# Probabilistic and Smoothed Analysis of Algorithms Assignment # 3

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#### Answering any 5.

- 1. This exercise is to demonstrate the limitations of considering expected running time of an algorithm as a useful measure. For any n > 0, describe a function  $f: \{0,1\}^n \to \mathbb{N}$  such that
  - $\mathbb{E}[f] = \mathbb{E}_{x \in \{0,1\}^n}[f(x)] = n^c$  for some constant c and
  - $\bullet \ \operatorname{var}[f] = E[f^2] (E[f])^2 = \Omega(2^n).$

I.e., there can be performance measures f which is polynomial in expectation, but variance being exponential. Give formal justification for your answer (i.e., computation of expectation and variance for the function f constructed). Further, write your views on why the function f that you have constructed may/maynot be a good performance measure for any algorithm in practice.

- 2. Compute the Fourier expansion of the following Boolean functions. (Note the functions are described in the Boolean/Fourier domain, you need to convert the function to Fourier domain first.)
  - (a) Majority function MAJ<sub>3</sub> $\{-1,1\}^n \to \{-1,1\}$ , MAJ<sub>3</sub> $(x_1,x_2,x_3) = \text{sgn}(x_1 + x_2 + x_3)$ .

**Ans:** MAJ<sub>3</sub> computes Majority of three boolean variables  $x_1$  and  $x_2$  and  $x_3$ .

We can plot the truth table for the MAJ<sub>3</sub> function which is the following,

$x_1$	$x_2$	$x_3$	$\mathrm{Maj}_3(x_1, x_2, x_3)$
1	1	1	1
1	1	-1	1
1	-1	1	1
-1	1	1	1
-1	1	-1	-1
-1	-1	1	-1
1	-1	-1	-1
-1	-1	-1	-1

Following this truth table we can arrive at the equation for Maj<sub>3</sub> via interpolation. For each point  $(x_1, x_2, x_3)$  we need to cook a polynomal that is 1 at  $(x_1, x_2, x_3)$  and 0 everywhere else.

Such polynomal is the following. As  $x_i \in \{-1, 1\}$ 

$$\left(\frac{1 + a_1 x_1}{2} \cdot \frac{1 + a_2 x_2}{2} \cdot \frac{1 + a_3 x_3}{2}\right) = \begin{cases} 1 \text{ if } (a_i) = \operatorname{sgn}(x_i) \text{ and } x_i = |x_i| \\ 0 \text{ otherwise} \end{cases}$$

$$\operatorname{Maj}_{3}(x_{1}, x_{2}, x_{3}) = (+1) \left( \frac{1+x_{1}}{2} \cdot \frac{1+x_{2}}{2} \cdot \frac{1+x_{3}}{2} \right) +$$

$$(+1) \left( \frac{1+x_{1}}{2} \cdot \frac{1+x_{2}}{2} \cdot \frac{1-x_{3}}{2} \right) +$$

$$(+1) \left( \frac{1+x_{1}}{2} \cdot \frac{1-x_{2}}{2} \cdot \frac{1+x_{3}}{2} \right) +$$

$$(+1) \left( \frac{1-x_{1}}{2} \cdot \frac{1+x_{2}}{2} \cdot \frac{1+x_{3}}{2} \right) +$$

$$(-1) \left( \frac{1-x_{1}}{2} \cdot \frac{1-x_{2}}{2} \cdot \frac{1+x_{3}}{2} \right) +$$

$$(-1) \left( \frac{1+x_{1}}{2} \cdot \frac{1-x_{2}}{2} \cdot \frac{1-x_{3}}{2} \right) +$$

$$(-1) \left( \frac{1-x_{1}}{2} \cdot \frac{1-x_{2}}{2} \cdot \frac{1-x_{3}}{2} \right) +$$

$$(-1) \left( \frac{1-x_{1}}{2} \cdot \frac{1-x_{2}}{2} \cdot \frac{1-x_{3}}{2} \right) +$$

Simplifying this will result into the following equation

$$\mathsf{Maj}_3(x_1,x_2,x_3) = \frac{1}{2}x_1 + \frac{1}{2}x_2 + \frac{1}{2}x_3 - \frac{1}{2}x_1 \cdot x_2 \cdot x_3$$

(b)  $NAE_n : \{-1,1\}^n \to \mathbb{R}, NAE_n(x) = 1 \text{ if not all of the input bits are equal,}$  and 0 otherwise. Compute the Fourier coefficients for n = 4.

