

Application Descriptions

HVAC ObIS

Fan Actuator Continuous – Position Driven

Summary

This object is used to control a fan continuously depending on the continuous actuating values. This ObIS allows e.g. in combination with the other ObIS for HVAC to control a fan coil unit with one or two heat exchangers.

Version 01.00.01 is a KNX Approved Standard.

This document is part of the KNX Specifications v2.1.

7

19

10

Document updates

Version	Date	Modifications
1.0	2002.04.04	Editorially restyled, based on "05-02_ObIS_FAC-PD.doc"
1.0	2009.06.15	Editorial update in view of inclusion in the KNX Specifications v2.0.
01.00.01	2013.10.29	Editorial updates for the publication of KNX Specifications 2.1.

References

None.

Filename: 07_19_10 OblS FAC-PD v01.00.01 AS.docx

Version: 01.00.01

Status: Approved Standard

Savedate: 2013.10.29

Number of pages: 13

Contents

1	Appli	cation Model(s)	4
2	ObIS	Function Model(s)	5
		ObIS Function Model "Fan Actuator Continuous-Position Driven"	
	_	.1.1 Aims and objectives	
	2.	.1.2 Functional specification	5
	2.	.1.3 Constraints	
	2.	.1.4 Functional Block	6
	2.	.1.5 Priority of the Inputs	6
	2.	.1.6 Properties	7
3	Datar	point Type(s)	12
		Datapoint Type "Fan Actuator Status"	
		Datapoint Type "8-bit unsigned integer with special function for zero"	
		Datapoint Type "Boolean"	

1 Application Model(s)

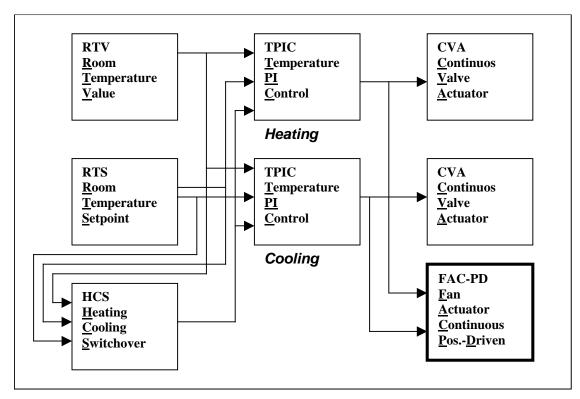


Figure 1 - Application of the ObIS "Fan Actuator Continuous-Position Driven" for Individual Room Temperature Control with a Fan Coil Unit

2 ObIS Function Model(s)

2.1 ObIS Function Model "Fan Actuator Continuous-Position Driven"

2.1.1 Aims and objectives

This object is used to control a fan continuously depending on the continuous actuating values. This ObIS allows e.g. in combination with the other ObIS for HVAC (see Figure 1) to control a fan coil unit with one or two heat exchangers.

2.1.2 Functional specification

This ObIS controls the fan speed continuously depending on the continuous actuating values. The fan speed may be the same as well for heating mode as for cooling mode (if no parameters for cooling mode are defined). The fan speed will be different for heating and for cooling mode if separate parameters are defined.

The fan speed also depends on the optional Inputs "Manual Override Enable" and "Manual Override Fan Speed" and on the Input "Forced Fan Speed Enable" and the parameter "Forced Fan Speed". The priority of these Inputs is defined in clause 2.1.5 "Priority of the Inputs" below. The FAC status information is an optional output.

2.1.3 Constraints

No constraints are defined for the ObIS Fan Actuator Continuous – Position Driven.

