

### STM32F446xC/xE device errata

#### Applicability

This document applies to the part numbers of STM32F446xC/xE devices and the device variants as stated in this page. It gives a summary and a description of the device errata, with respect to the device datasheet and reference manual RM00390. Deviation of the real device behavior from the intended device behavior is considered to be a device limitation. Deviation of the description in the reference manual or the datasheet from the intended device behavior is considered to be a documentation erratum. The term “*errata*” applies both to limitations and documentation errata.

**Table 1. Device summary**

Reference	Part numbers
STM32F446xx	STM32F446MC, STM32F446ME, STM32F446RC, STM32F446RE, STM32F446VC, STM32F446VE, STM32F446ZC, STM32F446ZE.

**Table 2. Device variants**

Reference	Silicon revision codes	
	Device marking <sup>(1)</sup>	REV_ID <sup>(2)</sup>
STM32F446xx	A	0x1000
	1	

1. Refer to the device datasheet for how to identify this code on different types of package.

2. REV\_ID[5:0] bitfield of DBGMCU\_IDCODE fuse.

**Note:** DBGMCU\_IDCODE register is not automatically shadowed with OTP content, so a fuse read sequence must be issued to get the register updated once (clear after reading). Refer to product reference manual - BSEC section “Operations on fuses”.

## 1 Summary of device errata

The following table gives a quick reference to the STM32F446xC/xE device limitations and their status:

A = limitation present, workaround available

N = limitation present, no workaround available

P = limitation present, partial workaround available

“-” = limitation absent

Applicability of a workaround may depend on specific conditions of target application. Adoption of a workaround may cause restrictions to target application. Workaround for a limitation is deemed partial if it only reduces the rate of occurrence and/or consequences of the limitation, or if it is fully effective for only a subset of instances on the device or in only a subset of operating modes, of the function concerned.

**Table 3. Summary of device limitations**

Function	Section	Limitation	Status	
			Rev. A	Rev. 1
Core	2.1.1	Interrupted loads to SP can cause erroneous behavior	A	A
	2.1.2	VDIV or VSQRT instructions might not complete correctly when very short ISRs are used	A	A
	2.1.3	Store immediate overlapping exception return operation might vector to incorrect interrupt	A	A
System	2.2.1	Debugging Stop mode and SysTick timer	A	A
	2.2.2	Debugging Stop mode with WFE entry	A	A
	2.2.3	Debugging Sleep/Stop mode with WFE/WFI entry	A	A
	2.2.4	Wake-up sequence from Standby mode when using more than one wake-up source	A	A
	2.2.5	Full JTAG configuration without NJTRST pin cannot be used	A	A
	2.2.6	MPU attribute to RTC and IWDG registers incorrectly managed	A	A
	2.2.7	Delay after an RCC peripheral clock enabling	A	A
	2.2.8	Internal noise impacting the ADC accuracy	A	A
	2.2.9	Data cache might be corrupted during flash memory read-while-write operation	A	A
	2.2.10	Possible delay in backup domain protection disabling/enabling after programming the DBP bit	A	A
FSMC	2.2.11	PC13 signal transitions disturb LSE	N	N
	2.3.1	Dummy read cycles inserted when reading synchronous memories	N	N
	2.3.2	Wrong data read from a busy NAND memory	A	A
	2.3.3	Spurious clock stoppage with continuous clock feature enabled	A	A
QUADSPI	2.3.4	Data read might be corrupted when the write FIFO is disabled	A	A
	2.4.1	Extra data written in the FIFO at the end of a read transfer	A	A
	2.4.2	First nibble of data not written after dummy phase	A	A
	2.4.3	Wrong data from memory-mapped read after an indirect mode operation	A	A
	2.4.4	Memory-mapped read operations may fail when timeout counter is enabled	P	P
ADC	2.4.5	Memory-mapped access in indirect mode clearing QUADSPI_AR register	P	P
	2.5.1	ADC sequencer modification during conversion	A	A
DAC	2.6.1	DMA request not automatically cleared by clearing DMAEN	A	A

Function	Section	Limitation	Status	
			Rev. A	Rev. 1
DAC	2.6.2	DMA underrun flag not set when an internal trigger is detected on the clock cycle of the DMA request acknowledge	N	N
TIM	2.7.1	PWM re-enabled in automatic output enable mode despite of system break	P	P
	2.7.3	Consecutive compare event missed in specific conditions	N	N
	2.7.4	Output compare clear not working with external counter reset	P	P
IWDG	2.8.1	RVU flag not reset in Stop	A	A
	2.8.2	PVU flag not reset in Stop	A	A
	2.8.3	RVU flag not cleared at low APB clock frequency	A	A
	2.8.4	PVU flag not cleared at low APB clock frequency	A	A
RTC	2.9.1	Spurious tamper detection when disabling the tamper channel	N	N
	2.9.2	RTC calendar registers are not locked properly	A	A
	2.9.3	RTC interrupt can be masked by another RTC interrupt	A	A
	2.9.4	Calendar initialization may fail in case of consecutive INIT mode entry	A	A
	2.9.5	Alarm flag may be repeatedly set when the core is stopped in debug	N	N
	2.9.6	Detection of a tamper event occurring before enabling the tamper detection is not supported in edge detection mode	A	A
FMPI2C	2.10.1	10-bit master mode: new transfer cannot be launched if first part of the address is not acknowledged by the slave	A	A
	2.10.2	Wrong data sampling when data setup time ( $t_{SU,DAT}$ ) is shorter than one FMPI2C kernel clock period	P	P
	2.10.3	Spurious bus error detection in master mode	A	A
	2.10.4	Last-received byte loss in reload mode	P	P
	2.10.5	Spurious master transfer upon own slave address match	P	P
	2.10.7	OVR flag not set in underrun condition	N	N
	2.10.8	Transmission stalled after first byte transfer	A	A
	2.10.9	SDA held low upon SMBus timeout expiry in slave mode	A	A
I2C	2.11.1	Spurious bus error detection in master mode	A	A
	2.11.2	SMBus standard not fully supported	A	A
	2.11.3	Start cannot be generated after a misplaced Stop	A	A
	2.11.4	Mismatch on the "Setup time for a repeated Start condition" timing parameter	A	A
	2.11.5	Data valid time ( $t_{VD,DAT}$ ) violated without the OVR flag being set	A	A
	2.11.6	Both SDA and SCL maximum rise times ( $t_r$ ) violated when the VDD_I2C bus voltage is higher than $(V_{DD} + 0.3) / 0.7$ V	A	A
USART	2.12.1	Idle frame is not detected if the receiver clock speed is deviated	N	N
	2.12.2	In full-duplex mode, the Parity Error (PE) flag can be cleared by writing to the data register	A	A
	2.12.3	Parity Error (PE) flag is not set when receiving in Mute mode using address mark detection	N	N
	2.12.4	Break frame is transmitted regardless of CTS input line status	N	N
	2.12.5	RTS signal abnormally driven low after a protocol violation	A	A

Function	Section	Limitation	Status	
			Rev. A	Rev. 1
USART	2.12.6	Start bit detected too soon when sampling for NACK signal from the smartcard	N	N
	2.12.7	Break request can prevent the transmission complete flag (TC) from being set	A	A
	2.12.8	Guard time not respected when data are sent on TXE events	A	A
	2.12.9	RTS is active while RE or UE = 0	A	A
SPI/I2S	2.13.1	BSY bit may stay high when SPI is disabled	A	A
	2.13.2	Anticipated communication upon SPI transit from slave receiver to master	A	A
	2.13.3	I <sup>2</sup> S slave in PCM short pulse mode sensitive to timing between WS and CK	P	P
	2.13.4	Wrong CRC calculation when the polynomial is even	A	A
	2.13.5	Corrupted last bit of data and/or CRC received in Master mode with delayed SCK feedback	A	A
	2.13.6	BSY flag may stay high at the end of a data transfer in Slave mode	A	A
SDIO	2.14.1	Wrong CCRCFAIL status after a response without CRC is received	A	A
	2.14.2	No underrun detection with wrong data transmission	A	A
bxCAN	2.15.1	bxCAN time-triggered communication mode not supported	N	N
OTG_FS	2.16.1	Transmit data FIFO is corrupted when a write sequence to the FIFO is interrupted with accesses to certain OTG_FS registers	A	A
	2.16.2	Host packet transmission may hang when connecting through a hub to a low-speed device	N	N
	2.16.3	Data in RxFIFO is overwritten when all channels are disabled simultaneously	A	A
	2.16.4	OTG host blocks the receive channel when receiving IN packets and no TxFIFO is configured	A	A
	2.16.5	Host channel-halted interrupt not generated when the channel is disabled	A	A
	2.16.6	Wrong software-read OTG_FS_DCFG register values	A	A
OTG_HS	2.17.1	Transmit data FIFO is corrupted when a write sequence to the FIFO is interrupted with accesses to certain OTG_HS registers	A	A
	2.17.2	Host packet transmission may hang when connecting the full speed interface through a hub to a low-speed device	N	N
CEC	2.18.1	Transmission blocked when transmitted start bit is corrupted	P	P
	2.18.2	Missed CEC messages in normal receiving mode	A	A
	2.18.3	Unexpected TXERR flag during a message transmission	A	A

The following table gives a quick reference to the documentation errata.

**Table 4. Summary of device documentation errata**

Function	Section	Documentation erratum
TIM	2.7.2	TRGO and TRGO2 trigger output failure
FMPI2C	2.10.6	START bit is cleared upon setting ADDRCONF, not upon address match
	2.10.10	Inconsistent FMPI2C peripheral instance naming

## 2 Description of device errata

The following sections describe the errata of the applicable devices with Arm® core and provide workarounds if available. They are grouped by device functions.

*Note:* Arm is a registered trademark of Arm Limited (or its subsidiaries) in the US and/or elsewhere.

**arm**

### 2.1 Core

Reference manual and errata notice for the Arm® Cortex®-M4F core revision r0p1-v1 is available from <http://infocenter.arm.com>. Only applicable information from the Arm errata notice is replicated in this document.

#### 2.1.1 Interrupted loads to SP can cause erroneous behavior

This limitation is registered under Arm ID number 752770 and classified into “Category B”. Its impact to the device is minor.

##### Description

If an interrupt occurs during the data-phase of a single word load to the stack-pointer (SP/R13), erroneous behavior can occur. In all cases, returning from the interrupt will result in the load instruction being executed an additional time. For all instructions performing an update to the base register, the base register will be erroneously updated on each execution, resulting in the stack-pointer being loaded from an incorrect memory location.

The affected instructions that can result in the load transaction being repeated are:

- LDR SP, [Rn],#imm
- LDR SP, [Rn,#imm]!
- LDR SP, [Rn,#imm]
- LDR SP, [Rn]
- LDR SP, [Rn,Rm]

The affected instructions that can result in the stack-pointer being loaded from an incorrect memory address are:

- LDR SP,[Rn],#imm
- LDR SP,[Rn,#imm]!

As compilers do not generate these particular instructions, the limitation is only likely to occur with hand-written assembly code.

##### Workaround

Both issues may be worked around by replacing the direct load to the stack-pointer, with an intermediate load to a general-purpose register followed by a move to the stack-pointer.

#### 2.1.2 VDIV or VSQRT instructions might not complete correctly when very short ISRs are used

This limitation is registered under Arm ID number 776924 and classified into “Category B”. Its impact to the device is limited.

##### Description

The VDIV and VSQRT instructions take 14 cycles to execute. When an interrupt is taken a VDIV or VSQRT instruction is not terminated, and completes its execution while the interrupt stacking occurs. If lazy context save of floating point state is enabled then the automatic stacking of the floating point context does not occur until a floating point instruction is executed inside the interrupt service routine.

