

Math 2311 — Assignment 2

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Contents

1	Show that $S = \{1 + 2x + x^2, 2 + 9x, 3 + 3x + 4x^2\}$ is a basis for P_2 and write $p = 2 + 17x - 3x^2$ as a linear combination of vectors in S. Finally, write $[p]_S$.	3
1.a	Show that $S = \{1 + 2x + x^2, 2 + 9x, 3 + 3x + 4x^2\}$ is a basis for P_2	3
1.b	Write $\vec{p} = 2 + 17x - 3x^2$ as a linear combination of vectors in S	4
1.c	Finally, write $[p]_S$	4
2	Recall the standard basis of \mathbb{R}^3, $\vec{e}_1 = [1 \ 0 \ 0]^T$, $\vec{e}_2 = [0 \ 1 \ 0]^T$, $\vec{e}_3 = [0 \ 0 \ 1]^T$	5
2.a	Consider the matrix A Does the set of vectors $\{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ form a basis for \mathbb{R}^3 .	5
2.b	Consider the matrix B Does the set of vectors $\{B\vec{e}_1, B\vec{e}_2, B\vec{e}_3\}$ form a basis for \mathbb{R}^3 ?	5
2.c	Make a conjecture of the form “ $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 if and only if A (<i>insert appropriate property of A here</i>)”	5
2.d	Bonus: Prove your conjecture.	6
3	For each of the following subspaces of M_{33} find a basis and state the dimension.	7
3.a	$W_1 = \{A \in M_{33} A \text{ is a diagonal matrix}\}$	7
3.b	$W_2 = \{A \in M_{33} A = A^T\}$ (the symmetric matrices)	7
3.c	$W_1 = \{A \in M_{33} A = -A^T\}$ (the anti-symmetric matrices)	7
4	Find a basis for the subspace of P^3 spanned by the following polynomials (vectors):	
	$p_1 = 1 + x + 3x^2 + 4x^3$, $p_2 = 1 + 2x^2 + 3x^3$, $p_3 = x + x^2 + 2x^3$, $p_4 = 1 + x + 3x^2 + 5x^3$	8
5	Let $\vec{x} = [1 \ 2 \ 3]^T$, $\mathcal{B} = \{[1 \ 0 \ 0]^T, [1 \ 1 \ 0]^T, [1 \ 1 \ 1]^T\}$, and $\mathcal{C} = \{[1 \ 1 \ 0]^T, [0 \ 1 \ 1]^T, [1 \ 0 \ 1]^T\}$.	9
5.a	Find $[\vec{x}]_{\mathcal{B}}$	9
5.b	Find $[\vec{x}]_{\mathcal{C}}$	9
5.c	Find $P_{\mathcal{C} \leftarrow \mathcal{B}}$ and compute $P_{\mathcal{C} \leftarrow \mathcal{B}}[\vec{x}]_{\mathcal{B}}$	9
5.d	Find $P_{\mathcal{B} \leftarrow \mathcal{C}}$ and compute $P_{\mathcal{B} \leftarrow \mathcal{C}}[\vec{x}]_{\mathcal{C}}$	10
6	Problem 6	11
6.a	Find a basis for each of $\text{null}(A)$, $\text{row}(A)$, $\text{col}(A)$, and state the dimension of each of these subspaces.	11
6.b	Is the vector $\vec{b} = [4 \ 6 \ -2]^T$ in the column space of A ? If so, write \vec{b} as a linear combination of the columns of A	12

1 Show that $S = \{1 + 2x + x^2, 2 + 9x, 3 + 3x + 4x^2\}$ is a basis for P_2 and write $p = 2 + 17x - 3x^2$ as a linear combination of vectors in S . Finally, write $[p]_S$.

1.a Show that $S = \{1 + 2x + x^2, 2 + 9x, 3 + 3x + 4x^2\}$ is a basis for P_2

Solution: vectors $\{\vec{p}_1, \vec{p}_2, \vec{p}_3\}$ are a basis for P_3

Proof. The set $S = \{\vec{p}_1, \vec{p}_2, \vec{p}_3\}$ in a vector space P_2 , is called a basis if.

- (1) S spans P_2 .
- (2) S is linearly independent.

