DS & AI

Artificial Intelligence

Informed Search 1500+ Series

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Lecture_01





#Q. Consider the state space with the branching factor of 4 and assume that goal occurs somewhere at depth 6.

How many maximum numbers of nodes will be inspected if we used BFS

search algorithm?





#Q. Which of the following statements is/are correct about Iterative deepening depth-first search?

- In terms of node generation, it is asymptotically similar to breadth-first search (BFS)
- IDS is preferred for large search spaces when the depth of the solution is known.
- It combines benefits of depth-first and breadth-first search, offering modest memory requirements and completeness
- In 105, the predefined limit is used to start the search.





#Q. Consider the following graph:



What is the correct DFS traversal starting from node A? Assume that you visit alphabetically smaller nodes first.

- A {ABSCDEHGF}
- C {ABSTHEDGF}

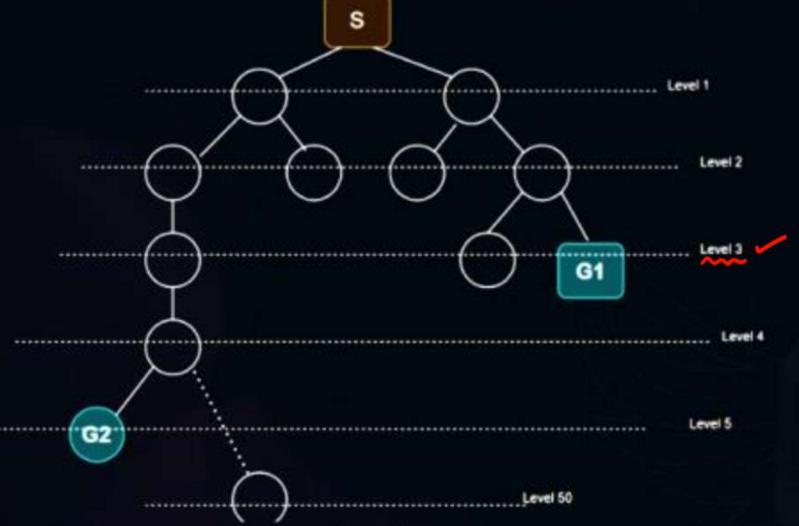
- B {ABSCDEGFH}
- P {ABCSDEHGF}





#Q. Consider the below infinite search space, S is start state and G is the Goal

State.



Suppose Depth Limited Search Algorithm is used to find the Goal Node G2 with the predefined search limit of level 3. Based on the performance of DLS DLS algorithm, choose the correct option.



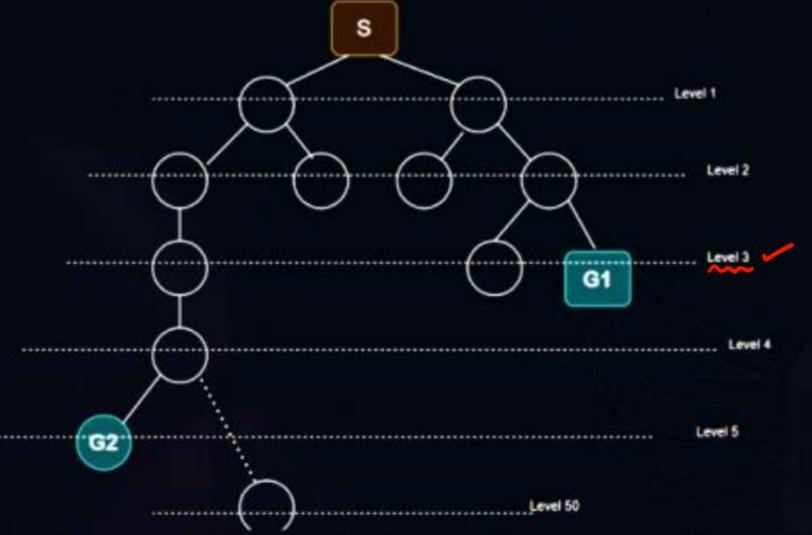
- A Search will be Complete
 - B Search will be Incomplete
- Search will provide optimal solution
- Search will provide a solution but may not be optimal





