DS & AI

Artificial Intelligence

Informed and Uninformed Search



Lecture -0,3



Topic: Informed Search



Consider a graph having nodes y1, y2, y3, y4, y5, S (starting node) and G #Q. (goal node). It uses GBFS algorithm.

The heuristic function h(n) is defined as follows:

$$h(v_i) = \begin{cases} i^2 - 2, & i \text{ is even} \\ 2i, & i \text{ is odd} \end{cases}$$

 $h(v_i) = \begin{cases} i^2 - 2, & i \text{ is even} \\ 2i, & i \text{ is odd} \end{cases}$ $expanded \rightarrow \text{ fisike.} \qquad \text{heweistice}$

Node: the tie breaker will be the vertex with highest order.

$$i = 1$$
 2 $\forall 19.75$ mot Visited.

3 6 \leftarrow
4 14
5 10

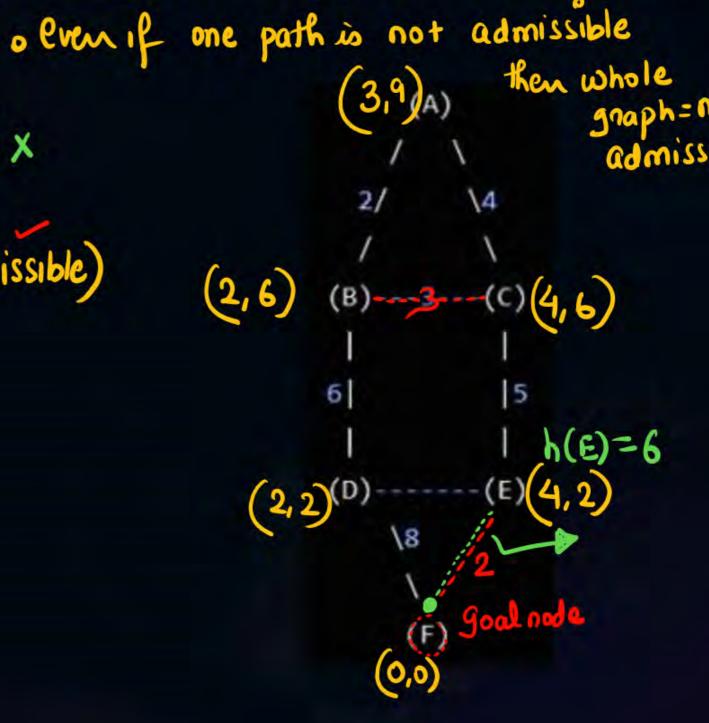


 $\mathbb{Q}_{\mathbf{W}}$

- graph in
- 1. $h_1(n) = Manhattan distance to F. x$
- 2. $*h_2(n) = 2 \times \text{actual cost to F.} \leftarrow (\text{not admissible})$

Which of the following is correct?

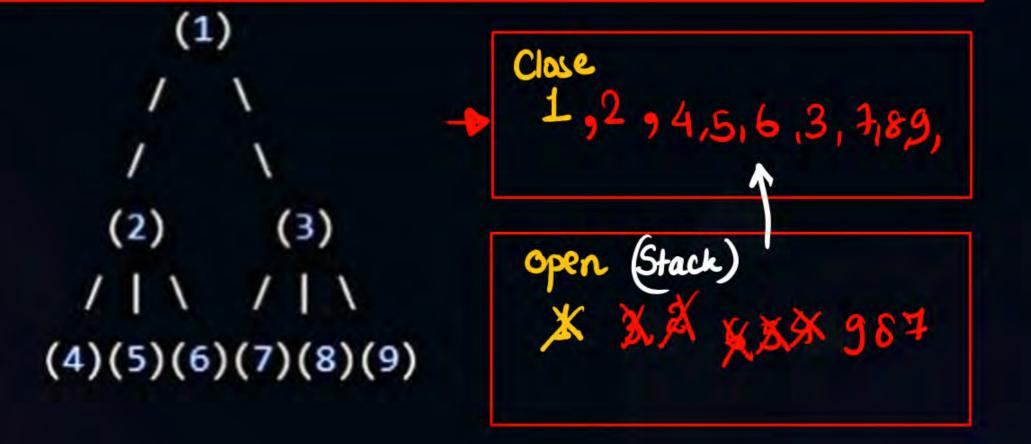
- A Both h₁ and h₂ are admissible.
- B h₁ is admissible, but h₂ is not.
- C Both h₁ and h₂ are inadmissible.
- D Neither h_1 nor h_2 can be used for A*.



DFS is applied starting from node 1, exploring the leftmost child first.

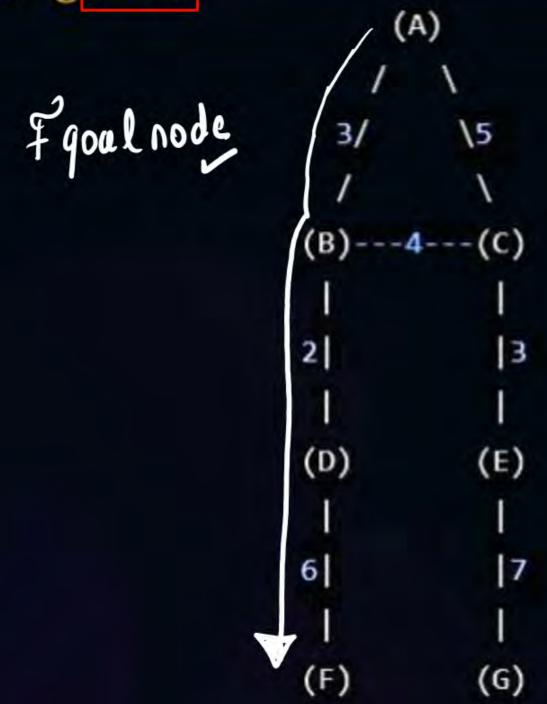
How many times is a node pushed onto the stack during the DFS

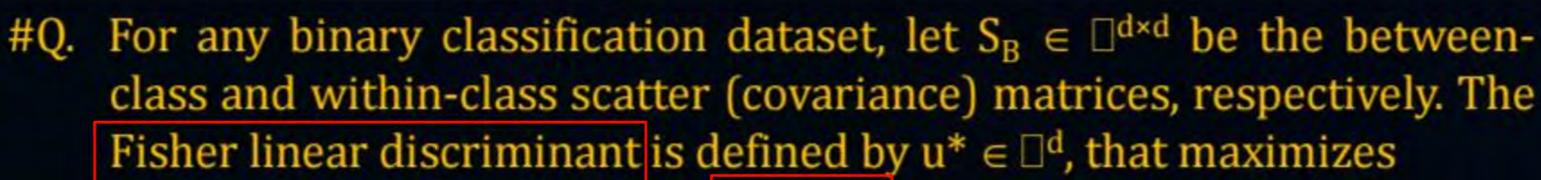
traversal of this graph?



