

Week 5 Notes: The Bootstrap

Antonio R. Linero
University of Texas at Austin

Goals

1. Learn how to use the bootstrap to estimate the sampling distribution of (almost) any statistic $T = T(\mathcal{D})$.
2. Learn the distinction between various types of bootstraps (nonparametric and parametric bootstraps).
3. Get practice implementing the bootstrap and apply it to several problems.

Motivation

Goal: estimate the *sampling distribution* of a statistic

$$T = T(\mathcal{D})$$

Why? If T is a “good” estimator of a parameter ψ then

$$T \pm z_{\alpha/2} \times \text{std. error}(T)$$

will be a “good” confidence interval for ψ .

Motivation

Goal: estimate the *sampling distribution* of a statistic

$$T = T(\mathcal{D})$$

Why? If T is a “good” estimator of a parameter ψ then

$$T \pm z_{\alpha/2} \times \text{std. error}(T)$$

will be a “good” confidence interval for ψ .

Other types of intervals are of course possible, and bootstrap can help with those as well.

Motivation: Robust Standard Errors

Assume we fit a GLM such that

$$g(\mu_i) = X_i^\top \beta$$

correctly describes the mean model. How does MLE behave?

Motivation: Robust Standard Errors

Assume we fit a GLM such that

$$g(\mu_i) = X_i^\top \beta$$

correctly describes the mean model. How does MLE behave?

1. $\sqrt{N}(\hat{\beta} - \beta_0) \rightarrow N(0, \Sigma)$ (\sqrt{N} -consistent!)
2. $\Sigma \neq$ the inverse Fisher information.

Motivation: Robust Standard Errors

Problem: given $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$, what if I want a CI for

$$m_F = \text{median}(F)?$$

Several ways to do this! But one is to use the fact that

$$M \stackrel{\circ}{\sim} \text{Normal}\{m_F, \sigma_M^2\} \quad \text{where} \quad M = \text{median}(X_1, \dots, X_N).$$

But hard to estimate σ_M^2 !

Motivation: Robust Standard Errors

Problem: given $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$, what if I want a CI for

$$m_F = \text{median}(F)?$$

Several ways to do this! But one is to use the fact that

$$M \rightsquigarrow \text{Normal}\{m_F, \sigma_M^2\} \quad \text{where} \quad M = \text{median}(X_1, \dots, X_N).$$

But hard to estimate σ_M^2 !

More generally: many estimators are *asymptotically linear*, meaning that

$$\hat{\theta} = \theta_0 + \frac{1}{N} \sum_i \phi(X_i; \theta_0) + o_P(N^{-1/2})$$

for a mean-0 function $\phi(X_i; \theta_0)$ called the *influence function*.

Implies a CLT, but may be difficult to estimate variance!

The Bootstrap Principle

The Bootstrap Principle:

Suppose that $\mathcal{D} \sim G$, $\psi = \psi(G)$ is a parameter of G we are interested in, and $T = T(\mathcal{D})$ is an estimator of ψ . Then we can approximate the sampling distribution of $T(\mathcal{D})$ by

1. estimating G with some \hat{G} ; and
2. using the sampling distribution of $T^* = T(\mathcal{D}^*)$ to estimate the sampling distribution of T , where $\mathcal{D}^* \sim \hat{G}$.

Example

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$.

- Estimate $\mu \approx \bar{X}$ and $\sigma^2 \approx s^2 = \frac{\sum_i (X_i - \bar{X})^2}{N-1}$.

Example

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$.

- Estimate $\mu \approx \bar{X}$ and $\sigma^2 \approx s^2 = \frac{\sum_i (X_i - \bar{X})^2}{N-1}$.
- $\hat{F} = \text{Normal}(\bar{X}, s^2)$.

Example

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$.

- Estimate $\mu \approx \bar{X}$ and $\sigma^2 \approx s^2 = \frac{\sum_i (X_i - \bar{X})^2}{N-1}$.
- $\hat{F} = \text{Normal}(\bar{X}, s^2)$.
- $\mathcal{D}^* = \{X_1^*, \dots, X_N^*\}$ with $X_i^* \stackrel{\text{iid}}{\sim} \text{Normal}(\bar{X}, s^2)$.

Example

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$.

- Estimate $\mu \approx \bar{X}$ and $\sigma^2 \approx s^2 = \frac{\sum_i (X_i - \bar{X})^2}{N-1}$.
- $\hat{F} = \text{Normal}(\bar{X}, s^2)$.
- $\mathcal{D}^* = \{X_1^*, \dots, X_N^*\}$ with $X_i^* \stackrel{\text{iid}}{\sim} \text{Normal}(\bar{X}, s^2)$.
- From properties of normal $\bar{X}^* \sim \text{Normal}(\bar{X}, s^2/N)$.

Example

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$.

- Estimate $\mu \approx \bar{X}$ and $\sigma^2 \approx s^2 = \frac{\sum_i (X_i - \bar{X})^2}{N-1}$.
- $\hat{F} = \text{Normal}(\bar{X}, s^2)$.
- $\mathcal{D}^* = \{X_1^*, \dots, X_N^*\}$ with $X_i^* \stackrel{\text{iid}}{\sim} \text{Normal}(\bar{X}, s^2)$.
- From properties of normal $\bar{X}^* \sim \text{Normal}(\bar{X}, s^2/N)$.
- Approximate sampling variance of \bar{X} is therefore s^2/N .

Example: Nonparametric Bootstrap

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$. What is the distribution of $M = \text{median}(X_1, \dots, X_N)$?

- Estimate F with $\hat{F} = \frac{1}{N} \sum_i \delta_{X_i}$.

