		Read/W	rite	\boxtimes				
Protection		Read level			Write	level				
Exception Handlin	ng:	Value after Powerup	Stored \	/alue 🛚	Act Va	lue 🔲 De	fault Value)		
Special Features:	Special Features:									
	•									

1.5.33 Parameter SlatStepTime

FB:	SAB	Proper	pperty Name (Server): SlatStepTime Mandatory ☐ Optional ☒						
Desc	ription:	-	-			-			
			he time in the drive mo						
The v	alue of this	parame	ter could also be calc	ulated from the para	meters	MaximumSla	atMoveTim	ie and	
Numb	erOfSlatSt	eps							
DPT:	Name	DPT_T	imePeriodMsec	DPT ID 7.002	Dat	tatype format	U ₁₆		
Field Description Sup. Range Unit Default									
TimePeriodMSec Time needed for the blinds mechanics M cs ms cs							CS		
	to move the slats for one step								
Comi	nunication	ո։							
DP	Address:		IO Type(ID):	800(SAB)	Prope	erty ID:	117		
(in t	he server)	1	Start-Index:	1	N° of	elements	1		
Pro	perty acce	ss:	Read only	Read/W	/rite	\boxtimes			
Pro	tection		Read level		Write	level			
Exce	ption Hand	lling:	Value after Powerup	Stored Value 🛛	Act Va	alue 🔲 🛮 De	fault Value	, 🗌	
Spec	Special Features:								
This p	oarameter i	s only us	seful if the sunblind ca	n be operated in ste	eps (see	also StopSto	epUpDowi	n and	
StopS	StopStepUpDownCmd).								

1.5.34 Parameter NumberOfSlatSteps

FB:	SAB	Proper	perty Name (Server): NumberOfSlatSteps Mandatory ☐ Optional ☐						
Desc	ription:								
This	oarameter o	defines tl	he number of steps to	move the s	lats from	the fina	al upper 0 %	to the fina	llower
100 %	6 position								
			ter could also be calcu				MaximumSla	ıtMoveTim	e and
SlatS	tepTime if I	<u>Maximur</u>	nSlatMoveTime is a m	ultiple of S	latStepTi	me.			
DPT:	Name	DPT_V	alue_1_Ucount	DPT ID	5.010	Dat	atype format	U ₈	
Field									
Coun	Counter value Number of slats steps M cs cs								
Com	munication	า:			•	=	-		
DP	Address:		IO Type(ID):	800(SAB)		Prope	rty ID:	118	
(in t	he server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	/rite	\boxtimes		
Pro	tection		Read level			Write	level		
Exce	ption Hand	dling:	Value after Powerup:	Stored \	/alue ⊠	Act Va	lue 🗌 Def	ault Value	; <u> </u>
Spec	Special Features:								
This	oarameter i	s only us	seful if the sunblind car	n be operat	ted in ste	ps (see	also StopSte	epUpDowr	n and
Stops	topStepUpDownCmd).								

1.5.35 Parameter MaximumSlatMoveTime

FB:	SAB	Proper	ty N	Name (<u>Server</u>):	(Server): SlatStepTime Mandatory Optional							
Desc	ription:			-				-				
This p	oarameter o	defines tl	he to	otal time in the driv	e model of	the SAB	to me	ove the slats fr	om the fin	al upper		
0 % to	the final lo	ower 100) %	position.								
The v	alue of this	parame	ter (could also be calcu	ulated from	the para	meter	s SlatStepTime	e and			
Numb	erOfSlatSt	eps										
DPT:	Name	DPT_T	ime	PeriodMsec	DPT ID	7.002	D	atatype format	U ₁₆			
Field												
Timel	PeriodMSe	C	Tir	me needed for the	blinds mec	hanics	М	CS	ms	cs		
			to	move the slats from	m 0 % to 10	00 %						
Comi	municatior) :										
DP	Address:		10	IO Type(ID):	800(SAB)		Prop	erty ID:	119			
(in t	he server)		5	Start-Index:	1		N° c	f elements	1			
Pro	perty acce	ss:	F	Read only		Read/W	'rite	\boxtimes				
Pro	tection		F	Read level			Writ	e level				
Exce	ption Hand	lling:	Va	alue after Powerup:	Stored \	/alue ⊠	Act \	/alue 🗌 Def	ault Value	e 🗌		
Spec	Special Features:											
This p	oarameter i	s only us	sefu	ıl if the sunblind car	n be opera	ted in ste	ps (se	ee also StopSte	epUpDow	n and		
StopS	topStepUpDownCmd).											

