Forelesning 11

Vi kan finne de korteste veiene fra hver node etter tur, men mange av delproblemene vil overlappe – om vi har mange nok kanter lønner det seg å bruke dynamisk programmering med dekomponeringen «Skal vi innom k eller ikke?»

Pensum

☐ Kap. 25. All-pairs shortest paths: Innledning, 25.2 og 25.3

Læringsmål

- [K₁] Forstå forgjengerstrukturen for alle-til-alle-varianten av korteste vei-problemet
 Operasjoner: Print-All-Pairs-Shortest-Path
- [K₂] Forstå Floyd-Warshall
- [K₃] Forstå Transitive-Closure
- [K₄] Forstå Johnson

Forelesningen filmes











1. Johnsons algoritme

2. Transitiv lukning

3. Floyd-Warshall

Johnsons algoritme

Efficient Algorithms for Shortest Paths in Sparse Networks

DONALD B. JOHNSON

The Pennsylvania State University, University Park, Pennsylvania

ABSTRACT Algorithms for finding shortest paths are presented which are faster than algorithms previously known on networks which are relatively sparse in arcs. Known results which the results of this paper extend are surveyed briefly and analyzed. A new implementation for priority queues is employed, and a class of "arc set partition" algorithms is introduced. For the single source problem on networks with nonnegative arcs a running

Input: En vektet, rettet graf G = (V, E) uten negative sykler, der $V = \{1, ..., n\}$, og vektene er gitt av matrisen $W = (w_{ij})$.

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Output: En $n \times n$ -matrise D = (d_{ij}) med avstander, dvs., $d_{ij} = \delta(i, j)$.

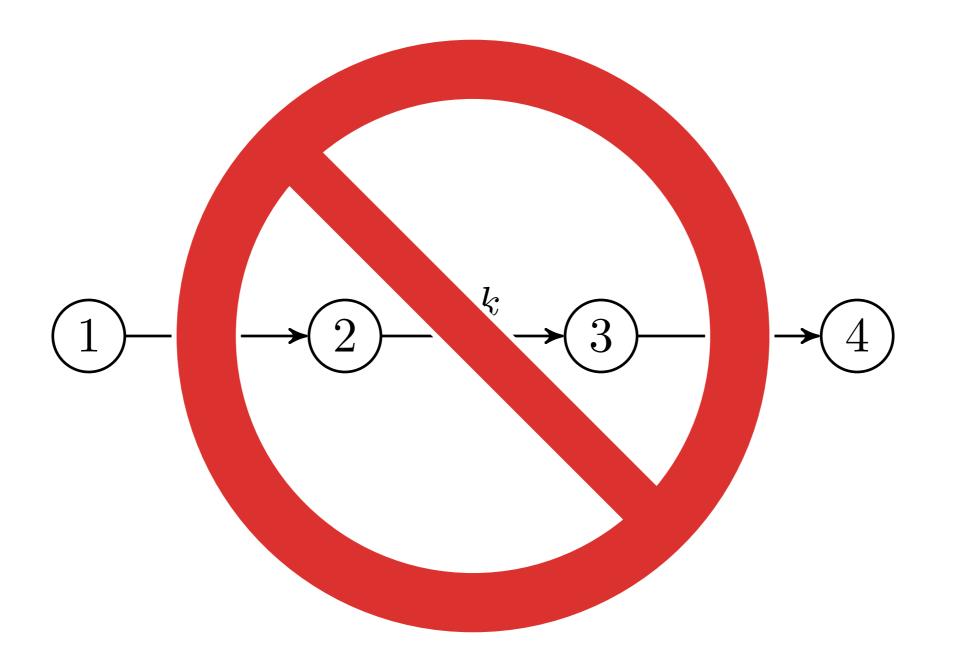
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For spinkle grafer: Dijkstra fra hver node! Men ... hva om vi har negative kanter?

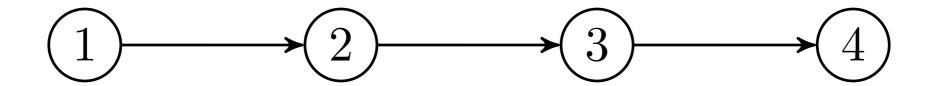
$$1 \xrightarrow{+k} 2 \xrightarrow{+k} 3 \xrightarrow{+k} 4$$

Fast økning: Stier med mange kanter taper på det

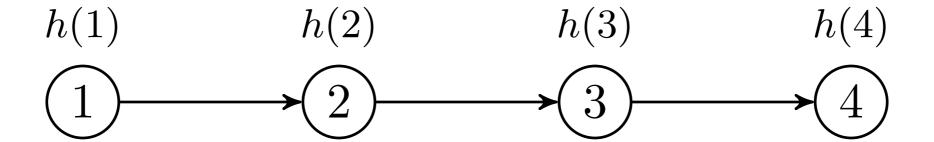


Fast økning: Stier med mange kanter taper på det

korteste vei > johnson



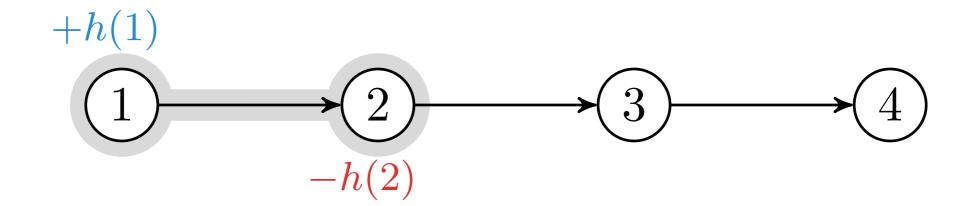
Vi kan tillate oss en <u>teleskopsum</u>...



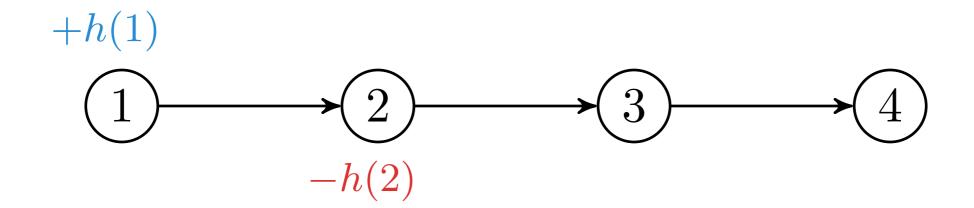
korteste vei > johnson

$$1 \longrightarrow 2 \longrightarrow 4$$

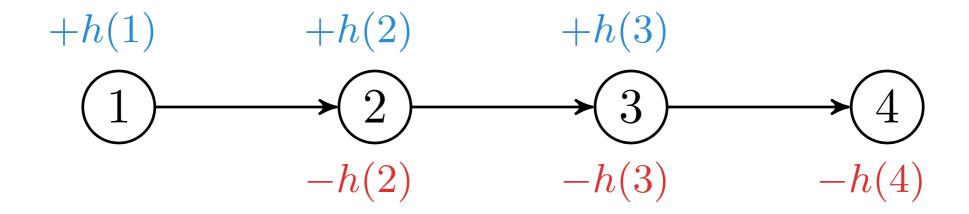
Vekten w(u,v) økes med differansen h(u) - h(v)



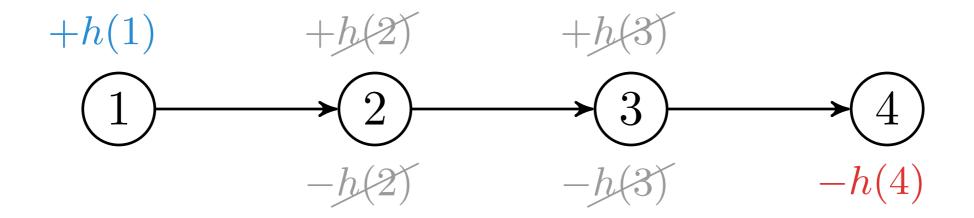
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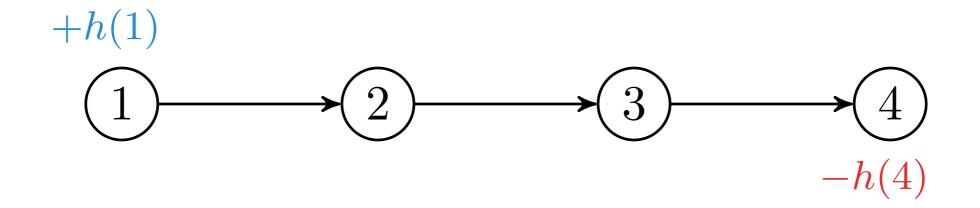
Positive og negative ledd opphever hverandre...

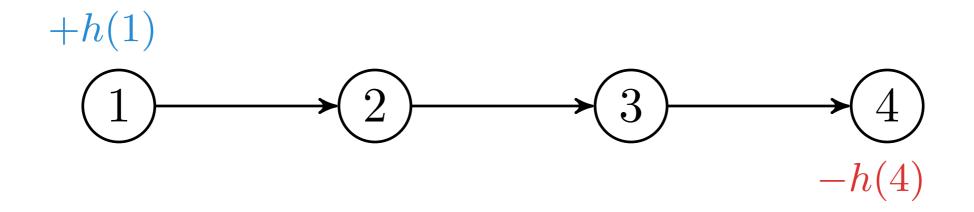


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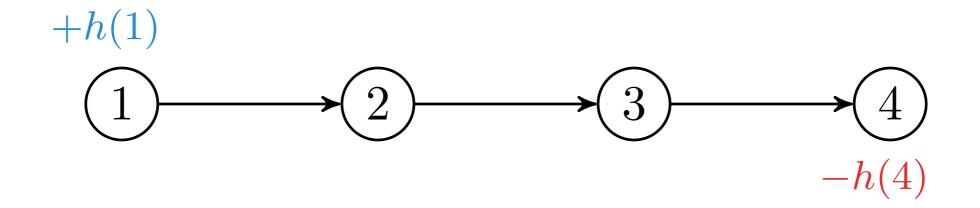


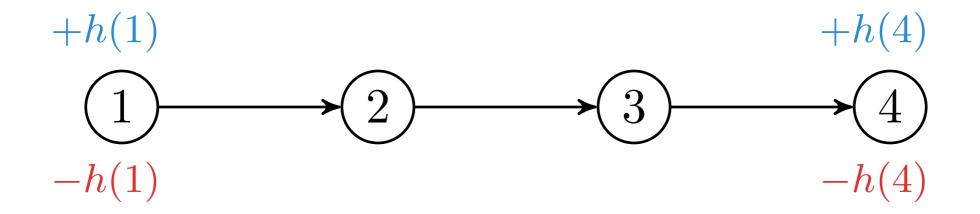
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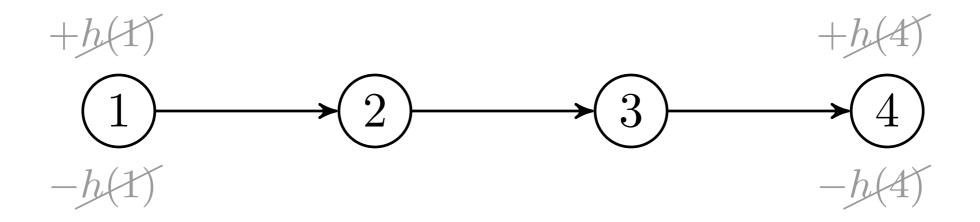


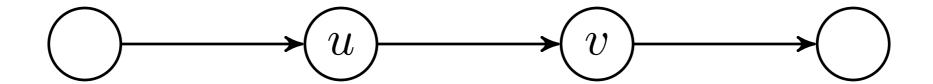


Men disse deles av alle stier mellom disse nodene!

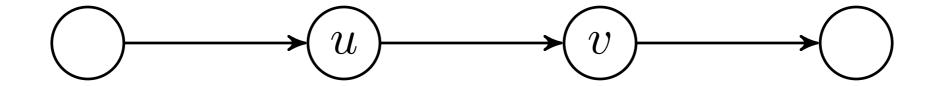




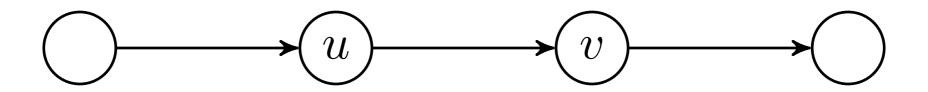




Hvordan sikrer vi ikke-negative vekter?

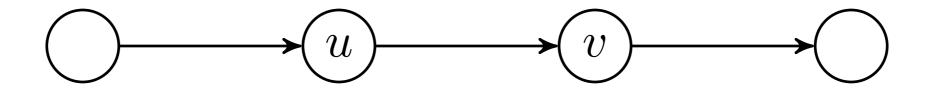


Vi må ha $w(u,v) + h(u) - h(v) \ge 0$, dvs. $w(u,v) + h(u) \ge h(v)$

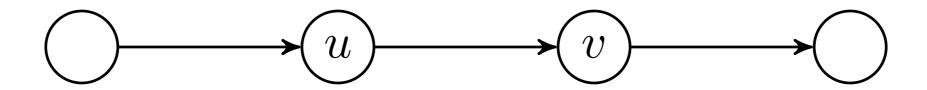


$$w(u,v) + h(u) \geqslant h(v)$$

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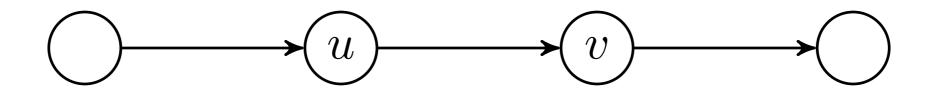


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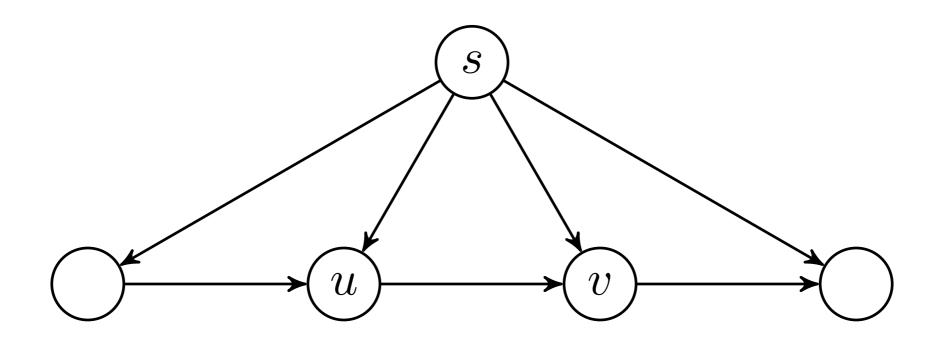
$$w(u, v) + h(u) \ge h(v)$$
$$w(u, v) + \delta(s, u) \ge \delta(s, v)$$

Men hva er s? Vi må sikre at vi når alle...



$$w(u, v) + h(u) \ge h(v)$$
$$w(u, v) + \delta(s, u) \ge \delta(s, v)$$

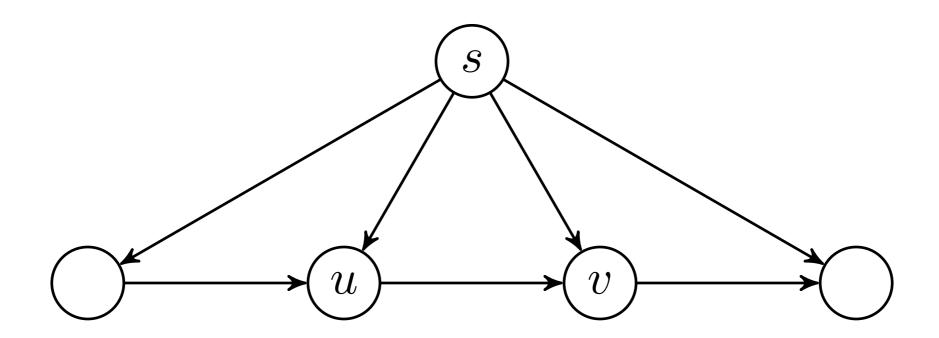
Vi kan legge til en ny node!



$$w(u, v) + h(u) \ge h(v)$$

$$w(u, v) + \delta(s, u) \ge \delta(s, v)$$

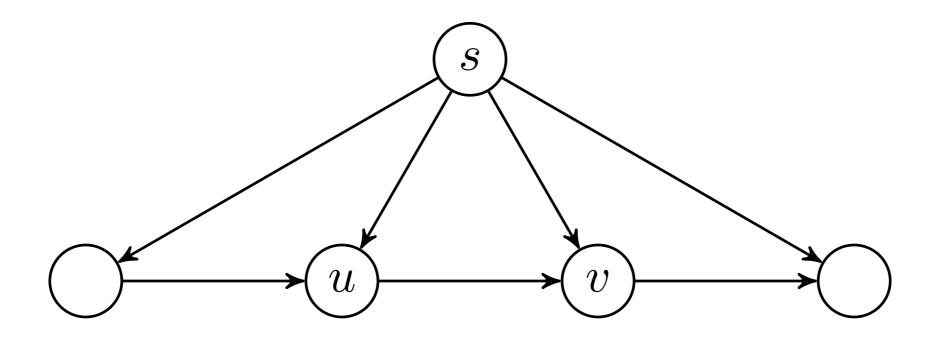
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$$w(u, v) + h(u) \ge h(v)$$

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Kantene fra s kan f.eks. få vekt 0



$$w(u, v) + h(u) \geqslant h(v)$$
$$w(u, v) + \delta(s, u) \geqslant \delta(s, v)$$

(Merk: Vi verken innfører eller fjerner negative sykler)

G graf w vekting

JOHNSON(G, w)

Forenkling: Antar at vi ikke har negative sykler, heller enn å sjekke for det – dvs., jeg ignorerer returverdien fra Bellman-Ford. Vil normalt avbryte om den er false (som de gjør i boka).

Johnson(G, w)

1 construct G' with start node s

G graf
w vekting

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(Cormen et al. bruker her G', men s er overflødig)

- construct G' with start node s
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- h(v) = v.d

graf vekting

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G graf
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 $v \mod \epsilon$