#Q. You need to find the shortest path from A to any of the goal nodes {F, G} using UCS.







$$J(u) = \frac{u^T S_B u}{u^T S_W u}$$

If $\lambda = J(u^*)$, S_w is non-singular and $S_B \neq 0$, then (u^*, λ) must satisfy which ONE of the following equations? Note: 1R denotes the set of real numbers.

$$S_w^{-1}S_Bu = \lambda u *$$

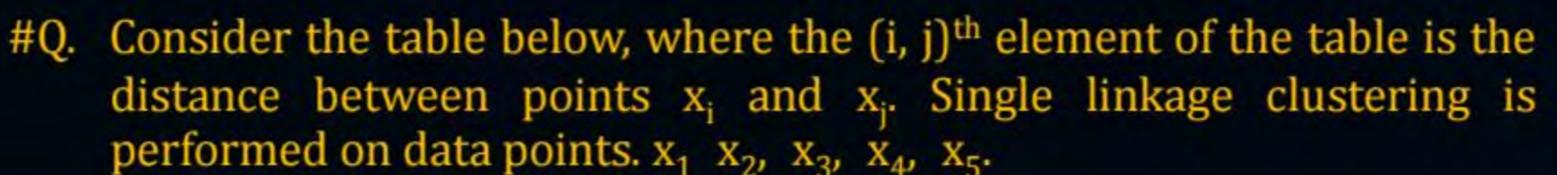
$$\left(So^{\dagger}Se^{\dot{\omega}} = \lambda \omega^{*}\right)$$

