

Application Descriptions

Common Functional Blocks

Common Sensors

Summary

This document specifies Common Sensor Functional Blocks.

Version 01.01.02 is a KNX Approved Standard.

This document is part of the KNX Specifications v2.1.

7

1

2

Document updates

Version	Date	Modifications
0.1	2005.02.14	Document created
0.2	2005.05.12	APS updated according to TFI inputs
0.3	2005.10.14	Publication of the TFI approved version.
0.4	2006.02.01	Added FB Scene Sensor
	2006.05.09	FB Scene Sensor
		 added Outputs Scene AB Activate and Scene AB Teach. Combinations specified in Table 2.
		FB Priority Sensor
		First specification proposal.
		FB Lock Sensor
		First specification proposal.
	2006.09.18	TF Editing:
		Inclusion of the feedback from TFI of 2006.05.19. See comment below
		Table 2.
		FB Timed Sensor added.
0.4		Publication of the TFI approved version.
0.6	2008.08.09	AN106 "Phasing out TP0" integrated.
		AN107 "Phasing out LT-R" integrated.
		AN108 "Phasing out LT-S" integrated.
		AN109 "Phasing out PL132" integrated.
		AN110 "Phasing out A-Mode" integrated.
1.0 AS	2009.04.27	Publication of the Approved Standard.
01.01.01	2013.09.04	AN150 "FB Profiles for existing FBs" integrated.
		Minor editorial correction.
01.01.02	2013.10.29	Editorial updates for the publication of KNX Specifications 2.1.

Copies with the same version number but a newer save date contain small corrections without impact on the content.

References

[1] Chapter 3/7/2 "Datapoint Types"

[2] Chapter 7/10/10 "HVAC Interface Object Type Identifier"

[3] Part 10/1 "Logical Tag Extended"

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Contents

1	Intr	oduction	4
	1.1	Scope	4
	1.2	Objectives	4
		Dependence on Configuration Modes	
	1.4	Glossary	6
		Abbreviations	
2	Phy	sical Sensor	8
		Atmospheric Pressure Sensor (APS)	
3	Log	ic Functions Blocks	16
		FB Scene Sensor	
	3.2	FB Priority Sensor	22
	3.3	FB Lock Sensor	25
		FB Timed Sensor	

1 Introduction

1.1 Scope

This document is part of the KNX Application Interworking Standard. It contains the specification of Common Sensor Functional Blocks.

1.2 Objectives

This document includes the information necessary to build interoperable sensor products with Functional Blocks of common interest, using the KNX system. Runtime Interworking between the sensor Functional Block and a controller, display etc is the focus. Also data-interfaces for parameter setting, visualisation etc. are specified where appropriate (only state of the art Datapoints generally used in all companies).

In addition, this document specifies the specific mechanisms for zoning and runtime process data distribution used in HVAC for an 'easy installation' system (LTE-HEE Mode [3]).

This is a technical specification with informative material provided as needed to convey key concepts. The approach taken here is a top-down view of interoperability.

Every Functional Block may be part of a complex device (e.g. a heating controller) containing more than one Functional Block. Because of this modular approach, there is no attempt in this specification to describe or dictate the internal construction of a Functional Block or to describe specific device types.

This document only includes details of the transport protocol as needed to specify interoperability and easy installation mechanisms. The document does not specifically cover implementation aspects, but guidelines are included where appropriate.

Completely protocol dependent parts of the sensor specification such as data encoding and Datapoint Types, object address tables, Group Address tables etc. are not part of this document.

1.3 Dependence on Configuration Modes

The main focus of this document is the specification of the **Basic Functional Blocks** and the **LTE specific parts**.

The document provides all necessary information needed

- for a complete implementation of the Functional Blocks in LTE-Mode, and
- for the implementation of mandatory objects used for runtime Interworking in Standard Mode (Basic Functional Block).

1.3.1 Runtime Interworking

Configuration Mode dependent (S-Mode, Ctrl-Mode, PB-Mode) implementation of optional runtime Interworking objects is not specified in this document, e.g. "E-Mode Channel" definitions.

The following table (example) shows the mode dependencies concerning runtime Interworking.

			STANDARD MODE		NDED DDE
		Basic FB	S-Mode	Standard Mode Interface	LTE-HEE
Inputs	Inp1	NA	NA	NA	М
	Inp2	NA	NA	NA	0
	Inp3	(GO _b)		(GO)	0
Outputs	Outp1	NA	NA	NA	М
	- Outp1-1	GO _b	GO	GO	NA
	- Outp1-2	GO _b	GO	GO	NA
	Outp 2	GO _b	GO	GO	М

- Inp1: is mandatory M in LTE-Mode but the information is not available (NA) in the Basic FB and all other modes because the Datapoint Type (DPT) is <u>today</u> not available in Standard Mode and there are no products on the market with this functionality.
- Inp2: is optional O in LTE-Mode but the information is not available (NA) in the Basic FB and all other modes because the DPT is <u>today</u> not available in Standard Mode and there are no products on the market with this functionality.
- Inp3: is optional O in LTE-Mode and an optional Group Object in the Basic FB (GO_b) . The Datapoint is optionally supported as Group Object in the LTE Standard Mode Interface (GO). For all other modes the implementation is not defined. This is indicated by an empty field.
- Outp1: is mandatory M in LTE-Mode and has a structured DPT or a DPT with extended features which is today not available in Standard Mode. In the Basic FB the information of Outp1 is split up into Outp1-1 and Outp1-2 (separate Datapoints with standard DPT).

 Outp1-1 and Outp1-2 are mandatory Group Objects GO in the Basic FB and are therefore mandatory in all modes.

Outp2: is mandatory in all modes.

1.3.2 Parameters and Diagnostic Data

LTE implementation

- Parameters and Diagnostic Data of a Functional Block shall be implemented as Properties of the corresponding Interface Object that are accessed using point-to-point addressing.
- These Properties are addressed via the standard Interface Object Type (IO Type) for this Functional Block. This IO Type is also used for Datapoint addressing in the LTE runtime Interworking model.
- Standard DPT or HVAC specific DPT with extended features are used where appropriate.

Other modes

- Parameters and Diagnostic Data can in principle be implemented as memory mapped Datapoints or Group Objects or Properties of an Interface Object using individual addressing. This document does not lay down how to implement Parameters and Diagnostic Data in S-Mode, Ctrl-Mode and PB-Mode.
- In case of Memory Mapped Datapoints the DPT may be manufacturer specific
- In case of **Group Objects** standard DPT shall be used instead of HVAC specific (extended) DPT. The description of these Group Objects shall be part of the mode-dependent specification (e.g. Channel definition).
- In case of **Properties**, the implementation of HVAC specific DPT with extended features may be a problem (depending on the available microcontroller resources). The manufacturer has the choice:
 - ⇒ to use the LTE style Property implementation as specified in this document (with the DPT and IO Type for LTE implementations) IO Type^{used} = IO Type^{HVAC-LTE}
 - ⇒ to implement these Properties using standard DPT only.

 In this case, the same Property ID but a different IO Type shall be used since the DPT of a Property shall be unambiguous for each IO Type.

Simple IOT mapping rule: IO Type^{used} = IO Type standardDPT = IO Type $^{HVAC-LTE}$ + 10000d

(e.g.
$$BUC^{HVAC-LTE} = 128 \Rightarrow BUC^{standardDPT} = 10128$$
)

⇒ It is allowed to implement in a device both Interface Object Types IO Type^{HVAC-LTE} and IO Type^{standardDPT}. The implementation of parameters and diagnostic data of one given Functional Block shall however be complete. It is thus not allowed to implement part of the Datapoints of a Functional Block in IO Type^{standardDPT} and the remaining in IO Type^{HVAC-LTE}.