Lazy context save is enabled by default. When it is enabled, the minimum time for the first instruction in the interrupt service routine to start executing is 12 cycles. In certain timing conditions, and if there is only one or two instructions inside the interrupt service routine, then the VDIV or VSQRT instruction might not write its result to the register bank or to the FPSCR.

The failure occurs when the following condition is met:

1. The floating point unit is enabled
2. Lazy context saving is not disabled
3. A VDIV or VSQRT is executed
4. The destination register for the VDIV or VSQRT is one of s0 - s15
5. An interrupt occurs and is taken
6. The interrupt service routine being executed does not contain a floating point instruction
7. Within 14 cycles after the VDIV or VSQRT is executed, an interrupt return is executed

A minimum of 12 of these 14 cycles are utilized for the context state stacking, which leaves 2 cycles for instructions inside the interrupt service routine, or 2 wait states applied to the entire stacking sequence (which means that it is not a constant wait state for every access).

In general, this means that if the memory system inserts wait states for stack transactions (that is, external memory is used for stack data), then this erratum cannot be observed.

The effect of this erratum is that the VDIV or VSQRT instruction does not complete correctly and the register bank and FPSCR are not updated, which means that these registers hold incorrect, out of date, data.

### Workaround

A workaround is only required if the floating point unit is enabled. A workaround is not required if the stack is in external memory.

There are two possible workarounds:

- Disable lazy context save of floating point state by clearing LSPEN to 0 (bit 30 of the FPCCR at address 0xE000EF34).
- Ensure that every interrupt service routine contains more than 2 instructions in addition to the exception return instruction.

## 2.1.3 Store immediate overlapping exception return operation might vector to incorrect interrupt

This limitation is registered under Arm ID number 838869 and classified into "Category B (rare)". Its impact to the device is minor.

### Description

The core includes a write buffer that permits execution to continue while a store is waiting on the bus. Under specific timing conditions, during an exception return while this buffer is still in use by a store instruction, a late change in selection of the next interrupt to be taken might result in there being a mismatch between the interrupt acknowledged by the interrupt controller and the vector fetched by the processor.

The failure occurs when the following condition is met:

1. The handler for interrupt A is being executed.
2. Interrupt B, of the same or lower priority than interrupt A, is pending.
3. A store with immediate offset instruction is executed to a bufferable location.
  - STR/STRH/STRB <Rt>, [<Rn>,#imm]
  - STR/STRH/STRB <Rt>, [<Rn>,#imm]!
  - STR/STRH/STRB <Rt>, [<Rn>],#imm
4. Any number of additional data-processing instructions can be executed.
5. A BX instruction is executed that causes an exception return.
6. The store data has wait states applied to it such that the data is accepted at least two cycles after the BX is executed.
  - Minimally, this is two cycles if the store and the BX instruction have no additional instructions between them.
  - The number of wait states required to observe this erratum needs to be increased by the number of cycles between the store and the interrupt service routine exit instruction.
7. Before the bus accepts the buffered store data, another interrupt C is asserted which has the same or lower priority as A, but a greater priority than B.

Example:

The processor should execute interrupt handler C, and on completion of handler C should execute the handler for B. If the conditions above are met, then this erratum results in the processor erroneously clearing the pending state of interrupt C, and then executing the handler for B twice. The first time the handler for B is executed it will be at interrupt C's priority level. If interrupt C is pending by a level-based interrupt which is cleared by C's handler then interrupt C will be pending again once the handler for B has completed and the handler for C will be executed.

As the STM32 interrupt C is level based, it eventually becomes pending again and is subsequently handled.

### Workaround

For software not using the memory protection unit, this erratum can be worked around by setting DISDEFWBUF in the Auxiliary Control Register.

In all other cases, the erratum can be avoided by ensuring a DSB occurs between the store and the BX instruction. For exception handlers written in C, this can be achieved by inserting the appropriate set of intrinsics or inline assembly just before the end of the interrupt function, for example:

ARMCC:

```
...
__schedule_barrier();
__asm{DSB};
__schedule_barrier();
}
```

GCC:

```
...
__asm volatile ("dsb 0xf":::"memory");
}
```

## 2.2 System

### 2.2.1 Debugging Stop mode and SysTick timer

#### Description

If the SysTick timer interrupt is enabled during the Stop mode debug (DBG\_STOP bit set in the DBGMCU\_CR register), it wakes up the system from Stop mode.

#### Workaround

To debug the Stop mode, disable the SysTick timer interrupt.

### 2.2.2 Debugging Stop mode with WFE entry

#### Description

When the Stop debug mode is enabled (DBG\_STOP bit set in the DBGMCU\_CR register), the software debugging is allowed during Stop mode. However, if the application software uses the WFE instruction to enter Stop mode, after wake-up, some instructions may be missed if the WFE is followed by sequential instructions. This affects only Stop debug mode with WFE entry.

#### Workaround

To debug Stop mode with WFE entry, the WFE instruction must be inside a dedicated function with one instruction (NOP) between the execution of the WFE and the Bx LR. For example:

```
__asm void _WFE(void)
WFE
NOP
BX lr }
```

### 2.2.3 Debugging Sleep/Stop mode with WFE/WFI entry

#### Description

When the Sleep debug or Stop debug mode is enabled (DBG\_SLEEP bit or DBG\_STOP bit are set in the DBGMCU\_CR register), software debugging is allowed during Sleep or Stop mode. After wake-up, some unreachable instructions can be executed if the following conditions are met:

- The application software disables the Prefetch queue,
- the number of wait states configured for the flash memory interface is higher than zero, and
- the linker places the WFE or WFI instruction on a 4-byte aligned addresses (0x080xx xxx4).

#### Workaround

Apply one of the following measures:

- Add three NOPs after WFI/WFE instruction.
- Keep one AHB master active during Sleep (example keep DMA1 or DMA2 RCC clock enable bit set).
- Execute WFI/WFE instruction from routines inside the SRAM.

### 2.2.4 Wake-up sequence from Standby mode when using more than one wake-up source

#### Description

The various wake-up sources are logically OR-ed in front of the rising-edge detector that generates the wake-up flag (WUF). The WUF needs to be cleared before Standby mode entry, otherwise the MCU wakes up immediately. If one of the configured wake-up sources is kept high during the clearing of the WUF (by setting the CWUF bit), it may mask further wake-up events on the input of the edge detector. As a consequence, the MCU may not be able to wake up from Standby mode.

#### Workaround

To avoid this problem, apply the following sequence before entering Standby mode:

1. Disable all used wake-up sources.
2. Clear all related wake-up flags.
3. Reenable all used wake-up sources.
4. Enter Standby mode.

*Note: Be aware that, when applying this workaround, if one of the wake-up sources is still kept high, the MCU enters Standby mode but then it wakes up immediately and generates a power reset.*

### 2.2.5 Full JTAG configuration without NJTRST pin cannot be used

#### Description

When using the JTAG debug port in debug mode, the connection with the debugger is lost if the NJTRST pin (PB4) is used as a GPIO. Only the 4-wire JTAG port configuration is impacted.

#### Workaround

Use the SWD debug port instead of the full 4-wire JTAG port.

### 2.2.6 MPU attribute to RTC and IWDG registers incorrectly managed

#### Description

If the MPU is used and the nonbufferable attribute is set to the RTC or IWDG memory map region, the CPU access to the RTC or IWDG registers may be treated as bufferable, provided there is no APB prescaler configured (AHB/APB prescaler is equal to 1).



### Workaround

If the nonbufferable attribute is required for these registers, perform by software a read after the write to guaranty the completion of the write access.

## 2.2.7 Delay after an RCC peripheral clock enabling

### Description

A delay may be observed between an RCC peripheral clock enable and the effective peripheral enabling. It must be taken into account in order to manage the peripheral read/write from/to registers.

This delay depends on the peripheral mapping:

- If the peripheral is mapped on the AHB: the delay may be equal to two AHB cycles.
- If the peripheral is mapped on the APB: the delay may be equal to 1 + (AHB/APB prescaler) cycles.

### Workaround

Apply one of the following measures:

- Use the DSB instruction to stall the Arm® Cortex®-M4 CPU pipeline until the instruction has completed.
- Insert "n" NOPs between the RCC enable bit write and the peripheral register writes (n = 2 for AHB peripherals, n = 1 + AHB/APB prescaler for APB peripherals).
- Simply insert a dummy read operation from the corresponding register just after enabling the peripheral clock.

## 2.2.8 Internal noise impacting the ADC accuracy

### Description

An internal noise generated on V<sub>DD</sub> supplies and propagated internally may impact the ADC accuracy. This noise is always present whatever the power mode of the MCU (Run or Sleep).

### Workaround

Use the following sequence to adapt the accuracy level to the application requirements:

1. Configure the flash memory ART with prefetch OFF and data + instruction cache ON.
2. Use averaging and filtering algorithms on ADC output codes.

For more detailed workarounds, refer to the application note "*How to improve ADC accuracy when using STM32F2xx and STM32F4xx microcontrollers*" (AN4073).

## 2.2.9 Data cache might be corrupted during flash memory read-while-write operation

### Description

When a write operation to the internal flash memory is done, the data cache is updated to reflect the data update. If a read operation to the other memory bank occurs during the data cache update, the data cache content may be corrupted. In this case, subsequent read operations from the same address (cache hits) is corrupted.

This issue only occurs in dual bank mode when reading (data access or code execution) from one flash memory bank while writing to the other flash bank with data cache enabled.

### Workaround

When the application is performing data accesses in both Flash memory banks, the data cache must be disabled by resetting the DCEN bit in FLASH\_ACR register before performing any write operation to Flash memory. Before enabling the data cache again, the cache must be reset by setting and then resetting the DCRST bit in FLASH\_ACR register.

Example of code:

```
/* Disable data cache */
__HAL_FLASH_DATA_CACHE_DISABLE();
/* Set PG bit */
SET_BIT(FLASH->CR, FLASH_CR_PG);
/* Program the Flash word */
WriteFlash(Address, Data);
/* Reset data cache */
__HAL_FLASH_DATA_CACHE_RESET();
/* Enable data cache */
__HAL_FLASH_DATA_CACHE_ENABLE();
```

## 2.2.10 Possible delay in backup domain protection disabling/enabling after programming the DBP bit

### Description

Depending on the AHB/APB1 prescaler, a delay between DBP bit programming and the effective disabling/enabling of the backup domain protection can be observed and must be taken into account.

The higher the APB1 prescaler value, the higher the delay.

### Workaround

Apply one of the following measures:

- Insert a dummy read operation to the PWR\_CR register just after programming the DBP bit.
- Wait for the end of the operation (reset through the BDRST bit or write to the backup domain) via a polling loop on targeted registers.

## 2.2.11 PC13 signal transitions disturb LSE

### Description

On LQFP packages, PC13 toggling in input or output (for example when used for RTC\_AF1) may cause an incorrect LSE crystal oscillator clock frequency.

*Note: The external clock input (LSE bypass), and WLCSP and UFBGA package are not impacted by this limitation. Avoid toggling PC13 when LSE is used on LQFP packages.*

### Workaround

None.

## 2.3 FSMC

### 2.3.1 Dummy read cycles inserted when reading synchronous memories

#### Description

When performing a burst read access from a synchronous memory, two dummy read accesses are performed at the end of the burst cycle whatever the type of burst access.

The extra data values read are not used by the FSMC and there is no functional failure.

#### Workaround

None.

### 2.3.2 Wrong data read from a busy NAND memory

#### Description

When a read command is issued to the NAND memory, the R/B signal gets activated upon the de-assertion of the chip select. If a read transaction is pending, the NAND controller might not detect the R/B signal (connected to NWAIT) previously asserted and sample a wrong data. This problem occurs only when the MEMSET timing is configured to 0x00 or when ATTHOLD timing is configured to 0x00 or 0x01.

