

Stephen Eick

Curriculum Vitae

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Education

- 2016–Present **Master of Computer Science**, *Georgia Institute of Technology*, Atlanta, GA.
◦ Specialization in Computational Perception & Robotics
◦ Concurrently pursuing a Graduate Certificate in Public Policy
- 2011–2016 **Bachelor of Computer Engineering & Computer Science**, *University of Wisconsin–Madison*, Madison, WI.

Experience

- 2017 **Software Engineer Intern**, *FICON*, IBM, Poughkeepsie, NY.
- 2017 **Robot Engineering Intern**, *iRobot*, Bedford, MA.
- 2015–2016 **Research Assistant**, *WiNGS Lab*, Madison, WI.
- 2014 **Hardware Design Verification Co-op**, *Extreme Engineering Solutions, Inc.*, Middleton, WI.
- 2013 **App Hosting Admin/Ops Intern**, *CUNA Mutual Group*, Madison, WI.

Awards & Honors

- 2017 **Verizon Fellowship**, *Georgia Institute of Technology*.
- 2017 **Roomba Pull Winner**, *iRobot*.
- 2016 **Dean's List**, *University of Wisconsin–Madison*.
- 2015 **Best Staff Writer**, *Wisconsin Engineer Magazine*.

Organizations

University of Wisconsin–Madison

- 2015–2016 **President**, *Wisconsin Robotics*.
- 2015–2016 **Power & Control Systems Lead**, *Badger Robotic Mining Team*.
- 2015–2016 **Staff Writer**, *Wisconsin Engineer Magazine*.
- 2015–2016 **Project Lead**, *Garage Physics*.
- 2014–2015 **Treasurer & Embedded Lead**, *Wisconsin Robotics*.
- 2013–2014 **Embedded Member**, *Wisconsin Robotics*.

Volunteering

- 2017 **Exhibit Coordinator**, *Northeast Elementary School*, Waltham, MA.
- 2013–2016 **Exhibit Coordinator**, *Engineering Expo*, Madison, WI.
- 2014–2016 **Exhibit Coordinator**, *Museum of Science and Industry*, Chicago, IL.
- 2013–2015 **Exhibit Coordinator**, *Wisconsin Science Festival*, Madison, WI.
- 2014 **Robot Design Judge**, *FIRST Lego League*, Madison, WI.

Teaching Experience

2016 **Scratch Programming Instructor**, *Shorewood Elementary School*, Madison, WI.

Coursework Sampling

Georgia Institute of Technology

Fall 2017 **Privacy Technology, Policy, & Law**, *Annie Antón & Peter Swire*.
Artificial Intelligence, *Thad Starner*.
Computer Vision, *James Hays*.

Fall 2016 **Human-Robot Interaction**, *Sonia Chernova*.
Smart and Connected Communities, *Ellen Do*.
Computing For Good, *Ellen Zegura & Beki Grinter*.

Skills & Abilities

Programming	Bash, C, C++, Javascript, MATLAB, Python, ARM Assembly, CSS, HTML, Java, Verilog.	(Proficient) (Familiar)
Technical	Embedded systems design and development, robot design and development, software development, analysis.	
General	Leadership, project management, collaboration, writing, teaching.	

Projects

Software	Data Processing Pipeline for Machine Learning , <i>IBM</i> . <ul style="list-style-type: none">◦ A self-led, experimental, in-house data acquisition and filtering tool as the input to a machine learning pipeline. Imaging Pipeline Extension , <i>iRobot</i> . <ul style="list-style-type: none">◦ Designed and implemented a substantial modification to fundamental on-robot capabilities to be shipped in future products. Image Annotation Tool , <i>iRobot</i> . <ul style="list-style-type: none">◦ Designed for in-house robotic research. Mapping Justice , <i>Georgia Institute of Technology</i> . <ul style="list-style-type: none">◦ Developed for the Atlanta Legal Aid Society to visualize contract-for-deed properties in the Atlanta metro area. Interactive Music Exhibit , <i>Georgia Institute of Technology</i> . <ul style="list-style-type: none">◦ Tracked people and objects in 2D plane using arrays of ultrasonic distance sensors to create music. Network Performance Testing Suite , <i>WiNGS Lab</i> .
Robots	Insomnia , <i>Wisconsin Robotics</i> . <ul style="list-style-type: none">◦ Robot which navigated Martian-like terrain, manipulated objects, and performed scientific measurements at the University Rover Challenge. Atlas , <i>Wisconsin Robotics</i> . <ul style="list-style-type: none">◦ Autonomous tour-guide robot. Minibot , <i>Wisconsin Robotics</i> . <ul style="list-style-type: none">◦ Carbon-fiber unibody robot for prototyping and outreach. BLER , <i>Badger Robotic Mining Team</i> . <ul style="list-style-type: none">◦ Lunar regolith simulant mining robot built for the NASA Robotic Mining Competition.
Hardware	CNC Router, FPGA Arduino Shield, Eight-Layer SBC Backplane, H-Bridge Motor Controller, Arduino-Based Microcontroller Board, LED Cube