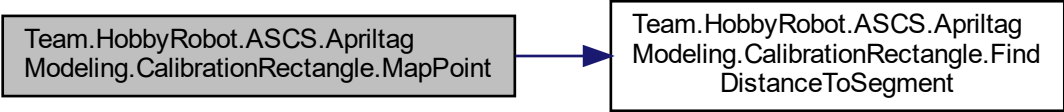


Team.HobbyRobot.ASCS.Apritag  
Modeling.CalibrationRectangle.MapPoint



```
graph LR; A["Team.HobbyRobot.ASCS.Apritag  
Modeling.CalibrationRectangle.MapPoint"] --> B["Team.HobbyRobot.ASCS.Apritag  
Modeling.CalibrationRectangle.Find  
DistanceToSegment"]
```

Team.HobbyRobot.ASCS.Apritag  
Modeling.CalibrationRectangle.Find  
DistanceToSegment