Plume

Variant: Preliminary

Integrated Actuators Laboratory (LAI)

Semester project: 02/2025 - 06/2025
Student: Théo Heng - theoheng@icloud.com
Supervisors: Maël Dagon, Paolo Germano

2025-04-07

Rev 1.0

TOP VIEW

3D render of your PCB here (Top View)

BOTTOM VIEW

3D render of your PCB here (Bottom View)

NOTES

MULTIPLE MOTOR CONTROLLER WITH SENSORLESS POSITION CONTROL

Not fitted components are marked as X

DRAFT - Very early stage of schematic, ignore details.
PRELIMINARY - Close to final schematic.
CHECKED - There shouldn't be any mistakes. Contact the engineer if you find any.
RELEASED - A board with this schematic has been sent to production.

Preliminary - XX/XX/2025

DESIGN CONSIDERATIONS

DESIGN NOTE: Example text for informational design notes.

DEBUG NOTE: Example text for debug notes.

DESIGN NOTE: Example text for cautionary design notes.

DESIGN NOTE: Example text for critical design notes.

LAYOUT NOTE: Example text for critical layout guidelines.

Comments: KiCad Template by Vincent Nguyen	Laboratory: Integrated Actuators Laboratory EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Cover Page	File Name: Plume.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /		Supervisor: Maël Dagon, Paolo Germano	Size: A3	Sheet: 1 of 31

[2] Block Diagram

Target specifications:

Battery Input voltage:	3.08 - 4.25 V
Max charge current:	200 mA
Nb of controlled motors:	18
Max load current:	3A
Standby Current:	50 mA
Sleep Current:	15 uA

6 layer, 2oz out/1oZ in stackup: JLC061621-7628

JLC061621-7628(Standard/Finished thickness1.57mm±10%) | JLC061621-7628A(SpecialTg170/Finished thickness1.59mm±10%) | JLC061621-1080(Special/

Impedance (Ω)	Type	Signal Layer	Top Ref	Bottom Ref	Trace Width	Trace Spacing	Impedance trace to copper
50	Single Ended (Non coplanar)	L1	/	L2	0.3353	/	/

Layer	Material	Thickness (mil)	Thickness (mm)
L1	Outer Copper Weight2oz	2.76	0.0700
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
L2	Inner Copper Weight	1.18	0.0300
Core	0.25mm 1/1OZ without copper	9.84	0.2500
L3	Inner Copper Weight	1.18	0.0300
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
L4	Inner Copper Weight	1.18	0.0300
Core	0.25mm 1/1OZ without copper	9.84	0.2500
L5	Inner Copper Weight	1.18	0.0300
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
L6	Outer Copper Weight2oz	2.76	0.0700

6 layer, 1oz out/1oZ in stackup: JLC061611-7628

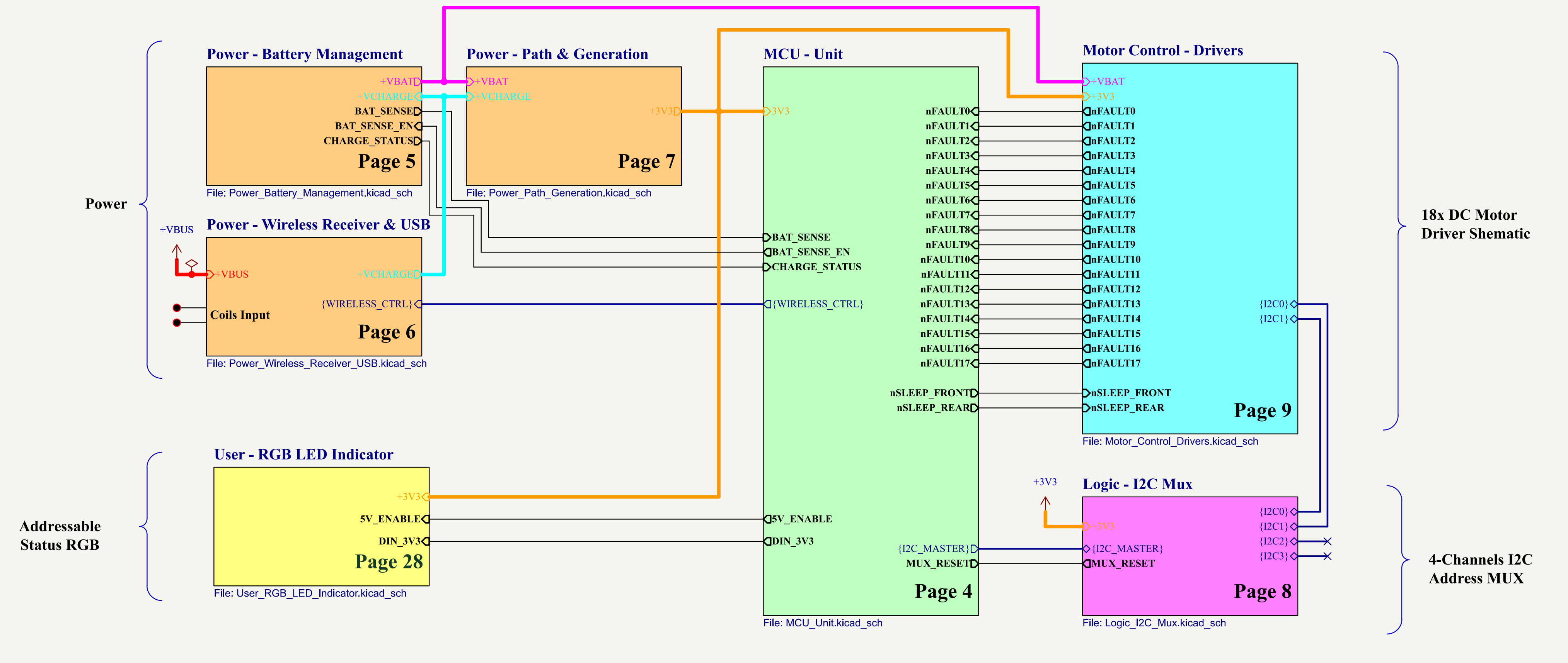
/Finished thickness1.58mm±10%) | JLC061611-7628B(Special/Finished thickness1.66mm±10%) | JLC061611-7628(Standard/Finished thickness1.6mm±10%)

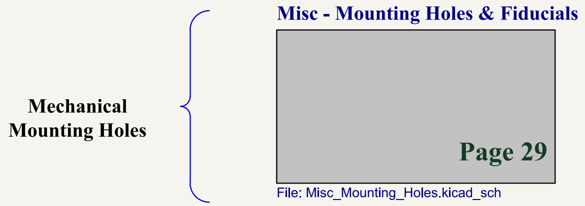
Impedance (Ω)	Type	Signal Layer	Top Ref	Bottom Ref	Trace Width	Trace Spacing	Impedance trace to copper
50	Single Ended (Non coplanar)	L1	/	L2		/	/

Layer	Material	Thickness (mil)	Thickness (mm)
L1	Outer Copper Weight1oz	1.38	0.0350
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
L2	Inner Copper Weight	1.18	0.0300
Core	0.25mm 1/1OZ without copper	9.84	0.2500
L3	Inner Copper Weight	1.18	0.0300
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
Prepreg	3313 RC57% 4.2mil	4.21	0.1070
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
L4	Inner Copper Weight	1.18	0.0300
Core	0.25mm 1/1OZ without copper	9.84	0.2500
L5	Inner Copper Weight	1.18	0.0300
Prepreg	7628, RC 49%, 8.6 mil	7.99	0.2030
L6	Outer Copper Weight1oz	1.38	0.0350

Comments:	Laboratory: Integrated Actuators Laboratory	Variant: Preliminary	
	Board Name: Plume	Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Block Diagram	File Name: Block Diagram.kicad_sch	Designer: Théo Heng	Date: 2025-04-05 / Revision: 1.0
Sheet Path: /Block Diagram/		Supervisor: Maël Dagon, Paolo Germano	Size: A3 / Sheet: 2 of 31

[3] Project Architecture

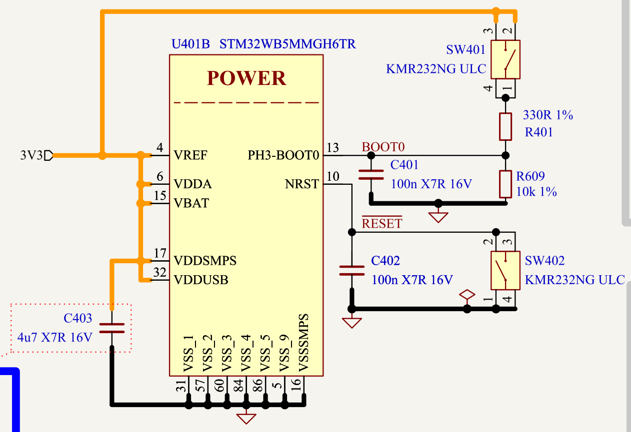




Comments:	Laboratory: Integrated Actuators Laboratory (EPFL)		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Project Architecture	File Name: Project Architecture.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 3 of 31

[4] MCU - Unit

MCU - Power



LAYOUT NOTE: An additional capacitor of 4.7 uF is added to eliminate ripple from the SMPS power supply. Place close to the VDDSMPS pin.

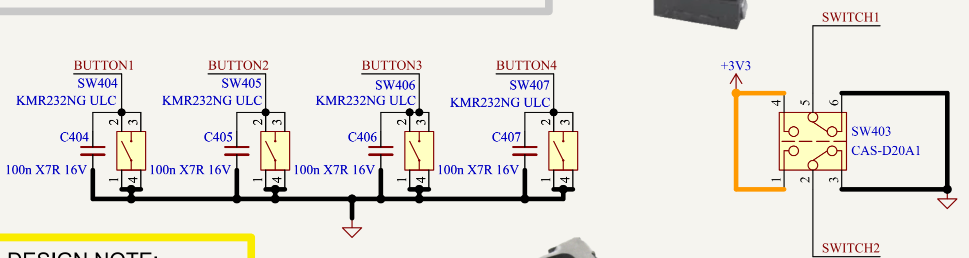
DESIGN NOTE:
PH3_BOOT0 is tied low through an internal pull-down to enable start from flash memory. However, it can be tied high with a low resistive pull-up if required.

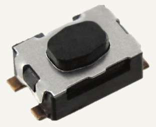
A low-pass filter is added for debouncing purposes, to have and extra user button after startup.

DESIGN NOTE:
A reset pull-up is already implemented in the STM32WB Series microcontrollers. The reset circuitry only requires an external capacitor for filtering purpose

MCU - User Buttons & Switches

DESIGN NOTE:
The STM32 needs to configure the buttons and switches GPIO as input with pull-up. The internal pull equivalent resistor have a value of 40kΩ. -> 82.5uA

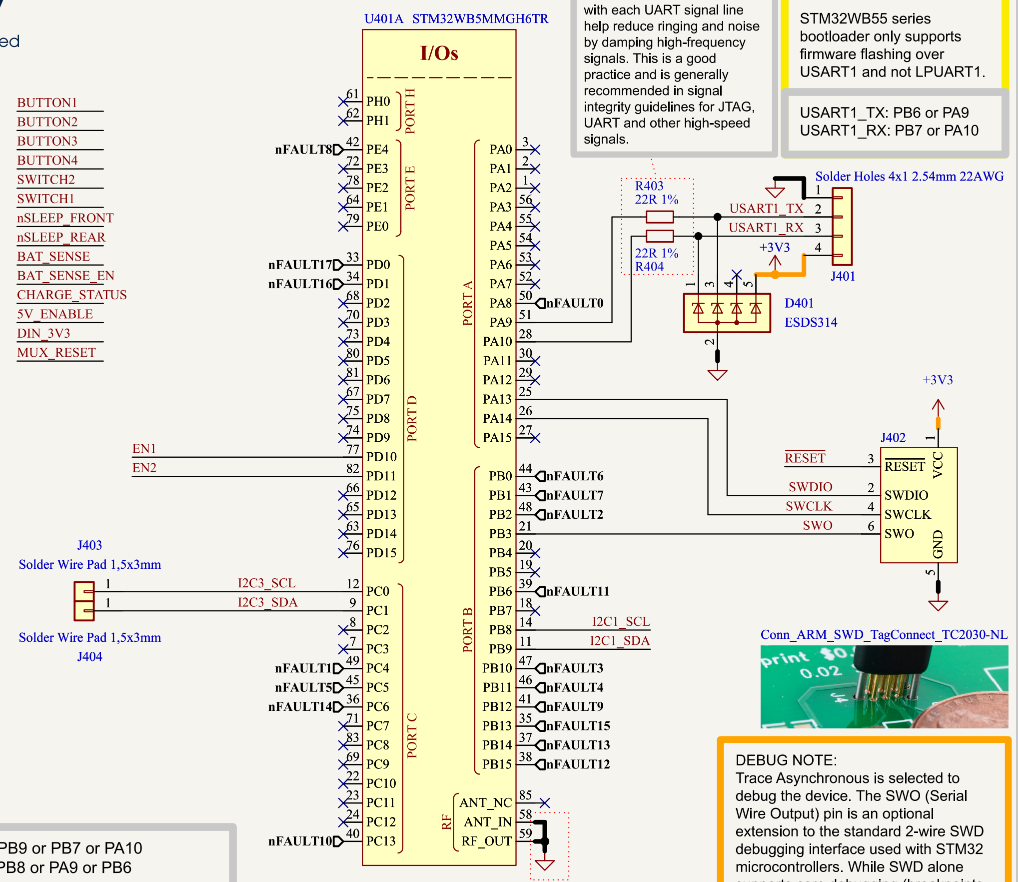




DESIGN NOTE:

I/Os with wake-up from Standby/Shutdown capability: PA0, PC13, PC12, PA2, PC5.

