

# Introduction to Data Management

#### Parallel Processing

Alyssa Pittman Based on slides by Jonathan Leang, Dan Suciu, et al

Paul G. Allen School of Computer Science and Engineering University of Washington, Seattle

#### **Course Context**

- Core RDBMS
  - SQL and RA
  - Logical and Physical Database Design
  - Transactions
- Misc. RDBMS Topics
  - Distributed Relational Databases
  - Spark query language
- NoSQL

#### We Need More Power

- Humans have a tendency to tackle problems that are too big to compute
  - Breaking the enigma code (WWII)
    - Using automation (the bombe)
  - Computing rocket trajectories (Space Race)
    - Using programming languages (FORTRAN)
  - Now: Data driven applications
    - Protein folding
    - Internet of things
    - Financial forecasting
    - Weather prediction
    - Social media platforms
    - ...

#### More Data, More Problems

- The rates at which we generate and use information have outpaced the capabilities of a single computer
- Problems:
  - Need more speed
  - Need more scale

#### Parallel Computation

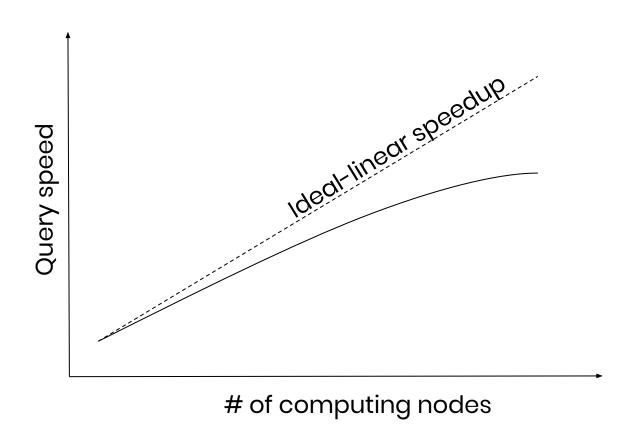
- Solution: Add more computing nodes
  - Multiple nodes  $\square$  Parallel data management
- Most all computers have multiple cores
- Distributed architecture is easily available on cloud services

### Speed Up

#### Speed up:

same data, more nodes 

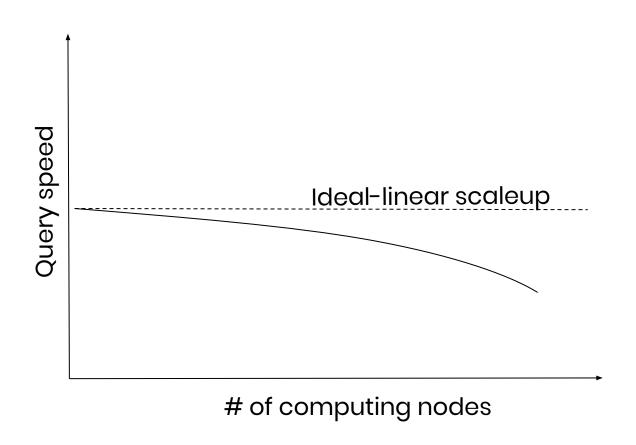
higher speed



### Scale Up

#### Scale up:

more data, more nodes  $\square$  same speed



#### Sublinear Expected Performance

- Parallel computing is not a magic bullet
- Common reasons for sublinear performance:
  - Overhead cost
    - Starting and coordinating operations on many nodes
  - Interference/Contention
    - Shared resources are not perfectly split
  - Skew
    - Process is only as fast as the slowest node

#### Implementations for Database Parallelism

#### Architecture Parallelism

- Shared Memory
- Shared Disk
- Shared Nothing\*

#### Query Parallelism

- Inter-Query Parallelism
- Intra-Query Parallelism
  - Inter-Operator Parallelism
  - Intra-Operator Parallelism\*