Ans: Using interpolation technique we can get the truth table based representation of the function which is the following

$$\begin{aligned} \mathrm{NAE}_4(x_1, x_2, x_3, x_4) &= \frac{1}{16}(1 - x_1)(1 - x_2)(1 - x_3)(1 - x_4) \cdot 0 \\ &+ \frac{1}{16}(1 - x_1)(1 - x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 - x_1)(1 - x_2)(1 + x_3)(1 + x_4) \cdot 1 \\ &+ \frac{1}{16}(1 - x_1)(1 + x_2)(1 - x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 - x_1)(1 + x_2)(1 - x_3)(1 + x_4) \cdot 1 \\ &+ \frac{1}{16}(1 - x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 - x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 - x_2)(1 - x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 - x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 - x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 - x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 - x_3)(1 + x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 - x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \\ &+ \frac{1}{16}(1 + x_1)(1 + x_2)(1 + x_3)(1 - x_4) \cdot 1 \end{aligned}$$

(c) The inner product function:  $IP_{2n}: \{-1,1\}^n \times \{-1,1\}^n \to \{-1,1\}$ , given by  $IP_{2n}(x,y) = \operatorname{sgn}(\sum_{i=1}^n x_i y_i)$ . First write down the Fourier coefficients for the case of n=2 (3 points) and then obtain a general formula (2 points). No proof needed for the general formula.

## Ans:

3. Exercise 1.8 in the book Analysis of Boolean Functions by Ryan O'Donell. Point split: 4+2+4.

The (Boolean) dual of  $f: \{-1,1\}^n \to \mathbb{R}$  is the function  $f^t$  defined by  $f^t = -f(-x)$ . The function f is said to be odd if it equals its dual, equivalently if  $f(-x) = -f(x) \, \forall x$ . The function f is said to be even if  $f(-x) = f(x) \, \forall x$ . Given

any function  $f: \{-1,1\}^n \to \mathbb{R}$  its odd part is the function  $f^{\text{odd}} = \frac{f(x) - f(-x)}{2}$  and its even part is the function  $f^{\text{even}} = \frac{f(x) + f(-x)}{2}$ 

(a) Express  $\hat{f}^t(S)$  in terms of  $\hat{f}(S)$ .

Ans:

- (b) Verify that  $f = f^{\text{even}} + f^{\text{odd}}$  and that f is odd (respectively, even) if and only if  $f = f^{\text{odd}}$ .
- 4. (a) Exercise 1.15 in the book Analysis of Boolean Functions by Ryan O'Donell.
  - (b) Let  $f: \{-1,1\}^n \to \{-1,1\}$  be a Boolean function. For  $k \in [1,n]$ , let  $f^{=k}$  be the function given by  $f^{=k}(x) = \sum_{S \subset [n], |S| = k} \widehat{f}(S) \chi_S(x)$ . Prove the formula for  $\langle f^{=k}, f^{=\ell} \rangle$  given in Exercise 1.18 of the book "Analysis of Boolean Functions" by Ryan O'Donnel.

Ans: Collaborators: None

We need to show the following

$$\langle f^{=k}, f^{=l} \rangle = \begin{cases} W^k[f] \text{ if } k = l \\ 0 \text{ otherwise} \end{cases}$$

**Definition** For  $f: \{-1,1\}^n \to \mathbb{R}$  and  $0 \le k \le n$  Fourier weight at degree k is the following

$$W^{k}[f] = \sum_{\substack{card(S)=k\\S\subseteq [n]}} \hat{f}(S)^{2} \tag{1}$$

Using Definition (1) we can arrive at the inner product asked in the question. From Parseval's theorem we can say that  $W^k[f] = ||f^{=k}||_2^2$ . Where  $f^{=k} = \sum_{card(S)=k} \hat{f}(S)\chi_S$ .

Now we calculate  $\langle f^{=k}, f^{=l} \rangle$ 

$$\langle f^{=k}, f^{=l} \rangle = \left\langle \sum_{card(S)=k} \hat{f}(S) \chi_S, \sum_{card(T)=l} \hat{f}(T) \chi_T \right\rangle$$
 (2)

$$= \sum_{card(S)=k} \sum_{card(T)=l} \hat{f}(S)\hat{f}(T)\langle \chi_S, \chi_T \rangle$$
 (3)

From class we know that the quantity  $\langle \chi_S, \chi_T \rangle = 1$  if S = T hence  $\langle \chi_S, \chi_T \rangle = 1$  iff card(S) = card(T) = k.

