

₁ A Combinatorics Approach to Pattern Recognition of
₂ Bitarray Datastreams

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5 Abstract

6 In our lives, we try to make decisions that increase the possibility of moral outcomes. We judge
7 others by their moral objectives and their adherence to them. Identifying, understanding, and
8 mitigating the flaws of human thought process and decision making is essential for human progress.
9 Despite much progress made in the field of artificial intelligence, a tool that makes better, more
10 informed moral decisions than a human has not been developed and is the aim of this study. A
11 novel approach that involves the field of combinatorics to bitarray datastreams with a likeness to
12 the neuronal communication in the brain was developed to achieve these ends. The possibility of
13 succeeding is incalculable but increases with effort, time, and expertise. However, if good progress
14 towards these aims are made, the consequences will pave the way for the future of a more moral
15 society.

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78 Chapter 1

79 Introduction

80 1.1 Morality

81 Morality is the principles that define right and wrong actions. A moral agent acts according to a
82 moral system. Those moral systems can contain moral subsystems that they may chose or not. In
83 a moral system, an event is considered morally good if its consequences increase the probability
84 of a moral end.

85 1.1.1 Moral origins

86 Moral systems can be descibed as natural or non-natural in origin. Natural morals are those that
87 are installed without observation. A proportion of all moral agents will act randomly. Actions
88 that are observed implies that those actions did not result in the death of the other individual.
89 This filter ensures that random actions that result in death are not observed and are therefore not
90 continued. Non-natural morals are those that are installed from observation.

91 1.1.2 Moral relationships - Interaction between two moral systems

92 Moral ends vary between individuals. The morality of others and their moral compatibility can be
 93 only be predicted from a record of past actions. When individual moral agents interact, one of three
 94 possible interactions can be observed. Firstly, a Rejective interaction manifests as an assumption
 95 that each other's actions are bad (-/-). Secondly, an Assymetric interaction is a consequence of
 96 the willingness of only one moral agent to encourage the others pursuit of their respective moral
 97 systemi (+/-). Lastly, an Acceptive interaction is the understanding that the ends described by
 98 a moral system converges to the point that their continued actions weighted by their estimated
 99 probability is similar to those actions taken by the moral system of another individual (+/+).

100 1.1.3 Moral consensus - Majority moral opinion

101 An estimation of common "good" is essential for collective progress. The search for this consensus
 102 is done at a personal or a collective level when we vote, poll, or protest. An estimation of common
 103 "good" is also necessary for collective arbitration of an action; a field referred to as descriptive
 104 or comparative ethics. Once a consensus is established, the application of the golden rule, the
 105 principle of treating others as you wish to be treated, forms the basic principles of justice and social
 106 contract. Communication of intention can often be reciprocal, that is to say one individual has and
 107 understanding of the others understanding of your understanding (and so on). An understanding
 108 of the consequences of breaking this rule encourages the enforcement of a social contract. The
 109 lesser the amount of knowledge surrounding subject matter, the greater the room for reasonable
 110 disagreement. Factual consensus has no claim to moral authority.

111 1.1.4 Moral evolution - How morality changes over time

112 Consensus morality changes over time. Although opinions of an action can be changed by a greater
 113 understanding of probabilities of consequences that arise after the action, morals are unaffected
 114 by facts. Moral re-evaluation is also possible through the revelation of inconsistencies. The cause
 115 of this can be due to incomplete data relating to a moral question or cognitive dissonance.

116 1.2 The state of current majority moral opinion

117 Although the secularisation of western countries and adoption of enlightenment ideals is often
118 considered a loss of moral congruency, the opposite is most likely as a consequence of interreligious
119 moral alignment. Based on polling data, core moral principles include:

120 1.2.1 How is society improving?

121 With respect to the current moral consensus, there has been significant moral progress¹.

122 1.2.2 How is society deteriorating?

123 1.3 Fallibilities and limitations of human decision making

124 In all humans there is a preinstalled moral operating system referred to as natural morality. This
125 system has evolved to promote reproduction and survival. Consensus morality today is different
126 from natural morality In order to suppress these naturalistic urges and reverse these forms of societal
127 deterioration, it is important to look at the origins. The pursuit of overcoming these urges is one
128 which we should all share².