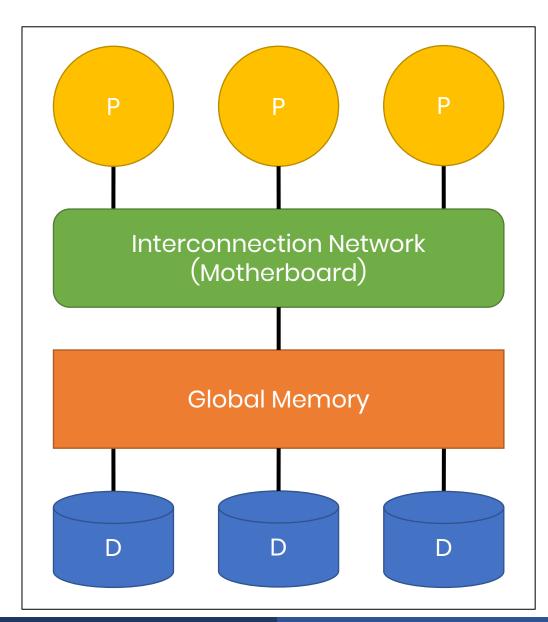
Hardware considerations

Software considerations

#### Implementations for Database Parallelism

- Architecture Parallelism
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# Shared-Memory Architecture



- Shared main memory and disks
- Your laptop or desktop uses this architecture
- Expensive to scale
- Easiest to implement on

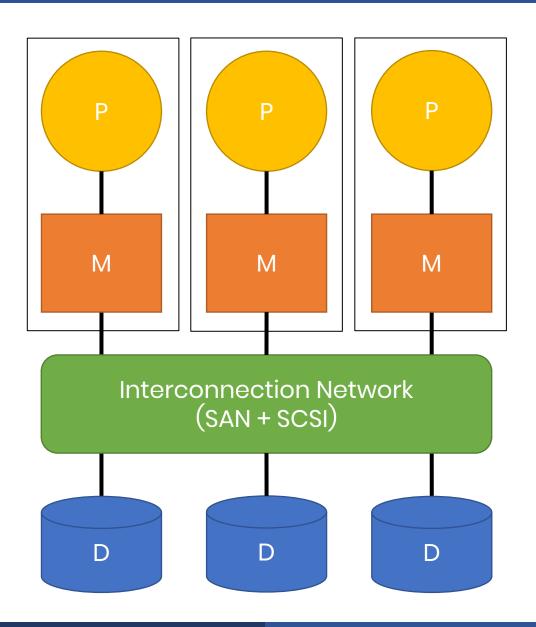








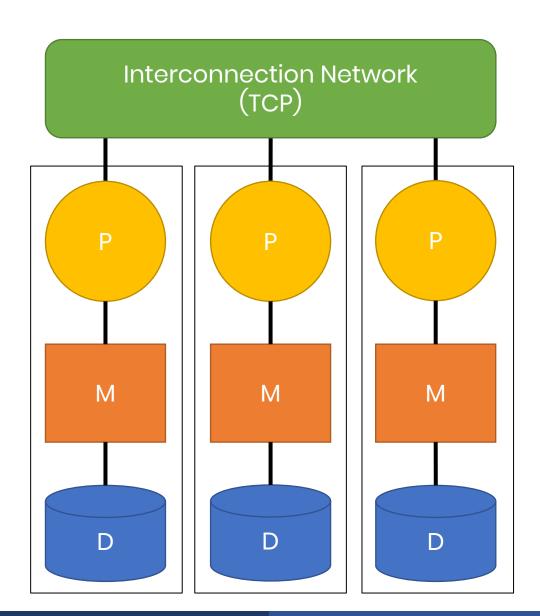
#### Shared-Disk Architecture



- Only shared disks
- No contention for memory and high availability
- Typically 1-10 machines