1.5.36 Parameter PowerReturnMode

FB:	SAB	Proper	ty Name (<u>Server</u>):	PowerRetu	ırnMode		Mandato	ry 🔲 Opt	ional 🛚
Desc	ription:	-		-					
		fine the b	ehaviour of the actua	ator after ret	urn of the	supply	power or af	ter a resta	rt of the
applic	ation.								
DPT:	Name	DPT_S	ABExceptBehaviour	DPT ID	20.801	Dat	tatype format	t N ₈	
Field			Description			Sup.	Range	Unit	Default
Mode			- 0 = Up			М	[0 to 4]		CS
			- 1 = Down						
			- 2 = no change						
			- 3 = value according	g additional					
			parameter Pov	werReturnVa	alue				
			- 4 = stop						
Comr	nunicatior	1:			•	='	•	-	
DP .	Address:		IO Type(ID):	800 (SAB)	Prope	erty ID:	120	
(in t	he server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	rite	\boxtimes		
Prot	tection		Read level			Write	level		
Exce	ption Hand	lling:	Value after Powerup	: Stored \	/alue ⊠	Act Va	lue 🗌 De	fault Value	: 🗌
Speci	ial Feature	s:							
It is al	llowed to re	estrict the	range of values of the	nis paramete	er				

1.5.37 Parameter PowerReturnValue

			y Name (<u>Server</u>):	1 011011100	urnValue	•	Vlandatory	<u> </u>	ional 🖂
Description	on:								
Parameter	r in add	lition to p	arameter PowerRet	urnMode =	3; to define t	he beha	viour after	power r	eturn.
Field Slats	Positio	n shall b	e ignored if the actu	ator is only	able to contr	ol the h	eight posit	ion (e.g.	in case
of shutter of	control).							
Field Heigl	htPosit	ion shall	be ignored if the act	uator is onl	y able to con	trol the	angle posi	tion of th	e slats
(e.g. contro	ol of ve	ertical sur	nblinds).						
DPT: N	lame	DPT_Co	mbinedPosition	DPT ID	240.800	Datatyp	oe format	U ₈ U ₈ B	8
Field		Descri	ption			Sup.	Range	Unit	Default
HeightPos	ition	Target	height position of the	ne blinds in	percentage	M	CS	%	cs
SlatsPositi	ion	Target	slats-angle position	in percenta	age	М	CS	%	cs
Attributes		Bit #		•					
- ValidHeig	ghtPos	0	Validity of field I	- HeightPositi	on	М	{0, 1}		cs
- ValidSlat	sPos	1	Validity of field S	SlatsPositio	n	М	{0, 1}		cs
- reserved		2-7	reserved bits sh	all be ignor	ed		0		0
Communi	ication	:							
DP Addr	ress:		IO Type(ID):	800 (SAB) Pi	roperty I	D:	121	
(in the s	erver)		Start-Index:	1	N'	° of elen	nents	1	
Property	y acces	ss:	Read only		Read/Write	: [
Protection	on		Read level		W	rite leve	el		
Exception	n Hand	ling:	Value after Powerup	: Stored	Value 🛛 Ad	t Value	Defa	ault Value	е 🗌
Special Fe	eature	s:							

1.5.38 Parameter BusFailureMode

FB:	SAB	Proper	ty Name (<u>Server</u>):	BusFailureMode		Mandator	y 🗌 Opt	ional 🛚
Desc	ription:							
Parar	neter to de	fine the b	ehaviour of the actua	ator in case of a bu	us failure			
DPT:	Name	DPT_S	ABExceptBehaviour	DPT ID 20.8	01 Da	tatype format	: N ₈	
Field			Description		Sup.	Range	Unit	Default
Mode			- 0 = Up		M	[0 to 4]		CS
			- 1 = Down					
			- 2 = no change					
			- 3 = value according					
			parameter Bus					
			- 4 = stop					
Communication:						-	-	<u>-</u>
DP Address: IO Type(ID): 800 (SAB) Property ID: 122								
(in the server) Start-Index: 1						elements	1	
Pro	perty acce	ss:	Read only	/Write	\boxtimes			
Pro	tection		Read level	Write	level			
Exception Handling: Value after Powerup: Stored Value						lue 🗌 Def	ault Value) <u> </u>
	•	•		_				•
Spec	ial Feature	s:						
It is allowed to restrict the range of values of this parameter								