 $h \quad \delta(s,v)$

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G graf

w vekting

u node

 $v \mod \epsilon$

 $h \quad \delta(s,v)$

 \hat{w} ny vekting

$$h(v) \leq h(u) + w(u, v) \implies \hat{w}(u, v) \geqslant 0$$

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 d_{uv} $\delta(u,v)$

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11
12
    return D
```

G graf w vekting u node v node h $\delta(s,v)$ \hat{w} ny vekting d_{uv} $\delta(u,v)$

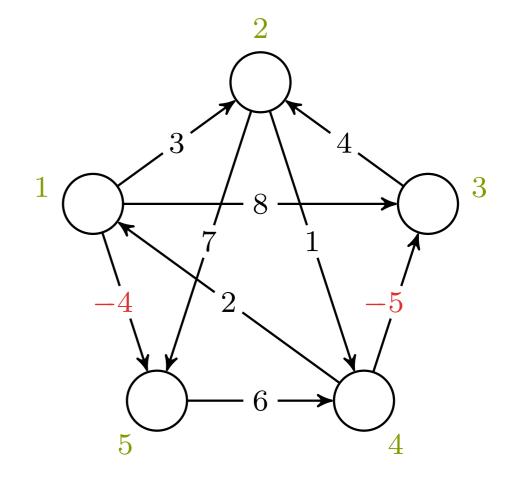
Rett fordi $w(p) \leq w(q) \iff \hat{w}(p) \leq \hat{w}(q)$ for stier $u \stackrel{p,q}{\leadsto} v$

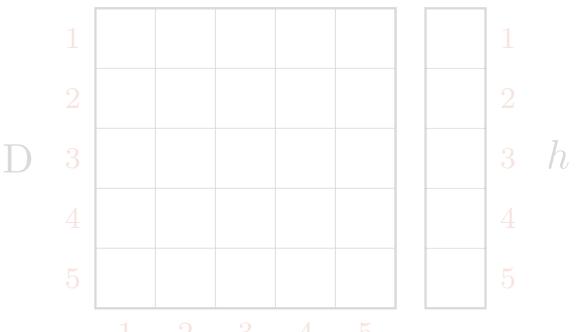
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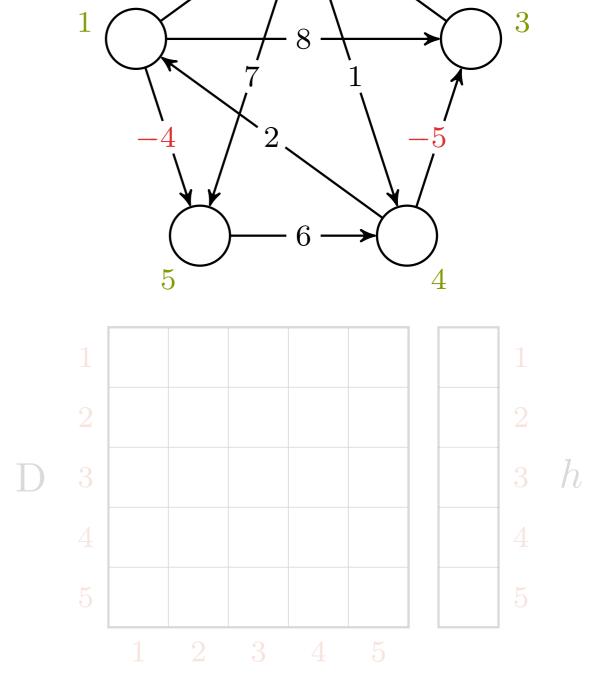
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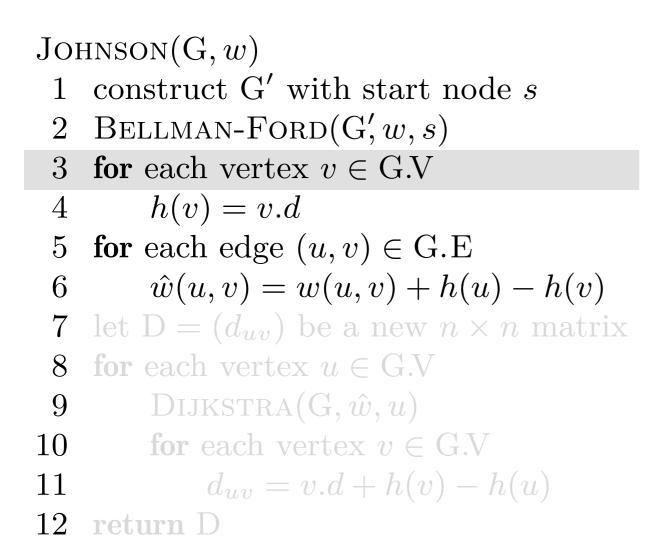


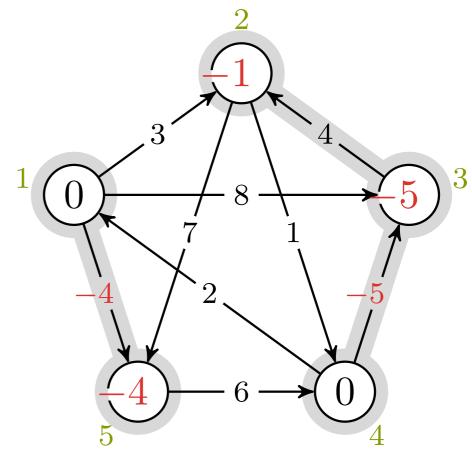


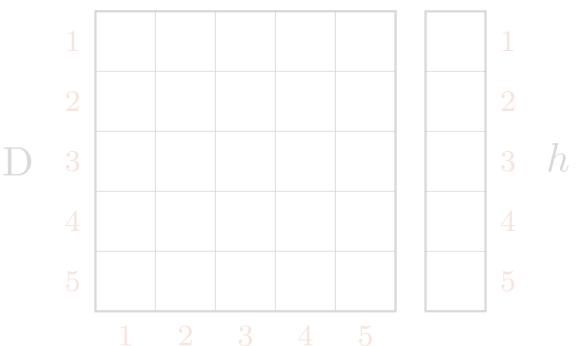
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Merk: s er ikke tegnet inn







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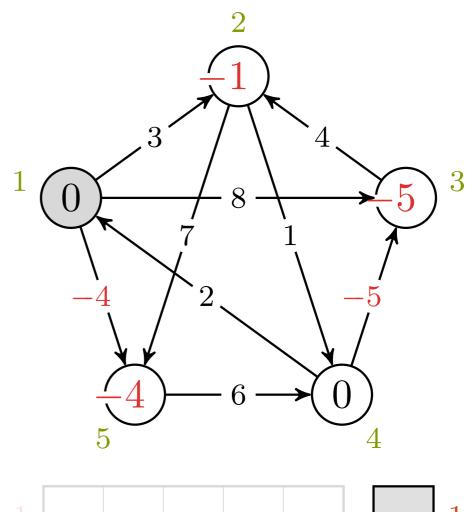
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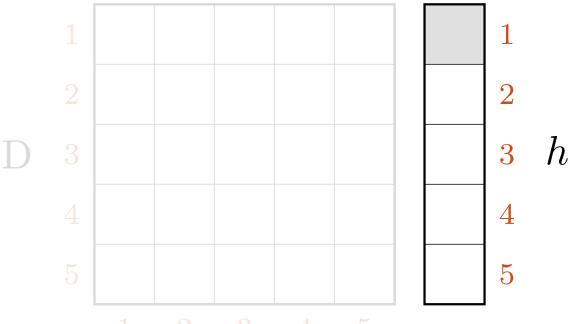
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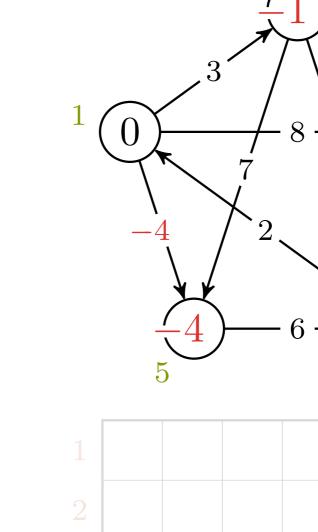
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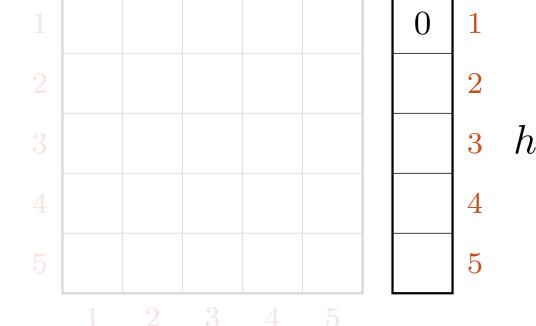
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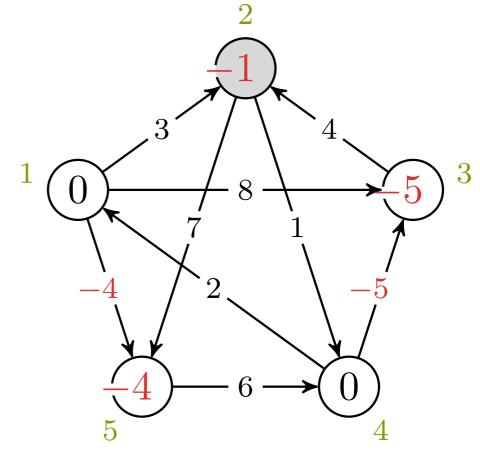
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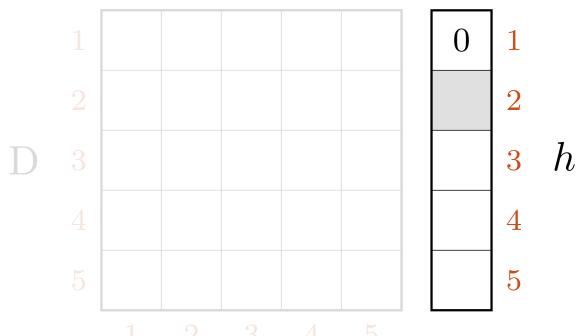
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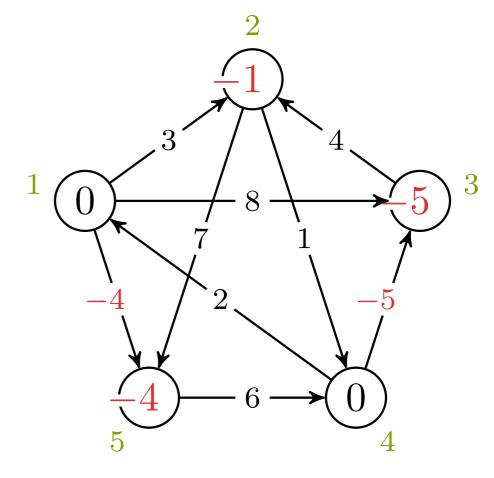
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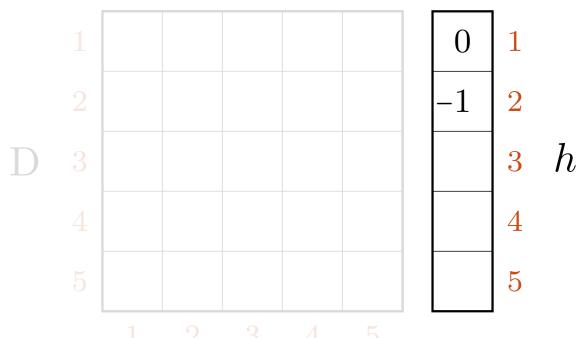
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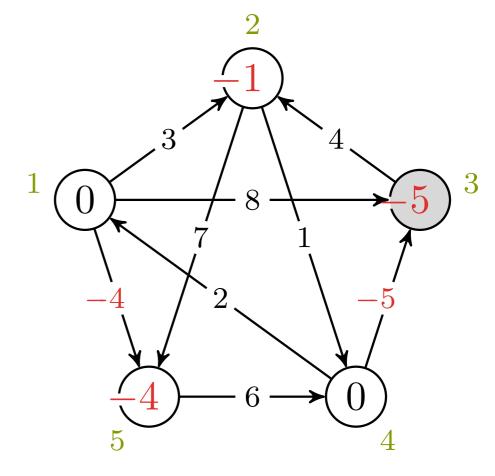
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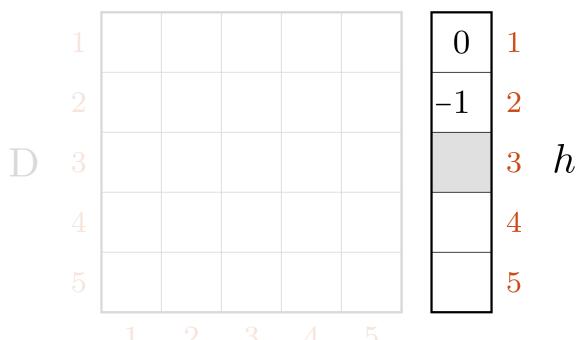
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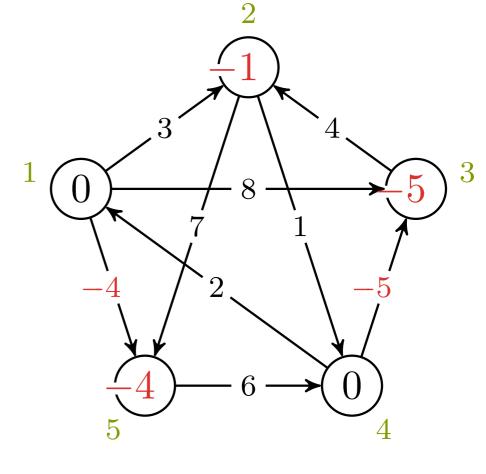
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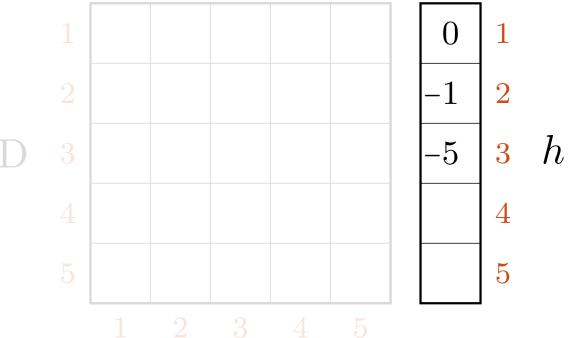
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7 let D = (d_{uv}) be a new $n \times n$ matrix

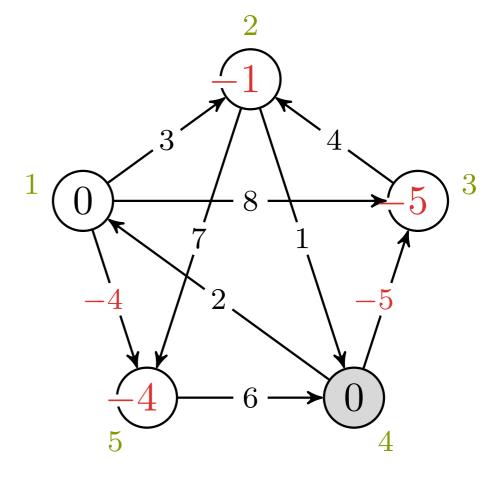
8 for each vertex $u \in G.V$

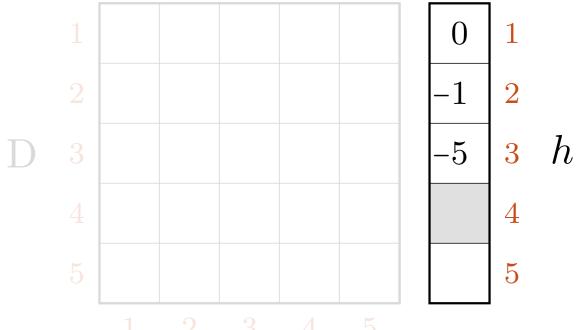
9 DIJKSTRA(G, \hat{w} , u)

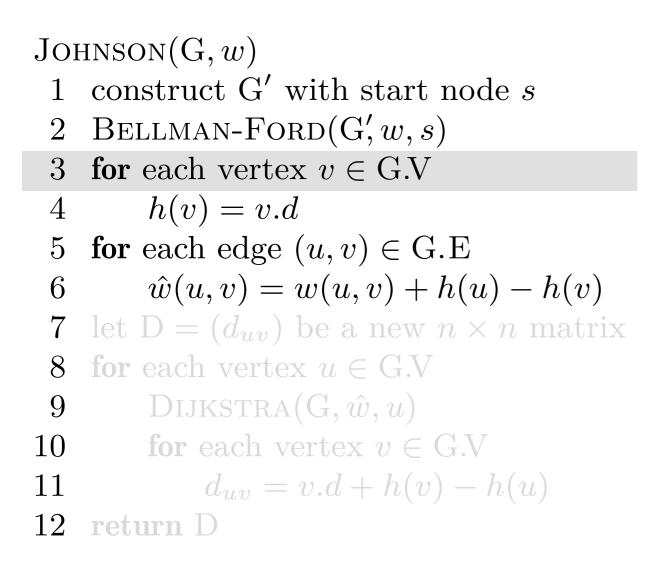
10 for each vertex $v \in G.V$

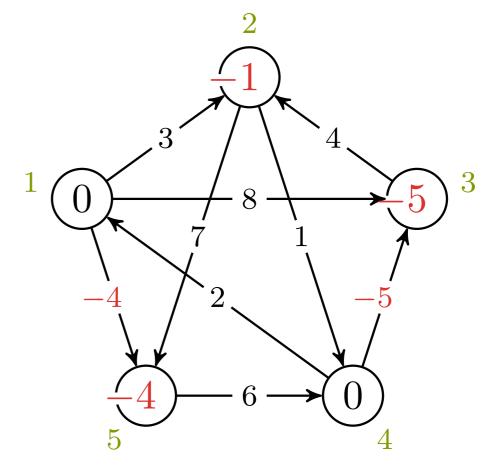
11 $d_{uv} = v.d + h(v) - h(u)$

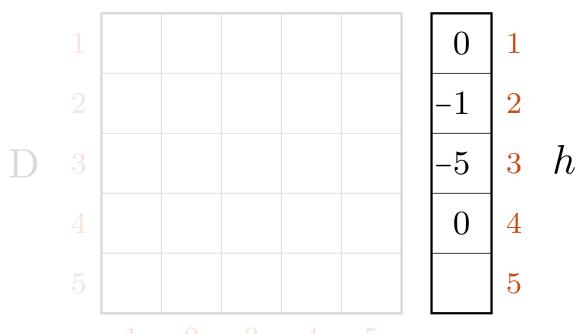
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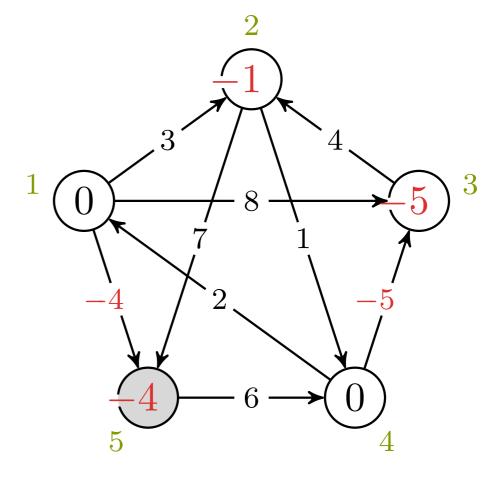
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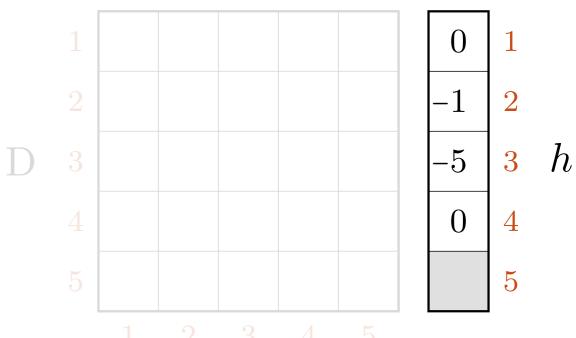
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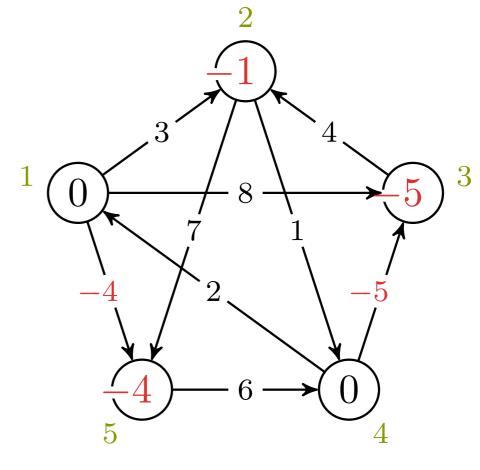
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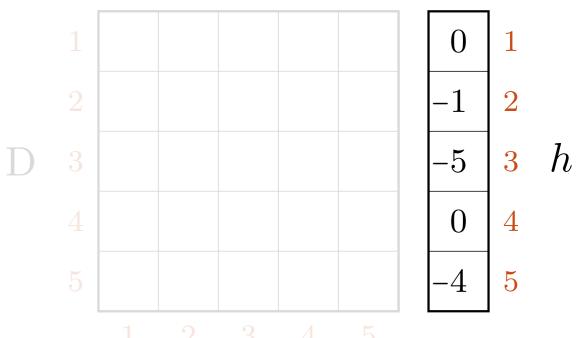
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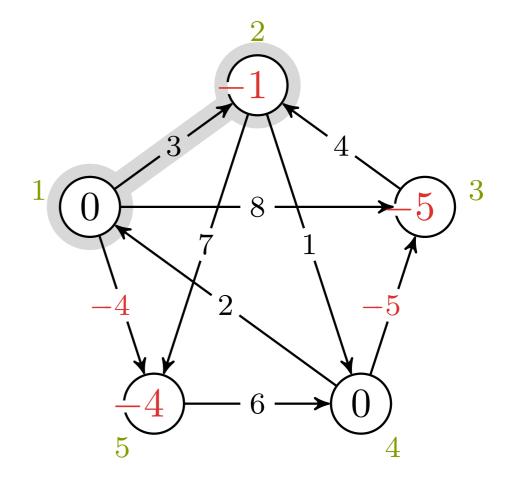
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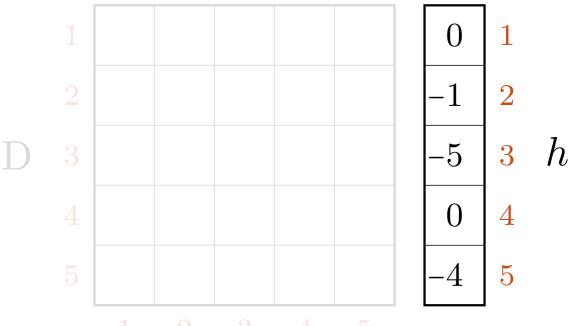
11 $d_{uv} = v.d + h(v) - h(u)$

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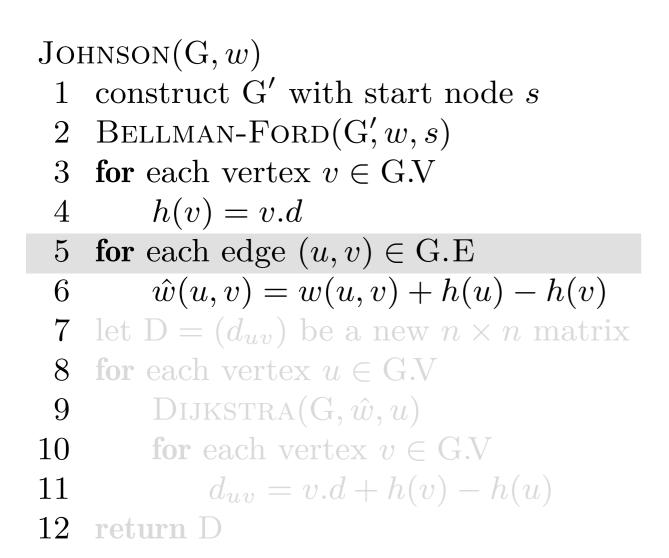


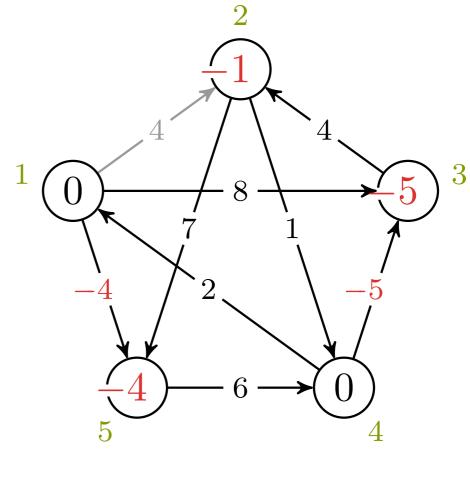


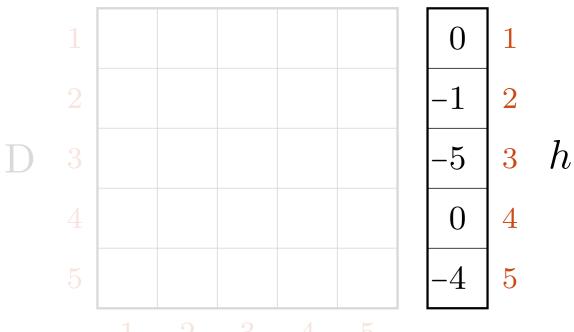
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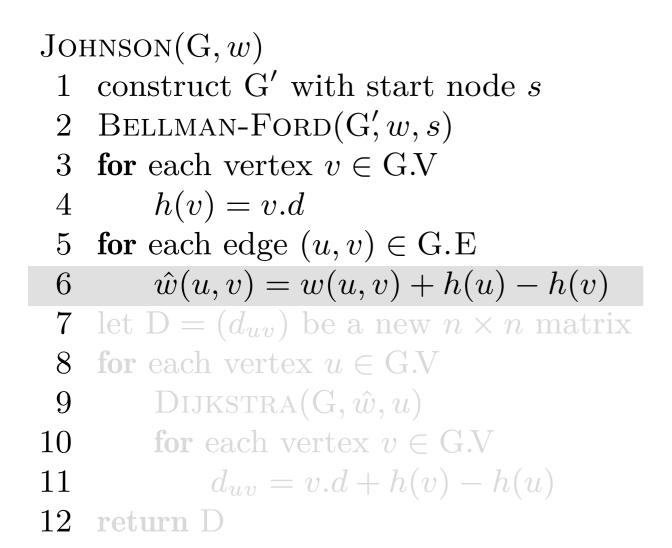
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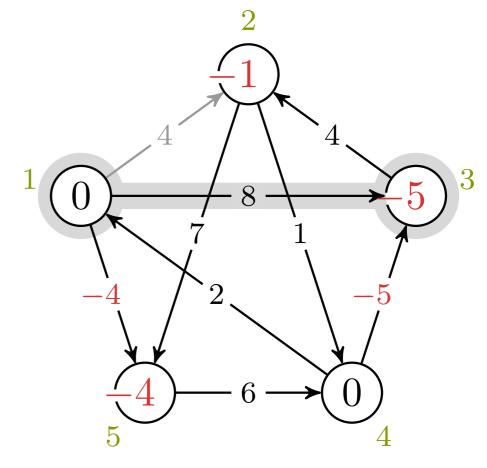
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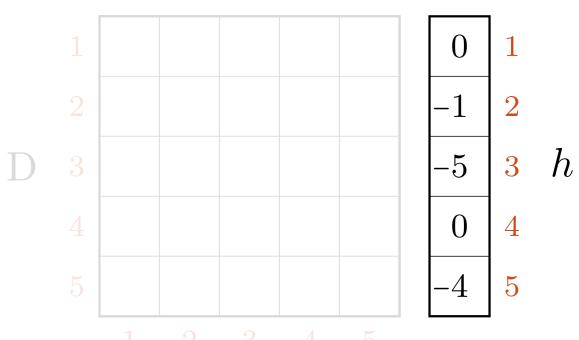












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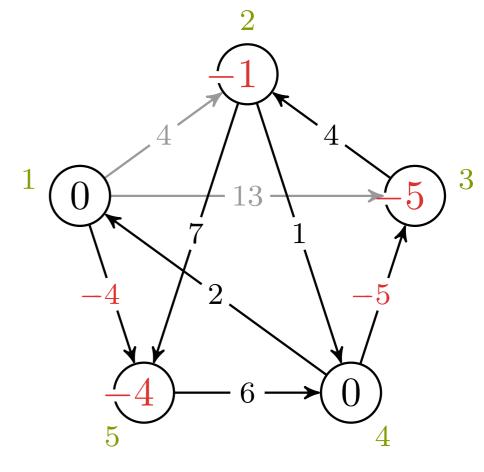
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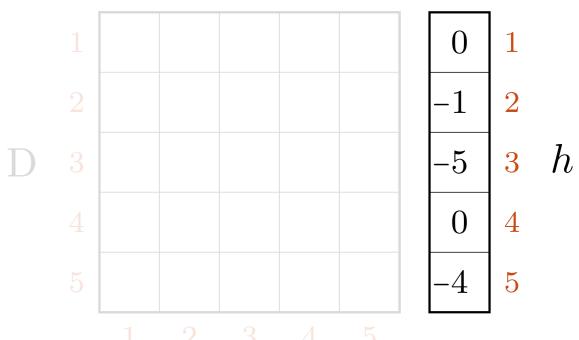
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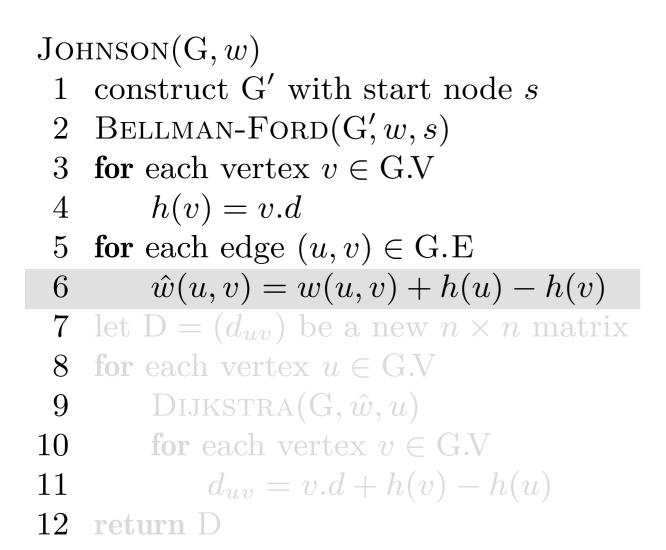
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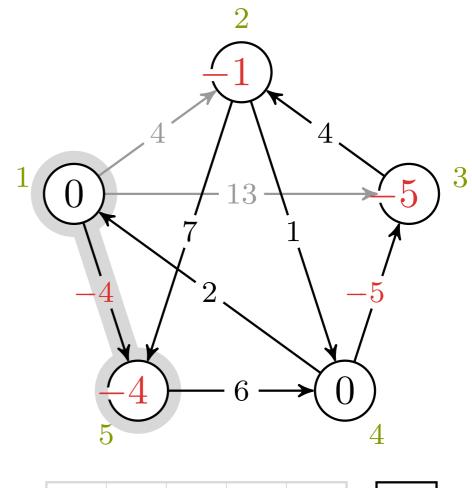
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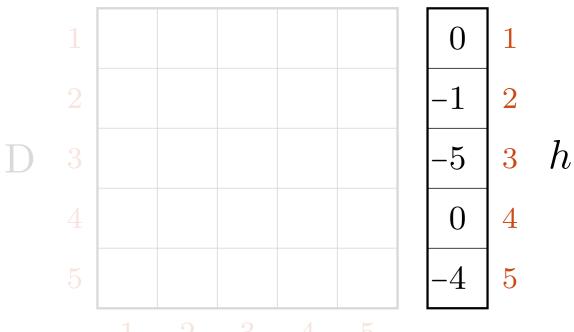
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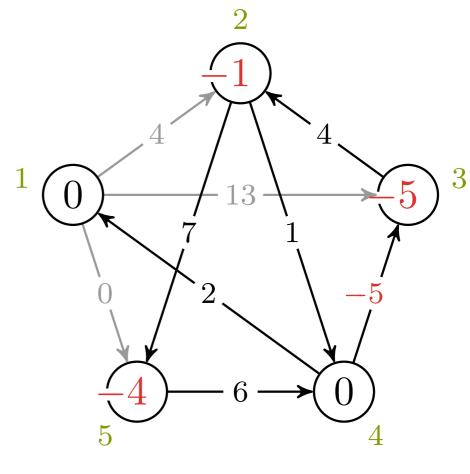
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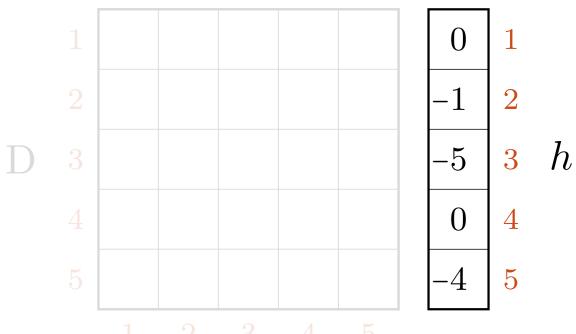
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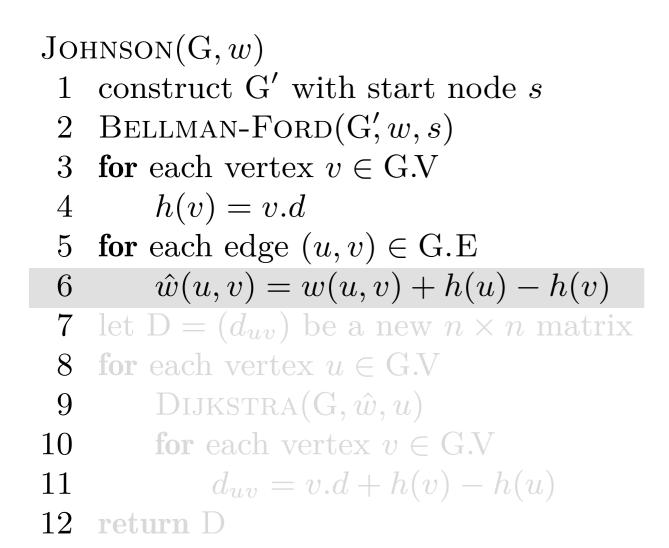