MCU - I/Os



DESIGN NOTE:
The 22Ω resistors in series with each UART signal line help reduce ringing and noise by damping high-frequency signals. This is a good practice and is generally recommended in signal integrity guidelines for JTAG, UART and other high-speed signals.

CAUTION NOTE:

STM32WB55 series bootloader only supports firmware flashing over USART1 and not LPUART1.

USART1_TX: PB6 or PA9
USART1_RX: PB7 or PA10

I2C_1 SDA: PB9 or PB7 or PA10
I2C_1 SCL: PB8 or PA9 or PB6

I2C_3 SDA: PC1 or PB4 or PB14 or PB11
I2C_3 SCL: PC0 or PA7 or PB10 or PB13

DESIGN NOTE:
ANT_IN and RF_OUT pins must be connected to GND. This module already integrates an antenna, so no external antenna required

DESIGN NOTE:

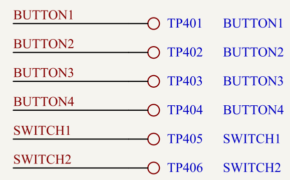
PB0 and PB1 are only available for revision X parts.

DEBUG NOTE:
Trace Asynchronous is selected to debug the device. The SWO (Serial Wire Output) pin is an optional extension to the standard 2-wire SWD debugging interface used with STM32 microcontrollers. While SWD alone supports core debugging (breakpoints, stepping, memory access), adding the SWO pin enables real-time tracing and non-intrusive data logging. This allows to use features like ITM printf-style debugging, event tracing, and performance monitoring without halting program execution, making it very interesting for diagnosing complex or time-sensitive embedded applications.

DESIGN NOTE:

Any floating input pin can also settle to an intermediate voltage level or switch inadvertently, as a result of external electromagnetic noise. To avoid current consumption related to floating pins, they must either be configured in analog mode, or forced internally to a definite digital value. This can be done either by using pull-up/down resistors or by configuring the pins in output mode.

Test Points



Battery Management

BAT_SENSE → BAT_SENSE
BAT_SENSE_EN → BAT_SENSE_EN
CHARGE_STATUS → CHARGE_STATUS

Wireless Control

EN1, EN2 → {WIRELESS_CTRL}

Motor Sleep Control

nSLEEP_FRONT → nSLEEP_FRONT
nSLEEP_REAR → nSLEEP_REAR

CAUTIOUS NOTE:

This board contains three sensitive GPIOs: PB10, PB11, PC5

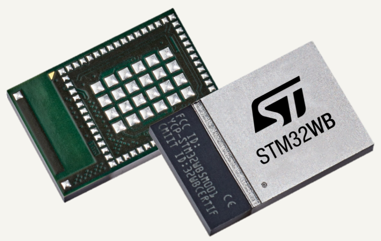
When PB10, PB11 and/or PC5 are used, a 3.3 pF capacitor in a small package such as the 0201 or smaller, mustbe placed as close as possible to the output pin. Also border the GPIO tracks with the ground plane.

Motor Control I2C Bus

MUX_RESET → MUX_RESET
I2C1_SCL, I2C1_SDA → {I2C_MASTER}

RGB LED Control

5V_ENABLE → 5V_ENABLE
DIN_3V3 → DIN_3V3



Comments: AN5165 Application Note: How to develop RF hardware using STM32WB microcontrollers; AN2606 Application Note: STM32 microcontroller system memory boot mode; Debounce a Switch - Texas Instrument	Laboratory: Integrated Actuators Laboratory		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: MCU - Unit	File Name: MCU_Unit.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/MCU - Unit/		Supervisor: Maël Dagon, Paolo Germano	Size: A3	Sheet: 4 of 31

[5] Power - Battery Management

Current analysis:

Normal:
BQ29737: 4uA
MCP73831: 100nA

Shutdown:
BQ297377: 100nA
MCP73831: 100nA

DESIGN NOTE - gate-source resistors:

TI recommends placing a high impedance 5MΩ across the gate source of each external FET to deplete any charge on the gate-source capacitance.

DESIGN NOTE - EXTERNAL PROTECTION FETs:

The external FET selection is important to ensure the battery pack protection is sufficient and complies to the requirements of the system.

BQ29737 charge overcurrent threshold: -50mV
BQ29737 discharge overcurrent threshold: 100mV

The CSD85302L when driven at 3.7V at the gate, have a source to source resistance of ≈22 mΩ.

Resulting charge overcurrent protection:
50mV / 22mΩ ≈ 2.27A

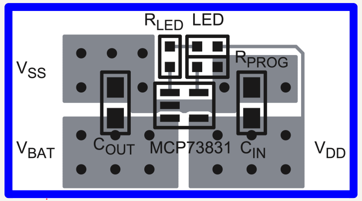
Resulting discharge overcurrent protection:
100mV / 22mΩ ≈ 4.54A

LAYOUT NOTE:
The input RC filter on the BAT pin should be close to the terminal of the IC

DESIGN NOTE - CHARGE STATUS LED:

APT1608CGCK has a typical luminous intensity of 50mcd (millicandela) @20mA, and 25mcd @10mA.
Typ. Vf = 2V @10mA,

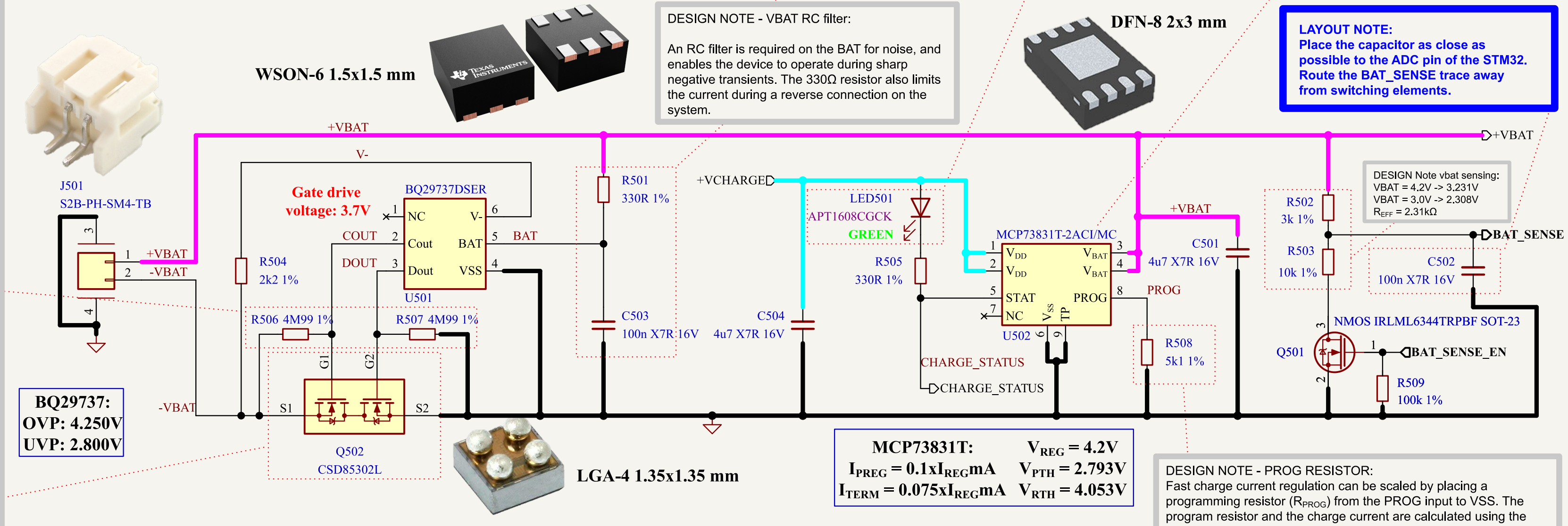
Typ. If = (5V - 2V)/330hm ≈ 9 mA
P = 2V×9mA ≈ 18 mW < 75 mW (max rating)



DESIGN NOTE - VBAT RC filter:

An RC filter is required on the BAT for noise, and enables the device to operate during sharp negative transients. The 330Ω resistor also limits the current during a reverse connection on the system.

LAYOUT NOTE:
Place the capacitor as close as possible to the ADC pin of the STM32. Route the BAT_SENSE trace away from switching elements.



BQ29737:
OVP: 4.250V
UVP: 2.800V

MCP73831T:
$V_{REG} = 4.2V$
$I_{PREG} = 0.1xI_{REG}mA$
$V_{PTH} = 2.793V$
$I_{TERM} = 0.075xI_{REG}mA$
$V_{RTH} = 4.053V$

DESIGN NOTE - PROG RESISTOR:
Fast charge current regulation can be scaled by placing a programming resistor (R_{PROG}) from the PROG input to VSS. The program resistor and the charge current are calculated using the following equation:

I_{REG} = 1000V / R_{PROG}
I_{REG} = 1000V / 5100 ≈ 196mA

Voltage and Current Protection Integrated Circuit for Single-Cell Li-Ion and Li-Polymer Batteries and Miniature Single-Cell, Fully Integrated Li-Ion, Li-Polymer Charge Management Controller

Test Points

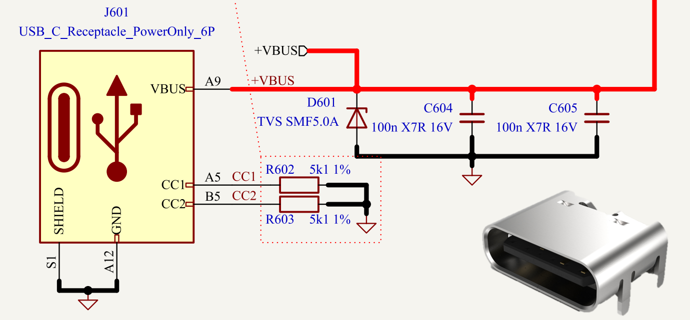
Net	Test point	Label
COUT	TP501	COUT
DOUT	TP502	DOUT
CHARGE_STATUS	TP503	CHARGE_STATUS
BAT_SENSE_EN	TP504	BAT_SENSE_EN
BAT_SENSE	TP505	BAT_SENSE
-VBAT	TP506	-VBAT
+VBAT	TP507	VBAT

Comments:	Laboratory: Integrated Actuators Laboratory		Variant: Preliminary
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care
Sheet Title: Power - Battery Management	File Name: Power_Battery_Management.kicad_sch	Designer: Théo Heng	Date: 2025-04-05 / Revision: 1.0
Sheet Path: /Project Architecture/Power - Battery Management/		Supervisor: Maël Dagon, Paolo Germano	Size: A4 / Sheet: 5 of 31

[6] Power - Wireless Receiver & USB

DESIGN NOTE - USB-C Configuration Channel pins:

Device Detection: When the CC1 and CC2 pins have pull-down resistors, the USB-C power source detects that a "sink" device is connected and needs power. This signals to the power source to supply the default 5V over the VBUS line.
Power Negotiation: The 5.1kΩ resistors indicate that the device is a standard USB device that only requires 5V, which is the default voltage for USB-C.
Orientation Detection: Since USB-C is a reversible connector, the CC1 and CC2 pins help determine which way the connector is inserted. Only one of the pins will be connected to the host's CC line when inserted. By tying both to ground through pull-down resistors, the device can receive power regardless of orientation, with the host powering up the correct side.