To prove that the vectors $\text{span}\{S\} = P_2$ we must show that every vector $\vec{p} = a_0 + a_1x + a_2x^2$ in P_2 can be expressed as $c_1\vec{p}_1 + c_2\vec{p}_2 + c_3\vec{p}_3 = \vec{p}$

$$c_1(1 + 2x + x^2) + c_2(2 + 9x) + c_3(3 + 3x + 4x^2) = \vec{v} \quad (1)$$

$$\begin{aligned} 1c_1 + 2c_2 + 3c_3 &= a_0 \\ 2c_1 + 9c_2 + 3c_3 &= a_1 \\ 1c_1 + 0c_2 + 4c_3 &= a_2 \end{aligned}$$

To prove linear independence we must show that $c_1\vec{p}_1 + c_2\vec{p}_2 + c_3\vec{p}_3 = \vec{0}$ has only the trivial solution.

$$c_1(1 + 2x + x^2) + c_2(2 + 9x) + c_3(3 + 3x + 4x^2) = \vec{0} \quad (2)$$

$$\begin{aligned} 1c_1 + 2c_2 + 3c_3 &= 0 \\ 2c_1 + 9c_2 + 3c_3 &= 0 \\ 1c_1 + 0c_2 + 4c_3 &= 0 \end{aligned}$$

Thus, we have reduced the problem to showing that the homogenous system (2) has only the trivial solution, and that the nonhomogenous system (1) is consistent for all values c_1, c_2, c_3 . The two systems have the same coefficient matrix.

$$A = \left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 2 & 9 & 3 & 0 \\ 1 & 0 & 4 & 0 \end{array} \right]$$

We will prove both results by showing that $\det(A) \neq 0$

$$\begin{aligned} \det(A) &= (1) \begin{vmatrix} 2 & 3 \\ 9 & 3 \end{vmatrix} + (4) \begin{vmatrix} 1 & 2 \\ 2 & 9 \end{vmatrix} \\ &= 1[(2)(3) - (3)(9)] + 4[(1)(9) - (2)(2)] = -1. \end{aligned}$$

This proves that $\{\vec{p}_1, \vec{p}_2, \vec{p}_3\}$ is a basis for P_2 . □

1.b Write $\vec{p} = 2 + 17x - 3x^2$ as a linear combination of vectors in S

Solution: $\vec{p} = (1)(1 + 2x + x^2) + (2)(2 + 9x) + (-1)(3 + 3x + 4x^2)$

Proof. The equation $c_1\vec{p}_1 + c_2\vec{p}_2 + c_3\vec{p}_3 = \vec{p}$ which can be written as the linear system

$$\begin{array}{rrrrr} 1c_1 & + & 2c_2 & + & 3c_3 & = & 2 \\ 2c_1 & + & 9c_2 & + & 3c_3 & = & 17 \\ 1c_1 & + & 0c_2 & + & 4c_3 & = & -3 \end{array}$$

is an expression for a vector \vec{p} in terms of the basis S , with scalars c_1, c_2, c_3 being the coordinates of \vec{p} relative to the basis S . Whose augmented matrix has the reduced row echelon form,

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -1 \end{array} \right]$$
$$c_1 = 1, c_2 = 2, c_3 = -1.$$

This gives $\vec{p} = (1)(1 + 2x + x^2) + (2)(2 + 9x) + (-1)(3 + 3x + 4x^2)$

□

1.c Finally, write $[p]_S$.

Solution: $[p]_S = [1 \ 2 \ -1]^T$

Proof. We use c_1, c_2, c_3 from 1.b to construct the coordinate vector $[1 \ 2 \ -1]^T$ of \vec{p} relative to S . □

2 Recall the standard basis of \mathbb{R}^3 , $e_1 = [1 \ 0 \ 0]^T$, $e_2 = [0 \ 1 \ 0]^T$, $e_3 = [0 \ 0 \ 1]^T$

2.a Consider the matrix $A = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 3 & 2 \\ 0 & 3 & 2 \end{bmatrix}$. Does the set of vectors $S_1 = \{Ae_1, Ae_2, Ae_3\}$ form a basis for \mathbb{R}^3 ?