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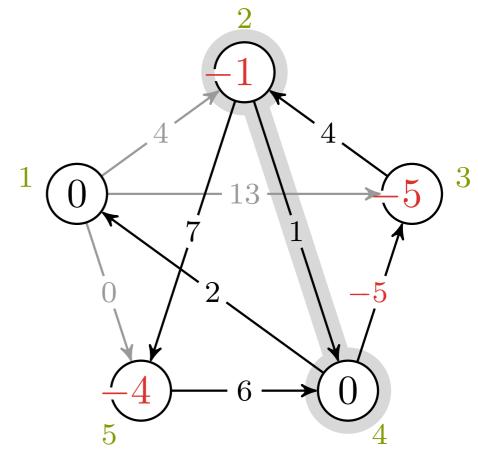
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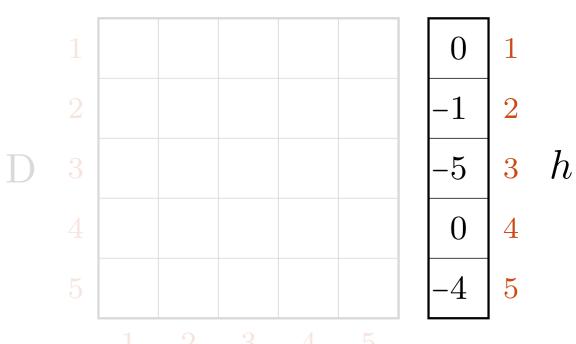
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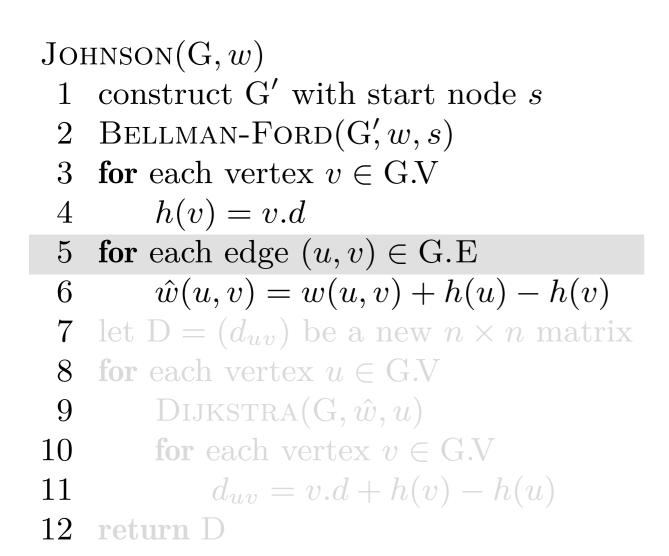


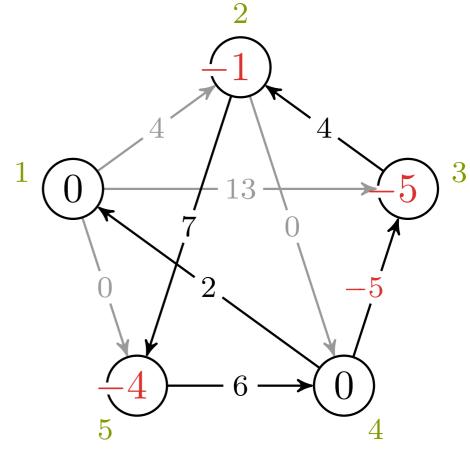


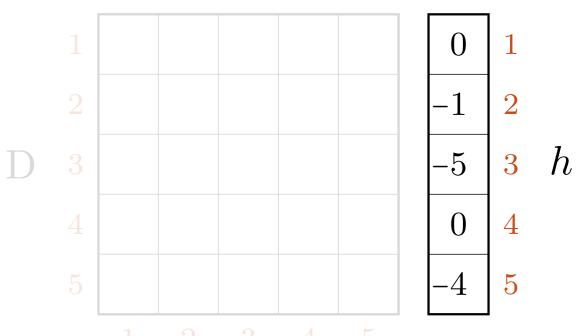


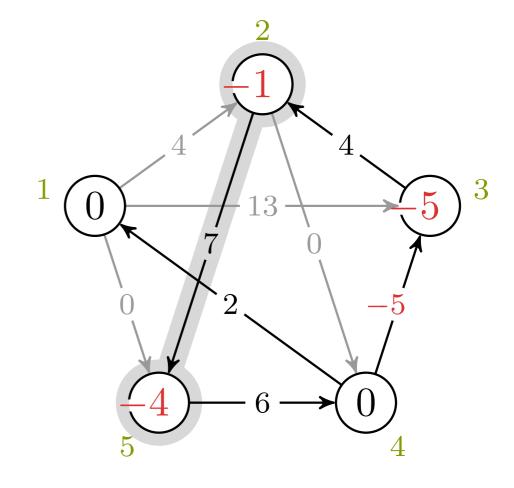


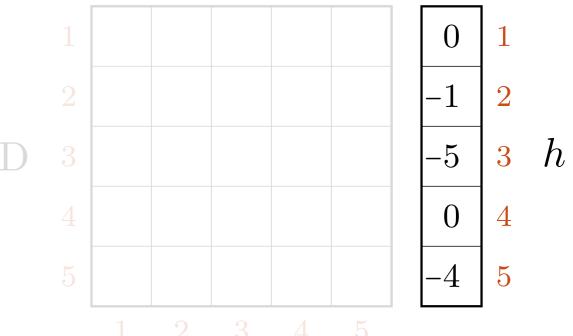












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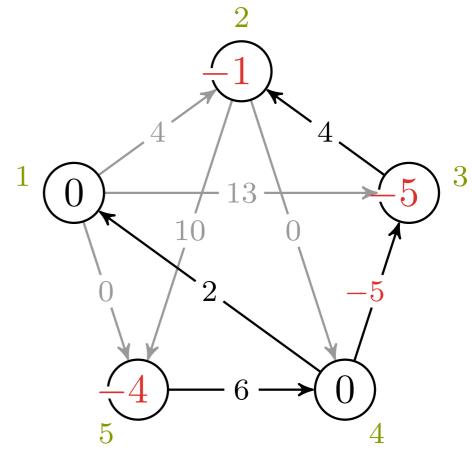
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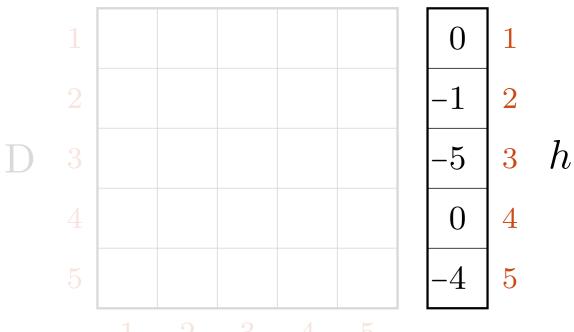
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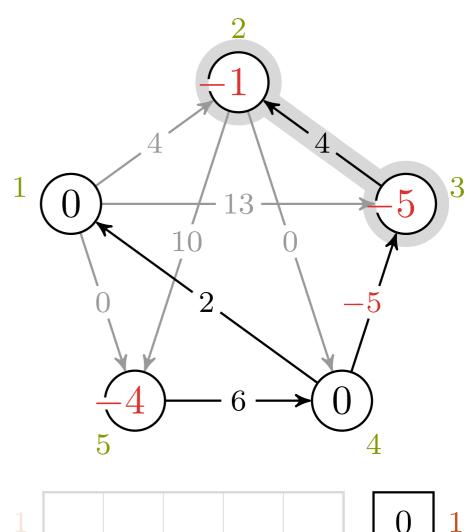
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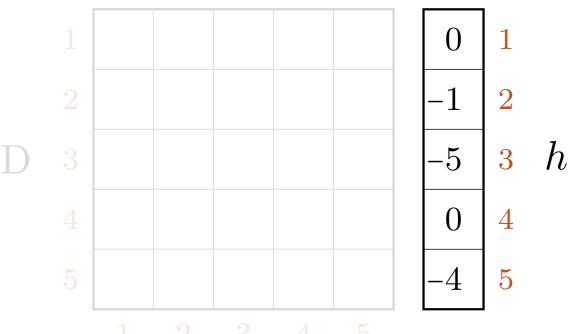
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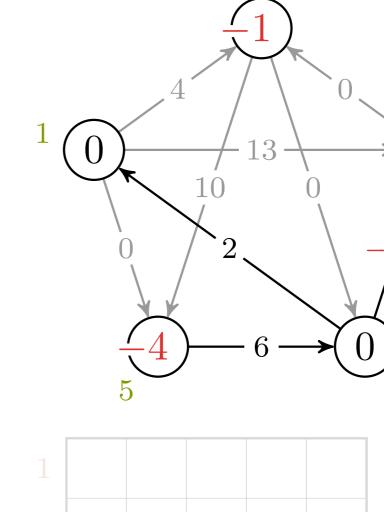
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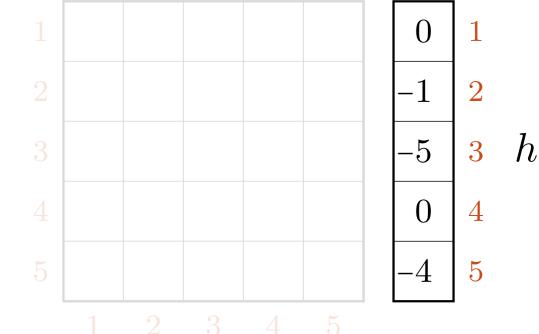
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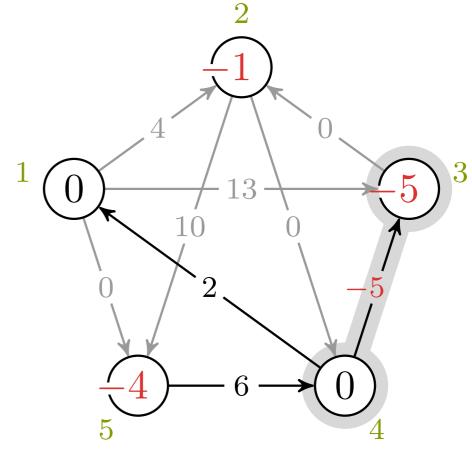
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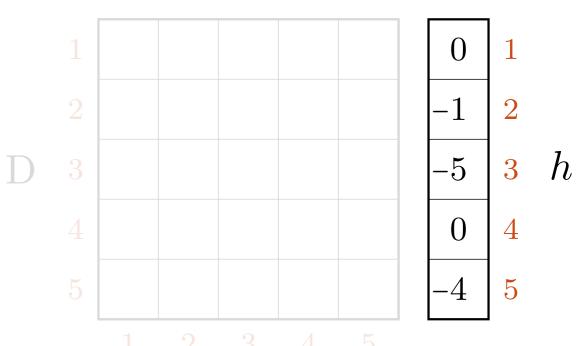
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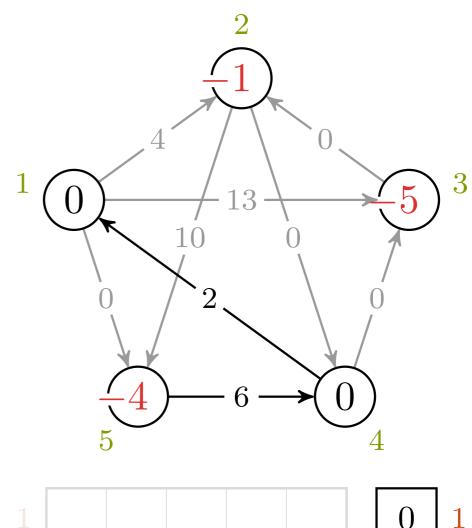
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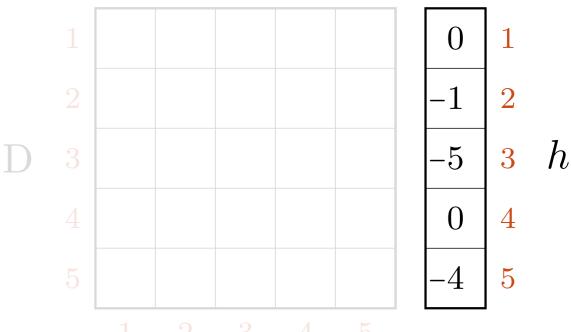
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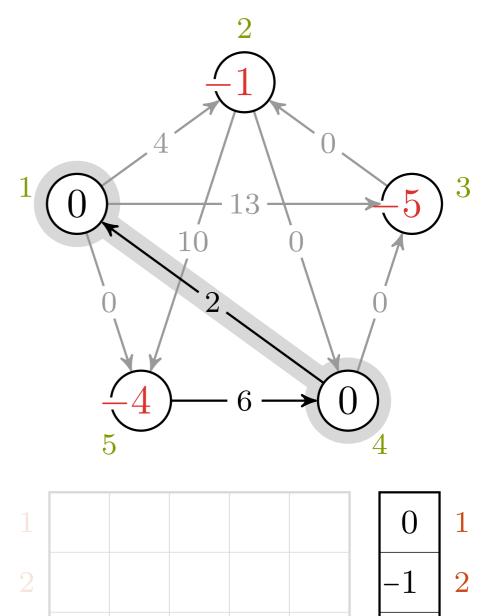
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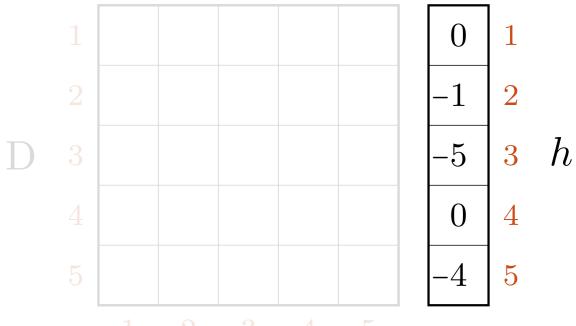
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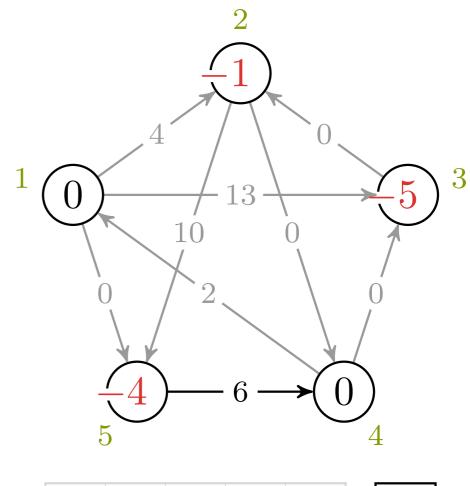
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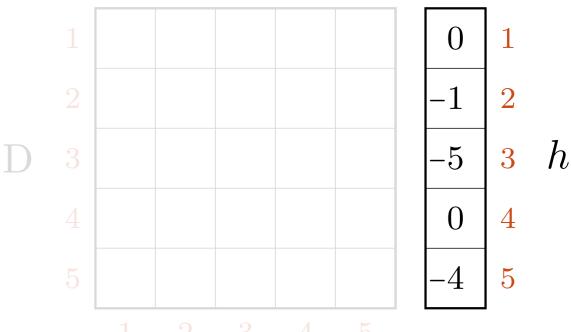
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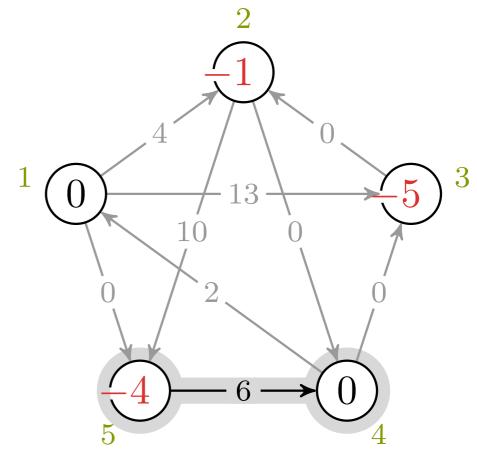
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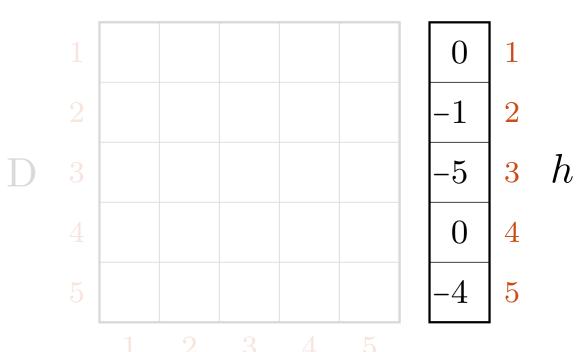
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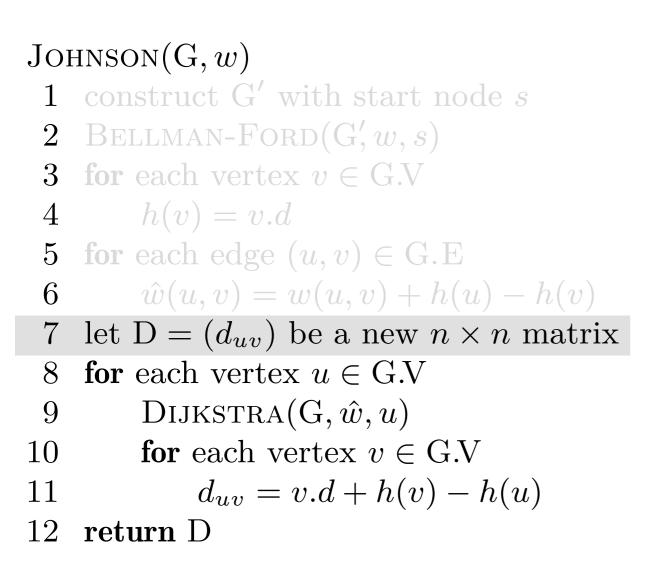
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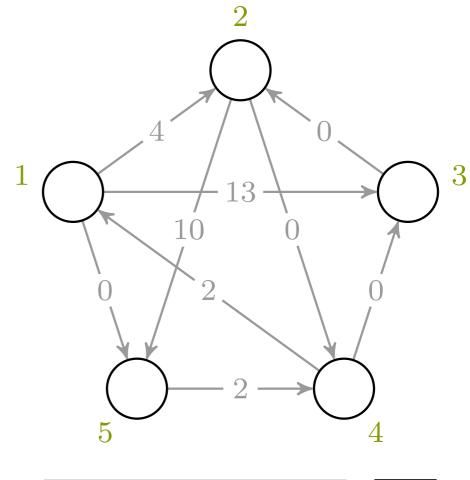
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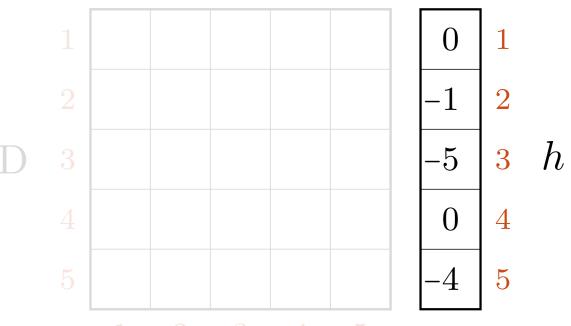
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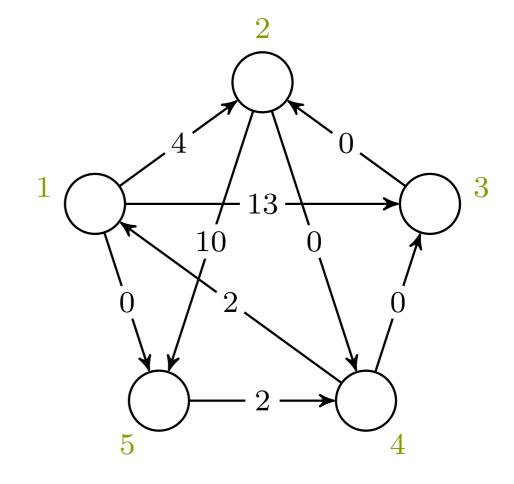


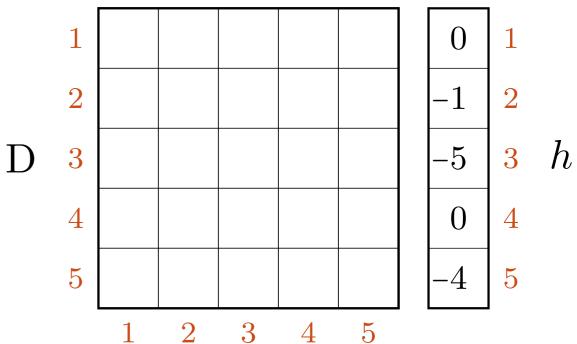






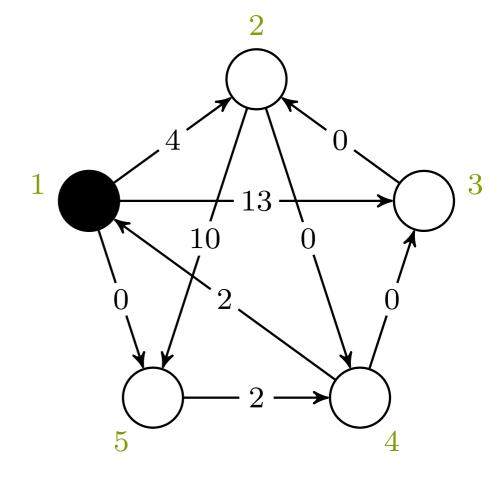


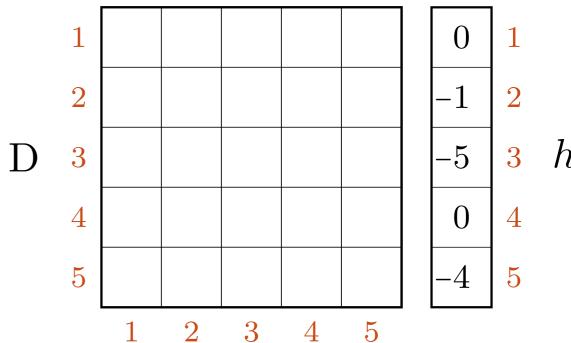




JOHNSON(G, w)

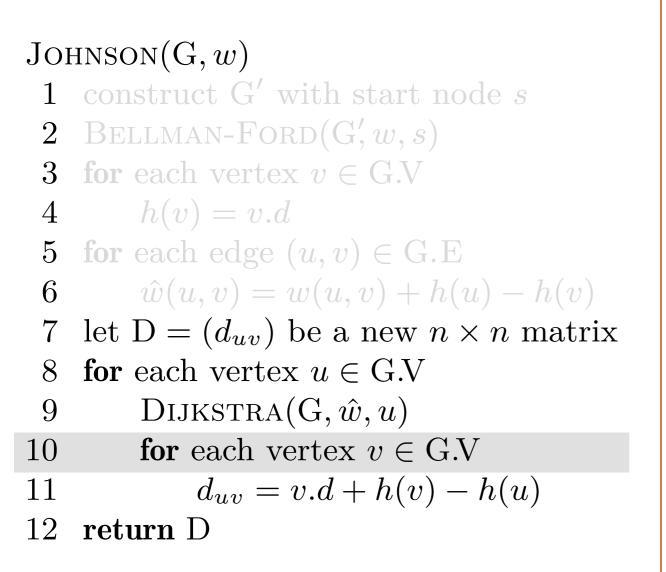
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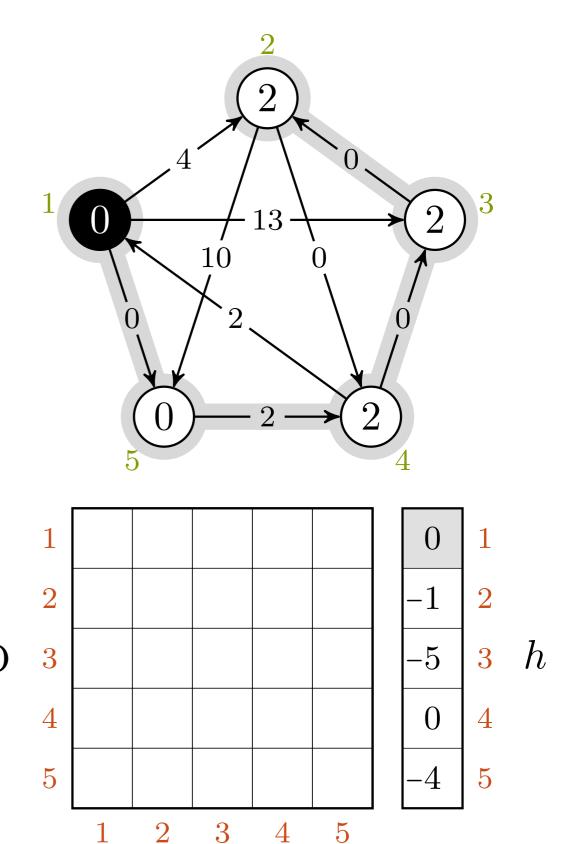


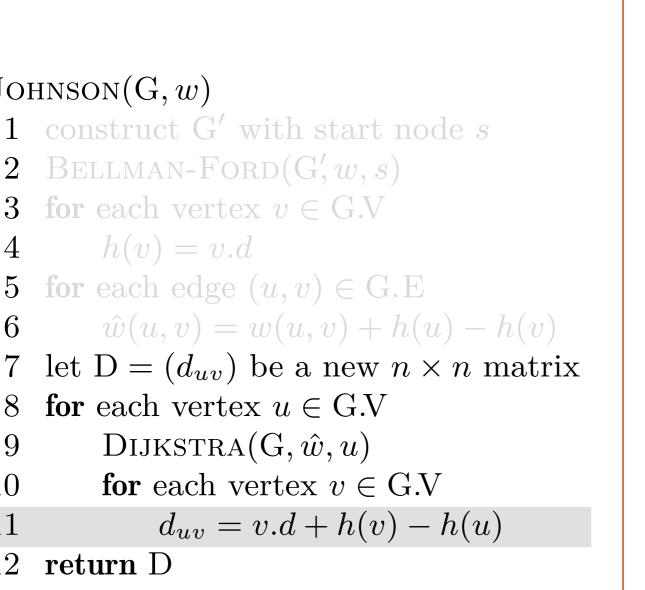


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10

11

12

Bellman-Ford(G', w, s)

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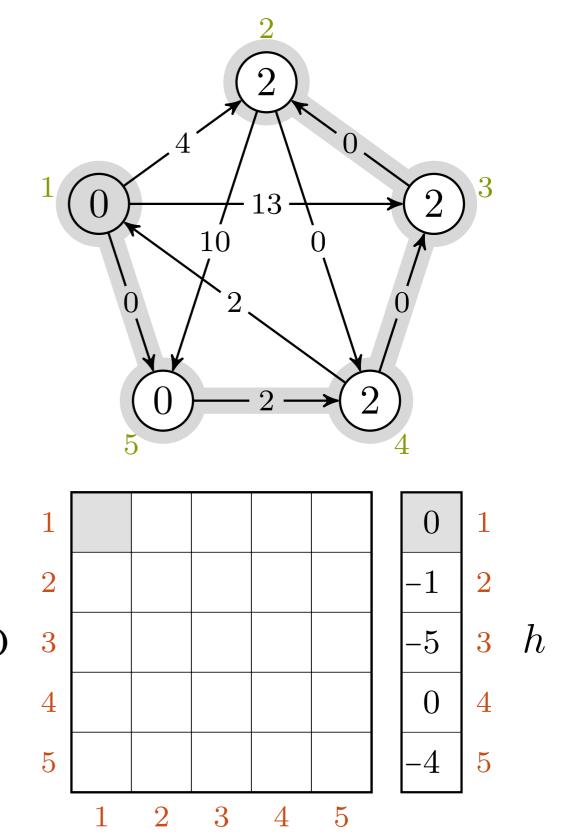
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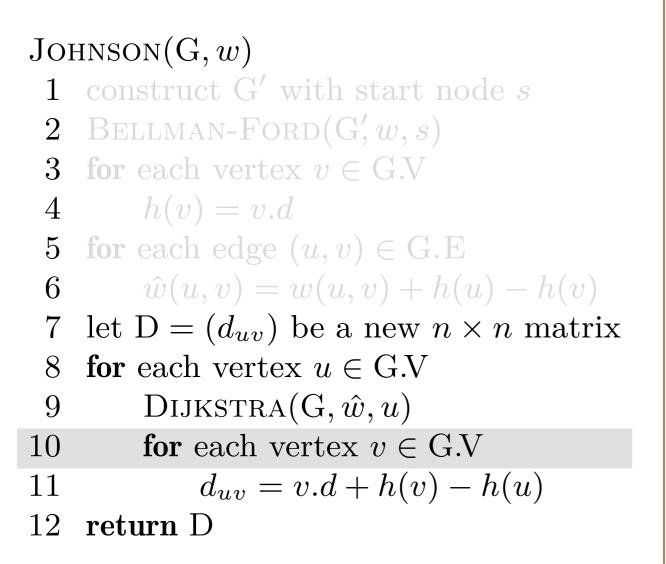
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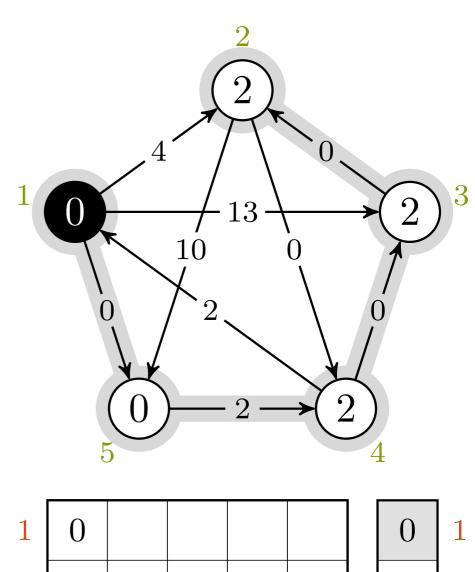
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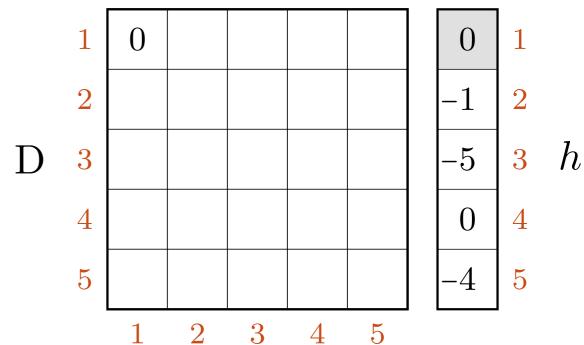
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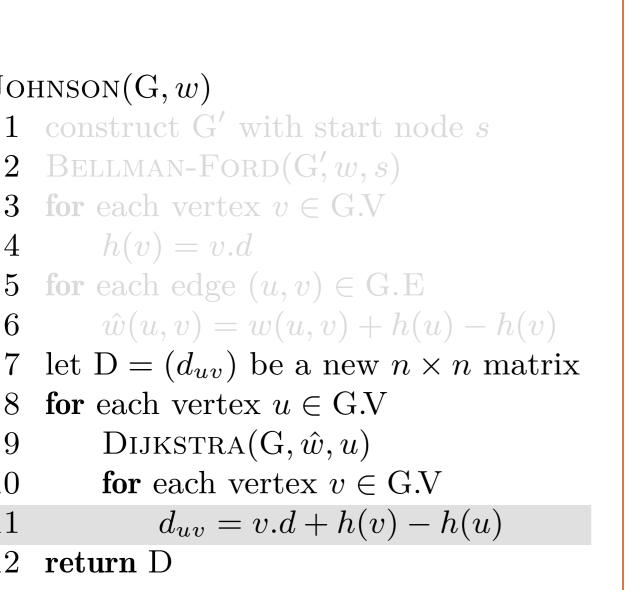
h(v) = v.d











JOHNSON(G, w)

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10

11

12

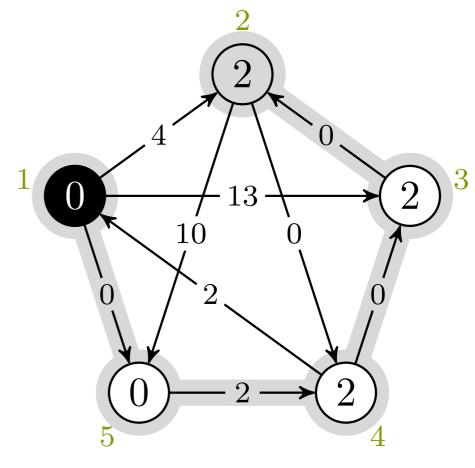
Bellman-Ford(G', w, s)

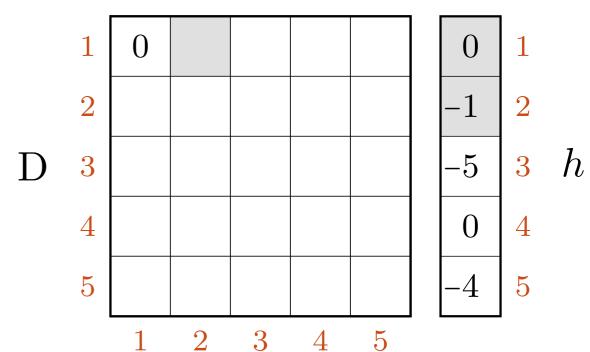
for each vertex $v \in G.V$

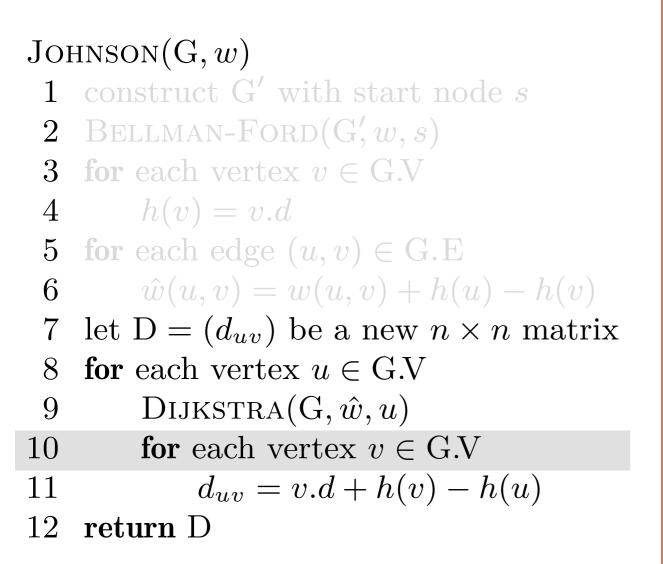
for each vertex $u \in G.V$

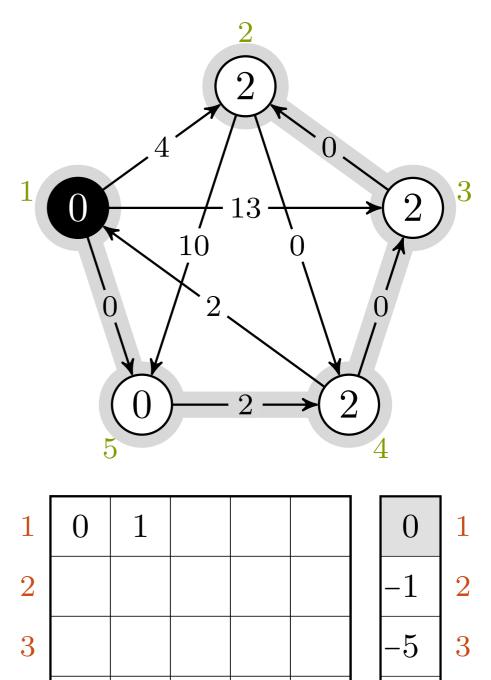
DIJKSTRA (G, \hat{w}, u)

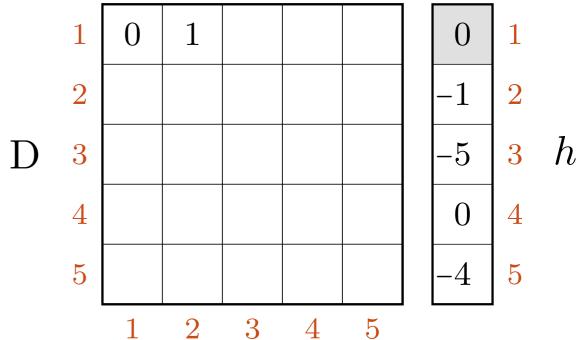
h(v) = v.d



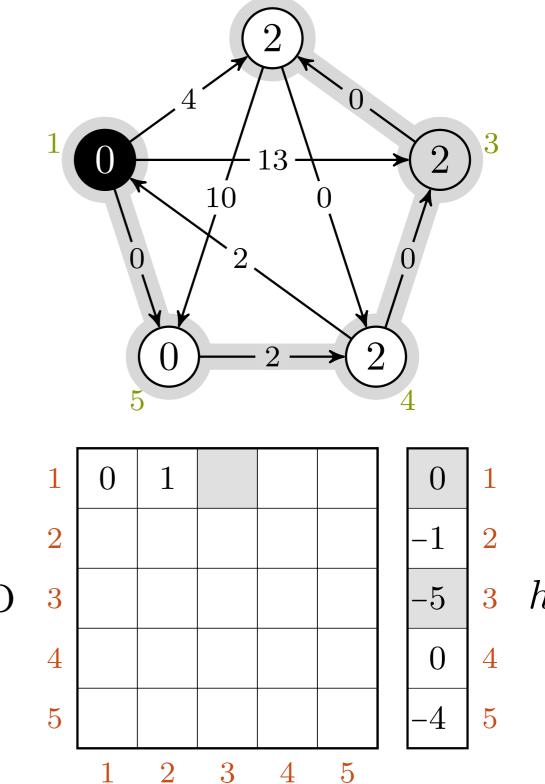










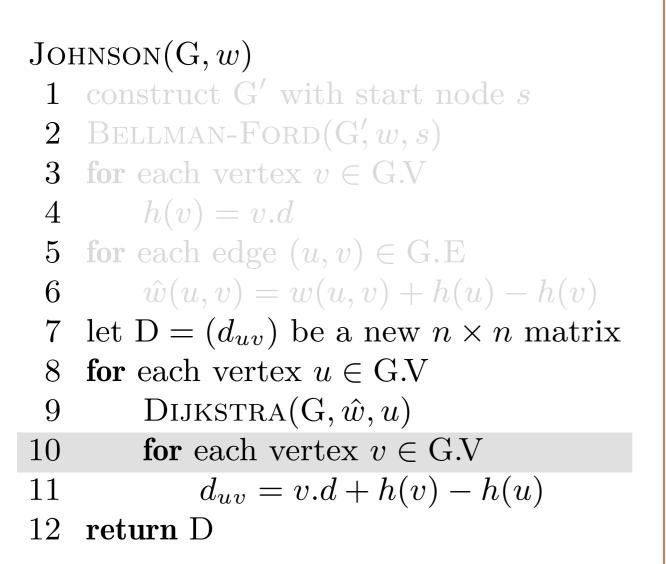


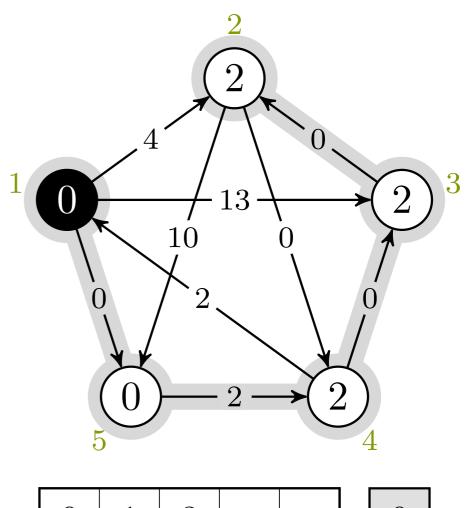
JOHNSON(G, w)

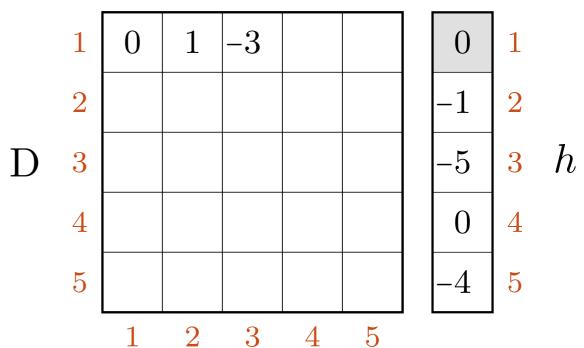
- 1 construct G' with start node s
- 2 Bellman-Ford(G, w, s)
- 3 for each vertex $v \in G.V$
- 4 h(v) = v.d
- 5 for each edge $(u, v) \in G.E$
- 6 $\hat{w}(u,v) = w(u,v) + h(u) h(v)$
- 7 let $D = (d_{uv})$ be a new $n \times n$ matrix
- 8 for each vertex $u \in G.V$
- 9 DIJKSTRA (G, \hat{w}, u)
- 10 **for** each vertex $v \in G.V$

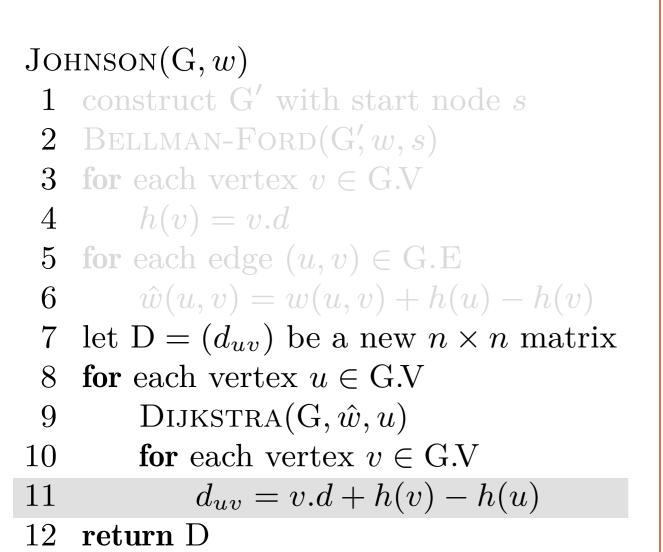
$$11 d_{uv} = v.d + h(v) - h(u)$$

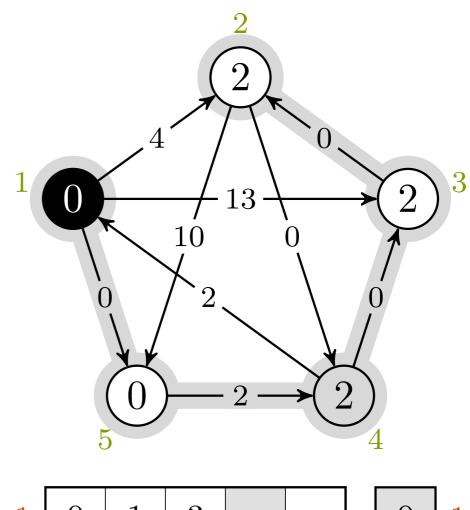
12 return D

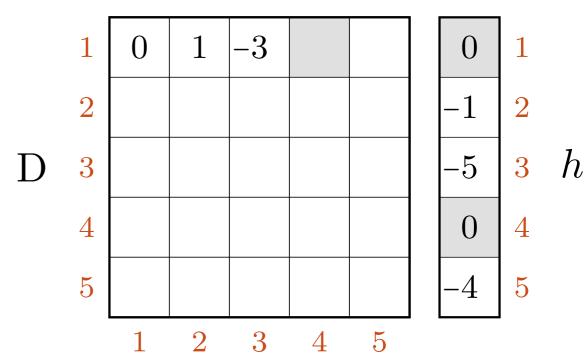