$$S_w u *= \lambda S_B u *$$

$$S_B S_w u *= \lambda u *$$

$$\mathbf{D} \quad u *^T u *= \lambda^2$$



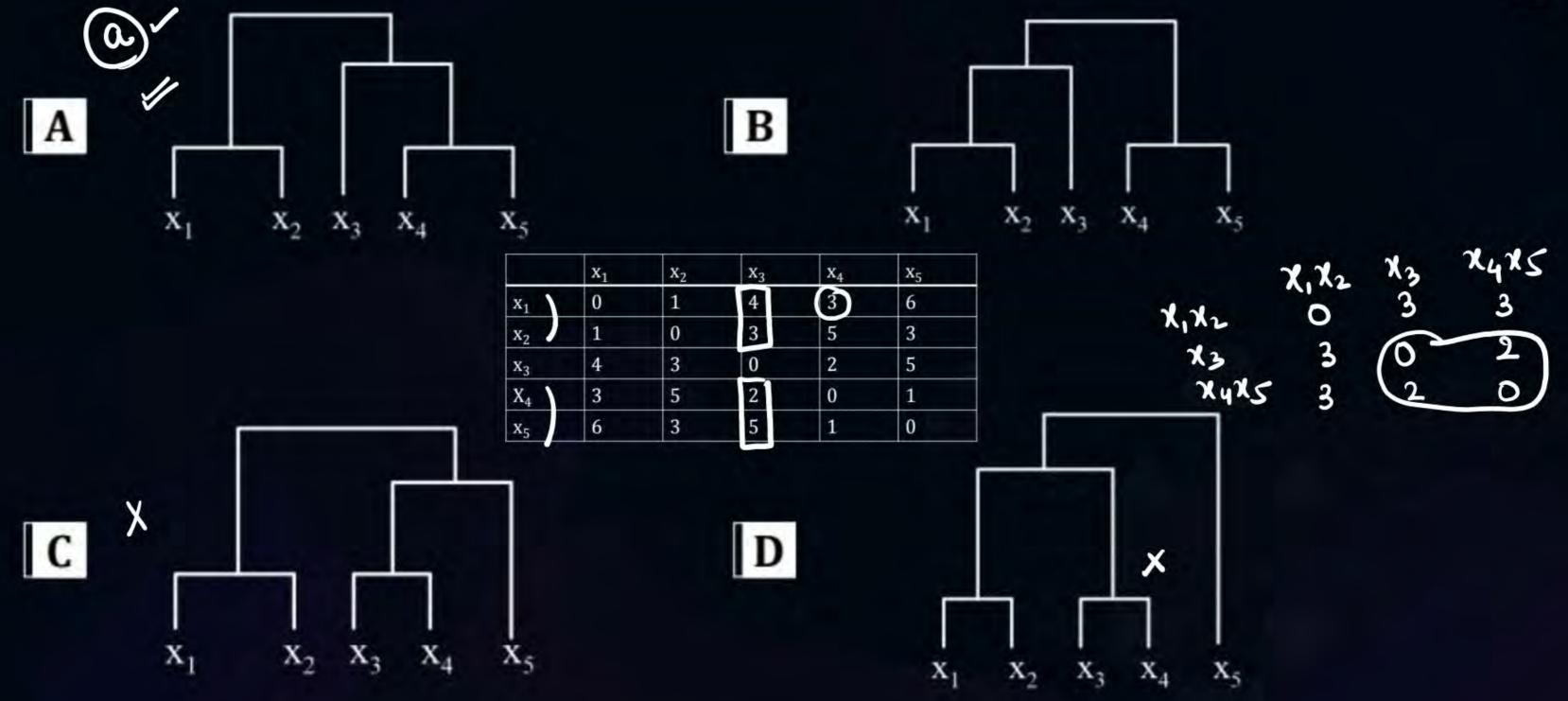


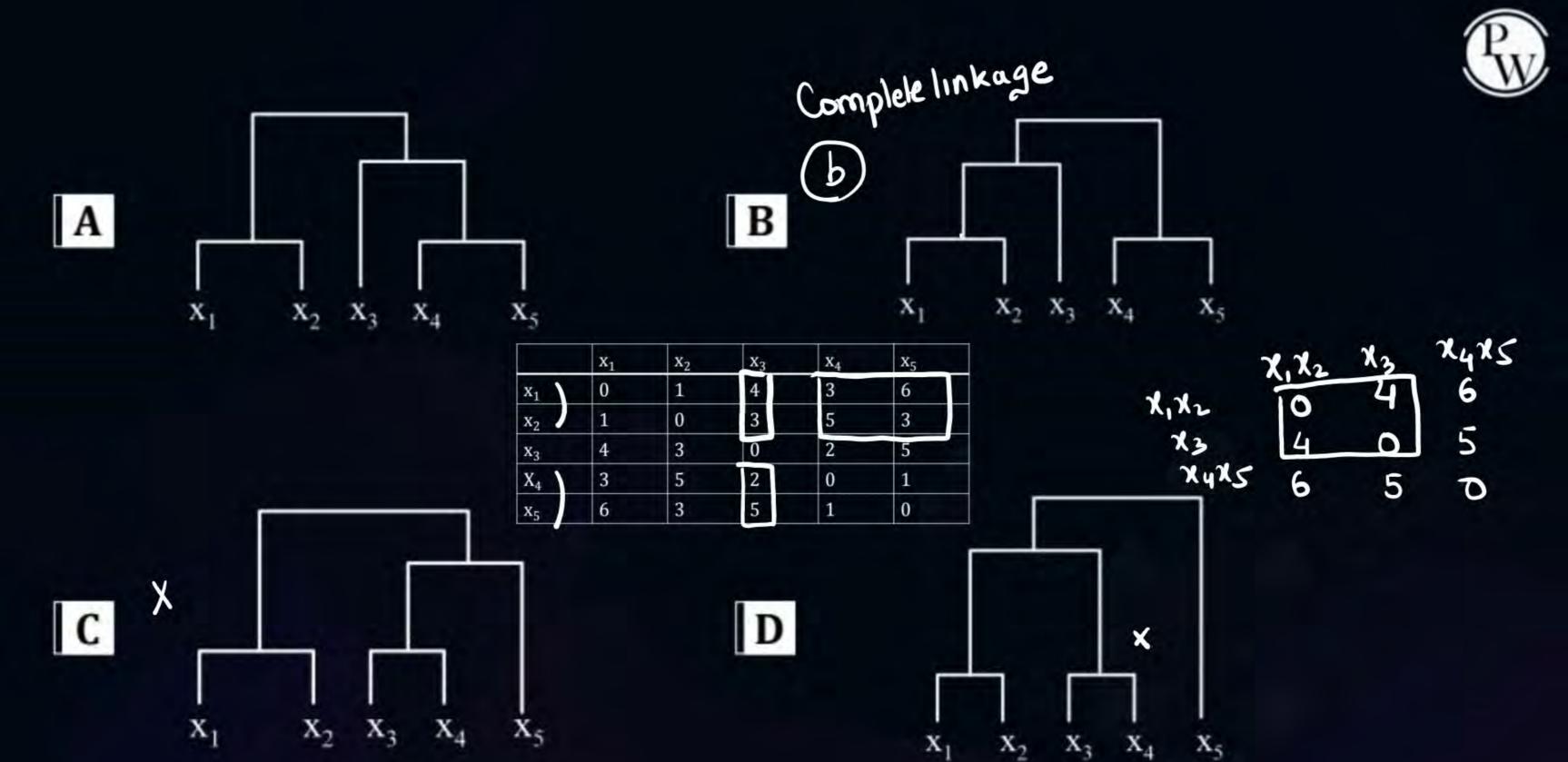


	\mathbf{x}_1	x ₂	\mathbf{x}_3	X_4	X ₅
\mathbf{x}_1	0	1	4	3	6
x ₂	1	0	3	5	3
x ₃	4	3	0	2	5
X ₄	3	5	2	0	1
X ₅	6	3	5	1	0

Which ONE of the following is the correct representation of the clusters produced?





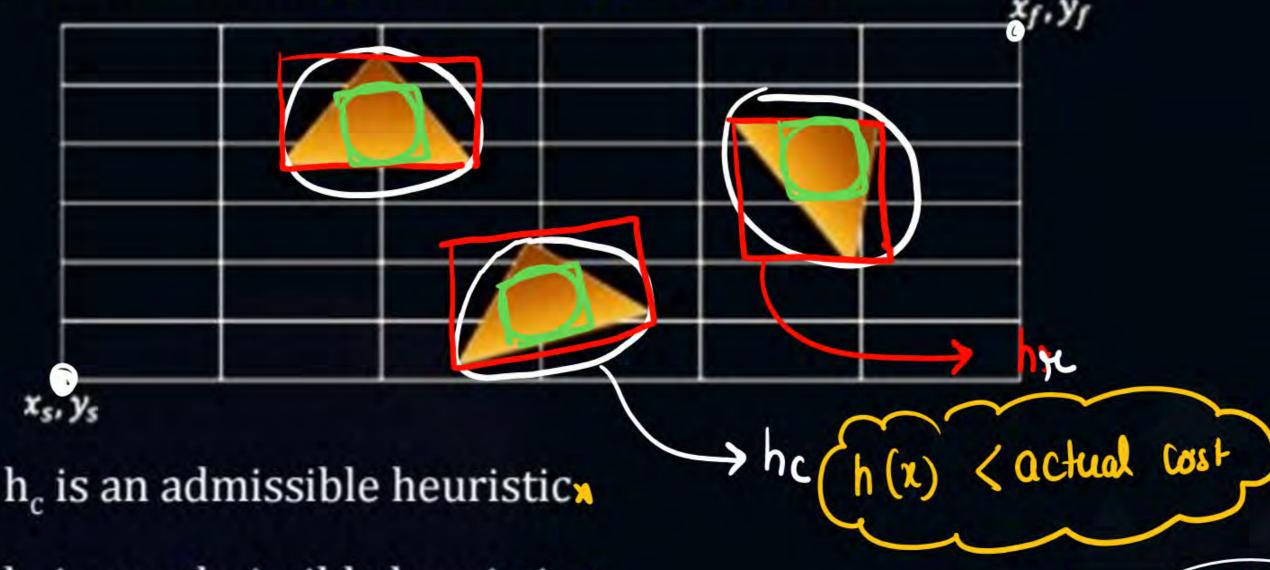




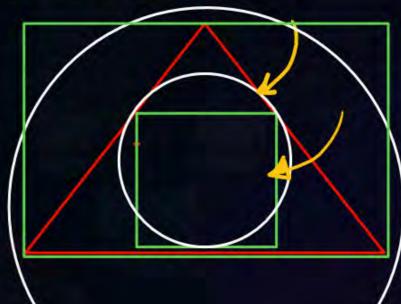
- #Q. Consider the grid world shown in the figure below. An agent is planning to move from the starting location (x_s, y_s) to the final location (x_f, y_f) . The obstacles along the path are triangular in form. Consider the following heuristic functions to conduct A* search.
 - (a) h_c assumes the obstacles are the smallest circles circumscribing the triangles.
 - (b) h_r assumes the obstacles are smallest rectangles circumscribing the triangles.
 - (c) h_c' assumes the obstacles are largest circles inscribed in the triangles.
 - (d) h_r' assumes the obstacles are largest rectangles inscribed the triangles.

Which of the following statement(s) is (are) true?





- B h_r is an admissible heuristic x
- C h_c' is an admissible heuristic
- D h_r' is an admissible heuristic



#Q. Consider the search space depicted in the figure below. S is the initial state.