#### Workaround

Either configure MEMSET timing to a value greater than 0x00 or ATTHOLD timing to a value greater than 0x01.

### 2.3.3 Spurious clock stoppage with continuous clock feature enabled

#### Description

With the continuous clock feature enabled, the FSMC\_CLK clock may spuriously stop when:

- the FSMC\_CLK clock is divided by 2, and
- an FSMC bank set as 32-bit is accessed with a byte access.

division ratio set to 2, the FSMC\_CLK clock may spuriously stop upon an

*Note: With static memories, a spuriously stopped clock can be restarted by issuing a synchronous transaction or any asynchronous transaction different from a byte access on 32-bit data bus width.*

#### Workaround

With the continuous clock feature enabled, do not set the FSMC\_CLK clock division ratio to 2 when accessing 32-bit asynchronous memories with byte access.

### 2.3.4 Data read might be corrupted when the write FIFO is disabled

#### Description

When the write FIFO is disabled, the FIFO empty event is generated for every write access. During a write access, if a new read access occurs, the FMC grants the read access and waits till the FIFO gets empty. If another read access occurs in a very short window (one cycle of the FIFO empty event), the returned data are corrupted. This issue occurs only when the write FIFO is disabled (the WFDIS bit of the FSMC\_BCR1 register is set).

#### Workaround

Enable the write FIFO.

## 2.4 QUADSPI

### 2.4.1 Extra data written in the FIFO at the end of a read transfer

#### Description

When the following condition is met:

- QUADSPI is used in indirect mode,
  - QUADSPI clock is AHB/2 (PRESCALER = 0x01 in the QUADSPI\_CR),
  - QUADSPI is in quad mode (DMODE = 0b11 in the QUADSPI\_CCR),
  - QUADSPI is in DDR mode (DDRM = 0b1 in the QUADSPI\_CCR),
  - a data is read in the instant when the FIFO buffer gets full at the end of a read transfer,
- an extra data is unduly written in the FIFO buffer.

### Workaround

Apply one of the following measures:

- Read out the extra data until the BUSY flag goes low, then discard the extra data.
- After reading out all the expected received data, set the ABORT bit of the QUADSPI\_CR register to flush FIFO and keep the BUSY flag low. The last register configuration is kept.

## 2.4.2 First nibble of data not written after dummy phase

### Description

The first nibble of data to be written to the external flash memory is lost when the following condition is met:

- QUADSPI is used in indirect write mode.
- At least one dummy cycle is used.

### Workaround

Use alternate bytes instead of dummy phase to add latency between the address phase and the data phase. This works only if the number of dummy cycles to substitute corresponds to a multiple of eight bits of data.

Example:

- To substitute one dummy cycle, send one alternate byte (only possible in DDR mode with four data lines).
- To substitute two dummy cycles, send one alternate byte in SDR mode with four data lines.
- To substitute four dummy cycles, send two alternate bytes in SDR mode with four data lines, or one alternate byte in SDR mode with two data lines.
- To substitute eight dummy cycles, send one alternate byte in SDR mode with one data line.

## 2.4.3 Wrong data from memory-mapped read after an indirect mode operation

### Description

The first memory-mapped read in indirect mode can yield wrong data if the QUADSPI peripheral enters memory-mapped mode with bits ADDRESS[1:0] of the QUADSPI\_AR register both set.

### Workaround

Before entering memory-mapped mode, apply the following measure, depending on access mode:

- Indirect read mode: clear the QUADSPI\_AR register then issue an abort request to stop reading and to clear the BUSY bit.
- Indirect write mode: clear the QUADSPI\_AR register.

**Caution:** The QUADSPI\_DR register must not be written after clearing the QUADSPI\_AR register.

## 2.4.4 Memory-mapped read operations may fail when timeout counter is enabled

### Description

In memory-mapped mode with the timeout counter enabled (by setting the TCEN bit of the QUADSPI\_CR register), the QUADSPI peripheral may hang and memory-mapped read operation fail. This occurs if the timeout flag TOF is set at the same clock edge as a new memory-mapped read request.

### Workaround

Disable the timeout counter. To raise the chip select, perform an abort at the end of each memory-mapped read operation.

## 2.4.5 Memory-mapped access in indirect mode clearing QUADSPI\_AR register

### Description

Memory-mapped accesses to the QUADSPI peripheral operating in indirect mode unduly clear the QUADSPI\_AR register to 0x00.

### Workaround

Adopt one of the following measures:

- Avoid memory-mapped accesses to the QUADSPI peripheral operating in indirect mode.
- After each memory-mapped access to the QUADSPI operating in indirect mode, write the QUADSPI\_AR register with a desired value

## 2.5 ADC

### 2.5.1 ADC sequencer modification during conversion

#### Description

When a software start-of-conversion is used as an ADC trigger, and if the ADC\_SQRx or ADC\_JSQRx register is modified during the conversion, the current conversion is reset and the ADC does not automatically restart the new conversion sequence. The hardware start-of-conversion trigger is not impacted and the ADC automatically restarts the new sequence when the next hardware trigger occurs.

#### Workaround

When a software start-of-conversion is used, apply the following sequence:

1. First set the SWSART bit in the ADC\_CR2 register.
2. Then restart the new conversion sequence.

## 2.6 DAC

### 2.6.1 DMA request not automatically cleared by clearing DMAEN

#### Description

Upon an attempt to stop a DMA-to-DAC transfer, the DMA request is not automatically cleared by clearing the DAC channel bit of the DAC\_CR register (DMAEN) or by disabling the DAC clock.

If the application stops the DAC operation while the DMA request is pending, the request remains pending while the DAC is reinitialized and restarted, with the risk that a spurious DMA request is serviced as soon as the DAC is enabled again.

#### Workaround

Apply the following sequence to stop the current DMA-to-DAC transfer and restart the DAC:

1. Check if DMAUDR bit is set in DAC\_CR.
2. Clear the DAC channel DMAEN bit.
3. Disable the DAC clock.
4. Reconfigure the DAC, DMA and the triggers.
5. Restart the application.

## 2.6.2 DMA underrun flag not set when an internal trigger is detected on the clock cycle of the DMA request acknowledge

### Description

When the DAC channel operates in DMA mode (DMAEN of DAC\_CR register set), the DMA channel underrun flag (DMAUDR of DAC\_SR register) fails to rise upon an internal trigger detection if that detection occurs during the same clock cycle as a DMA request acknowledge. As a result, the user application is not informed that an underrun error occurred.

This issue occurs when software and hardware triggers are used concurrently to trigger DMA transfers.

### Workaround

None.

## 2.7 TIM

### 2.7.1 PWM re-enabled in automatic output enable mode despite of system break

#### Description

In automatic output enable mode (AOE bit set in TIMx\_BDTR register), the break input can be used to do a cycle-by-cycle PWM control for a current mode regulation. A break signal (typically a comparator with a current threshold ) disables the PWM output(s) and the PWM is re-armed on the next counter period.

However, a system break (typically coming from the CSS Clock security System) is supposed to stop definitively the PWM to avoid abnormal operation (for example with PWM frequency deviation).

In the current implementation, the timer system break input is not latched. As a consequence, a system break indeed disables the PWM output(s) when it occurs, but PWM output(s) is (are) re-armed on the following counter period.

#### Workaround

Preferably, implement control loops with the output clear enable function (OCxCE bit in the TIMx\_CCMR1/CCMR2 register), leaving the use of break circuitry solely for internal and/or external fault protection (AOE bit reset).

### 2.7.2 TRGO and TRGO2 trigger output failure

#### Description

Some reference manual revisions may omit the following information.

The timers can be linked using ITRx inputs and TRGOx outputs. Additionally, the TRGOx outputs can be used as triggers for other peripherals (for example ADC). Since this circuitry is based on pulse generation, care must be taken when initializing master and slave peripherals or when using different master/slave clock frequencies:

- If the master timer generates a trigger output pulse on TRGOx prior to have the destination peripheral clock enabled, the triggering system may fail.
- If the frequency of the destination peripheral is modified on-the-fly (clock prescaler modification), the triggering system may fail.

As a conclusion, the clock of the slave timer or slave peripheral must be enabled prior to receiving events from the master timer, and must not be changed on-the-fly while triggers are being received from the master timer.

This is a documentation issue rather than a product limitation.

#### Workaround

No application workaround is required or applicable as long as the application handles the clock as indicated.

### 2.7.3 Consecutive compare event missed in specific conditions

#### Description

Every match of the counter (CNT) value with the compare register (CCR) value is expected to trigger a compare event. However, if such matches occur in two consecutive counter clock cycles (as consequence of the CCR value change between the two cycles), the second compare event is missed for the following CCR value changes:

- in edge-aligned mode, from ARR to 0:
  - first compare event: CNT = CCR = ARR
  - second (missed) compare event: CNT = CCR = 0
- in center-aligned mode while up-counting, from ARR-1 to ARR (possibly a new ARR value if the period is also changed) at the crest (that is, when TIMx\_RCR = 0):
  - first compare event: CNT = CCR = (ARR-1)
  - second (missed) compare event: CNT = CCR = ARR
- in center-aligned mode while down-counting, from 1 to 0 at the valley (that is, when TIMx\_RCR = 0):
  - first compare event: CNT = CCR = 1
  - second (missed) compare event: CNT = CCR = 0

This typically corresponds to an abrupt change of compare value aiming at creating a timer clock single-cycle-wide pulse in toggle mode.

As a consequence:

- In toggle mode, the output only toggles once per counter period (squared waveform), whereas it is expected to toggle twice within two consecutive counter cycles (and so exhibit a short pulse per counter period).
- In center mode, the compare interrupt flag does not rise and the interrupt is not generated.

*Note:* The timer output operates as expected in modes other than the toggle mode.

#### Workaround

None.

### 2.7.4 Output compare clear not working with external counter reset

#### Description

The output compare clear event (ocref\_clr) is not correctly generated when the timer is configured in the following slave modes: Reset mode, Combined reset + trigger mode, and Combined gated + reset mode.

The PWM output remains inactive during one extra PWM cycle if the following sequence occurs:

1. The output is cleared by the ocref\_clr event.
2. The timer reset occurs before the programmed compare event.

#### Workaround

Apply one of the following measures:

- Use BKIN (or BKIN2 if available) input for clearing the output, selecting the Automatic output enable mode (AOE = 1).
- Mask the timer reset during the PWM ON time to prevent it from occurring before the compare event (for example with a spare timer compare channel open-drain output connected with the reset signal, pulling the timer reset line down).

## 2.8 IWDG

### 2.8.1 RVU flag not reset in Stop

#### Description

Successful write to the IWDG\_RLR register raises the RVU flag and prevents further write accesses to the register until the RVU flag is automatically cleared by hardware. However, if the device enters Stop mode while the RVU flag is set, the hardware never clears that flag, and writing to the IWDG\_RLR register is no longer possible.

#### Workaround

Ensure that the RVU flag is cleared before entering Stop mode.

### 2.8.2 PVU flag not reset in Stop

#### Description

Successful write to the IWDG\_PR register raises the PVU flag and prevents further write accesses to the register until the PVU flag is automatically cleared by hardware. However, if the device enters Stop mode while the PVU flag is set, the hardware never clears that flag, and writing to the IWDG\_PR register is no longer possible.

#### Workaround

Ensure that the PVU flag is cleared before entering Stop mode.

### 2.8.3 RVU flag not cleared at low APB clock frequency

#### Description

Successful write to the IWDG\_RLR register raises the RVU flag and prevents further write accesses to the register until the RVU flag is automatically cleared by hardware. However, at APB clock frequency lower than twice the IWDG clock frequency, the hardware never clears that flag, and writing to the IWDG\_RLR register is no longer possible.