### Shared-Nothing Architecture\*

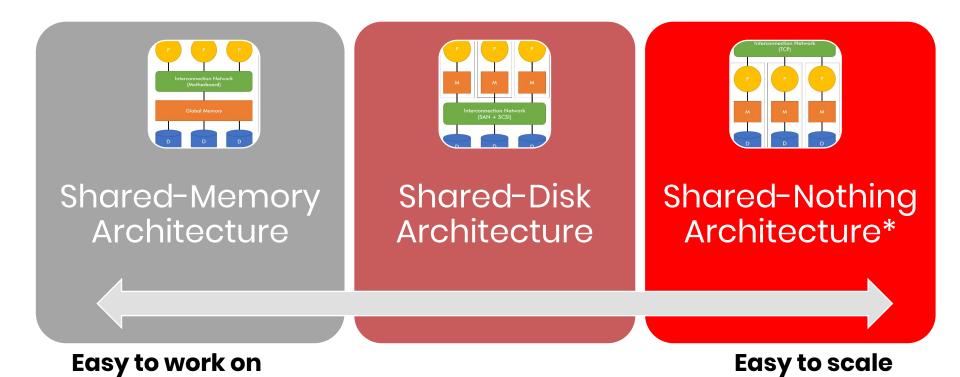


- Uses cheap, commodity hardware
- No contention for memory and high availability
- Theoretically can scale infinitely
- Hardest to implement on



#### **Architecture Tradeoffs**

Main tradeoff is administration difficulty vs ability to scale



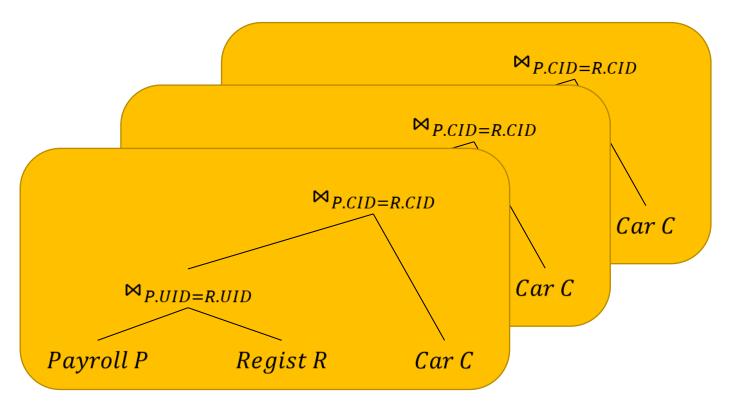
If you can't scale, your product dies, and everyone loses their job

#### Implementations for Database Parallelism

- Architecture Parallelism
  - Shared Memory
  - Shared Disk
  - Shared Nothing\*
- Query Parallelism
  - Inter-Query Parallelism
  - Intra-Query Parallelism
    - Inter-Operator Parallelism
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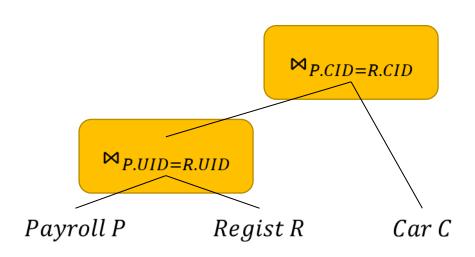
# Inter-Query Parallelism

- Each transaction is processed on a separate node
- Scales very well for lots of simple transactions



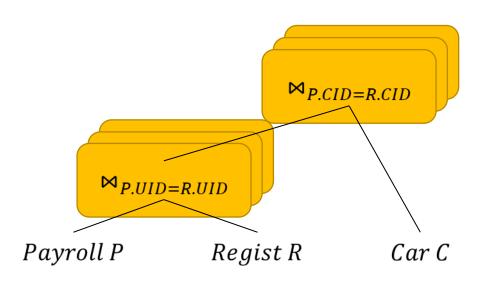
#### Inter-Operator Parallelism

- Each operator is processed on a separate node
- Scales very well for complex analytical queries



### Intra-Operator Parallelism\*

- Each operator is processed by multiple nodes
- Scales well in general



#### Shared-Nothing, Intra-Operator Database

From here, we will assume a system that consists of multiple commodity machines on a common network where nodes may carry out specified relational operations.

New problem: Where does the data go?