2.1.4 Functional Block

2.1.4 Functional Block					
<u>Input(s)</u>		Fan Actuate Continuou Position Driv	ıs		Output(s)
Continuous Actuating Value	DPT 5.001	CAV	FSP	DPT 5.001 	Fan Speed in Percent
Continuous Actuating Value Cooling	DPT 5.001	CAVC	FACS	See 3.1	Fan Actuator Continuous Status
Manual Override Enable	See 3.3 DPT	MOE			
Manual Override Fan Speed	5.001	MOS			
Forced Fan Speed Enable	See 3.3	FFSE			
Parameter(s)					
CAV for FSP = 0%	DPT 5.001	CAVFS0			
CAV for FSP = 100%	DPT 5.001	CAVFS100			
Cooling CAV for FSP = 0%	DPT 5.001	CCAVFS0			
Cooling CAV for FSP = 100%	DPT 5.001	CCAVFS10			
Forced Fan Speed	DPT 5.001	FFS			
Delta Transmit Fan Speed	DPT 5.001	DTFS			
Transmit Cycle Time Fan Speed Transmit FACS	See 3.3 see 3.4	TCTFS			
On Change Enable		TFACSE			
Transmit Cycle Time FACS	See 3.3	TCTFACS			

2.1.5 Priority of the Inputs

The Fan Speed is controlled by the Inputs "Manual Override Enable" and "Forced Fan Speed Enable". The priority of these Inputs is shown in the table below:

Table 1 - Priority rules for the ObIS FAC-PD

Manual Override Enable MOE	Forced Fan Speed Enable FFSE	Fan Speed
0	0	Fan Speed in Percent FSP
0	1	Forced Fan Speed FFS
1	0	Manual Override Fan Speed MOS
1	1	Manual Override Fan Speed MOS

2.1.6 Properties

ID	Name	Abbr.	Description	Datapoint Type	M/O
1	PID_OBJECT_TYPE		Object Type	KNX_PropD ataType	М

Input(s)

ID	Name	Abbr.	Description	Datapoint Type	M/O
<tbd></tbd>	PID_VALUE_ACTUATING CONTINUOUS_HEATING	CAVH	Continuous Actuating Value Heating	DPT 5.001	М
<tbd></tbd>	PID_VALUE_ACTUATING CONTINUOUS_COOLING	CAVC	Continuous Actuating Value Cooling	DPT 5.001	0
<tbd></tbd>	PID_OVERRIDE_MANUAL_ENABLE	MOE	Manual Override Enable	See 3.3	0
<tbd></tbd>	PID_OVERRIDE_MANUAL_SPEED _FAN	MOS	Manual Override Fan Speed	DPT 5.001	0
<tbd></tbd>	PID_FAN_SPEED_FORCED_ENAB LE	FFSE	Forced Fan Speed Enable	See 3.3	0

Output(s)

ID	Name	Abbr.	Description	Datapoint Type	M/O
<tbd></tbd>	PID_SPEED_FAN_PERCENT	FSP	Fan Speed in Percent	DPT 5.001	0
<tbd></tbd>	PID_STATUS_FAN_ACTUATOR	FACS	Fan Actuator Continuous	See 3.1	0
	CONTINUOUS		Status		

Parameter(s)

ID	Name	Abbr.	Description	Datapoint Type	M/O
<tbd></tbd>	PID_ACTUATING_VALUE CONTINUOUS_FSP0	CAVFS0	Continuous Actuating Value for FSP = 0%	DPT 5.001	M
<tbd></tbd>	PID_ACTUATING_VALUE CONTINUOUS_FSP100	CAVFS100	Continuous Actuating Value for FSP = 100%	DPT 5.001	М
<tbd></tbd>	PID_ACTUATING_VALUE CONTINUOUS_FSP0_COOLING	CCAVFS0	Continuous Actuating Value for FSP = 0 % at Cooling	DPT 5.001	0
<tbd></tbd>	PID_ACTUATING_VALUE CONTINUOUS_FSP100_COOLING	CCAVFS1 00	Continuous Actuating Value for FSP = 100 % at Cooling	DPT 5.001	0
<tbd></tbd>	PID_FAN_SPEED_FORCED	FFS	Forced Fan Speed	DPT 5.001	0
<tbd></tbd>	PID_TRANSMIT_DELTA_SPEED FAN	DTFS	Delta Transmit Fan Speed	DPT 5.001	0
<tbd></tbd>	PID_TRANSMIT_CYCLE_TIME SPEED_FAN	TCTFS	Transmit Cycle Time Fan Speed	See 3.2	0
<tbd></tbd>	PID_ENABLE_TRANSMIT_FACS_ ON_CHANGE	TFACSE	Transmit FACS on Change Enable	See 3.3	0
<tbd></tbd>	PID_TRANSMIT_CYCLE_TIME FACS	TCTFACS	Transmit Cycle Time FACS	See 3.2	0