#### Workaround

Set the APB clock frequency higher than twice the IWDG clock frequency.

### 2.8.4 PVU flag not cleared at low APB clock frequency

#### Description

Successful write to the IWDG\_PR register raises the PVU flag and prevents further write accesses to the register until the PVU flag is automatically cleared by hardware. However, at APB clock frequency lower than twice the IWDG clock frequency, the hardware never clears that flag, and writing to the IWDG\_PR register is no longer possible.

#### Workaround

Set the APB clock frequency higher than twice the IWDG clock frequency.

## 2.9 RTC

### 2.9.1 Spurious tamper detection when disabling the tamper channel

#### Description

If the tamper detection is configured for detecting on the falling edge event (TAMPFLT = 00 and TAMPxTRG = 1) and if the tamper event detection is disabled when the tamper pin is at high level, a false tamper event is detected.



## Workaround

None.

## 2.9.2 RTC calendar registers are not locked properly

### Description

When reading the calendar registers with BYPSHAD = 0, the RTC\_TR and RTC\_DR registers may not be locked after reading the RTC\_SSR register. This happens if the read operation is initiated one APB clock period before the shadow registers are updated. This can result in a non-consistency of the three registers. Similarly, the RTC\_DR register can be updated after reading the RTC\_TR register instead of being locked.

### Workaround

Apply one of the following measures:

- Use BYPSHAD = 1 mode (bypass shadow registers), or
- If BYPSHAD = 0, read SSR again after reading SSR/TR/DR to confirm that SSR is still the same, otherwise read the values again.

## 2.9.3 RTC interrupt can be masked by another RTC interrupt

### Description

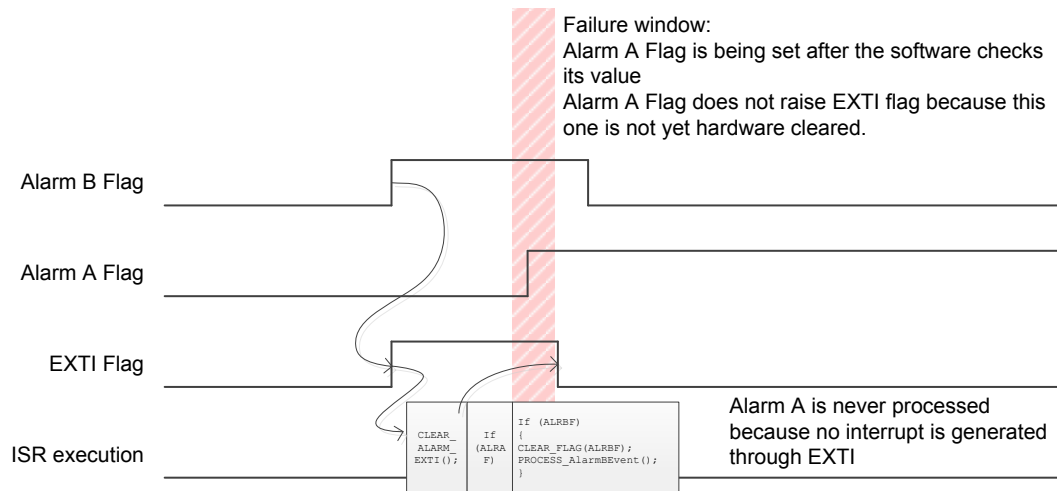
One RTC interrupt request can mask another RTC interrupt request if they share the same EXTI configurable line. For example, interrupt requests from Alarm A and Alarm B or those from tamper and timestamp events are OR-ed to the same EXTI line (refer to the *EXTI line connections* table in the *Extended interrupt and event controller (EXTI)* section of the reference manual).

The following code example and figure illustrate the failure mechanism: The Alarm A event is lost (fails to generate interrupt) as it occurs in the failure window, that is, after checking the Alarm A event flag but before the effective clear of the EXTI interrupt flag by hardware. The effective clear of the EXTI interrupt flag is delayed with respect to the software instruction to clear it.

Alarm interrupt service routine:

```
void RTC_Alarm_IRQHandler(void)
{
    CLEAR_ALARM_EXTI(); /* Clear the EXTI line flag for RTC alarms*/
    If(ALRAF) /* Check if Alarm A triggered ISR */
    {
        CLEAR_FLAG(ALRAF); /* Clear the Alarm A interrupt pending bit */
        PROCESS_AlarmAEvent(); /* Process Alarm A event */
    }
    If(ALRBF) /* Check if Alarm B triggered ISR */
    {
        CLEAR_FLAG(ALRBF); /* Clear the Alarm B interrupt pending bit */
        PROCESS_AlarmBEvent(); /* Process Alarm B event */
    }
}
```

Figure 1. Masked RTC interrupt



DT4747V1

### Workaround

In the interrupt service routine, apply three consecutive event flag checks - source one, source two, and source one again, as in the following code example:

```

void RTC_Alarm_IRQHandler(void)
{
    CLEAR_ALARM_EXTI(); /* Clear the EXTI's line Flag for RTC Alarm */
    If(ALRAF) /* Check if AlarmA triggered ISR */
    {
        CLEAR_FLAG(ALRAF); /* Clear the AlarmA interrupt pending bit */
        PROCESS_AlarmAEvent(); /* Process AlarmA Event */
    }
    If(ALRBF) /* Check if AlarmB triggered ISR */
    {
        CLEAR_FLAG(ALRBF); /* Clear the AlarmB interrupt pending bit */
        PROCESS_AlarmBEvent(); /* Process AlarmB Event */
    }
    If(ALRAF) /* Check if AlarmA triggered ISR */
    {
        CLEAR_FLAG(ALRAF); /* Clear the AlarmA interrupt pending bit */
        PROCESS_AlarmAEvent(); /* Process AlarmA Event */
    }
}
    
```

## 2.9.4

### Calendar initialization may fail in case of consecutive INIT mode entry

#### Description

If the INIT bit of the RTC\_ISR register is set between one and two RTCCLK cycles after being cleared, the INITF flag is set immediately instead of waiting for synchronization delay (which should be between one and two RTCCLK cycles), and the initialization of registers may fail.

Depending on the INIT bit clearing and setting instants versus the RTCCLK edges, it can happen that, after being immediately set, the INITF flag is cleared during one RTCCLK period then set again. As writes to calendar registers are ignored when INITF is low, a write during this critical period might result in the corruption of one or more calendar registers.

#### Workaround

After exiting the initialization mode, clear the BYPSHAD bit (if set) then wait for RSF to rise, before entering the initialization mode again.

**Note:** *It is recommended to write all registers in a single initialization session to avoid accumulating synchronization delays.*

## 2.9.5 Alarm flag may be repeatedly set when the core is stopped in debug

### Description

When the core is stopped in debug mode, the clock is supplied to subsecond RTC alarm downcounter even when the device is configured to stop the RTC in debug.

As a consequence, when the subsecond counter is used for alarm condition (the MASKSS[3:0] bitfield of the RTC\_ALRMASSR and/or RTC\_ALRMBSSR register set to a non-zero value) and the alarm condition is met just before entering a breakpoint or printf, the ALRAF and/or ALRBF flag of the RTC\_SR register is repeatedly set by hardware during the breakpoint or printf, which makes any attempt to clear the flag(s) ineffective.

### Workaround

None.

## 2.9.6 Detection of a tamper event occurring before enabling the tamper detection is not supported in edge detection mode

### Description

When the tamper detection is enabled in edge detection mode (TAMPFLT = 00):

- When TAMPxTRG = 0 (rising edge detection): if the tamper input is already high before enabling the tamper detection, the tamper event may or may not be detected when enabling the tamper detection. The probability to detect it increases with the APB frequency.
- When TAMPxTRG = 1 (falling edge detection): if the tamper input is already low before enabling the tamper detection, the tamper event is not detected when enabling the tamper detection.

### Workaround

Check the I/O state by software in the GPIO registers, just after enabling the tamper detection and before writing sensitive values in the backup registers. This ensures that no active edge occurred before enabling the tamper event detection.

## 2.10 FMPI2C

### 2.10.1 10-bit master mode: new transfer cannot be launched if first part of the address is not acknowledged by the slave

#### Description

An I<sup>2</sup>C-bus master generates STOP condition upon non-acknowledge of I<sup>2</sup>C address that it sends. This applies to 7-bit address as well as to each byte of 10-bit address.

When the MCU set as I<sup>2</sup>C-bus master transmits a 10-bit address of which the first byte (5-bit header + 2 MSBs of the address + direction bit) is not acknowledged, the MCU duly generates STOP condition but it then cannot start any new I<sup>2</sup>C-bus transfer. In this spurious state, the NACKF flag of the FMPI2C\_ISR register and the START bit of the FMPI2C\_CR2 register are both set, while the START bit should normally be cleared.

#### Workaround

In 10-bit-address master mode, if both NACKF flag and START bit get simultaneously set, proceed as follows:

1. Wait for the STOP condition detection (STOPF = 1 in FMPI2C\_ISR register).
2. Disable the FMPI2C peripheral.
3. Wait for a minimum of three APB cycles.
4. Enable the FMPI2C peripheral again.

### 2.10.2 Wrong data sampling when data setup time ( $t_{SU,DAT}$ ) is shorter than one FMPI2C kernel clock period

#### Description

The I<sup>2</sup>C-bus specification and user manual specify a minimum data setup time ( $t_{SU,DAT}$ ) as:

- 250 ns in Standard mode
- 100 ns in Fast mode
- 50 ns in Fast mode Plus

The device does not correctly sample the I<sup>2</sup>C-bus SDA line when  $t_{SU,DAT}$  is smaller than one FMPI2C kernel clock (I<sup>2</sup>C-bus peripheral clock) period: the previous SDA value is sampled instead of the current one. This can result in a wrong receipt of slave address, data byte, or acknowledge bit.

#### Workaround

Increase the FMPI2C kernel clock frequency to get FMPI2C kernel clock period within the transmitter minimum data setup time. Alternatively, increase transmitter's minimum data setup time. If the transmitter setup time minimum value corresponds to the minimum value provided in the I<sup>2</sup>C-bus standard, the minimum FMPI2CCLK frequencies are as follows:

- In Standard mode, if the transmitter minimum setup time is 250 ns, the FMPI2CCLK frequency must be at least 4 MHz.
- In Fast mode, if the transmitter minimum setup time is 100 ns, the FMPI2CCLK frequency must be at least 10 MHz.
- In Fast-mode Plus, if the transmitter minimum setup time is 50 ns, the FMPI2CCLK frequency must be at least 20 MHz.

### 2.10.3 Spurious bus error detection in master mode

#### Description

In master mode, a bus error can be detected spuriously, with the consequence of setting the BERR flag of the FMPI2C\_SR register and generating bus error interrupt if such interrupt is enabled. Detection of bus error has no effect on the I<sup>2</sup>C-bus transfer in master mode and any such transfer continues normally.

#### Workaround

If a bus error interrupt is generated in master mode, the BERR flag must be cleared by software. No other action is required and the ongoing transfer can be handled normally.

### 2.10.4 Last-received byte loss in reload mode

#### Description

If in master receiver mode or slave receive mode with SBC = 1 the following conditions are all met:

- I<sup>2</sup>C-bus stretching is enabled (NOSTRETCH = 0)
- RELOAD bit of the FMPI2C\_CR2 register is set
- NBYTES bitfield of the FMPI2C\_CR2 register is set to N greater than 1
- byte N is received on the I<sup>2</sup>C-bus, raising the TCR flag
- N - 1 byte is not yet read out from the data register at the instant TCR is raised,

then the SCL line is pulled low (I<sup>2</sup>C-bus clock stretching) and the transfer of the byte N from the shift register to the data register inhibited until the byte N-1 is read and NBYTES bitfield reloaded with a new value, the latter of which also clears the TCR flag. As a consequence, the software cannot get the byte N and use its content before setting the new value into the NBYTES field.