Example: Nonparametric Bootstrap

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$. What is the distribution of $M = \text{median}(X_1, \dots, X_N)$?

- Estimate F with $\hat{F} = \frac{1}{N} \sum_i \delta_{X_i}$.
- Approximate sampling distribution of M with $\text{median}(X_1^*, \dots, X_N^*)$ where $X_i^* \stackrel{\text{iid}}{\sim} \hat{F}$.

Example: Nonparametric Bootstrap

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$. What is the distribution of $M = \text{median}(X_1, \dots, X_N)$?

- Estimate F with $\hat{F} = \frac{1}{N} \sum_i \delta_{X_i}$.
- Approximate sampling distribution of M with $\text{median}(X_1^*, \dots, X_N^*)$ where $X_i^* \stackrel{\text{iid}}{\sim} \hat{F}$.
- Cannot do this in closed form...

Example: Nonparametric Bootstrap

Suppose $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$. What is the distribution of $M = \text{median}(X_1, \dots, X_N)$?

- Estimate F with $\hat{F} = \frac{1}{N} \sum_i \delta_{X_i}$.
- Approximate sampling distribution of M with $\text{median}(X_1^*, \dots, X_N^*)$ where $X_i^* \stackrel{\text{iid}}{\sim} \hat{F}$.
- Cannot do this in closed form...
- So use Monte Carlo instead! Sample many new datasets, compute the median on each, and use the resulting empirical distribution of M !

Bootstrap Variance Estimation

The bootstrap can be used to approximate the variance (or standard deviation) of T as follows:

1. Draw $\mathcal{D}^* \sim \hat{G}$ (for example, if $X_1, \dots, X_N \stackrel{\text{iid}}{\sim} F$ then we take $X_1^*, \dots, X_N^* \stackrel{\text{iid}}{\sim} \mathbb{F}$).
2. Compute $T^* = T(\mathcal{D}^*)$.
3. Repeat steps 1 and 2 B times to get T_1^*, \dots, T_B^* .
4. Let $v_{\text{boot}} = \frac{1}{B} \sum_{b=1}^B \left(T_b^* - \bar{T}\right)^2$ where $\bar{T} = \frac{1}{B} \sum_b T_b^*$.

Pseudocode

```
## Let  $X$  be a vector of size  $N$ , sampled from  $F$ 
T <- median(X)
Tboot <- numeric(N)
for(i in 1:B) {
  ## Sample  $N$  iid draws from the empirical distribution of  $X$ 
  Xstar <- sample(x = X, size = N, replace = TRUE)
  ## Save the result
  Tboot[i] <- median(Xstar)
}
v_boot <- var(Tboot)
se_boot <- sqrt(v_boot)
```

The Normal Interval

For asymptotically linear statistics, it makes sense to use the interval

$$T \pm z_{\alpha/2} \times \text{se}_{\text{boot}}$$

Great if we are close to normality! Can also use a $t_{\alpha/2}$ interval if worried about Monte Carlo error...

Basic Percentile Method

Mimics Bayesian reasoning:

1. Sample many T^* 's according to the nonparametric bootstrap.
2. Use the interval $(T_{\alpha/2}^*, T_{1-\alpha/2}^*)$ where T_{γ}^* denotes the $100\gamma^{\text{th}}$ percentile of T^* .

Why does this work?

Pivotal Intervals

- Don't approximate the sampling distribution of T with that of T^*
- Instead, approximate the sampling distribution of $\zeta = T - \psi$ with $\zeta^* = T^* - T$.
- Leads to the interval

$$\psi \in (T - \zeta_{1-\alpha/2}^*, T - \zeta_{\alpha/2}^*) = (2T - T_{1-\alpha/2}^*, 2T - T_{\alpha/2}^*).$$

Show on board why this works.

Pivotal Intervals

- Don't approximate the sampling distribution of T with that of T^*
- Instead, approximate the sampling distribution of $\zeta = T - \psi$ with $\zeta^* = T^* - T$.
- Leads to the interval

$$\psi \in (T - \zeta_{1-\alpha/2}^*, T - \zeta_{\alpha/2}^*) = (2T - T_{1-\alpha/2}^*, 2T - T_{\alpha/2}^*).$$

Show on board why this works.

*Works best when $T - \psi$ is a **pivotal quantity**.* Exact pivots are hard to get without strong assumptions, however...

Exercise

Exercise: Wasserman 8.1

Consider the following dataset:

```
df <- data.frame(  
  LSAT = c(576, 635, 558, 578, 666, 580, 555, 661, 651,  
           605, 653, 575, 545, 572, 594),  
  GPA = c(3.39, 3.30, 2.81, 3.03, 3.44, 3.07, 3.00, 3.43,  
          3.36, 3.13, 3.12, 2.74, 2.76, 2.88, 3.96)  
)
```

which are LSAT scores (for entrance to law school) and GPA. Estimate the standard error of the correlation coefficient ρ using the bootstrap. Find a 95 percent confidence interval using the normal, pivotal, and percentile methods.

Exercise: Wasserman 8.2

Conduct a simulation to compare the various bootstrap confidence interval methods. Let $N = 50$ and let $\psi = \frac{1}{\sigma^3} \int (x - \mu)^3 F(dx)$ be the skewness. Draw $Y_1, \dots, Y_N \sim \text{Normal}(0, 1)$ and set $X_i = e^{Y_i}$, $i = 1, \dots, N$. Construct the three types of bootstrap 95 percent intervals for ψ from the data X_1, \dots, X_N . Repeat this whole thing many times and estimate the true coverage of the three intervals.