	Imp	Implementation of Parameter and Diagnostic Data											
	Proper LTE style	ty based Standard DPT	Group Object	Memory mapped									
ІО Туре	IO Type ^{HVAC-LTE} e.g. BUC=128	IO Type ^{HVAC-LTE} + 10000 e.g. BUC=10128											
Property ID	Property ID x	Property ID x											
	if standard DPT	⇒ same standard DPT	⇒ same standard DPT	company specific									
DPT	if HVAC-LTE specific*) e.g. 205.100	⇒ mapped standard DPT, e.g. 9.001	⇒ mapped standard DPT, e.g. 9.001										

In this document only the **HVAC-LTE style** of Parameters and Diagnostic Data is specified for IO Type HVAC-LTE.

In the FB **D**atapoint overview those Parameters and Diagnostic Data with HVAC-LTE specific (extended) DPT are marked "*"

The mapping of HVAC specific DPT to standard DPT is generic and described in the document [1].

1.4 Glossary

No new terms are introduced in this document.

1.5 Abbreviations

General

Abbreviation	Description
(GO)	Group Object optional
cs	Company Specific
GO	Group Object mandatory
M	Mandatory
NA	Not Allowed / Not Applicable
O	Optional
S	Has to be implemented in Standard Mode, if implemented in LTE-HEE Mode
HEE	HVAC Easy Extension
HVAC	Heating Ventilation Air Conditioning
LTE	Logical Tag Extended
IR	LTE-Service InfoReport
W	LTE-Service Write

2 Physical Sensor

2.1 Atmospheric Pressure Sensor (APS)

2.1.1 Aims and objectives

The Functional Block 'Atmospheric Pressure Sensor' shall measure the absolute air pressure and shall deliver the data to the KNX system. The data may be used for barometer functionality, weather station, displaying etc.

2.1.2 Functional specification

The distribution of the atmospheric pressure in the KNX system shall be event-driven (COV-condition, change of value) and shall in addition be repeated periodically.

In the LTE-Mode the 'Atmospheric Pressure Sensor' shall support <u>LTE outside sensor zoning</u>, i.e. multiple sensor values may be distributed in the system in parallel for different zones. (e.g. OutsideSensorZone_1= 'north', OutsideSensorZone_2= 'south' etc.)

Optional features in LTE-Mode:

- Faults in the sensor device may be detected and reported.
- The sensor value may temporary be overridden by means of a tool for service purposes.

The 'Overridden' condition must be reported.

- Alarm limits may be detected by the sensor and are reported.

The alarm may be acknowledged.

- The sensor may be set / reset out of service by means of a tool for service purposes.

Outputs

• AtmosphericPressureAbs This output shall deliver the atmospheric pressure value to the

bus.

• StatusGO This output shall only be available in Standard Mode and shall

contain the Z₈ information of the output sensor value.

Binding Group (LTE)

• OutsideSensorZone no special features

Parameters

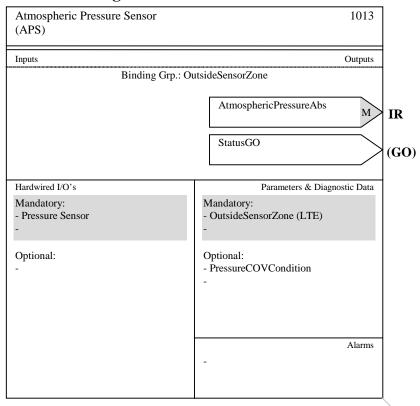
• PressureCOVCondition This parameter shall define the delta pressure value at which the

information shall be transmitted spontaneously.

2.1.3 Constraints

None.

2.1.4 Functional Block diagram



2.1.5 Datapoint Description

Overview

Datapoints	Description / Remarks	Datapoint Type	Additional Info
Outputs			
AtmosphericPressure Abs	Atmospheric pressure value with: - COV and RepPer - Z ₈ STATUS and - Z ₈ COMMAND supported to FB various controller	$ \begin{array}{ll} LTE: & 203.015 \\ DPT_AtmPressureAbs_Z \\ U_{16}Z_8 \\ S: & 9.006 \\ DPT_Value_Pres \\ F_{16} \end{array} $	LTE: M Mbar S: GO Pa
StatusGO	Z ₈ information as a Group Object	LTE: NA S: 21.001 DPT_StatusGen B ₈	LTE: NA S: (GO) Bitset as Z_8
Parameters			
Outside Sensor Zone Pressure COV	LTE zoning number for outside sensor zone Value for COV condition with:	202.002 DPT_UcountValue8_Z U ₈ Z ₈ 203.015 1)	M 1 O
Condition	- Z ₈ not supported	DPT_AtmPressureAbs_Z U ₁₆ Z ₈	cs

¹⁾ Implementation of Properties using standard DPT see clause 1.3.2.

APS Runtime Interworking - Dependence on Configuration Modes

			STANDARD MODE		ENDED IODE	
		Basic FB	S-Mode	Standard Mode Interface	HEE	
Inputs						
Outputs	AtmosphericPressureAbs	GO _b	GO	GO	M	
	StatusGO	(GO _b)		(GO)	NA	

APS LTE specific Properties

		Support
Parameter	OutsideSensorZone	M

APS Standard Properties of Interface Objects (or memory mapped DP)

_		Support
Parameter	PressureCOVCondition	0

2.1.6 Detailed specification of the Datapoints

2.1.6.1 Output Atmospheric Pressure

Standard Mode

DI	P Name:	Atm	osphe	ericPre	ssureA	bs		Α	bbr.:		Manda			itory	
FE	3 Name:	APS	S										Can be	e intern	al 🗌
D	escription														
Tł	This output shall contain the value of the the atmospheric pressure														
D	Datapoint Type														
D	PT_Name:	DPT_Value_Pres													
D	PT Format:		F ₁₆ DPT_ID: 9.006												
Fi	eld	D	escrip	tion							Supp.	R	ange	Unit	Default
FI	oatValue	Th	ne atm	osphe	ric pres	ssure i	n F ₁₆ .				M		Full	Pa	CS
A	Access Type														
◆ Output															
	$this \to M$				this \rightarrow	1									
Spontaneous			s 🛛 COV:		•		Delta Value		cs 1)		MinRepTime:			10 s	
				Cycli	С	\boxtimes	Period: 15 min (recommende					nde	d value	!)	
	Request														
C	ommunicat	tion	Туре												
•	Group Ob	oject	Datap	oint								Ma	andator	y: 🛛	
	Default Gr	oup	Addre	ss:											
D	ynamics														
	Power dov	wn:	Save) :											
	Power up:		Valu	e:	No in	itialisa	tion:		D)efa	ult value:				
					Save	d value	e:		Α	ctua	al value:				
			Tran	smit or	bus:			\triangleright							
E	xception H	andli	ing												
	-														
S	pecial Feat	ures													
1)	COV see	oaraı	meter,	recom	mende	ed valu	ie 20 P	a (0,2 n	nbar)						