For FMPI2C instances with independent clock, the last-received data is definitively lost (never transferred from the shift register to the data register) if the data N - 1 is read within four APB clock cycles preceding the receipt of the last data bit of byte N and thus the TCR flag raising. Refer to the product reference manual or datasheet for the FMPI2C implementation table.

### Workaround

- In master mode or in slave mode with SBC = 1, use the reload mode with NBYTES = 1.
- In master receiver mode, if the number of bytes to transfer is greater than 255, do not use the reload mode. Instead, split the transfer into sections not exceeding 255 bytes and separate them with repeated START conditions.
- Make sure, for example through the use of DMA, that the byte N - 1 is always read before the TCR flag is raised. Specifically for FMPI2C instances with independent clock, make sure that it is always read earlier than four APB clock cycles before the receipt of the last data bit of byte N and thus the TCR flag raising.

The last workaround in the list must be evaluated carefully for each application as the timing depends on factors such as the bus speed, interrupt management, software processing latencies, and DMA channel priority.

## 2.10.5 Spurious master transfer upon own slave address match

### Description

When the device is configured to operate at the same time as master and slave (in a multi-master I<sup>2</sup>C-bus application), a spurious master transfer may occur under the following condition:

- Another master on the bus is in process of sending the slave address of the device (the bus is busy).
- The device initiates a master transfer by bit set before the slave address match event (the ADDR flag set in the FMPI2C\_ISR register) occurs.
- After the ADDR flag is set:
  - the device does not write FMPI2C\_CR2 before clearing the ADDR flag, or
  - the device writes FMPI2C\_CR2 earlier than three FMPI2C kernel clock cycles before clearing the ADDR flag

In these circumstances, even though the START bit is automatically cleared by the circuitry handling the ADDR flag, the device spuriously proceeds to the master transfer as soon as the bus becomes free. The transfer configuration depends on the content of the FMPI2C\_CR2 register when the master transfer starts. Moreover, if the FMPI2C\_CR2 is written less than three kernel clocks before the ADDR flag is cleared, the FMPI2C peripheral may fall into an unpredictable state.

### Workaround

Upon the address match event (ADDR flag set), apply the following sequence.

Normal mode (SBC = 0):

1. Set the ADDRCONF bit.
2. Before Stop condition occurs on the bus, write FMPI2C\_CR2 with the START bit low.

Slave byte control mode (SBC = 1):

1. Write FMPI2C\_CR2 with the slave transfer configuration and the START bit low.
2. Wait for longer than three FMPI2C kernel clock cycles.
3. Set the ADDRCONF bit.
4. Before Stop condition occurs on the bus, write FMPI2C\_CR2 again with its current value.

The time for the software application to write the FMPI2C\_CR2 register before the Stop condition is limited, as the clock stretching (if enabled), is aborted when clearing the ADDR flag.

Polling the BUSY flag before requesting the master transfer is not a reliable workaround as the bus may become busy between the BUSY flag check and the write into the FMPI2C\_CR2 register with the START bit set.

## 2.10.6 START bit is cleared upon setting ADDRCONF, not upon address match

### Description

Some reference manual revisions may state that the START bit of the FMPI2C\_CR2 register is cleared upon slave address match event.

Instead, the START bit is cleared upon setting, by software, the ADDRCONF bit of the FMPI2C\_ICR register, which does not guarantee the abort of master transfer request when the device is being addressed as slave. This product limitation and its workaround are the subject of a separate erratum.

### Workaround

No application workaround is required for this description inaccuracy issue.

## 2.10.7 OVR flag not set in underrun condition

### Description

In slave transmission with clock stretching disabled (NOSTRETCH = 1 in the FMPI2C\_CR1 register), an underrun condition occurs if the current byte transmission is completed on the I<sup>2</sup>C bus, and the next data is not yet written in the TXDATA[7:0] bitfield. In this condition, the device is expected to set the OVR flag of the FMPI2C\_ISR register and send 0xFF on the bus.

However, if the FMPI2C\_TXDR is written within the interval between two FMPI2C kernel clock cycles before and three APB clock cycles after the start of the next data transmission, the OVR flag is not set, although the transmitted value is 0xFF.

### Workaround

None.

## 2.10.8 Transmission stalled after first byte transfer

### Description

When the first byte to transmit is not prepared in the TXDATA register, two bytes are required successively, through TXIS status flag setting or through a DMA request. If the first of the two bytes is written in the FMPI2C\_TXDR register in less than two FMPI2C kernel clock cycles after the TXIS/DMA request, and the ratio between APB clock and FMPI2C kernel clock frequencies is between 1.5 and 3, the second byte written in the FMPI2C\_TXDR is not internally detected. This causes a state in which the FMPI2C peripheral is stalled in master mode or in slave mode, with clock stretching enabled (NOSTRETCH = 0). This state can only be released by disabling the peripheral (PE = 0) or by resetting it.

### Workaround

Apply one of the following measures:

- Write the first data in FMPI2C\_TXDR before the transmission starts.
- Set the APB clock frequency so that its ratio with respect to the FMPI2C kernel clock frequency is lower than 1.5 or higher than 3.

## 2.10.9 SDA held low upon SMBus timeout expiry in slave mode

### Description

For the slave mode, the SMBus specification defines  $t_{\text{TIMEOUT}}$  (detect clock low timeout) and  $t_{\text{LOW:SEXT}}$  (cumulative clock low extend time) timeouts. When one of them expires while the FMPI2C peripheral in slave mode drives SDA low to acknowledge either its address or a data transmitted by the master, the device is expected to report such an expiry and release the SDA line.

However, although the device duly reports the timeout expiry, it fails to release SDA. This stalls the I<sup>2</sup>C bus and prevents the master from generating RESTART or STOP condition.

### Workaround

When a timeout is reported in slave mode (TIMEOUT bit of the FMPI2C\_ISR register is set), apply this sequence:

1. Wait until the frame is expected to end.
2. Read the STOPF bit of the FMPI2C\_ISR register. If it is low, reset the FMPI2C kernel by clearing the PE bit of the FMPI2C\_CR1 register.
3. Wait for at least three APB clock cycles before enabling again the FMPI2C peripheral.

## 2.10.10 Inconsistent FMPI2C peripheral instance naming

### Description

In the silicon product documentation (reference manual, data sheet, and application notes), and in the STM32CubeF4 and STM32CubeMX ecosystem tools and documentation, *I2C4* and *FMPI2C1* refer to the same peripheral instance. This also impacts the associated signal and pin names.

This is a documentation erratum, not a device limitation.

### Workaround

No application workaround is required. Read all occurrences of *I2C4* as *FMPI2C1*.

## 2.11 I2C

### 2.11.1 Spurious bus error detection in master mode

#### Description

In master mode, a bus error can be detected spuriously, with the consequence of setting the BERR flag of the I2C\_SR register and generating bus error interrupt if such interrupt is enabled. Detection of bus error has no effect on the I<sup>2</sup>C-bus transfer in master mode and any such transfer continues normally.

#### Workaround

If a bus error interrupt is generated in master mode, the BERR flag must be cleared by software. No other action is required and the ongoing transfer can be handled normally.

### 2.11.2 SMBus standard not fully supported

#### Description

The I2C peripheral is not fully compliant with the SMBus v2.0 standard since it does not support the capability to NACK an invalid byte/command.

#### Workaround

A higher-level mechanism must be used to verify that a write operation is being performed correctly at the target device, such as:

- the SMBAL pin if it is supported by the host
- the alert response address (ARA) protocol
- the host-notify protocol

### 2.11.3 Start cannot be generated after a misplaced Stop

#### Description

If a master generates a misplaced Stop on the bus (bus error) while the microcontroller I2C peripheral attempts to switch to Master mode by setting the START bit, the Start condition is not properly generated.

#### Workaround

In the I<sup>2</sup>C standard, it is allowed to send a Stop only at the end of the full byte (8 bits + acknowledge), so this scenario is not allowed. Other derived protocols such as CBUS allow it, but they are not supported by the I2C peripheral.

A software workaround consists in asserting the software reset using the SWRST bit of the I2C\_CR1 control register.

#### 2.11.4 Mismatch on the “Setup time for a repeated Start condition” timing parameter

##### Description

In case of repeated Start, the “Setup time for a repeated Start condition” (named  $T_{su;sta}$  in the I<sup>2</sup>C specification) can be slightly violated when the I<sup>2</sup>C operates in Master standard mode at a frequency between 88 kHz and 100 kHz.

The issue can occur only in the following configuration:

- In Master mode
- In Standard mode at a frequency between 88 kHz and 100 kHz (no limitation in Fast mode)
- SCL rise time:
  - If the slave does not stretch the clock and the SCL rise time is more than 300 ns (if the SCL rise time is less than 300 ns, the issue does not occur).
  - If the slave stretches the clock.

The setup time can be violated independently of the APB peripheral frequency.

##### Workaround

Reduce the frequency down to 88 kHz or use the I<sup>2</sup>C Fast mode, if it is supported by the slave.

#### 2.11.5 Data valid time ( $t_{VD;DAT}$ ) violated without the OVR flag being set

##### Description

The data valid time ( $t_{VD;DAT}$ ,  $t_{VD;ACK}$ ) described by the I<sup>2</sup>C standard can be violated (as well as the maximum data hold time of the current data ( $t_{HD;DAT}$ )) under the conditions described below. This violation cannot be detected because the OVR flag is not set (no transmit buffer underrun is detected).

This limitation can occur only under the following conditions:

- in Slave transmit mode
- with clock stretching disabled (NOSTRETCH = 1)
- if the software is late to write to the DR data register, but not late enough to set the OVR flag (the data register is written before)

##### Workaround

If the master device allows it, use the clock stretching mechanism by clearing the bit NOSTRETCH of the I2C\_CR1 register.

If the master device does not allow it, ensure that the software is fast enough when polling the TXE or ADDR flag to immediately write to the DR data register. For instance, use an interrupt on the TXE or ADDR flag and boost its priority to the higher level.

#### 2.11.6 Both SDA and SCL maximum rise times ( $t_r$ ) violated when the VDD\_I2C bus voltage is higher than $((V_{DD} + 0.3) / 0.7)$ V

##### Description

When an external legacy I<sup>2</sup>C bus voltage ( $V_{DD\_I2C}$ ) is set to 5 V while the MCU is powered from  $V_{DD}$ , the internal 5-Volt tolerant circuitry is activated as soon the input voltage ( $V_{IN}$ ) reaches the  $V_{DD} +$  diode threshold level. An additional internal large capacitance then prevents the external pull-up resistor ( $R_P$ ) from rising the SDA and SCL signals within the maximum timing ( $t_r$ ), which is 300 ns in Fast mode and 1000 ns in Standard mode.

The rise time ( $t_r$ ) is measured from  $V_{IL}$  and  $V_{IH}$  with levels set at  $0.3 V_{DD\_I2C}$  and  $0.7 V_{DD\_I2C}$ .

##### Workaround

The external  $V_{DD\_I2C}$  bus voltage must be limited to a maximum value of  $((V_{DD} + 0.3) / 0.7)$  V. As a result, when the MCU is powered from  $V_{DD} = 3.3$  V,  $V_{DD\_I2C}$  must not exceed 5.14 V to be compliant with I<sup>2</sup>C specifications.



## 2.12 USART

### 2.12.1 Idle frame is not detected if the receiver clock speed is deviated

#### Description

If the USART receives an idle frame followed by a character, and the clock of the transmitter device is faster than the USART receiver clock, the USART receive signal falls too early when receiving the character start bit, with the result that the idle frame is not detected (the IDLE flag is not set).

#### Workaround

None.