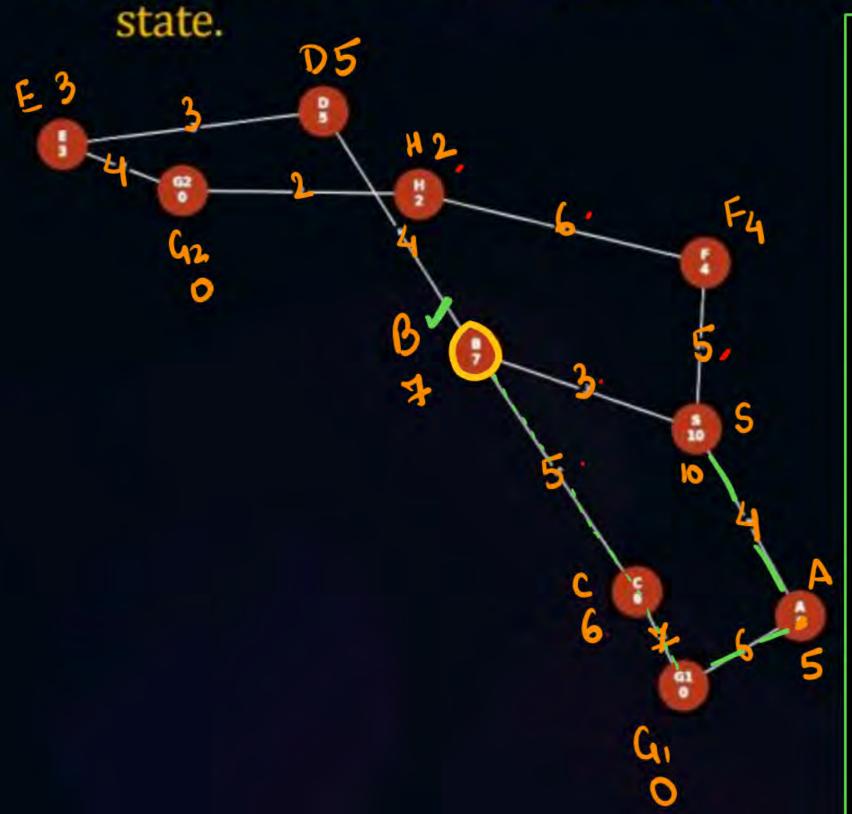


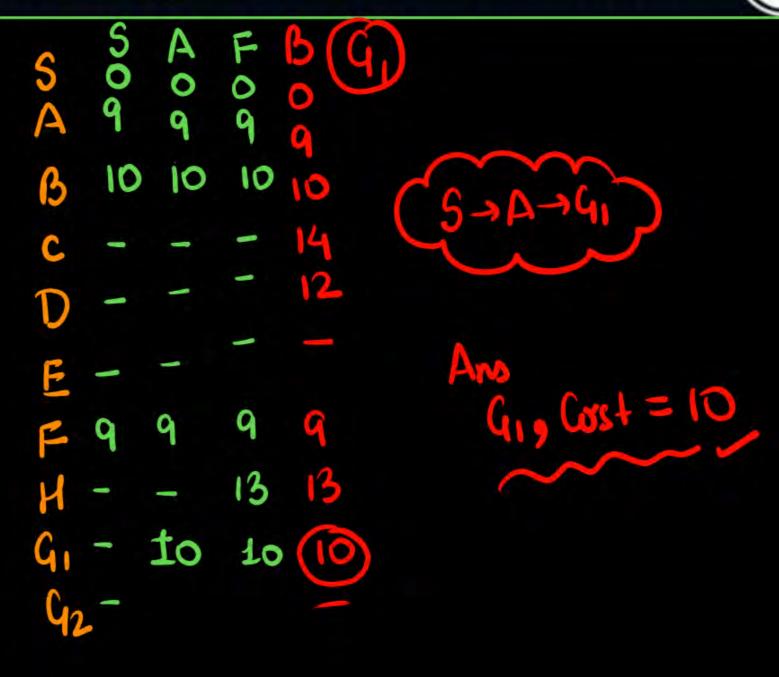


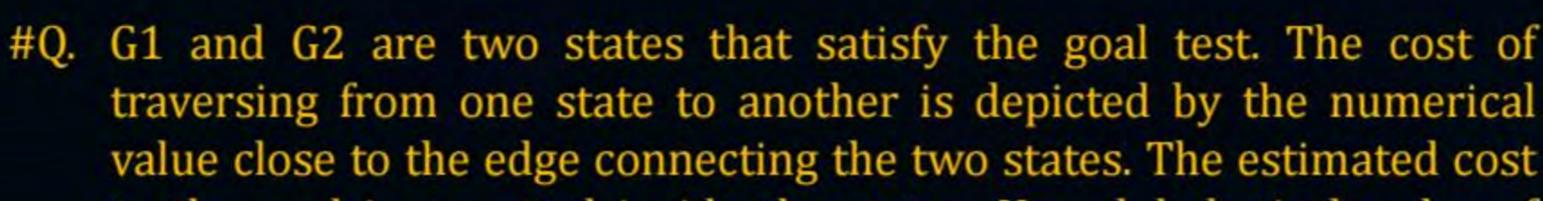
Continue...

#Q. Consider the search space depicted in the figure below. S is the initial

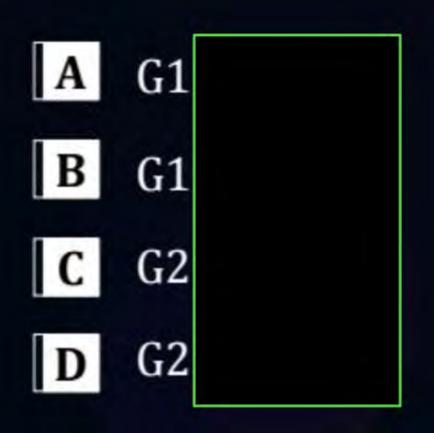


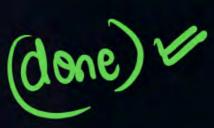






traversing from one state to another is depicted by the numerical value close to the edge connecting the two states. The estimated cost to the goal is reported inside the states. Use alphabetical order of nodes to break ties. Which goal state is reached if you perform an A* (graph) search? What is the largest value that the heuristic function can take for node B while still being admissible?





