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ACM 模板

数据结构

并查集

```
struct dsu{
   int n;
   vector<int> fa;
   dsu(int _n) :n(_n){
       fa.resize(n + 1);
       iota(fa.begin(), fa.end(), 0);
   }
   int find(int x){
        return x == fa[x] ? x : fa[x] = find(fa[x]);
   }
   int merge(int x, int y){
       int fax = find(x), fay = find(y);
       if(fax == fay)return 0; // 一个集合
       return fa[find(x)] = find(y); // 合并到哪个集合了
   }
};
```

树状数组

```
#define lowbit(x) ((x)&(-(x)))
template<class T>
```

```
struct Fenwick_tree{
    Fenwick tree(int size){
        n = size;
        tree.assign(n + 1, 0);
    T query(int l, int r){
        auto query = [&](int pos){
            T res = 0;
            while(pos){ res += tree[pos]; pos -= lowbit(pos); }
            return res;
        };
        return query(r) - query(l - 1);
    void update(int pos, T num){
        while(pos <= n){ tree[pos] += num; pos += lowbit(pos); }</pre>
    }
private:
    int n;
    vector<T> tree;
};
```

线段树

```
template <class Data, class Num>
struct Segment Tree{
    inline void update(int l,int r,Num x){update(1,l,r,x);}
    inline Data query(int l,int r){return query(1,l,r);}
    Segment Tree(vector<Data>& a){
        n=a.size();
        tree.assign(n*4+1,{});
        build(a, 1, 1, n);
    }
    private:
    int n;
    struct Tree{int l,r;Data data;};
    vector<Tree> tree;
    inline void pushup(int pos){
        tree[pos].data=tree[pos<<1].data+tree[pos<<1|1].data;</pre>
    }
    inline void pushdown(int pos){
        tree[pos<<1].data=tree[pos<<1].data+tree[pos].data.lazytag;</pre>
        tree[pos<<1|1].data=tree[pos<<1|1].data+tree[pos].data.lazytag;
        tree[pos].data.lazytag=Num::zero();
    void build(vector<Data>& a, int pos, int l, int r){
        tree[pos].l=l;tree[pos].r=r;
        if(l==r){tree[pos].data=a[l-1];return;}
        int mid=(tree[pos].l+tree[pos].r)>>1;
        build(a,pos<<1,l,mid);</pre>
        build(a,pos << 1 | 1,mid+1,r);
        pushup(pos);
```

```
void update(int pos,int& l,int& r,Num& x){
        if(l>tree[pos].r||r<tree[pos].l)return;</pre>
        if(l<=tree[pos].l&&tree[pos].r<=r)</pre>
{tree[pos].data=tree[pos].data+x;return;}
        pushdown(pos);
        update(pos<<1,l,r,x);update(pos<<1|1,l,r,x);
        pushup(pos);
    }
    Data query(int pos,int& l,int& r){
        if(l>tree[pos].r||r<tree[pos].l)return Data::zero();</pre>
        if(l<=tree[pos].l&&tree[pos].r<=r)return tree[pos].data;</pre>
        pushdown(pos);
        return query(pos<<1,l,r)+query(pos<<1|1,l,r);</pre>
    }
};
struct Num{
    ll add:
    inline static Num zero(){return {0};}
    inline Num operator+(Num b){return {add+b.add};}
};
struct Data{
    ll sum, len;
    Num lazytag;
    inline static Data zero(){return {0,0,Num::zero()};}
    inline Data operator+(Num b){return {sum+len*b.add,len,lazytag+b};}
    inline Data operator+(Data b){return
{sum+b.sum,len+b.len,Num::zero()};}
};
```

图论

存图

```
struct Graph{
   int n;
   struct Edge{ int to, w; };
   vector<vector<Edge>> graph;
   Graph(int _n){ n = _n; graph.assign(n + 1, vector<Edge>()); };
   void add(int u, int v, int w){ graph[u].push_back({ v,w }); }
};
```

树上问题

树链剖分

```
vector<int> fa, siz, dep, son, dfn, rnk, top;
fa.assign(n + 1, 0);
siz.assign(n + 1, 0);
```

```
dep.assign(n + 1, 0);
son.assign(n + 1, 0);
dfn.assign(n + 1, 0);
rnk.assign(n + 1, 0);
top.assign(n + 1, 0);
void hld(int root){
    function<void(int)> dfs1 = [&](int t){
        dep[t] = dep[fa[t]] + 1;
        siz[t] = 1;
        for(auto& [to, w] : graph[t]){
            if(to == fa[t])continue;
            fa[to] = t;
            dfs1(to);
            if(siz[son[t]] < siz[to])son[t] = to;</pre>
            siz[t] += siz[to];
        }
    }; dfs1(root);
    int dfn tail = 0;
    for(int i = 1; i \le n; i++)top[i] = i;
    function<void(int)> dfs2 = [&](int t){
        dfn[t] = ++dfn_tail;
        rnk[dfn tail] = t;
        if(!son[t])return;
        top[son[t]] = top[t];
        dfs2(son[t]);
        for(auto& [to, w] : graph[t]){
            if(to == fa[t] || to == son[t])continue;
            dfs2(to);
        }
    }; dfs2(root);
}
int lca(int x, int y){
    while(top[x] != top[y]){
        if(dep[top[x]] < dep[top[y]])swap(x, y);
        x = fa[top[x]];
    }
    if(dep[x] < dep[y])swap(x, y);
    return y;
};
```