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Topic: Informed

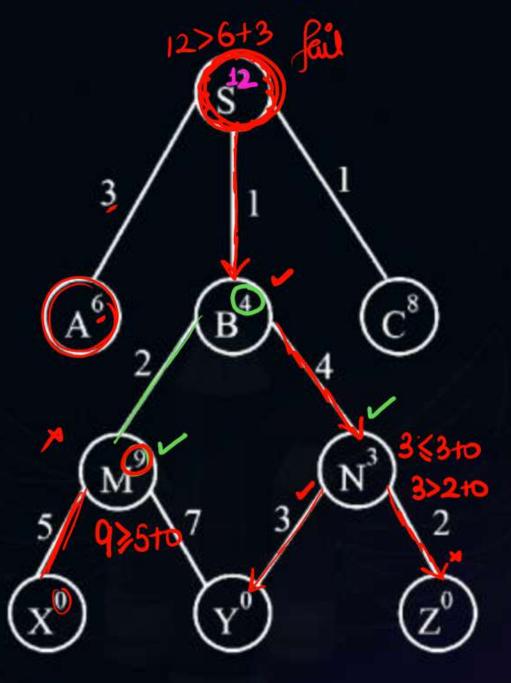
GBFS - minheunistic Physics SBNY, SBNZ

#Q.

Consider the search space depicted in the Figure below. S is the initial state. X, Y, an Z are the states that satisfy the goal test. Use alphabetical order of nodes to break ties. Let P denote the set of states present in the optimal path using A^* algorithm and Q represent the set of states present in the optimal path using GBFS. The cardinality of $P \cap Q$ is _____.