1.5.39 Parameter BusFailureValue

FB:	SAB	Property	y Name (<u>Server</u>):	BusFailure	Value		Mandatory	☐ Opt	ional 🖂
Desc	ription:								
Parar	neter in add	dition to p	arameter BusFailure	Mode = 3;	to define the	behavi	our in case	of a bus	s failure
Field	SlatsPosition	on shall b	e ignored if the actua	ator is only	able to contr	ol the h	eight posit	ion (e.g.	in case
of shu	utter control).							
Field	HeightPosi [*]	tion shall	be ignored if the act	uator is only	y able to con	trol the	angle posi	tion of th	e slats
(e.g. (control of ve	ertical sur	ıblinds).						
DPT:	Name	DPT_Cc	mbinedPosition	DPT ID	240.800	Dataty	oe format	U ₈ U ₈ B	8
Field		Descr	ption			Sup.	Range	Unit	Default
Heigh	tPosition	Targe	t height position of th	ne blinds in	percentage	M	CS	%	cs
Slatsl	Position	Targe	slats-angle position	in percent	age	М	CS	%	cs
Attrib	utes	Bit #			-				
- Valid	dHeightPos	0	Validity of field h	- TeightPositi	on	М	{0, 1}		cs
- Valid	dSlatsPos	1	Validity of field S	SlatsPositio	n	М	{0, 1}		cs
- rese	rved	2-7	reserved bits sh	all be ignor	ed		0		0
Com	nunication):							
DP	Address:		IO Type(ID):	800 (SAB) Pi	roperty	ID:	123	
(in t	he server)		Start-Index:	1	, N	° of eler	nents	1	
Pro	perty acce	ss:	Read only		Read/Write	:			
Pro	tection		Read level		W	rite leve	el		
Exce	ption Hand	lling:	Value after Powerup	: Stored	Value 🛛 Ad	t Value	☐ Defa	ault Value	е 🗌
Spec	ial Feature	s:							

1.5.40 Parameter BusReturnMode

FB:	SAB	Proper	ty Name (<u>Server</u>):	Лode		Mandator	y 🔲 Opt	ional 🛚			
Desc	ription:										
Parar	neter to de	fine the b	ehaviour of the actuat	tor in case c	f a reco	overy of the bus.					
DPT:	Name	DPT_S	ABExceptBehaviour	DPT ID	20.801	Dat	atype format	: N ₈			
Field			Description			Sup.	Range	Unit	Default		
Mode			- 0 = Up			M	[0 to 4]		CS		
			- 1 = Down								
			- 2 = no change								
			- 3 = value according	additional							
			parameter Busk								
- 4 = stop											
Comi	nunicatior) :					•	-			
DP	Address:		IO Type(ID):	800 (SAB)		Prope	erty ID:	124			
(in t	he server)		Start-Index:	1		N° of	elements	1			
Pro	perty acce	ss:	Read only		Read/W	rite	\boxtimes				
Pro	tection		Read level			Write	level				
Exce	ption Hand	lling:	Value after Powerup:	Stored V	alue 🛚	Act Va	lue 🔲 Def	ault Value	: <u> </u>		
	•			•				•	•		
Spec	ial Feature	s:			-	-	·	_			
It is a	llowed to re	estrict the	range of values of thi	is paramete	r						

1.5.41 Parameter BusReturnValue

FB:	SAB	Property	/ Name (<u>Server</u>):	BusRetur	∩Value	N	Mandatory	Opt	ional 🔀
Desc	ription:			-		-			
Paran	neter in add	dition to pa	arameter BusRetur	nMod = 3 to	define the be	ehaviou	r after a re	covery o	f the
bus.									
Field	SlatsPosition	on shall be	e ignored if the actu	uator is only	able to contro	ol the h	eight positi	on (e.g.	in case
	ıtter control								
			be ignored if the ac	tuator is on	y able to cont	trol the	angle posit	ion of th	e slats
(e.g. o	control of ve	ertical sun	blinds).						
DPT:	Name	DPT_Co	mbinedPosition	DPT ID	240.800	Datatyp	oe format	U ₈ U ₈ B ₈	3
Field		Descri	ption			Sup.	Range	Unit	Default
Heigh	tPosition	Targe	t height position of	the blinds in	percentage	M	CS	%	CS
Slats	Position	Targe	t slats-angle position	n in percen	tage	M	CS	%	CS
Attrib	utes	Bit #							
- Valid	dHeightPos	0	Validity of field	HeightPosit	ion	M	{0, 1}		CS
- Valid	dSlatsPos	1	Validity of field	SlatsPositio	n	M	{0, 1}		CS
- rese	rved	2-7	reserved bits sl	hall be ignoi	ed		0		0
Comr	nunication):	-			-	•	-	
DP .	Address:		IO Type(ID):	800 (SAE	B) Pr	operty I	D:	125	
(in t	he server)		Start-Index:	1	N°	of elen	nents	1	
Pro	perty acce	ss:	Read only		Read/Write	Σ	3		
Pro	tection		Read level		W	rite leve	el .	-	
Exce	otion Hand	lling: \	/alue after Poweru	p: Stored	Value 🛛 Ac	t Value	☐ Defa	ult Value	
				-					
Speci	ial Feature	s:							