Solution: S_1 is a basis for \mathbb{R}^3

Proof. To see if the vectors in S_1 are a basis for \mathbb{R}^3 , we will verify A is invertable.

$$[0 \ 0 \ 0]^T = c_1 Ae_1 + c_2 Ae_2 + c_3 Ae_3$$

$$\begin{aligned} 1c_1 + 0c_2 + 2c_3 &= 0 \\ 1c_1 + 3c_2 + 2c_3 &= 0 \\ 0c_1 + 3c_2 + 2c_3 &= 0 \end{aligned}$$

The augmented matrix has the reduced row echelon form,

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] = I_3$$

From inspecting the pivots of $rref(A)$, we can see that $col(A) = \{[1 \ 1 \ 0]^T, [0 \ 3 \ 3]^T, [2 \ 2 \ 2]^T\}$, is a basis for \mathbb{R}^3 , but $A = [Ae_1 \mid Ae_2 \mid Ae_3] \implies col(A) = S_1 \therefore S_1$ is a basis for \mathbb{R}^3 . \square

2.b Consider the matrix $B = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 3 & 0 \\ 0 & 3 & -2 \end{bmatrix}$. Does the set of vectors $S_2 = \{Be_1, Be_2, Be_3\}$ form a basis for \mathbb{R}^3 ?

Solution: S_2 is not a basis for \mathbb{R}^3

Proof. To see if the vectors in S_2 are a basis for \mathbb{R}^3 , we will verify B is invertable.

$$[0 \ 0 \ 0]^T = c_1 Be_1 + c_2 Be_2 + c_3 Be_3$$

$$\begin{aligned} 1c_1 + 0c_2 + 2c_3 &= 0 \\ 1c_1 + 3c_2 + 0c_3 &= 0 \\ 0c_1 + 3c_2 + -2c_3 &= 0 \end{aligned}$$

The augmented matrix has the reduced row echelon form,

$$\left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1 & -\frac{2}{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \neq I_3$$

S_2 is not a basis for \mathbb{R}^3 because $rank(B) = 2 \neq dim(\mathbb{R}^3)$ \square

2.c Make a conjecture of the form “ $S = \{Ae_1, Ae_2, Ae_3\}$ forms a basis for \mathbb{R}^3 if and only if A (insert appropriate property of A here)”.

Conjecture $S = \{Ae_1, Ae_2, Ae_3\}$ forms a basis for \mathbb{R}^3 if and only if A (is an invertible matrix).

2.d Bonus: Prove your conjecture.

We will prove our conjecture $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 if and only if A (is an invertible matrix), using our list of equivalent statements. Since we have already proven if A is invertible, then $A\vec{x} = \vec{0}$ has only the trivial solution, we will use this. Asserting if R is any row echelon form of a 3×3 matrix A , then either R has at least one row of zeros, or R is the identity matrix I_3 .

We will prove the reverse direction first "if A is an invertible matrix, then $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 ."

Proof. Suppose R is the identity matrix I_3 , then A has an inverse, and $A\vec{x}$ is a linear combination of the column vectors of A . Since $A\vec{x} = \vec{0}$ has only the trivial solution, the column vectors of A must be linearly independent. Since we know that the 3 column vectors of A are linearly independent in the 3-dimensional vector space \mathbb{R}^3 , they must span \mathbb{R}^3 , and form a basis for \mathbb{R}^3 .

$$\begin{aligned} A\vec{e}_1 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = (1) \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} + (0) \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} + (0) \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} \\ A\vec{e}_2 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = (0) \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} + (1) \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} + (0) \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} \\ A\vec{e}_3 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = (0) \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} + (0) \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} + (1) \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} \\ A &= [A\vec{e}_1 \mid A\vec{e}_2 \mid A\vec{e}_3] \\ &\implies \text{col}(A) = S \end{aligned}$$

Therefore $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ is a basis for \mathbb{R}^3 □

We will now prove the forward direction "if $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 then A is an invertible matrix." by proving its contrapositive "if A is not an invertible matrix, then $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ does not form a basis for \mathbb{R}^3 "

Proof. Suppose R has at least one row of zeros, then A has no inverse. We know from analysis of the positions of the 0's and 1's of R that elementary row operations don't change the dimension of the row space or the column space of our matrix, so it must be true that

$$\dim(\text{row space of } A) = \dim(\text{row space of } R) \text{ and } \dim(\text{column space of } A) = \dim(\text{column space of } R).$$

