

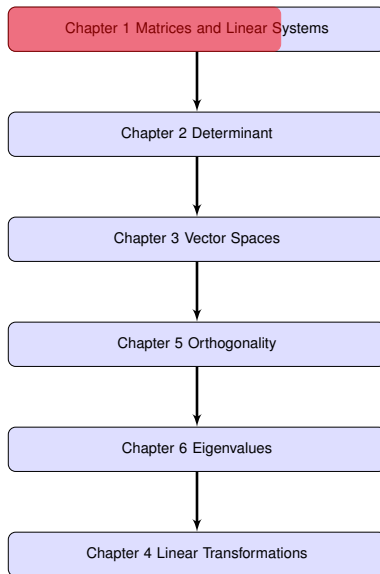
# Chapter 1: Linear Systems and Matrices

## Section: Matrices and Gaussian Elimination

### Lecture #3

Lebanese University

Prof. Ali WEHBE



- 1 Row Echelon form
  - Row Echelon form for a Matrix
  - Elementary Row Operations
- 2 Terminologies For Linear Systems
- 3 Gaussian Elimination with back substitution
  - Solving by Back substitution
  - Overdetermined Systems
  - Under-determined Systems
- 4 Reduced Row Echelon Form
- 5 Gauss-Jordan Reduction

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## Definition

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### Definition

A matrix is said to be in **Row Echelon Form - REF** if

- a) The first nonzero entry in each nonzero row is **1** (called a leading **1**).
- b) Every leading 1 is to the right of the one above it.
- c) Any row that consists of zero entries must be at the bottom of the matrix.

### Remark

All the entries below the leading 1 from each row are zeros.



## Example (REF)

$$\begin{bmatrix} 1 & 4 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 6 & 4 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

## Example (Not REF)

$$\begin{bmatrix} 1 & 4 & 2 \\ 0 & 3 & 6 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 6 & 4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

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## Definition

The **Elementary Row Operation** that we can apply on a matrix are:

- a) Interchange two rows.
- b) Multiply a row with a nonzero constant.
- c) Add a multiple of a row to another row.

### Example

Find the REF of the following Matrix

$$A = \begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix}$$

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$$A_1 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 2 & -5 & 5 & 17 \end{bmatrix} \quad R_3 - 2R_1 \longrightarrow R_3 \implies$$

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$$A_1 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 2 & -5 & 5 & 17 \end{bmatrix} \quad R_3 - 2R_1 \longrightarrow R_3 \implies A_2 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix}$$

## Example

$$A_2 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix}$$

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## Example

$$A_2 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix} R_3 + R_2 \longrightarrow R_3 \implies A_3 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

$$A_3 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix} \frac{1}{2}R_3 \longrightarrow R_3 \implies$$

## Example

$$A_2 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix} R_3 + R_2 \longrightarrow R_3 \implies A_3 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

$$A_3 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix} \frac{1}{2}R_3 \longrightarrow R_3 \implies A_4 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

## Example

$$A_2 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix} R_3 + R_2 \longrightarrow R_3 \implies A_3 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

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How can we get benefits from REF to solve systems of Linear Equations?



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## Definition (Coefficient Matrix)

Consider the system of linear equations

$$(S) : \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1, \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2, \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m, \end{cases}$$

The **coefficient matrix** of **S** is:

$$C = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

## Definition (Augmented Matrix)

Consider the system of equations

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The **Augmented matrix** of **S** is:

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & : & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & : & b_2 \\ & & \vdots & & : & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & : & b_m \end{bmatrix}$$

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## Strategy

To solve a system of Linear equation using **Gaussian Elimination with back substitution**, we apply the following steps:

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To solve a system of Linear equation using **Gaussian Elimination with back substitution**, we apply the following steps:

- a) Write the **Augmented Matrix** associated to the system.
- b) Apply the **Elementary Row Operation** in order to transform the **Augmented Matrix** in **Row Echelon Form - REF**.



## Strategy

To solve a system of Linear equation using **Gaussian Elimination with back substitution**, we apply the following steps:

- a) Write the **Augmented Matrix** associated to the system.
- b) Apply the **Elementary Row Operation** in order to transform the **Augmented Matrix in Row Echelon Form - REF**.
- c) Write the **equivalent system** associated to the **REF Matrix**.

## Strategy

To solve a system of Linear equation using **Gaussian Elimination with back substitution**, we apply the following steps:

- a) Write the **Augmented Matrix** associated to the system.
- b) Apply the **Elementary Row Operation** in order to transform the **Augmented Matrix in Row Echelon Form - REF**.
- c) Write the **equivalent system** associated to the **REF Matrix**.
- d) Use substitution method to solve the obtained system.