LTE-HEE Mode

FB:	APS	LTE Serv	ver Output Name:	Atmospl	AtmosphericPressureAbs				Mandatory Optional			
Desc	ription:							<u> </u>	-			
			the value of the atmo		essure a	s well	as a S	TATUS in	formatio	n. The		
DPT:	Name	DPT_A	tmPressureAbs_Z	DPT ID	203.01	5 Da	atatype	format	U ₁₆ Z ₈			
Field	.		Description	<u>'</u>	Sup.	Rang		Unit	COV	Default		
Atmo	sphericPr	essure	Actual pressure valu	М	Full F	Range	mbar	cs ¹⁾	cs			
STAT	US		For LTE-Service Info and Property-Service Response only				_	Bitset				
	OfService		Sensor out of service		0		false	Bit 0	Υ	false		
- Faul			Sensor value is corru		0		false	Bit 1	Υ	false		
- Ove	rridden		Sensor is temporarily	У	0	true/	false	Bit 2	Y	false		
- InAla	arm		overridden Sensor is in alarm		0	true	false	Bit 3	Y	false		
	mUnAck		Acknowledgement of	f alarm	ő	1	false	Bit 4	Ϋ́	false		
	ner bits		reserved		NA			Bit 5-7	Y	false		
						J.		Sup.	Range			
СОМ	MAND		For Property-Service		enum							
- Ove	rride / Re	lease	Temporary override			value		0	1/2			
	/ Reset O			Set / reset of out of service								
- Alar	mAck		Acknowledgement of	cknowledgement of alarm								
- all o	ther comr	nands		NA								
Comi	municatio	n:										
Bin	ding Gro	up:	_									
Clas	SS		Туре	Type Defau								
Ge	eographic	al 🗌										
Ap	plication	Specific $oxtime \Sigma$	OutsideSensorZon									
Ur	nassigned		Broadcast	Broadcast Configurable								
DP	Address:		IO Type(ID):	1013 (APS	3)	Prop	erty ID): 5	1			
LTE	-Services	s (event):	cov ⊠ ı	MinRepTim	ne:	10 s	6	Hearth	eat:	15 min		
Inf	oReport	\boxtimes	Output per default	communica	ating 🖂	Bind	ing Gro	oup Wildo	ard allov	ved 🗌		
(L	TE Read-		Tx Prio:	High 🗌		N	ormal [Low	<u> </u>		
the	esponse p e output s ways be s	hall	Transm after Powe	r-up: Store	d Value		Act Val	lue 🛛 🏻 🗅	efault V	alue 🗌		
	perty-Ser lividual a		Read only		Read/\	Vrite	\boxtimes					
Exce	ption Har	ndling:						Save a	t Powerd	down		
Spec	ial Featur	es:										
1) C(DV see pa	arameter,	recommended value	0,2 mbar								

2.1.6.2 Output StatusGO

LTE-HEE Mode

Not applicable.

Standard Mode

DP	Name:	Stat	tusGO)					Abbr.	:		Mandatory			
FB I	Name:	APS	3									Can be	e intern	al	
Des	cription														
This output contains the Z ₈ status information as a Group Object.															
Datapoint Type															
DP1	Γ_Name:	DI	PT_StatusGen												
DP1	Γ Format:	B ₈	B ₈ DPT_ID: 21.001												
Field	d		escript								Supp.	Range	Unit	Defa	ult
Stat					rmation						0	Bitset		cs	
Bit			utOfSe	ervice							0 0		t/f		
Bit Bit			ault verrido	don							0		t/f t/f		
Bit			Alarm								0		t/f		
Bit	-				owledg	ed					Ö		t/f		
Bit	s 57		serve		Ū						NA				
Acc	Access Type														
•	Output														
t	his → M				this \rightarrow	1									
3	Spontaneo	us		CO	/ :	: Delta-Value: I				MinRepTir	MinRepTime: 10 s				
				Сус	lic	Period: 15 min (recomme					nended valu	ended value)			
F	Request														
Con	nmunicati	ion T	Гуре												
*	Group Ob	ject	Datap	oint								Mandator	y: 🛛		
	Default Gro	oup .	Addre	ss:											
Dyn	namics														
F	Power dow	n:	Save) :											
F	Power up:		Value	e:	No ir	nitialisa	ation:			Def	fault value:				
					Save	d valu	ıe:			Act	ual value:				
Transmit on bus:															
Exc	eption Ha	ndli	ng												
Spe	cial Featu	ıres													

2.1.6.3 Parameter OutsideSensorZone

FB: APS	S	Property	Name (<u>Server</u>):	Outsid	eSensorZoi	ne		Mandatory Optional	, ⊠ □
Description	on:			-					
Number o	f the	outside se	ensor zone.						
DPT: N	lame	DPT_U	countValue8_Z	DPT ID	202.002	Dataty	oe format	U ₈ Z ₈	
Field			Description			Sup.	Range	Unit	Default
Sensor Zo	one		Number of the se	ensor zone)	М	131		1
STATUS	TUS					Bitset			
- OutofService zone active / inactive			0	true/false	Bit 0	false			
- all other	bits		not supported, fixed to '0'			NA			false
COMMAN	1D	D				enum		cs	
	· NormalWrite			М	0				
- SetOSV			Set zone inactive	/ active		0	3 / 4		
ResetOS\	-								
- all other			not supported			NA			
Commun	icatio	on:							
DP Add			IO Type(ID):	1013	(APS)	Prope	rty ID:	101	
(in the s	serve	r)	Start-Index:	1		N° of e	elements	1	
Property	у асс	ess:	Read only		Read/	Write			
Protecti	ion		Read level	-		Write	level	-	
Exception	n Har	ndling:	Value after Powe	er-up: St	ored Value	⊠ Act V	/alue 🔲 🏻 🖸	efault Val	ue 🗌
Zone = 0	Zone = 0 (wildcard) NOT allowed								
Special Features:									
The device	e is n	ot LTE co	mmunicating in th	nis zone if	zone is 'Out	tOfServio	e'		

2.1.6.4 Parameter PressureCOVCondition

FB:	APS	Property	y Name (<u>Server</u>):	PressureCOVCondition				Mandatory [Optional				
Desc	ription:						<u>.</u>					
Delta	Delta pressure value for COV condition											
DPT:	Name	DPT_A	AtmPressureAbs_Z	mPressureAbs_Z DPT ID 20			Datat	ype 1	format	U.	$U_{16}Z_{8}$	
Field			Description			Sup.	Range		Unit		Defau	lt
Atmo	spericPre	essure	pressure COV valu	ıe		0	Full Rang		mbar		0,2 mba	ar*)
STATUS									Bitset			
- all bits			not supported, fixed to '0'			NA					false	
COMMAND							enun	า			cs	
- NormalWrite					M	0						
- all c	ther com	mands	not supported			NA						
	municati											
	Address		IO Type(ID):	•	1013 (APS	S)	Property	/ ID:	•	112		
(in	the serve	er)	Start-Index:	•	1		N° of ele	emer	nts	1		
Pro	perty ac	cess:	Read only			Read/W	rite					
Pro	tection		Read level	-	-		Write le	vel	-	-		
Exce	ption Ha	ndling:	Value after Power	-up	: Stored	Value 🗵	Act Va	lue [] De	faul	lt Value [
		•			•			•	•			
Spec	Special Features:											
			_		•			•				

The resolution of typical sensor elements is 0,1 mbar.

During exceptional storms like "Lothar" the atmospheric pressure changed 15 mbar within 6 hours.

This is a change of 0,625 mbar in 15 min (heartbeat). In case of storm "Lothar" a message would be generated approximately every 5 minutes with a COV of 0,2 mbar. This is sufficient to generate storm warnings or to calculate a tendency.

DPT_AtmPressureAbs_Z (203.015) is specified in [1]. In Standard Mode, DPT_Value_Pres (9.006) shall be used.

^{*)} recommended COV = 0.2 mbar (= 0.2 hPa).

3 Logic Functions Blocks

3.1 FB Scene Sensor

3.1.1 Aims and objectives

The FB Scene Sensor shall be used to call and teach scenes in other FBs.

The implementation of this functionality is not restricted to push buttons only. It may for instance be implemented in a larger controller, scheduler, gateway, weather station ...

3.1.2 Functional specification

3.1.2.1 Scene Control without learning

The output DP Scene Control shall allow for teaching scenes in the receivers. It is optionally allowed to support this DP limiting the functionality to solely calling scenes without teaching, under the condition that the parameter Scene Teaching Enable is implemented.

If no scene teaching is supported or can be activated, than the DP Scene Number shall be used.

3.1.2.2 Scene number range

The number of scene numbers that can be supported is manufacturer specific.

This range of supported scene numbers does not have to start at 0 and does not have to be continuous.

3.1.3 Constraints

None.