1.5.42 Parameter PowerFailureMode

FB:	SAB	Proper	y Name (<u>Server</u>):	PowerFailu	ureM	ode		Mandator	y 🔲 Opt	ional 🛚
Desc	ription:	3	-					-		
Paran	neter to def	fine the b	ehaviour of the actua	tor in case	of the	supply	y pov	ver failure, to	switch e.	g. a
bistab	le relay be	fore pow	er down of the device							
DPT:	Name	DPT_S	ABExceptBehaviour	DPT ID	20.	801	Data	atype format	N ₈	
Field			Description			Sup	٠.	Range	Unit	Default
Mode			- 0 = Up			M		[0;1;2;4]		CS
			- 1 = Down							
			- 2 = no change							
			- 4 = stop							
Com	nunication):				=		-		-
DP Address: IO Type(ID): 800 (SAB) Property ID: 126										
(in t	he server)		Start-Index:	1		N	l° of e	elements	1	
Pro	perty acce	ss:	Read only		Rea	d/Write		\boxtimes		
Prof	tection		Read level			V	/rite I	level		
Exce	otion Hand	lling:	Value after Powerup:	Stored \	/alue	Ac Ac	t Val	ue 🗌 Def	ault Value)
Spec	ial Feature	s:								
It is a	lowed to re	strict the	range of values of thi	s paramete	er	•		·		

1.5.43 Parameter BehaviourAtLocking

FB:	SAB	Property	/ Name (<u>Server</u>):	Behaviour/	AtLocking	3	Mandator	y 🔲 Opt	tional 🛚
Descr	iption:		-				-		
		efine the be	haviour of the actua	tor in case	of input L	.ockDe	vice changing	from	
false -	> true								
DPT:	Name	_	BBehaviour_Lock_	DPT ID	20.802	Dat	tatype format	N ₈	
		Unlock							
Field	Des	cription				Sup.	Range	Unit	Default
Mode	- 0	= up				M	[0 to 4]		CS
	- 1	= down							
	- 2	= no chan	ge						
	- 3	= value ac	cording to paramete	r LockSetva	alue				
	- 4	= stop							
Comn	nunicatio	n:					-		
DP /	Address:		IO Type(ID):	800 (SAB)	Prope	erty ID:	127	
(in t	he server	·)	Start-Index:	1		N° of	elements	1	
Prop	perty acc	ess:	Read only		Read/W	rite	\boxtimes		
Prot	ection		Read level			Write	level		
Excep	otion Han	dling: \	/alue after Powerup:	Stored \	/alue ⊠	Act Va	lue 🗌 Def	ault Value	, 🗌
				_		•			
Speci	al Featur	es:							
It is al	lowed to r	estrict the	range of values of th	s paramete	er				

1.5.44 Parameter LockSetvalue

FB:	SAB	Pro	pert	y N	lame (<u>Server</u>):	LockSetva	lue		N	/landatory	/ 🗌 Op	tional 🛚
Desc	ription:				<u>-</u>							
Paran	neter in add	dition	to p	ara	ameter BehaviourA	tLocking =	: 3; to	define	the beh	aviour at	the begir	ning of
the lo	ck state					_					_	
Field	SlatsPosition	on sh	all b	е і	gnored if the actua	tor is only	able	to contr	ol the he	eight posi	tion (e.g.	in case
	ıtter contro					-					, ,	
Field	HeightPosi	tion s	shall	be	ignored if the actu	ator is only	y abl	e to con	trol the	angle pos	ition of th	ne slats
(e.g. o	control of ve	ertica	al sui	nbli	nds).	•				•		
DPT:	Name	DP	T_Co	oml	binedPosition	DPT ID	240	0.800	Datatyp	e format	U ₈ U ₈ B	8
Field			De	scri	iption				Sup.	Range	Unit	Default
Heigh	tPosition	Та	rget	hei	ight position of the	blinds in p	erce	ntage	M	CS	%	CS
Slats	Position				ts-angle position in				M	CS	%	CS
Attrib	utes		Bit	#		-						
- Valid	dHeightPos	;	0		Validity of field H	eightPositi	on		M	{0, 1}		CS
- Valid	SlatsPos		1		Validity of field S	latsPositio	<u> </u>		M	{0, 1}		CS
- rese	rved		2-7		reserved bits sha	all be ignore	ed			0		0
DPT:	Name	DP	T_Co	oml	binedPosition	DPT ID	240	0.800	Datatyp	e format	U ₈	
Field				De	scription			Sup.	Range		Unit	Default
Setva	lue			Dir	nming value in per	rcent		•	0 % to		%	CS
Comr	nunicatior	1:			·							•
DP	Address:			10	O Type(ID):	800 (SAB)	Pi	operty I	D:	128	
(in t	he server)			S	Start-Index:	1	•	N'	of elen	nents	1	
Pro	perty acce	ss:		R	Read only		Rea	ad/Write	\triangleright]		
	ection				Read level			W	rite leve			
Exce	otion Hand	lling	:	Val	lue after Powerup:	Stored '	Value	e 🛛 Ac	t Value	☐ Def	ault Valu	e 🗌
					•							
Spec	ial Feature	s:										