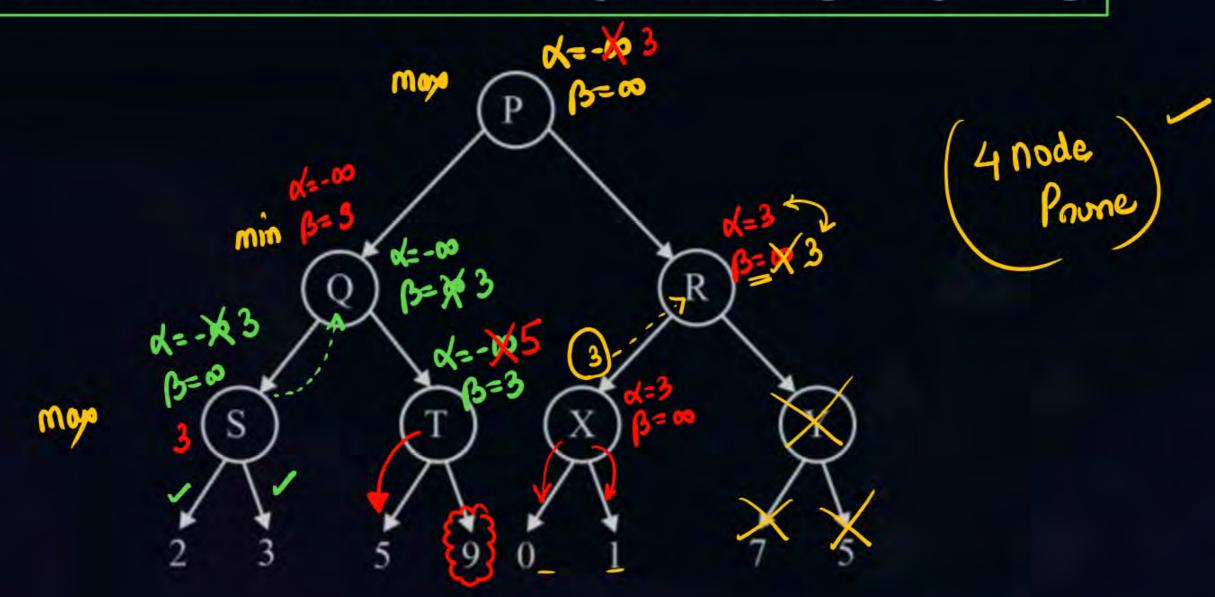
. h(B) & actual cost to

actual Cost





#Q. Count the number of nodes that will be pruned using a -b pruning



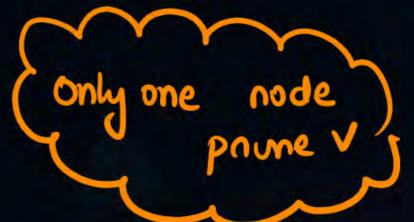




#Q.

Consider the tree green below. The root node S is the max player. What will be the best score for this root node S. No of node poune.





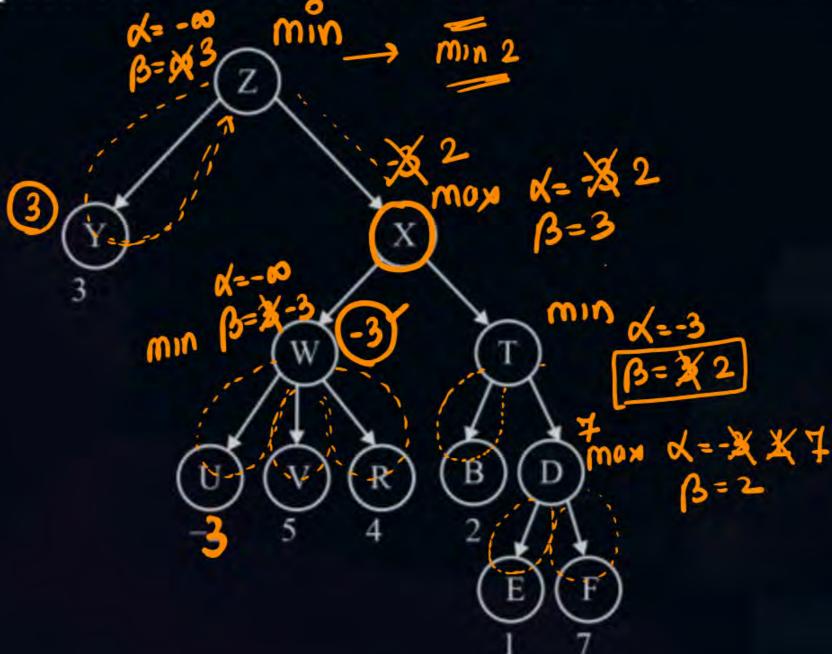




#Q. The best score possible for the root node which is a minimum player is

Node prime ??