3.1.4 Functional Block diagram

	FB Scene Sensor	
Inputs		Outputs
	Scene Control	(SC)
	Scene Number	(SN)
	Scene AB Activate	(SABA)
	Scene AB Teach	(SABT)
additional I/Os		Parameters
	Scene Teaching Enable	(STE)

3.1.5 Datapoint description

Table 1 – Datapoint overview

Datapoint	Description/Remarks	Datapoint Type
Outputs		
Scene Control	To call or teach a scene identified by the contained scene number in the receiver.	DPT_SceneControl (18.001)
Scene Number	To call a scene identified by the contained scene number in the receiver.	DPT_SceneNumber (17.001)
Scene AB Activate	To call one out of two scenes.	DPT_Scene_AB (1.022)
Scene AB Teach	To teach one out of two scenes.	DPT_Scene_AB (1.022)

Datapoint Description/Remarks		Datapoint Type							
Inputs									
None.									
Parameters	Parameters								
Scene Teaching Enable	Allows for limiting the output Scene Control to calling scenes without learning possibility.	DPT_Enable (1.003)							

FB Profiles

		Standard Mode						
Features and options	Basic FB	FB profile 1	FB profile 2	FB profile 3	FB profile 4			
SABA	0	GO	GO	(GO)	(GO)			
SABT	0	(GO)	GO	(GO)	(GO)			
SN	0	(GO)	(GO)	GO	(GO)			
// Full Scene Control								
SC	0	(GO)	(GO)	(GO)	GO			
IF Scene Teaching can be disabled								
STE	0	0	0	0	М			

Figure 1 – FB Profiles for the FB Scene Sensor

The FB Profiles 1 and 2 use DPT_Scene_AB for activating and teaching scenes in the receivers. The number of scenes is by this limited to two. These Outputs are mainly modelled for compatibility with E-Mode channel specifications. For S-Mode realisations, these flavours are not recommended.

This FB Scene Sensor features a DP Scene Control, that shall allow teaching scenes in the receiver and a DP Scene Number that only supports calling scenes without teaching.

		Combination								
	Without	teaching	With teaching							
Datapoints	1a	1b	2a	2b						
SN	М	0	0	0						
SABA	0	М	0	М						
SC	0	0	М	0						
SABT	0	0	0	М						

Table 2 - Combination of mandatory Datapoints

The flavours 1b and 2b use DPT_Scene_AB for activating and teaching scenes in the receivers. The number of scenes is by this limited to two. These Outputs are mainly modelled for compatibility with E-Mode channel specifications. For S-Mode realisations, these flavours are not recommended.

3.1.6 Detailed specification of Datapoints

3.1.6.1 Output Scene Control (SC)

FB Name: FB Scene Sensor	DP Name:	Scene Control		Abbr.:	SC		Mano	latory			
This output shall be used to call or teach a scene identified by the contained scene number in the receivers. The maximal scene number that is supported is company specific. Datapoint Type DPT_Name:	FB Name:	FB Scene Ser	nsor				Can b	oe interna	al 🔲		
Teceivers. The maximal scene number that is supported is company specific. Datapoint Type DPT_Name: DPT_SceneControl DPT Format: B ₁ f ₁ U ₆ DPT_ID: 18.001 Field Supp. Range Unit Default C Shall indicate whether the contained scene number shall be taught or called. SceneNumber Scene number. M ⟨0, 1⟩ none None Access Type ♦ Output this → M Spontaneous COyclic Deriod: Request Cyclic Default Coyclic Default Group Address: Default Group Address: Saved value: Current value (not for input): Transmit on bus (only for output): Exception Handling None. Special Features											
The maximal scene number that is supported is company specific. Datapoint Type DPT_Name: DPT_SceneControl DPT Format: B ₁ r ₁ U ₆	This output sha	all be used to ca	all or teach a scene ident	tified by th	e containe	ed scen	e num	ber in th	е		
Datapoint Type DPT_Name: DPT_SceneControl DPT Format: B₁r₁U6											
DPT_Name: DPT_SceneControl DPT Format: B₁r₁U₀ Supp. Range Unit Default C Shall indicate whether the contained scene number shall be taught or called. M {0, 1} none None SceneNumber Scene number. M cs none None Access Type Φ Output Winstance Winstance Winstance Winstance None Spontaneous COV: A-Value: Minstance Winstance Wi											
DPT Format: B ₁ r ₁ U ₆		· • • • • • • • • • • • • • • • • • • •									
Field Supp. Range Unit None Default C Shall indicate whether the contained scene number shall be taught or called. M {0, 1} none None SceneNumber Scene number. M cs none None Access Type Φ Output Min repetition time: Image: None None Access Type Φ COV:											
C Shall indicate whether the contained scene number shall be taught or called. SceneNumber Scene number. Access Type ◆ Output this → M	1110										
Number shall be taught or called. Scene Number Scene number. M CS none None								Unit			
Scene Number Scene number. M Cs none None Access Type Output this → M	C				M	{0,	1}	none	None		
Access Type this → M □ this → 1 □ Spontaneous □ COV: □ □ A-Value: □ Min repetition time: □ Request □ Period: □ Request □ Communication Type ◆ Group Object Datapoint □ Mandatory: □ Default Group Address: □ Default Group Address: □ Dynamics Power down: Save: □ No initialisation: □ Default value: □ □ Power up: Value: No initialisation: □ Current value (not for input): □ □ Saved value: □ Current value (not for input): □ □ Exception Handling None. Special Features											
Voltput this → M Image: second of the content of		Scene numb	er.		M	CS	3	none	None		
this → M	Access Type										
Spontaneous											
Cyclic Period: Request Communication Type	this \rightarrow M $ \square $ this \rightarrow 1 $ \square $										
Request ☐ Communication Type Group Object Datapoint	Spontaneou				M	in repe	tition t	ime:			
Communication Type ◆ Group Object Datapoint		Cyclic	Period:								
◆ Group Object Datapoint Mandatory: Default Group Address: Dynamics Power down: Save: Power up: Value: No initialisation: Default value: Saved value: Current value (not for input): Transmit on bus (only for output): Read from bus (only for input): Exception Handling None. Special Features											
Default Group Address: Dynamics Power down: Save: Power up: Value: No initialisation: Default value: Current value (not for input): Transmit on bus (only for output): Read from bus (only for input): Exception Handling None. Special Features											
Dynamics Power down: Save: □ Power up: Value: No initialisation: □ Default value: □ Saved value: □ Current value (not for input): □ Transmit on bus (only for output): □ Read from bus (only for input): □ Exception Handling None. Special Features	♦ Group Object	ect Datapoint				Ma	andato	ry: 🛮 🖂			
Power down: Save: Power up: Value: No initialisation: Default value: Saved value: Current value (not for input): Transmit on bus (only for output): Read from bus (only for input): Exception Handling None. Special Features	Default Gro	up Address:									
Power up: Value: No initialisation: Saved value: Current value (not for input): Transmit on bus (only for output): Exception Handling None. Special Features	Dynamics										
Saved value: Current value (not for input): Transmit on bus (only for output): Exception Handling None. Special Features	Power down	n: Save:									
Transmit on bus (only for output): Read from bus (only for input): Exception Handling None. Special Features	Power up:	Value:	No initialisation:		efault valu	ıe:					
None. Special Features			Saved value:		urrent valu	ue (not	for inp	out):			
None. Special Features		Transmit or	n bus (only for output):	□ R	ead from l	bus (on	ly for i	nput):			
Special Features	Exception Han	dling									
	None.					·					
None.	Special Feature	Special Features									
	None.										