2.1.6.1 Property PID_VALUE_ACTUATING_CONTINUOUS

CAV

Unit: %
Range: 0..100

Default Value: Communication Object/Parameter: C
Input/Output: I

R/W Rate $\gg 10/day$

Description: Fan Coil Units may be supplied by two pipes or three/four pipes.

Fan Coil Units with two pipes:

This is the positioning command used for calculating the fan speed based on

the parameters CAVFS0 .. CAVFS100. Fan Coil Units with three/four pipes:

This is the positioning command for the heating valve, used for calculating the fan speed steps based on the parameters CAVFS0...CAVFS100.

2.1.6.2 Property PID_VALUE_ACTUATING_CONTINUOUS_COOLING

CAVC

Unit: %
Range: 0 ... 100

Default Value: Communication Object/Parameter: C
Input/Output: I

R/W Rate $\gg 10/day$

Description: This is the positioning command for the cooling valve (see ObIS TPIC). It is

used for calculating the fan speed either based on the parameters CAVFS0 and CAVFS100 or (in case of different speeds for the cooling mode) based on the parameters CCAVFS0 and CCAVFS100. This communication object

CAVC is only available in Fan Coil Units with three/four pipes.

2.1.6.3 Property PID OVERRIDE MANUAL ENABLE

MOE

Unit Range: 0,1
Default Value: 0
Communication Object/Parameter: C
Input/Output: I
R/W Rate < 1/day

Description: This object serves to switch over the fan from automatic mode (0) to manual

mode (1). In manual mode the Input Manual Override Fan Speed MOS is

used for the Fan Speed in Percent FSP.

2.1.6.4 Property PID_OVERRIDE_MANUAL_SPEED_FAN

MOS

Unit %
Range: 0 .:. 100
Default Value: Communication Object/Parameter: C
Input/Output: I
R/W Rate < 1/day

Description: The Input Manual Override Fan Speed MOS is used for manual control of

the Fan Speed in Percent FSP.

2.1.6.5 Property PID_FAN_SPEED_FORCED_ENABLE

FFSE

Unit Range: 0,1
Default Value: 0
Communication Object/Parameter: C
Input/Output: I
R/W Rate < 1/day

Description: This Input Forced Fan Speed Enable FFSE is used to switch the Fan Speed

in Percent FSP to a predefined value. This value is defined as parameter

FFS (see 2.1.6.12).

2.1.6.6 Property PID_SPEED_FAN_PERCENT

FSP

Unit: %
Range: 0-100
Default Value: Communication Object/Parameter: C
Input/Output: O
R/W Rate >> 1/day
Description: .This is the actual fan speed in percent.

2.1.6.7 Property PID_STATUS_FAN_ACTUATOR_CONTINUOUS

FACS

Unit: Range: Default Value: Communication Object/Parameter: C
Input/Output: O

R/W Rate >> 10/day

Description: This object contains several information about the fan actuator status (see

3.1).

2.1.6.8 Property PID_ACTUATING_VALUE_CONTINUOUS_FSP0

CAVFS0

Unit: %

Range: min 0 ... 30

Default Value:

Communication Object/Parameter:

Input/Output:

R/W

R/W Rate

- P

R/W

- A/W

Description: This parameter defines the continuous actuating value up to which the fan

speed is 0 %. This parameter is used for both heating and cooling if no separate parameters for cooling (CCAVFS0 and CCAVFS100) are

available.

2.1.6.9 Property PID_ACTUATING_VALUE_CONTINUOUS_FSP100 CAVFS100

Unit: %

Range: min 1 ... 100

Default Value: Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: This parameter defines the continuous actuating value at which the fan

speed becomes 100 %. This parameter is used for both heating and cooling if no separate parameters for cooling (CCAVFS0 and CCAVFS100) are

available.