Since these two numbers are the same, the row and column space have the same dimension $\text{rank}(A)$; the dimension of the null space of A is $\text{nullity}(A)$

$$\begin{aligned} 0 &< \text{nullity}(A) \leq \dim(\mathbb{R}^3) \\ \text{rank}(A) + \text{nullity}(A) &= \dim(\mathbb{R}^3) \\ \text{nullity}(A) &= \dim(\mathbb{R}^3) - \text{rank}(A) \\ \implies 0 &< [\dim(\mathbb{R}^3) - \text{rank}(A)] \leq \dim(\mathbb{R}^3) \implies \dim(\mathbb{R}^3) > \text{rank}(A) \geq 0 \\ \therefore \text{rank}(A) &< \dim(\mathbb{R}^3) \end{aligned}$$

This proves, if R has atleast one row of zeros then $\text{rank}(A) < \dim(\mathbb{R}^3) \therefore S$ is not a basis for \mathbb{R}^3 □

3 For each of the following subspaces of M_{33} find a basis and state the dimension.

3.a $W_1 = \{A \in M_{33} | A \text{ is a diagonal matrix}\}$

Solution: $\dim(W_1) = 3$

Proof.

$$D = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}, A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\therefore D = aA_1 + bA_2 + cA_3$$

The matrices A_1, A_2, A_3 form a basis for W_1 consequently, the dimension of W_1 is 3. \square

3.b $W_2 = \{A \in M_{33} | A = A^T\}$ (the symmetric matrices)

Solution: $\dim(W_2) = 6$

Proof.

$$S = \begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix}, A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$A_4 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_5 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, A_6 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\therefore S = aA_1 + bA_2 + cA_3 + dA_4 + eA_5 + fA_6$$

The matrices $A_1, A_2, A_3, A_4, A_5, A_6$ form a basis for W_2 consequently, the dimension of W_2 is 6. \square

3.c $W_3 = \{A \in M_{33} | A = -A^T\}$ (the anti-symmetric matrices)

Solution: $\dim(W_3) = 3$

Proof.

$$S = \begin{bmatrix} 0 & b & c \\ -b & 0 & d \\ -c & -d & 0 \end{bmatrix}, A_1 = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, A_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

$$\therefore S = aA_1 + bA_2 + cA_3$$

The matrices A_1, A_2, A_3 form a basis for W_3 consequently, the dimension of W_3 is 3. \square

4 Find a basis for the subspace of P^3 spanned by the following polynomials (vectors):

$$p_1 = 1 + x + 3x^2 + 4x^3, \quad p_2 = 1 + 2x^2 + 3x^3, \quad p_3 = x + x^2 + 2x^3, \quad p_4 = 1 + x + 3x^2 + 5x^3$$

Solution: the vectors $\vec{p}_1, \vec{p}_2, \vec{p}_3$ form a basis for $\text{span}\{p_1, p_2, p_3, p_4\}$

Proof. The equation $k_1\vec{p}_1 + k_2\vec{p}_2 + k_3\vec{p}_3 + k_4\vec{p}_4 = \vec{0}$ can be written as a linear system

$$\begin{aligned} 1k_1 + 1k_2 + 0k_3 + 1k_4 &= 0 \\ 1k_1 + 0k_2 + 1k_3 + 1k_4 &= 0 \\ 3k_1 + 2k_2 + 1k_3 + 3k_4 &= 0 \\ 4k_1 + 3k_2 + 2k_3 + 5k_4 &= 0 \end{aligned}$$

whose augmented matrix has the reduced row echelon form

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$
$$\implies k_1 = 0, \quad k_2 = -s, \quad k_3 = -s, \quad k_4 = s$$

removing vector \vec{p}_4 gives $\text{span}\{p_1, p_2, p_3\} = \text{span}\{p_1, p_2, p_3, p_4\}$. Since the vector equation $k_1\vec{p}_1 + k_2\vec{p}_2 + k_3\vec{p}_3 = \vec{0}$ has only the trivial solution. We conclude that the vectors $\vec{p}_1, \vec{p}_2, \vec{p}_3$ form a basis for $\text{span}\{p_1, p_2, p_3, p_4\}$. \square

5 Let $\vec{x} = [1 \ 2 \ 3]^T$, $\mathcal{B} = \{[1 \ 0 \ 0]^T, [1 \ 1 \ 0]^T, [1 \ 1 \ 1]^T\}$, and $\mathcal{C} = \{[1 \ 1 \ 0]^T, [0 \ 1 \ 1]^T, [1 \ 0 \ 1]^T\}$.