Continuing from (3)

$$\langle f^{=k}, f^{=l} \rangle = \sum_{card(S)=k} \hat{f}(S)^2$$
 (4)

(4) is defined to be  $W^k[f]$ . Hence the following is proved.

$$\langle f^{=k}, f^{=l} \rangle = \begin{cases} W^k[f] \text{ if } k = l \\ 0 \text{ otherwise} \end{cases}$$

- 5. We had stated in the class that Knapsack problem admits a pseudo linear time algorithm. This question is on developing such an algorithm and using it for a simple approximation algorithm for Knapsack.
  - (a) Using the standard dynamic programing approach, develop a  $O(\mathsf{poly}(n)W)$  time algorithm for the Knapsack problem with n items. Clearly mention each step and give a complexity analysis of the algorithm.

**Ans: Collaborators:** 

(b) Using the above algorithm, devlop an algorithm that given  $\epsilon$ , obtains an  $1 - \epsilon$  approximate solution (i.e., outputs a solution with profit at least  $(1-\epsilon)$  times the maximum) in time poly(n, 1/epsilon).

**Ans: Collaborators:** 

- 6. Let A be an algorithm for a Euclidean optimization problem  $\mathcal{P}$ . in the plane. Consider an input instance x and the simple perturbation model with a given parameter  $\delta \in (0, 1/2)$ . Let  $x \in ([0, 1]^2)^n$ . A  $\delta$  perturbation of x is given by  $(x_1 + y_1, \ldots, x_n + y_n)$ , where  $y_1, \ldots, y_n$  are chosen uniformly and independent on  $[-\delta, \delta]$ . The algorithm A is said to be  $(\epsilon, \delta)$  stable with respect to x, if  $Pr[|A(x) A(y)| \le \epsilon] = 1 o(1)$ , where y is a  $\delta$  perturbation of x.
  - (a) Consider the Christofide's algorithm for ETSP (Euclidean TSP) in the plane. Construct an infinite family of inputs  $X = (X_n)_{n>0}$  (i.e., for every n > 0, construct an instance  $X_n$  with O(n) many points) such that  $CHR(X_n) = (1.5 o(n))TSP(X)$ ).

**Ans: Collaborators:** 

(b) Are the instance you have constructed above  $(\epsilon, \delta)$  stable for suitable values of  $\delta$  and  $\epsilon$ ? Give a detailed justification to your answer.

#### **Ans: Collaborators:**

- 7. This question uses the same notion of perturbation as in the above question. Let  $\mathcal{P}$  be a Euclidean optimization problem in the plane and  $x \in (\mathbb{R})^2$  be an input instance and y be a  $\delta$  perturbation of x. We say that  $\mathcal{P}$  is  $(\epsilon, \delta)$  stable at x, if  $Pr[|\mathcal{P}(x) \mathcal{P}(y)| \le \epsilon] = 1 o(1)$ .
  - (a) Suppose  $\mathcal{P}$  be an NP hard Euclidean optimization problem such that  $\forall x \in (\mathbb{R}^2)^n$ ,  $\mathcal{P}$  is  $(\epsilon, \delta)$  stable at x, for some  $\epsilon$  and  $\delta$ . Can we have a smoothed polynomial time algorithm that solves  $\mathcal{P}$  exactly? Justify your answer.
  - (b) Suppose A is approximation algorithm for  $\mathcal{P}$  with some approximation performance  $\gamma$ . Assume that  $X = (X_n)$  is an infinite family of worst case instances for A (i.e., approximation ratio of A on  $X_n$  is  $\gamma o(1)$ ). Further, suppose that  $X_n$  is  $(\epsilon, \delta)$  stable for  $\mathcal{P}$  for every n. What will be the best possible smoothed approximation ratio of A under  $\delta$  perturbations? Prove your answers.
- 8. Consider the pathTSP problem: Given a set of n points  $x_1, \ldots, x_n \in [0, 1]^2$ , in the Euclidean plane, compute the minimum weight of a Hamiltonian path through the points. Define a Euclidean functional corresponding to pathTSP. Decide if the newly defined function satisfy any of the properties among subadditivity, superadditivity, smoothness, growth bound. Give detailed arguments justifying your answer.

### Bonus

1. Let X be an instance of the k-means clusturing problem, with |X| = n. Let  $B_1, \ldots, B_r$  be a sequence of clusturings obtained by the k-means algorithm. Show that there is some constant c such that if r > c, then at least one of the clusters among the clusterings  $B_1, \ldots, B_r$ , has seen at least three different configurations. (Note: in the class we had shown this for  $r > 2^k$ , using the pigeonhole principle.)