### 2.12.2 In full-duplex mode, the Parity Error (PE) flag can be cleared by writing to the data register

#### Description

In full-duplex mode, when the Parity Error flag is set by the receiver at the end of a reception, it may be cleared while transmitting by reading the USART\_SR register to check the TXE or TC flags and writing data to the data register. Consequently, the software receiver can read the PE flag as '0' even if a parity error occurred.

#### Workaround

The Parity Error flag should be checked after the end of reception and before transmission.

### 2.12.3 Parity Error (PE) flag is not set when receiving in Mute mode using address mark detection

#### Description

If the USART receiver is in Mute mode, and is configured to exit from Mute mode using the address mark detection, when the USART receiver recognizes a valid address with a parity error, it exits from Mute mode without setting the Parity Error flag.

#### Workaround

None.

### 2.12.4 Break frame is transmitted regardless of CTS input line status

#### Description

When the CTS hardware flow control is enabled (CTSE = 1) and the send break bit (SBK) is set, the transmitter sends a break frame at the end of the current transmission regardless of CTS input line status. Consequently, if an external receiver device is not ready to accept a frame, the transmitted break frame is lost.

#### Workaround

None.

### 2.12.5 RTS signal abnormally driven low after a protocol violation

#### Description

When RTS hardware flow control is enabled, the RTS signal goes high when data is received. If this data was not read and new data is sent to the USART (protocol violation), the RTS signal goes back to low level at the end of this new data.

Consequently, the sender gets the wrong information that the USART is ready to receive further data.

On the USART side, an overrun is detected, which indicates that data has been lost.

### Workaround

A workaround is required only if the other USART device violates the communication protocol, which is not the case in most applications.

Two workarounds can be used:

- After data reception and before reading the data in the data register, the software takes over the control of the RTS signal as a GPIO, and holds it high as long as needed. If the USART device is not ready, the software holds the RTS pin high, and releases it when the device is ready to receive new data.
- Make sure the time required by the software to read the received data is always lower than the duration of the second data reception. For example, this can be ensured by handling all the receptions in DMA mode.

## 2.12.6 Start bit detected too soon when sampling for NACK signal from the smartcard

### Description

According to ISO/IEC 7816-3 standard, when a character parity error is detected, the receiver shall transmit a NACK error signal  $10.5 \pm 0.2$  ETUs after the character START bit falling edge. In this case, the transmitter is able to detect correctly the NACK signal until  $11 \pm 0.2$  ETUs after the character START bit falling edge. In Smartcard mode, the USART peripheral monitors the NACK signal during the receiver time frame ( $10.5 \pm 0.2$  ETUs), while it should wait for it during the transmitter one ( $11 \pm 0.2$  ETUs). In real cases, this would not be a problem as the card itself needs to respect a 10.7 ETU period when sending the NACK signal. However, this may be an issue to undertake a certification.

### Workaround

None.

## 2.12.7 Break request can prevent the transmission complete flag (TC) from being set

### Description

After the end of transmission of a data (D1), the transmission complete (TC) flag is not set if the following conditions are met:

- CTS hardware flow control is enabled,
- D1 is being transmitted,
- a break transfer is requested before the end of D1 transfer,
- CTS is de-asserted before the end of D1 data transfer.

### Workaround

If the application needs to detect the end of a data transfer, check that the TC flag is set, and issue a break request.

## 2.12.8 Guard time not respected when data are sent on TXE events

### Description

In Smartcard mode, when sending a data on TXE event, the programmed guard time is not respected, that is the data written in the data register is transferred to the bus without waiting the completion of the guard-time duration corresponding to the previous transmitted data.

### Workaround

Since in Smartcard mode the TC flag is set at the end of the guard time duration, wait until TC is set, then write the data.

## 2.12.9 RTS is active while RE or UE = 0

### Description

The RTS line is driven low as soon as the RTSE bit is set, even if the USART is disabled (UE = 0) or if the receiver is disabled (RE = 0) that is not ready to receive data.

### Workaround

After setting the UE and RE bits, configure the I/O used for RTS as an alternate function.

## 2.13 SPI/I2S

### 2.13.1 BSY bit may stay high when SPI is disabled

#### Description

The BSY flag may remain high upon disabling the SPI while operating in:

- master transmit mode and the TXE flag is low (data register full).
- master receive-only mode (simplex receive or half-duplex bidirectional receive phase) and an SCK strobing edge has not occurred since the transition of the RXNE flag from low to high.
- slave mode and NSS signal is removed during the communication.

#### Workaround

When the SPI operates in:

- master transmit mode, disable the SPI when TXE = 1 and BSY = 0.
- master receive-only mode, ignore the BSY flag.
- slave mode, do not remove the NSS signal during the communication.

### 2.13.2 Anticipated communication upon SPI transit from slave receiver to master

#### Description

Regardless of the master mode configured, the communication clock starts upon setting the MSTR bit even though the SPI is disabled, if transiting from receive-only (RXONLY = 1) or half-duplex receive (BIDIMODE = 1 and BIDIOE = 0) slave mode to master mode.

#### Workaround

Apply one of the following measures:

- Before transiting to master mode, hardware-reset the SPI via the reset controller.
- Set the MSTR and SPE bits of the SPI configuration register simultaneously, which forces the immediate start of the communication clock. In transmitter configuration, load the data register in advance with the data to send.

### 2.13.3 I<sup>2</sup>S slave in PCM short pulse mode sensitive to timing between WS and CK

#### Description

When the device is configured in I<sup>2</sup>S slave PCM short frame mode (I2SMOD = 1, I2SCFG[1:0] = 00 or 01, I2SSTD[1:0] = 11, PCMSYNC = 0), with the asynchronous start disabled (ASTREN = 0), then if the master does not respect the WS hold time versus clock, the data transmitted and received by the device get desynchronized (shifted by one bit). This results in discarding two frames instead of one, irrespectively of the clock polarity.

#### Workaround

Use legacy mode (ASTERN = 1), while ensuring a perfect synchronization between the master and the slave.

## 2.13.4 Wrong CRC calculation when the polynomial is even

### Description

When the CRC is enabled, the CRC calculation is wrong if the polynomial is even.

### Workaround

Use odd polynomial.

## 2.13.5 Corrupted last bit of data and/or CRC received in Master mode with delayed SCK feedback

### Description

When performing a receive transaction in I2S or SPI Master mode, the last bit of the transacted frame is not captured when the signal provided by an internal feedback loop from the SCK pin exceeds a critical delay. The lastly transacted bit of the stored data then keeps the value from the pattern received previously. As a consequence, the last receive data bit may be wrong, and/or the CRCERR flag can be unduly asserted in the SPI mode if any data under checksum, and/or just the CRC pattern is wrongly captured.

In SPI mode, data are synchronous with the APB clock. A delay of up to two APB clock periods can thus be tolerated for the internal feedback delay.

The I2S mode is more sensitive than the SPI mode, especially in the case where an odd I2S prescaler factor is set and the APB clock is the system clock divided by two. In this case, the internal feedback delay is lower than 1.5 APB clock period.

The main factors contributing to the delay increase are low  $V_{DD}$  level, high temperature, high SCK pin capacitive load, and low SCK I/O output speed. The SPI communication speed has no impact.

### Workaround

The following workarounds can be adopted, jointly or individually:

- Decrease the APB clock speed.
- Configure the I/O pad of the SCK pin to be faster.

The following table gives the maximum allowable APB frequency (that still prevents the issue from occurring) versus GPIOx\_OSPEEDR output speed for the SCK pin, with a 30 pF capacitive load.

**Table 5. Maximum allowable APB frequency at 30 pF load**

OSPEEDR [1:0] for SCK pin	Max. APB frequency for SPI mode (MHz)	Max. APB frequency for I2S mode (MHz)
11 (very high), 10 (high)	84	42
01 (medium)	75	35
00 (low)	25	16

## 2.13.6 BSY flag may stay high at the end of a data transfer in Slave mode

### Description

The BSY flag may sporadically remain high at the end of a data transfer in Slave mode. The issue appears when an accidental synchronization happens between the internal CPU clock and the external SCK clock provided by the master.

This is related to the end of data transfer detection while the SPI is enabled in Slave mode.

As a consequence, the end of the data transaction may be not recognized when the software needs to monitor it (for example at the end of a session before entering the low-power mode or before the direction of the data line has to be changed at half duplex bidirectional mode). The BSY flag is unreliable to detect the end of any data sequence transaction.

### Workaround

When the NSS hardware management is applied and the NSS signal is provided by the master, the end of a transaction can be detected by the NSS polling by the slave:

- If the SPI receiving mode is enabled, the end of a transaction with the master can be detected by the corresponding RXNE event signaling the last data transfer completion.
- In SPI transmit mode, the user can check the BSY under timeout corresponding to the time necessary to complete the last data frame transaction. The timeout must be measured from TXE event signaling the last data frame transaction start (it is raised once the second bit transaction is ongoing). Either BSY becomes low normally or the timeout expires when the synchronization issue happens.

When the above workarounds are not applicable, the following sequence can be used to prevent the synchronization issue during SPI transmit mode:

1. Write the last data to the data register.
2. Poll TXE until it becomes high to ensure the data transfer has started.
3. Disable SPI by clearing SPE while the last data transfer is still ongoing.
4. Poll the BSY bit until it becomes low.
5. The BSY flag works correctly and can be used to recognize the end of the transaction.

*Note: This workaround can be used only when the CPU has enough performance to disable the SPI after a TXE event is detected, while the data frame transfer is still ongoing. It is impossible to achieve it when the ratio between CPU and SPI clock is low, and the data frame is short. In this specific case, the timeout can be measured from TXE, while calculating the fixed number of CPU clock periods corresponding to the time necessary to complete the data frame transaction.*

## 2.14 SDIO

### 2.14.1 Wrong CCRCFAIL status after a response without CRC is received

#### Description

The CRC is calculated even if the response to a command does not contain any CRC field. As a consequence, after the SDIO command IO\_SEND\_OP\_COND (CMD5) is sent, the CCRCFAIL bit of the SDIO\_STA register is set.

#### Workaround

The CCRCFAIL bit in the SDIO\_STA register must be ignored by the software. CCRCFAIL must be cleared by setting the CCRCFAILC bit of the SDIO\_ICR register after receiving the response to the CMD5 command.

### 2.14.2 No underrun detection with wrong data transmission

#### Description

In case there is an ongoing data transfer from the SDIO host to the SD card and the hardware flow control is disabled (bit 14 of the SDIO\_CLKCR is not set), if an underrun condition occurs, the controller may transmit a corrupted data block (with a wrong data word) without detecting the underrun condition when the clock frequencies have the following relationship:

$$[3 \times \text{period}(\text{PCLK2}) + 3 \times \text{period}(\text{SDIOCLK})] \geq (32 / (\text{BusWidth})) \times \text{period}(\text{SDIO\_CK})$$

#### Workaround

Avoid the above-mentioned clock frequency relationship, by applying one of the following measures:

- Increment the APB frequency, or
- decrease the transfer bandwidth, or
- reduce SDIO\_CK frequency.

## 2.15 bxCAN

### 2.15.1 bxCAN time-triggered communication mode not supported

#### Description

The time-triggered communication mode described in the reference manual is not supported. As a result, timestamp values are not available. The TTCM bit of the CAN\_MCR register must be kept cleared (time-triggered communication mode disabled).

#### Workaround

None.

## 2.16 OTG\_FS

### 2.16.1 Transmit data FIFO is corrupted when a write sequence to the FIFO is interrupted with accesses to certain OTG\_FS registers

#### Description

When the USB on-the-go full-speed peripheral is in Device mode, interrupting transmit FIFO write sequence with read or write accesses to OTG\_FS endpoint-specific registers (those ending in 0 or x) leads to corruption of the next data written to the transmit FIFO.