1.5.45 Parameter BehaviourAtUnlocking

FB:	SAB	Prope	erty Name (<u>Server</u>):	Behaviour/	∖tUı	nlocking	Mandatory	Opt	tional 🛚	
Desc	ription:		-				-			
Paran	neter to de	fine the	behaviour of the actua	tor in case o	of ir	nput Lock	kDevice changing	from		
true -:	> false									
DPT:	Name	DPT_	SABBehaviour_Lock_	DPT ID	20).802	Datatype format	N ₈		
		Unloc	k							
Field			Description			Sup.	Range	Unit	Default	
Mode			-0 = up			М	[0 to 3; 5 6]		cs	
			- 1 = down							
			- 2 = no change							
- 3 = value according to parameter										
UnlockSetvalue										
			- 5 = updated value							
- 6 = value before locking										
Communication:										
DP .	DP Address: IO Type(ID): 800 (SAB) Property ID: 129									
(in t	(in the server) Start-Index: 1 N° of elements 1									
Pro	Property access: Read only ☐ Read/Write ☒									
Pro	tection		Read level			V	/rite level			
Exce	otion Hand	lling:	Value after Powerup:	Stored V	'alu	e 🛛 Ac	t Value 🗌 Defa	ult Value	, 🗌	
						-		-		
Spec	ial Feature	s:								
It is a	It is allowed to restrict the range of values of this parameter									

1.5.46 Parameter UnlockSetvalue

FB:	SAB	Pro	pert	y N	lame (<u>Server</u>):	UnlockSet	value)	N	Mandatory	у 🔲 Ор	tional 🛚
Desc	ription:											
Paran	neter in add	dition	ı to p	ara	ameter BehaviourA	tUnlocking	j = 3;	to defin	ne the b	ehaviour	at the en	d of the
lock s	tate		-									
Field	SlatsPosition	on sh	nall b	e iç	gnored if the actua	tor is only	able t	to contr	ol the he	eight posi	tion (e.g.	in case
of shu	ıtter contro	l).										
Field	HeightPosi	tion	shall	be	ignored if the actu	ator is only	/ able	e to con	trol the	angle pos	sition of th	ne slats
(e.g. c	control of ve	ertica	al sur	nbli	nds).							
DPT:	Name	DP.	T_Co	ml	binedPosition	DPT ID	240	.800	Datatyp	e format	U ₈ U ₈ E	8
Field			Des	scri	iption				Sup.	Range	Unit	Default
Heigh	tPosition	T	arget	he	eight position of the	e blinds in p	oerce	entage	М	cs	%	CS
SlatsF	Position				ats-angle position				М	cs	%	CS
Attribu	utes		Bit	#								
- Valid	dHeightPos	;	0		Validity of field H	eightPosition	on		М	{0, 1}		CS
- Valid	dSlatsPos		1		Validity of field S	latsPositior	1		М	{0, 1}		CS
- rese	rved		2-7		reserved bits sha	all be ignore	ed			0		0
DPT:	Name	DP	T_Sc	alii	ng	DPT ID	5.00	01	Datatyp	e format	U ₈	
Field					scription			Sup.	Range		Unit	Default
Setva	lue			Dir	nming value in per	rcentage			0 % to	100 %	%	CS
Comr	nunicatior	1:			-				<u> </u>	*		
DP .	Address:			10	O Type(ID):	800 (SAB))	P	roperty I	D:	130	
(in t	he server)				Start-Index:	1			° of elen		1	
Pro	perty acce	SS:		R	Read only		Rea	d/Write				
Prof	ection			R	Read level			W	rite leve	<u> </u>		
Exce	otion Hand	lling	:	Val	lue after Powerup:	Stored \	/alue	e 🛛 Ad	t Value	☐ Def	ault Valu	е 🗌
Speci	ial Feature	s:										

1.5.47 Parameter SceneLearningModeEnable

FB:	SAB	Property	Name (<u>Server</u>):	SceneLearn	ingMode	Enable	Mandator	/ 🗌 Opt	ional 🛚
Desc	ription:		-				-		
			o enable or disable glo						
			ized modification of so		ardless o	f the va	lue of the field	d Storage	Function
of the	Scene In	dex in the	Parameter SceneNur	mberList					
DPT:	Name	DPT_E	nable	DPT ID	1.003	Dat	tatype format	B ₁	
Field			Description			Sup.	Range	Unit	Default
			0: disable scene lear	ning					disable
			1: enable scene lear	ning					
Com	municatio	n:							
DP	Address:		IO Type(ID):	800 (SAB))	Prope	erty ID:	131	
(in t	the serve	r)	Start-Index:	1		N° of	elements	1	
Pro	perty acc	ess:	Read only		Read/W	'rite	\boxtimes		
Pro	tection		Read level			Write	level		
Exce	ption Har	ndling:	Value after Powerup:	Stored \	/alue ⊠	Act Va	alue 🔲 🛮 Def	ault Value	
 Spec	ial Featu	res:							

1.5.48 Parameter SceneNumberList[n]

FB:	SAB	Property Name (Server):	SceneNumberList[n]	Mandatory Optional
Desc	ription:	-	-	-

This parameter contains the list of Scene Numbers that are supported by FB SAB. The list is implemented as an array property with.

