

lane_line

Q1 Make Trackbar for the following images to tune the parameters of canny detection.

[Image1](#)

[image2](#)

Write your observation.

Feel free to use helper function that been used in lecture.

Q2 The out of question 1 make it as input for question 2 after make region of interest then make trackbar for houghlines parameters (`threshold ,min_line_length`

`max_line_gap`

and then draw 2 line on image.

[Image1](#)

[image2](#)

Write your observation.

Feel free to use helper function that been used in lecture.