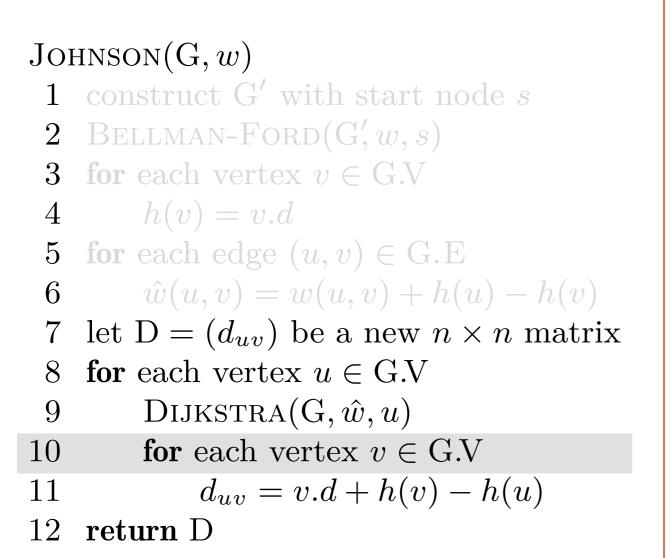


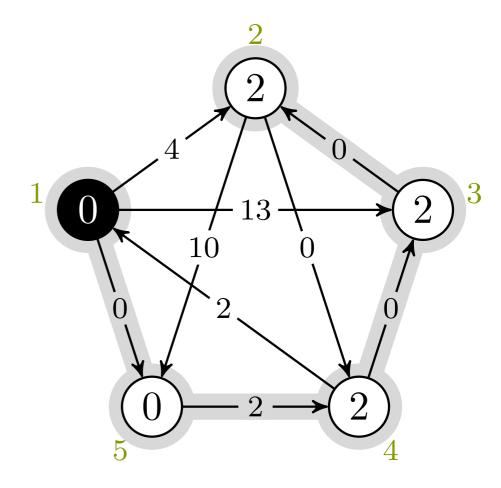


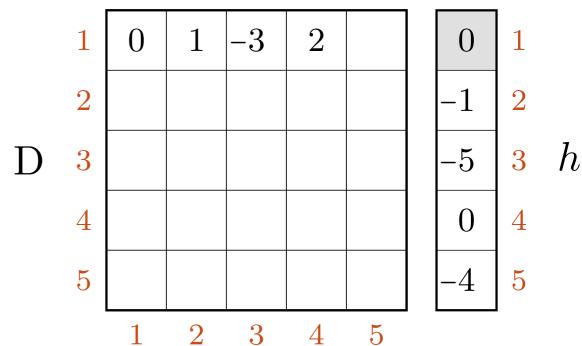


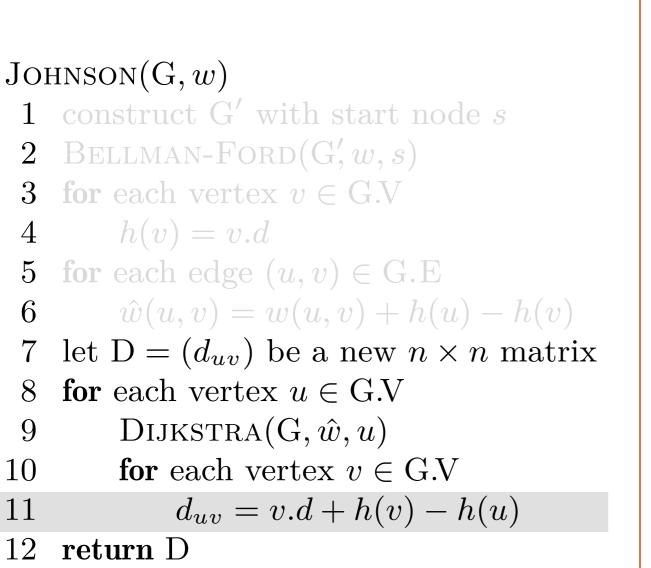


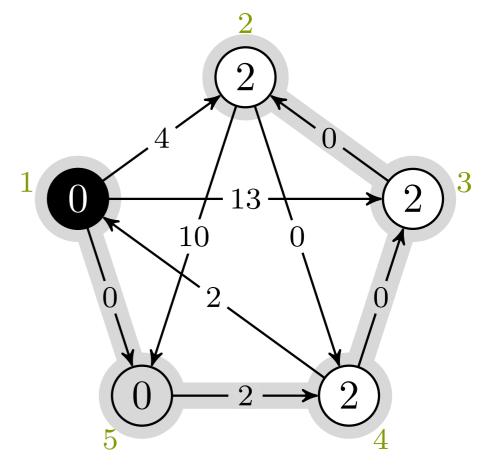


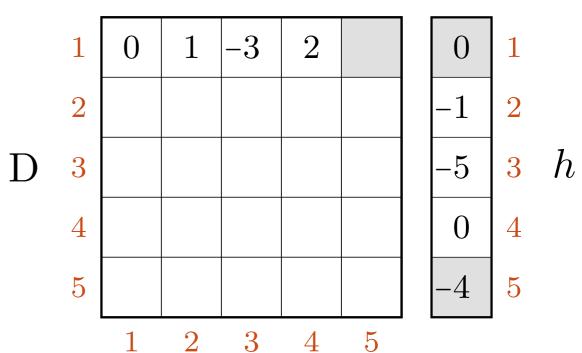


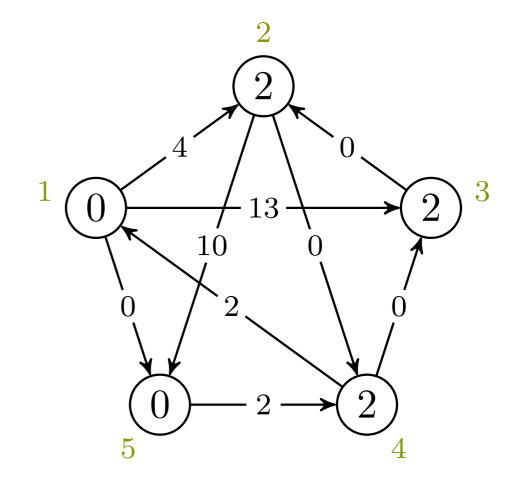


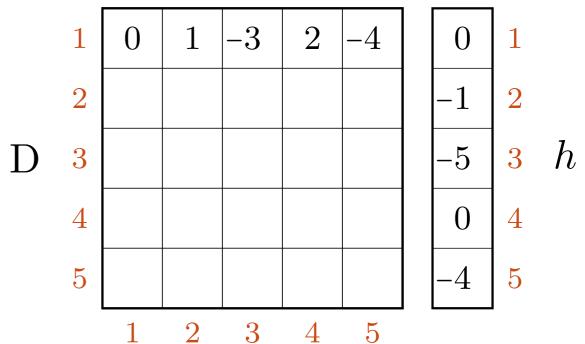






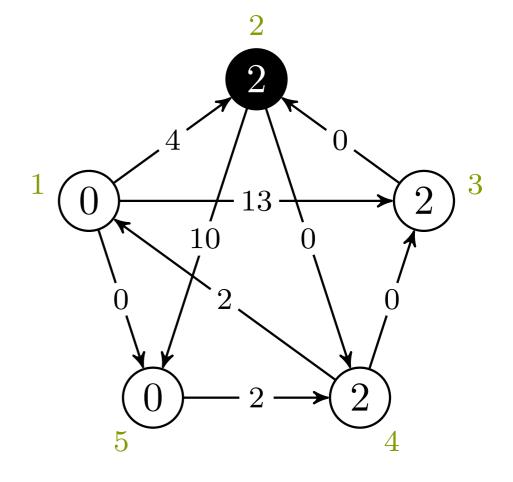


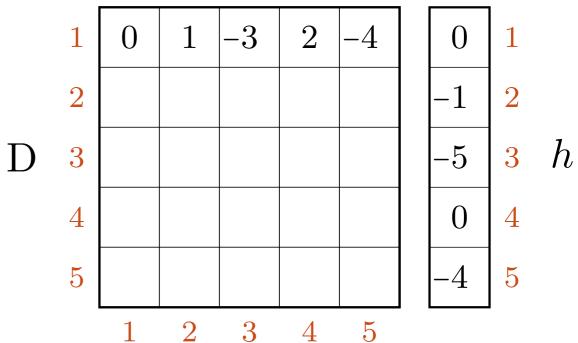




JOHNSON(G, w)

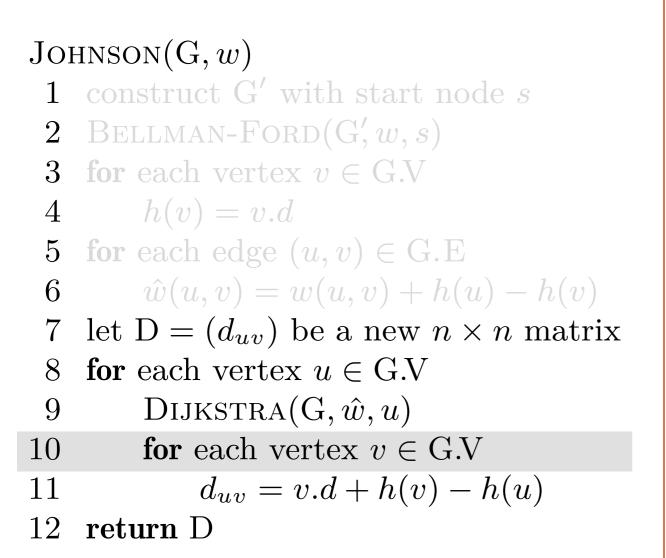
- 1 construct G' with start node s
- 2 Bellman-Ford(G', w, s)
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- 6 $\hat{w}(u,v) = w(u,v) + h(u) h(v)$
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- 8 for each vertex $u \in G.V$
- 9 DIJKSTRA (G, \hat{w}, u)
- 10 **for** each vertex $v \in G.V$
- $d_{uv} = v.d + h(v) h(u)$
- 12 return D

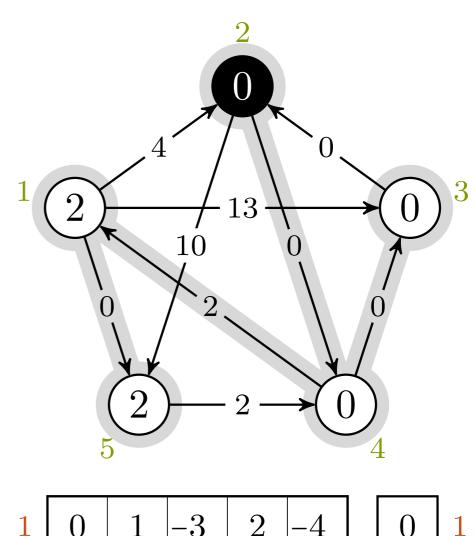


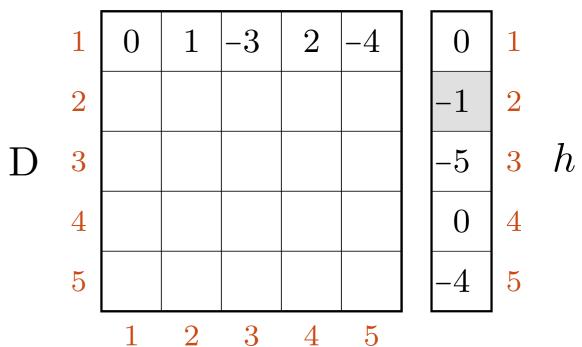


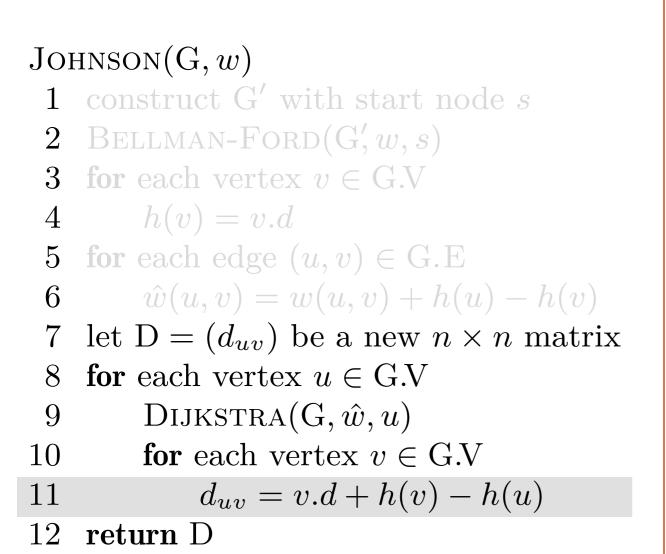
JOHNSON(G, w)

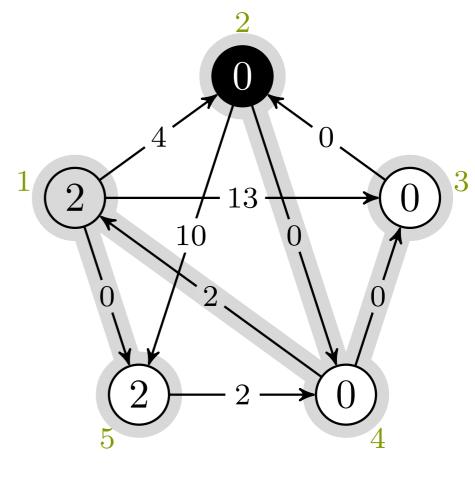
- 1 construct G' with start node s
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- 10 **for** each vertex $v \in G.V$
- $11 d_{uv} = v.d + h(v) h(u)$
- 12 **return** D

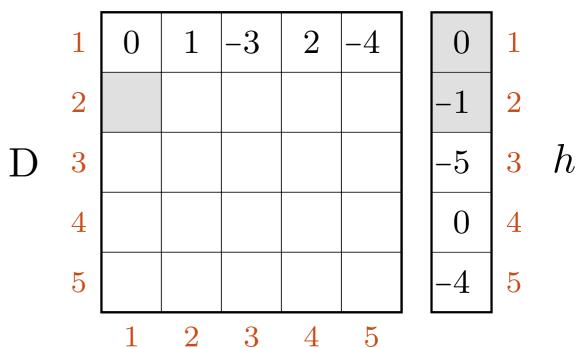


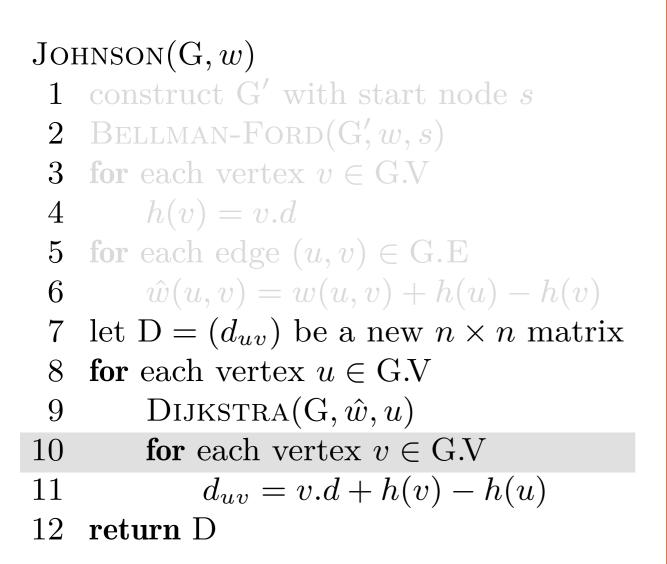


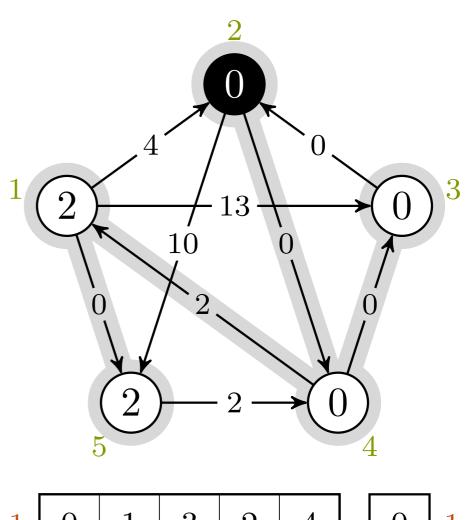


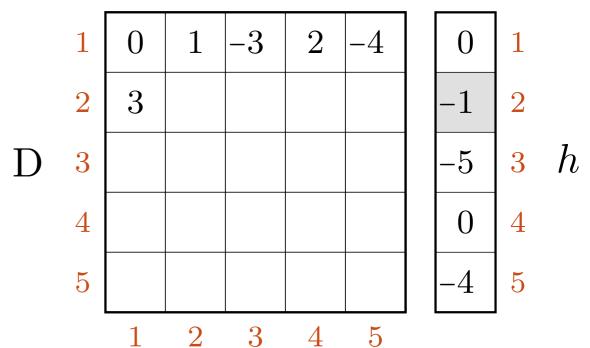


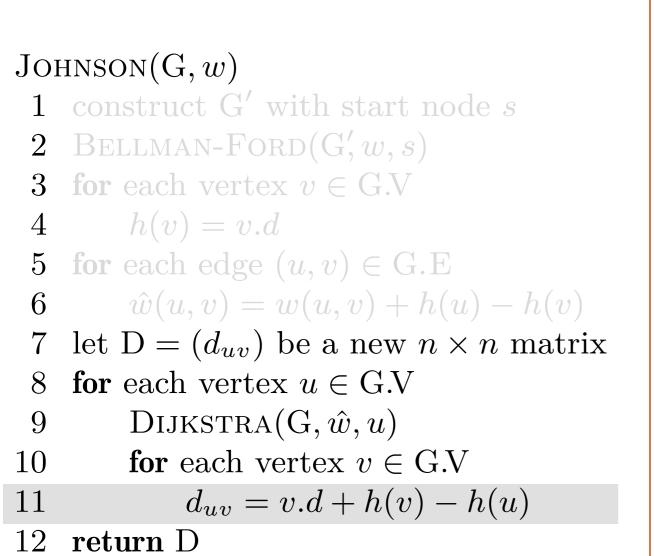


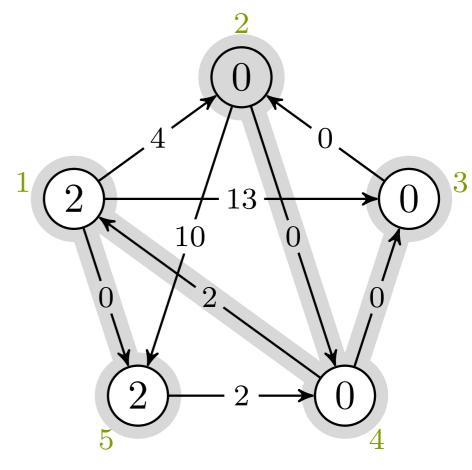


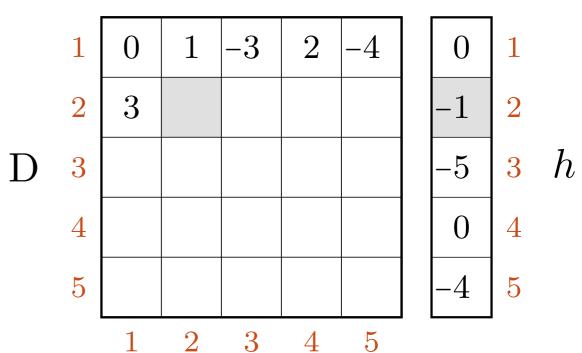


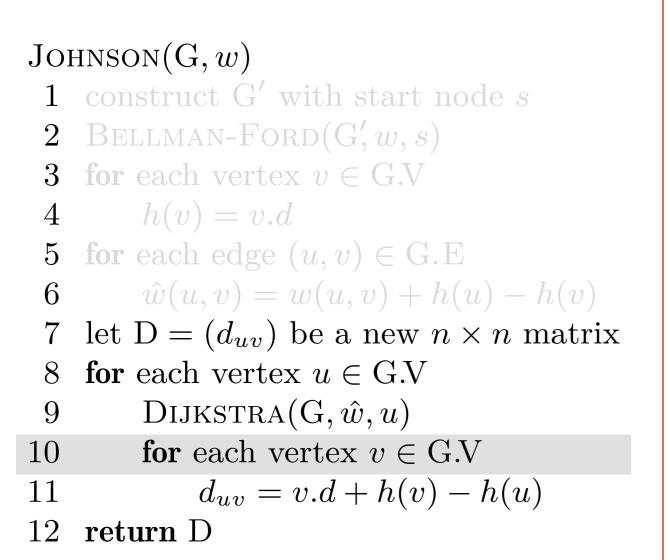


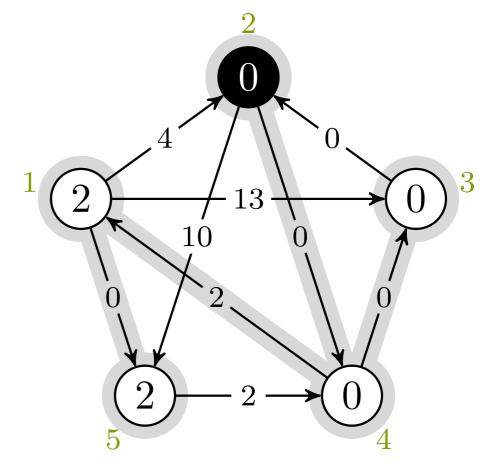


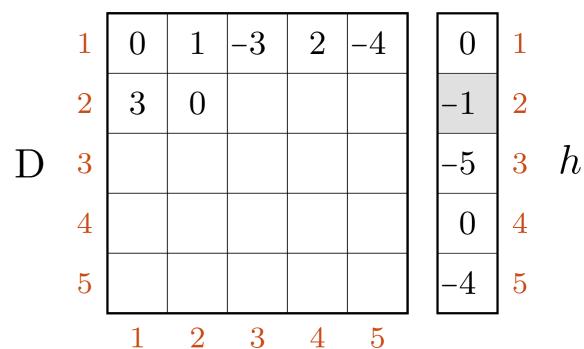


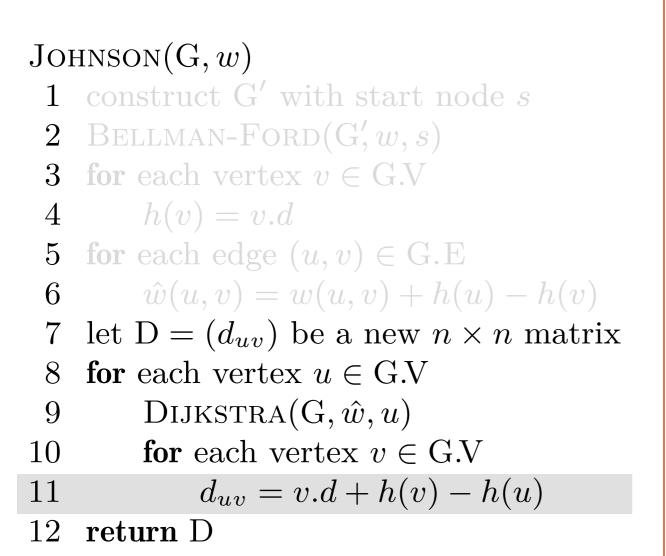


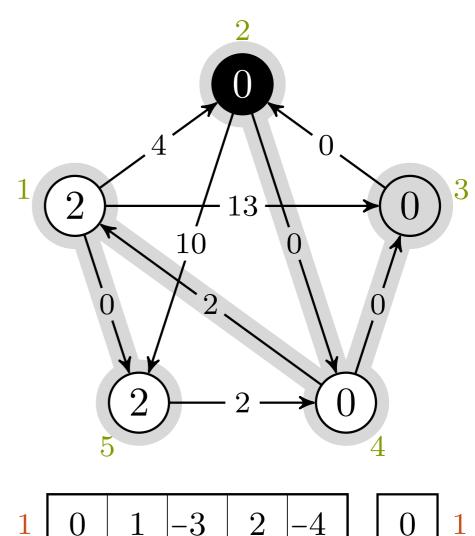


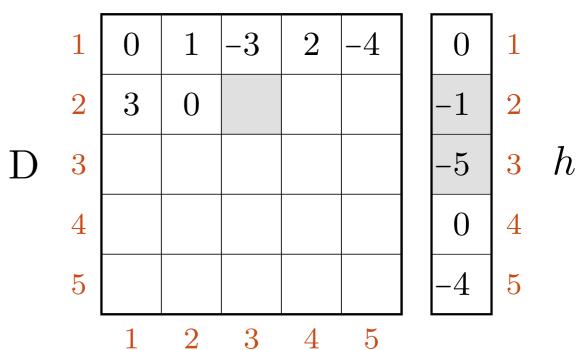


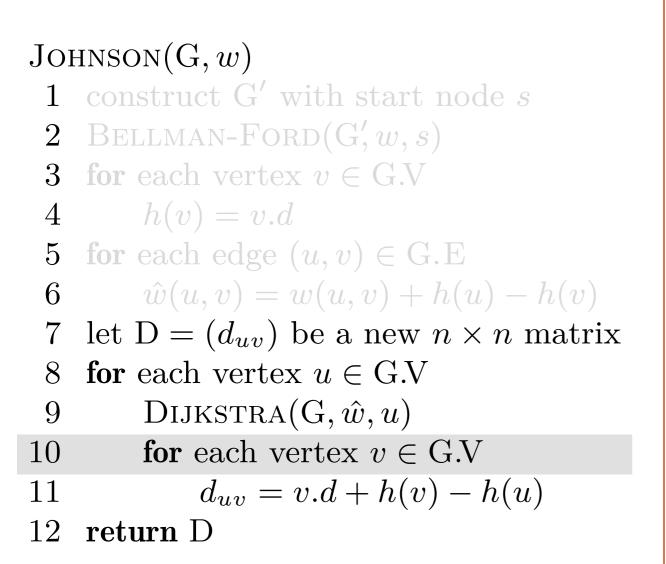


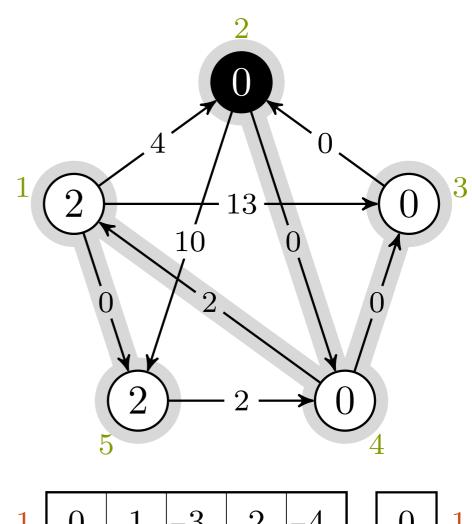


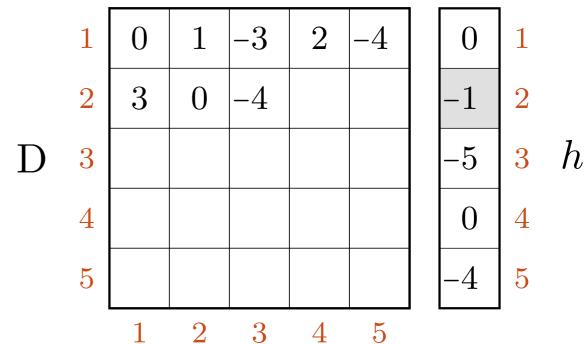


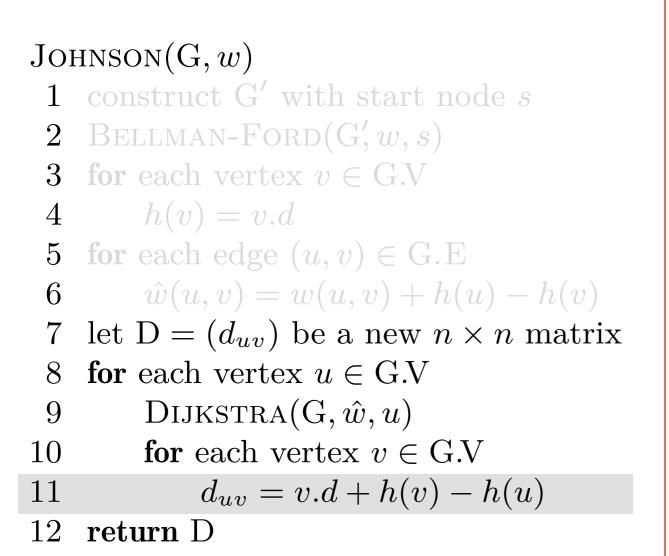


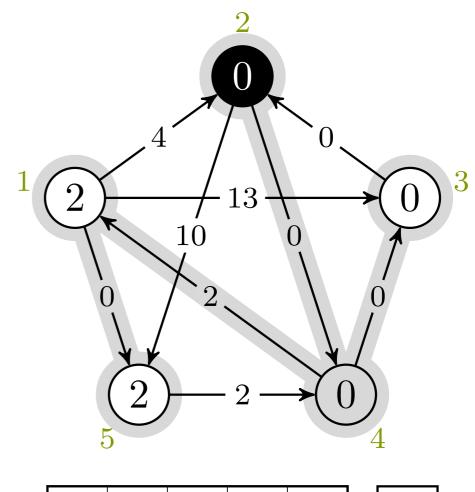


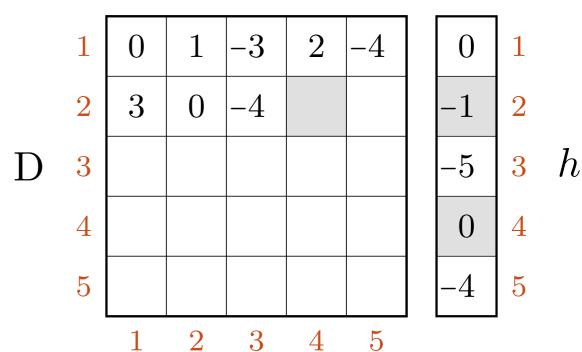


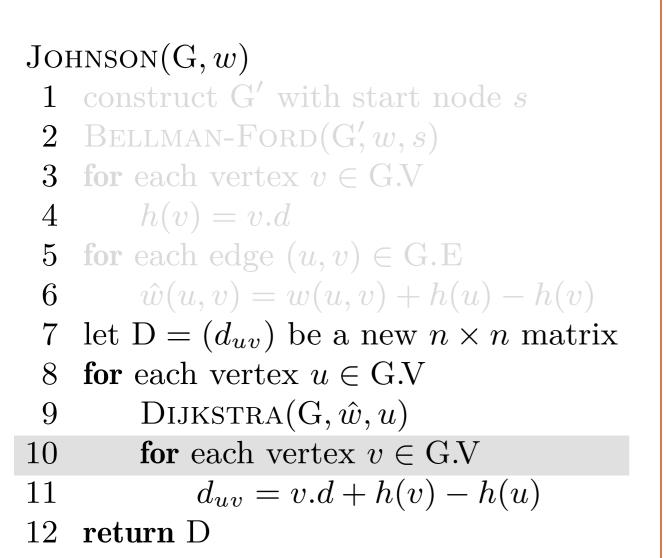


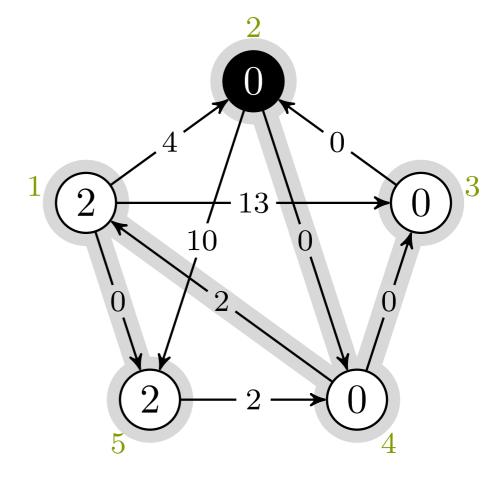


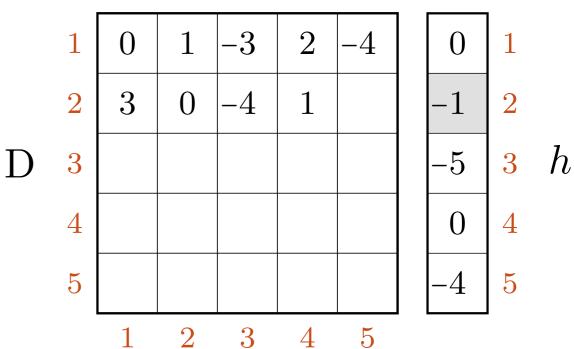


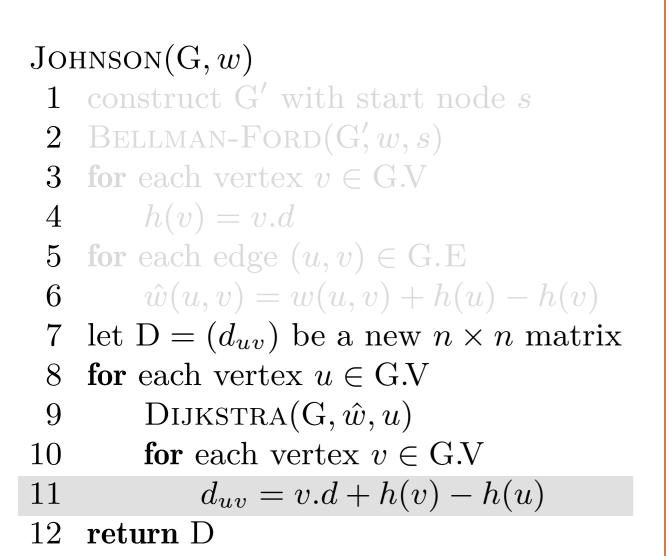


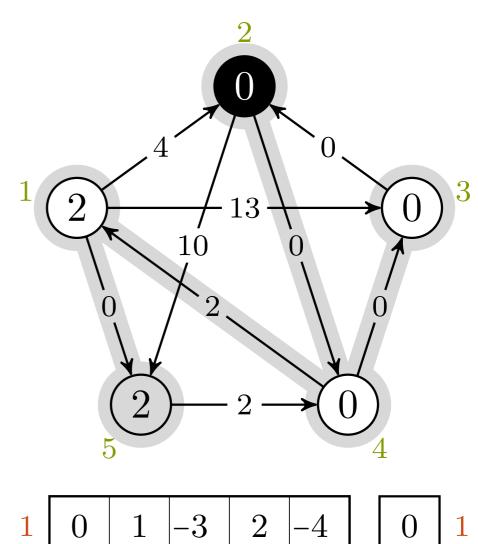


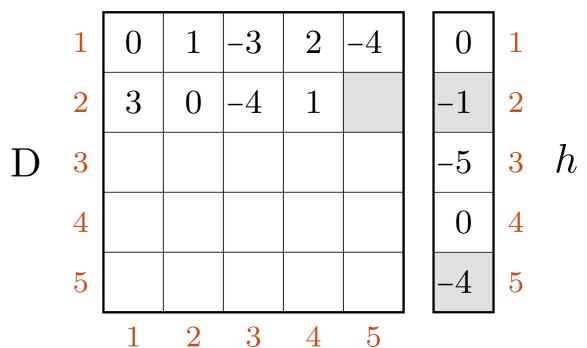


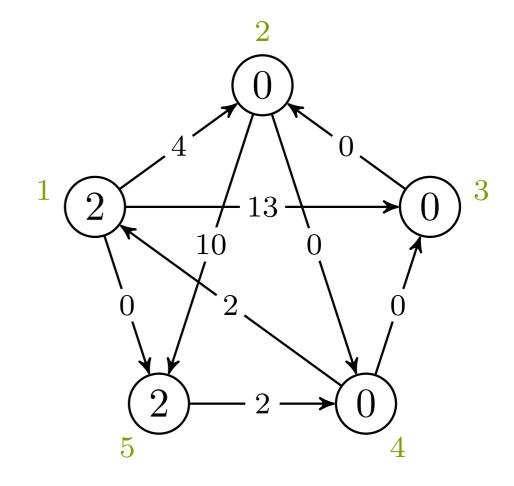








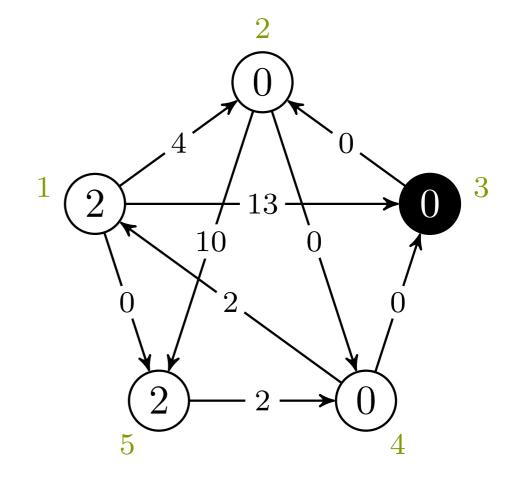




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	2	3	0	-4	1	-1	-1	2	
D	3						-5	3	h
	4						0	4	
	5						-4	5	
	'	1	2	2	1	K		•	

JOHNSON(G, w)

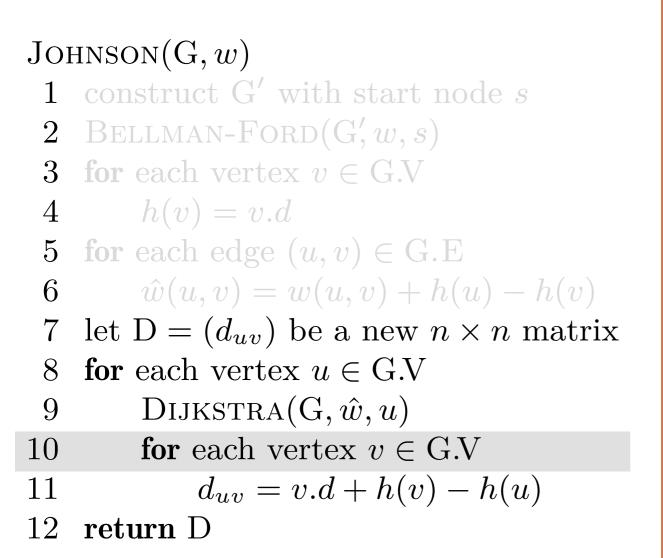
- 1 construct G' with start node s
- 2 Bellman-Ford(G, w, s)
- 3 for each vertex $v \in G.V$
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- 9 DIJKSTRA (G, \hat{w}, u)
- 10 **for** each vertex $v \in G.V$
- $d_{uv} = v.d + h(v) h(u)$
- 12 return D

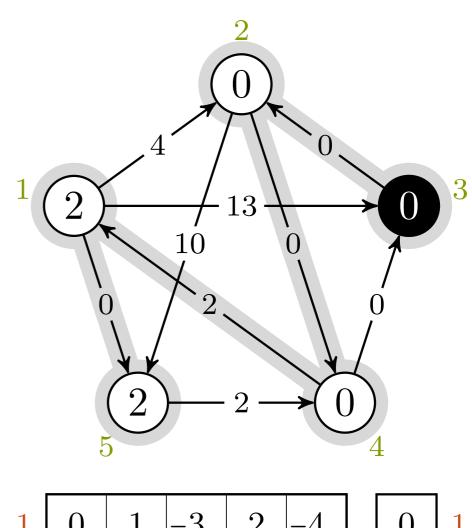


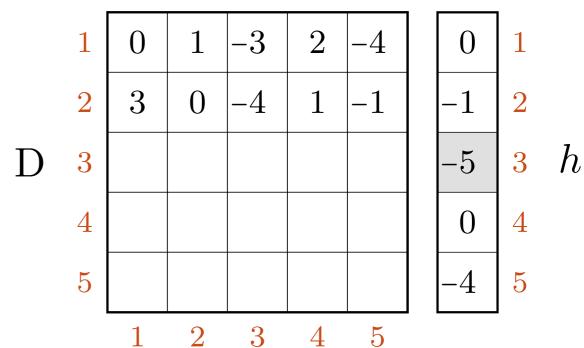
								ı	
	1	0	1	-3	2	$\left -4\right $	0	1	
	2	3	0	-4	1	-1	-1	2	
D	3						-5	3	h
	4						0	4	
	5						-4	5	
	'	1	0	0	4				

JOHNSON(G, w)

- 1 construct G' with start node s
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- 9 DIJKSTRA (G, \hat{w}, u)
- 10 **for** each vertex $v \in G.V$
- $11 d_{uv} = v.d + h(v) h(u)$
- 12 return D







-4

-1

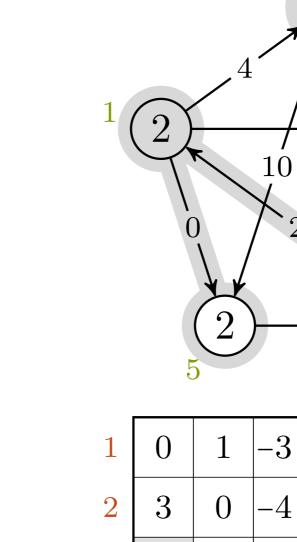
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3

2

-1

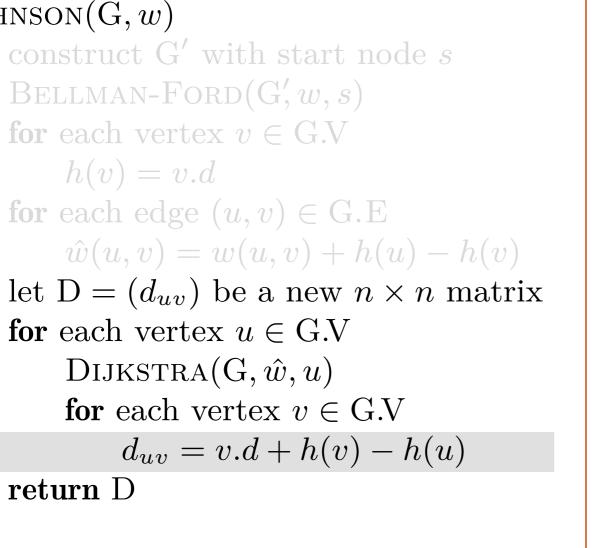
-5



3

4

5



JOHNSON(G, w)

return D

10

11

12

1 construct G' with start node s

Bellman-Ford(G', w, s)

for each edge $(u, v) \in G.E$

for each vertex $u \in G.V$

DIJKSTRA (G, \hat{w}, u)

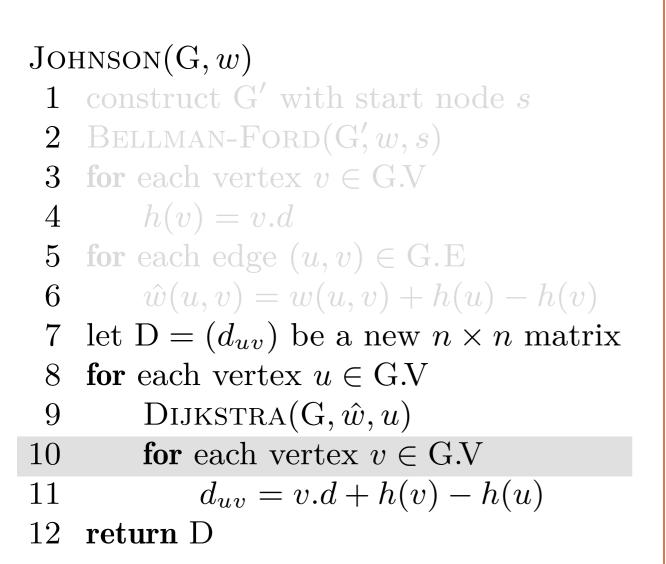
for each vertex $v \in G.V$

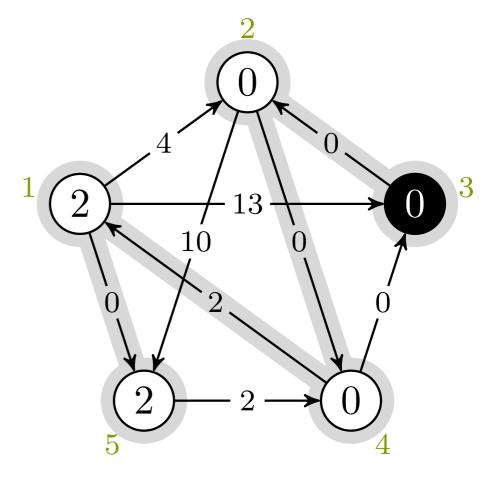
 $d_{uv} = v.d + h(v) - h(u)$

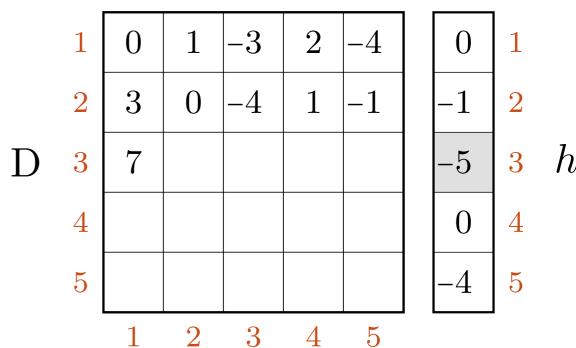
for each vertex $v \in G.V$

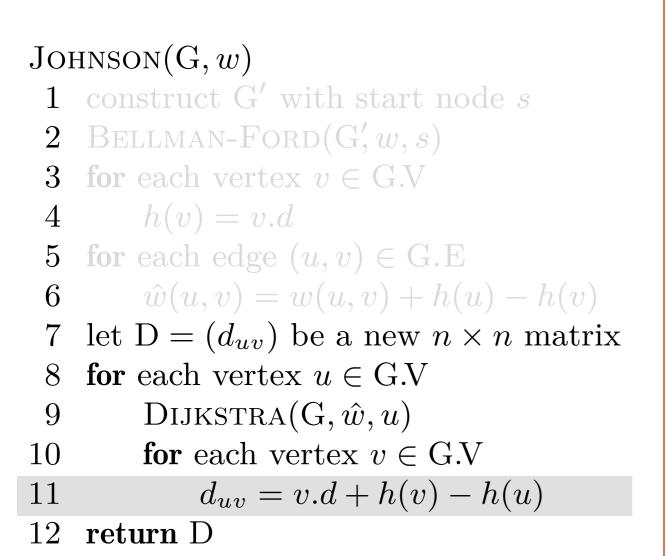
h(v) = v.d

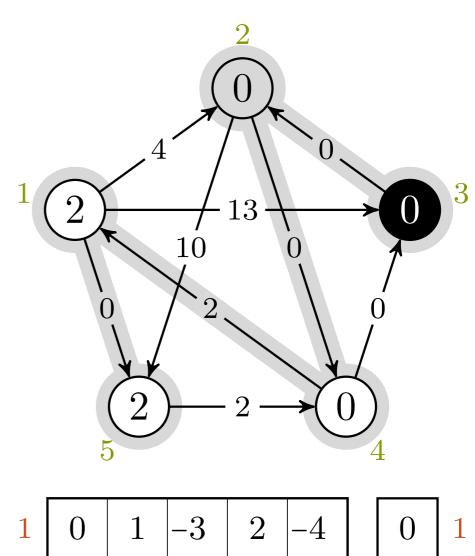
3 5

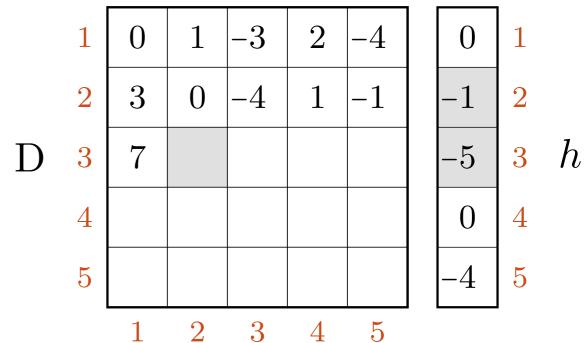


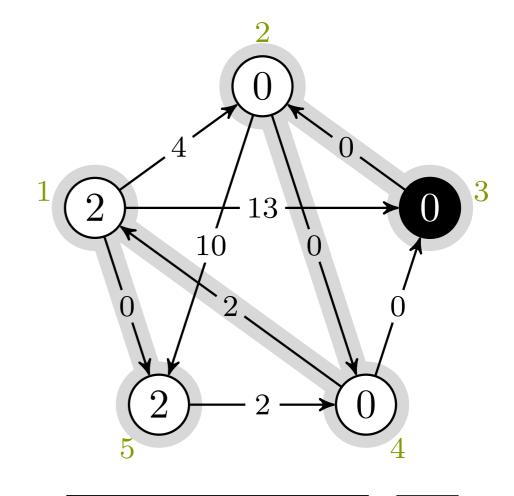








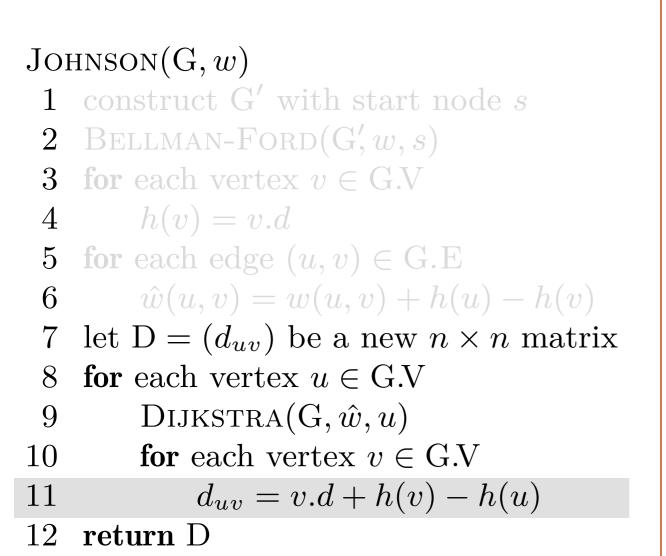


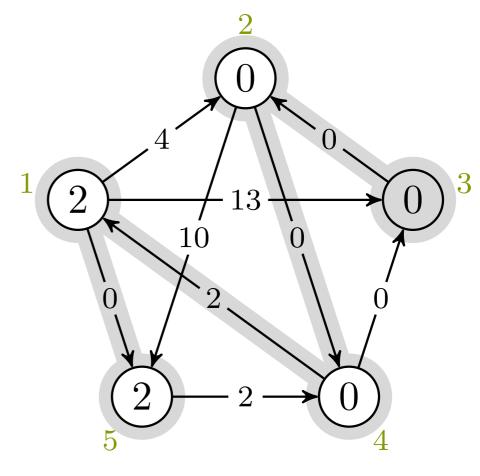


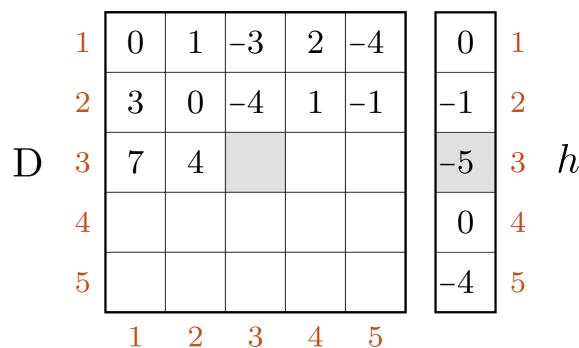
	1	0	1	-3	2	-4	0	1	
	2	3	0	-4	1	-1	-1	2	
D	3	7	4				-5	3	h
	4						0	4	
	5						-4	5	
	'	1	2	3	4	5		1	

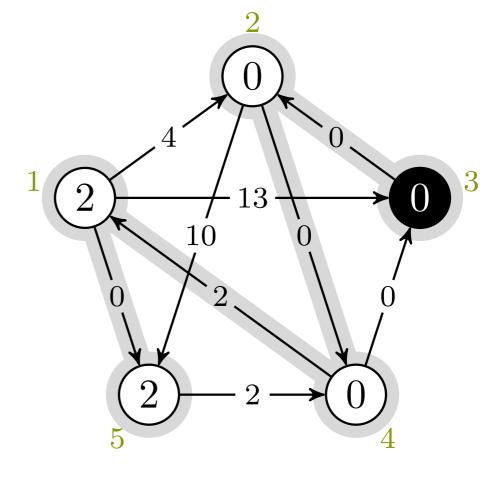
JOHNSON(G, w)

- 1 construct G' with start node s
