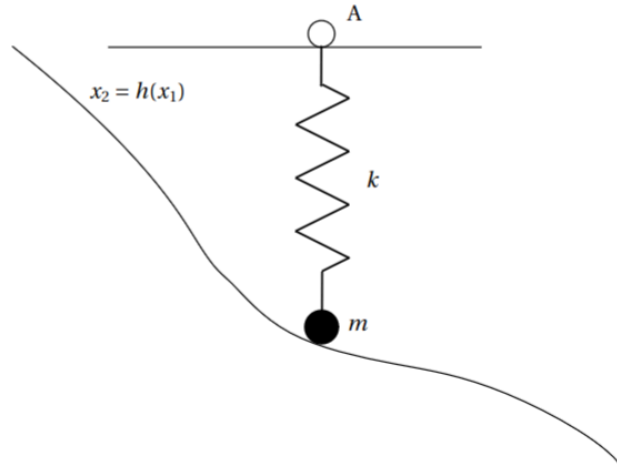


Consider the mechanical system depicted below. A ball with (point-like) mass m has the position (x_1, x_2) , where x_1 is the horizontal and x_2 the vertical coordinate. The ball is gliding without friction along a rail that is described by the relation $x_2 = h(x_1)$. Further, the ball is attached to one end of a spring, having the spring constant k . The other end of the spring (A) is gliding without friction along a horizontal rail, so that the spring is always vertical.

The forces acting on the ball are thus the spring force (assuming the neutral position of the force corresponds to $x_2 = 0$), gravity g , and the normal force from the rail.



- (a) (4 points) Determine the Lagrange function for the system. *Reminder:* Potential energy of a spring is defined as $\frac{1}{2}kp^2$ where k is spring constant and p denotes spring displacement.
- (b) (4 points) Derive a dynamic model of the system.

Consider two masses of mass m (the black balls in Fig. 1) linked by a massless rigid rod of length L . The masses are gliding without friction on a surface of equation:

$$z = \frac{1}{2}x^2 + \frac{1}{2}y^2 \quad (1)$$

- (a) (4 points) Write the Lagrange function describing the system, assuming gravity is the only external force.
- (b) (4 points) Derive the equations of motion
- (c) (3 points) What are the consistency conditions associated to the equations?

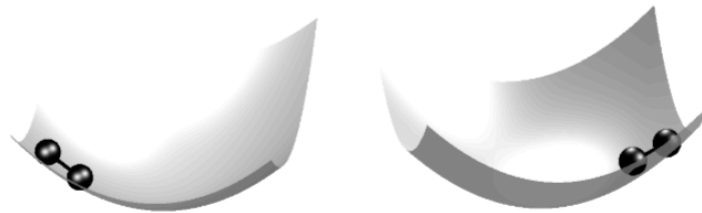


Figure 1: Illustration of the rollercoaster