5.a Find $[\vec{x}]_{\mathcal{B}}$

Solution: $[\vec{x}]_{\mathcal{B}} = [-1 \ -1 \ 3]^T$

Proof. By inspection: $\vec{x} = (-1)[1 \ 0 \ 0]^T + (-1)[1 \ 1 \ 0]^T + (3)[1 \ 1 \ 1]^T$ $[\vec{x}]_{\mathcal{B}} = [-1 \ -1 \ 3]^T$ \square

5.b Find $[\vec{x}]_{\mathcal{C}}$

Solution: $[\vec{x}]_{\mathcal{C}} = [0 \ 2 \ 1]^T$

Proof. By inspection: $\vec{x} = (0)[1 \ 1 \ 0]^T + (2)[0 \ 1 \ 1]^T + (1)[1 \ 0 \ 1]^T \implies [\vec{x}]_{\mathcal{C}} = [0 \ 2 \ 1]^T$ \square

5.c Find $P_{\mathcal{C} \leftarrow \mathcal{B}}$ and compute $P_{\mathcal{C} \leftarrow \mathcal{B}}[\vec{x}]_{\mathcal{B}}$

$$\text{Solutions : } P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} 1/2 & 1 & 1/2 \\ -1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 \end{bmatrix}; [\vec{x}]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}}[\vec{x}]_{\mathcal{B}} = [0 \ 2 \ 1]^T$$

Proof.

$$\begin{aligned} \text{Partitioned matrix } [\mathcal{C} \mid \mathcal{B}] &= \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \\ \text{Transition matrix } [I_3 \mid \mathcal{C} \leftarrow \mathcal{B}] &= \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1/2 & 1 & 1/2 \\ 0 & 1 & 0 & -1/2 & 0 & 1/2 \\ 0 & 0 & 1 & 1/2 & 0 & 1/2 \end{array} \right] \\ P_{\mathcal{C} \leftarrow \mathcal{B}} &= \begin{bmatrix} 1/2 & 1 & 1/2 \\ -1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} [\vec{x}]_{\mathcal{C}} &= P_{\mathcal{C} \leftarrow \mathcal{B}}[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} 1/2 & 1 & 1/2 \\ -1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 \end{bmatrix} [-1 \ -1 \ 3]^T \\ &= [-1] \begin{bmatrix} 1/2 \\ -1/2 \\ 1/2 \end{bmatrix} + [-1] \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + [3] \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \end{bmatrix} \\ &= [0 \ 2 \ 1]^T \end{aligned}$$

\square

5.d Find $P_{\mathcal{B} \leftarrow \mathcal{C}}$ and compute $P_{\mathcal{B} \leftarrow \mathcal{C}}[\vec{x}]_{\mathcal{C}}$

$$\text{Solutions : } P_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} ; [\vec{x}]_{\mathcal{B}} = P_{\mathcal{B} \leftarrow \mathcal{C}}[\vec{x}]_{\mathcal{C}} = [-1 \ -1 \ 3]^T$$

Proof.

$$\begin{aligned} \text{Partitioned matrix } [\mathcal{B} \mid \mathcal{C}] &= \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right] \\ \text{Transition matrix } [I_3 \mid \mathcal{B} \leftarrow \mathcal{C}] &= \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right] \\ P_{\mathcal{B} \leftarrow \mathcal{C}} &= \begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} [\vec{x}]_{\mathcal{B}} = P_{\mathcal{B} \leftarrow \mathcal{C}}[\vec{x}]_{\mathcal{C}} &= \begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} [0 \ 2 \ 1]^T \\ &= [0] \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + [2] \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + [1] \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \\ &= [-1 \ -1 \ 3]^T \end{aligned}$$

□

6 Let $A = \begin{bmatrix} 1 & 4 & 5 & 2 \\ 2 & 1 & 3 & 0 \\ -1 & 3 & 2 & 2 \end{bmatrix}$

6.a Find a basis for each of $\text{null}(A)$, $\text{row}(A)$, $\text{col}(A)$, and state the dimension of each of these subspaces.