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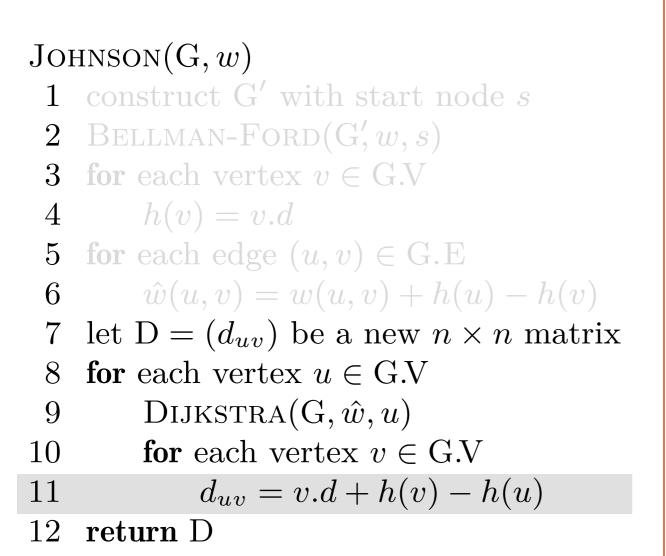


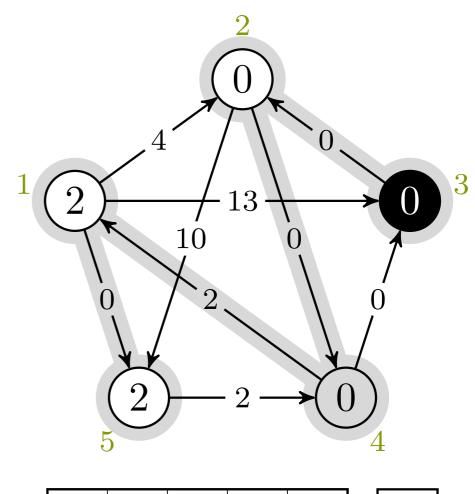


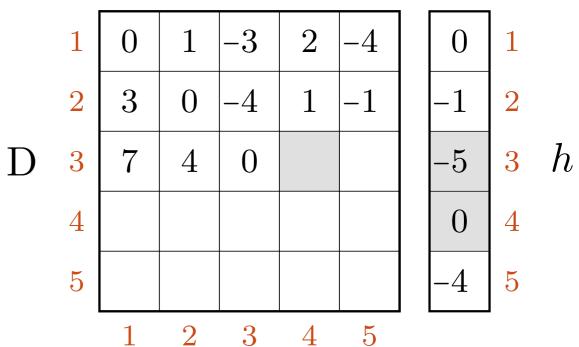


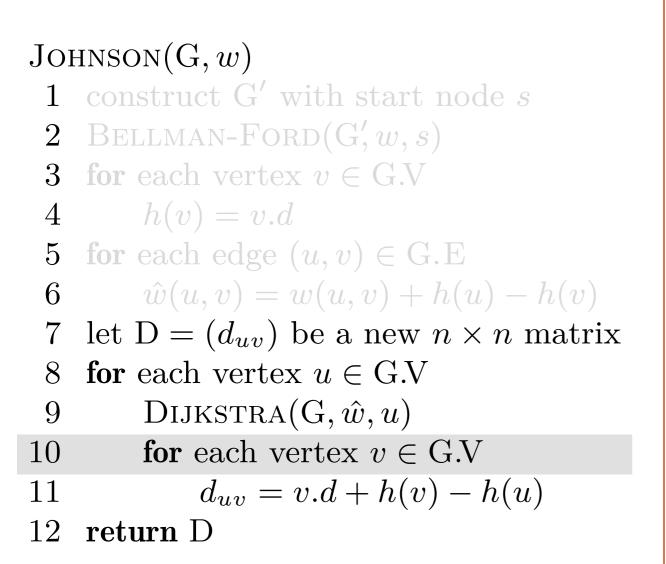
							ı		1	
	1	0	1	-3	2	-4		0	1	
	2	3	0	$\left -4\right $	1	-1		-1	2	
D	3	7	4	0				-5	3	h
	4							0	4	
	5							-4	5	
	'	1	2	2	1	7			l	

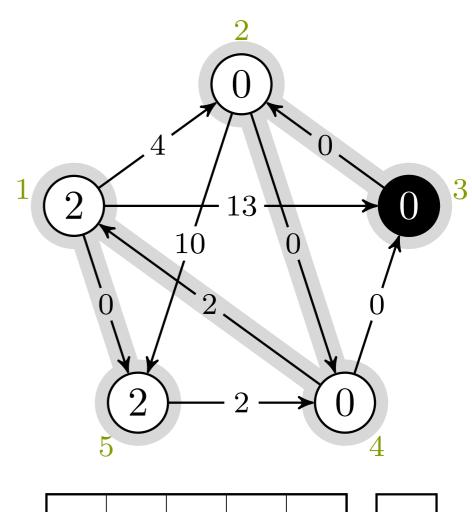
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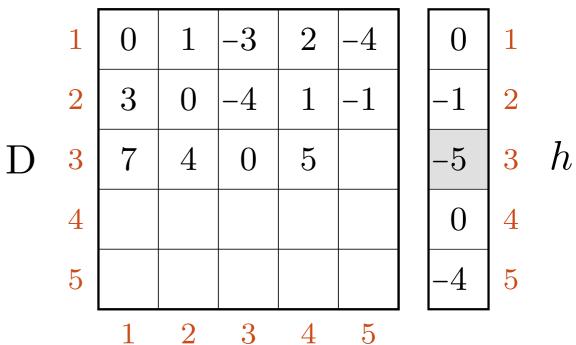


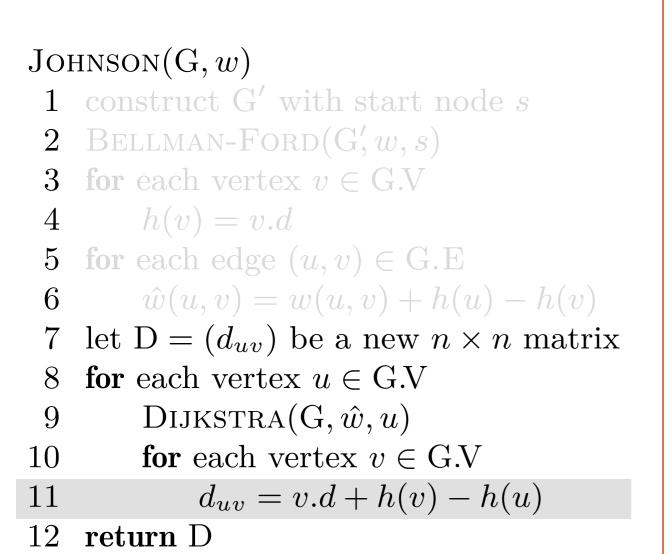


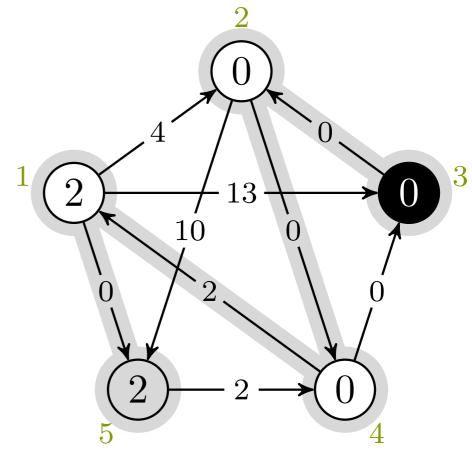


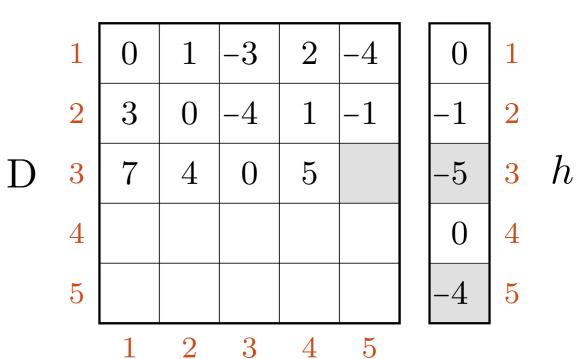


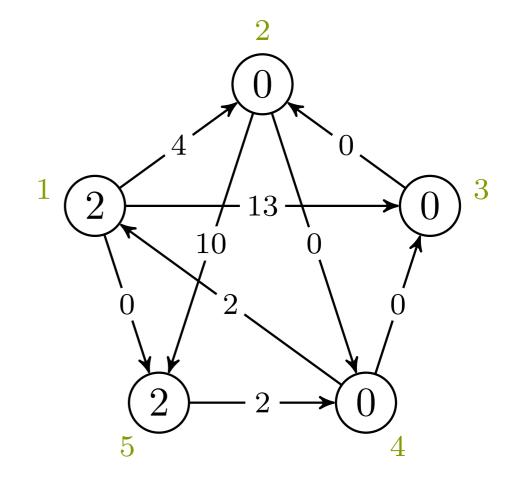






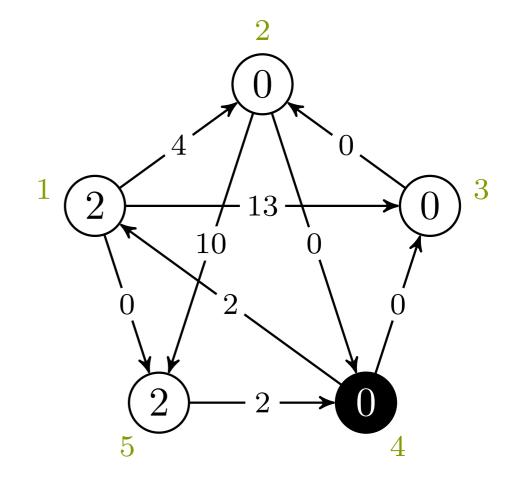






	1	0	1	-3	2	-4	0	1
	2	3	0	-4	1	-1	-1	2
D	3	7	4	0	5	3	-5	3
	4						0	4
	5						-4	5
	!	1	2	3	4	5		I

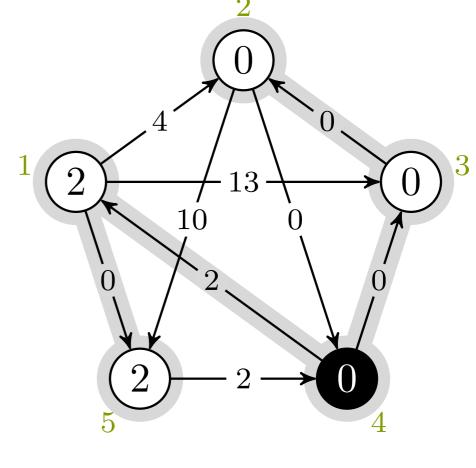
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	_						_		_	
	1	0	1	-3	2	-4		0	1	
	2	3	0	-4	1	-1		-1	2	
D	3	7	4	0	5	3		-5	3	h
	4							0	4	
	5							-4	5	
	•	1	2	2	1	5			1	

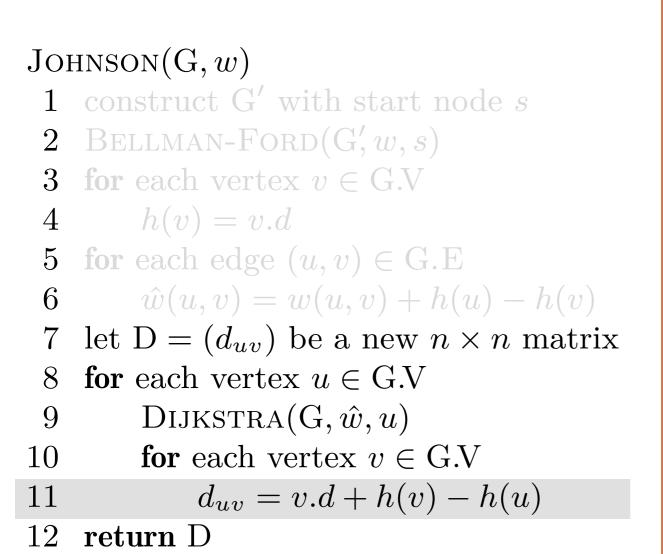
Johnson(G, w)

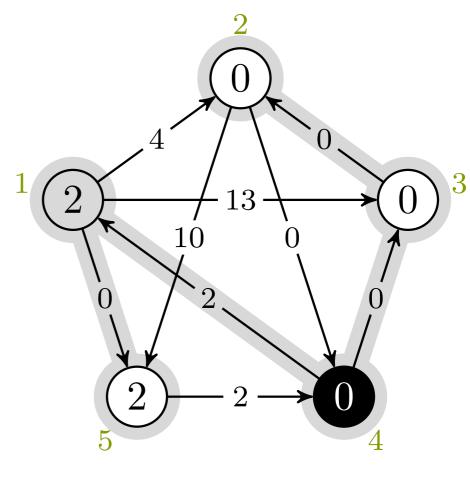
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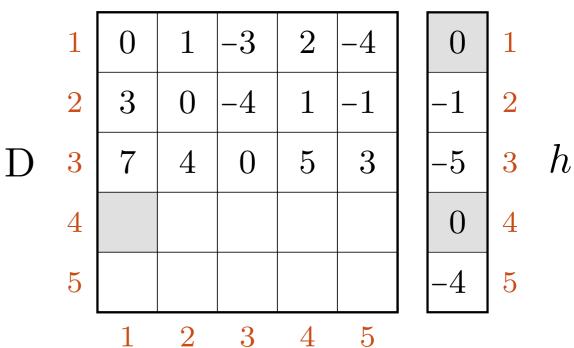


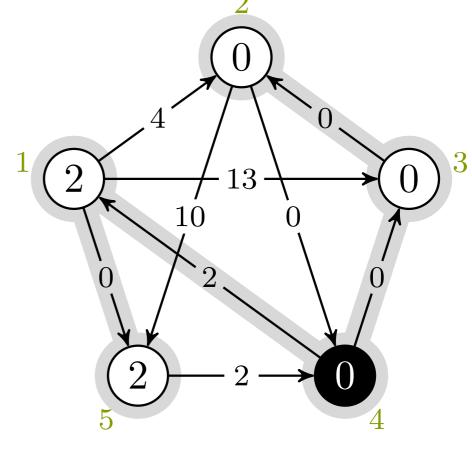
	1	0	1	-3	2	-4		0	1	
	2	3	0	-4	1	-1		-1	2	
	4		U	-4		_1			4	
D	3	7	$\mid 4 \mid$	0	5	3		-5	3	h
	4							0	4	
	5							-4	5	
		1	2	3	4	5	-		-	

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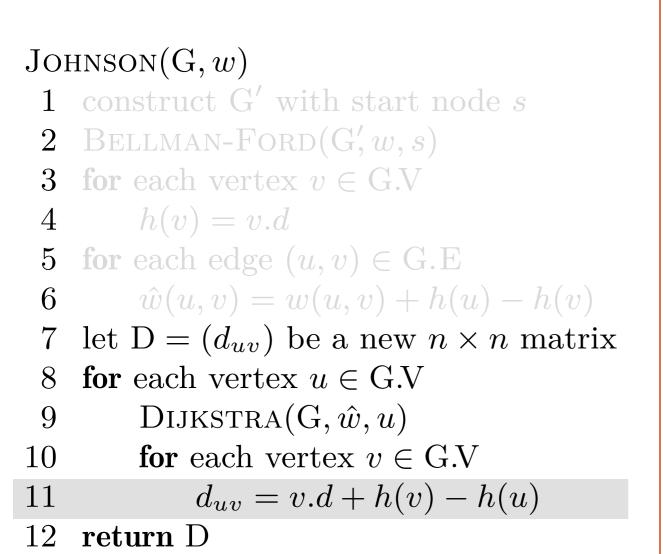


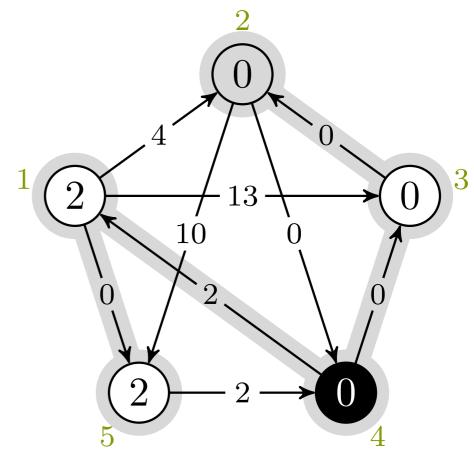


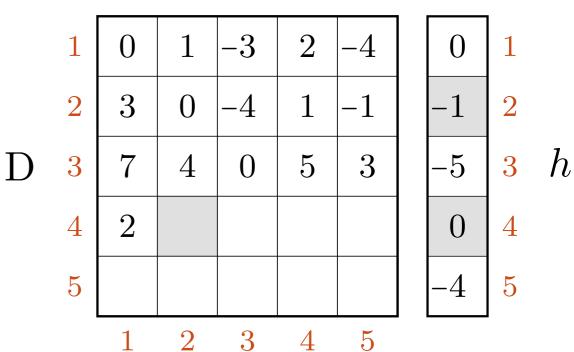


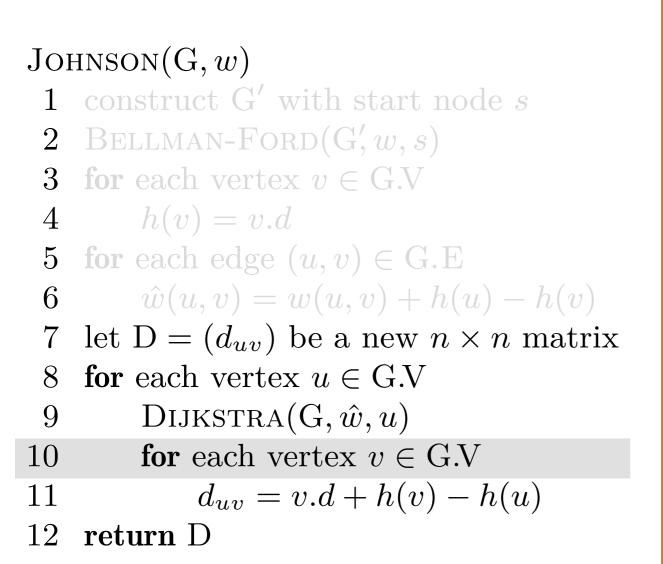
							ı		l	
	1	0	1	-3	2	-4		0	1	
	2	3	0	-4	1	-1		-1	2	
D	3	7	4	0	5	3		-5	3	h
	4	2						0	4	
	5							-4	5	
	'	1	2	3	4	5				

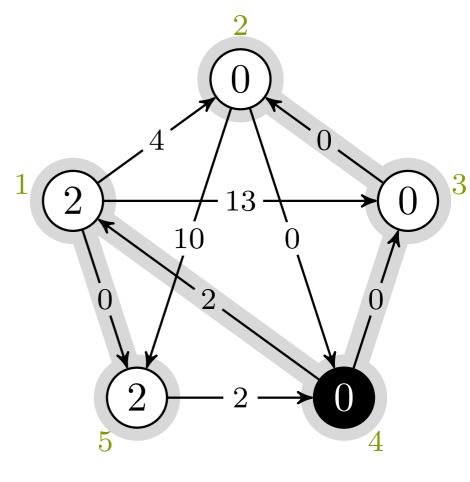
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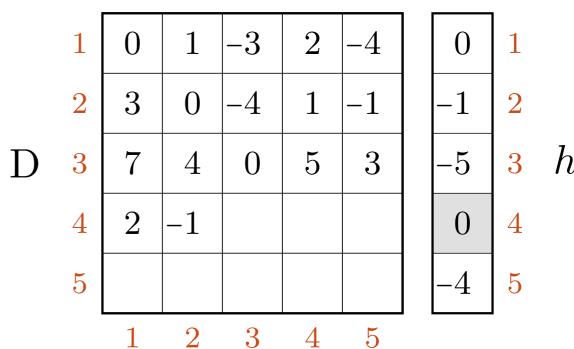


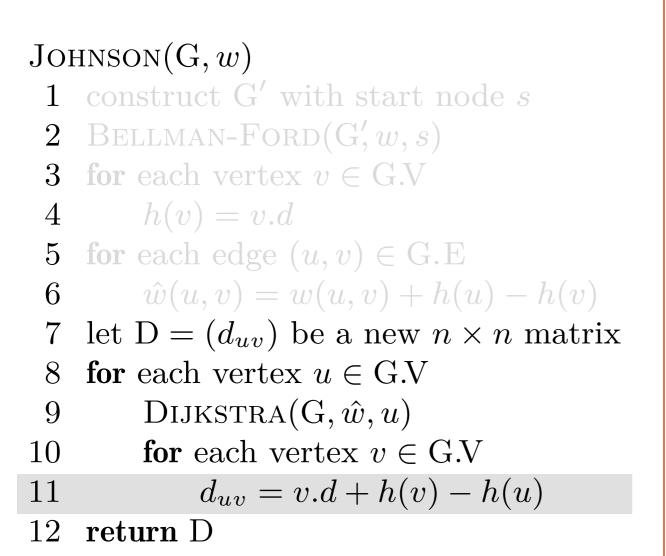


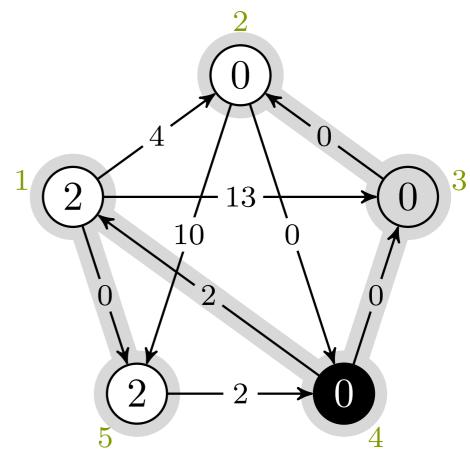


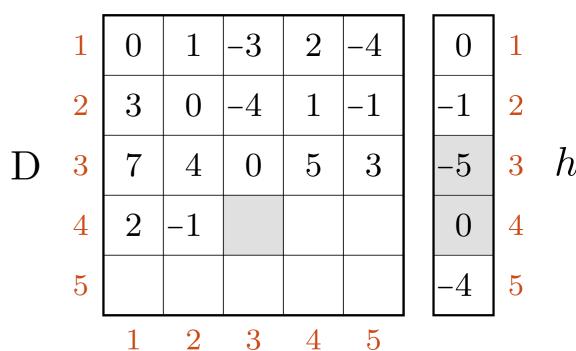


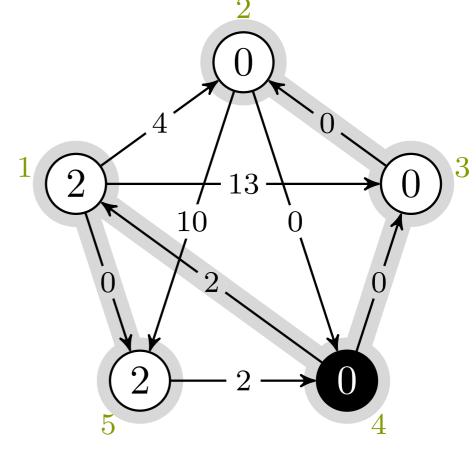






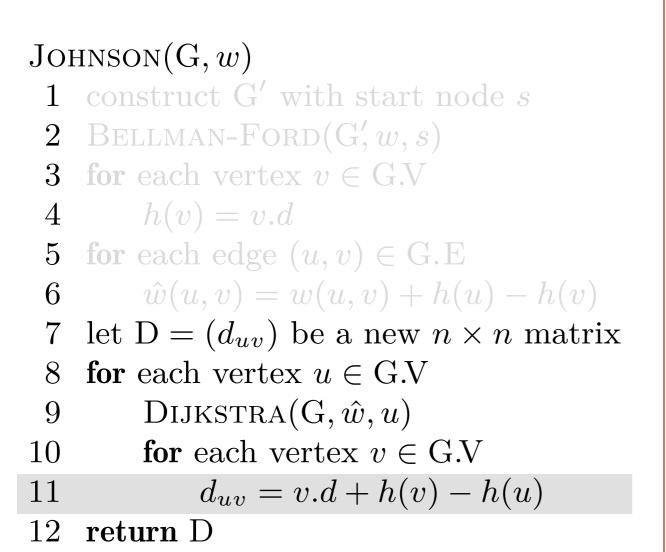


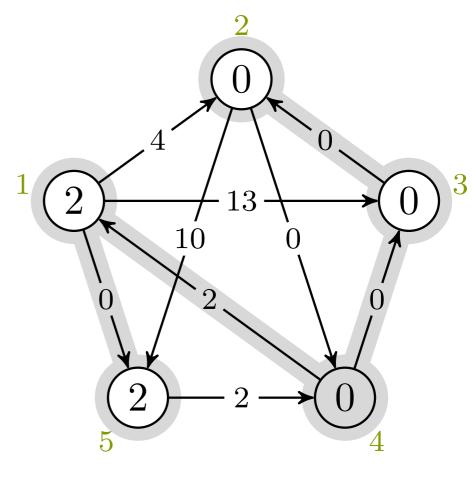


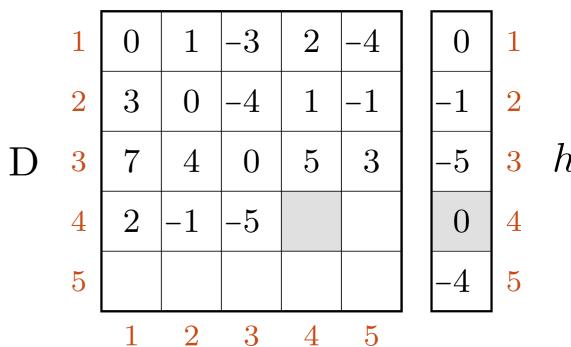


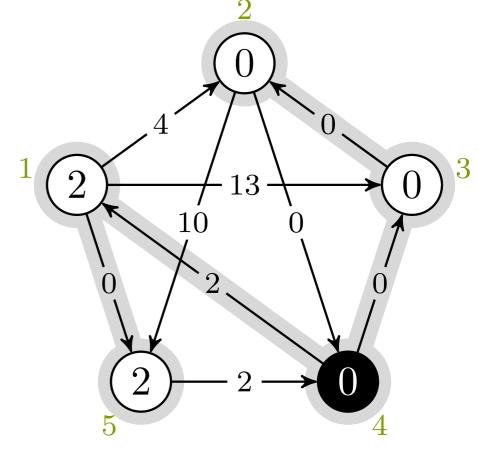
	1	0	1	-3	2	-4		0	1	
	2	3	0	-4	1	-1		-1	2	
D	3	7	4	0	5	3		-5	3	1
	4	2	-1	-5				0	4	
	5							-4	5	
	'	1	2	2	1	5	ı		•	

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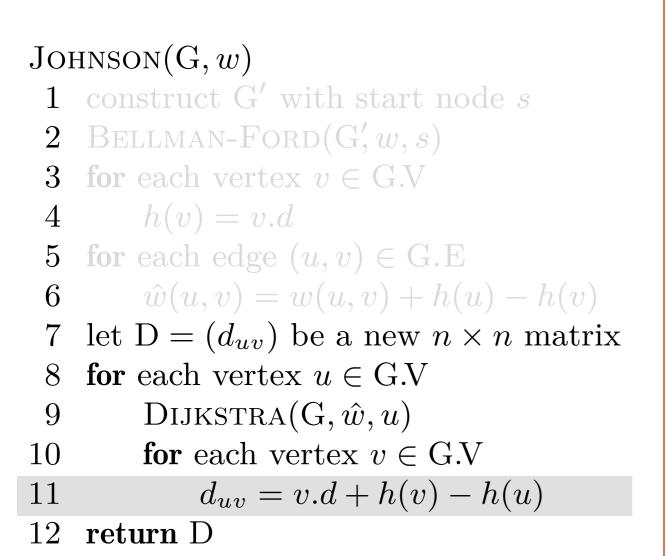


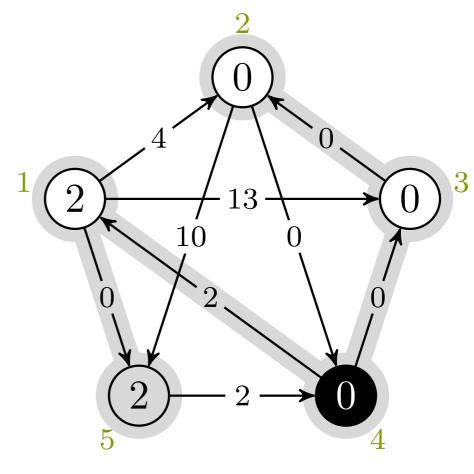


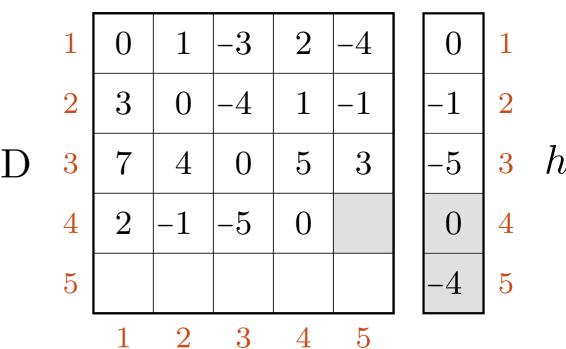


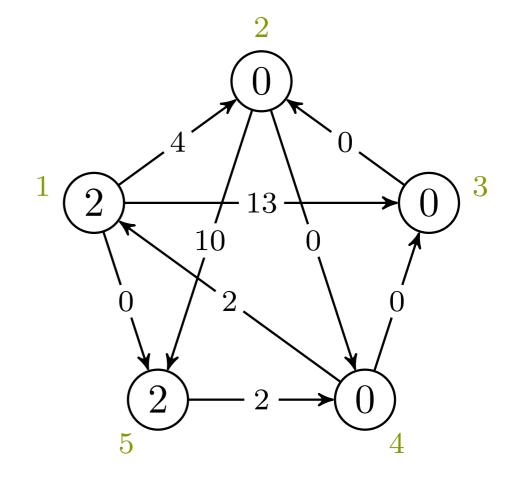
					ı		ı		ı	
	1	0	1		2	-4		0	1	
	2	3	0			-1		-1	2	
D	3	7		I		3		-5	3	1
	4	2	-1	-5	0			0	4	
	5							$\overline{-4}$	5	
	'	1	2	2	1	5				

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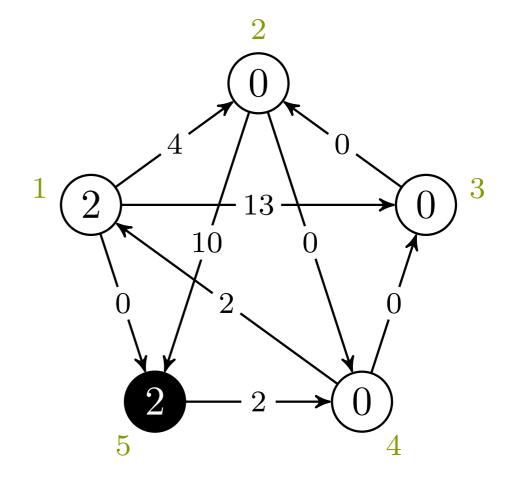






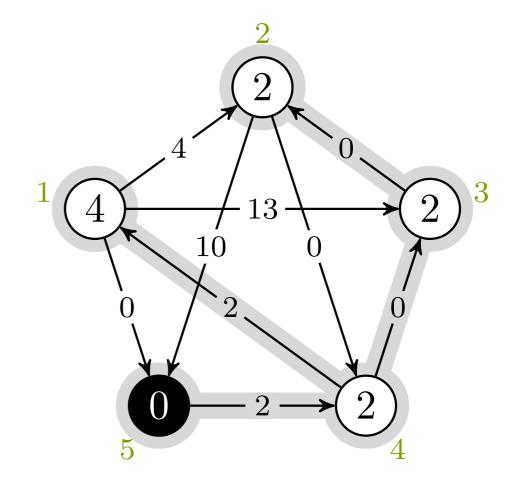
	ı						ı		l	
	1	0				-4		0	1	
	2	3	0			-1		-1	2	
D	3	7	4			3		-5	3	}
	4	2	-1	-5	0	-2		0	4	
	5							-4	5	
	•	1	2	2	1	K			_	

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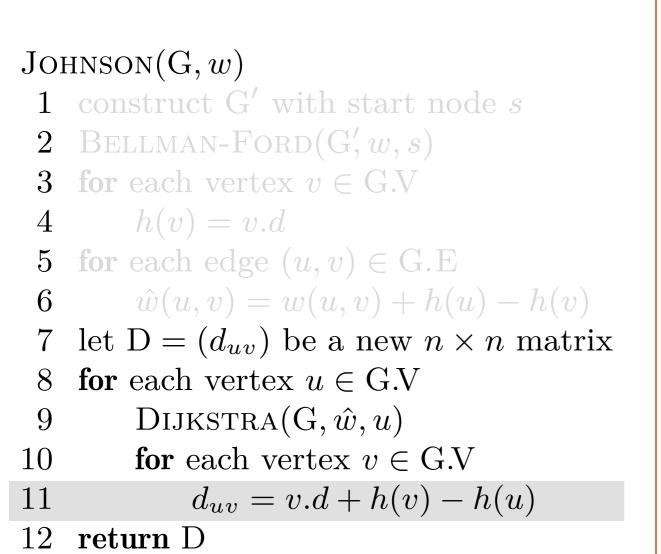
	1	0	1	-3	2	-4	0	1
	2	3	0	-4	1	-1	-1	2
D	3	7	4	0	5	3	-5	3
	4	2	-1	-5	0	-2	0	4
	5						-4	5
	'	1	2	3	1	5		1

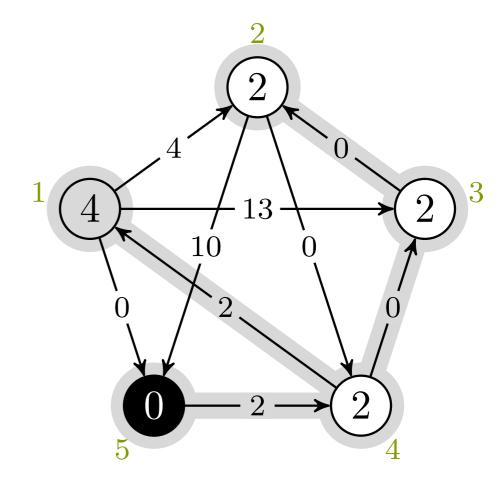
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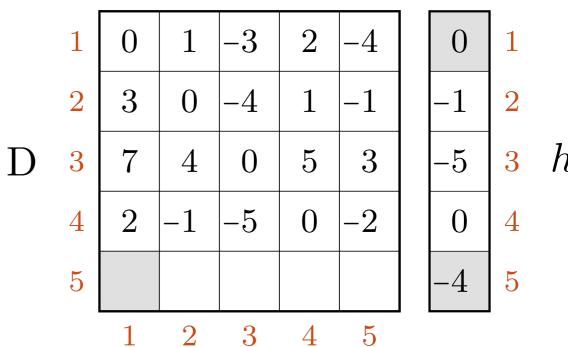


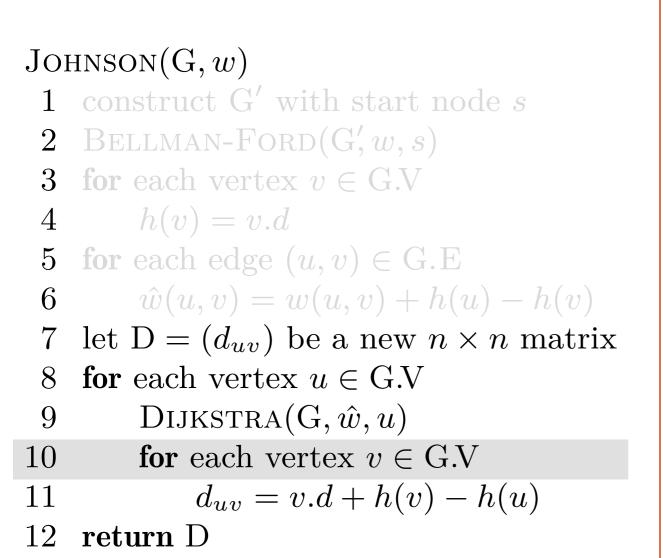
	1	0	1	-3	2	-4	0	1
	2	3	0	-4	1	-1	-1	2
D	3	7	4	0	5	3	-5	3
	4	2	-1	-5	0	-2	0	4
	5						-4	5
	'	1	2	2	1	K		ı

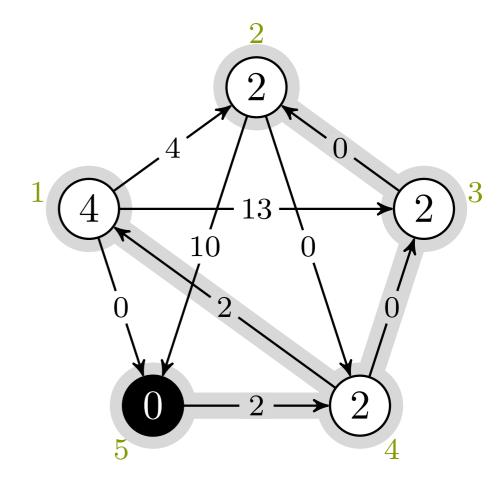
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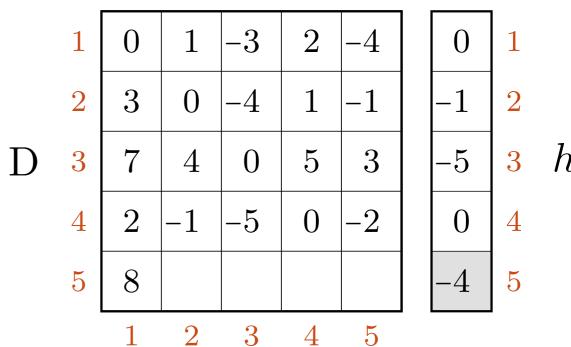


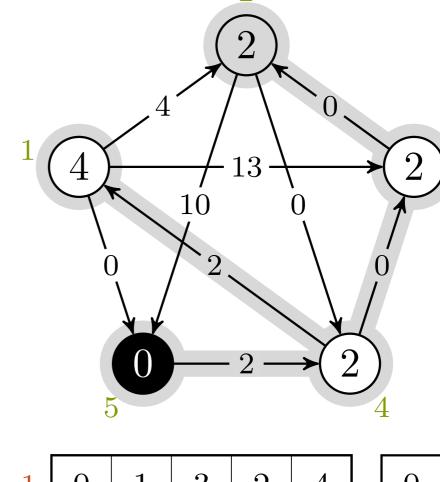












	1	0	1	-3	2	-4	0
	2	3	0	-4	1	-1	-1
D	3	7	4	0	5	3	-5
	4	2	-1	-5	0	-2	0
	5	8					-4
	'	1	0	า	1		

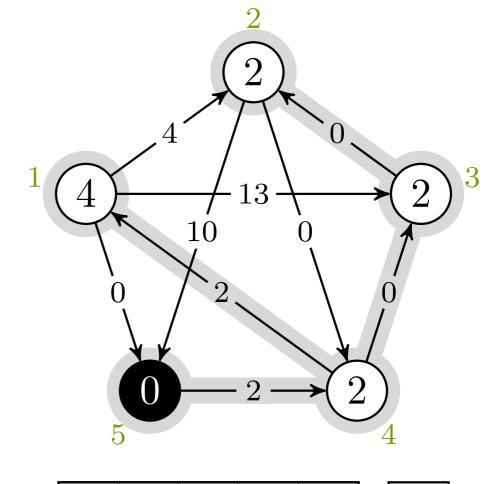


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3

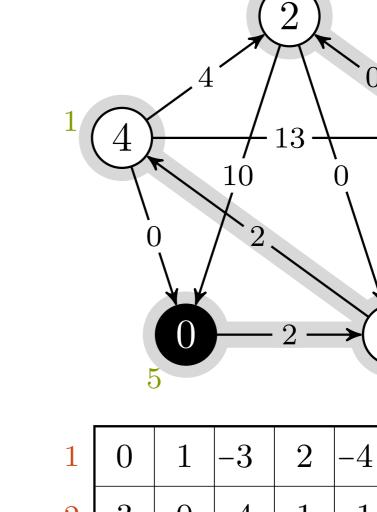
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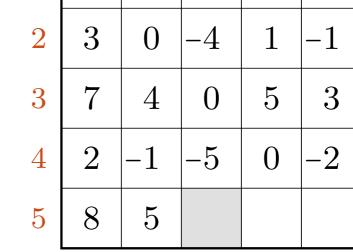
 \mathbf{c}



	1	0	1	-3	2	-4	0	1
	2	3	0	-4	1	-1	-1	2
D	3	7	4	0	5	3	-5	3
	4	2	-1	-5	0	-2	0	4
	5	8	5				-4	5
	'	1	2	2	1	K		

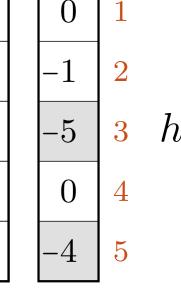
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3

5

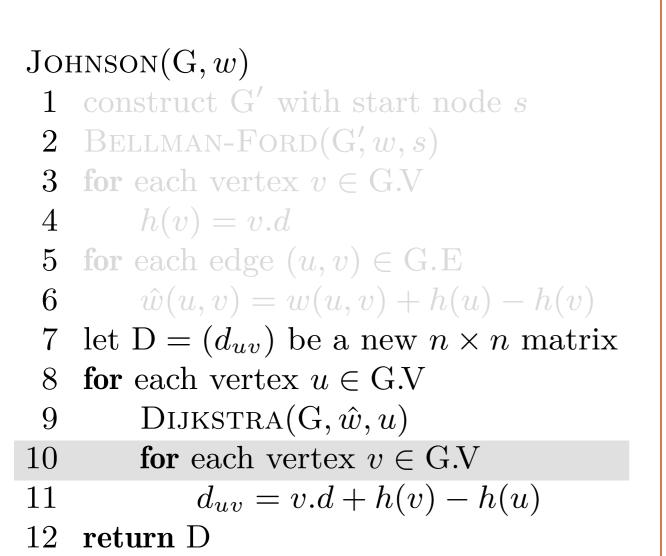


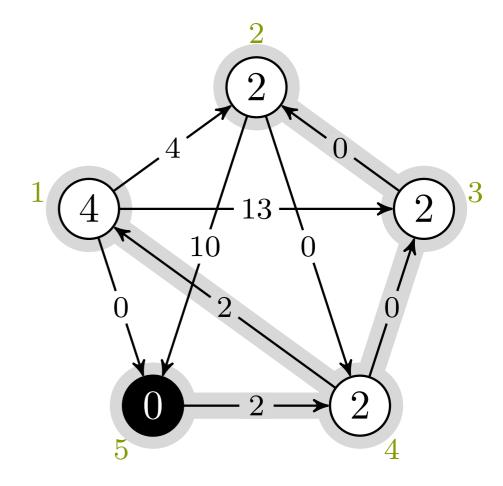


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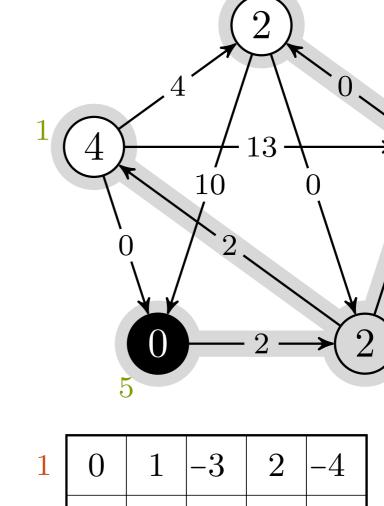