• Hevaistic Consistent → h(n) ≤ h(neighboun)t

Conneighboun





Topic: Informed

CA* (SIDN 2) + 7

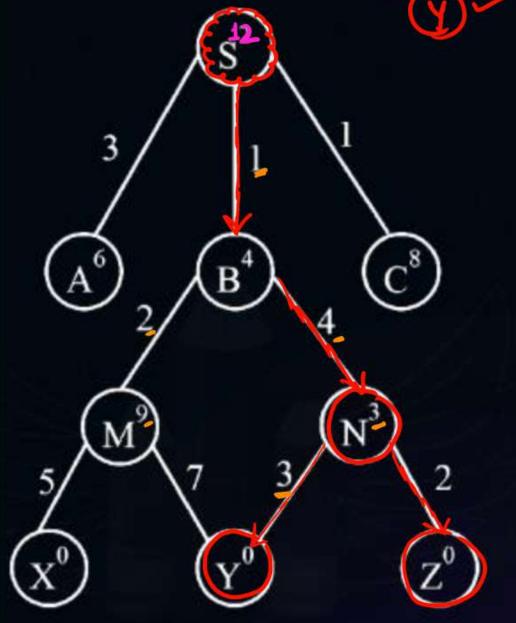
Pag > S.B.N

GBF Q minheunistic

> SIBNY - Break





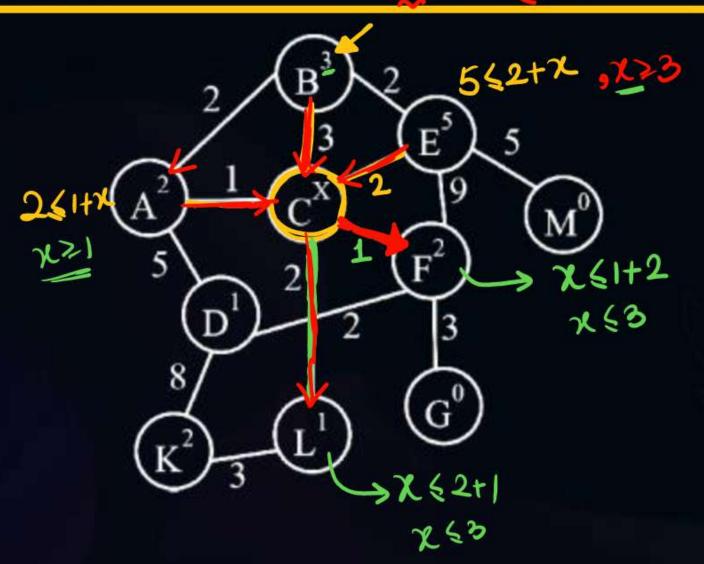






#Q.

What can be the minimum value of 'x' possible to keep the graph consistent? (x>0) (x=3)

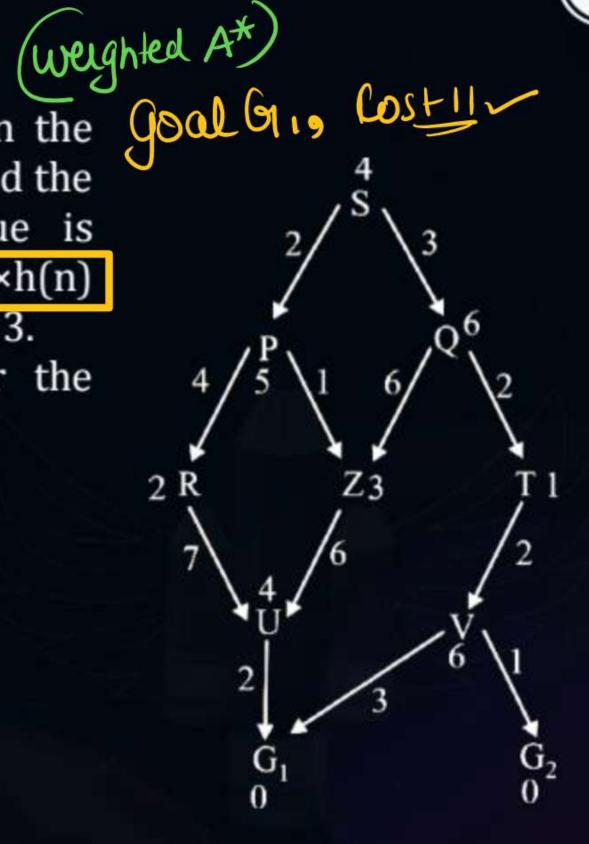


$$max = 100 \text{ M} = 100 \text{ M}$$



Pw

#Q. You are performing Weighted A* search on the following graph where the start node is S, and the goal nodes are G1 and G2. The f-value is calculated using the formula: $f(n)=g(n)+w\times h(n)$ where the weight w for the heuristic is set to 3. Calculate the size of the Open list after the completion of the entire process.







alphabetical order

Path Cost 11, goal Gi

SPRZQTUG







#Q.

The branch factor for a graph is 5 and the depth threshold is 3. The difference between the worst case time and space complexity if Iterative Deepening A* search is used will be _____.

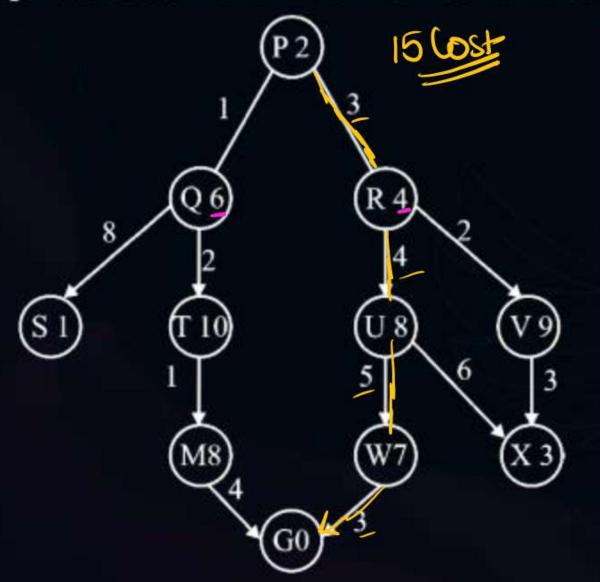
Time
$$C \rightarrow O(b^d)$$
 DFS
• Space $C \rightarrow O(b \times d)$
 $\Rightarrow (5^3 - 5 \times 3)$