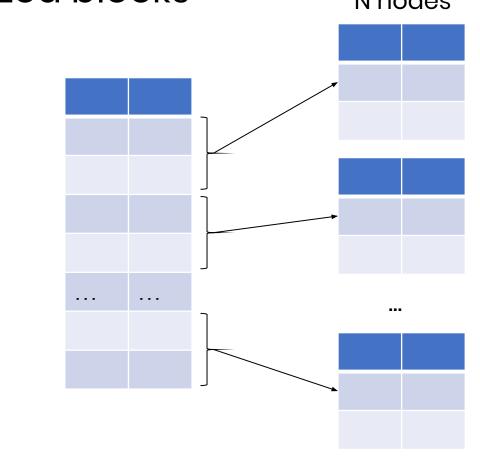
#### **Unpartitioned Table**

- Simplest choice if data can fit on a single node
- Might result in being a bottleneck

### **Block Partitioning**

B(R) = K

Tuples are horizontally partitioned arbitrarily in equally sized blocks N nodes



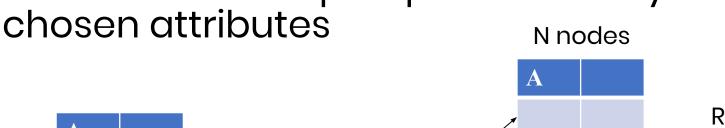
$$B(R_1) = K/N$$

$$B(R_2) = K/N$$

$$B(R_N) = K/N$$

# Hash Partitioning

Node contains tuples partitioned by hash on



h(A)

$$R_{1}$$
, 1 = h(A)%N

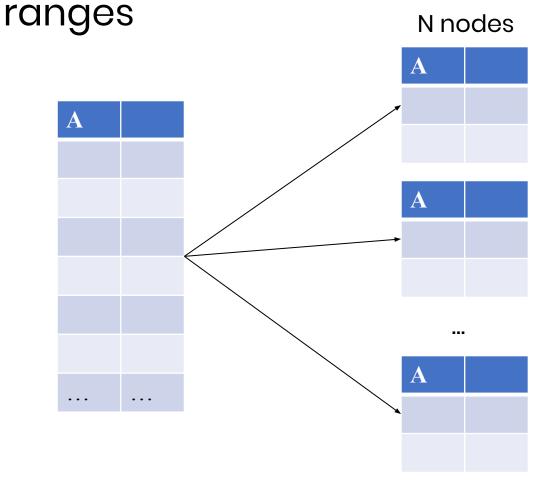
$$R_2$$
, 2 = h(A)%N

$$R_N$$
,  $0 = h(A)%N$ 

A

# Range Partitioning

Node contains tuples in chosen attribute



$$R_1$$
, -inf < A <=  $V_1$ 

$$R_2, V_1 < A <= V_2$$

$$R_{N}, V_{N} < A < inf$$

#### The Justin Bieber Effect

- Hashing data to nodes is very good when the attribute chosen approximates a uniform distribution
- Keep in mind: Certain nodes will become bottlenecks if a poorly chosen attribute is hashed

### Back to the algorithms....

So how do we get data to the right nodes for our operations?

- 1. Hash shuffle tuples
- 2. Local aggregation

```
Assume:
R is block partitioned

SELECT *
FROM R
GROUP BY R.A
```

Node 1

Node 2

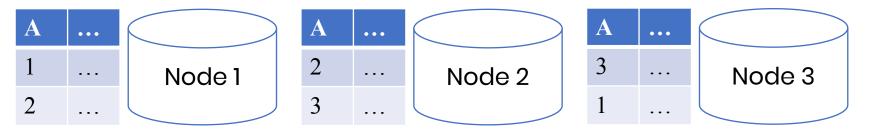
Node 3

- 1. Hash shuffle tuples
- 2. Local aggregation

Assume:
R is block partitioned

SELECT \*
FROM R
GROUP BY R.A

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- 1. Hash shuffle tuples
- 2. Local aggregation

