

The Butterfly Effect

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1 Introduction

A Non-linear Dynamical System is a sequence of numbers x_0, x_1, \dots such that x_0 is fixed and $x_{n+1} = \phi(x_n)$ where ϕ is some function. When studying Dynamical Systems we are often more interested in general questions than specific results, for example, Does the system eventually settle down?, or, Does the long-term behavior of the system depend on its initial condition?. Even simple Dynamical Systems can yield interesting results to these questions and in this document we will be looking at one in particular, the Logistic Map.

Mathematics can be typed in to L^AT_EX as x^2 and/or $(a + b)^2 = a^2 + 2ab + b^2$.

2 Logistic Map

The Logistic Map is defined such that $\phi(x) = \lambda x(1 - x)$ where $0 < \lambda \leq 4$ and $0 \leq x \leq 1$. ie;

$x_{n+1} = \lambda x_n(1 - x_n)$, $0 \leq x_n \leq 1$. I have used sage to plot the Logistic Map in 1. The line $y = x$ is included because it clearly illustrates the idea of stationary point.

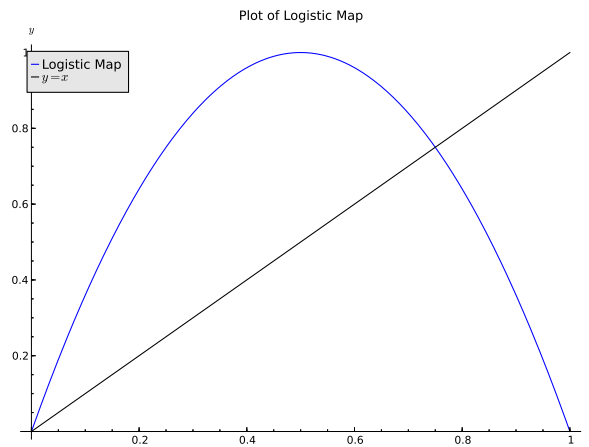


Figure 1: The Logistic Map where $\lambda = 4$ and the line $y = x$.

3 Stationary Points

Stationary Points occur when $x_{n+1} = x_n$. We can find them by solving the equation $\phi(x) = x$. This is very easy to compute just by hand, and gives the solution: $x = 3/4$ and $x = 0$ when $\lambda = 4$. A more interesting question is whether these stationary points are stable.

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logistic(x) = 4*x*(1-x)
solve(logistic(x) == x,x)

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4 The Butterfly Effect

The Butterfly Effect is a common term used to describe the behaviour of a non-linear dynamical system. The name, coined by Edward Lorenz, is derived from the theoretical example of a hurricane's formation being contingent on whether or not a distant butterfly had flapped its wings several weeks earlier.[1] It refers to how the choice of initial starting index can have large impacts later on.

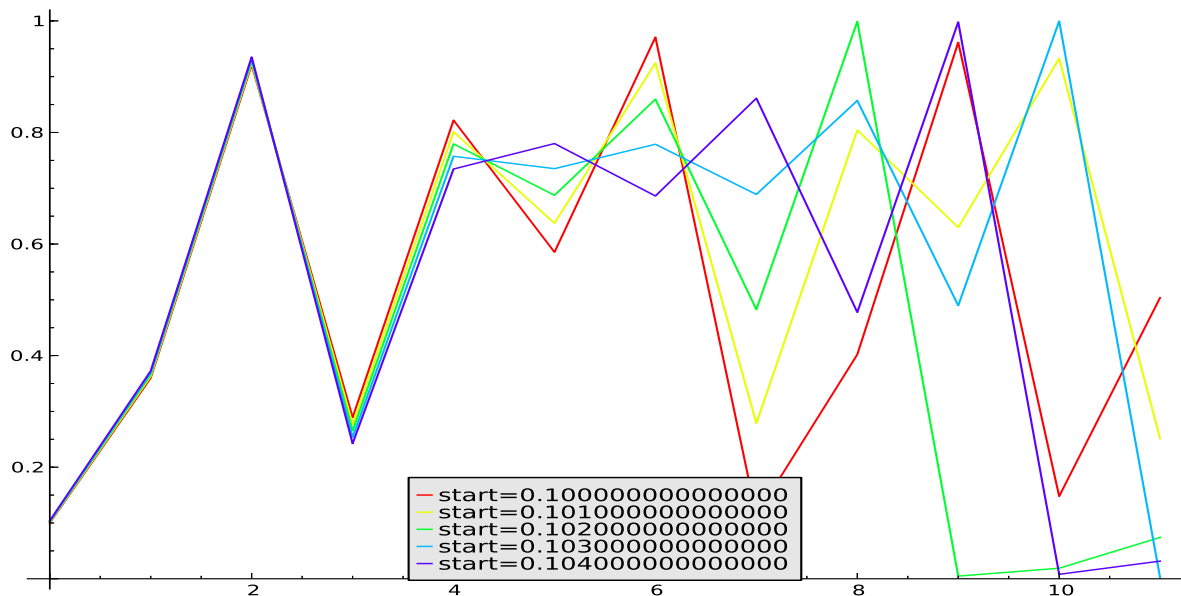


Figure 2: The Logistic Map over 12 iterations using 5 different starting points.

References

- [1] Wikipedia. Butterfly effect — wikipedia, the free encyclopedia, 2013. [Online; accessed 2-December-2013].