**Configuration environment for instant-ngp**

* Visual studio 2019 community with C++
* CUDA 11.6.2
* Optix
* Git
* Clone original code from <https://github.com/NVlabs/instant-ngp>

**Modify transformation.json file to be compatible with drone 3d restructuring project**

* Adding <https://github.com/nickponline/dd-nerf-dataset>
* Understanding code
* Figure out requirements
* Customize camera parameter etc.
* Add more thing to make different
* Test