6-Pins, Power-Only, USB-C connector

Test Points

+VBUS	TP601	+VBUS
+VCHARGE	TP602	+VCHARGE
AD_EN	TP603	AD_EN
CHG	TP604	CHG

SELECTED COIL
diam: 26.3mm

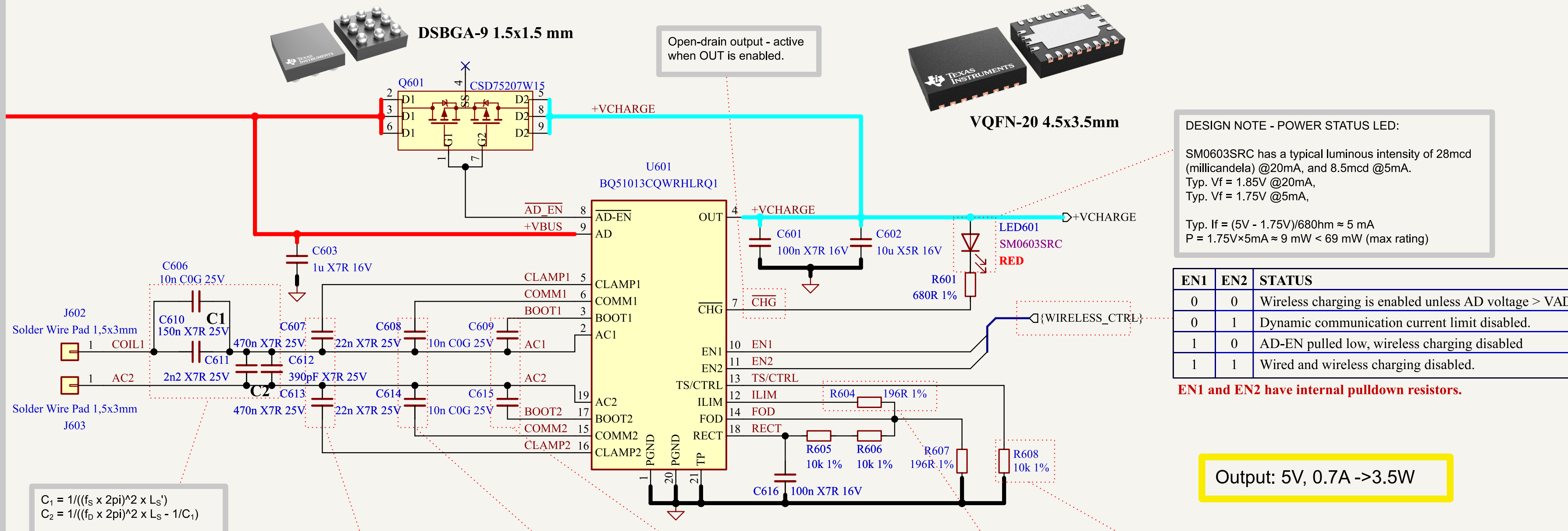
760308101309 Wireless Charging Coil

Properties		Test conditions	Value	Unit	Tol.
Inductance	L	125 kHz/ 10 mA	10	µH	±10%
Rated Current	I_R	ΔT = 40 K	1.5	A	max.
Q-Factor	Q	125 kHz/ 10 mA	20		typ.
Power Capability	P	V_{DC} = 20 V	20	W	typ.
DC Resistance	R_{DC}	@ 20 °C	350	mΩ	typ.
DC Resistance	R_{DC}	@ 20 °C	450	mΩ	max.
Self Resonant Frequency	f_{res}		19	MHz	typ.

DSBGA-9 1.5x1.5 mm

VQFN-20 4.5x3.5mm

Open-drain output - active when OUT is enabled.



DESIGN NOTE - POWER STATUS LED:

SM0603SRC has a typical luminous intensity of 28mcd (millicandela) @20mA, and 8.5mcd @5mA.
Typ. Vf = 1.85V @20mA,
Typ. Vf = 1.75V @5mA,

Typ. If = (5V - 1.75V)/680hm ≈ 5 mA
P = 1.75V×5mA ≈ 9 mW < 69 mW (max rating)

EN1	EN2	STATUS
0	0	Wireless charging is enabled unless AD voltage > VAD_{Pres}.
0	1	Dynamic communication current limit disabled.
1	0	AD-EN pulled low, wireless charging disabled
1	1	Wired and wireless charging disabled.

EN1 and EN2 have internal pulldown resistors.

Output: 5V, 0.7A ->3.5W

$C_1 = 1/((f_S \times 2pi)^2 \times L_S')$
$C_2 = 1/((f_D \times 2pi)^2 \times L_S - 1/C_1)$

where:
f_S = 100 kHz
f_D = 1 MHz
L_S = 10 uH
L_S' = 16 uH

Therefore:

$C_1 \approx$ 158.3nF
-> 150nF + 10nF = 160nF

$C_2 \approx$ 2.57nF
-> 2.2nF + 0.39nF = 2.59nF

The CLAMP capacitors are used to aid in the clamping process to protect against overvoltage. These capacitors are from AC1 to CLAMP1 and from AC2 to CLAMP2 and must have a minimum 25-V rating. A 0.47-µF capacitor with a 25-V rating is chosen.

The COMM capacitors are used to facilitate the communication from the RX to the TX. This selection can vary a bit more than the BOOT and CLAMP capacitors. In general, a 22-nF capacitor is recommended.

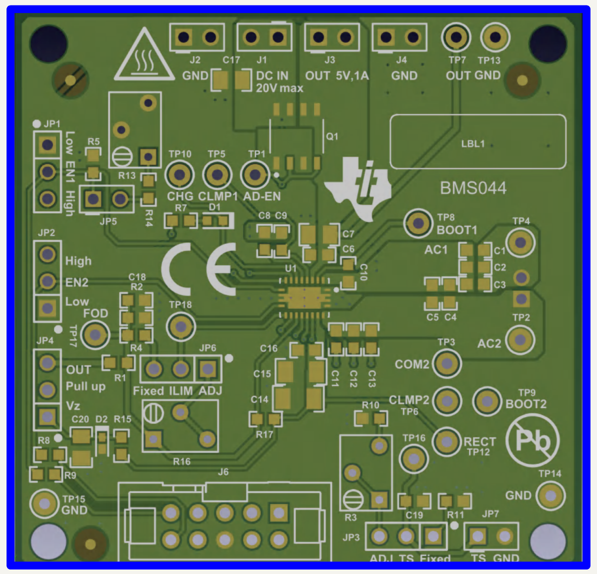
The BOOT capacitors are used to allow the internal rectifier FETs to turn on and off properly. These capacitors are from AC1 to BOOT1 and from AC2 to BOOT2 and must have a minimum 25-V rating. A 10-nF capacitor with a 25-V rating is chosen.

DESIGN NOTE - ILIM resistor:

$I_{ILIM} = K_{ILIM}/(R_{ILIM} + R_{FOD})$
$I_{ILIM} = 314/(196 + 196) \approx 0.8$ A
$I_{MAX} = I_{ILIM} / 1.2 \approx 0.66$ A

If the NTC function is not desired, connect to PGND with a 10-kΩ resistor.

Automotive Highly Integrated Wireless Receiver Qi (WPC v2.0) Compliant Power Supply



Comments: EVM User's Guide: BQ51013C-Q1EVM BQ51013C-Q1 Evaluation Module	Laboratory: Integrated Actuators Laboratory		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Power - Wireless Receiver & USB	File Name: Power_Wireless_Receiver_USB.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Power - Wireless Receiver & USB/		Supervisor: Maël Dagon, Paolo Germano	Size: A3	Sheet: 6 of 31

[7] Power - Path & Generation

Design Note - Simple Power-Path with PMOS and Schottky diode:

When no USB-C supply nor coil power is present, this simple circuit will by default conduct the battery to the LDO, through the PMOS.

But if USB-C supply or coil power is active, the PMOS will turn off, and the LDO will use the power from the external power supply through the schottky diode.

Design Note - Power Path Schottky diode:

A diode is required to prevent reverse current from flowing to the power source. Selecting the right diode can minimize the leakage current and the forward voltage drop from the power source to the system load. A schottky diode, which has lower forward voltage drop, is recommended.
Forward voltage @ If = 200mA: 420mV
Reverse current @ Vr = 5V: 70nA

Active-low reset output. $\overline{\text{RESET}}$ has a push-pull output drive and is capable of directly driving input pins. $\overline{\text{RESET}}$ is low as long as VDD remains below the factory threshold voltage of 3.08V, and until the delay time (td = 200ms) elapses after VDD rises above the threshold voltage.

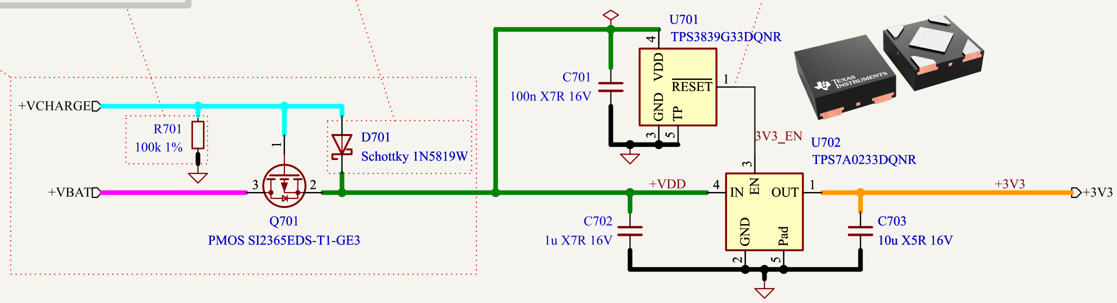
Current analysis:

Normal:
TPS3839: 150nA
TPS7A02: 25nA
PMEG60T20ELR: 65nA

Shutdown
TPS3839: 150nA
TPS7A02: 3nA
PMEG60T20ELR: 60nA

This pull down resistor ensures that the gate is properly pulled to GND when VBUS and VCOIL are not connected.

X2SON-4 1x1mm



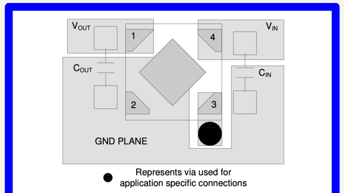


Figure 8-6. Layout Example for the DQN Package

3.3V current draw estimation:

STM32 absolute max: <= 130mA
Pull-ups: 33uA/Pull-up -> max 1mA
I2C MUX: <1mA
I2C Pull-ups: 2.2mAx2 ~5mA
Fault LEDs: 2mA/LED -> max 36mA
RGB LED: (1mA + 3x5mA)x1.25 = 20mA

Total Max: 193mA < 200mA

Nanopower IQ, 25-nA, 200-mA, Low-Dropout Voltage Regulator With Fast Transient Response paired with 150-nA, Ultralow Power, Supply Voltage Monitor

Test Points

Net	Test point	Label
3V3_EN	TP701	3V3_EN
+3V3	TP702	+3V3
+VDD	TP703	+VDD

Comments:

Laboratory: Integrated Actuators Laboratory — EPFL

Variant: Preliminary

Board Name: Plume

Project Name: Smart Footwear for Diabetic Foot Care

Sheet Title: Power - Path & Generation

File Name: Power_Path_Generation.kicad_sch

Designer: Théo Heng

Date: 2025-04-05

Revision: 1.0

Sheet Path: /Project Architecture/Power - Path & Generation/

Supervisor: Maël Dagon, Paolo Germano

Size: A4

[8] Logic - I2C Mux

DESIGN NOTE - I2C pull-Up resistors:

$R_{MIN} = (VDD_{MAX} - VOL_{MAX}) / IOL$
System I/O voltage: VDD = 3.3V +- 5% -> 3.47V
Low level output volatge (I2C specs): VOL_{MAX} = 0.4V
Low level output current (I2C specs): IOL = 3mA
Rmin = (3.47V - 0.4V) / 3mA ≈ 1kΩ

$R_{MAX} \approx (1.18 \times tr_{MAX}) / Cb_{MAX}$
Standard mode (I2C specs): tr_{MAX} = 1000ns
Fast mode (I2C specs): tr_{MAX} = 300ns

The maximum bus capacitance for an I2C bus must not exceed 400 pF for fast-mode operation. The bus capacitance can be approximated by adding the capacitance of the STM32, C_{STM}, the TCA9546A, C_{TCA}, the capacitance of wires/connections/traces, C_{TRACE}, and the capacitance of each individual slave (driver) on a given channel C_{DRV}. If multiple channels will be activated simultaneously, each of the slaves on all channels will contribute to total bus capacitance.

