

DSA Mini Textbook

Theo Park

Contents

Preface	3
1 Runtime Analysis	4
2 Intro to Data Structures	5
3 Sorting Algorithms	6
4 Hash Tables	7
4.1 Division Method	7
4.2 Multiplication Method	7
4.3 Collision	7
4.3.1 Chaining	7
4.3.2 Open Addressing	7
5 Search Tree	8
5.1 Binary Search Tree and Its Limit	8
5.2 2-3 Tree	8
5.3 Red-Black Tree	8
5.4 Left-Leaning Red-Black Tree	8
5.4.1 Deletion in LLRBT	8
6 Undirected Graph	9
6.1 Adjacency Matrix and List	9
6.2 DFS	9
6.3 BFS	9
7 Directed Graphs	11
7.1 Strong Connectivity	11
7.1.1 Brute-force Strong Connectivity Algorithm	11
7.1.2 Brute-force using Stack	11
7.1.3 Strongly Connected Components and Kosaraju's Algorithm	11
7.2 Directed Acyclic Graphs	11
7.2.1 Topological Sort	11
8 Weighted Graphs	12
8.1 Shortest Path	12
8.1.1 Dijkstra's Algorithm	12
8.1.2 Bellman-Ford Algorithm	12
8.2 Articulation Points	13
8.3 Minimum Spanning Tree	13
8.3.1 Cycle and Cut Properties	13
8.3.2 Prim's Algorithm	13

8.4	Union-Find	13
8.4.1	Kruskal MST Algorithm	13
9	Strings	14
9.1	Brute-force String Pattern Matching	14
9.2	KMP Algorithm	14
9.3	Trie	14
9.4	PATRICIA	14
9.5	Huffman Coding	14

Preface

Chapter 1

Runtime Analysis

Chapter 2

Intro to Data Structures

Chapter 3

Sorting Algorithms

Chapter 4

Hash Tables

4.1 Division Method

4.2 Multiplication Method

4.3 Collision

4.3.1 Chaining

4.3.2 Open Addressing

Chapter 5

Search Tree

5.1 Binary Search Tree and Its Limit

5.2 2-3 Tree

5.3 Red-Black Tree

5.4 Left-Leaning Red-Black Tree

5.4.1 Deletion in LLRBT

Chapter 6

Undirected Graph

Graph is a set of vertices V and a collection of edges E that connect a pair of vertices. *Undirected graph* is a graph where edges do not have direction. *Degree of a vertex* representing how many edges is this vertex connected to.

- **Handshaking Theorem:** For any undirected graphs, $\sum_{v \in V} \deg(v) = 2 \cdot |E|$
- Maximum degree of a vertex: $\deg(v) \leq |V| - 1$, because a vertex can be connected to all other vertices at most
- Maximum edge count: $|E| \leq \frac{|V|(|V|-1)}{2}$
- **Complete graph:** A graph is said to be complete when each vertex pair is connected by a unique edge. I.e., a complete graph has the maximum number of edges ($|E| = \frac{|V|(|V|-1)}{2}$) and each vertex has the maximum degree ($\deg(v) = |V| - 1$)

6.1 Adjacency Matrix and List

6.2 DFS

```
1: function DEPTH-FIRST-SEARCH( $G, s$ )
2:    $S \leftarrow$  new stack
3:   Push  $s$  to  $S$ 
4:   while  $S$  is not empty do
5:      $u \leftarrow$  popped element from  $S$ 
6:     if  $u$  is not visited then
7:       for  $w$  adjacent to  $v$  do
8:         if  $w$  is not visited then
9:           Push  $w$  to  $S$ 
```

▷ G is a graph containing $|V|$ vertices, s is the starting node

6.3 BFS

```
1: function DEPTH-FIRST-SEARCH( $G, s$ )
2:    $Q$  is a new queue
3:   Enqueue  $s$  to  $Q$ 
```

▷ G is a graph containing $|V|$ vertices, s is the starting node

```
4:   Mark  $v$  as visited
5:   while  $Q$  is not empty do
6:        $u \leftarrow$  dequeued item from  $Q$ 
7:       for  $w$  adjacent to  $u$  do
8:           if  $w$  is not visited then
9:               Enqueue  $w$  to  $Q$ 
10:          Mark  $w$  as visited
```