3.1.6.2 Output Scene Number (SN)

DP Name:	Scene Number	ſ	Abbr.:	SN		Mand	atory			
FB Name:	FB Scene Sens	sor				Can b	e interna	al 🗌		
Description										
	This output shall be used to call a scene identified by the contained scene number in the receivers.									
The maximal scene number that is supported is company specific.										
Datapoint Type										
DPT_Name: DPT_SceneNumber										
DPT Format:	r ₂ U ₆			DPT_		17.00	1			
Field				Supp.	Rar	nge	Unit	Default		
SceneNumber	Scene number	er to be called		M	С	S	none	None		
Access Type										
♦ Output										
this \rightarrow M	\boxtimes this \rightarrow	1 📗								
Spontaneou	ıs 🛛 🖾 COV:	\[\Delta\-\D		M	in repe	etition t	ime:			
	Cyclic	Period:								
Request										
Communication	n Type									
♦ Group Obj	ect Datapoint				M	andato	ry: 🛛 🖂			
Default Gro	up Address:									
Dynamics										
Power down	n: Save:									
Power up:	Value:	No initialisation:		Default valu	ıe:					
		Saved value:		Current valu	•					
	Transmit on	bus (only for output):		Read from I	bus (or	nly for i	nput):			
Exception Han	dling									
None.										
Special Featur	es									
None.										

3.1.6.3 Output Scene AB Activate (SABA)

DP Name:	Scene AB Acti	vate	Abbr.:	SABA	Mano	latory				
FB Name:	FB Scene Sen	sor			Can l	oe interna	al 🗌			
Description										
	This Output shall be used to activate one out of two possible scenes in the receivers.									
	DP is not recon	nmended for S-Mode a	pplications	. DP Scene Nu	mber sh	iould be ι	ısed			
instead.										
Datapoint Type										
DPT_Name:	DPT_Scene_A	AB .								
DPT Format:	B ₁			DPT_ID:	1.022					
Field					ange	Unit	Default			
b	•	which of the scenes A	or B	M {0	0, 1}	none	None			
	shall be calle	<u>d.</u>								
Access Type										
♦ Output										
this \rightarrow M	\boxtimes this \rightarrow									
Spontaneou		Δ-Value:		Min rep	etition t	ime:				
	Cyclic	Period:								
Request										
Communicatio						1 5 7				
	ect Datapoint			ſ	Mandato	ory: 🛛 🖂				
	up Address:									
Dynamics										
Power dow										
Power up:	Value:	No initialisation:		efault value:						
		Saved value:		urrent value (no						
		bus (only for output):	_	ead from bus (only for	input):				
Exception Han	dling									
None.										
Special Featur	es									
None.										

3.1.6.4 Output Scene AB Teach (SABT)

DP Name: Scene AB	Teach	Abbr.:	SABT		Mand	atory				
FB Name: FB Scene	Sensor				Can b	e interna	al 🗌			
Description										
	This Output shall be used to teach one out of two possible scenes in the receivers.									
	ecommended for S-Mode a	pplications	s. DP Scene	e Cont	rol sho	ould be u	sed			
instead.										
Datapoint Type										
DPT_Name: DPT_Scer	ne_AB									
DPT Format: B ₁			DPT_I		1.022					
Field			Supp.	Ran		Unit	Default			
	icate which of the scenes A	or B	M	{0,	1}	none	none			
shall be	teached.									
Access Type										
◆ Output										
	s → 1 ∐									
	DV: Δ-Value:		Mir	n repe	tition ti	me:				
	/clic ☐ Period:									
Request										
Communication Type						1 5-7				
♦ Group Object Datapoir				Ma	andato	ry: 🛛 🖂				
Default Group Address	:									
Dynamics										
Power down: Save:	Ш									
Power up: Value:	No initialisation:		Default value							
	Saved value:		Current value	•						
	nit on bus (only for output):		Read from b	us (on	ly for i	nput):				
Exception Handling										
None.										
Special Features										
None.										

3.1.6.5 Parameter Scene Teaching Enable (STE)

FB:	Scene Sensor	Property Name	(<u>Server</u>):	: Scene Teaching Enable		Enable	Man Opti	datory 🗌 onal 🖂		
Desc	ription:									
This	This parameter allows limiting the functionality of the output Scene Control to only calling scenes without									
	the functionality to teach scenes. If this parameter is not implemented then the output Scene Control shall									
be im	be implemented without limitation.									
DPT:	Name DPT_Er	able	e DPT ID 1.003			pe format	B ₁			
Field	Description	ion				Range	Unit	Default		
b	Setting whether	teaching of scenes	ching of scenes shall be enabled or			{0, 1}	none	Enabled		
	not.									
Comi	munication:									
DP A	ddress:	object_type:	403		PID: 51					
(in th	e server)	start_index:	1	nr_of_elem: 1			1			
Prope	erty access:	Read only] Read	d/Write	\boxtimes					
Prote	ction	Read level	-		Write lev	el	-			
Exce	Exception Handling: Value after Power-up: Stored Value Act Value Default Value									
None	None.									
Spec	Special Features:									
None		·								

3.2 FB Priority Sensor

3.2.1 Aims and objectives

The FB Priority Sensor shall be used for high priority control of any single bit state of a receiver.

This priority control is modelled in many receiving FBs as dedicated Input.

EXAMPLE FB Dimming Actuator (Chapter 7/20/2 "Lighting Actuators") features the Input Forced to allow overriding the data from lower priority Inputs and impose the binary output state to assume the value as imposed by this DP.

3.2.2 Functional specification

3.2.2.1 General

This FB Priority Sensor allows imposing the state of actuators that have a single bit state ¹⁾ and other receivers to assume another value than the one that is given by its normal Inputs. This Input allows to override the output state of the receiver with a value that may differ from the values that would result from the Inputs that are controlled by automatic or manual control.

This requires that the receiver differentiates between its Inputs and introduces a priority concept between them.

3.2.2.2 Realisation

The implementation of this functionality is not restricted to push buttons only. It may for instance be implemented in a larger controller, scheduler, gateway, weather station ...

In combination with the other FBs, this FB Priority Sensor will only result in the availability of the Output Force.

EXAMPLE This FB can be implemented in combination with the FBs Switching Sensor Basic, Dimming Sensor Basic, Sunblind Sensor Basic...

3.2.2.3 Output Force

This Output is not fixed to one single Datapoint Type; several DPTs with coding B_2 , as specified in clause 3.2 in Chapter 3/7/2 "Datapoint Types" may make sense. Most meaningful however are the Datapoint Types as listed in Table 3.

Datapoint Type	Use
2.001 DPT_Switch_Control	Priority setting of lighting actuators (on/off).
2.008 DPT_Direction1_Control	Priority setting of of shutters and blinds actuators (fully up or fully down).

Table 3 – Typical use of priority control

3.2.2.4 Value of the high priority state

If the priority control becomes active, then the value field of the DP Force shall have the value acccording the Parameter Control Activation Value. If this Parameter is not implemented, then the value is implementation specific.

If the priority control is released, then the value field of the DP Force shall have the value according the Parameter Control Release Value. If this Parameter is not implemented, then the value is implementation specific.

¹⁾ EXAMPLE Off/On, Up/Down, Open/Close...

3.2.3 Constraints

None.