129 1.3.1 Bias and Discrimination, Misinformation, and Information deficit

130 1.3.2 The scale of human computation

131 With the advancements in electronic data storage, the availability of data brings with it the
132 potential for more accurate predictive tools than any point previously. However, the current
133 restraints of human computational load limits the rate at which these tools can be utilised.

1.4 Alternative decision making algorithms

Computation makes decisions. Currently, there has been no success in the construction of an artificial moral agent that mitigates the real issues in human moral decision making process.

1.4.1 Deep learning

1.4.2 HTM

Numenta³, alpha go, etc

1.4.3 How to align intelligent systems with consensus moral beliefs

As with humans, if an agent has greater intelligence then there is a greater importance that the agent has a moral system that aligns with the core values that supports the current majority moral opinion. Transparency of decision making process is crucial for the public arbitration of artificial decision making algorithms.

1.5 AI safety and responsibility

1.6 Project aims

Current attempts have fallen short at achieving these ends and resulted in hyperspecific reward seeking behaviour. The aim of this study is to leverage the advancements of computing to create a system that will make more moral choices than those made by a human. Separate from traditional neural network architectures, Hierarchical Temporal Memory (HTM) is a technique developed by Numenta that more closely resembles the connections between axons in the brain. In this study, the guiding principles of HTM combined with a novel system for self validation will be designed to evaluate *ab initio* learning of a new machine learning model. Python will be used principally for development, testing, and validation.

155 **Chapter 2**

156 **Input**

157 **2.1 Sources of data**

158 **2.2 Binary conversion**

159 **2.3 Sparcity**

160 **2.4 Tandem data input**

Chapter 3

Output

3.1 How are decisions made

Decision field theory is a method of mathematically modelling the change in utility when comparing multiple choices⁴. Currently, machines do not act this way.

3.2 The random-pianist method

3.3 The Upgrade workflow

No delayed combinations only reinforce if you see it multiple times I = input that does not result from an action A = input that results from an action R = random input (or choice of previous set: pseudorandom) [] = combination expansion Both the action and the actions effects should be recognised by combinations

I1, R1 → A1[I1, R1] I2, A1, R2 → A2[I2, A1, R2] I3, A2, R3 → A3[I3, A2, R3] I4, A3, R4 → A4[I4, A3, R4]

Aims: 1: Learn actions from inputs 2: Decrease entropy from the UEI 3: Learn inputs from inputs

175 Whats being combined for each timepoint: Random doping I1, R1 I2, R2, A1[I1, R1] I3, R3,
 176 A2[I2, R2, A1[I1, R1]] ...

177 actions included I1, A1 I2, A1(I1) I3, A2(I2), A2(A1(I1)), A2(I2 + A1(T1))

178 W/O random doping I1 I2, A1[I1] I3, A2[I2, A1[I1]] ...

179 expanded W/O random doping I1 I2, A1(I1) I3, A2(I2), A2(A1(I1)), A2(I2 + A1(T1)) ...

180 translated: new input the action resulting from the second input the action resulting from the
 181 action resulting from the first input the action resulting from a combination of the second input
 182 and the action resulting from the first input

183 R1, I1, A1

Chapter 4

Memory

4.1 Classical combinatorics

4.2 The combination problem of scale

4.3 Slicing the combinations array

4.3.1 Combinations of combinations

4.4 Storage

4.5 Prediction

4.6 Persistence of activation

4.7 Edge contraction

4.8 Delay function

197 Chapter 5

198 Runtime

199 5.1 Chapter introduction

200 Chapter 6

201 Testing

202 6.1 Chapter introduction

203 This chapter will focus on some of the more well known problems that face current machine
204 learning models. As opposed to traditional testing nomenclature in software design (unit testing,
205 integration testing), I will refer to all forms of experimentation as testing (such as Turing testing).

206 **6.2 Test 1 - Parrot**

207 **6.3 Test 2 - Mathematics**

208 **6.3.1 True/False**

209 **6.3.2 Addition**

210 **6.3.3 Sine prediction**

211 **6.3.4 Modelling and the stock market**

212 **6.4 Test 3 - Natural language modelling**

213 **6.4.1 Text prediction**

214 **6.5 Test 4 - Sound signal processing**

215 **6.5.1 Voice recognition**

216 **6.6 Test 5 - Image classification**

217 **6.6.1 Breast cancer tissue classification**

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