$$11 d_{uv} = v.d + h(v) - h(u)$$

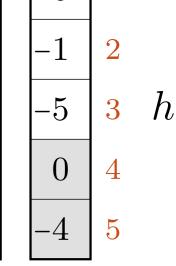
12 return D



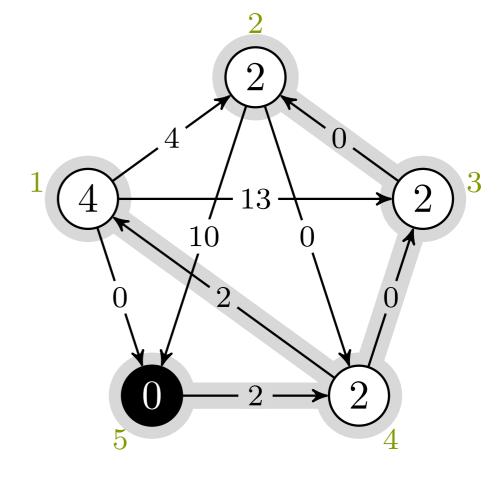


	_								
	1	0		-3	2	-4	0	1	
D	2	3	0	_	1	-1	-1	2	
	3	7	4	0	5	3	-5	3	h
	4	2	-1	-5	0	-2	0	4	
	5	8	5	1			-4	5	
	•	1	2	3	4	5		•	



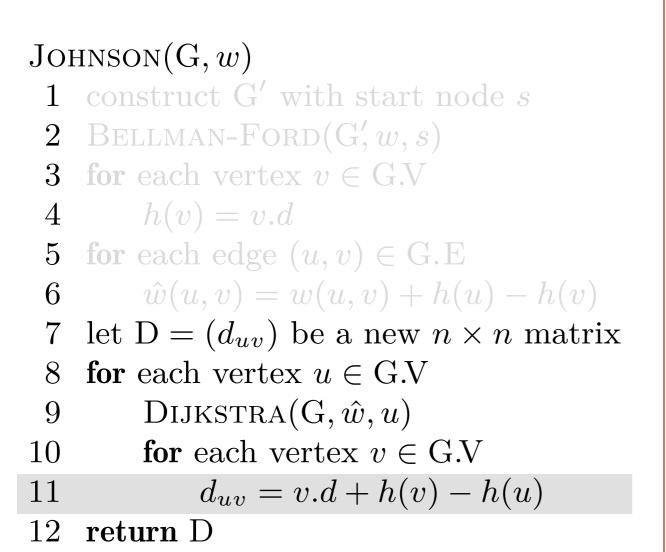


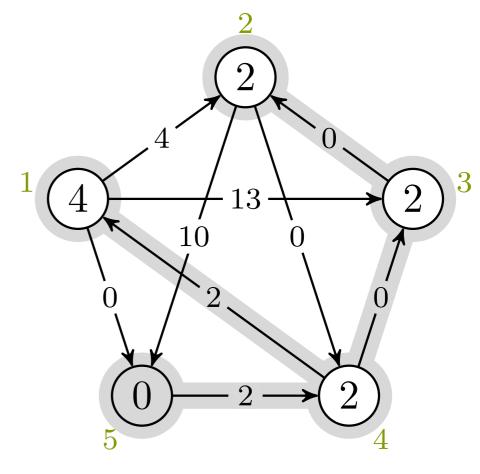
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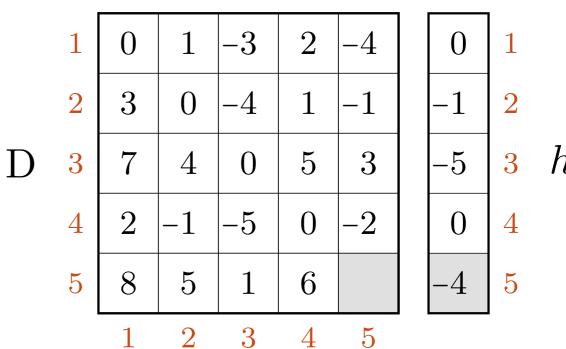


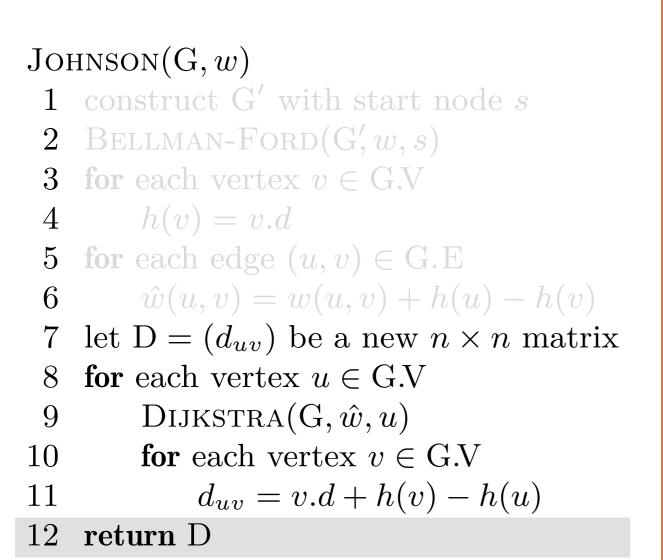
	1	0	1	-3	2	-4	0	1	
	2	3	0		1	-1	-1	2	
D	3	7	4	0	5	3	-5	3	
	4	2	-1	-5	0	-2	0	4	
	5	8	5	1	6		-4	5	
	•	1	2	3	1	5		•	

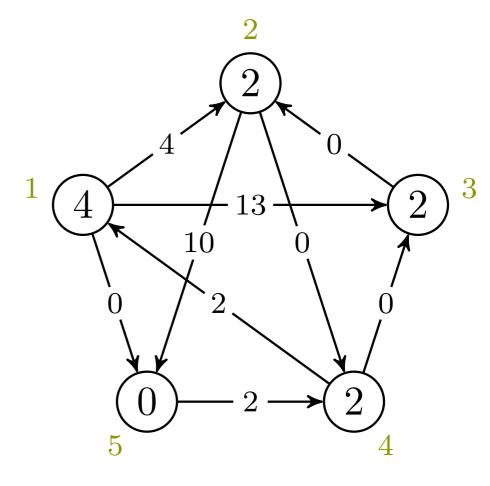
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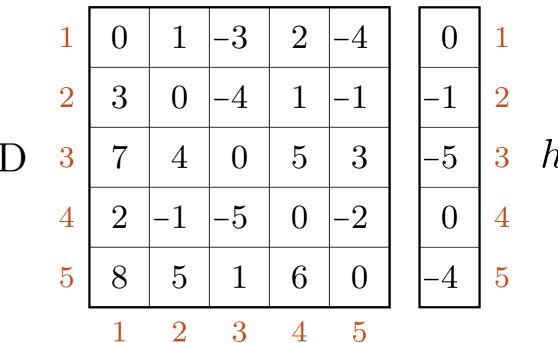


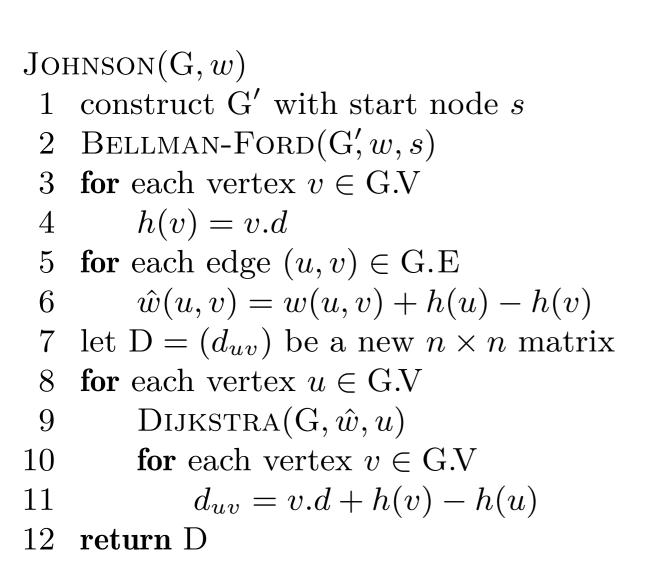


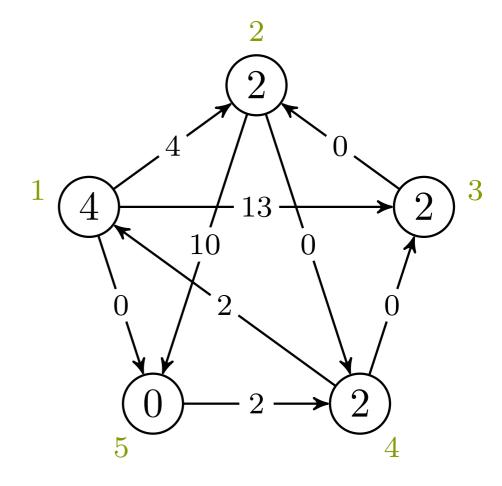


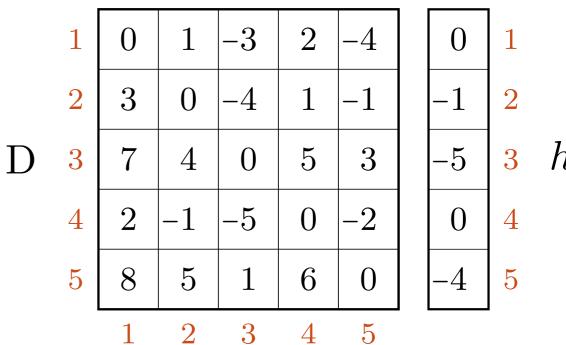












Transitiv lukning

$A\ Theorem\ on\ Boolean\ Matrices*$

 S_{TEPHEN} $W_{ARSHALL}$ †

Computer Associates, Inc., Woburn, Massachusetts Given two boolean matrices A and B, we define the boolean product $A \wedge B$ as that matrix whose (i, j)th entry is $\mathbf{v}_k(a_{ik} \wedge b_{kj})$.

We define the boolean sum $A \lor B$ as that matrix whose (i, j)th entry is The Use of boolean matrices to represent program topology (Prosser [1], and The use of boolean matrices to represent program topology (Prosser [1], and the description of the descripti Warmont [2], for example) has led to interest in algorithms for transformatrix M to the $d \times d$ boolean matrix M' given by:

 $M' = \bigvee_{i=1}^{d} M^{i}$ where we define $M^{1} = M$ and M^{i+1}

The convenience of describing the

Fra 1960 (publisert 1962). Bernhard Roy publiserte samme resultat separat i 1959.

korteste vei > transitiv lukning > problemet

Input: En rettet graf G = (V, E).

Input: En rettet graf G = (V, E).

Output: En rettet graf $G^* = (V, E^*)$ der $(i, j) \in E^*$ hvis og bare hvis det finnes en sti fra i til j i G.

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Output: En rettet graf $G^* = (V, E^*)$ der $(i, j) \in E^*$ hvis og bare hvis det finnes en sti fra i til j i G.

korteste vei > transitiv lukning

Traversér fra hver node?

 $Y = Kj \text{ gretid: } V \times \Theta(E + V) = \Theta(VE + V^2)$

- \rightarrow Kjøretid: $V \times \Theta(E + V) = \Theta(VE + V^2)$
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Vi fokuserer på tilfellet $E = \Theta(V^2)$

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> Korteste stier har felles segmenter

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Dekomponering: Hva blir «koordinatene» til delproblemene?



Det finnes en vei fra $i \dots$



Det finnes en vei fra i til j...

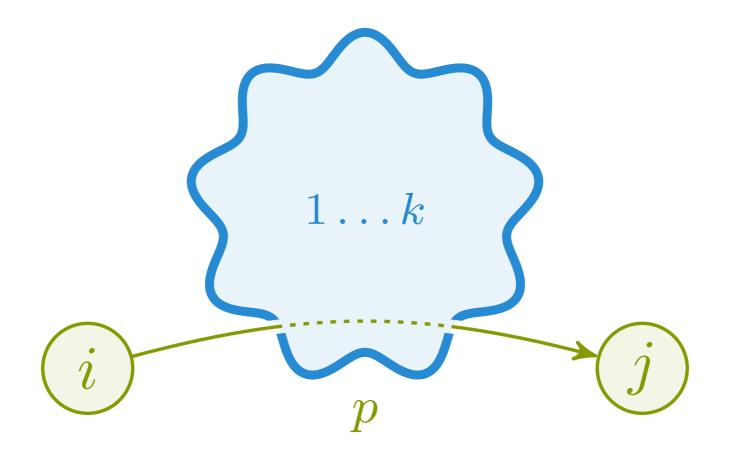




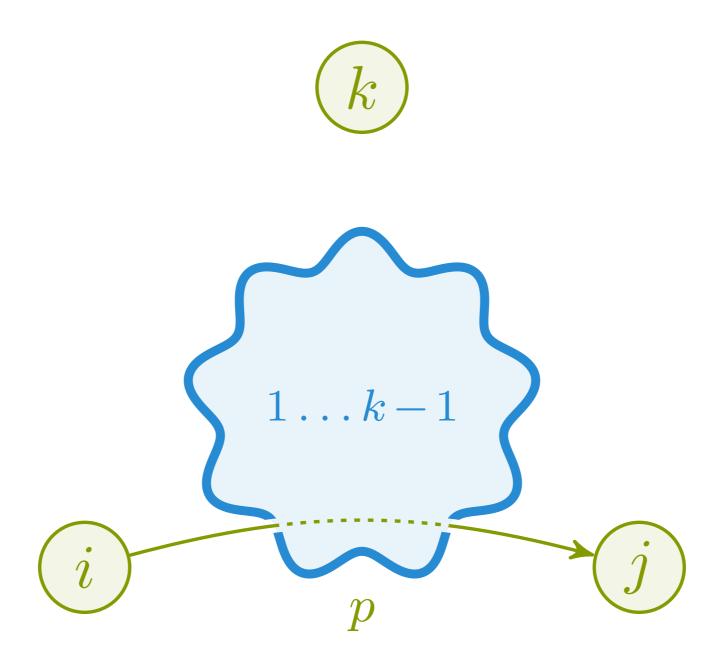
Det finnes en vei fra i til j via noder fra $\{1 \dots k\}$



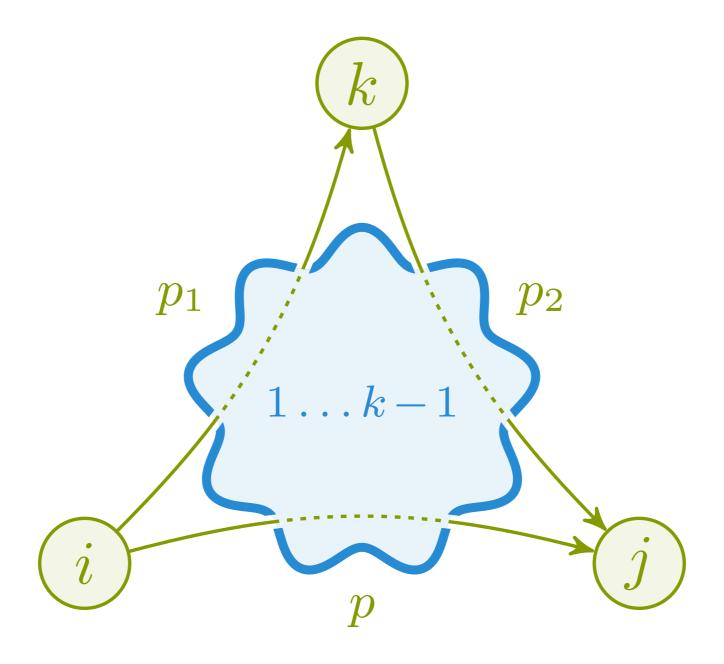
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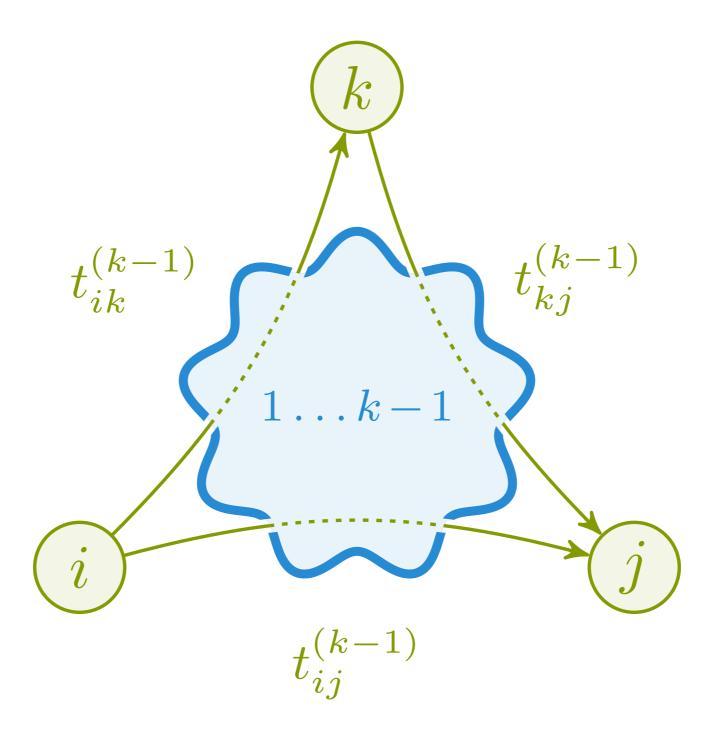
 $t_{ij}^{(k)} = \det \text{ går en vei fra } i \text{ til } j \text{ via noder fra } \{1 \dots k\}$

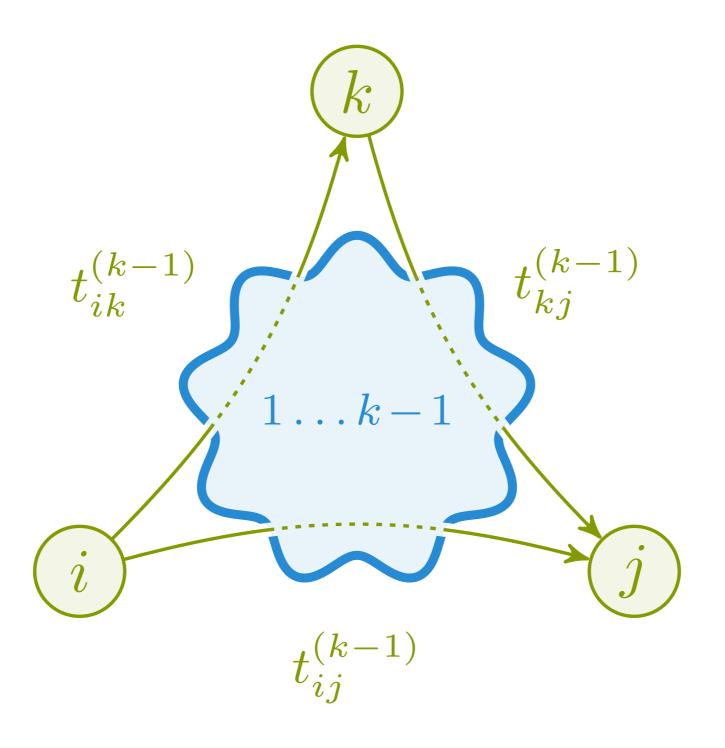


Som for ryggsekkproblemet: Skal k være med eller ikke?



De mulige stiene p, p_1 og p_2 går kun via noder fra $\{1 \dots k-1\}$





$$t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)})$$

$$t_{ij}^{(0)} = \begin{cases} 0 & \text{if } i \neq j \text{ and } (i,j) \notin E, \\ 1 & \text{if } i = j \text{ or } (i,j) \in E. \end{cases}$$

korteste vei > transitiv lukning

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Problemet er at iterasjonene 1...k «blandes», så vi kan risikere at noen av del-stiene allerede går innom k – så kanskje vi går innom k mer enn én gang? I så fall har vi en sykel ... men om det finnes en sti *med* en sykel, så finnes det også en sti *uten* en sykel!

Det er trygt å bruke én tabell. Hvorfor?

G graf

Transitive-Closure(G)
1
$$n = |GV|$$

$$1 \quad n = |GV|$$

2 let
$$T^{(0)} = (t_{ij}^{(0)})$$
 be a new $n \times n$ matrix

G graf

$$n$$
 ant. noder

 $t_{ij}^{(k)} i \stackrel{1 \cdots k}{\leadsto} j$?

Finnes en sti $i \rightsquigarrow j$ som ikke går via andre noder?

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- 5 if i == j or $(i, j) \in G.E$

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4 for j = 1 to n

5 if i == j or (i, j) \in G.E

6 t_{ij}^{(0)} = 1
```

