Advanced Behaviour



Dynamic Binders & Faults

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Previously on Jolie

OutputPorts information

Locations and protocols (called binding information) of OutputPorts can be accessed at runtime

```
outputPort MyPort {
  Location: "socket://p.com:8000"
  Protocol: sodep
  Interfaces: MyInterface
main
  println@Console(
   MyPort.location )();
// prints "socket://p.com:8000"
  println@Console(
   MyPort.protocol )()
   prints "sodep"
```

Dynamic Binding

Locations and protocols (called binding information) of OutputPorts can be changed at runtime

```
outputPort P {
 Interfaces: MyInterface
main
 P.location = "socket://localhost:8000";
 P.protocol = "sodep"
```

Dynamic Binding

The Jolie Standard Library at "types/Binding.iol" provides the **Biding** type

```
type Binding:void {
  .location:string
  .protocol?:string { ? }
}
```

Dynamic Binding

```
interface RegistryInterface {
   RequestResponse: getBinding( string )( Binding )
inputPort In {
Location: ...
Protocol: ...
Interfaces: RegistryInterface
main
   getBinding( name )( b ){
      if ( name == "LaserPrinter" ){
         b.location = "socket://p1.com:80/";
         b.protocol = "sodep"
      } else if ( name == "InkJetPrinter" ) {
         b.location = "socket://p2.it:80/";
         b.protocol = "soap"
```

Fault Handling

Four concepts behind Jolie's fault handling:

- Scopes;
- Faults;
- Throw;
- Install.

Fault Handling - Scopes We already met **scopes** talking about parallel composition

Good practice: use **scope** {} o explicitly group parallel statements when mixed with sequences

```
print@Console( "A" )()|
print@Console( "B" )();
print@Console( "C" )()
```

is equal to

But this is easier to understand

```
{ print@Console( "A" )()|
  print@Console( "B" )()
};
print@Console( "C" )()
```

Fault Handling - Scopes A scope is a behavioural container denoted by a unique name and able to manage faults.

```
main { ... } & init { ... }
```

Are (special) scopes named main and init

Fault Handling - Scopes A scope is a behavioural container denoted by a unique name and able to manage faults.

{ ... }

This is an unnamed scope

Fault Handling - Scopes A scope is a behavioural container denoted by a unique name and able to manage faults.

```
scope( scope_name )
{
  // code
}
```

Fault Handling - Faults

A fault is a **signal**, identified by its name, raised by a behaviour **towards the enclosing scope**.

Jolie provides the statement throw to raise faults.

```
scope( scope_name )
{
  // omitted code
  throw( fault_name )
}
```

Fault Handling - Faults

Jolie provides the statement throw to raise faults.

```
scope( division )
n = 42;
d = 0;
 if( d == 0 ) {
 throw( DivisionByZero )
} else {
  result = n/d
```



Thrown unhandled fault: DivisionByZero

Fault Handling - Install

The install statement provides the installation of dynamic fault handlers.

```
scope( scope_name )
  install ( fault_name1 => /* fault handling code */,
            /* ... */ => /* fault handling code */,
            fault_nameN => /* fault handling code */
 );
 // omitted code
  throw( fault_name )
```

Fault Handling - Install

install joins a fault to a process and its handler is executed when the scope catches the fault.

```
scope( scope_name )
  install ( fault_name1 => /* fault handling code */,
            /* ... */ => /* fault handling code */,
            fault_nameN => /* fault handling code */
 );
 // omitted code
  throw( fault_name )
```

Fault Handling - Install

install joins a fault to a process and its handler is executed when the scope catches the fault.

```
scope( division )
install( DivisionByZero =>
println@Console(
  "Caught division by zero!" )()
 n = 42;
 if( d == 0 ) {
 throw( DivisionByZero )
} else {
  result = n/d
```

Will (gracefully) print

Caught division by zero!

Fault handling - Install priority

Jolie always prioritises the install primitive when composed in parallel with other (possibly faulty) instructions. This makes handler installation predictable.

Fault handling - Install priority

Install always goes first

```
scope( s )
 throw(f)
 install( f =>
   println@Console( "Fault caught!" )()
```

Uncaught fault signals in a request-response body are automatically sent to the invoker. Invokers are always notified of unhandled faults.

RequestResponse operations declaration can define faults (and their data type) that could be sent back to invokers.

Fault handling - Raising faults with Operations RequestResponse operations declaration can define faults (and their data type) that could be sent back to invokers.

```
interface MyInterface {
  RequestResponse:
    RR1(t1)(t2) throws error1(e_type1)
                          error2( e_type2 )
     //...
    RRN( ... )( ... ) throws errorN( e_typeN )
```