#### Workaround

Ensure that the transmit FIFO write sequence is not interrupted with accesses to the OTG\_FS registers.

### 2.16.2 Host packet transmission may hang when connecting through a hub to a low-speed device

#### Description

When the USB on-the-go full-speed peripheral connects to a low-speed device via a hub, the transmitter internal state machine may hang. This leads, after a timeout expiry, to a port disconnect interrupt.

#### Workaround

None. However, increasing the capacitance on the data lines may reduce the occurrence.

### 2.16.3 Data in RxFIFO is overwritten when all channels are disabled simultaneously

#### Description

If the available RxFIFO is just large enough to host one packet plus its data status, and it is currently occupied by the last received data plus its status, and, at the same time, the application requests that more IN channels are disabled, the OTG\_FS peripheral does not first check for available space before inserting the disabled status of the IN channels. It just inserts them by overwriting the existing data payload.

#### Workaround

Use one of the following measures:

- Configure the RxFIFO to host a minimum of  $2 \times \text{MPSIZ} + 2 \times \text{data status entries}$ .
- Check the RXFLVL bit (RxFIFO nonempty) of the OTG\_FS\_GINTSTS register before disabling each IN channel. If this bit is cleared, then disable an IN channel at a time. Each time the application disables an IN channel, it first has to check that the RXFLVL bit = 0 condition is true.

## 2.16.4 OTG host blocks the receive channel when receiving IN packets and no TxFIFO is configured

### Description

When receiving data, the OTG\_FS core erroneously checks for available TxFIFO space when it should only check for RxFIFO space. If the OTG\_FS core cannot see any space allocated for data transmission, it blocks the reception channel, and no data is received.

### Workaround

Set at least one TxFIFO equal to the maximum packet size. In this way, the host application, which intends to support only IN traffic, also has to allocate some space for the TxFIFO.

Since a USB host is expected to support any kind of connected endpoint, it is good practice to always configure enough TxFIFO space for OUT endpoints.

## 2.16.5 Host channel-halted interrupt not generated when the channel is disabled

### Description

When the application enables then immediately disables the host channel before the OTG\_FS host has had time to begin the transfer sequence, the OTG\_FS core, as a host, does not generate a channel-halted interrupt. The OTG\_FS core continues to operate normally.

### Workaround

Do not disable the host channel immediately after enabling it.

## 2.16.6 Wrong software-read OTG\_FS\_DCFG register values

### Description

When the application writes to the DAD and PFIVL bitfields of the OTG\_FS\_DCFG register, and then reads the newly written bitfield values, the read values may not be correct.

However, the values written by the application are correctly retained by the core, and the normal operation of the device is not affected.

### Workaround

Do not read the OTG\_FS\_DCFG register DAD and PFIVL bitfields just after programming them.

## 2.17 OTG\_HS

### 2.17.1 Transmit data FIFO is corrupted when a write sequence to the FIFO is interrupted with accesses to certain OTG\_HS registers

#### Description

When the USB on-the-go high-speed peripheral is in Device mode, interrupting transmit FIFO write sequence with read or write accesses to OTG\_HS endpoint-specific registers (those ending in 0 or x) leads to corruption of the next data written to the transmit FIFO.

#### Workaround

Ensure that the transmit FIFO write sequence is not interrupted with accesses to the OTG\_HS registers. Note that enabling DMA mode guarantees this.

## 2.17.2 Host packet transmission may hang when connecting the full speed interface through a hub to a low-speed device

### Description

When the USB on-the-go high-speed peripheral is used with the full speed interface (DM and DP pins, N.B. not available on all devices), and connects to a low-speed device via a hub, the transmitter internal state machine may hang. This leads, after a timeout expiry, to a port disconnect interrupt.

### Workaround

None. However, increasing the capacitance on the data lines may reduce the occurrence.

## 2.18 CEC

### 2.18.1 Transmission blocked when transmitted start bit is corrupted

#### Description

When the CEC communication start bit transmitted by the device is corrupted by another device on the CEC line, the CEC transmission is stalled.

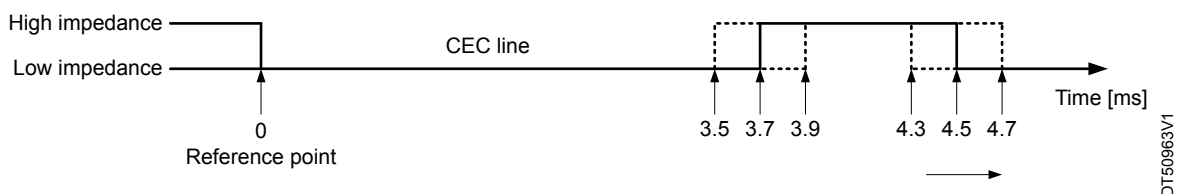
This failure is unlikely to happen as the CEC start bit corruption by another device can only occur if that device does not respect the CEC communication protocol.

The start bit timing standard tolerances are shown in Figure 2. The start bit is initiated by the device by driving the CEC line low (reference point). After 3.7 ms, the device releases the CEC line and starts checking its level. The following conditions must be met for the start bit to be valid:

- the CEC line goes high no later than 3.9 ms (4.05 ms with extended tolerance) from the reference point
- a falling edge on the CEC line does not occur earlier than 4.3 ms (4.15 ms with extended tolerance) from the reference point

If one of these conditions is not met, the transmission is aborted and never automatically retried. No error flag is set and the TXSOM (Tx Start Of Message) bit is not cleared.

**Figure 2. CEC start bit format with tolerances**



### Workaround

The only way to detect this error is for the application software to start a timeout when setting the TXSOM bit, restart it upon ARBLST or any RX event (as the transmission can be delayed by interleaved reception), and stop it upon TXBR (proof that the start bit was transmitted successfully) or TXEND event, or upon any TX error (which clears TXSOM). If the timeout expires (because none of those events occurred), the application software must restart the CEC peripheral and retransmit the message.



## 2.18.2 Missed CEC messages in normal receiving mode

### Description

In normal receiving mode, any CEC message with destination address different from the own address should normally be ignored and have no effect to the CEC peripheral. Instead, such a message is unduly written into the reception buffer and sets the CEC peripheral to a state in which any subsequent message with the destination address equal to the own address is rejected (NACK), although it sets RXOVR flag (because the reception buffer is considered full) and generates (if enabled) an interrupt. This failure can only occur in a multi-node CEC framework where messages with addresses other than own address can appear on the CEC line.

The listen mode operates correctly.

### Workaround

Use listen mode (set LSTEN bit) instead of normal receiving mode. Discard messages to single listeners with destination address different from the own address of the CEC peripheral.

## 2.18.3 Unexpected TXERR flag during a message transmission

### Description

During the transmission of a 0 or a 1, the HDMI-CEC drives the open-drain output to high-Z, so that the external pull-up implements a voltage rising ramp on the CEC line.

In some load conditions, with several powered-off devices connected to the HDMI-CEC line, the rising voltage may not drive the HDMI-CEC GPIO input buffer to  $V_{IH}$  within two HDMI-CEC clock cycles from the high-Z activation to TXERR flag assertion.

### Workaround

Limit the maximum number of devices connected to the HDMI-CEC line to ensure the GPIO  $V_{IH}$  threshold is reached within a time of two HDMI-CEC clock cycles ( $\sim 61 \mu s$ ).

The maximum equivalent 10%-90% rise time for the HDMI-CEC line is  $111.5 \mu s$ , considering a  $V_{IH}$  threshold equal to  $0.7 \times V_{DD}$ .

## Important security notice

The STMicroelectronics group of companies (ST) places a high value on product security, which is why the ST product(s) identified in this documentation may be certified by various security certification bodies and/or may implement our own security measures as set forth herein. However, no level of security certification and/or built-in security measures can guarantee that ST products are resistant to all forms of attacks. As such, it is the responsibility of each of ST's customers to determine if the level of security provided in an ST product meets the customer needs both in relation to the ST product alone, as well as when combined with other components and/or software for the customer end product or application. In particular, take note that:

- ST products may have been certified by one or more security certification bodies, such as Platform Security Architecture ([www.psacertified.org](http://www.psacertified.org)) and/or Security Evaluation standard for IoT Platforms ([www.trustcb.com](http://www.trustcb.com)). For details concerning whether the ST product(s) referenced herein have received security certification along with the level and current status of such certification, either visit the relevant certification standards website or go to the relevant product page on [www.st.com](http://www.st.com) for the most up to date information. As the status and/or level of security certification for an ST product can change from time to time, customers should re-check security certification status/level as needed. If an ST product is not shown to be certified under a particular security standard, customers should not assume it is certified.
- Certification bodies have the right to evaluate, grant and revoke security certification in relation to ST products. These certification bodies are therefore independently responsible for granting or revoking security certification for an ST product, and ST does not take any responsibility for mistakes, evaluations, assessments, testing, or other activity carried out by the certification body with respect to any ST product.
- Industry-based cryptographic algorithms (such as AES, DES, or MD5) and other open standard technologies which may be used in conjunction with an ST product are based on standards which were not developed by ST. ST does not take responsibility for any flaws in such cryptographic algorithms or open technologies or for any methods which have been or may be developed to bypass, decrypt or crack such algorithms or technologies.
- While robust security testing may be done, no level of certification can absolutely guarantee protections against all attacks, including, for example, against advanced attacks which have not been tested for, against new or unidentified forms of attack, or against any form of attack when using an ST product outside of its specification or intended use, or in conjunction with other components or software which are used by customer to create their end product or application. ST is not responsible for resistance against such attacks. As such, regardless of the incorporated security features and/or any information or support that may be provided by ST, each customer is solely responsible for determining if the level of attacks tested for meets their needs, both in relation to the ST product alone and when incorporated into a customer end product or application.
- All security features of ST products (inclusive of any hardware, software, documentation, and the like), including but not limited to any enhanced security features added by ST, are provided on an "AS IS" BASIS. AS SUCH, TO THE EXTENT PERMITTED BY APPLICABLE LAW, ST DISCLAIMS ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, unless the applicable written and signed contract terms specifically provide otherwise.