G graf

n ant. noder

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Da finnes det en sti $i \leadsto j$ som ikke går via andre noder

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6 \quad t_{ij}^{(0)} = 1
7 \quad \text{else } t_{ij}^{(0)} = 0
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G graf

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$$t_{ij}^{(k)}$$
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Transitive-Closure(G) $7 \dots$

G graf n ant. noder $t_{ij}^{(k)} i \stackrel{1 \cdots k}{\leadsto} j$?

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G graf

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Finnes en sti $i \leadsto j$ som kun får gå innom $\{1, \ldots, k\}$?

Transitive-Closure(G)

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7 ...
```

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G graf

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For hver mulig startnode...

Transitive-Closure(G)

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7 ...
8 for k = 1 to n
9 let T^{(k)} = (t_{ij}^{(k)}) be a new n \times n matrix
10 for i = 1 to n
11 for j = 1 to n
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G graf

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For hver mulig sluttnode...

Transitive-Closure(G)

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12 t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)})
```

G graf

$$n$$
 ant. noder

 $t_{ij}^{(k)} i \stackrel{1 \cdots k}{\leadsto} j$?

Finnes $i \leadsto j$ eller $i \leadsto k \leadsto j$, om vi kun får gå innom $\{1, \ldots, k-1\}$?

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Transitive-Closure(G)
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13 return T^{(n)}
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G graf

$$n$$
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 $t_{ij}^{(k)}$ $i \stackrel{1 \cdots k}{\leadsto} j$?

Finnes det en sti $i \rightsquigarrow j$ som får gå innom $\{1, \ldots, n\}$, dvs. alle?

Transitive-Closure'(G)

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$$k = 1$$
 to n

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$$i = 1$$
 to n

5 **for**
$$j = 1$$
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$$6 t_{ij} = t_{ij} \lor (t_{ik} \land t_{kj})$$

	1	2	3	4	5
1	1		1		1
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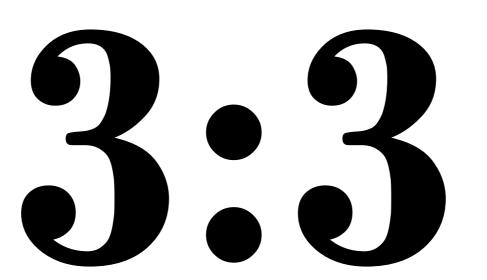
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Korteste vei > Transitiv lukning > Kjøretid

$$\operatorname{init}
ightarrow \Theta(n^2)$$
 $\operatorname{for} i = 1 \operatorname{to} n$
 $\operatorname{sett} t_{ij}^{(0)}
ightarrow \operatorname{O}(1)$
 $\operatorname{for} k = 1 \operatorname{to} n$
 $\operatorname{evt. ny matrise}
ightarrow \Theta(n^2)$
 $\operatorname{for} i = 1 \operatorname{to} n$
 $\operatorname{for} j = 1 \operatorname{to} n$
 $\operatorname{sett} t_{ij}^{(k)}
ightarrow \operatorname{O}(1)$
 $\operatorname{return}
ightarrow \operatorname{O}(1)$

```
init \Theta(n^2)
for i = 1 to n
      for j = 1 to n
            sett t_{ij}^{(0)} \rightarrow \mathcal{O}(1)
for k = 1 to n
      evt. ny matrise \Theta(n^2)
      for i = 1 to n
            for j = 1 to n
                  sett t_{ij}^{(k)} \to \mathrm{O}(1)
return \rightarrow O(1)
Totalt: \Theta(n^3)
```

Fra 1962.