## Example

Solve the following System of Linear Equations:

$$(S_1) \begin{cases} x_1 & -2x_2 & +3x_3 & = & 9, \\ -x_1 & +3x_2 & & = & -4, \\ 2x_1 & -5x_2 & +5x_3 & = & 17. \end{cases}$$

The **Augmented matrix** of system  $(S_1)$  is given by

$$A = \begin{bmatrix} 1 & -2 & 3 & \vdots & 9 \\ -1 & 3 & 0 & \vdots & -4 \\ 2 & -5 & 5 & \vdots & 17 \end{bmatrix}$$

**Note:** The **coefficient matrix** associated to system  $(S_1)$  is given by

$$B = \begin{bmatrix} 1 & -2 & 3 \\ -1 & 3 & 0 \\ 2 & -5 & 5 \end{bmatrix}$$

# Use the augmented matrix to solve system ( $S_1$ )

$$A = \begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix}$$

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$$A = \begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix} \xrightarrow{\text{REF}}$$

Use the augmented matrix to solve system ( $S_1$ )

$$A = \begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix} \xrightarrow{\text{REF}} A_4 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

Use the augmented matrix to solve system  $(S_1)$ 

$$A = \begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix} \xrightarrow{\text{REF}} A_4 = \begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

So the following systems have the same solution:

$$(S_1) \begin{cases} x_1 & -2x_2 & +3x_3 & = & 9, \\ -x_1 & +3x_2 & & = & -4, \\ 2x_1 & -5x_2 & +5x_3 & = & 17. \end{cases} \quad (S_4) \begin{cases} x_1 & -2x_2 & +3x_3 & = & 9, \\ & x_2 & +3x_3 & = & 5, \\ & & x_3 & = & 2. \end{cases}$$

Using back substitution the solution of system  $(S_4)$  is  $x_1 = 1$ ,  $x_2 = -1$  and  $x_3 = 2$ .

Thus the solution of  $(S_1)$  is  $S = \{(1, -1, 2)\}$

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## Definition

A linear System is said to be **Overdetermined** if there are more equations than unknowns,  $m > n$ . Overdetermined systems are *usually* (but not always) inconsistent.

## Example

Solve the following systems:

a)

$$\begin{cases} x_1 + x_2 = 1, \\ x_1 - x_2 = 3, \\ -x_1 + 2x_2 = -2. \end{cases}$$

**Solution:**

## Example

Solve the following systems:

a)

$$\begin{cases} x_1 + x_2 = 1, \\ x_1 - x_2 = 3, \\ -x_1 + 2x_2 = -2. \end{cases}$$

**Solution:** Step 1 and Step 2:

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**Solution:** Step 1 and Step 2:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 3 \\ -1 & 2 & -2 \end{bmatrix}$$

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Solve the following systems:

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**Solution:** Step 1 and Step 2:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 3 \\ -1 & 2 & -2 \end{bmatrix} \quad R_2 - R_1 \rightarrow R_2$$

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**Solution:** Step 1 and Step 2:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 3 \\ -1 & 2 & -2 \end{bmatrix} \quad R_2 - R_1 \rightarrow R_2 \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ -1 & 2 & -2 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ -1 & 2 & -2 \end{bmatrix} \quad R_3 + R_1 \rightarrow R_3$$



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$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 3 \\ -1 & 2 & -2 \end{bmatrix} \quad R_2 - R_1 \rightarrow R_2 \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ -1 & 2 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ -1 & 2 & -2 \end{bmatrix} \quad R_3 + R_1 \rightarrow R_3 \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{bmatrix}$$

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## Example

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{bmatrix} \quad R_2 \times -\frac{1}{2}$$

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$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{bmatrix} \xrightarrow{R_2 \times -\frac{1}{2}} R_2 \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -1 \end{bmatrix}$$

## Example

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{bmatrix} \quad R_2 \times -\frac{1}{2} \longrightarrow R_2 \implies \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -1 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -1 \end{bmatrix} \quad R_3 - 3R_2 \longrightarrow R_3$$

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$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{bmatrix} \quad R_2 \times -\frac{1}{2} \longrightarrow R_2 \implies \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -1 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & 2 \\ 0 & 3 & -1 \end{bmatrix} \quad R_2 \times -\frac{1}{2} \longrightarrow R_2 \implies \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -1 \end{bmatrix}$$

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## Example

Step 3:

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

## Example

Step 3:

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 = 1, \\ x_2 = -1, \\ 0 = 1. \end{cases}$$