- current nr of elem: shall equal the number of scenes that is currently configured in this FB
- max_nr_of_elem: shall equal the maximal number of scenes that is supported by this FB
- current_nr_of_elem ≤ max_nr_of_elem ≤ 64

Array elements beyond the current_nr_of_elem are void and shall not be evaluated by the FB at runtime. These array elements have not been configured yet and are invalid.

Each array element represents scene configuration information for one Scene Index.

This list shall allow linking a Scene Number to a Scene Index within the FB.

Values at an index n in this array Property shall relate to the same Scene Number as the array elements in the following array Properties:

- SceneTaughtIn[]
- AbsPositionScene[]

Each array element defines the following configuration information for one dedicated Scene Index:

- SceneNumber (0 to 63)
- activation/inactivation
- storage function enable/disable

DPT:	Name	DPT_Sc	eneConfig		DPT ID	238.001	1 Da	tatype format	B ₂ U ₆	
Field		Descri	ption				Sup.	Range	Unit	Default
Storage	Function	possib this So from F Number - 0: tea	eld shall indicate was to be not to change the Number at ruse SCS through in the second of the secon	e the ntime out abled	set value e over the	e for	O ¹)	{0, 1}	none	CS
scen If this Scer Scer and I			Index is inactive a	is active. is active. is last the value inactive then this Index is inactive and the contained Number shall be regarded as void of supported by the FB. ene is active			M	{0, 1}	none	CS
SceneN	umber	that is In case than s Scene index	eld shall contain the assigned to this Seless Scene Numupported by this Factive shall be set and the value of the Number shall be contained.	cene bers B, the to "li e fiel	Index. are confen the fien nactive"	igured eld	M	0 to 63	none	cs
	ınication:									
	ldress:		IO Type(ID):	80	00 (SAB))		erty ID:	132	
	server)		Start-Index:	1				elements	see abov	/e
	rty acces	ss:	Read only			Read/W		\boxtimes		
Protec			Read level				Write			
Excepti	cception Handling: Value after Powerup: Stored Value Act Value Default Value									

Special Features:

This list does not need to be sorted. Active and inactive Scene Numbers can be at any Index position. Any Scene Number shall appear at maximum once in this list, and this list shall not have duplicate entries. This is the responsibility of the Management Client that sets this Property Value.

1) Support of this control field is optional. Teach-in may be enabled/disabled globally via ScenelearningModeEnable parameter.

Behaviour of the property server if this field is not supported: the receiver (server) shall ignore the written value of this bit and respond with the actual (default) value.

1.5.49 Parameter SceneTaughtIn[n]

FB:	SAB	Property Name (Server):	SceneTaughtIn[n]	Mandatory ☐ Optional ⊠
Des	cription:			
For	each Scen	e Index this Property shall co	ntain a Boolean indication wheth	ner or not the corresponding
scei	ne has bee	n taught in already via input N	lumberedSceneControl.	
This	Datapoint	shall be an array Property wh	nich contains one entry for each	Scene Index that is
sup	ported by the	he FB SAB, with:		
- 0	current_nr_	of_elem: shall equal the numl	per of scenes that is currently co	onfigured in this FB
- r	nax_nr_of_	_elem: shall equal the maxima	Il number of scenes that is supp	orted by this FB
- (current_nr_	of_elem ≤ max_nr_of_elem ≤	64	
Arra	y elements	s beyond the current nr of el	em are void and shall not be ev	aluated by the FB at runtime.

These array elements have not been configured yet and are invalid.

Scene TaughtIn information is interlinked with Scene Number via the Scene Index. Values at an index n in this array Property shall relate to the same Scene Number as the array elements in the following array Properties:

- SceneNumberList[]

- AbsPositionS	AbsPositionScene[]								
DPT: Name	DPT_Bo	ol	DPT ID	1.002	Da	atype format	B ₁		
Field	Descript	ion			Sup.	Range	Unit	Default	
b [n]	- false: t	he Scene with Scene	e Index n is	not	M	{0, 1}	none	false	
		(yet) taught in.							
- true: the Scene with Scene Index n is taught									
	in.								
Communication	า:								
DP Address:		IO Type(ID):	800 (SAB)		Prope	rty ID:	133		
(in the server)		Start-Index:	1		N° of	elements	see abov	ve ¹⁾	
Property acce	ss:	Read only	Read/Write						
Protection		Read level			Write	level			
Exception Handling: Value after Powerup: Stored Value ☐ Act Value ☐ Default Value ☐									
	-								
Special Feature	Special Features:								
1) The number of	The number of array elements shall be the same as for Property SceneNumberList.								

1.5.50 Parameter AbsPositionScene[n]

FB:	SAB	Property Name (Server):	AbsPositionScene[n]	Mandatory ☐ Optional ☐
Desc	ription:			

For each Scene Index this Property shall define the target position (height and slats-angle) after recalling a dedicated Scene Number.