C_{STM} worst case = (not speciefied in the datasheet, we assume 10pF x 2 = 20pF)
C_{TCA_IN} worst case = 19pF x 2 = 38pF on the SCL, SDA lines
C_{TCA_OUT} worst case = 8pF x 2 = 16pF on the SC3-SC0, SD3-SD0 lines
C_{DRV} worst case = (not speciefied in the datasheet, we assume 8pF x 2 = 16pF)
C_{TRACE} = nb of traces x (lenght of a trace / 25mm) X 2.5pF
C_{TRACE} = 2 x (75mm / 25mm) X 2.5pF = 15pF

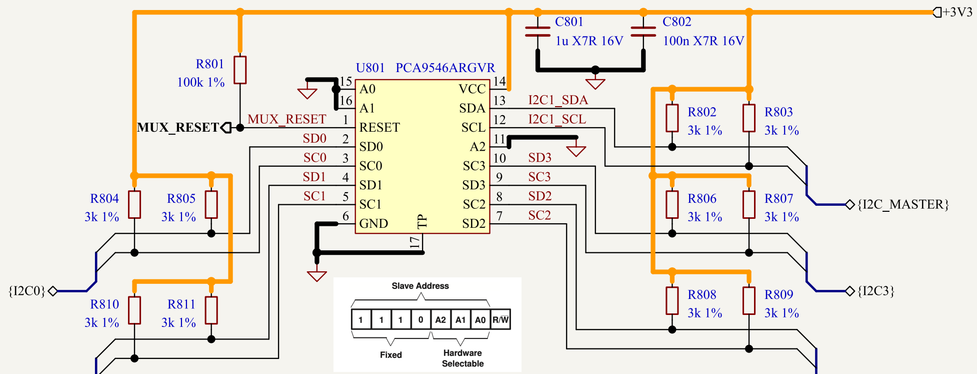
For one active channel:
$Cb_{MAX} = C_{STM} + C_{TCA\_IN} + C_{TCA\_OUT} + 9 \times C_{DRV} + C_{TRACE}$
Cb_{MAX} = 20pF + 38pF + 16pF + 9 x 16pF + 15pF ≈ 233pF
-> R_{MAX} = (1.18 x 300ns) / 113pF ≈ 1519Ω

To be safe, a value of 1k5Ω is chosen. Since both the master I2C lines and fanned channels need pull ups, there will be 2 resistors in parallel, when a channel is activated. Therefore, 3kΩ resistors are chosen, in order to get 1k5Ω.

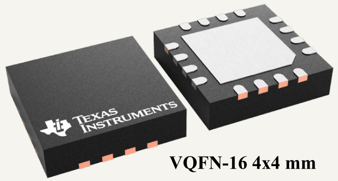
For two active channel:
$Cb_{MAX} = C_{STM} + C_{TCA\_IN} + 2x\ C_{TCA\_OUT} + 18 \times C_{DRV} + 1.66 \times C_{TRACE}$
Cb_{MAX} = 20pF + 38pF + 32pF + 18 x 16pF + 25pF ≈ 403pF > 400

Therefore, only one channel can be enabled at a time, meaning that 9 drivers only can be driven simultaneously.

Smaller resistors decrease rise time but increase power consumption. In our case: I = 3V3 / 1500 ≈ 2.2mA



Device 7-bits Adress: 0b1110000 = 0h70
Device 8-bits Write Adress: 0b11100000 = 0hE0
Device 8-bits Read Adress: 0b11100001 = 0hE1



VQFN-16 4x4 mm

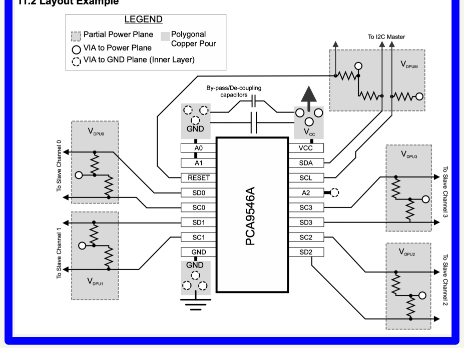
Low Voltage 4-Channel I2C and SMBus Switch with Reset Function

Current analysis:
Normal:
PCA9546A = 3uA
Pull-ups = (3.3/1500) x 2 x 0.5 = 2.2mA
Standby:
PCA9546A = 1uA
Pull-ups: = 0uA

MUX_RESET — TP801 MUX_RESET
+3V3 — TP802 +3V3

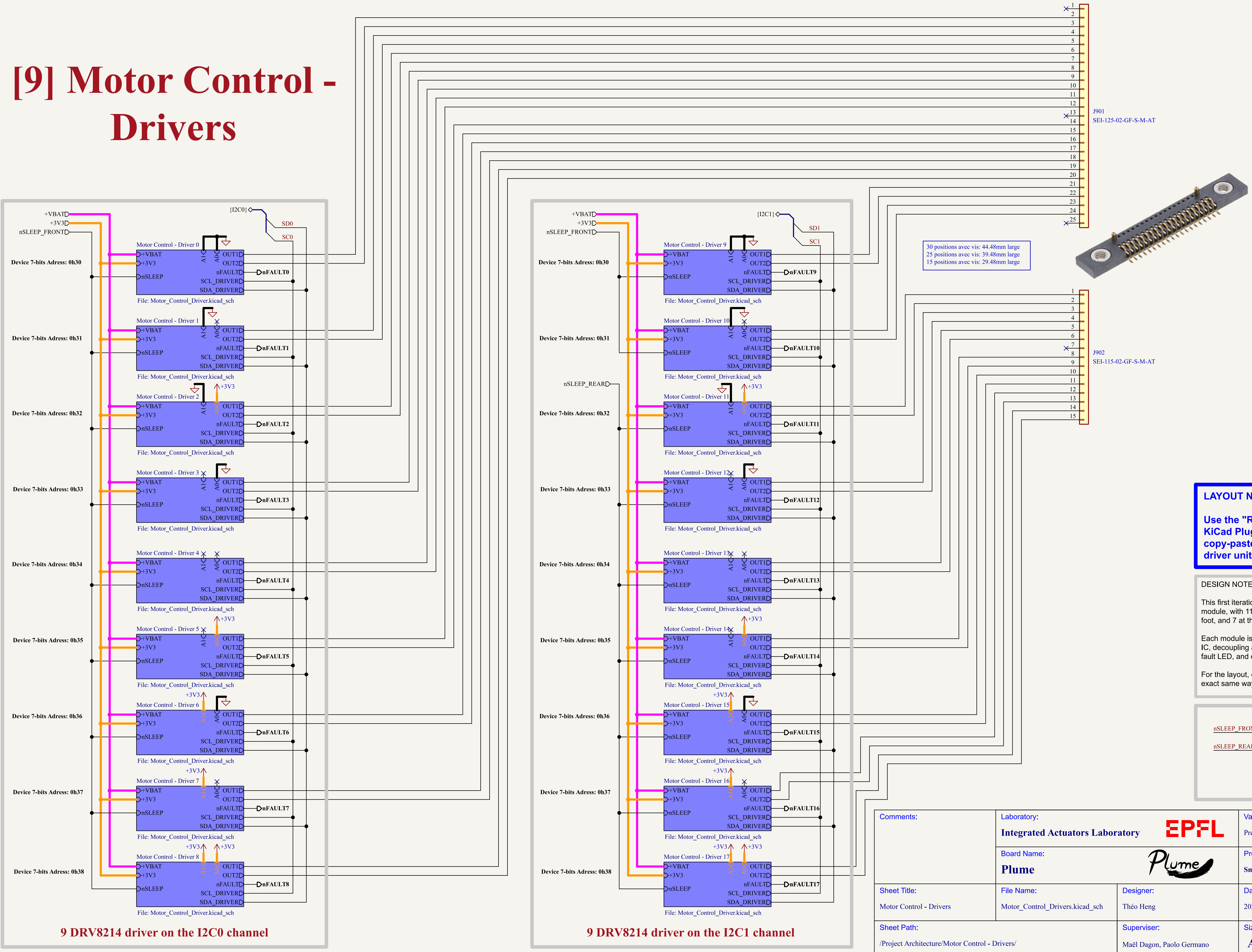
Test Points

11.2 Layout Example



Comments:	Laboratory: Integrated Actuators Laboratory (EPFL)			Variant: Preliminary	
	Board Name: Plume			Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Logic - I2C Mux	File Name: Logic_I2C_Mux.kicad_sch	Designer: Théo Heng		Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Logic - I2C Mux/		Superviser: Maël Dagon, Paolo Germano		Size: A4	Sheet: 8 of 31

[9] Motor Control - Drivers



LAYOUT NOTE:

Use the "Replicate Layout" KiCad Plugin to layout copy-paste the layout of each driver unit.

DESIGN NOTE:

This first iteration implements 18 drivers module, with 11 of them used at the front of the foot, and 7 at the rear.

Each module is similar, with the DRV8214RTER IC, decoupling and bulk capacitors, test points, fault LED, and current sense resistor.

For the layout, every module are routed in the exact same way.

nSLEEP_FRONT — TP901 nSLEEP_FRONT

nSLEEP_REAR — TP902 nSLEEP_REAR

Test Points

Comments:	Laboratory: Integrated Actuators Laboratory (EPFL)		Variant: Preliminary
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care
Sheet Title: Motor Control - Drivers	File Name: Motor_Control_Drivers.kicad_sch	Designer: Théo Heng	Date: 2025-04-05 / Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/		Supervisor: Maël Dagon, Paolo Germano	Size: A3 / Sheet: 9 of 31

[10] Motor Control - Driver 10

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

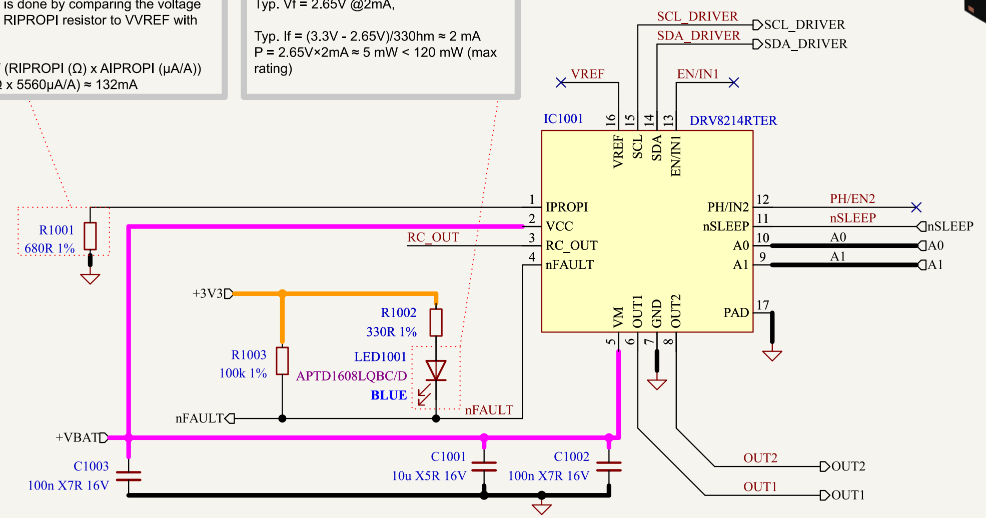
The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

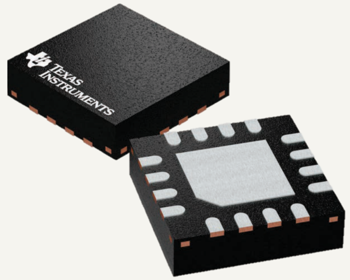
ITRIP (A) = VVREF (V) / (RIPROPI (Ω) x AIPROPI (μA/A))
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

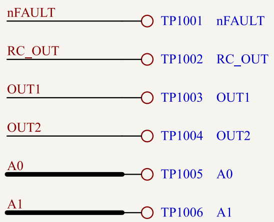
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 0/		Superviser: Maël Dagon, Paolo Germano	Size: A4	Sheet: 10 of 31

[11] Motor Control - Driver 11

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

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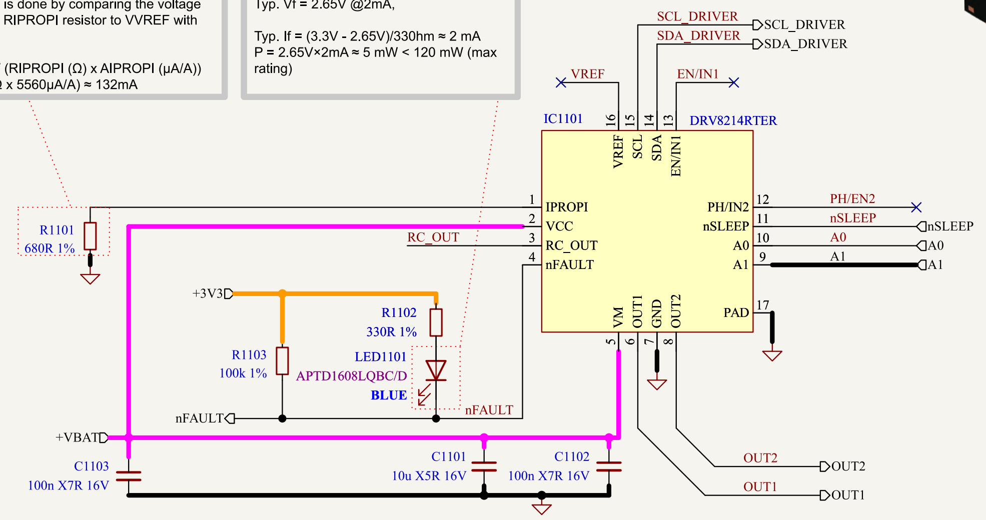
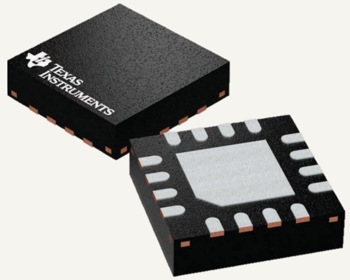
ITRIP (A) = 0.5V / (680Ω x 5560µA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