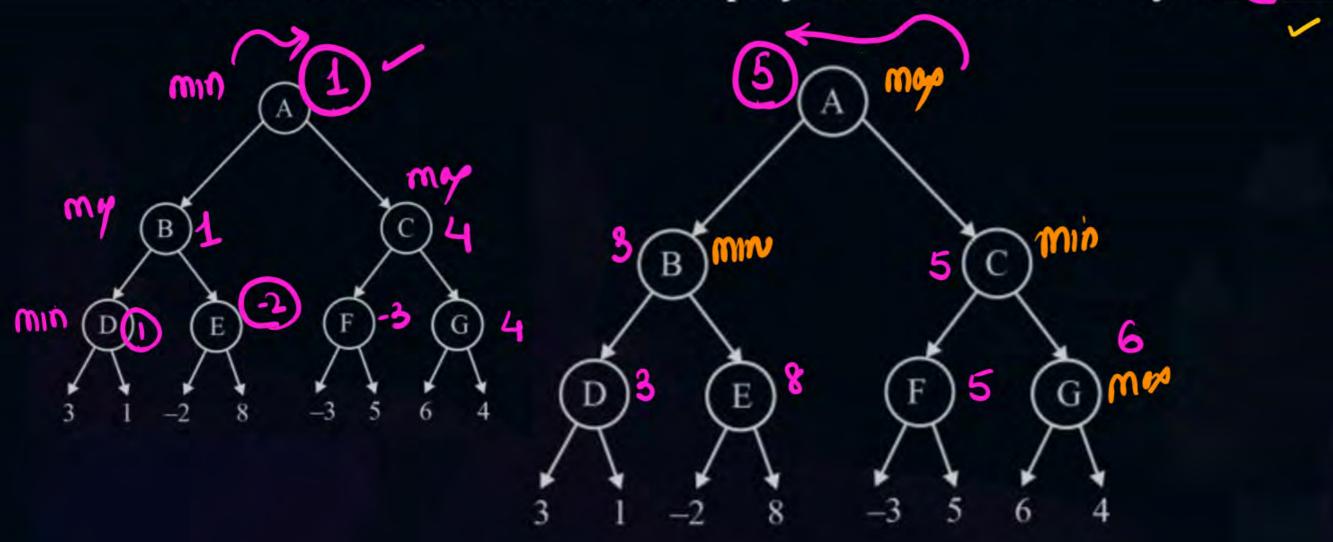
Amo 2







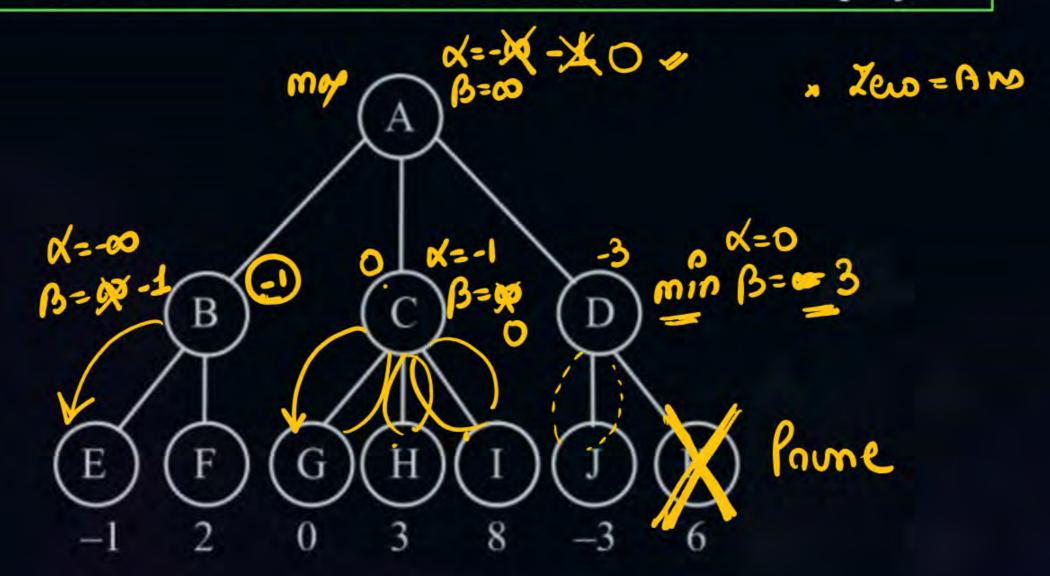
#Q. Consider the following tree. Let X denote the best score of the root node when it acts as the 'max' player. Let Y denote the best score of the rootnode when if acts as the 'min' player. The value of x + y is _____.







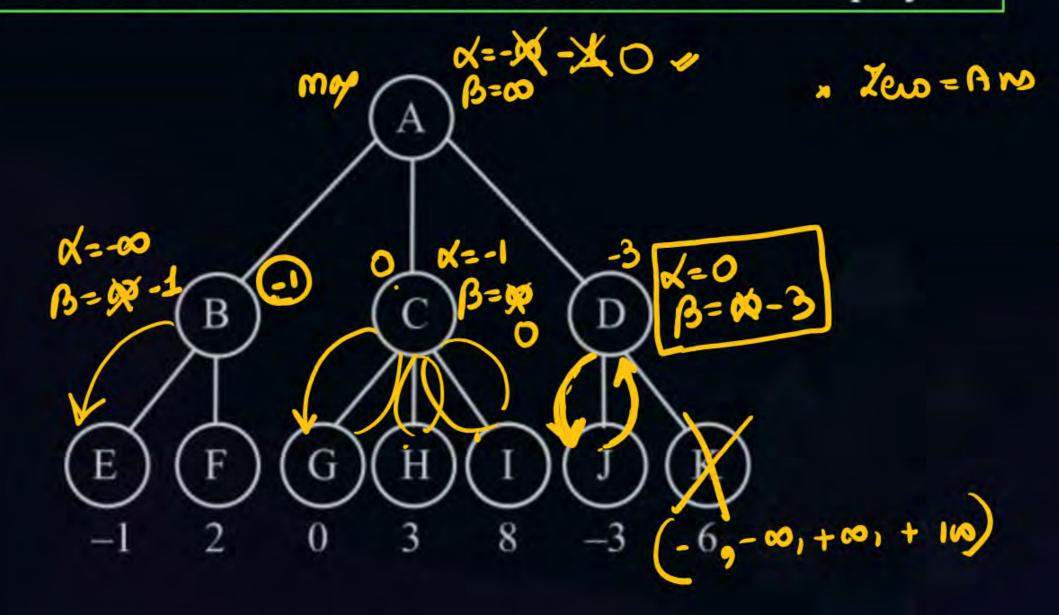
#Q. Find the best result for the root where root acts as the max player:







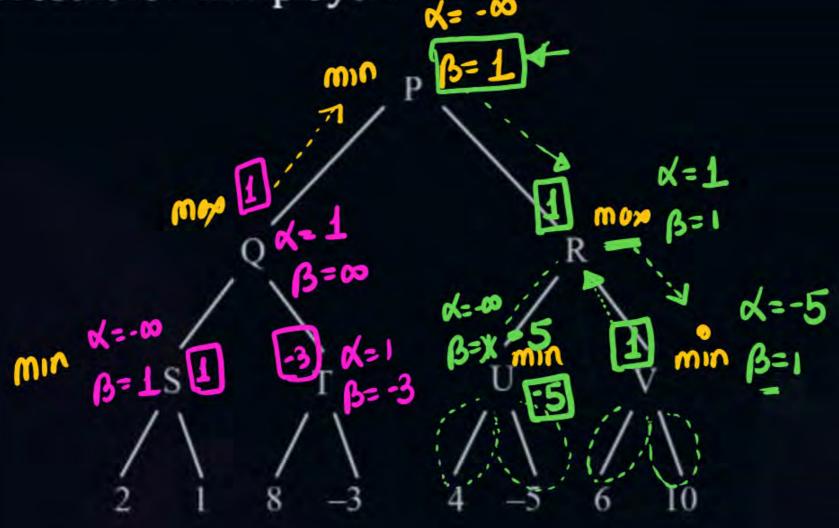
#Q. Find the best result for the root where root acts as the max player:







#Q. Find the best result for min player:

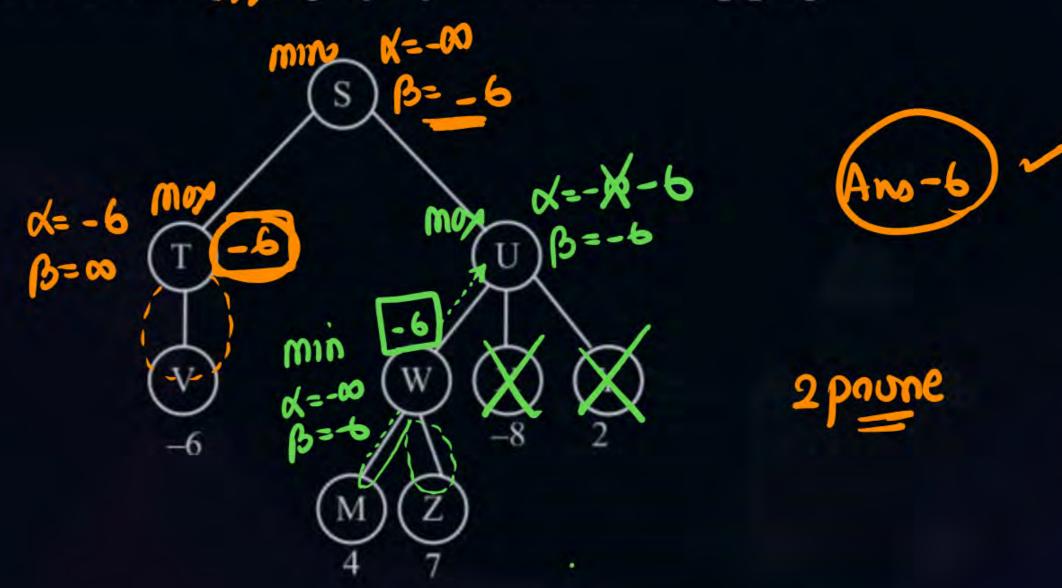






MIN

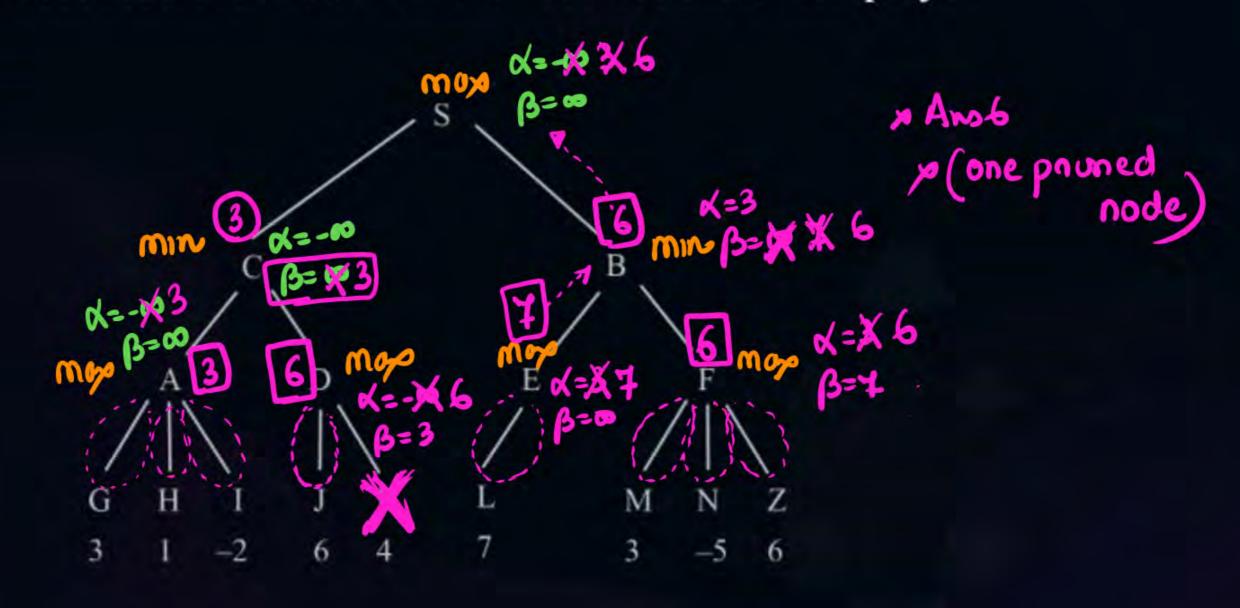
#Q. Find the best score for S (propplayer) in the following graph:







#Q. What is the best result for node C if the root node is a max player?







#Q. The number of nodes that will be pruned using alpha-beta pruning in the following graph is _____.







#Q. What is the minimax value of the root node for the game tree below?

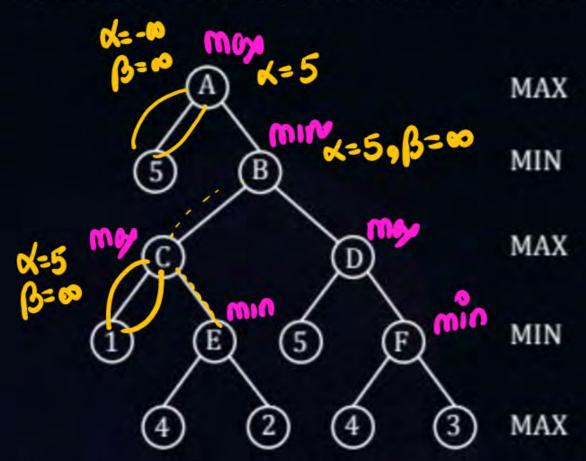


Assuming that it performs a depth-first search that always generates the leftmost child node first and a loss (and win) of MAX (and MIN) corresponds to a value of $-\infty$ (and ∞ , respectively).





#Q. Consider the below search tree.



If we apply alpha-beta pruning method to above tree, then which of the node(s) will get pruned?

Assuming that it performs a depth-first search that always generates the leftmost child node first and a loss (and win) of MAX (and MIN) corresponds to a value of $-\infty$.







A F

B D

C D, F

D E, F





#Q. What type of games is the Minimax algorithm well-suited for?

- A Single-player games
- B Cooperative games
- Two-player, zero-sum games
- Games with random elements





#Q. How does alpha-beta pruning impact the time complexity of the minimax algorithm?

A It increases time complexity.

It decreases time complexity.

It has no effect on time complexity.

It depends on the game being played.





#Q. What branch is expanded further.

incomplete

- The branch is expanded further.
- B The branch is evaluated immediately.
- The branch is eliminated from consideration
- The branch is assigned a utility value of 0





#Q. In alpha-beta pruning, what is the initial value of alpha at maximizing nodes?

A It varies based on the game

B -∞(negative infinity)

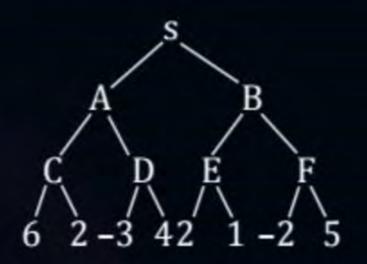
© ∞(negative infinity)