This Datapoint shall be an array Property which contains one entry for each Scene Index that is supported by the FB SAB, with:

- current_nr_of_elem: shall equal the number of scenes that is currently configured in this FB
- max_nr_of_elem: shall equal the maximal number of scenes that is supported by this FB
- current_nr_of_elem ≤ max_nr_of_elem ≤ 64

Array elements beyond the current_nr_of_elem are void and shall not be evaluated by the FB at runtime. These array elements have not been configured yet and are invalid.

AbsPositionScene information is interlinked with Scene Number via the Scene Index. Values at an index n in this array Property shall relate to the same Scene Number as the array elements in the following array Properties:

- SceneNumberList[]
- SceneTaughtIn[]

AbsPositionScene may be solely defined by configuration or may be changed at runtime via input NumberedSceneControl if the storage function is enabled for that Scene Index.

Field SlatsPosition shall be ignored if the actuator is only able to control the height position (e.g. in case of shutter control).

Field HeightPosition shall be ignored if the actuator is only able to control the angle position of the slats (e.g. control of vertical sunblinds).

DPT:	Name	DP	T_Com	binedPosition	DPT ID	240.800	Datatyp	e format	U ₈ U ₈ B	8
Field			Descr	ription	Sup.	Range	Unit	Default		
HeightPosition			Targe	t height position of	M	CS	%	cs		
			perce	ntage						
SlatsPosition Target slats-angle position in percentage					M	CS	%	cs		
Attribute	es		Bit #							
- Validh	leightPos	3	0	Validity of field H	leightPositi	on	M	{0, 1}		cs
- ValidS	SlatsPos		1	Validity of field S	latsPositio	n	M	{0, 1}		CS
- reserved 2-7 reserved bits shall be ignored					0		0			
Communication:										
DP A	ddress:		ı	O Type(ID):	800 (SAB)	Property I	D.	134	

Communication:								
DP Address:	IO Type(ID):	800 (SAB)	Property ID:	134				
(in the server)	Start-Index:	1	N° of elements	see above 1)				
Property access:	Read only	Read/W	rite 🛛					
Protection	Read level		Write level					
Exception Handling:	Value after Powerup:	Stored Value 🛛	Act Value De	fault Value				
Special Features:								
1) The number of array e	lements shall be the sa	ame as for Property	SceneNumberList.					

1.5.51 Parameter EnableBlindsMode

FB:	SAB	Proper	ty Name (<u>Server</u>):	EnableBlindsMode		Mandator	y 🔲 Opt	ional 🛚	
Desc	ription:	•							
			hether the actuator fu		actuato	r (with slats)	or only as	a shutter	
actua	itor (no sla	ts -> ste	p command is interpre	eted as stop)					
DPT:	Name	DPT_E	nable	DPT ID 1.003	Dat	tatype format	B ₁		
Field			Description		Sup.	Range	Unit	Default	
			0: disable \Rightarrow shutter	mode				CS	
	1: enable ⇒ blinds mode								
Com	munication	າ:			-				
DP	Address:		IO Type(ID):	800(SAB)	Prope	erty ID:	135		
(in	the server)		Start-Index:	1	N° of	elements	1		
Pro	perty acce	ss:	Read only	Read/W	/rite	\boxtimes			
Pro	tection		Read level		Write	level			
Exce	ption Hand	dling:	Value after Powerup	: Stored Value 🛛	Act Va	alue 🗌 🛮 Def	ault Value		
Spec	ial Feature	es:							

1.5.52 Parameter ReactionWindAlarm

FB:	SAB	Propert	y Name (<u>Server</u>):	ReactionW	'indAlarr	n	Mandatory	Opt	tional 🔀
Desc	ription:	-					-		
Parar	neter to de	fine the b	ehaviour of the actua	itor in case	of a wind	d alarm	l.		
DPT:	Name	DPT_A	arm_Reaction	DPT ID	23.002	2 Da	atatype format	N_2	
Field			Description			Sup.	Range	Unit	Default
Mode			- 0 = no reaction, ala	ırm is not us	ed	M	[0 to 2]		CS
			- 1 = up						
			2 = down						
Com	municatior	า :							
DP	Address:		IO Type(ID):	800 (SAB) Prope		erty ID:	140		
(in t	he server)		Start-Index:	1		N° o	f elements	1	
Pro	perty acce	ss:	Read only		Read/W	√rite	\boxtimes		
Pro	tection		Read level			Write	e level		
Exce	ption Hand	dling:	Value after Powerup	: Stored \	/alue 🛚	Act V	alue 🔲 Defa	ult Value	
Spec	ial Feature	s:							