2.1.6.10 Property PID_ACTUATING_VALUE_CONTINUOUS_FSP0_COOLING

CCAVFS0

FFS

Unit: %

Range: min 0 ... 30

Default Value: Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: This parameter defines the continuous actuating value for cooling mode up

to which the fan speed is 0 %.

2.1.6.11 Property PID_ACTUATING_VALUE_CONTINUOUS_FSP100_COOLING CCAVFS100

Unit: %

Range: min 1 ... 100

Default Value: Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: This parameter defines the continuous actuating value for cooling mode at

which the fan speed becomes 100 %.

2.1.6.12 Property PID_FAN_SPEED_FORCED

Unit %

Range: 0 .. 100 Default Value: -

Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: This parameter is used as Fan Speed in Percent FSP if the Forced Fan

Speed Enable FFSE object is set.

2.1.6.13 PID_TRANSMIT_DELTA_SPEED_FAN

DTFS

Unit: %

Range: min 0 ... 20

Default Value: 5
Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: The Fan Speed in Percent FSP will be transmitted automatically if the

difference between the last transmitted FSP and the current FSP is greater than the given delta value. It will not be transmitted automatically if DTFS

is set to "0".

2.1.6.14 PID_TRANSMIT_CYCLE_TIME_SPEED_FAN

TCTFS

Unit: minutes Range: min 0, 15..60

Default Value: 0
Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: The Fan Speed in Percent FSP will be transmitted cyclically after the given

cycle time. It will not be transmitted cyclically if the cycle time is set to

"0".

2.1.6.15 PID_ENABLE_TRANSMIT_FACS_ON_CHANGE

TFACSE

Unit: Range: 0,1
Default Value: 1
Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: The parameter defines whether the Fan Actuator Continuous Status FACS

will be transmitted on change (1) or not (0).

2.1.6.16 PID_TRANSMIT_CYCLE_TIME_FACS

TCTFACS

Unit: minutes
Range: min 0, 15..60

Default Value: 0
Communication Object/Parameter: P
Input/Output: R/W
R/W Rate << 1/day

Description: The status object Fan Actuator Continuous Status FACS will be

transmitted cyclically after the given cycle time. It will not be transmitted

cyclically if the cycle time is set to "0".

3 Datapoint Type(s)

3.1 Datapoint Type "Fan Actuator Status"

Format:	1 octet							
	EEEE DCBA	EEEE DCBA						
Encoding:	See below							
Range:	AD= {0,1}							
<u>Unit:</u>	-							
Datapoint	Types							
Code:	Symbol:	Encoding:						
<tbd></tbd>	<tbd></tbd>	A: 0 = automatic; 1 = manual/forced (1) B: 0 = heating; 1 cooling C: 0 = CAV = 0 1 = CAV > 0 (0 = heating valve closed) D: 0 = CAVC = 0 1 = CAVHC > 0 (0 = cooling valve closed) E reserved; shall be 0						

(1) B = 1 if MOE or FFSE = 1

3.2 Datapoint Type "8-bit unsigned integer with special function for zero"

	_	0	2				
Format:	1 octet						
	VVVVVV	V					
Encoding:	See below						
Range:	V = [02	255] binary encoded					
<u>Unit:</u>	See below						
Datapoint	Datapoint Types						
Code:	Symbol:	Encoding:	Range:	<u>Unit</u> :			
<tbd></tbd>	<tbd></tbd>	"time"	1255	1 min			
			0 = corresponding function disabled				

3.3 Datapoint Type "Boolean"

Format:	1 bit		
	V		
Encoding :	See below		
Range:	$V = \{0,1\}$		
<u>Unit:</u>	-		
Datapoint	Types		
Code:	Symbol:	Encoding: V = 0	V = 1
1.003	MOE (Manual_Overide_Enable)	disable	enable
1.003	TFACSE (Transmit On Change Enable)	disable	enable
1.003	FFSE (Forced Fan Speed Enable)	disable	enable