## Example

Step 3:

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 = 1, \\ x_2 = -1, \\ 0 = 1. \end{cases} \quad \text{X}$$

## Example

Step 3:

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 = 1, \\ x_2 = -1, \\ 0 = 1. \end{cases} \quad \text{X False Statement}$$

## Example

Step 3:

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 = 1, \\ x_2 = -1, \\ 0 = 1. \end{cases} \quad \text{X False Statement}$$

The system has no solution. The system is inconsistent.

b)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 - x_2 + x_3 = 2, \\ 4x_1 + 3x_2 + 3x_3 = 4, \\ 2x_1 - x_2 + 3x_3 = 5. \end{cases}$$

**Solution:**

## Example

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{bmatrix}$$



## Example

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{bmatrix} \text{REF}$$

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$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow$$

## Example

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 + x_3 = 1, \\ \phantom{x_1} x_2 + \frac{1}{5}x_3 = 0, \\ \phantom{x_1} \phantom{x_2} x_3 = \frac{3}{2}, \\ \phantom{x_1} \phantom{x_2} \phantom{x_3} 0 = 0. \end{cases}$$

## Example

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 2 & -1 & 3 & 5 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 + x_3 = 1, \\ x_2 + \frac{1}{5}x_3 = 0, \\ x_3 = \frac{3}{2}, \\ 0 = 0. \end{cases}$$

Using Back substitution, we deduce the system has a unique solution  $x_1 = \frac{1}{10}$ ,  $x_2 = -\frac{3}{10}$  and  $x_3 = \frac{3}{2}$ .

## Example

c)

$$\begin{cases} x_1 & +2x_2 & +x_3 & = & 1, \\ 2x_1 & -x_2 & +x_3 & = & 2, \\ 4x_1 & +3x_2 & +3x_3 & = & 4, \\ 3x_1 & +x_2 & +2x_3 & = & 3. \end{cases}$$

Solution:



## Example

c)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 - x_2 + x_3 = 2, \\ 4x_1 + 3x_2 + 3x_3 = 4, \\ 3x_1 + x_2 + 2x_3 = 3. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 3 & 1 & 2 & 3 \end{bmatrix}$$

## Example

c)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 - x_2 + x_3 = 2, \\ 4x_1 + 3x_2 + 3x_3 = 4, \\ 3x_1 + x_2 + 2x_3 = 3. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 3 & 1 & 2 & 3 \end{bmatrix} \text{REF}$$

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Solution:

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## Example

c)

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Solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 3 & 1 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & \frac{1}{5} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 + x_3 = 1, \\ \phantom{x_1} x_2 + \frac{1}{5}x_3 = 0, \\ \phantom{x_1} \phantom{x_2} 0 = 0, \\ \phantom{x_1} \phantom{x_2} 0 = 0. \end{cases}$$

### Example

Setting  $x_3 = t \in \mathbb{R}$ . Then, the system has an infinite number of solutions given by

$$\begin{cases} x_1 &= 1 - \frac{6}{10}t, \\ x_2 &= -\frac{2}{10}t, \\ x_3 &= t. \end{cases}$$

- 1 Row Echelon form
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## Definition

A system of Linear Equation is said to be **under-determined** if the number of equations is less than the number of unknowns, i.e. if  $m < n$ .

**Under-determined** systems are usually (but not always) consistent with infinitely number of solutions.

### Definition

A system of Linear Equation is said to be **under-determined** if the number of equations is less than the number of unknowns, i.e. if  $m < n$ .

**Under-determined** systems are usually (but not always) consistent with infinitely number of solutions.

### Remark:

It is not possible for an **under-determined** system to have a unique solution.

## Example

a)

$$\begin{cases} x_1 & +2x_2 & +x_3 & = & 1, \\ 2x_1 & +4x_2 & +2x_3 & = & 3. \end{cases}$$

solution:

## Example

a)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 + 4x_2 + 2x_3 = 3. \end{cases}$$

solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix}$$

## Example

a)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 + 4x_2 + 2x_3 = 3. \end{cases}$$

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## Example

a)

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$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \text{REF} \Rightarrow$$

## Example

a)

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solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

## Example

a)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 + 4x_2 + 2x_3 = 3. \end{cases}$$

solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



## Example

a)

$$\begin{cases} x_1 & +2x_2 & +x_3 & = & 1, \\ 2x_1 & +4x_2 & +2x_3 & = & 3. \end{cases}$$

solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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## Example

a)

$$\begin{cases} x_1 & +2x_2 & +x_3 & = & 1, \\ 2x_1 & +4x_2 & +2x_3 & = & 3. \end{cases}$$

solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 & +2x_2 & +x_3 & = & 1, \\ & & 0 & = & 1. \end{cases} \quad \text{X}$$

