



# Part 1: Priority Queue

Project 5



# Priority Queue

- Implementing a priority queue through a binary heap.
- `PQ *createQueue(int (*compare)());`
  - return a pointer to a new priority queue using `compare` as its comparison function
- `void destroyQueue(PQ *pq);`
  - deallocate memory associated with the priority queue pointed to by `pq`
- `int numEntries(PQ *pq);`
  - return the number of entries in the priority queue pointed to by `pq`
- `void addEntry(PQ *pq, void *entry);`
  - add entry to the priority queue pointed to by `pq`
- `void *removeEntry(PQ *pq);`
  - remove and return the smallest entry from the priority queue pointed to by `pq`



# Structure

```
struct pqueue {  
    int count;          /* number of entries in array*/  
    int length;         /* length of allocated array */  
    void **data;        /* allocated array of entries */  
    int (*compare)();   /* comparison function */  
};
```



# Dynamically allocated min heap

- Set initial length to 10, dynamically grow array in `addElement` when needed
- When adding, assume element starts at the end and reheap up
- When removing, save the root and replace it with the element at the end, then reheap down



# addEntry and removeEntry

- Parent =  $((x) - 1) / 2$
- Left child =  $((x) * 2 + 1)$
- Right child =  $((x) * 2 + 2)$
- Tip: When reheaping, do not move the new entry until after you find out where to put it



# Testing

- Generic data-type -> use the passed in comparison function
- Test with sort.c
  - Compile with “make sort”
  - Run with “./sort”
  - Works exactly like radix.c from the previous lab
- 2nd week’s lab will use 1st week’s lab!