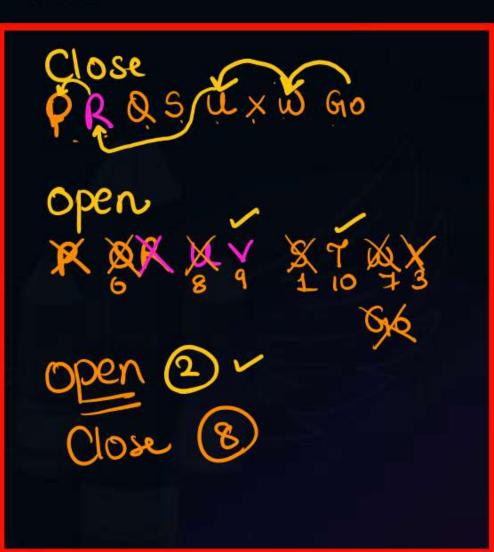






#Q. What will be the path cost in reaching the goal node G starting from node P, when Breadth First Heuristic Search algorithm is applied on the following graph? Note: Use alphabetical order of nodes to break ties.

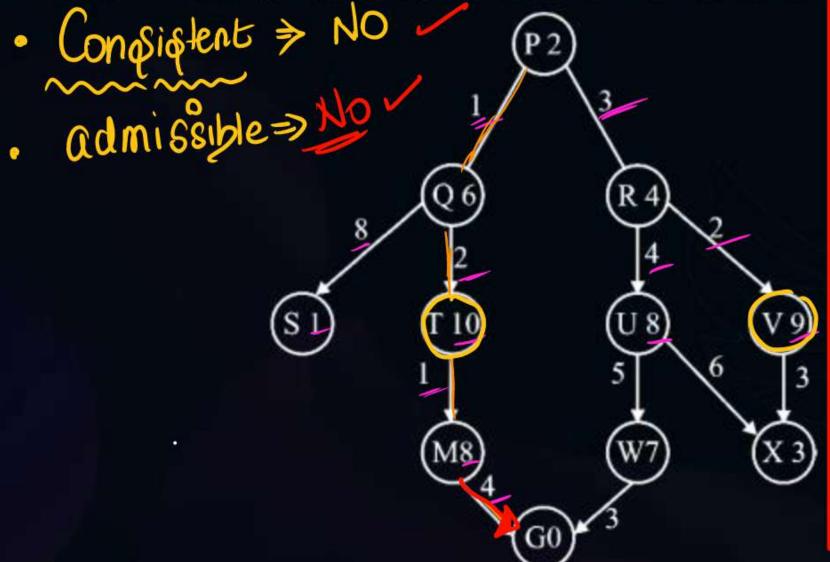






albhabetical

#Q. What will be the path cost in reaching the goal nod when Breadth First Heuristic Search algorithm is a graph? Note: Use alphabetical order of nodes to brooks.