## Example

a)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 + 4x_2 + 2x_3 = 3. \end{cases}$$

solution:

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 + x_3 = 1, \\ \phantom{x_1 + 2x_2} \phantom{+ x_3} \phantom{=} \phantom{=} \phantom{=} 0 = 1. \end{cases} \quad \text{X alert False Statement}$$

## Example

a)

$$\begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 2x_1 + 4x_2 + 2x_3 = 3. \end{cases}$$

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$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 4 & 2 & 3 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 2x_2 + x_3 = 1, \\ 0 = 1. \end{cases} \quad \text{X alert False Statement}$$

The system is **inconsistent**. The system has **no solutions**.

## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix}$$

## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \text{REF}$$

## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$



## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

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## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

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$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \Rightarrow$$

## Example

b)

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ x_1 + x_2 + x_3 + 2x_4 + 2x_5 = 3, \\ x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 2. \end{cases}$$

Solution:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \Rightarrow \begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ \phantom{x_1} \phantom{x_2} \phantom{x_3} x_4 + x_5 = 1, \\ \phantom{x_1} \phantom{x_2} \phantom{x_3} \phantom{x_4} x_5 = -1. \end{cases}$$

## Example

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ \phantom{x_1 +} \phantom{x_2 +} \phantom{x_3 +} x_4 + x_5 = 1, \\ \phantom{x_1 +} \phantom{x_2 +} \phantom{x_3 +} \phantom{x_4 +} x_5 = -1. \end{cases}$$

## Example

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Setting  $x_2 = t \in \mathbb{R}$  and  $x_3 = s \in \mathbb{R}$ , then the system has an infinite number of solutions given by

## Example

$$\begin{cases} x_1 + x_2 + x_3 + x_4 + x_5 = 2, \\ \phantom{x_1 + x_2 + x_3} x_4 + x_5 = 1, \\ \phantom{x_1 + x_2 + x_3} \phantom{x_4} x_5 = -1. \end{cases}$$

Setting  $x_2 = t \in \mathbb{R}$  and  $x_3 = s \in \mathbb{R}$ , then the system has an infinite number of solutions given by

$$\begin{cases} x_1 = 1 - t - s, \\ x_2 = t, \\ x_3 = s, \\ x_4 = 2, \\ x_5 = -1. \end{cases}$$

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### Definition (RREF)

A matrix is said to be in **reduced row echelon form** if



**Definition (RREF)**

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A matrix is said to be in **reduced row echelon form** if

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- b) The first nonzero entry in each row (leading one) is the only nonzero entry in its columns.

## Example

a)  $A = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$

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a)  $A = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$  is in **RREF**.

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a)  $A = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$  is in **RREF**.

b)  $B = \begin{bmatrix} 1 & 3 & 1 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$

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## Example

a)  $A = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$  is in **RREF**.

b)  $B = \begin{bmatrix} 1 & 3 & 1 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$  is not in **RREF**, but it is in **REF**.

## Strategy

To solve a system of Linear equation using **Gauss-Jordan Reduction - GJR** , we apply the following steps:

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To solve a system of Linear equation using **Gauss-Jordan Reduction - GJR** , we apply the following steps:

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## Strategy

To solve a system of Linear equation using **Gauss-Jordan Reduction - GJR** , we apply the following steps:

- a) Apply Gaussian Elimination method without back substitution.
- b) Apply the **Elementary Row Operation** in order to transform the obtained matrix in **RREF**.

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix}$$

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix} \begin{array}{l} R_2 + 3R_1 \longrightarrow R_2 \\ R_3 + 2R_1 \longrightarrow R_3 \end{array}$$

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + 3R_1 \longrightarrow R_2 \\ R_3 + 2R_1 \longrightarrow R_3 \end{matrix} \Rightarrow$$

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 + x_2 - x_3 + 3x_4 = 0, \\ 3x_1 + x_2 - x_3 - x_4 = 0, \\ 2x_1 - x_2 - 2x_3 - x_4 = 0. \end{cases}$$

Solution:

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + 3R_1 \longrightarrow R_2 \\ R_3 + 2R_1 \longrightarrow R_3 \end{matrix} \Rightarrow \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix}$$

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

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Use **Gauss-Jordan Reduction** to solve the system

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Solution:

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + 3R_1 \longrightarrow R_2 \\ R_3 + 2R_1 \longrightarrow R_3 \end{matrix} \Rightarrow \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \begin{matrix} R_2 \times \frac{1}{4} \longrightarrow R_4 \end{matrix}$$



## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + 3R_1 \longrightarrow R_2 \\ R_3 + 2R_1 \longrightarrow R_3 \end{matrix} \implies \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \begin{matrix} R_2 \times \frac{1}{4} \longrightarrow R_4 \end{matrix} \implies$$

## Example

Use **Gauss-Jordan Reduction** to solve the system

$$\begin{cases} -x_1 & +x_2 & -x_3 & +3x_4 & = & 0, \\ 3x_1 & +x_2 & -x_3 & -x_4 & = & 0, \\ 2x_1 & -x_2 & -2x_3 & -x_4 & = & 0. \end{cases}$$

Solution:

$$\begin{aligned} \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 & 0 \\ 2 & -1 & -2 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + 3R_1 \longrightarrow R_2 \\ R_3 + 2R_1 \longrightarrow R_3 \end{matrix} &\Rightarrow \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \\ \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 4 & -4 & 8 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} R_2 \times \frac{1}{4} \longrightarrow R_4 &\Rightarrow \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \end{aligned}$$

## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix}$$

## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} R_3 - R_2 \rightarrow R_3$$

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$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} R_3 - R_2 \rightarrow R_3 \Rightarrow$$

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## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \begin{matrix} R_3 - R_2 \longrightarrow R_3 \end{matrix} \Rightarrow \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix} \begin{matrix} R_3 \times -\frac{1}{3} \longrightarrow R_3 \\ R_1 \times (-1) \longrightarrow R_1 \end{matrix}$$



## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \xrightarrow{R_3 - R_2 \rightarrow R_3} \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix} \xrightarrow{\begin{array}{l} R_3 \times -\frac{1}{3} \rightarrow R_3 \\ R_1 \times (-1) \rightarrow R_1 \end{array}} \Rightarrow$$

## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \xrightarrow{R_3 - R_2 \rightarrow R_3} \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix} \xrightarrow{\begin{array}{l} R_3 \times -\frac{1}{3} \rightarrow R_3 \\ R_1 \times (-1) \rightarrow R_1 \end{array}} \begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \xrightarrow{R_3 - R_2 \rightarrow R_3} \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix} \xrightarrow{\begin{matrix} R_3 \times -\frac{1}{3} \rightarrow R_3 \\ R_1 \times (-1) \rightarrow R_1 \end{matrix}} \begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

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## Example

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$$\begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + R_3 \longrightarrow R_2 \\ R_1 - R_3 \longrightarrow R_1 \end{matrix}$$

## Example

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$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix} \begin{matrix} R_3 \times -\frac{1}{3} \longrightarrow R_3 \\ R_1 \times (-1) \longrightarrow R_1 \end{matrix} \Rightarrow \begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + R_3 \longrightarrow R_2 \\ R_1 - R_3 \longrightarrow R_1 \end{matrix} \Rightarrow$$

## Example

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 1 & -4 & 5 & 0 \end{bmatrix} \begin{matrix} R_3 - R_2 \longrightarrow R_3 \end{matrix} \Rightarrow \begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & -3 & 3 & 0 \end{bmatrix} \begin{matrix} R_3 \times -\frac{1}{3} \longrightarrow R_3 \\ R_1 \times (-1) \longrightarrow R_1 \end{matrix} \Rightarrow \begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 1 & -3 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} \begin{matrix} R_2 + R_3 \longrightarrow R_2 \\ R_1 - R_3 \longrightarrow R_1 \end{matrix} \Rightarrow \begin{bmatrix} 1 & -1 & 0 & -2 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

## Example

$$\begin{bmatrix} 1 & -1 & 0 & -2 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

## Example

$$\begin{bmatrix} 1 & -1 & 0 & -2 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} R_1 + R_2 \rightarrow R_1$$



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$$\begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 & & -x_4 & = & 0, \\ & x_2 & +x_4 & = & 0, \\ & & x_3 & -x_4 & = & 0. \end{cases}$$

## Example

$$\begin{bmatrix} 1 & -1 & 0 & -2 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix} R_1 + R_2 \longrightarrow R_1 \Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{bmatrix}$$

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Setting  $x_4 = t \in \mathbb{R}$ , then the system has an infinite number of solutions given by

## Example

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Setting  $x_4 = t \in \mathbb{R}$ , then the system has an infinite number of solutions given by

$$\begin{cases} x_1 & = & t, \\ x_2 & = & -t, \\ x_3 & = & t, \\ x_4 & = & t. \end{cases}$$