3.2.4 Functional Block diagram

	FB Priority Sensor	
Inputs		Outputs
	Force	(FO)
additional I/Os		Parameters
	(CAV)	Control Activation Value
	(CRV)	Control Release Value

3.2.5 Datapoint description

Table 4 – Datapoint overview

Datapoint	Description/Remarks	Datapoint Type
Outputs		
Force	Priority control active or inactive and priority value.	2.nnn
Inputs		
None.		
Parameters		
Control Activation Value	Defines the value of the v-field of the Output Force when the priority becomes active.	1.nnn
Control Release Value	Defines the value of the v-field of the Output Force when the priority is released.	1.nnn

3.2.6 Runtime Interworking – Dependence on Configuration Mode

		STANDARD MODE	Exten Mo	
	Basic FB	S-Mode	Standard Mode Interface	HEE
Inputs				
Outputs FO	GO _b	GO _b	GO _b	NA

Figure 2 - Runtime Interworking – Dependence on Configuration Mode

Table 5 - Parameters

		Basic FB	S-Mode
Parameters			
	CAV	0	0
	CRV	0	0

3.2.7 Detailed specification of Datapoints

3.2.7.1 Output Force (FO)

DP Name:		Force	Abbr.:	FO		Mand	datory	
FB Name:		FB Priority Sensor				Can l	be interna	al 🗌
Description								
		I be used to lock or release the						case the
	te is lo	cked, this Output also specifies	the outputs sta	te that shal	I be as	sume	d by the	
receivers.								
The value		field						
Datapoint								
DPT_Nam		<all 2.nnn="" dpts="" of=""></all>						
DPT Form	at: E	B_2		DPT_		2.nnr		
Field				Supp.	Rar		Unit	Default
С		0: the priority control is re		M	{0,	1}	none	none
		1: the priority control is a						
V							none	
		DPT. Please refer to Chapter 3/7/2						
		"Datapoint Types" clause 3.2.						
		The value can be given by the	parameters					
A T		CAV and CRV.						
Access Ty	•							
◆ Outpu								
this →		\boxtimes this \rightarrow 1						
Sponta	ineous		•	M	in repe	itition t	time:	
D	- 1	Cyclic Period:						
Reques		T						
Communic							orv: 🛛	
		et Datapoint			IVI	andato	Jry: 🔼	
	Group	o Address:						
Dynamics	down	Save:						
Power		Value: No initialisation:		Default valu				
Power	up.					foring	0.1.t\.	
		Saved value:		Current valu				
	11	Transmit on bus (only for out	put): F	Read from I	ous (or	ny for	input):	
Exception	Handi	ing						
None.	ofurce							
Special Fe	alures							
None.								

3.2.7.2 Parameter Control Activation Value (CAV)

FB:	FB Priority Sensor	Property Nam	e (<u>Server</u>):	Cont	rol Activat	ion Value		datory ∐ onal ⊠	
							Optio	nai 🔼	
Desc	ription:								
This I	Parameter shall spec	ify the value for the	v-field of the	e Outpu	t Force in	case the p	oriority cor	ntrol	
beco	nes active (c-field = 1	1).							
Multip	Multiple DPTs of the type B₁ (Chapter 3/7/2 "Datapoint Types" clause 3.1) may apply. The precise DPT								
shall	shall match the DPT as used for DP Force.								
EXAM	EXAMPLE If the Output Force is encoded according DPT_Switch_Control, then this Parameter shall be								
encod	encoded according DPT_Switch.								
DPT: Name <all 1.nnn="" b<sub="" datatype="" dpt="" dpts="" format="" id="" of="" ="">1</all>									
Field Description Sup. Range Unit Default						Default			
b	Value of v-field in	DP Force if c-field	is 1.		M	{0, 1}	none	none	
Comr	nunication								
DP A	ddress:	object_type:	1020		PID:		51		
(in the	e server)	start_index:	1 nr_of_		nr_of_ele	nr_of_elem: 1		1	
Prope	erty access:	Read only	Read/	Write	\boxtimes				
Prote	ction	Read level	-		Write level		-		
Exception Handling: Value after Power-up: S			ored Value	\boxtimes	Act V	/alue 🗌	Defau	ılt Value 🗌	
None	None.								
Spec	al Features:								
None	•								

3.2.7.3 Parameter Control Release Value (CRV)

FB:	FB Priorit	y Sensor	Property Name	(Server):	: Control Release Value Mai			Mano	datory 🔲
		-						Optio	onal 🖂
Desci	ription:								
This F	Parameter	shall spec	ify the value for the	v-field of tl	he Output	t Force in	case the p	riority co	ntrol
becor	nes releas	ed (c-field	= 0).						
Multip	Multiple DPTs of the type B₁ (Chapter 3/7/2 "Datapoint Types" clause 3.1) may apply. The precise DPT								
shall	shall match the DPT as used for DP Force.								
	EXAMPLE If the Output Force is encoded according DPT_Switch_Control, then this Parameter shall be								
	encoded according DPT_Switch.								
					pe format	B ₁			
Field Description					Sup.	Range	Unit	Default	
b	Value	of v-field ir	DP Force if c-field	is 0.		M	{0, 1}	none	none
Comr	nunication								
DP A	ddress:		object_type:	1020		PID:		52	
(in the	e server)		start_index:	1	nr_of_elem: 1		1		
Prope	erty access	:	Read only	Read	d/Write	\boxtimes			
Prote	ction		Read level	1	Write level -		-		
Exception Handling: Value after Power-up: Ste			ored Value		Act	Value	Defau	ult Value 🗌	
None	None.								
Speci	al Feature	s:							
None					· <u> </u>				

3.3 FB Lock Sensor

3.3.1 Aims and objectives

The FB Lock Sensor shall be used to enable and disable functionality in the receivers.

Many FBs feature an Input that allows their functionality to be enabled and disabled by this FB Lock Sensor.

EXAMPLE 1 FB Dimming Actuator (Chapter 7/20/2 "Lighting Actuators") features the Input Lock Device to freeze its output state under the control of this FB Lock Sensor.

EXAMPLE 2 FB Dimming Actuator (Chapter 7/20/2 "Lighting Actuators") features the Parameter Scene Learning Mode Enable (accessible as Group Object) to disable the scene learning functionality. This Parameter can be set by this FB Lock Sensor.

3.3.2 Functional specification

3.3.2.1 General

This FB Lock Sensor shall allow making the receiver ignore accesses to its Inputs that are controlled by automatic or manual control.

NOTE Compared to the FB Priority Sensor, this FB Lock Sensors does not impose a certain value of the receiver's Output state.

This requires that the receiver differentiates between its Inputs and introduces a priority concept between them.

3.3.2.2 Realisation

The implementation of this functionality is not restricted to push buttons only. It may for instance be implemented in a larger controller, scheduler, gateway, weather station ...

In combination with the other FBs, this FB Lock Sensor will only result in the availability of the Output Lock

EXAMPLE This FB can be implemented in combination with the FBs Switching Sensor Basic, Dimming Sensor Basic, Sunblind Sensor Basic...

3.3.2.3 Output Lock

This Output shall control whether the receiver is locked or not.

3.3.2.4 Interpretation by the receiver

There exists no complementary FB that specifies the communication partner for this FB Lock Sensor: this is typically realised through optional Inputs in many FBs.

The specifications of various FBs, the reaction of the FB when the Lock state becomes enabled and the reaction when the lock state becomes disabled can be controlled through optional Parameters.

3.3.3 Constraints

None.

3.3.4 Functional Block diagram

	FB Lock Sensor	
Inputs		Outputs
	Lock	(LO)
additional I/Os		Parameters
	None.	

3.3.5 Datapoint description

Table 6 – Datapoint overview

Datapoint	Description/Remarks	Datapoint Type
Outputs		
Lock	Enables or disables the lock state of the receiver.	1.003

Datapoint	Description/Remarks	Datapoint Type
Inputs		
None.		
Parameters		
None.		