强连通分量

```
void tarjan(Graph& g1, Graph& g2){
   int dfn_tail = 0, cnt = 0;
   vector<int> dfn(g1.n + 1, 0), low(g1.n + 1, 0), exist(g1.n + 1, 0),
belong(g1.n + 1, 0);
   stack<int> sta;
   function<void(int)> dfs = [&](int t){
      dfn[t] = low[t] = ++dfn_tail;
      sta.push(t); exist[t] = 1;
```

```
for(auto& [to] : g1.graph[t]){
            if(!dfn[to]){
                dfs(to);
                low[t] = min(low[t], low[to]);
            else if(exist[to])low[t] = min(low[t], dfn[to]);
        }
        if(dfn[t] == low[t]){
            cnt++:
            while(int temp = sta.top()){
                belong[temp] = cnt;
                exist[temp] = 0;
                sta.pop();
                if(temp == t)break;
            }
        }
    };
    for(int i = 1; i \le q1.n; i++)if(!dfn[i])dfs(i);
    q2 = Graph(cnt);
    for(int i = 1; i \le g1.n; i++)g2.w[belong[i]] += g1.w[i];
    for(int i = 1; i \le g1.n; i++)
        for(auto& [to] : g1.graph[i])
            if(belong[i] != belong[to])g2.add(belong[i], belong[to]);
}
```

拓扑排序

```
void toposort(Graph& q, vector<int>& dis){
    vector<int> in(g.n + 1, 0);
    for(int i = 1; i <= g.n; i++)
        for(auto& [to] : g.graph[i])in[to]++;
    queue<int> que;
    for(int i = 1; i \le g.n; i++)
        if(!in[i]){
            que.push(i);
            dis[i] = g.w[i]; // dp
        }
    while(!que.empty()){
        int u = que.front(); que.pop();
        for(auto& [to] : g.graph[u]){
            in[to]--;
            dis[to] = max(dis[to], dis[u] + g.w[to]); // dp
            if(!in[to])que.push(to);
        }
   }
}
```

字符串

哈希

```
constexpr int N = 2e6;
constexpr ll\ mod[2] = \{2000000011, 2000000033\}, base[2] = \{20011, 20033\}
};
vector<array<ll, 2>> pow_base(N);
pow base [0][0] = pow base [0][1] = 1;
for(int i = 1; i < N; i++){
    pow_base[i][0] = pow_base[i - 1][0] * base[0] % mod[0];
    pow base[i][1] = pow base[i - 1][1] * base[1] % mod[1];
}
struct Hash{
    int size:
    vector<array<ll, 2>> hash;
    Hash(){}
    Hash(const string& s){
        size = s.size();
        hash resize(size);
        hash[0][0] = hash[0][1] = s[0];
        for(int i = 1; i < size; i++){
            hash[i][0] = (hash[i - 1][0] * base[0] + s[i]) % mod[0];
            hash[i][1] = (hash[i - 1][1] * base[1] + s[i]) % mod[1];
        }
    }
    array<ll, 2> operator[](const array<int, 2>& range)const{
        int l = range[0], r = range[1];
        if(l == 0) return hash[r];
        auto single hash = [&](bool flag){
            return (hash[r][flag] - hash[l - 1][flag] * pow_base[r - l +
1][flag] % mod[flag] + mod[flag]) % mod[flag];
        };
        return { single_hash(0), single_hash(1) };
    }
};
```

manacher

```
void manacher(const string& _s, vector<int>& r){
    string s(_s.size() * 2 + 1, '$');
    for(int i = 0; i < _s.size(); i++)s[2 * i + 1] = _s[i];
    r.resize(_s.size() * 2 + 1);
    for(int i = 0, maxr = 0, mid = 0; i < s.size(); i++){
        if(i < maxr)r[i] = min(r[mid * 2 - i], maxr - i);
        while(i - r[i] - 1 >= 0 && i + r[i] + 1 < s.size() && s[i - r[i] - 1] == s[i + r[i] + 1]) ++r[i];
        if(i + r[i] > maxr) maxr = i + r[i], mid = i;
    }
}
```