Floyd-Warshall

m [j, k] :end ancestor

ALGORITHM 97
SHORTEST PATH
ROBERT W. FLOYD
Armour Research Foundation, Chicago, Ill.

procedure shortest path (m, n); value n; integrated in the length of a direct link in the length of the length of a network to point j. If no direct link point i of a network to point j. If no direct length initially will. At completion, m [i, j] is will initially will. At completion, m [i, j] is will path from i to j. If none exists, m [i, j] is will path from i to j. If none exists, m [i, j] is will path from i to j.

path from i to j. If none exists, m [i, j] is 1010, shall, S. A theorem on Boolean matrices. J, A begin integer i, j, k; real inf, s; inf := 1010; begin integer i, i, k; real inf, s; inf := 1010; for i:= 1 step 1 until n do for j:= 1 step 1 until n do for k:= 1 step 1 until n

Contributions to this department of the Algorithms Department of the Algorithms Department of the Algorithms Department of the Algorithms, February, 1960 (Communications, February, 1960) (Communications should be sent in Contributions should be sent in Contributions Should be sent in Contributions Department of Algorithm Washington 25, D. C. Algorithm form of Algorithms appeared and the convenience of the printer of the convenience of the printer delimiters to appear in the Although each algorithm Although each algorithm utor, no warranty, expressed

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The reproduction of the reproduction of the reproduction is for public production is for public made to the algorithm issue bearing the algorithm.

Fra hver node til alle andre?

 \rightarrow DIJKSTRA med tabell: $O(V^3 + VE)$

 \rightarrow DIJKSTRA med tabell: $O(V^3 + VE)$

 $\rightarrow \dots$ med binærhaug: $O(VE \lg V)$

 \rightarrow DIJKSTRA med tabell: $O(V^3 + VE)$

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 $O(V^2 \lg V + VE)$

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Målsetting:

> Vi vil tillate negative kanter

DIJKSTRA med tabell: $O(V^3 + VE)$

 $\rightarrow \dots$ med binærhaug: $O(VE \lg V)$

 $O(V^2 \lg V + VE)$

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- > Vi vil tillate negative kanter
- Vi vil ha lavere asymptotisk kjøretid...

 \rightarrow DIJKSTRA med tabell: $O(V^3 + VE)$

 $\rightarrow \dots$ med binærhaug: $O(VE \lg V)$

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- > Vi vil tillate negative kanter
- Vi vil ha lavere asymptotisk kjøretid...
- ... og vil ha lavere konstantledd

 \rightarrow DIJKSTRA med tabell: $O(V^3 + VE)$

 $\rightarrow \dots$ med binærhaug: $O(VE \lg V)$

 $O(V^2 \lg V + VE)$

 \rightarrow Bellman-Ford: $\Theta(V^2E)$

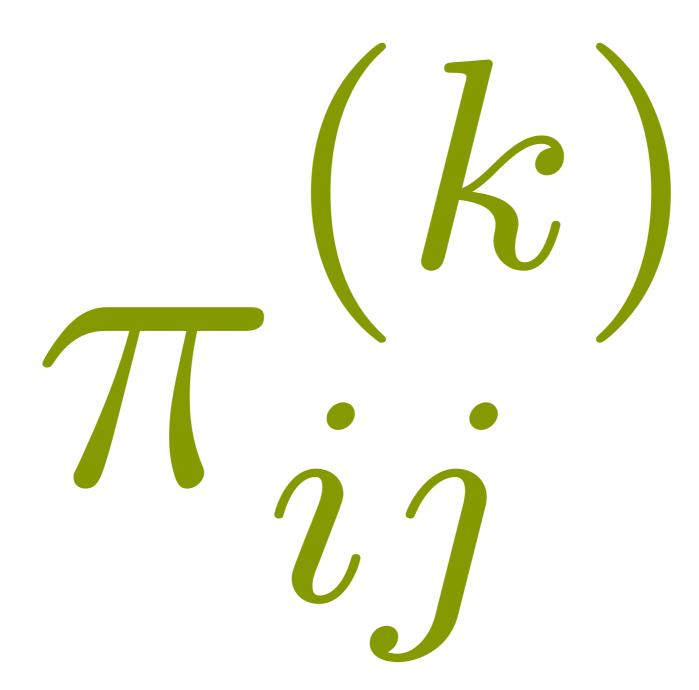
- > Vi vil tillate negative kanter
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- ... og vil ha lavere konstantledd



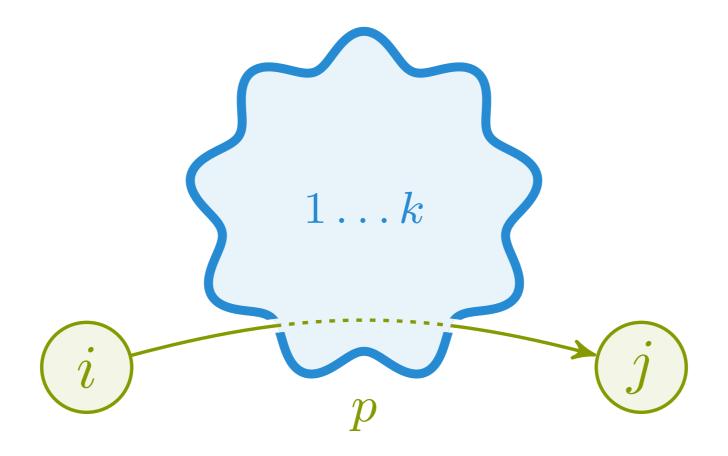
Korteste vei fra i til j via noder fra $\{1 \dots k\}$



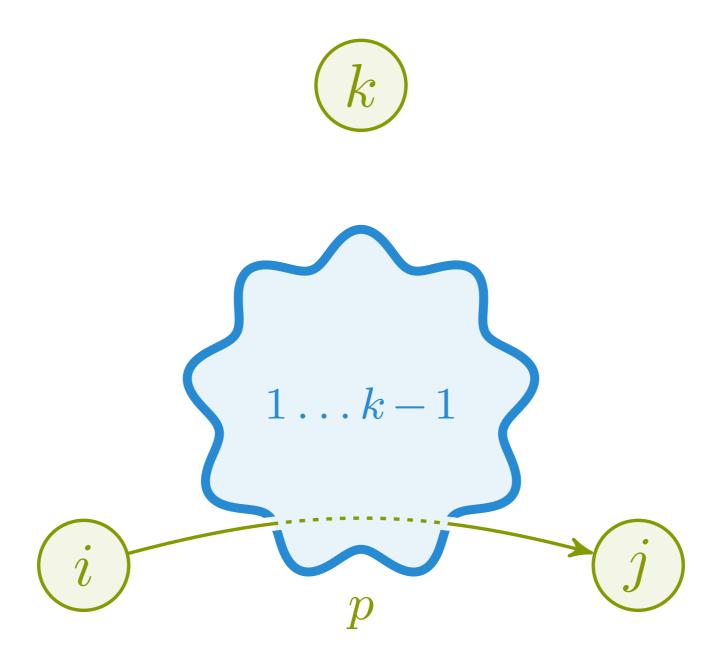
Korteste vei fra i til j via noder fra $\{1 \dots k\}$



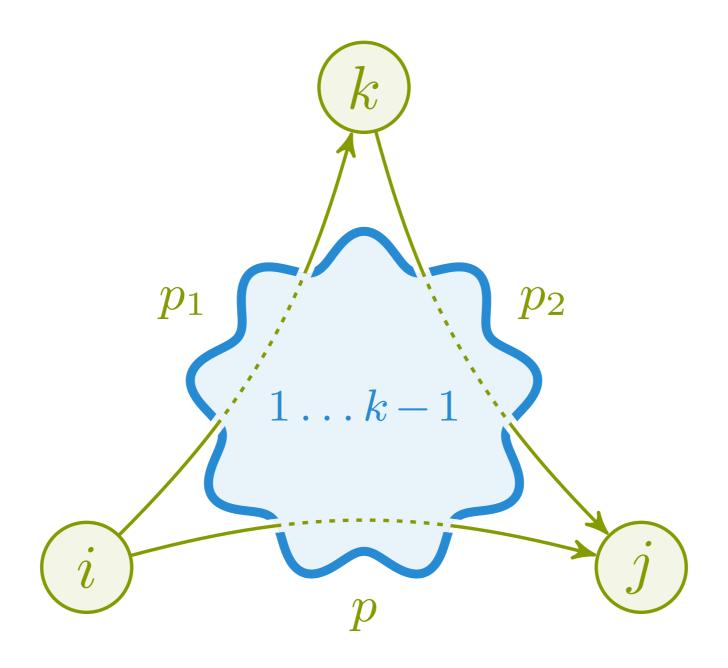
Forgjengeren til j om vi starter i i og går via noder fra $\{1 \dots k\}$



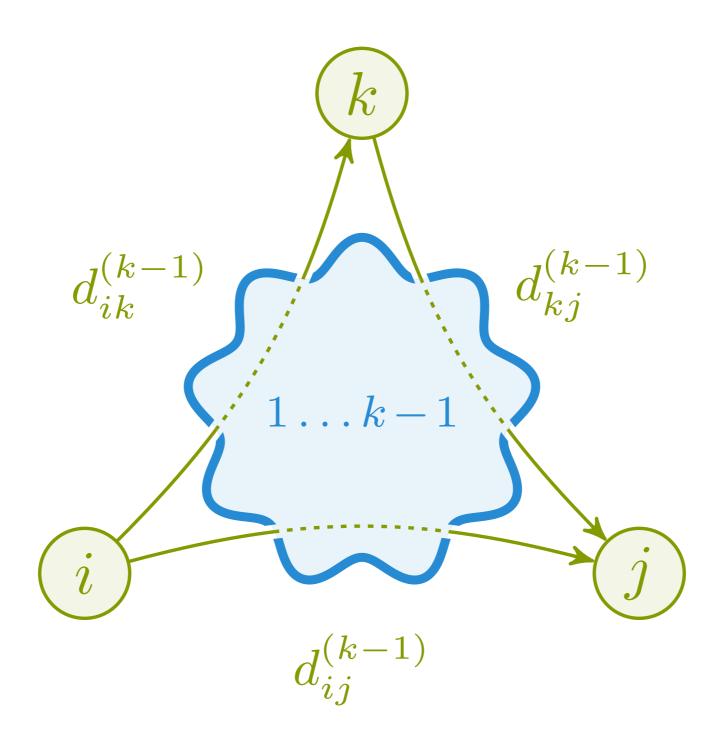
 $d_{ij}^{(k)} = \text{korteste vei fra } i \text{ til } j \text{ via noder fra } \{1 \dots k\}$



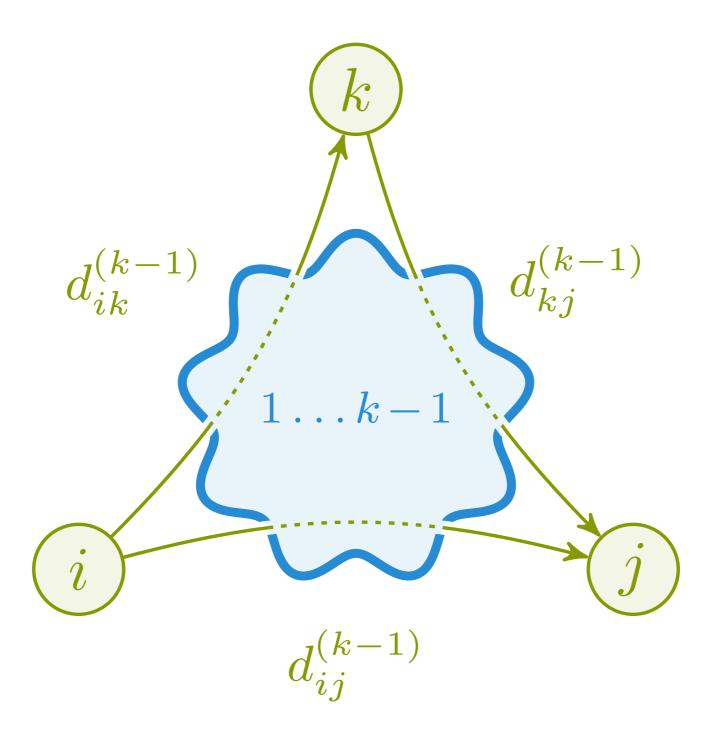
Som for ryggsekkproblemet: Skal k være med eller ikke?



Stiene p, p_1 og p_2 går kun via noder fra $\{1 \dots k-1\}$



 $\boldsymbol{d}_{ij}^{(k)}$ kan enten være $\boldsymbol{d}_{ij}^{(k-1)}$ eller $\boldsymbol{d}_{ik}^{(k-1)} + \boldsymbol{d}_{kj}^{(k-1)}$



$$d_{ij}^{(k)} = \min \left(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right)$$

$$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{if } k = 0, \\ \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}) & \text{if } k \ge 1. \end{cases}$$

$$\pi_{ij}^{(0)} = \begin{cases} \text{NIL} & \text{if } i = j \text{ or } w_{ij} = \infty, \\ i & \text{if } i \neq j \text{ and } w_{ij} < \infty. \end{cases}$$

$$\pi_{ij}^{(k)} = \left\{ \right.$$

if
$$d_{ij}^{(k-1)} \le d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$$
,

$$\pi_{ij}^{(k)} = \begin{cases} \pi_{ij}^{(k-1)} & \text{if } d_{ij}^{(k-1)} \le d_{ik}^{(k-1)} + d_{kj}^{(k-1)}, \\ \end{cases}$$

$$\pi_{ij}^{(k)} = \begin{cases} \pi_{ij}^{(k-1)} & \text{if } d_{ij}^{(k-1)} \le d_{ik}^{(k-1)} + d_{kj}^{(k-1)}, \\ & \text{if } d_{ij}^{(k-1)} > d_{ik}^{(k-1)} + d_{kj}^{(k-1)}. \end{cases}$$

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Som før: Vi kan ha gått innom k i én av delstiene, siden vi blander iterasjoner – men vi antar at det ikke er noen negative sykler, og en positiv sykel vil aldri lønne seg (og vil dermed ikke bli med).

Vi kan bruke én tabell igjen (se oppgave 25.2-4)

$$\pi_{ij}^{(k)} = \begin{cases} \pi_{ij}^{(k-1)} & \text{if } d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)}, \\ \pi_{kj}^{(k-1)} & \text{if } d_{ij}^{(k-1)} > d_{ik}^{(k-1)} + d_{kj}^{(k-1)}. \end{cases}$$

Fordi denne bare baserer seg på valget vi gjør for d.

Også her holder det med én tabell

FLOYD-WARSHALL(W) $1 \quad n = \text{W.} rows$

- $1 \quad n = W.rows$
- $2 D^{(0)} = W$

Korteste vei $i \leadsto j$ som ikke går via andre = w(i,j)

- $1 \quad n = W.rows$
- $2 D^{(0)} = W$
- 3 **for** k = 1 **to** n

- $1 \quad n = W.rows$
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- let $D^{(k)} = (d_{ij}^{(k)})$ be a new $n \times n$ matrix

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- 5 **for** i = 1 **to** n

For hver mulig startnode...

```
FLOYD-WARSHALL(W)

1 n = \text{W.}rows

2 D^{(0)} = \text{W}

3 for k = 1 to n

4 let D^{(k)} = (d_{ij}^{(k)}) be a new n \times n matrix

5 for i = 1 to n

6 for j = 1 to n
```

For hver mulig sluttnode...

```
FLOYD-WARSHALL(W)

1  n = \text{W.} rows

2  D^{(0)} = \text{W}

3  for k = 1 to n

4  let D^{(k)} = (d_{ij}^{(k)}) be a new n \times n matrix

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7  d_{ij}^{(k)} = \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})
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6  for j = 1 to n

7  d_{ij}^{(k)} = \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})

8  return D^{(n)}
```

FLOYD-WARSHALL'(W) $1 \quad n = \text{W.} rows$ FLOYD-WARSHALL'(W)

- 1 n = W.rows
- 2 initialize D and Π

FLOYD-WARSHALL'(W)

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FLOYD-WARSHALL'(W)

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For hver mulig startnode...

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		1	2	3	4	5
	1	0	3	8	∞	-4
	2	∞	0	∞	1	7
D	3	∞	4	0	∞	∞
	4	2	∞	-5	0	∞
	5	∞	∞	∞	6	0
	'					

		1	2	3	4	5
	1		1	1		1
	2				2	2
Π	3		3			
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	5				5	

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	,	1	2	9	1	X

		1	2	3	4	5
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	'					
D	3	∞	$4 \\ \infty \\ \infty$		6	$ \begin{array}{c} \gamma \\ \infty \\ 0 \end{array} $

		1	2	3	4	5
	1		1	1		1
	2				2	2
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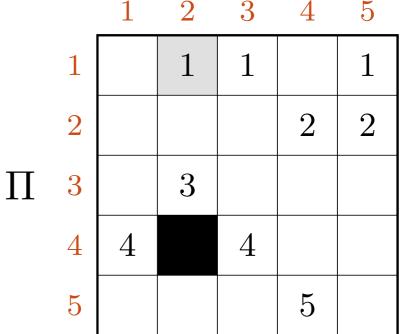
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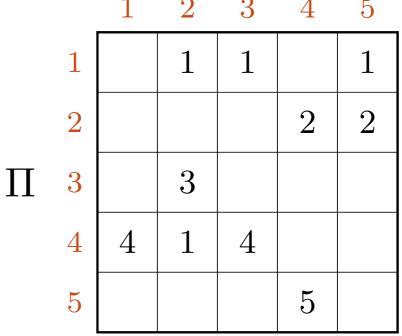
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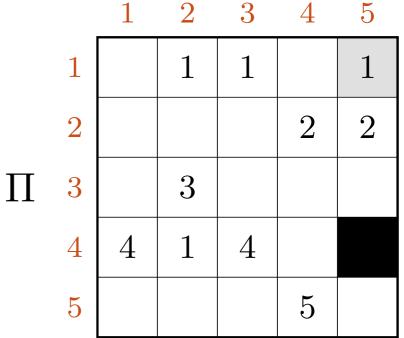
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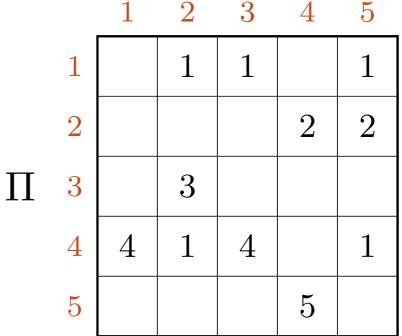
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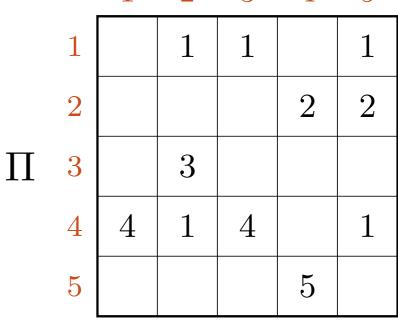
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	5	∞	∞	∞	6	0
	'					

		1	2	3	4	5
	1		1	1	2	1
	2				2	2
Π	3		3			
	4	4	1	4		1
	5				5	

FLOYD-WARSHALL'(W)

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	2	∞	0	∞	1	7
D	3	∞	4	0	∞	∞
	4	2	5	-5	0	-2
	5	∞	∞	∞	6	0

		1	2	3	4	5
	1		1	1	2	$\begin{array}{ c c c } 1 \end{array}$
	2				2	2
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D	3	∞	4	0	∞	∞
	4	2	5	-5	0	-2
	5	∞	∞	∞	6	0
		·	·			

		1	2	3	4	5
	1		1	1	2	1
	2				2	2
Π	3		3			
	4	4	1	4		1
	5				15	

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		1	2	3	4	5
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	5				5	

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	·			1		1

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		1	2	3	4	5
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3	∞	4	0	5	∞
4	2	5	-5	0	-2
5	∞	∞	∞	6	0
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		1	2	3	4	5
	1		1	1	2	1
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D	3	∞	4	0	5	∞
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	5	∞	∞	∞	6	0
	·					
			2	.7		5

		1	2	3	4	5
	1		1	1	2	1
	2				2	2
Π	3		3		2	
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		_	_		4	

		1	2	3	4	5
	1		1	1	2	1
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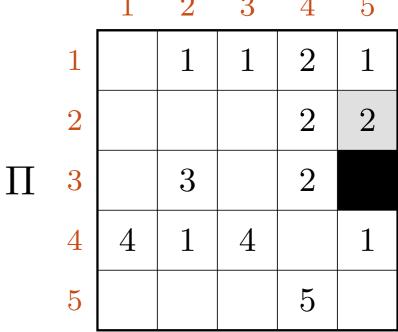
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D	3	∞	4	0	5	11
	4	2	5	-5	0	-2
	5	∞	∞	∞	6	0
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			•	•	•	•

		1	2	3	4	5
	1		1	1	2	1
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FLOYD-WARSHALL'(W)

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'	-1		9	4	F
	2 3 4	$egin{array}{c c} 1 & 0 \\ \hline 2 & \infty \\ \hline 3 & \infty \\ \hline 4 & 2 \\ \hline \end{array}$	$egin{array}{c cccc} 1 & 0 & 3 \\ 2 & \infty & 0 \\ 3 & \infty & 4 \\ 4 & 2 & -1 \\ 5 & \infty & \infty \\ \hline \end{array}$	$egin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

		1	2	3	4	5
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9 return D, Π

k, i, j = 3, 4, 5

		1	2	3	4	5
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	1	0	3	-1	4	-4
	2	∞	0	∞	1	7
D	3	∞	4	0	5	11
	4	2	-1	-5	0	-2
	5	∞	∞	∞	6	0
	'					

		1	2	3	4	5
	1		1	4	2	1
	2				2	2
Π	3		3		2	2
	4	4	3	4		1
	5				5	

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	5	∞	∞	∞	6	0
		1	2	3	4	5
	1		1	4	2	1
	2				2	2
П	2		2		2	2

	1		1	4	2	1
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	2	1		1	2	2

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		- 1			/	

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	5	4			5	

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		1	2	3	4	5
	1	0	3	-1	4	-4
	2	3	0	-4	1	-1
D	3	7	4	0	5	3
	4	2	-1	-5	0	-2
	5	8	∞	∞	6	0
	'	1	2	3	4	5

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		1
	5	4			5	

FLOYD-WARSHALL'(W)

1
$$n = \text{W.} rows$$

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D	3	7	4	0	5	3
	4	2	-1	-5	0	-2
	5	8	5	∞	6	0

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4			5	

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	4	2	-1	-5	0	-2
	5	8	5	∞	6	0

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		1
	5	4	3		5	

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		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		$\mid 1 \mid$
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	5	8	5	1	6	0

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		$\mid 1 \mid$
	5	4	3		5	

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	4	2	-1	-5	0	-2
	5	8	5	1	6	0

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	$\mid 1 \mid$
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		1
	5	4	3	4	5	

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	4	2	-1	-5	0	-2
	5	8	5	1	6	0

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	$\mid 1 \mid$
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		1
	5	4	3	4	5	

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9 return D, Π

4	5
4	-4
1	-1
5	3
0	-2
6	0
	1 5 0

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

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	5	8	5	1	6	0
	'					

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

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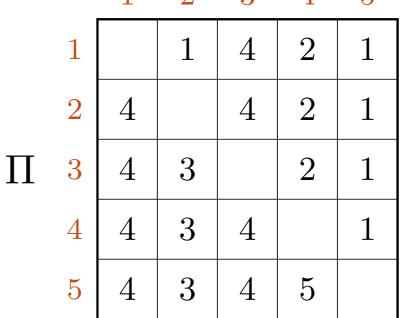
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		1	2	3	4	5
	1	0	3	-1	4	$\overline{-4}$
	2	3	0	-4	1	-1
D	3	7	4	0	5	3
	4	2	-1_	-5	0	-2
	5	8	5	1	6	0
	-					
		1	2	3	4	5
	1		1	4	2	1



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	5	8	5	1	6	0
	•					

		1	2	3	4	5
	1		1	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

FLOYD-WARSHALL'(W)

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	'		•			

		1	2	3	4	5
	1		3	4	2	1
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	!					

		1	2	3	4	5
	1		3	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

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D	3	7	4	0	5	3
	4	2	-1	-5	0	-2
	5	8	5	1	6	0
		1	2	3	4	5
	1		3	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1

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	5	8	5	1	6	0
	•					

		1	2	3	4	5
	1		3	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
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	2	3	0	-4	1	-1
D	3	7	4	0	5	3
	4	2	-1	-5	0	-2
	5	8	5	1	6	0
	!	1	2	3	1	5

		1	2	3	4	5
	1		3	4	2	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

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	'					

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	,					
		1	2	3	1	5

		1	2	3	4	5
	1		3	4	5	1
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	5	8	5	1	6	0
	!					

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	$\mid 1 \mid$
Π	3	4	3		2	$\mid 1 \mid$
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	1	2	3	4	5
1	0	1	-3	2	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	0
	2 3 4	 3 7 2 3 4 2 	1 0 1 2 3 0 3 7 4 4 2 -1	1 0 1 -3 2 3 0 -4 3 7 4 0 4 2 -1 -5	1 0 1 -3 2 2 3 0 -4 1 3 7 4 0 5 4 2 -1 -5 0

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
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9 return D, Π

		1	2	3	4	5
	1	0	1	-3	2	-4
	2	3	0	-4	1	-1
D	3	7	4	0	5	3
	4	2	-1	-5	0	-2
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	'					

		1	2	3	4	5
	1		3	4	5	1
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Π	3	4	3		2	$\mid 1 \mid$
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FLOYD-WARSHALL'(W)

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$$n = \text{W.}rows$$

2 initialize D and Π

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	1					
		1	\mathbf{O}	•	1	

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	4	4	3	4		1
	5	4	3	4	5	

```
FLOYD-WARSHALL'(W)

1 n = \text{W.}rows

2 initialize D and \Pi

3 for k = 1 to n

4 for i = 1 to n

5 for j = 1 to n

6 if d_{ij} > d_{ik} + d_{kj}

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		1	2	3	4	5
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	,				_	
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	1		3	4	5	1
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	4	4	3	4		1
	5	4	3	4	5	

Print-All-Pairs-Shortest-Path (Π, i, j)

Print-All-Pairs-Shortest-Path (Π, i, j) 1 if i == j Print-All-Pairs-Shortest-Path (Π, i, j)

- 1 **if** i == j
- 2 print i

...så bare skriv ut noden

Print-All-Pairs-Shortest-Path (Π, i, j)

- 1 **if** i == j
- 2 print i
- 3 elseif $\pi_{ij} == \text{NIL}$

Hvis vi ellers ikke kom fra noe sted...

```
Print-All-Pairs-Shortest-Path(\Pi, i, j)
1 if i == j
2 print i
3 elseif \pi_{ij} == \text{NIL}
4 print "no path from" i "to" j "exists"
```

```
Print-All-Pairs-Shortest-Path(\Pi, i, j)

1 if i == j

2 print i

3 elseif \pi_{ij} == \text{NIL}

4 print "no path from" i "to" j "exists"

5 else Print-All-Pairs-Shortest-Path(\Pi, i, \pi_{ij})
```

```
Print-All-Pairs-Shortest-Path(\Pi, i, j)

1 if i == j

2 print i

3 elseif \pi_{ij} == \text{NIL}

4 print "no path from" i "to" j "exists"

5 else Print-All-Pairs-Shortest-Path(\Pi, i, \pi_{ij})

6 print j
```

Print-Path (Π, i, j)

```
1 if i == j

2 print i

3 elseif \pi_{ij} == \text{NIL}

4 print "no such path"

5 else Print-Path(\Pi, i, \pi_{ij})

6 print j
```

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

Print-Path(
$$\Pi, i, j$$
)

1 if $i == j$

2 print i

3 elseif $\pi_{ij} == \text{NIL}$

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	4	4	3	4		1
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PRINT-PATH (Π, i, j)

```
1 if i == j

2 print i

3 elseif \pi_{ij} == \text{NIL}

4 print "no such path"

5 else PRINT-PATH(\Pi, i, \pi_{ij})

6 print j
```

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

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$$\Pi, i, j$$
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		1	2	3	4	5
	1		3	4	5	1
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Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

Print-Path(
$$\Pi, i, j$$
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3 elseif $\pi_{ij} == \text{NIL}$

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5 else Print-Path(Π, i, π_{ij})

6 print j

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	$\mid 1 \mid$
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		1
	5	4	3	4	5	

$$i, j = 1, 2 \rightarrow 1, 3 \rightarrow 1, 4 \rightarrow 1, 5$$

.

Print-Path(
$$\Pi, i, j$$
)

1 if $i == j$

2 print i

3 elseif $\pi_{ij} == \text{NIL}$

4 print "no such path"

5 else Print-Path(Π, i, π_{ij})

6 print j

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

$$i, j = 1, 2 \rightarrow 1, 3 \rightarrow 1, 4$$

Print-Path(
$$\Pi, i, j$$
)

1 if $i == j$

2 print i

3 elseif $\pi_{ij} == \text{NIL}$

4 print "no such path"

5 else Print-Path(Π, i, π_{ij})

6 print j

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

Print-Path
$$(\Pi, i, j)$$
1 if $i == j$
2 print i
3 elseif $\pi_{ij} == \text{NIL}$
4 print "no such path"
5 else Print-Path (Π, i, π_{ij})
6 print j

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	$\mid 1 \mid$
Π	3	4	3		2	$\mid 1 \mid$
	4	4	3	4		$\mid 1 \mid$
	5	4	3	4	5	

$$i, j = 1, 2$$

Pı	RINT-PATH (Π,i,j)
1	if $i == j$
2	print i
3	elseif $\pi_{ij} == NIL$
4	print "no such path"
5	else Print-Path (Π, i, π_{ij})
6	$\operatorname{print} j$

		1	2	3	4	5
	1		3	4	5	1
	2	4		4	2	1
Π	3	4	3		2	1
	4	4	3	4		1
	5	4	3	4	5	

$$i, j = 1, 2$$

Korteste vei > Floyd-Warshall > Kjøretid

```
\operatorname{for} k = 1 \text{ to } n
\operatorname{for} i = 1 \text{ to } n
\operatorname{for} j = 1 \text{ to } n
\min_{j \in \mathcal{O}(1)} \operatorname{O}(1)
```

```
egin{aligned} & \inf & \Theta(n^2) \ & \mathbf{for} \ k = 1 \ \mathbf{to} \ n \ & \mathbf{for} \ i = 1 \ \mathbf{to} \ n \ & \mathbf{for} \ j = 1 \ \mathbf{to} \ n \ & \min & \mathrm{O}(1) \end{aligned}
\mathbf{return} & \mathrm{O}(1)
```

1. Johnsons algoritme

2. Transitiv lukning

3. Floyd-Warshall