Assume:
R is block partitioned

SELECT \*
FROM R
GROUP BY R.A

 $\gamma_{R.A}$   $\gamma_{R.A}$   $\gamma_{R.A}$ 

A	•••	
1		Node 1
2		

A	•••	
2	•••	Node 2
3		

A	•••	
3	•••	Node 3
1		

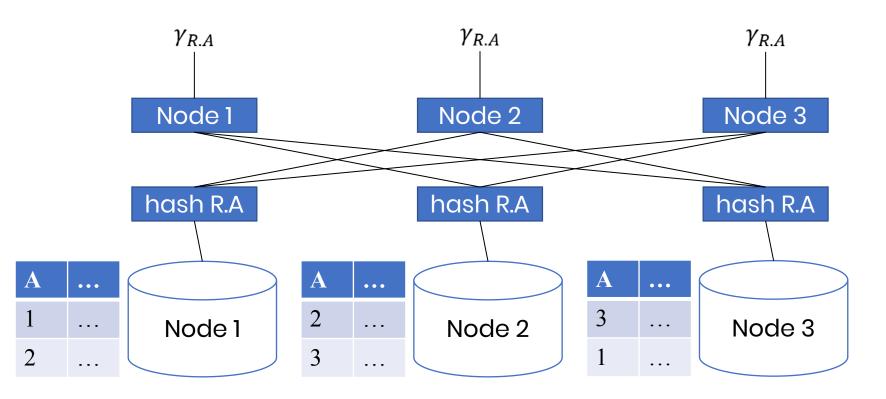
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- Hash shuffle tuples
- 2. Local aggregation

Assume:
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SELECT \*
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- Hash shuffle tuples
- 2. Local aggregation

