

1 Recall the standard basis of \mathbb{R}^3 , $\vec{e}_1 = [1 \ 0 \ 0]^T$, $\vec{e}_2 = [0 \ 1 \ 0]^T$, $\vec{e}_3 = [0 \ 0 \ 1]^T$

1.a Consider the matrix $A = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 3 & 2 \\ 0 & 3 & 2 \end{bmatrix}$. Does the set of vectors $S_1 = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ form a basis for \mathbb{R}^3 ?

Solution: S_1 is a basis for \mathbb{R}^3

Proof. To see if the vectors in S_1 are a basis for \mathbb{R}^3 , we will verify A is invertable.

$$[0 \ 0 \ 0]^T = c_1 A\vec{e}_1 + c_2 A\vec{e}_2 + c_3 A\vec{e}_3$$

$$\begin{aligned} 1c_1 + 0c_2 + 2c_3 &= 0 \\ 1c_1 + 3c_2 + 2c_3 &= 0 \\ 0c_1 + 3c_2 + 2c_3 &= 0 \end{aligned}$$

The augmented matrix has the reduced row echelon form,

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] = I_3$$

From inspecting the pivots of $rref(A)$, we can see that $col(A) = \{[1 \ 1 \ 0]^T, [0 \ 3 \ 3]^T, [2 \ 2 \ 2]^T\}$, is a basis for \mathbb{R}^3 , but $A = [A\vec{e}_1 \mid A\vec{e}_2 \mid A\vec{e}_3] \implies col(A) = S_1 \therefore S_1$ is a basis for \mathbb{R}^3 . \square

1.b Consider the matrix $B = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 3 & 0 \\ 0 & 3 & -2 \end{bmatrix}$. Does the set of vectors $S_2 = \{B\vec{e}_1, B\vec{e}_2, B\vec{e}_3\}$ form a basis for \mathbb{R}^3 ?

Solution: S_2 is not a basis for \mathbb{R}^3

Proof. To see if the vectors in S_2 are a basis for \mathbb{R}^3 , we will verify B is invertable.

$$[0 \ 0 \ 0]^T = c_1 B\vec{e}_1 + c_2 B\vec{e}_2 + c_3 B\vec{e}_3$$

$$\begin{aligned} 1c_1 + 0c_2 + 2c_3 &= 0 \\ 1c_1 + 3c_2 + 0c_3 &= 0 \\ 0c_1 + 3c_2 - 2c_3 &= 0 \end{aligned}$$

The augmented matrix has the reduced row echelon form,

$$\left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1 & -\frac{2}{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \neq I_3$$

S_2 is not a basis for \mathbb{R}^3 because $rank(B) = 2 \neq dim(\mathbb{R}^3)$ \square

1.c Make a conjecture of the form “ $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 if and only if A (insert appropriate property of A here)”.

Conjecture $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 if and only if A (is an invertible matrix).

1.d Bonus: Prove your conjecture.

We will prove our conjecture $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 if and only if A (is an invertible matrix), using our list of equivalent statements. Since we have already proven if A is invertible, then $A\vec{x} = \vec{0}$ has only the trivial solution, we will use this. Asserting if R is any row echelon form of a 3×3 matrix A , then either R has at least one row of zeros, or R is the identity matrix I_3 .

We will prove the reverse direction first "if A is an invertible matrix, then $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 ."

Proof. Suppose R is the identity matrix I_3 , then A has an inverse, and $A\vec{x}$ is a linear combination of the column vectors of A . Since $A\vec{x} = \vec{0}$ has only the trivial solution, the column vectors of A must be linearly independent. Since we know that the 3 column vectors of A are linearly independent in the 3-dimensional vector space \mathbb{R}^3 , they must span \mathbb{R}^3 , and form a basis for \mathbb{R}^3 .

$$\begin{aligned} A\vec{e}_1 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = (1) \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} + (0) \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} + (0) \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} \\ A\vec{e}_2 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = (0) \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} + (1) \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} + (0) \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} \\ A\vec{e}_3 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = (0) \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix} + (0) \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} + (1) \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} \\ A &= [A\vec{e}_1 \mid A\vec{e}_2 \mid A\vec{e}_3] \\ &\implies \text{col}(A) = S \end{aligned}$$

Therefore $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ is a basis for \mathbb{R}^3 □

We will now prove the forward direction "if $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ forms a basis for \mathbb{R}^3 then A is an invertible matrix." by proving its contrapositive "if A is not an invertible matrix, then $S = \{A\vec{e}_1, A\vec{e}_2, A\vec{e}_3\}$ does not form a basis for \mathbb{R}^3 "

Proof. Suppose R has at least one row of zeros, then A has no inverse. We know from analysis of the positions of the 0's and 1's of R that elementary row operations don't change the dimension of the row space or the column space of our matrix, so it must be true that

$$\dim(\text{row space of } A) = \dim(\text{row space of } R) \text{ and } \dim(\text{column space of } A) = \dim(\text{column space of } R).$$

Since these two numbers are the same, the row and column space have the same dimension $\text{rank}(A)$; the dimension of the null space of A is $\text{nullity}(A)$

$$\begin{aligned} 0 &< \text{nullity}(A) \leq \dim(\mathbb{R}^3) \\ \text{rank}(A) + \text{nullity}(A) &= \dim(\mathbb{R}^3) \\ \text{nullity}(A) &= \dim(\mathbb{R}^3) - \text{rank}(A) \\ \implies 0 &< [\dim(\mathbb{R}^3) - \text{rank}(A)] \leq \dim(\mathbb{R}^3) \implies \dim(\mathbb{R}^3) > \text{rank}(A) \geq 0 \\ \therefore \text{rank}(A) &< \dim(\mathbb{R}^3) \end{aligned}$$

This proves, if R has atleast one row of zeros then $\text{rank}(A) < \dim(\mathbb{R}^3) \therefore S$ is not a basis for \mathbb{R}^3 □