lane_line

Q1 Make Trackbar for the following images to tune the parameters of canny detection.

Image1

image2

Write your observation.

Feel free to use helper function that been used in lecture.

Q2 The out of question 1 make it as input for question 2 after make region of interest then make trackbar for houghlines parameters (`threshold ,min_line_length`

`max_line_gap`
 and then draw 2 line on image.

Image1

image2

Write your observation.

Feel free to use helper function that been used in lecture.

Q3 read the following video and apply lane line detection on it then show output using opencv.

video