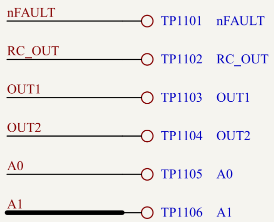
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL			Variant: Preliminary
	Board Name: Plume			Project Name: Smart Footwear for Diabetic Foot Care
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 1/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 11 of 31

[12] Motor Control - Driver 12

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

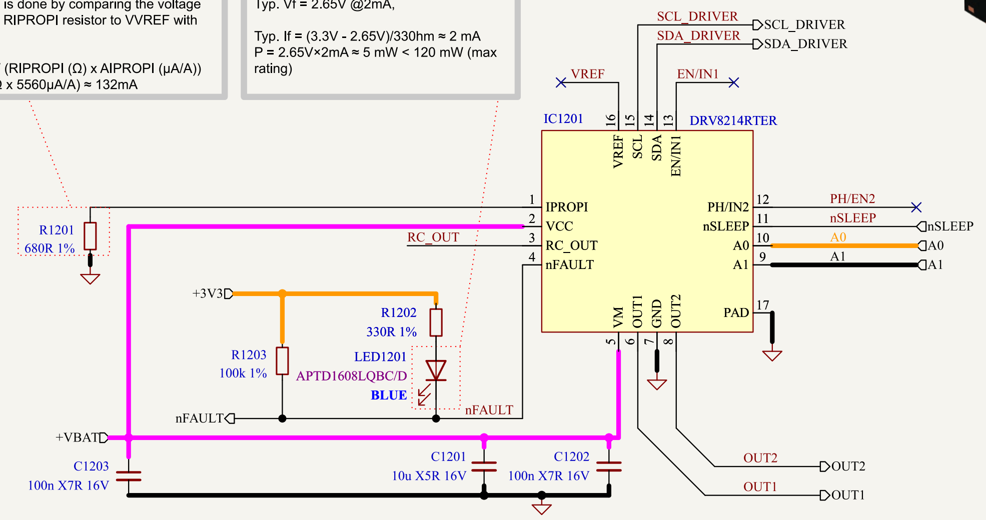
The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

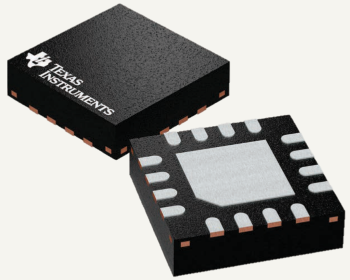
ITRIP (A) = VVREF (V) / (RIPROPI (Ω) x AIPROPI (μA/A))
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

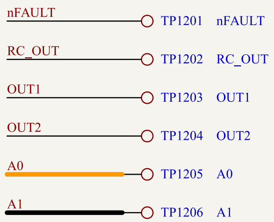
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 2/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 12 of 31

[13] Motor Control - Driver 13

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

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DESIGN NOTE - IPROPI Resistor:

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ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

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APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
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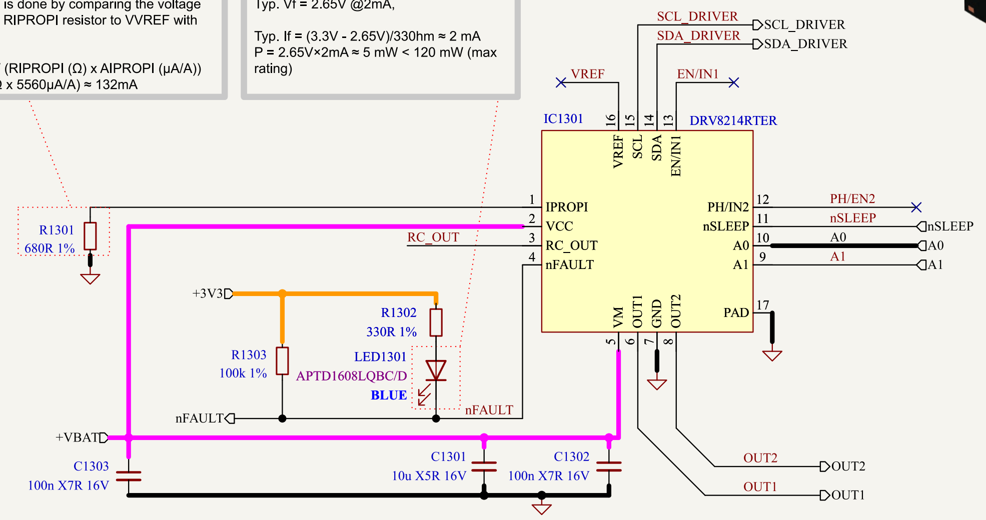
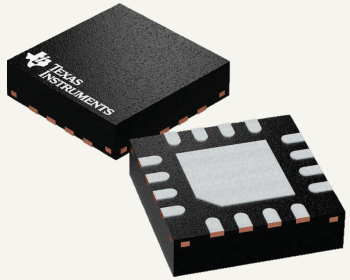
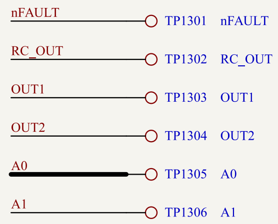
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: **Plume**		Project Name: **Smart Footwear for Diabetic Foot Care**	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 3/		Supervisor: Maël Dagon, Paolo Germano	Size: **A4**	Sheet: **13** of **31**

[14] Motor Control - Driver 14

DESIGN NOTE - Bulk Capacitance:

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The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
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• The acceptable voltage ripple
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DESIGN NOTE - IPROPI Resistor:

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ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

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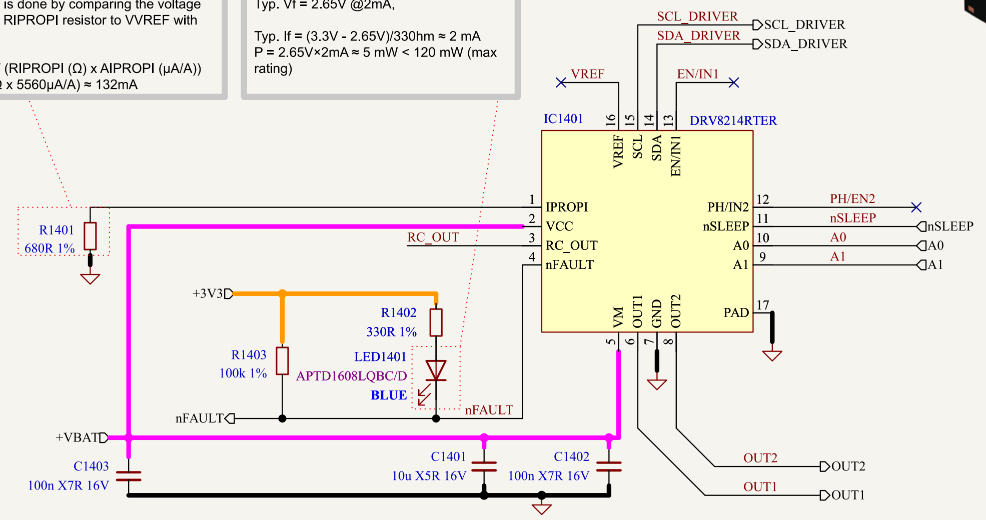
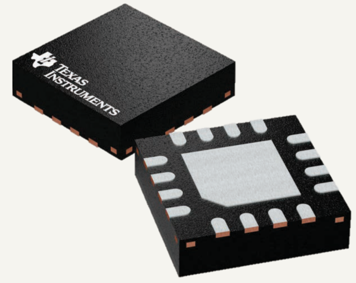
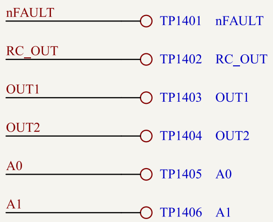




WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL	Variant: Preliminary	
	Board Name: Plume	Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05 / Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 4/		Superviser: Maël Dagon, Paolo Germano	Size: A4 / Sheet: 14 of 31

[15] Motor Control - Driver 15

DESIGN NOTE - Bulk Capacitance:

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• The highest current required by the motor system
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DESIGN NOTE - IPROPI Resistor:

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ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
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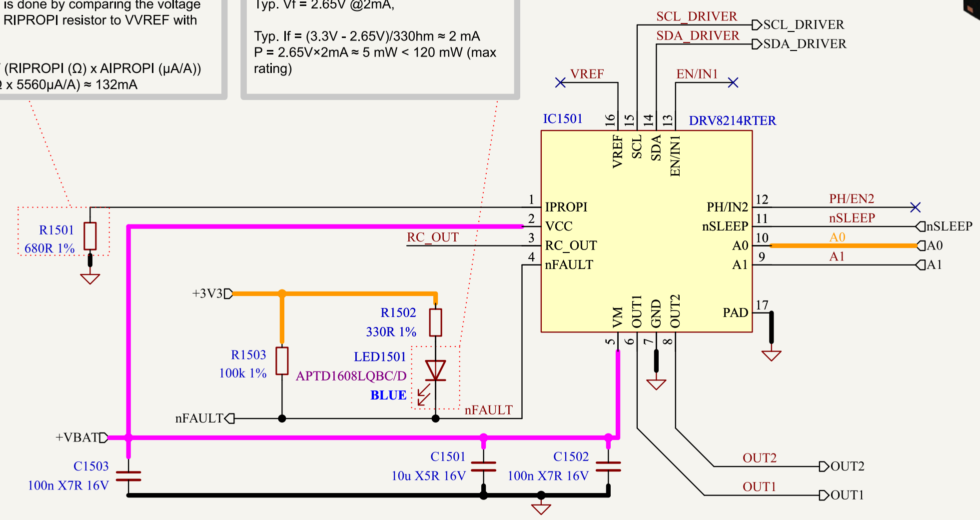
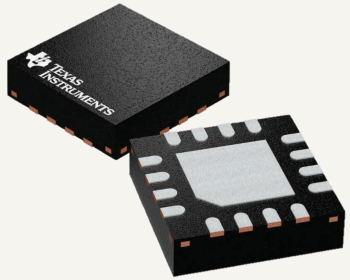
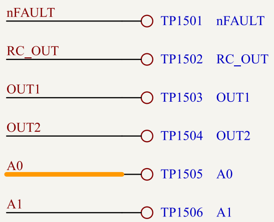




WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 5/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 15 of 31

[16] Motor Control - Driver 16

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
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DESIGN NOTE - FAULT LED:

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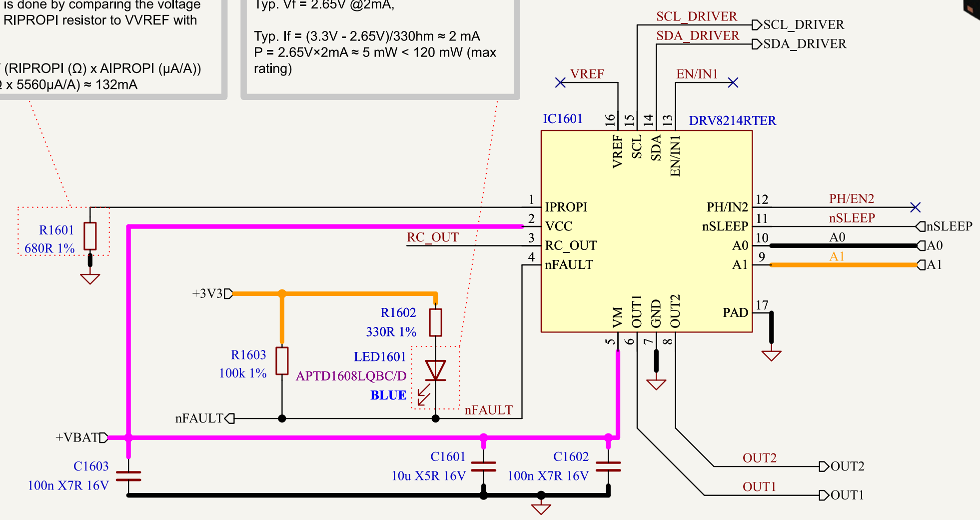
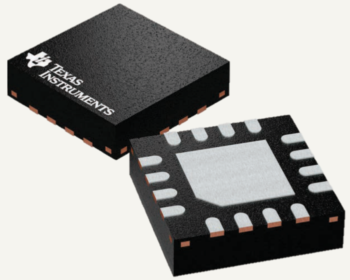
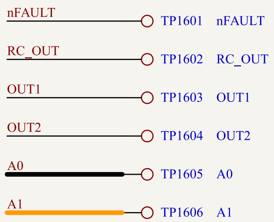
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)




WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 6/		Superviser: Maël Dagon, Paolo Germano	Size: A4	Sheet: 16 of 31

[17] Motor Control - Driver 17

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

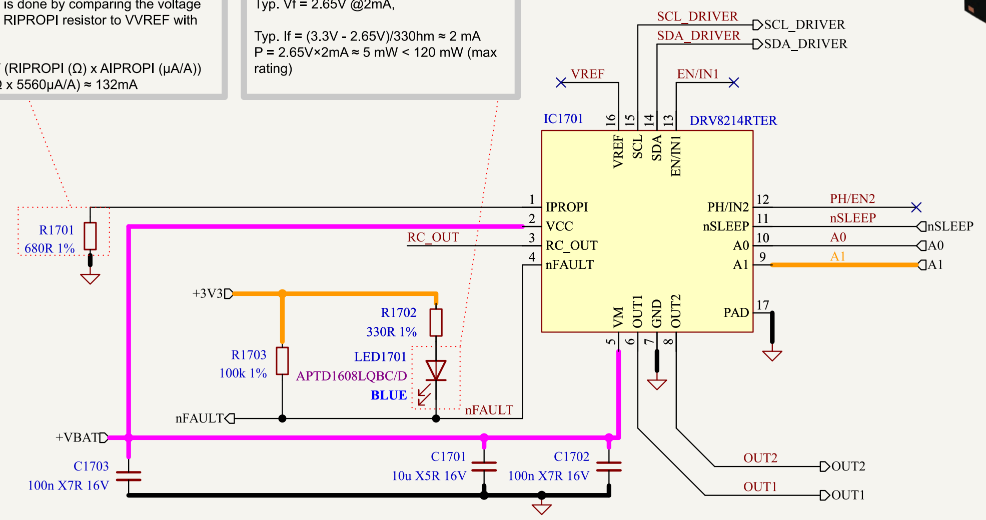
The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

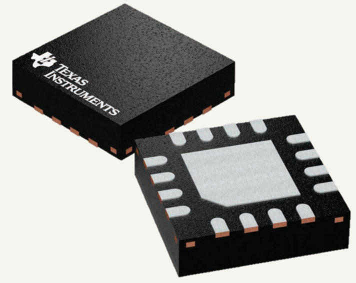
ITRIP (A) = VVREF (V) / (RIPROPI (Ω) x AIPROPI (μA/A))
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

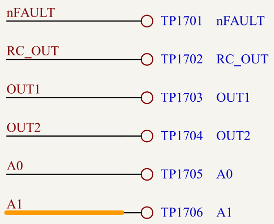
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL	Variant: Preliminary	
	Board Name: Plume	Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05 / Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 7/		Supervisor: Maël Dagon, Paolo Germano	Size: A4 / Sheet: 17 of 31

[18] Motor Control - Driver 18

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

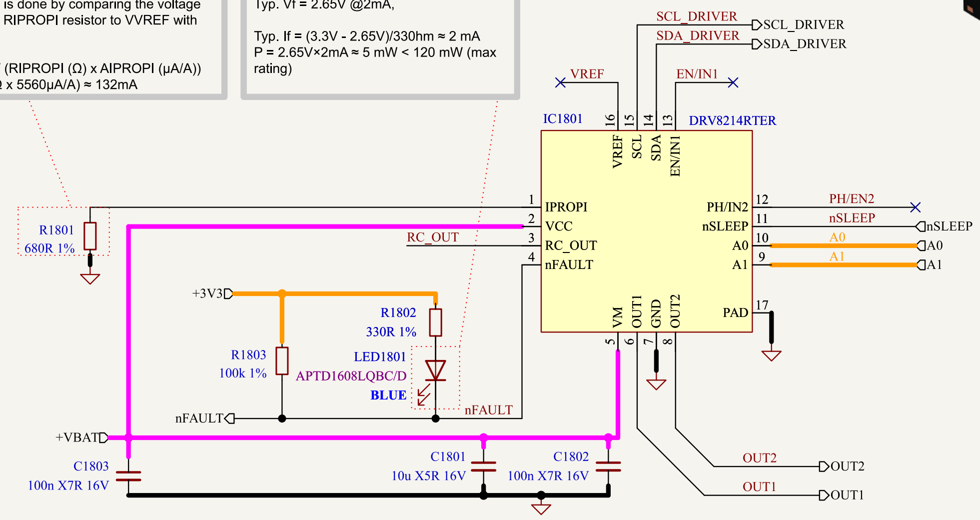
The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

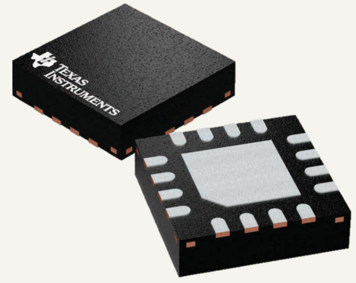
ITRIP (A) = VVREF (V) / (RIPROPI (Ω) x AIPROPI (μA/A))
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

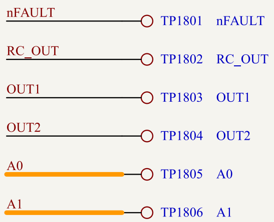
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:

Laboratory: EPFL

Variant: Preliminary

Board Name: Plume

Project Name: Smart Footwear for Diabetic Foot Care

Sheet Title: Motor Control - Driver

File Name: Motor_Control_Driver.kicad_sch

Designer: Théo Heng

Date: 2025-04-05

Revision: 1.0

Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 8/

Superviser: Maël Dagon, Paolo Germano

Size: A4

Sheet: 18 of 31

[19] Motor Control - Driver 19

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

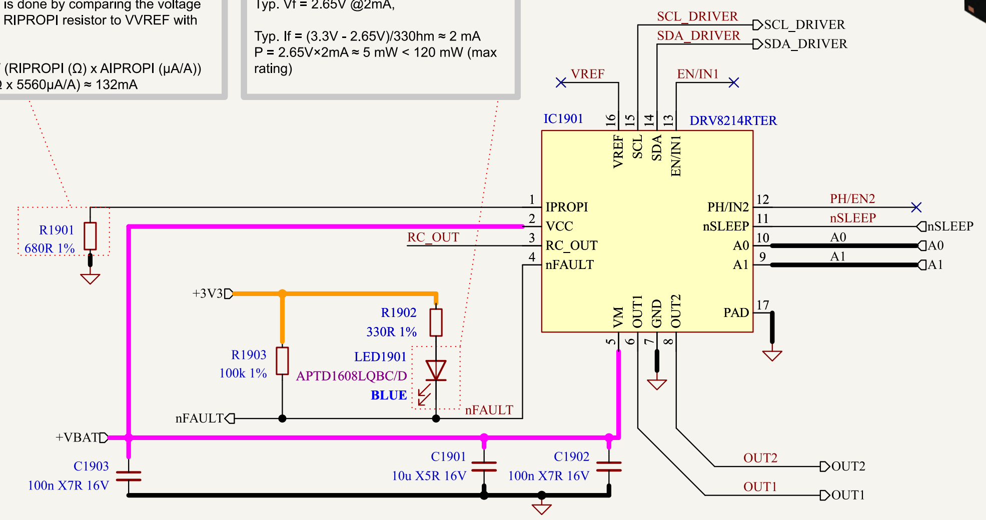
The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

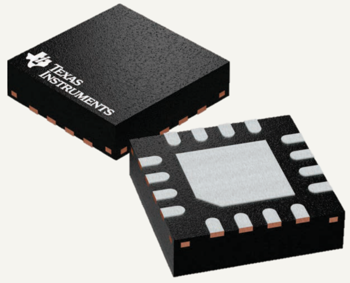
ITRIP (A) = VVREF (V) / (RIPROPI (Ω) x AIPROPI (μA/A))
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation

Net	Test point	Label
nFAULT	TP1901	nFAULT
RC_OUT	TP1902	RC_OUT
OUT1	TP1903	OUT1
OUT2	TP1904	OUT2
A0	TP1905	A0
A1	TP1906	A1

Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 9/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 19 of 31

[20] Motor Control - Driver 20

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

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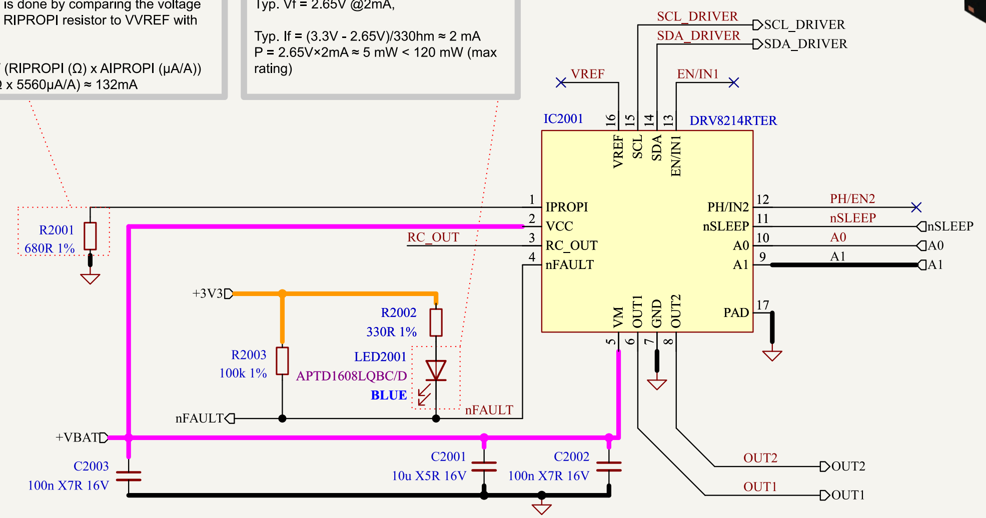
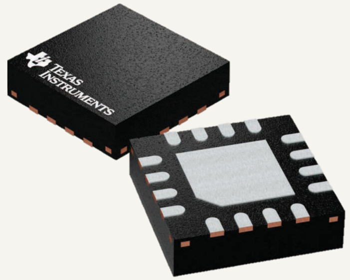
ITRIP (A) = 0.5V / (680Ω x 5560µA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

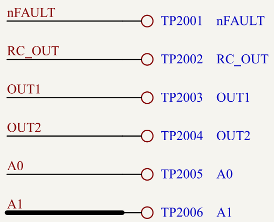
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL	Variant: Preliminary	
	Board Name: Plume	Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05 / Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 10/		Supervisor: Maël Dagon, Paolo Germano	Size: A4 / Sheet: 20 of 31

[21] Motor Control - Driver 21

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

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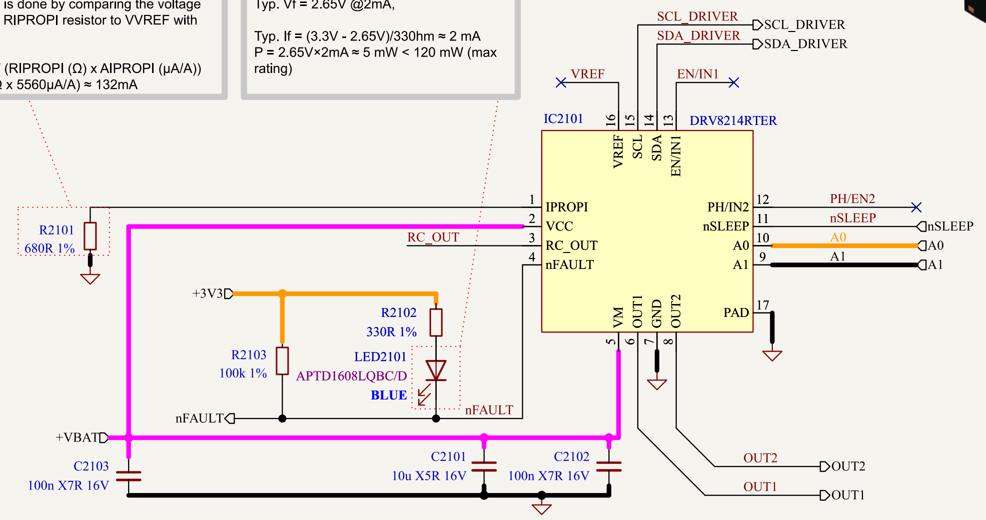
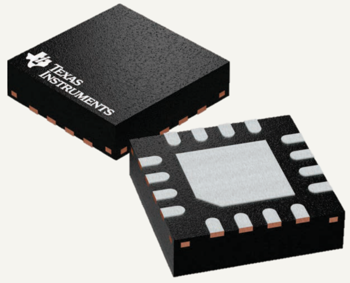
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