3.3.6 Runtime Interworking – Dependence on Configuration Mode

			EXTEN MOD	
	Basic FB	S-Mode	Standard Mode Interface	нее
Inputs				
Outputs LO	GO _b	GO _b	GO _b	NA

Figure 3 - Runtime Interworking - Dependence on Configuration Mode

3.3.7 Detailed specification of Datapoints

3.3.7.1 Output Lock (LO)

DD Names	1	` ´		A I. I		10		N 4	l = 4 = ··· ·	
DP Name:		ock		Abbr.:		LO			latory	
FB Name:	FE	B Lock Senso	<u>Or</u>					Can	oe interna	
Description										
		oe used to en	nable or disable the loc	k state i	n th	ne receive	<u>r</u>			
Datapoint Typ										
DPT_Name:	DF	PT_Enable								
DPT Format:	B ₁					DPT_	_ID:	1.003	3	
Field						Supp.	Rai	nge	Unit	Default
b	(0: disab	les the lock state			М	{0,	1}	none	none
	1	1: enab	les the lock state							
Access Type										
♦ Output										
this \rightarrow M \square this \rightarrow 1 \square										
Spontaneo	us	COV:	Δ-Value:			М	in repe	tition t	ime:	
		Cyclic	Period:							
Request										
Communication	n T	<u></u> √pe								
		Datapoint					М	andato	ry: 🛛	
Default Gr	•								, ,	
Dynamics	- q.o.									
Power dov	'n.	Save:	П							
Power up:		Value:	No initialisation:		D	efault valu	ie.			
i olioi ap.		raido.	Saved value:			urrent valu		for inc	orit).	
	-	Transmit on	bus (only for output):			ead from I				
Exception Ha	ndlin		i bas (only for output).		1,0		040 (01	, 101	ραι).	
None.	IGIIII	9								
Special Featu	roc									
None.	163									
inone.										

3.4 FB Timed Sensor

3.4.1 Aims and objectives

The FB Timed Sensor shall be used to trigger a timer in the receiver. Optionally, it can also be used to stop this timer.

EXAMPLE 1 The lighting actuators (Chapter 7/20/2 "Lighting Actuators") features an Input Timed Start Stop that can be accessed to switch on the light, after which the actuator switches off the light autonomously after a timer has expired.

The use of this FB Timed Sensor is not limited to the application domain of lighting.

EXAMPLE 2 In a rest room, a light switch may incorporate this FB Timed Sensor. By this, when switching the light, it can trigger the operation of a ventilator for a certain period.

3.4.2 Functional specification

3.4.2.1 General

This FB Timed Sensor shall allow triggering a timer in the receiver. This FB TSS models the communication partner for many FBs featuring an Input "Timed Start Stop" (or similar).

Furthermore, it allows redirecting data received from a sender that does not support timing, via the Input On Off In (OOI) either unchanged to the Output On Off Out (OOO) or the Output Timed Start Stop (TSS) under the control of the Input Timed Mode (TM). In this, the value received on OOI shall not be modified.

If the realisation of this FB features a HMI, then this HMI and the Input OOI shall not influence each other in either way. The value of OOI shall be passed unchanged to either Output OOI or TSS regardless of the last operation to the HMI. In the same way, the operation of the HMI is not changed (e.g. not inverted) in function of any reception of the Input OOI.

3.4.2.2 Timed Mode

The Input Timed Mode allows selecting either one of the Outputs TSS or OOO to be used. If one Output is activated the other Output shall be deactivated.

Timed Mode	Outputs
Active	The Output Timed Start Stop shall be used.
	The Output On Off Out shall not be used.
Inactive	The Output Timed Start Stop shall not be used.
	The Output On Off Out shall be used.

It shall thus not be possible to use the Outputs TSS and OOO at the same time.

3.4.2.3 Realisation

The implementation of this functionality is not restricted to push buttons only. It may for instance be implemented in a larger controller, scheduler, gateway, weather station ...

In combination with other FBs, this FB Timed Sensor will only result in the availability of the Output Timed Start Stop.

EXAMPLE This FB can be implemented in combination with the FBs Switching Sensor Basic, Dimming Sensor Basic.

3.4.2.4 Interpretation by the receiver

There exists no complementary FB that specifies the communication partner for this FB Timed Sensor: this is typically realised through optional Inputs in many FBs.

The functionality depends on the receiver. In general, the receiver performs a certain action when the timer starts and again takes some action, e.g. an action complementary to the first one, when the timer expires.

In the specifications of various FBs, the reaction of the FB on reception of an access to the corresponding Input may be controlled through parameters.

EXAMPLE 1 The Parameter Timed On Retrigger Function in the Light Switching Actuator Basic (see Chapter 7/20/2 "Lighting Actuators") may control whether or not the timer in the receiver can be retriggered by a subsequent access to the Input Timed Start Stop or not.

The reaction of the receiver on reception of the value "Stop" on its Input may or may not be identical to the reaction when the timer simply expires. This can again be influenced by parameters.

3.4.3 Constraints

This FB Timed Sensor only uses a single bit DPT_Start that does not contain any information concerning the timer period in the receiver. This may only be controlled through a parameter in the receiver.

The Datapoints OOI and TM are optional. They can however only be implemented if the DP OOO is implemented.

3.4.4 Functional Block diagram

FB Timed Sensor								
Inputs			Outputs					
OnOffIn	(OOI)	Timed Start Stop	(TSS)					
TimedMode	(TM)	OnOffOut	(000)					
additional I/Os			Parameters					
		Enable Sending Stop	(ESS)					

3.4.5 Datapoint description

Table 7 – Datapoint overview

Datapoint	Datapoint Description/Remarks			
Outputs				
Timed Start Stop	This Output shall be used to trigger the timing function in the receiver.	1.010 DPT_Start		
On Off Out	This Output shall be used to directly control the output of the receiver, without timer.	1.001 DPT_Switch		
Inputs				
On Off In	Commands to be directly sent on the OOO or to be transformed as a TSS in timed mode.	1.001 DPT_Switch		
Timed Mode	To set the timed mode or normal mode.	1.011 DPT_State		
Parameters				
Enable Sending Stop	Shall allow extending the values of the Output Timed Start Stop from only 1 to both 0 and 1.	1.003 DPT_Enable		

3.4.6 Runtime Interworking – Dependence on Configuration Mode

			STANDARD MODE	EXTENDED MODE	
		Basic FB			HEE
Inputs	001	(GO _b)	(GO _b)	(GO _b)	NA
	TM	(GO _b)	(GO _b)	(GO _b)	NA
Outputs	TSS	GO _b	GO _b	GO _b	NA
	000	(GO _b)	(GO _b)	(GO _b)	NA

Figure 4 - Runtime Interworking – Dependence on Configuration Mode

Table 8 - Parameters

		Basic FB	S-Mode
Parameters			
	ESS	0	0

3.4.7 Detailed specification of Datapoints

3.4.7.1 Output Timed Start Stop (TSS)

DP Name:	Timed Start Stop	Abbr.:	TSS		Mano	latory		
FB Name:	Timed Sensor				Can b	oe interna	al 🗌	
Description								
	all be used to trigger the timing function							
	r Enable Sending Stop is not impleme							
	nd has the value "Disable", then this O	output shall	only be tra	ansmitt	ted witl	h the valu	ле 1	
(= "Start").								
	If the parameter Enable Sending Stop is implemented and has the value "Enable" then this Output may							
transmit both values 0 (= "Stop") and 1 (= "Start").								
Datapoint Type								
DPT_Name:	DPT_Start							
DPT Format:	B ₁		DPT_		1.010			
Field			Supp.		nge	Unit	Default	
b	0: shall be used to request to stop	p the	M	{0,	1}	none	none	
	timer in the receiver							
	1: shall be used to request to star	rt the						
	timer in the receiver							
Access Type								
◆ Output								
this \rightarrow M	\boxtimes this \rightarrow 1 \square							
Spontaneou			M	in repe	etition t	ime:		
	Cyclic Period:							
Request								
Communication								
	ect Datapoint			M	andato	ory: 🛛		
	up Address:							
Dynamics								
Power down	n: Save:							
Power up:	Value: No initialisation:		efault valu	ıe:				
	Saved value:		urrent valu	ue (not	for inp	out):		
	Transmit on bus (only for output):	R	ead from I	bus (or	nly for i	input):		
Exception Han	dling							
None.								
Special Featur	es							
None.								