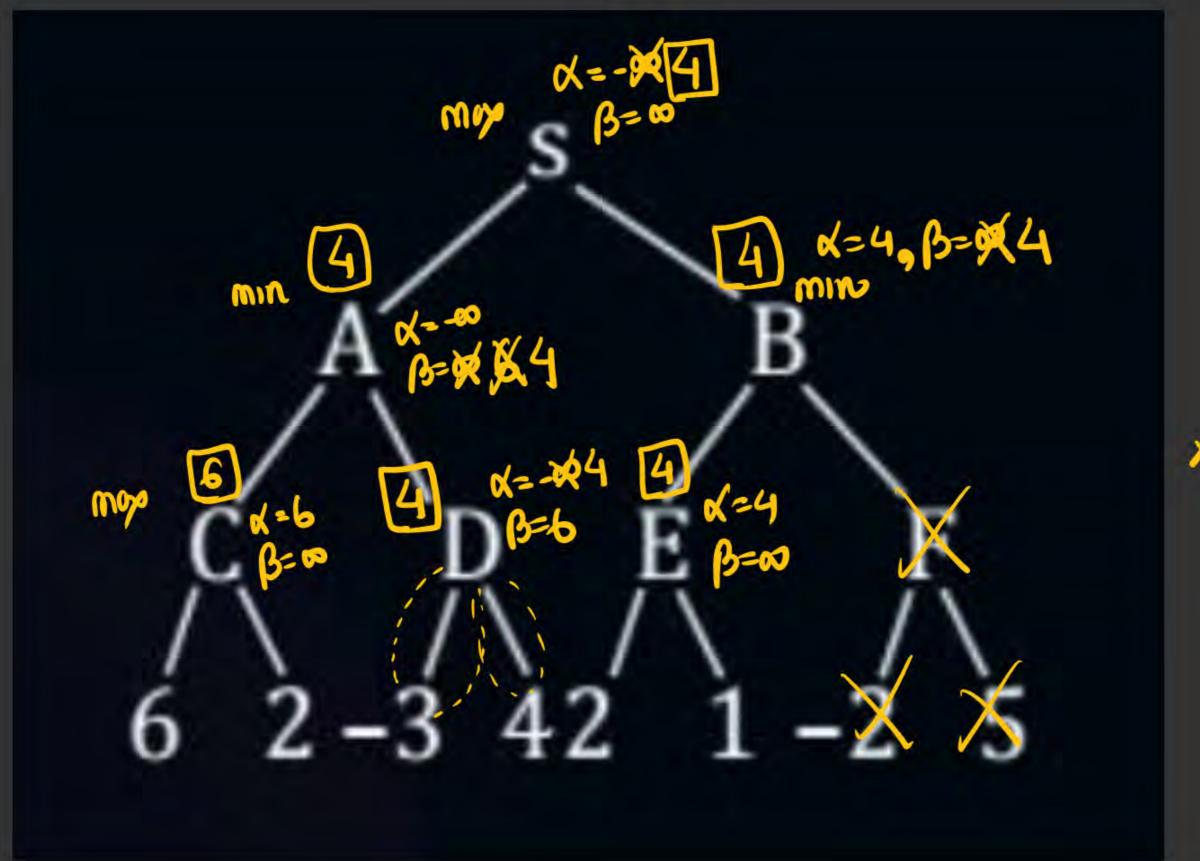
D 0





#Q. The value of $\alpha + \beta$ of node B(min player) is _____



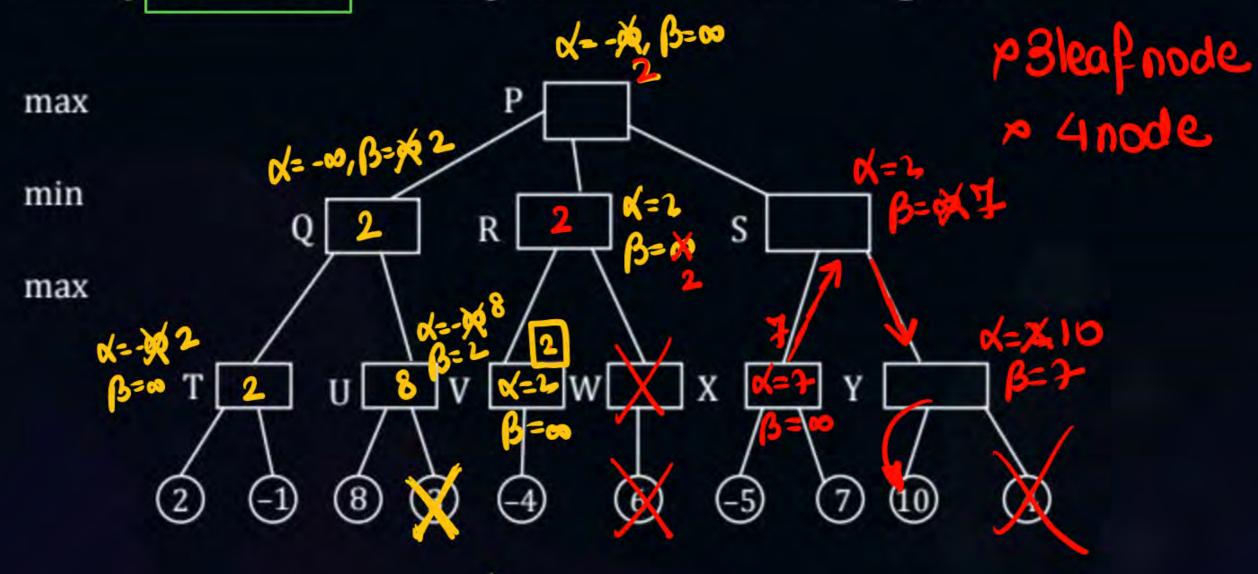


23 node Paire

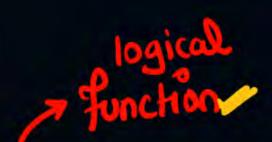




#Q. How many leaf nodes will be pruned in the following tree?







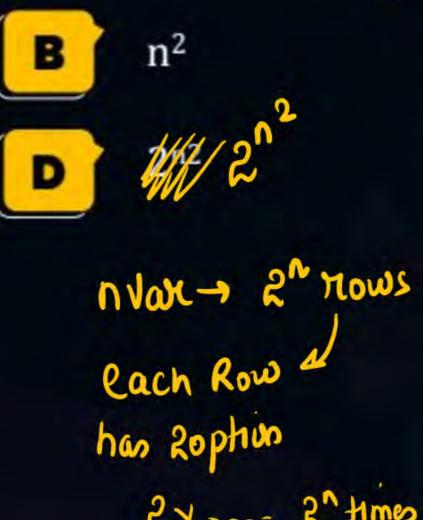


#Q. The number of different possible logical connectives on n variables is

digital elec

nyor -> Touth table





	£0	f=1	(MANMB)	CAI	1B) (A	4 ~~B)	Row	2x2x2x2	16
(A 15)	第 0 0 0	F2	43 1 0 0 0	40100	ま 0 0 4 0 0 1	F60001	好〇上上		





#Q. Consider the following statements:

S₁: AI stands for Artificial Intelligence.

 S_2 : 2 + 1 = 5

 S_1 is a proposition but S_2 is not a proposition

S₁ is not proposition but S₂ is a proposition

Both S_1 and S_2 are propositions.

Neither S_1 nor S_2 is a propositions.





#Q. The negation of the statement "We have those students who have applied for CS paper or DA paper" is

- We do not have those students who have applied for CS paper or DA paper
- We have students who have not applied for CS paper and not applied for DA paper.
- We have those students who have applied for CS paper and DA paper.
- None of the above





#Q. "If I am selected, then I will get the job" is equivalent to saying

- "If I am not selected, then I will not get the job"
- "If will not get the job, then I am not selected".
- "If I will get the job then I am selected.."
- None of the above





#Q. The expression $P \leftrightarrow q$ can also be stated as

- "p is necessary and sufficient for q"
- "if p then q, and conversely"
- "p exactly when q".





#Q. Simplify the expression $(p \lor \neg q) \rightarrow (p \land q)$

A p

C

B

q

DF



THANK - YOU