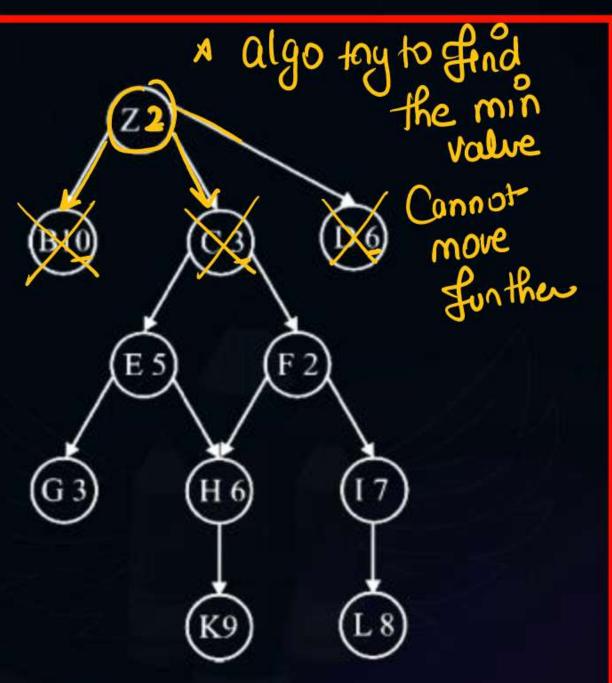






#Q.

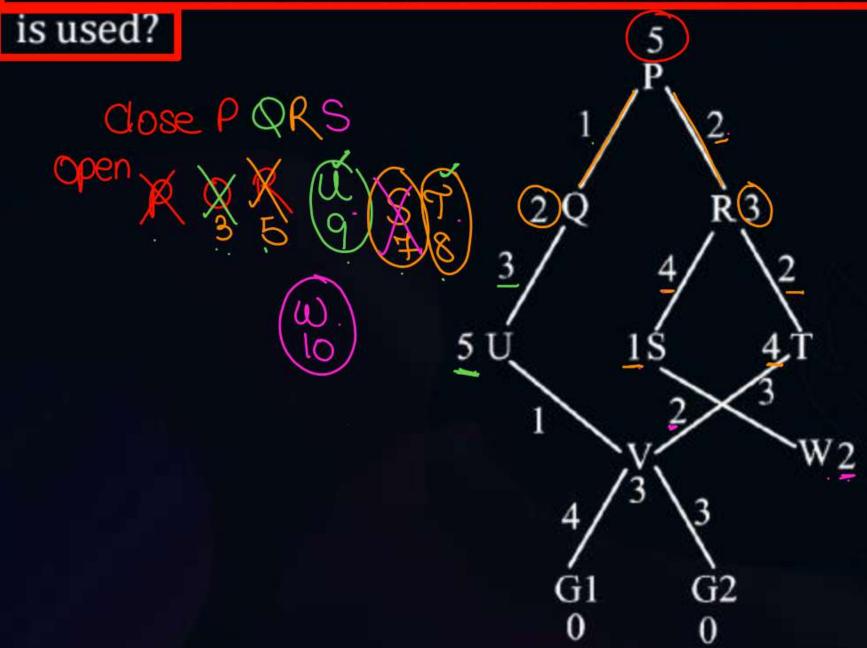
In a Hill Climbing problem, we have a graph where the nodes are represented by letters, and each letter is associated with a number based on its position in the alphabet. Z is the start node and G,K, and L are the goal nodes. Determine the code (number) corresponding to the letter on which the Hill Climbing algorithm will stop.







What will be the threshold value for second iteration when IDA* algorithm #Q.



- · First It > 5 · Second It > 7 · Thind It > 8





#Q. Let b denote the branching factor and d denote the maximum depth of a graph. The difference between the worst case time complexity and worst case space complexity on this graph using BFHS is _____.





#Q. Consider the following weighted graph where the heuristic values h(n) are provided for each node:

$$h(A) = 6$$

$$h(B) = 4$$
 $h(C) = 2$

$$h(C) = 2$$

$$h(D) = 6$$

$$h(E) = 1$$

$$h(F) = 0$$

Using the A search algorithm, what is the path from A to F?