1.5.53 Parameter ReactionRainAlarm

FB:	SAB	Proper	ty Name (<u>Server</u>):	ReactionR	ainAlarn	n	Mandatory	Opt	ional 🛚
Desc	ription:	-	-						
Parar	Parameter to define the behaviour of the actuator in case of a rain alarm.								
DPT: Name DPT_Alarm_Reaction DPT ID 23.002 Datatype format							N ₂		
Field			Description			Sup.	Range	Unit	Default
Mode	}		- 0 = no reaction, alar	rm is not us	sed	М	[0 to 2]		CS
			- 1 = up						
- 2 = down									
Comi	munication	າ:						_	
DP	Address:		IO Type(ID):	800 (SAB)	Property ID: 141			
(in t	he server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	/rite	\boxtimes		
Pro	tection		Read level			Write	elevel		
Exce	ption Hand	lling:	Value after Powerup:	Stored \	/alue 🛚	Act Va	alue 🔲 Defa	ult Value)
Spec	ial Feature	s:				•		•	
						•		•	

1.5.54 Parameter ReactionFrostAlarm

FB:	SAB	Propert	y Name (<u>Server</u>):	ReactionFi	ostAlarr	m	Mandatory	Op ^t	tional 🛚
Desc	ription:			-			_		
Parar	meter to def	ine the b	ehaviour of the actu	ator in case	of a fros	t alarm.	•		
DPT:	DPT: Name DPT_Alarm_Reaction DPT ID 23.002 Datatype format N ₂								
Field Description Su					Sup.	Range	Unit	Default	
Mode)		- 0 = no reaction, al	arm is not us	ed	M	[0 to 2]		cs
			- 1 = up						
			- 2 = down						
Com	munication):				-			
	Address:		IO Type(ID):	800 (SAB)		erty ID:	142	
(in t	the server)		Start-Index:	1		N° of	elements	1	
Pro	perty acce	ss:	Read only		Read/W	√rite	\boxtimes		
Pro	tection		Read level			Write	elevel		
Exce	ption Hand	lling:	Value after Powerup	: Stored \	∕alue ⊠	Act Va	alue 🗌 🛮 Defa	ault Value	
Spec	ial Feature	s:							

1.5.55 Parameter TimeoutWindAlarm

FB:	SAB	Proper	ty Name (<u>Server</u>):	TimeoutW	indAlarm		Mandator	y 🔲 Opt	ional 🛚
Desc	ription:	-	-				-		
This	This parameter defines the timeout period for receiving a message on input WindAlarm								
DPT:	Name	DPT_T	imePeriodMin	DPT ID	7.006	Da	tatype format	U ₁₆	
Field			Description			Sup.	Range	Unit	Default
Time	PeriodMin		Timeout on WindAla	rm input		M	cs	min	CS
Com	municatio	ո։				_	-	-	_
DP	Address:		IO Type(ID):	800(SAB)		Prope	erty ID:	143	
(in	the server)		Start-Index:	1 N° of elements		1			
Pro	perty acce	ess:	Read only		Read/W	/rite	\boxtimes		
Pro	tection		Read level			Write	level		
Exce	ption Hand	dling:	Value after Powerup:	Stored \	/alue ⊠	Act Va	alue 🗌 🛮 Def	fault Value	e 🗌
Spec	ial Feature	es:							
		•							•

1.5.56 Parameter TimeoutRainAlarm

FB:	SAB	Proper	ty Name (<u>Server</u>):	TimeoutRa	ainAlarm		Mandatory ☐ Optional ⊠			
Description:										
This parameter defines the timeout period for receiving a message on input RainAlarm										
DPT: Name DPT_T		imePeriodMin	DPT ID 7.006		Da	tatype format	U ₁₆			
Field			Description			Sup.	Range	Unit	Default	
TimePeriodMin			Timeout on RainAlarm input			М	CS	min	CS	
Communication:										
DP Address:			IO Type(ID):	800(SAB)		Property ID:		144		
(in the server)			Start-Index:	1		N° of	elements	1		
Property access:			Read only		Read/W	'rite	\boxtimes			
Protection			Read level			Write	level			
Exception Handling:			Value after Powerup: Stored Value ⊠			Act Value Default Value				
Special Features:										

1.5.57 Parameter TimeoutFrostAlarm

FB:	SAB	Prope	rty Name (<u>Server</u>):	TimeoutFrostAlarm			Mandatory Optional				
Description:											
This parameter defines the timeout period for receiving a message on input FrostAlarm											
DPT:	DPT: Name DPT_Ti		imePeriodMin	DPT ID	7.006	Da	tatype format	type format U ₁₆			
Field			Description			Sup.	Range	Unit	Default		
TimePeriodMin			Timeout on FrostAlarm input			М	CS	min	CS		
Communication:											
DP Address:			IO Type(ID):	800(SAB)		Property ID:		145			
(in the server)			Start-Index:	1		N° of elements		1			
Property access:			Read only		Read/W	/rite	\boxtimes				
Protection			Read level		Write level						
Exception Handling: Value after Pov				: Stored '	Value 🛚	Act Va	alue 🔲 🛮 De	fault Valu	е 🗌		
Special Features:											