Chapter 7

Directed Graphs

7.1 Strong Connectivity

7.1.1 Brute-force Strong Connectivity Algorithm

7.1.2 Brute-force using Stack

7.1.3 Strongly Connected Components and Kosaraju's Algorithm

7.2 Directed Acyclic Graphs

7.2.1 Topological Sort

Chapter 8

Weighted Graphs

8.1 Shortest Path

8.1.1 Dijkstra's Algorithm

```
1: function DIJKSTRA-SHORTEST-PATH( $G, s$ )           ▷  $G$  is a graph containing  $|V|$  vertices,  $s$  is the starting node
2:    $dist \leftarrow$  array size  $|V|$ 
3:    $prev \leftarrow$  array size  $|V|$ 
4:    $Q \leftarrow$  a new min-heap with distance values as keys

5:   ▷ Initialization step
6:   for  $v$  in  $Vertices$  do
7:     if  $v = s$  then  $dist[v] \leftarrow 0$ 
8:     if  $v \neq s$  then  $dist[v] \leftarrow \infty$ 
9:      $prev[v] \leftarrow -1$ 
10:    Add a tuple  $(dist[v], v)$  to  $Q$ 
11:    while  $Q$  is not empty do
12:       $u \leftarrow$  the value with minimum dist from  $Q$                                 ▷  $O(1)$ 
```

8.1.2 Bellman-Ford Algorithm

Dijkstra should not be used on a graph with negative edge(s).

```
1: function BELLMAN-FORD-SHORTEST-PATH( $G, V$ )           ▷  $G$  is the graph,  $V$  is the vertex list
2:    $dist \leftarrow$  array size  $|V|$ 
3:    $prev \leftarrow$  array size  $|V|$ 
4:   for  $v$  in  $V$  do
5:     if  $v = s$  then  $dist[v] \leftarrow 0$ 
6:     if  $v \neq s$  then  $dist[v] \leftarrow \infty$ 
7:      $prev[v] \leftarrow -1$ 
8:   for  $i = 1$  to  $|V| - 1$  do
9:     for  $e$  in  $E$  do                               ▷ Edge  $e$  connects vertex  $u$  and  $v$ 
10:      if  $weight[e] + dist[u] < dist[v]$  then
11:         $dist[v] = dist[u] + weight[e]$ 
12:         $prev[v] = u$ 
13:   ▷ Run the for loop once again. If the shortest distance is updated, then it means there is a negative weight cycle
```

```

14:   for  $e$  in  $E$  do
15:       if  $weight[e] + dist[u] < dist[v]$  then
16:           output Negative weight edge cycle detected
17:       return

```

\triangleright Edge e connects vertex u and v

8.2 Articulation Points

An articulation point is a vertex such that removing it from the graph increases the number of connected components.

```

1: function ( $G, s, d$ )
2:     Mark  $s$  as visited
3:      $discovery[s] \leftarrow d$ 
4:      $low[s] \leftarrow d$ 

```

$\triangleright G$ is the graph, s is the starting vertex, d is the //TODO

8.3 Minimum Spanning Tree

- Minimum: $\sum weight$ is minimum
- Spanning: All vertices in the graph are connected
- Tree: No cycle

There are two fundamental properties of MST:

1. *Cycle Property*: For any cycle C in the graph, if the weight of an edge $e \in C$ is higher than any of individual weights of all other edges in C , then its edge cannot belong in the MST.
2. *Cut Property*: For any cut (subdivision of graph with disjoint) C in the graph, if the weight of an edge e in the cut-set of C is strictly smaller than the weights of all other edges of the cut-set of C , then this edge belongs to all MST of the graph.

8.3.1 Cycle and Cut Properties

8.3.2 Prim's Algorithm

8.4 Union-Find

8.4.1 Kruskal MST Algorithm

Chapter 9

Strings

9.1 Brute-force String Pattern Matching

9.2 KMP Algorithm

9.3 Trie

9.4 PATRICIA

9.5 Huffman Coding