数学

线性筛法

```
constexpr int N = 10000000;
vector<int> min_prime(N + 1, 0), primes;
for(int i = 2; i <= N; i++){
    if(min_prime[i] == 0){
        min_prime[i] = i;
        primes.push_back(i);
    }
    for(auto& prime : primes){
        if(prime > min_prime[i] || prime > N / i)break;
        min_prime[prime * i] = prime;
    }
}
```

分解质因数

```
void solve_num_primes(int num, vector<int>& ans){
   for(auto i = lower_bound(primes.begin(), primes.end(),
   min_prime[num]); i != primes.end();i++){
      int prime = *i;
      if(prime > num / prime)break;
      cnt++;
      if(num % prime == 0){
            while(num % prime == 0)num /= prime;
            ans.push_back(prime);
      }
    }
   if(num > 1)ans.push_back(num);
}
```

计算几何

```
constexpr double PI = 3.141592653589793116;
constexpr double eps = 1e-8;
using T = double;

// 两浮点数是否相等
bool equal(const T& a, const T& b){
    return abs(a - b) < eps;
}

// 向量
struct vec{
    T x, y;
```

```
vec() : x(0), y(0){}
    vec(const T\& \_x, const T\& \_y) : x(\_x), y(\_y){}
    // 模
    double length()const{
        return sqrt(x * x + y * y);
    }
    // 与x轴正方向的夹角
    double angle()const{
        double angle = atan2(y, x);
        if(angle < 0)angle += 2 * PI;
        return angle;
    }
    // 逆时针旋转
    void rotate(const double& theta){
        double temp = x;
        x = x * cos(theta) - y * sin(theta);
        y = y * cos(theta) + temp * sin(theta);
    }
    bool operator == (const vec& other)const{ return equal(x, other.x) &&
equal(y, other.y); }
    bool operator<(const vec& other)const{ return angle() == other.angle()</pre>
? x < other.x : angle() < other.angle(); }</pre>
    vec operator+(const vec& other)const{ return { x + other.x,y + other.y
}; }
    vec operator-()const{ return { -x,-y }; }
    vec operator-(const vec& other)const{ return -other + (*this); }
    vec operator*(const T& other)const{ return { other * x,other * y }; }
   T operator*(const vec& other)const{ return x * other.x + y * other.y;
}
    // 叉积 结果大于0, a在b的顺时针, 小于0, a在b的逆时针, 等于0共线, 可能同向或反向, 结
果绝对值表示 a b形成的平行四边行的面积
   T operator^(const vec& other)const{ return x * other.y - y * other.x;
}
    friend istream& operator>>(istream& input, vec& data){
        input >> data.x >> data.y;
        return input;
    friend ostream& operator<<(ostream& output, const vec& data){</pre>
        output << fixed << setprecision(6);</pre>
        output << data.x << " " << data.y;
        return output;
    }
};
// 求两点间的距离
```

```
double distance(const vec& a, const vec& b){
          return (a.x - b.x) * (a.x - b.x) + (a.y - b.y) * (a.y - b.y);
}
// 求两向量夹角
double angle(const vec& a, const vec& b){
          double theta = abs(a.angle() - b.angle());
          if(theta > PI)theta = 2 * PI - theta;
          return theta:
}
// 计算多边形的面积, polygon里必须是存的相邻的点
T polygon_area(const vector<vec>& polygon){
          T ans = 0;
          for(int i = 1; i < polygon.size(); i++)ans += polygon[i - 1] ^
polygon[i];
          ans += polygon[polygon.size() - 1] ^ polygon[0];
          return abs(ans / 2);
}
// 直线
struct Line{
          vec point, direction;
          Line(){}
          Line(const vec& _point, const vec& _direction) :point(_point),
direction(_direction){}
};
// 两直线是否垂直
bool perpendicular(const Line& a, const Line& b){
          return a.direction * b.direction == 0 ? true : false;
}
// 两直线是否平行
bool parallel(const Line& a, const Line& b){
          return (a.direction ^ b.direction) == 0 ? true : false;
}
// 两直线交点
vec intersection(const T& A, const T& B, const T& C, const T& D, const T&
E, const T& F){
         return \{ (B * F - C * E) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * F) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * E - B * D), (C * D - A * E) / (A * D - A * E) / (A * E - B * D), (C * D - A * E) / (A *
B * D) };
}
// 两直线交点
vec intersection(const Line& a, const Line& b){
          return intersection(a.direction.y, -a.direction.x, a.direction.x *
a.point.y - a.direction.y * a.point.x,
                    b.direction.y, -b.direction.x, b.direction.x * b.point.y -
b.direction.y * b.point.x);
```