3.4.7.2 Output On Off Out (OOO)

DP Name:	On Off Out		Abbr.:	00	00	Mano	latory	
FB Name:	Timed Sensor	Sensor Can be internal						
Description	Description							
		FB Timed Sensor if th	e timed i	mode i	s inactive	e.		
Datapoint Type								
DPT_Name:	e: DPT_Switch							
DPT Format:	B ₁				DPT_ID:			
Field					Supp.	Range	Unit	Default
b		indicate whether the sv	witching		M	{0, 1}	none	none
	actuator will sw	vitch on (1) or off (0).						
Access Type								
♦ Output								
this \rightarrow M	this \rightarrow M \square this \rightarrow 1 \square							
Spontaneou	us 🛛 COV:	\[\Delta \Delta \- \Value:			Min r	epetition t	ime:	
	Cyclic	☐ Period:						
Request								
Communication	n Type							
♦ Group Obj	ect Datapoint					Mandato	ory: 🛮 🖂	
Default Gro	up Address:							
Dynamics								
Power down	n: Save:							
Power up:	Value:	No initialisation:			It value:			
		Saved value:				not for inp		
		bus (only for output):		Read	from bus	(only for	input):	
Exception Han	dling							
Special Featur	es							

3.4.7.3 Input On Off In (OOI)

DP Name:	0	n Off In		Abbr.:	0	OI		Mand	atory	
FB Name:	Т	Timed Sensor Can be internal								
Description										
	This is the value that shall be sent on the Output Timed Start Stop or Output On Off Out, according the									
value of the Ir		Timed Mode								
	Datapoint Type									
DPT_Name:	D	PT_Switch								
DPT Format:	В	1				DPT_ID:		1.001		
Field						Supp.	Ra	ange	Unit	Default
b			alue to be forwarded to		ut	M	{0), 1}	none	none
	Ti	med Start St	op or the Output On Of	f Out.						
Access Type										
♦ Input										
$N \rightarrow this$			$1 \rightarrow \text{this}$							
Spontaneo	us		Cyclically:			Time	-out	t:		
Request			Polling:			Perio	d:			
Communication	on T	уре								
♦ Group Ob	ject	Datapoint					Ma	andato	ry: 🛛	
Default Gr	oup	Address:								
Dynamics										
Power dov	vn:	Save:								
Power up:		Value:	No initialisation:		Defa	ult value:				
			Saved value:		Curre	ent value (not	for inp	out):	
		Transmit or	bus (only for output):		Read	I from bus	(on	ly for i	nput):	
Exception Ha	ndlir	ng								
None.										
Special Featu	res									
None.										

3.4.7.4 Input Timed Mode (TM)

DP Name:	Timed Mode		Abbr.:	TM	Man	datory		
FB Name:	Timed Sensor Can be internal						al 🗌	
Description								
This Input active	vates or inactiva	tes the Timed Mode of	the Timed	Sensor.				
Datapoint Type	9							
DPT_Name:								
DPT Format:	B ₁			DPT_ID				
Field				Supp.	Range	Unit	Default	
b	0 Timed I	Mode is inactive. The C	Output On O	off M	{0, 1}	none	1	
	1 Timed I	Mode is active. The Outop is used.	tput Timed					
Access Type								
◆ Input								
$N \rightarrow this$		$1 \rightarrow \text{this}$						
Spontaneo	us 🛛	Cyclically:		Time	e-out:			
Request		Polling:		Perio	od:			
Communicatio								
	ect Datapoint				Mandato	ory: 🛮 🖂		
	up Address:							
Dynamics		. —						
Power dow								
Power up:	Value:	No initialisation:		efault value:				
		Saved value:		urrent value (
		n bus (only for output):	_	ead from bus	(only for	input):		
Exception Han	dling							
None.								
Special Featur	es							
None.								

3.4.7.5 Parameter Enable Sending Stop

Timed Sensor	Property Name	(<u>Server</u>):	Enable	Sending S	datory 🔲				
						Opti	onal 🔀		
Description:									
This parameter shall allow limiting the values of the output Timed Start Stop to either only 1 (= "Start")									
both 1 (= "Start") as well as 0 (= "Stop").									
Name DPT_En	able	DPT ID	1.003	Dataty	pe format	: B ₁			
Description				Sup.	Range	Unit	Default		
0: the Output	Timed Start Stop sh	all only hav	e the	M	{0, 1}	none	none		
value 1 (= "	Start")								
1: the Output	Timed Start Stop ma	ay have bo	th the						
values 1 (=	"Start") as well as 0	(= "Stop")							
nunication:									
ddress:	object_type:	406	PID:			51			
e server)	start_index:	1		nr_of_ele	em:	1			
erty access:	Read only	Read	d/Write						
ction	Read level	-		Write lev	el	-			
otion Handling: Val	ue after Power-up:	Stored Va	alue 🛚	Act Value	☐ Def	fault Valu	e 🗌		
None.									
Special Features:									
•		•	•			•			
	ription: parameter shall allow 1 (= "Start") as well a Name DPT_En Description 0: the Output 1 value 1 (= "Start") 1: the Output 1 values 1 (= "Start") continuous differences continuo	ription: parameter shall allow limiting the values of (= "Start") as well as 0 (= "Stop"). Name DPT_Enable Description 0: the Output Timed Start Stop show value 1 (= "Start") 1: the Output Timed Start Stop may values 1 (= "Start") as well as 0 munication: Induction:	ription: parameter shall allow limiting the values of the output 1 (= "Start") as well as 0 (= "Stop"). Name DPT_Enable DPT ID Description 0: the Output Timed Start Stop shall only have value 1 (= "Start") 1: the Output Timed Start Stop may have bore values 1 (= "Start") as well as 0 (= "Stop") nunication: ddress: object_type: 406 et server start_index: 1 erty access: Read only Read et server Read level - option Handling: Value after Power-up: Stored Value After Power-up: S	ription: parameter shall allow limiting the values of the output Timeon (1 (= "Start") as well as 0 (= "Stop"). Name DPT_Enable DPT ID 1.003 Description 0: the Output Timed Start Stop shall only have the value 1 (= "Start") 1: the Output Timed Start Stop may have both the values 1 (= "Start") as well as 0 (= "Stop") munication: ddress: object_type: 406	ription: parameter shall allow limiting the values of the output Timed Start Store (a "Start") as well as 0 (= "Stop"). Name DPT_Enable DPT ID 1.003 Dataty Description Sup. 0: the Output Timed Start Stop shall only have the value 1 (= "Start") 1: the Output Timed Start Stop may have both the values 1 (= "Start") as well as 0 (= "Stop") munication: ddress: object_type: 406 PID: eserver) start_index: 1 nr_of_electy access: Read only Read/Write Starty access: Read only Read/Write Stored Value Act Value al Features:	ription: parameter shall allow limiting the values of the output Timed Start Stop to either 1 (= "Start") as well as 0 (= "Stop"). Name DPT_Enable DPT ID 1.003 Datatype format Description Sup. Range 0: the Output Timed Start Stop shall only have the value 1 (= "Start") 1: the Output Timed Start Stop may have both the values 1 (= "Start") as well as 0 (= "Stop") nunication: ddress: object_type: 406 PID: e server) start_index: 1 nr_of_elem: erty access: Read only Read/Write Server Read level - Write level ption Handling: Value after Power-up: Stored Value Act Value Description Description of the output Timed Start Stop may have both the values 1 (= "Stop") Note: The output Timed Start Stop may have both the values 1 (= "Stop") Read Read Read Read Read Read Read Read	Optimipation: parameter shall allow limiting the values of the output Timed Start Stop to either only 1 (= "Start") as well as 0 (= "Stop"). Name DPT_Enable DPT ID 1.003 Datatype format B ₁ Description Sup. Range Unit 0: the Output Timed Start Stop shall only have the value 1 (= "Start") 1: the Output Timed Start Stop may have both the values 1 (= "Start") as well as 0 (= "Stop") munication: ddress: object_type: 406 PID: 51 eserver) start_index: 1 nr_of_elem: 1 erty access: Read only Read/Write Stop ction Read level - Write level - Default Value al Features:		