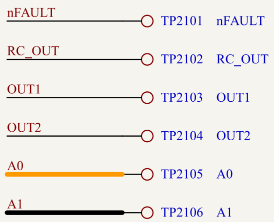
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: **Plume**	Plume	Project Name: **Smart Footwear for Diabetic Foot Care**	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 11/		Superviser: Maël Dagon, Paolo Germano	Size: **A4**	Sheet: **21** of **31**

[22] Motor Control - Driver 22

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

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ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

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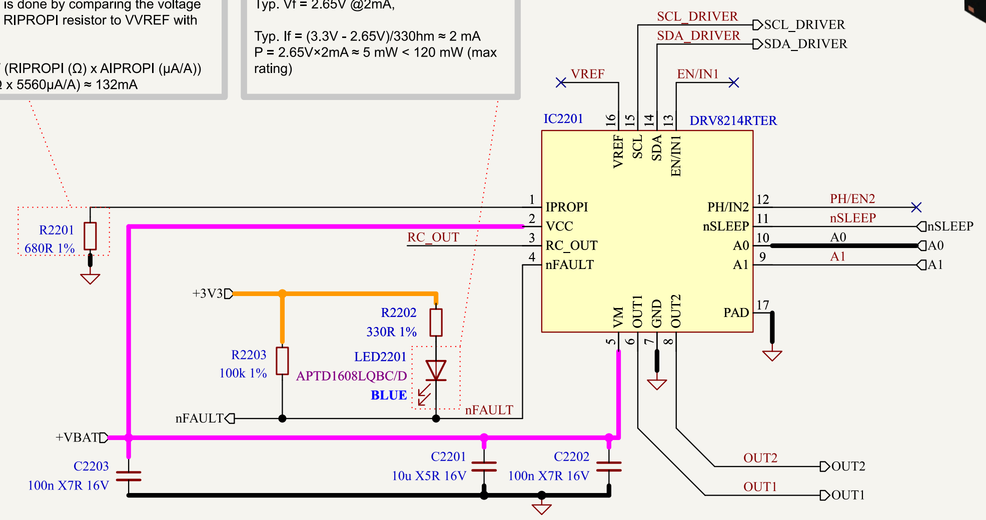
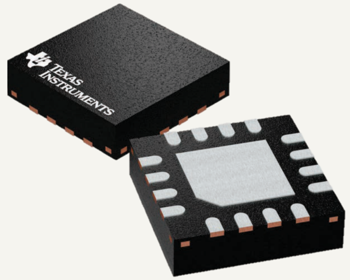
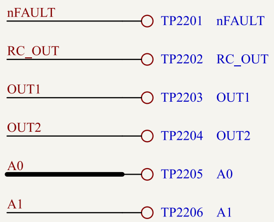




WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 12/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 22 of 31

[23] Motor Control - Driver 23

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
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• The amount of parasitic inductance between the power supply and motor system
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• The type of motor used (brushed DC, brushless DC, stepper)
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DESIGN NOTE - IPROPI Resistor:

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DESIGN NOTE - FAULT LED:

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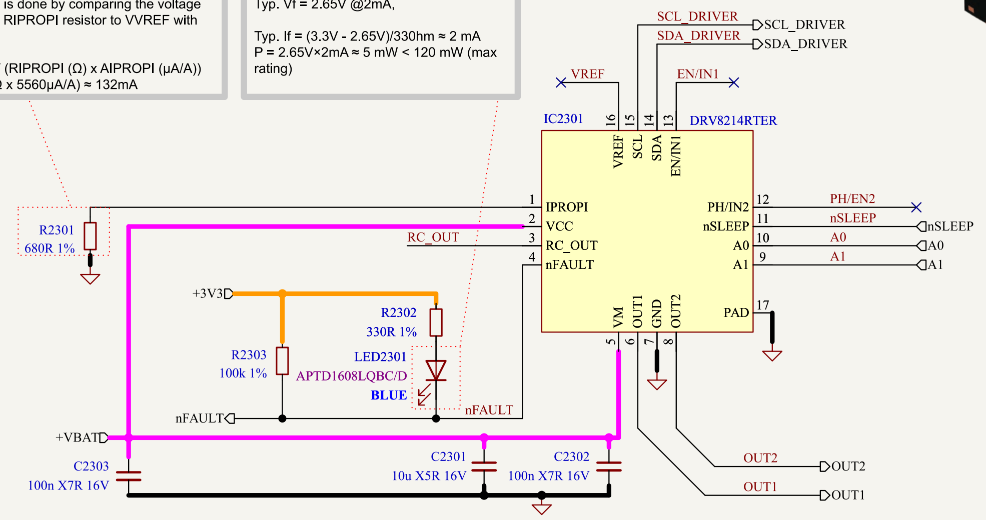
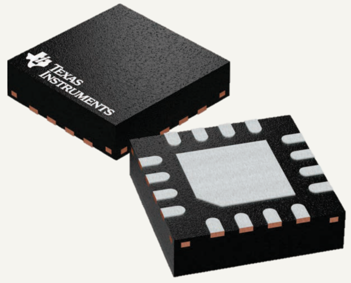
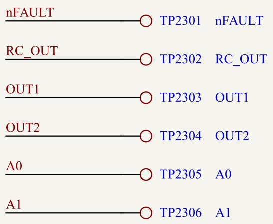




WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL			Variant: Preliminary	
	Board Name: **Plume**			Project Name: **Smart Footwear for Diabetic Foot Care**	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng		Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 13/		Supervisor: Maël Dagon, Paolo Germano		Size: **A4**	Sheet: **23** of **31**

[24] Motor Control - Driver 24

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
- The highest current required by the motor system
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DESIGN NOTE - FAULT LED:

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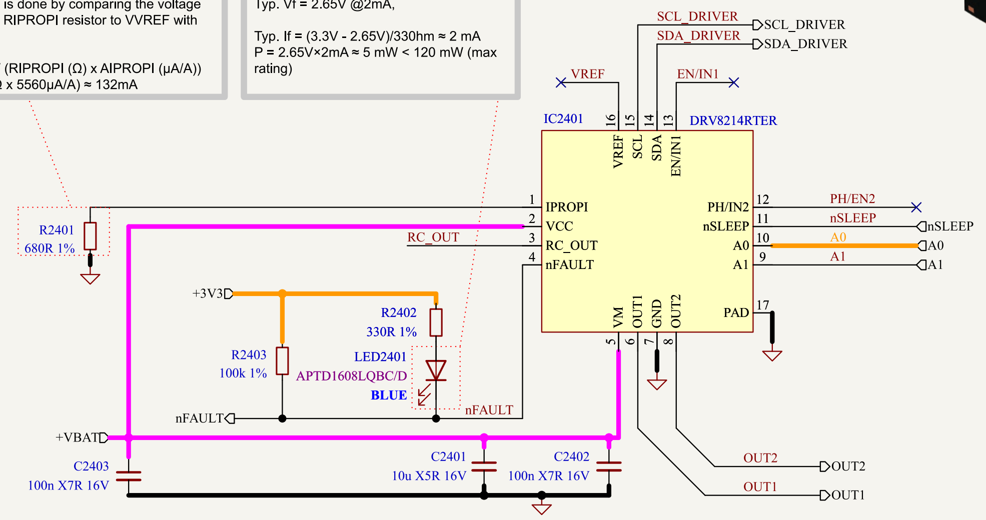
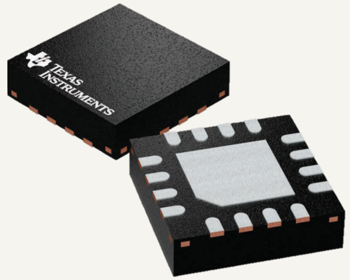
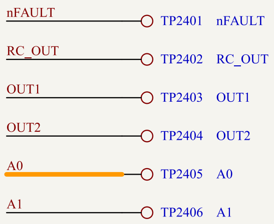




WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 14/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 24 of 31

[25] Motor Control - Driver 25

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
• The capacitance of the power supply and ability to source current
• The amount of parasitic inductance between the power supply and motor system
• The acceptable voltage ripple
• The type of motor used (brushed DC, brushless DC, stepper)
• The motor braking method

The inductance between the power supply and motor drive system limits how the rate current can change from the power supply. If the local bulk capacitance is too small, the system responds to excessive current demands or dumps from the motor with a change in voltage. When adequate bulk capacitance is used, the motor voltage remains stable and high current can be quickly supplied.

The data sheet generally provides a recommended value, but system-level testing is required to determine the appropriate sized bulk capacitor.

The voltage rating for bulk capacitors should be higher than the operating voltage, to provide margin for cases when the motor transfers energy to the supply.

DESIGN NOTE - IPROPI Resistor:

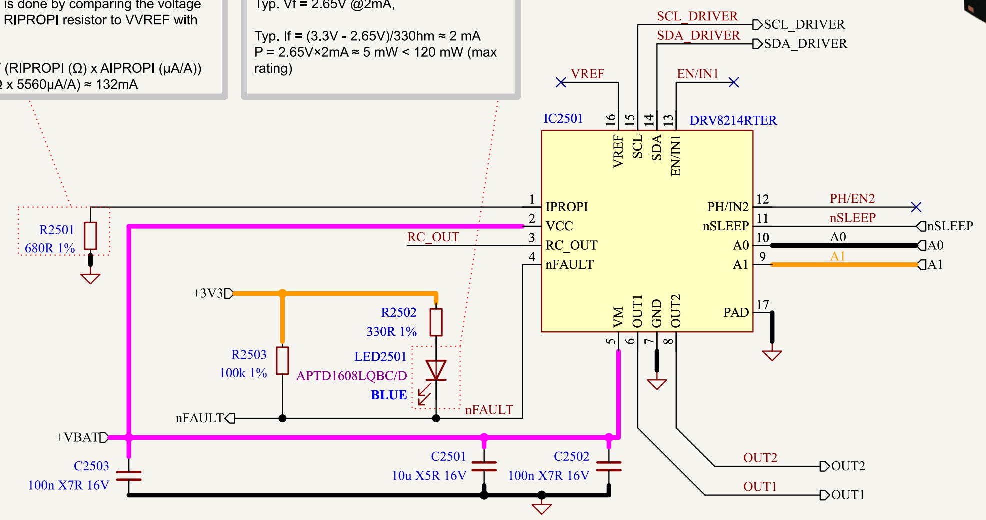
The current regulation threshold (ITRIP) is set through a combination of the VREF voltage and IPROPI output resistor (RIPROPI). This is done by comparing the voltage drop across the external RIPROPI resistor to VVREF with an internal comparator

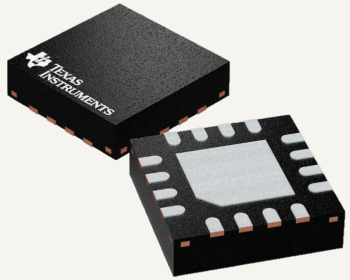
ITRIP (A) = VVREF (V) / (RIPROPI (Ω) x AIPROPI (μA/A))
ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

DESIGN NOTE - FAULT LED:

APTD1608LQBC/D has a typical luminous intensity of 20mcd (millicandela) @2mA
Typ. Vf = 2.65V @2mA,

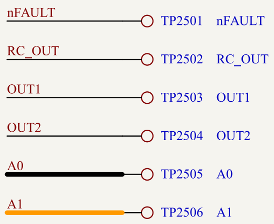
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 15/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 25 of 31

[26] Motor Control - Driver 26

DESIGN NOTE - Bulk Capacitance:

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The amount of local capacitance needed depends on a variety of factors, including:
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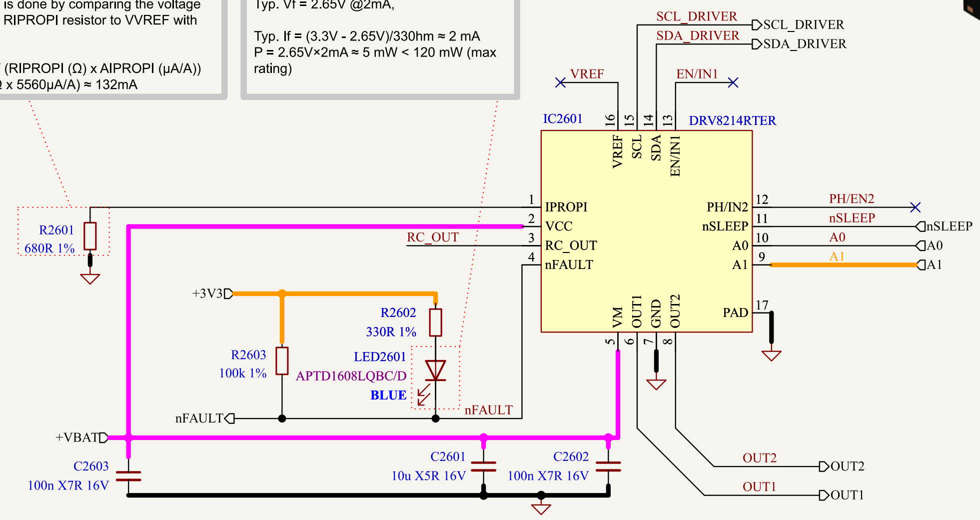
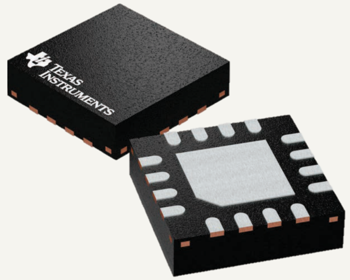
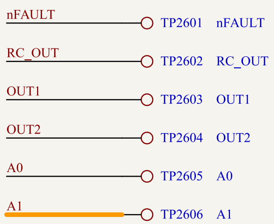
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 16/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 26 of 31

[27] Motor Control - Driver 27

DESIGN NOTE - Bulk Capacitance:

Having appropriate local bulk capacitance is an important factor in motor drive system design. Having more bulk capacitance is generally beneficial, while the disadvantages are increased cost and physical size.