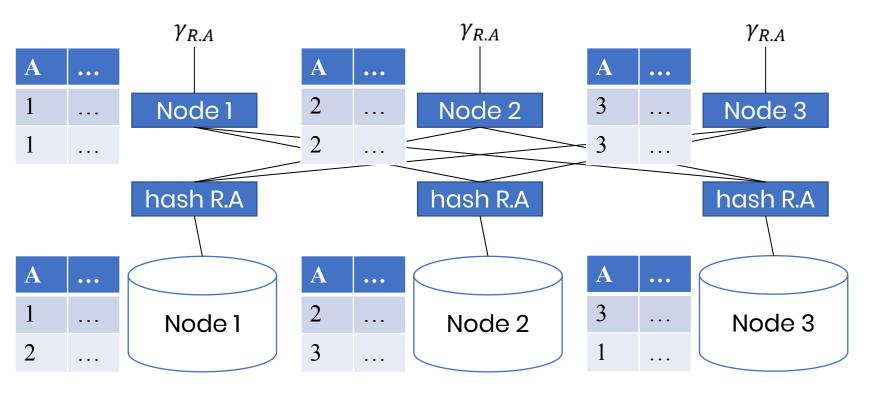
Assume:
R is block partitioned

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SELECT \*

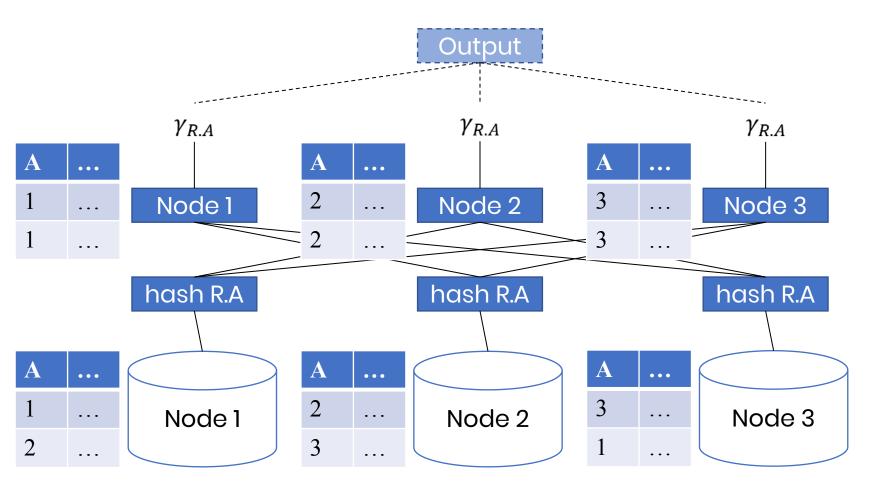
FROM R

**GROUP BY R.A** 



### Implicit Union

Parallel query plans implicitly union at the end

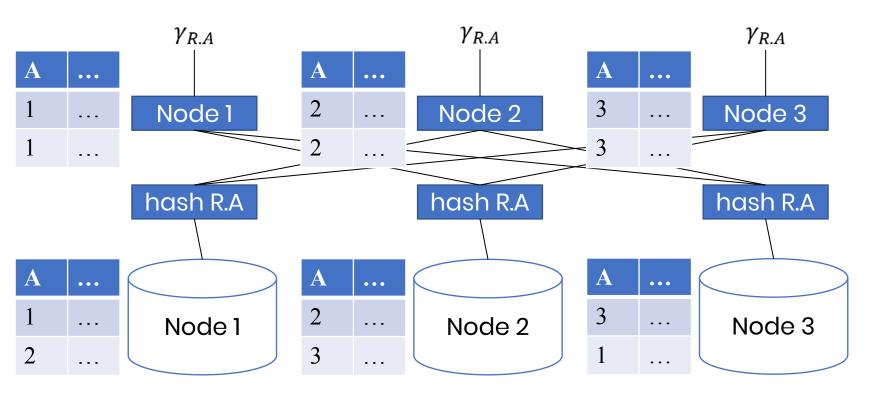


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- Hash shuffle tuples
- 2. Local aggregation

Would I need to shuffle if R was hash or range partitioned?

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- 1. Hash shuffle tuples on join attributes
- 2. Local join

 $\bowtie_{R} A=S.A$ 

 $\bowtie_{R.A=S.A}$ 

Assume:

R and S are block partitioned

WHERE 
$$R.A = S.A$$

$$\bowtie_{R.A=S.A}$$

Node 1

Node 2

Node 3

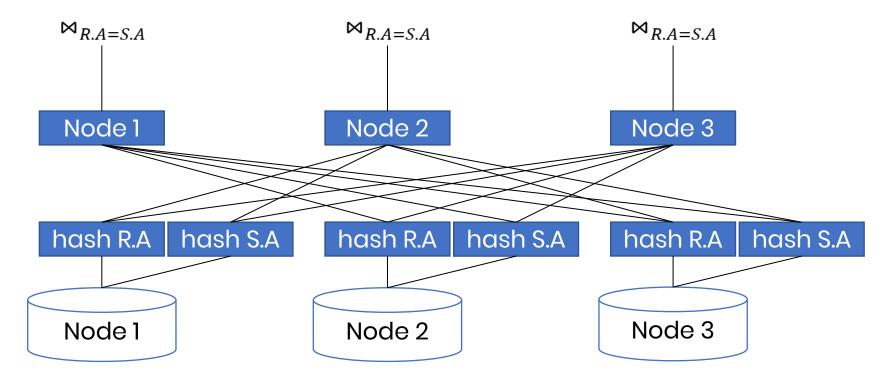
Hash shuffle tuples on join attributes

2. Local join

Assume:
R and S are block partitioned

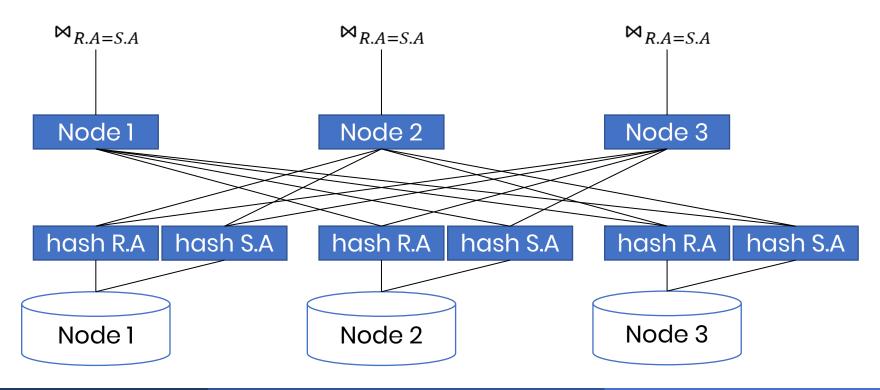
SELECT \*

FROM R, S
WHERE R.A = S.A



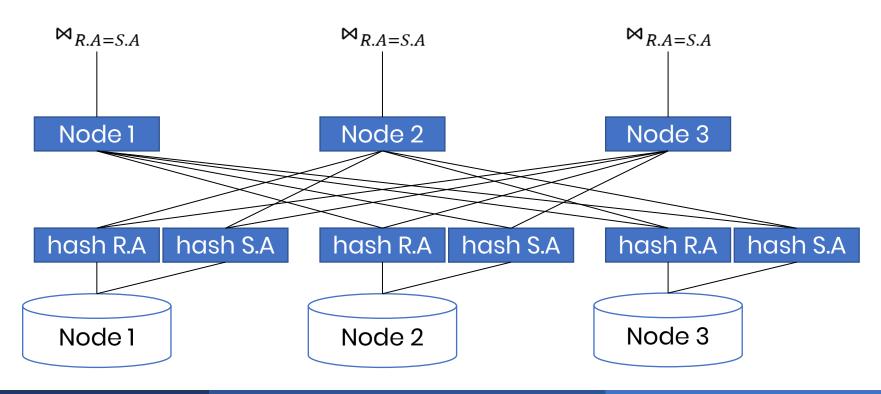
- 1. Hash shuffle tuples on join attributes
- 2. Local join

If S was **hash** partitioned on A (on the same hash function) would I need to shuffle S? R?



- 1. Hash shuffle tuples on join attributes
- 2. Local join

If S was **range** partitioned on A would I need to shuffle S? R?



#### **Broadcast Join**

Assume:

I. Broadcast unpartitioned table<sup>S is unpartitioned and small.</sup>

2. Local join

SELECT \*
FROM R, S
WHERE R.A = S.A

$$\bowtie_{R,A=S,A}$$

$$\bowtie_{R.A=S.A}$$

$$\bowtie_{R.A=S.A}$$

Node 1

Node 2

Node 3

S

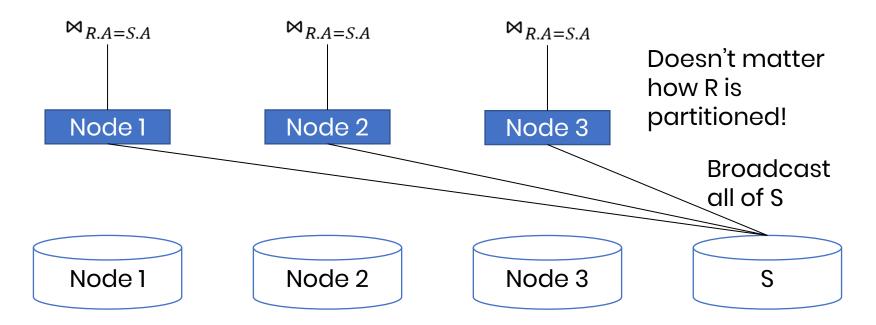
#### **Broadcast Join**

- I. Broadcast unpartitioned table<sup>S is unpartitioned and small.</sup>
- 2. Local join

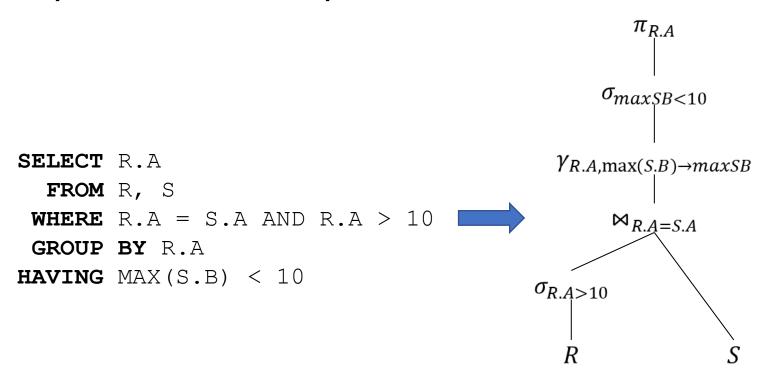
SELECT \*
FROM R, S
WHERE R.A = S.A

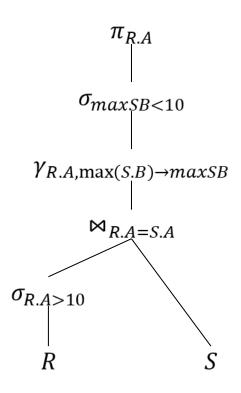
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Assume:



#### All queries can be parallelized!



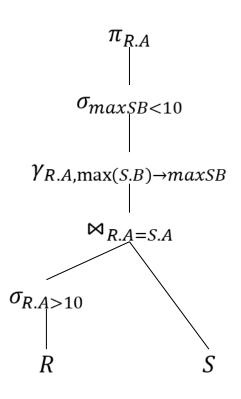


Assume: R is block partitioned S is hash partitioned on A

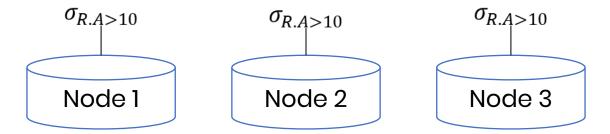
Node 1

Node 2

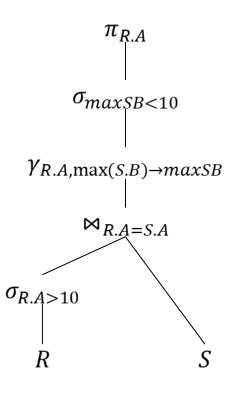
Node 3

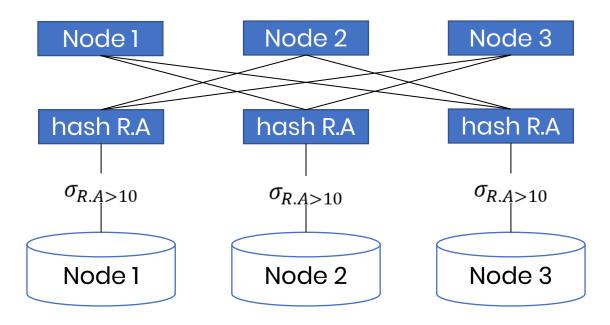


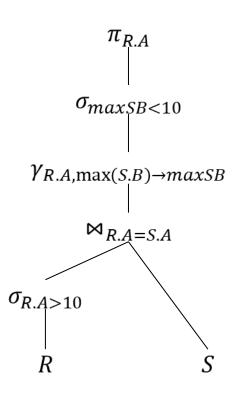
Assume: R is block partitioned S is hash partitioned on A



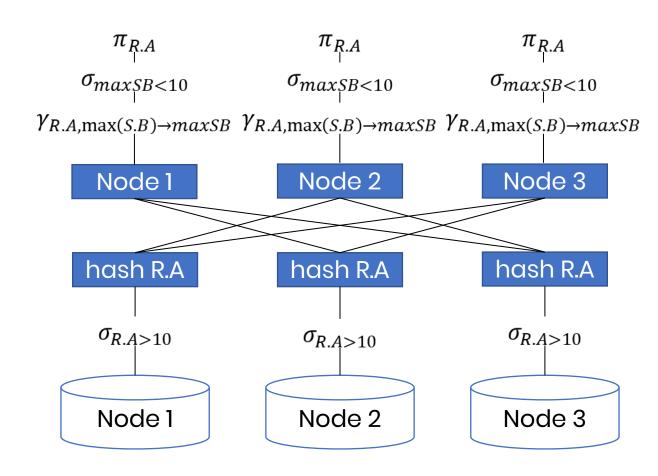
Assume:
R is block partitioned
S is hash partitioned on A







Assume:
R is block partitioned
S is hash partitioned on A



### Takeaways

- Distributing data on multiples nodes helps to scale processing.
  - but you need to decide how to partition data to avoid bottlenecks and copying data

#### **Next Time**

Programming with the Java Spark API