<p><i>Bases :</i></p> $\text{null}(A) = \{ [-1 \ -1 \ 1 \ 0]^T, [\frac{2}{7} \ -\frac{4}{7} \ 0 \ 1]^T \}$ <p><i>Solutions :</i></p> $\text{row}(A) = \{ [1 \ 0 \ 1 \ -\frac{2}{7}], [0 \ 1 \ 1 \ \frac{4}{7}] \}$ $\text{col}(A) = \{ [1 \ 2 \ -1]^T, [4 \ 1 \ 3]^T \}$ <p><i>Dimensions :</i></p> $\text{rank}(A) = \text{nullity}(A) = 2$	
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Proof.

$$\begin{aligned}
 \text{rref}(A) &= \begin{bmatrix} 1 & 0 & 1 & -\frac{2}{7} \\ 0 & 1 & 1 & \frac{4}{7} \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 \therefore [x_1 \ x_2 \ x_3 \ x_4]^T &= [-\mathcal{S} + \frac{2}{7}\mathcal{T}, -\mathcal{S} - \frac{4}{7}\mathcal{T}, \mathcal{S}, \mathcal{T}]^T \\
 &= \mathcal{S}[-1 \ -1 \ 1 \ 0]^T + \mathcal{T}[\frac{2}{7} \ -\frac{4}{7} \ 0 \ 1]^T \\
 \implies \text{null}(A) &= \{ [-1 \ -1 \ 1 \ 0]^T, [\frac{2}{7} \ -\frac{4}{7} \ 0 \ 1]^T \} \\
 \implies \text{row}(A) &= \{ [1 \ 0 \ 1 \ -\frac{2}{7}], [0 \ 1 \ 1 \ \frac{4}{7}] \} \\
 \implies \text{col}(A) &= \{ [1 \ 2 \ -1]^T, [4 \ 1 \ 3]^T \} \\
 \implies \text{rank}(A) &= 2 \\
 \implies \text{nullity}(A) &= 2
 \end{aligned}$$

$\text{row}(A)$ and $\text{null}(A)$ are 2 dimensional subspaces of R^4 , $\text{col}(A)$ is a 2 dimensional subspace of R^3 . □

6.b Is the vector $\vec{b} = [4 \ 6 \ -2]^T$ in the column space of A ? If so, write \vec{b} as a linear combination of the columns of A .

Solution: Yes $\vec{b} \in \text{col}(A) \wedge \vec{b} = \frac{20}{7}[1 \ 2 \ -1]^T + \frac{2}{7}[4 \ 1 \ 3]^T + (0)[5 \ 3 \ 2]^T + (0)[2 \ 0 \ 2]^T$
--

let $\vec{c1} = [1 \ 2 \ -1]^T$, $\vec{c2} = [4 \ 1 \ 3]^T$, and let $C = [\vec{c1} \ | \ \vec{c2}]$ we will show $\vec{b} \in \text{col}(A) \implies \text{rank}(C) = \text{rank}(C \ | \ \vec{b})$

Proof.

$$[4 \ 6 \ -2]^T = k_1[1 \ 2 \ -1]^T + k_2[4 \ 1 \ 3]^T$$

which can be expressed as,

$$\begin{array}{rcl} 1k_1 & + & 4k_2 = 4 \\ 2k_1 & + & 1k_2 = 6 \\ -1k_1 & + & 3k_2 = -2 \end{array}$$

whose augmented matrix has the reduced row echelon form

$$\left[\begin{array}{cc|c} 1 & 0 & \frac{20}{7} \\ 0 & 1 & \frac{2}{7} \\ 0 & 0 & 0 \end{array} \right]$$

because $\text{rank}(C) = 2$ and $\text{rank}(C \ | \ \vec{b}) = 2$ the system is consistent, so \vec{b} is in the column space of A . $\therefore \vec{b}$ as a linear combination of the columns of A can be expressed by the following,
 $\vec{b} = \frac{20}{7}[1 \ 2 \ -1]^T + \frac{2}{7}[4 \ 1 \ 3]^T + (0)[5 \ 3 \ 2]^T + (0)[2 \ 0 \ 2]^T$ □