Fault handling - Raising faults with Operations RequestResponse operations declaration can define faults (and their data type) that could be sent back to invokers.

```
type DivFaultType: void{
    .faultError: string
}
interface DivisionInterface {
    RequestResponse: divide( DivType )( int ) throws
        DivisionByZero( DivFaultType )
}
```

```
type DivType: void { .n: int .d: int } }
type DivFaultType: void { .error: string }
interface DivisionInterface {
RequestResponse: divide( DivType )( int ) throws DivisionByZero( DivFaultType )
inputPort In {
Location: // ...
Protocol: // ...
Interfaces: DivisionInterface
main
  divide( request )( request.n/request.d ){
   if( request.d == 0 ){
      throw( DivisionByZero, { .error = "You passed 0 as denominator" } )
```

```
type DivType: void { .n: int .d: int } }
type DivFaultType: void { .error: string }
interface DivisionInterface {
RequestResponse: divide( DivType )( int ) throws DivisionByZero( DivFaultType )
inputPort In {
Location: // ...
Protocol: // ...
Interfaces: DivisionInterface
main
  divide( request )( request.n/request.d ){
   if( request.d == 0 ){
      throw( DivisionByZero, { .error = "You passed 0 as denominator" } )
```

```
type DivType: void { .n: int .d: int } }
type DivFaultType: void { .error: string }
interface DivisionInterface {
RequestResponse: divide( DivType )( int ) throws
DivisionByZero( DivFaultType )
inputPort In {
Location: // ...
Protocol: // ...
Interfaces: DivisionInterface
main
  divide( request )( request.n/request.d ){
   if( request.d == 0 ){
      throw( DivisionByZero, { .error = "You
passed 0 as denominator" } )
```

Client

```
outputPort Out {
Location: // ...
Protocol: // ...
Interfaces: DivisionInterface
main
  req.n = 42;
  req.d = 0;
  divide@Out( req )( res )
```

Will print

Thrown unhandled fault: DivisionByZero

```
type DivType: void { .n: int .d: int } }
type DivFaultType: void { .error: string }
interface DivisionInterface {
RequestResponse: divide( DivType )( int ) throws
DivisionByZero( DivFaultType )
inputPort In {
Location: // ...
Protocol: // ...
Interfaces: DivisionInterface
main
  divide( request )( request.n/request.d ){
   if( request.d == 0 ){
      throw( DivisionByZero, { .error = "You
passed 0 as denominator" } )
```

Client

```
// ...
scope( divScope )
{
  install( DivisionByZero =>
    println@Console(
    divScope.DivisionByZero
    .error )()
  );
  req.n = 42;
  req.d = 0;
  divide@Out( req )( res )
  }
}
```

Will (gracefully) print

You passed 0 as denominator

Fault handling - Termination & Compensation Besides using a **specific fault** name, install can refer to

this or

default keywords

Useful to handle recovery

this refers to the enclosing scope and is used to handle its termination.

```
scope ( scope_name )
{
  install( this =>
    println@Console( "Recovery for scope_name" )()
  );
  println@Console( "I am scope_name" )()
}
throw( a_fault )
```

default is the fallback for all faults that do not have a specific fault handler.

```
install( default =>
    println@Console( "Recovery for all faults" )()
scope ( scope_name )
  install( this =>
    println@Console( "Recovery for scope_name" )()
  println@Console( "I am scope_name" )()
throw(a_fault)
```

When a scope terminates, first it terminates its own child scopes and then executers its recovery handler.

```
scope( granpa )
install( this =>
  println@Console( "rec. granpa" )()
 scope( dad )
   install( this =>
    println@Console( "rec. dad" )()
  scope ( son )
   install( this =>
    println@Console( "rec. son" )()
   sleep@Time( 500 )();
   println@Console( "son's code" )()
throw( a_fault )
```

Recovery
handlers can be
dynamically
updated like
fault handlers.

```
scope( scope_name )
 println@Console( "step 1" )();
 install( this =>
  println@Console( "rec step 1" )() );
 println@Console( "step 2" )();
 install( this =>
  println@Console( "rec step 2" )() );
 println@Console( "step 3" )();
 install( this =>
  println@Console( "rec step 3" )() );
 println@Console( "step 4" )();
 install( this =>
  println@Console( "rec step 4" )() )
throw( a_fault )
```

Recovery
handlers can
also be built
incrementally
via the current
handler cH

```
scope( scope_name )
 println@Console( "step 1" )();
 install( this =>
  println@Console( "rec step 1" )()
);
 println@Console( "step 2" )();
 install( this =>
  cH; println@Console( "rec step 2" )()
 );
 println@Console( "step 3" )();
 install( this =>
  cH; println@Console( "rec step 3" )()
);
 println@Console( "step 4" )();
 install( this =>
  cH; println@Console( "rec step 4" )()
throw( a_fault )
```

Compensation handles the recovery of a (successfully) executed scope.

Compensation is invoked by means of the comp statement, which can be used only within a handler.

```
install( a_fault =>
 println@Console( "a_fault handler" )();
 comp( myScope )
scope( myScope )
 install( this =>
  println@Console( "rec step 1" )()
 println@Console( "Code of myScope" )();
 install( this =>
 cH; println@Console( "rec step 2" )()
throw(a_fault)
```

Within fault handlers,
Jolie provides the ^
operator to "freeze" the
value of a variable.

(Useful for error reporting and debugging)

```
install( a_fault =>
 comp( example_scope )
scope( example_scope )
 install( this =>
   println@Console( "init rec" )()
  i = 1;
  while( true ){
   install( this =>
    cH;
    println@Console( "rec step" + ^i)()
throw( a_fault )
```