## Revision history

**Table 6. Document revision history**

Date	Version	Changes
16-Mar-2015	1	Initial release.
03-Jan-2017	2	<p>Updated:</p> <ul style="list-style-type: none"> <li>Section 2.1.5: Delay after an RCC peripheral clock enabling.</li> <li>Section 2.4.2: Start cannot be generated after a misplaced Stop</li> </ul> <p>Added:</p> <ul style="list-style-type: none"> <li>Section 2.1.7: Data cache might be corrupted during Flash read\write operation.</li> <li>Section 2.3.1: Spurious tamper detection when disabling the tamper channel</li> <li>Section 2.3.2: Detection of a tamper event occurring before enabling the tamper detection is not supported in edge detection mode</li> <li>Section 2.3.3: RTC calendar registers are not locked properly.</li> <li>Section 2.4.6: Spurious Bus Error detection in Master mode.</li> <li>Section 2.5.1: Wrong CRC calculation when the polynomial is even</li> <li>Section 2.5.2: Corrupted last bit of data and/or CRC, received in Master mode with delayed SCK feedback</li> <li>Section 2.5.3: Wrong CRC transmitted in Master mode with delayed SCK feedback</li> <li>Section 2.5.3: BSY bit may stay high at the end of a data transfer in Slave mode</li> <li>Section 2.6.3: Corrupted last bit of data and/or CRC, received in Master mode with delayed SCK feedback</li> </ul>
21-Dec-2020	3	<p>Updated:</p> <ul style="list-style-type: none"> <li>Silicon identification</li> <li>Table 1: Device identification</li> <li>Table 4: Summary of silicon limitations</li> </ul> <p>Deleted:</p> <ul style="list-style-type: none"> <li>Section 2.5.3: Wrong CRC transmitted in Master mode with delayed SCK feedback</li> </ul>
21-Jun-2023	4	<p>Core: added Store immediate overlapping exception return operation might vector to incorrect interrupt erratum.</p> <p>System:</p> <ul style="list-style-type: none"> <li>Added Debugging Stop mode and SysTick timer, Debugging Stop mode with WFE entry, Possible delay in backup domain protection disabling/enabling after programming the DBP bit, and PC13 signal transitions disturb LSE errata.</li> <li>Updated workaround of Internal noise impacting the ADC accuracy erratum.</li> </ul> <p>FSMC: added Wrong data read from a busy NAND memory, Spurious clock stoppage with continuous clock feature enabled, and Data read might be corrupted when the write FIFO is disabled errata. QUADSPI: added Memory-mapped read operations may fail when timeout counter is enabled and Memory-mapped access in indirect mode clearing QUADSPI_AR register errata.</p> <p>DAC: updated DMA underrun flag not set when an internal trigger is detected on the clock cycle of the DMA request acknowledge erratum.</p> <p>TIM: added PWM re-enabled in automatic output enable mode despite of system break, TRGO and TRGO2 trigger output failure, Consecutive compare event missed in specific conditions, and Output compare clear not working with external counter reset errata.</p> <p>IWDG: added RVU flag not cleared at low APB clock frequency and PVU flag not cleared at low APB clock frequency errata.</p>

Date	Version	Changes
		<p>RTC: added RTC interrupt can be masked by another RTC interrupt, Calendar initialization may fail in case of consecutive INIT mode entry, and Alarm flag may be repeatedly set when the core is stopped in debug errata.</p> <p>Added FMPI2C errata.</p> <p>USART:</p> <ul style="list-style-type: none"> <li>Changed nCTS and nRTS to CTS and RTS, respectively.</li> <li>Updated Break request can prevent the transmission complete flag (TC) from being set and Guard time not respected when data are sent on TXE events erratum workarounds.</li> </ul> <p>SPI/I2S:</p> <ul style="list-style-type: none"> <li>Added BSY bit may stay high when SPI is disabled, Anticipated communication upon SPI transit from slave receiver to master, and Wrong CRC transmitted in Master mode with delayed SCK feedback errata.</li> <li>Updated I<sup>2</sup>S slave in PCM short pulse mode sensitive to timing between WS and CK.</li> <li>Removed <i>Corrupted last bit of data and/or CRC, received in Master mode with delayed SCK feedback</i> and <i>In I2S Slave mode, with Bit ASTRTEN=1, WS level must be set by the external master when enabling the I2S</i> errata.</li> </ul> <p>Added OTG_FS, OTG_HS, and CEC errata.</p> <p>Added Section Important security notice.</p>
13-Feb-2024	5	Updated errata: <a href="#">PC13 signal transitions disturb LSE</a>
02-Apr-2024	6	Updated errata: <a href="#">Corrupted last bit of data and/or CRC received in Master mode with delayed SCK feedback</a>

## Contents

<b>1</b>	<b>Summary of device errata</b>	<b>2</b>
<b>2</b>	<b>Description of device errata</b>	<b>5</b>
2.1	Core	5
2.1.1	Interrupted loads to SP can cause erroneous behavior	5
2.1.2	VDIV or VSQRT instructions might not complete correctly when very short ISRs are used	5
2.1.3	Store immediate overlapping exception return operation might vector to incorrect interrupt	6
2.2	System	7
2.2.1	Debugging Stop mode and SysTick timer	7
2.2.2	Debugging Stop mode with WFE entry	7
2.2.3	Debugging Sleep/Stop mode with WFE/WFI entry	8
2.2.4	Wake-up sequence from Standby mode when using more than one wake-up source	8
2.2.5	Full JTAG configuration without NJTRST pin cannot be used	8
2.2.6	MPU attribute to RTC and IWDG registers incorrectly managed	8
2.2.7	Delay after an RCC peripheral clock enabling	9
2.2.8	Internal noise impacting the ADC accuracy	9
2.2.9	Data cache might be corrupted during flash memory read-while-write operation	9
2.2.10	Possible delay in backup domain protection disabling/enabling after programming the DBP bit	10
2.2.11	PC13 signal transitions disturb LSE	10
2.3	FSMC	10
2.3.1	Dummy read cycles inserted when reading synchronous memories	10
2.3.2	Wrong data read from a busy NAND memory	11
2.3.3	Spurious clock stoppage with continuous clock feature enabled	11
2.3.4	Data read might be corrupted when the write FIFO is disabled	11
2.4	QUADSPI	11
2.4.1	Extra data written in the FIFO at the end of a read transfer	11
2.4.2	First nibble of data not written after dummy phase	12
2.4.3	Wrong data from memory-mapped read after an indirect mode operation	12
2.4.4	Memory-mapped read operations may fail when timeout counter is enabled	12
2.4.5	Memory-mapped access in indirect mode clearing QUADSPI_AR register	13
2.5	ADC	13
2.5.1	ADC sequencer modification during conversion	13
2.6	DAC	13
2.6.1	DMA request not automatically cleared by clearing DMAEN	13
2.6.2	DMA underrun flag not set when an internal trigger is detected on the clock cycle of the DMA request acknowledge	14

<b>2.7</b>	<b>TIM</b>	<b>14</b>
2.7.1	PWM re-enabled in automatic output enable mode despite of system break	14
2.7.2	TRGO and TRGO2 trigger output failure	14
2.7.3	Consecutive compare event missed in specific conditions	15
2.7.4	Output compare clear not working with external counter reset	15
<b>2.8</b>	<b>IWDG</b>	<b>16</b>
2.8.1	RVU flag not reset in Stop	16
2.8.2	PVU flag not reset in Stop	16
2.8.3	RVU flag not cleared at low APB clock frequency	16
2.8.4	PVU flag not cleared at low APB clock frequency	16
<b>2.9</b>	<b>RTC</b>	<b>16</b>
2.9.1	Spurious tamper detection when disabling the tamper channel	16
2.9.2	RTC calendar registers are not locked properly	17
2.9.3	RTC interrupt can be masked by another RTC interrupt	17
2.9.4	Calendar initialization may fail in case of consecutive INIT mode entry	18
2.9.5	Alarm flag may be repeatedly set when the core is stopped in debug	19
2.9.6	Detection of a tamper event occurring before enabling the tamper detection is not supported in edge detection mode	19
<b>2.10</b>	<b>FMPI2C</b>	<b>19</b>
2.10.1	10-bit master mode: new transfer cannot be launched if first part of the address is not acknowledged by the slave	19
2.10.2	Wrong data sampling when data setup time ( $t_{\text{SU;DAT}}$ ) is shorter than one FMPI2C kernel clock period	20
2.10.3	Spurious bus error detection in master mode	20
2.10.4	Last-received byte loss in reload mode	20
2.10.5	Spurious master transfer upon own slave address match	21
2.10.6	START bit is cleared upon setting ADDRCF, not upon address match	21
2.10.7	OVR flag not set in underrun condition	22
2.10.8	Transmission stalled after first byte transfer	22
2.10.9	SDA held low upon SMBus timeout expiry in slave mode	22
2.10.10	Inconsistent FMPI2C peripheral instance naming	23
<b>2.11</b>	<b>I2C</b>	<b>23</b>
2.11.1	Spurious bus error detection in master mode	23
2.11.2	SMBus standard not fully supported	23
2.11.3	Start cannot be generated after a misplaced Stop	23
2.11.4	Mismatch on the "Setup time for a repeated Start condition" timing parameter	24
2.11.5	Data valid time ( $t_{\text{VD;DAT}}$ ) violated without the OVR flag being set	24
2.11.6	Both SDA and SCL maximum rise times ( $t_r$ ) violated when the VDD_I2C bus voltage is higher than $((V_{\text{DD}} + 0.3) / 0.7) \text{ V}$	24

<b>2.12</b>	<b>USART</b>	<b>25</b>
2.12.1	Idle frame is not detected if the receiver clock speed is deviated	25
2.12.2	In full-duplex mode, the Parity Error (PE) flag can be cleared by writing to the data register	25
2.12.3	Parity Error (PE) flag is not set when receiving in Mute mode using address mark detection	25
2.12.4	Break frame is transmitted regardless of CTS input line status	25
2.12.5	RTS signal abnormally driven low after a protocol violation	25
2.12.6	Start bit detected too soon when sampling for NACK signal from the smartcard	26
2.12.7	Break request can prevent the transmission complete flag (TC) from being set	26
2.12.8	Guard time not respected when data are sent on TXE events	26
2.12.9	RTS is active while RE or UE = 0	27
<b>2.13</b>	<b>SPI/I2S</b>	<b>27</b>
2.13.1	BSY bit may stay high when SPI is disabled	27
2.13.2	Anticipated communication upon SPI transit from slave receiver to master	27
2.13.3	I2S slave in PCM short pulse mode sensitive to timing between WS and CK	27
2.13.4	Wrong CRC calculation when the polynomial is even	28
2.13.5	Corrupted last bit of data and/or CRC received in Master mode with delayed SCK feedback	28
2.13.6	BSY flag may stay high at the end of a data transfer in Slave mode	28
<b>2.14</b>	<b>SDIO</b>	<b>29</b>
2.14.1	Wrong CCRCFAIL status after a response without CRC is received	29
2.14.2	No underrun detection with wrong data transmission	29
<b>2.15</b>	<b>bxCAN</b>	<b>30</b>
2.15.1	bxCAN time-triggered communication mode not supported	30
<b>2.16</b>	<b>OTG_FS</b>	<b>30</b>
2.16.1	Transmit data FIFO is corrupted when a write sequence to the FIFO is interrupted with accesses to certain OTG_FS registers	30
2.16.2	Host packet transmission may hang when connecting through a hub to a low-speed device	30
2.16.3	Data in RxFIFO is overwritten when all channels are disabled simultaneously	30
2.16.4	OTG host blocks the receive channel when receiving IN packets and no TxFIFO is configured	31
2.16.5	Host channel-halted interrupt not generated when the channel is disabled	31
2.16.6	Wrong software-read OTG_FS_DCFG register values	31
<b>2.17</b>	<b>OTG_HS</b>	<b>31</b>
2.17.1	Transmit data FIFO is corrupted when a write sequence to the FIFO is interrupted with accesses to certain OTG_HS registers	31
2.17.2	Host packet transmission may hang when connecting the full speed interface through a hub to a low-speed device	32

---

<b>2.18</b>	<b>CEC</b>	<b>32</b>
2.18.1	Transmission blocked when transmitted start bit is corrupted	32
2.18.2	Missed CEC messages in normal receiving mode	33
2.18.3	Unexpected TXERR flag during a message transmission	33
<b>Important security notice</b>		<b>34</b>
<b>Revision history</b>		<b>35</b>



**IMPORTANT NOTICE – READ CAREFULLY**

STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, enhancements, modifications, and improvements to ST products and/or to this document at any time without notice. Purchasers should obtain the latest relevant information on ST products before placing orders. ST products are sold pursuant to ST's terms and conditions of sale in place at the time of order acknowledgment.

Purchasers are solely responsible for the choice, selection, and use of ST products and ST assumes no liability for application assistance or the design of purchasers' products.

No license, express or implied, to any intellectual property right is granted by ST herein.

Resale of ST products with provisions different from the information set forth herein shall void any warranty granted by ST for such product.

ST and the ST logo are trademarks of ST. For additional information about ST trademarks, refer to [www.st.com/trademarks](http://www.st.com/trademarks). All other product or service names are the property of their respective owners.

Information in this document supersedes and replaces information previously supplied in any prior versions of this document.

© 2024 STMicroelectronics – All rights reserved