The amount of local capacitance needed depends on a variety of factors, including:
• The highest current required by the motor system
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ITRIP (A) = 0.5V / (680Ω x 5560μA/A) ≈ 132mA

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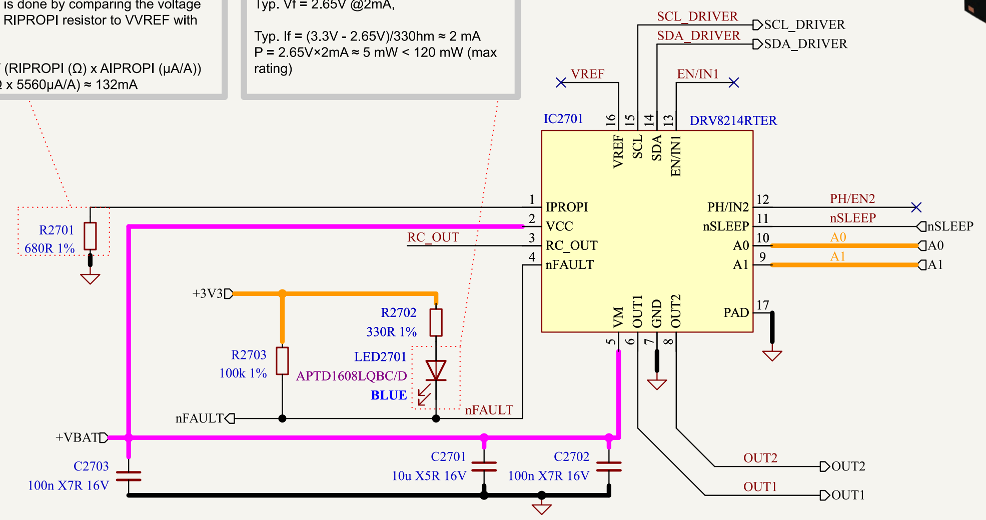
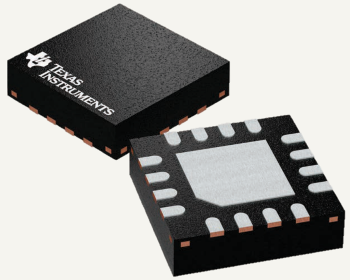
Typ. Vf = 2.65V @2mA,

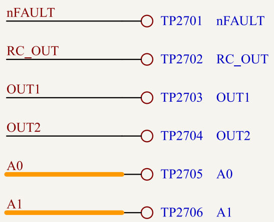
Typ. If = (3.3V - 2.65V)/330hm ≈ 2 mA
P = 2.65V×2mA ≈ 5 mW < 120 mW (max rating)





WQFN-16 3x3 mm

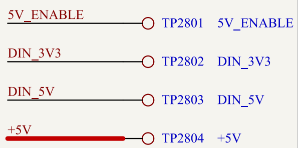
DRV8214 2-A Brushed DC Motor Driver with Ripple Counting, Stall Detection, and Speed Regulation



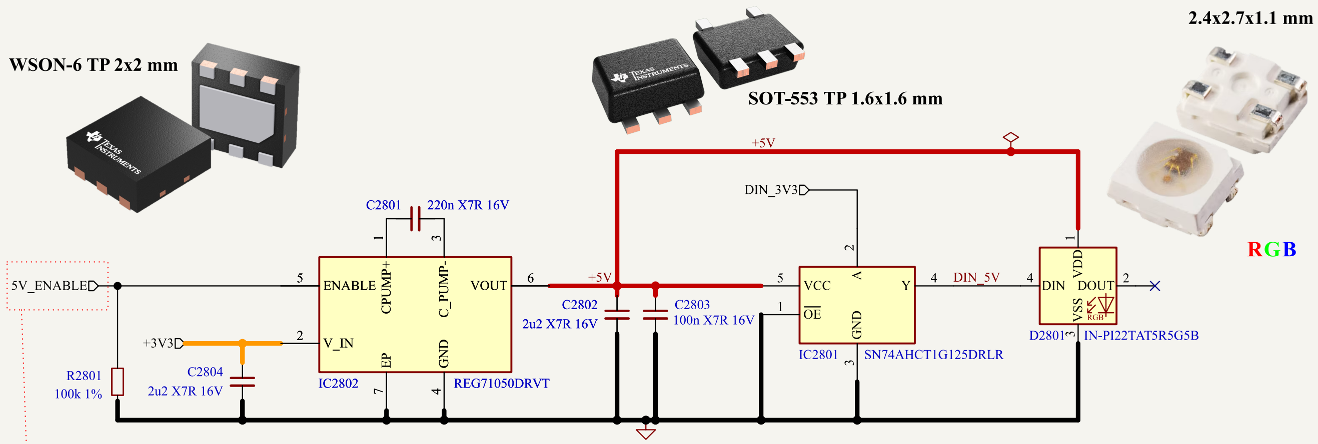
Test Points

Comments:	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Motor Control - Driver	File Name: Motor_Control_Driver.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Motor Control - Drivers/Motor Control - Driver 17/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 27 of 31

[28] User - RGB LED Indicator



Test Points



Hardware Enable/Disable pin (high=enable)
DO NOT LEAVE FLOATING
-> 100kΩ pull down added

60mA Buck-Boost Charge Pump, with 5V level shifter to control 4-pin RGB LED

Current analysis:

Normal:
REG71050: 65uA
SN74AHCT1G125: 10uA
IN-PI22TAT5R5G5B: 1mA

Shutdown:
REG71050: 10nA
SN74AHCT1G125: OFF
IN-PI22TAT5R5G5B: OFF

11.2 Layout Example

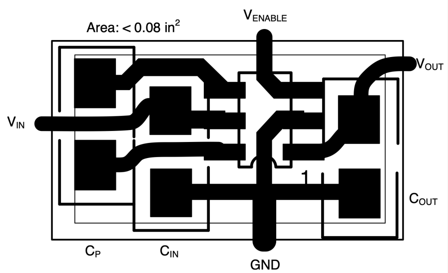


Figure 24. Suggested PCB Design for Minimum Ripple

Comments: This LED was chosen as it is relatively small compared to other well-known alternatives (e.g. WS2812B). The saved space is used to provide proper 5V supply and logic. This LED might work with 3V3 but this approach is safer.	Laboratory: EPFL		Variant: Preliminary	
	Board Name: **Plume**		Project Name: **Smart Footwear for Diabetic Foot Care**	
Sheet Title: User - RGB LED Indicator	File Name: User_RGB_LED_Indicator.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/User - RGB LED Indicator/		Superviser: Maël Dagon, Paolo Germano	Size: **A4**	Sheet: **28** of **31**

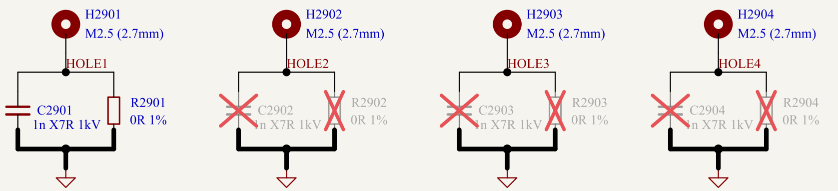
[29] Misc - Mounting Holes

DEBUG NOTE:

HOLE 1 is connected to GND and can be very useful if used as a GND reference for multimeter debug.

DESIGN NOTE:

Fiducials are ommited due to space constraints and are in any case unecessary in the forseable future because manual assembly is required since the DRV8214 ICs, among others, are unavailable on JLCPCB parts store.



Mechanical Mounting holes

DESIGN NOTE:

In general, do not ground mounting holes that are connected to chassis if there is a risk that the chassis sends current into the PCB and dammages it or if the PCB works with high voltage and there is a risk for the user which is in contact with the chassis.

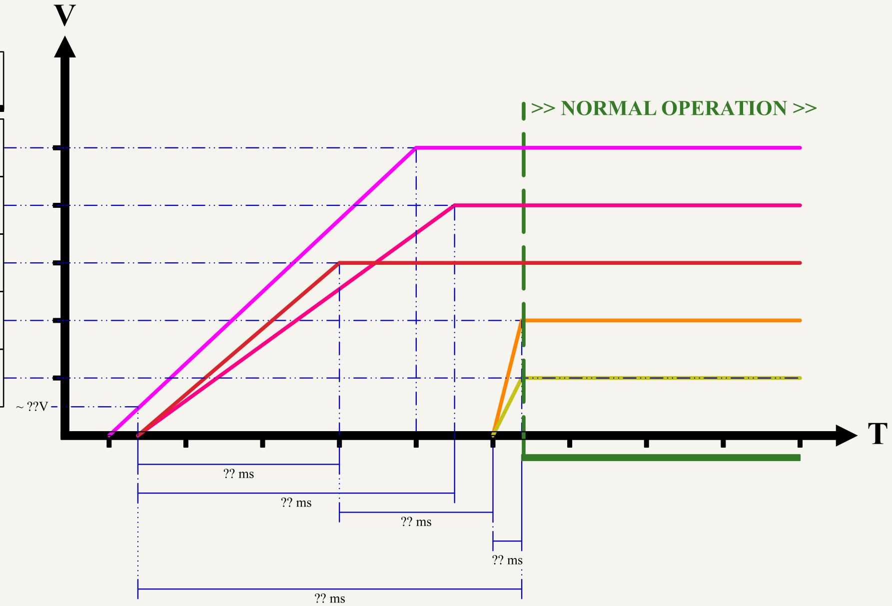
For a PCB in a metallic enclosure, the enclosure can act like a big antenna. The cavities (space between the ground plane on the pcb and the bottom metallic plane of the enclosure) cause capacitive coupling. This is because we have two metallic planes separated by a dielectric, at a separated potential, causing common mode noise. and result in the noise being amplified by the metal enclosure. Ideally, in this case, the case should be grounded. But the grounding will cause multiple return paths if multiples mounting holes are connected to GND. In that case, some current will flow in the enclosure and can give a little choc when the user touch it. This can be fine for small battery operated devices.

The best option is therefore to ground only one mounting hole.

Comments: Inspired by Amulet controller Schematics by Vincent Nguyen. How to connect mounting holes. PCB Mounting Holes	Laboratory: EPFL		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Misc - Mounting Holes	File Name: Misc_Mounting_Holes.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Project Architecture/Misc - Mounting Holes & Fiducials/		Superviser: Maël Dagon, Paolo Germano	Size: A4	Sheet: 29 of 31

[30] Power - Sequencing

NAME	SOURCE	LEVEL
+??V	SOURCE NAME	??V ± ??%
+??V	SOURCE NAME	??V ± ??%
+??V	SOURCE NAME	??V ± ??%
+??V	SOURCE NAME	??V ± ??%
+??V	SOURCE NAME	??V ± ??%



TO BE TESTED

Comments:	Laboratory: Integrated Actuators Laboratory		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Power - Sequencing	File Name: Power - Sequencing.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Power - Sequencing/		Superviser: Maël Dagon, Paolo Germano	Size: A4	Sheet: 30 of 31

[31] Revision History

DD.MM.YYYY - xxx Revision
Variant: xxx

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Comments:	Laboratory: Integrated Actuators Laboratory		Variant: Preliminary	
	Board Name: Plume		Project Name: Smart Footwear for Diabetic Foot Care	
Sheet Title: Revision History	File Name: Revision History.kicad_sch	Designer: Théo Heng	Date: 2025-04-05	Revision: 1.0
Sheet Path: /Revision History/		Supervisor: Maël Dagon, Paolo Germano	Size: A4	Sheet: 31 of 31