 $A \rightarrow B \rightarrow D \rightarrow E \rightarrow F$

 $A \rightarrow C \rightarrow E \rightarrow F$

 $A \rightarrow B \rightarrow C \rightarrow F$

 $A \rightarrow C \rightarrow F$





#Q. Consider the following weighted graph where the heuristic values h(n) are provided for each node. There are three possible goal state G1, G2, and G3.

$$h(A) = 10$$

$$h(B) = 8$$

$$h(C) = 5$$

$$h(C) = 5$$
 $h(D) = 7$

$$h(E) = 6$$

$$h(F) = 3$$

$$h(G1) = 0$$

$$h(G2) = 0$$

$$h(G3) = 0$$

Using the A search algorithm, what is the path from A to Good

Find Goal node · Close 5 Total Cost > · Cost 6 · A+C+E+G1~





#Q. Consider the following weighted graph where the heuristic values h(n) are provided for each node. There are three possible goal state G1, G2, and G3.

$$h(A) = 10$$

$$h(B) = 8$$

$$h(C) = 5$$

$$h(D) = 7$$

$$h(E) = 6$$

$$h(F) = 3$$

$$h(G1) = 0$$

$$h(G2) = 0$$

$$h(G3) = 0$$

Using the A search algorithm, what is the path from A to F?

Find Goal node
Total Cost >





#Q. Consider the following graph where the start node is S, the goal node is G, and the edge costs are given. The heuristic values (h(n)) for each node are as follows:

The edge costs (g(n)) are:

$$\bullet$$
 S \rightarrow A = 2

•
$$S \rightarrow B = 3$$

$$\bullet$$
 A \rightarrow D = 4

• B
$$\rightarrow$$
 D = 2

• D
$$\rightarrow$$
 G = 3

• A
$$\rightarrow$$
 C = 5

•
$$C \rightarrow G = 7$$

Node	Heuristic (h(n))
Α	5
В	4
С	6
D	3
G	0

Using the A* algorithm, what is the total cost of the optimal path from S to G?





#Q. You are given a graph with the following heuristic values for nodes and edge costs. Using Greedy Best-First Search, what will be the total path cost from

starting node S to goal node G? The edge costs (g(n)) are:

$$\bullet$$
 S \rightarrow A = 1

$$\bullet$$
 S \rightarrow B = 4

$$\bullet$$
 A \rightarrow C = 2

•
$$A \rightarrow D = 4$$

• B
$$\rightarrow$$
 D = 3

•
$$C \rightarrow G = 5$$

• D
$$\rightarrow$$
 G = 2

Node	Heuristic (h(n))
Α	3
В	6
С	2
D	1
G	0





#Q. Consider a graph with the following nodes and their respective heuristic

value:

The edges are as follows:

$$\bullet$$
 S \rightarrow A = 2

•
$$S \rightarrow B = 4$$

$$\bullet$$
 A \rightarrow C = 3

$$\bullet$$
 B \rightarrow D = 2

• D
$$\rightarrow$$
 G = 5

•
$$C \rightarrow G = 4$$

Node	Heuristic (h(n))
Α	10
В	8
С	7
D	5
E	3
G	0

The number nodes (including the start node and the goal node) that will be visited while reaching the goal using the Hill Climbing algorithm is ______.

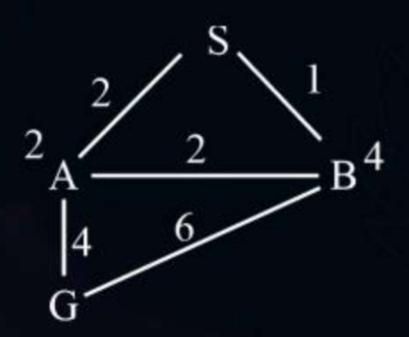




#Q. Use the A* algorithm to find the optimal path cost from node S to G using the following graph:

Costs:
$$S \rightarrow A = 2$$
, $S \rightarrow B = 1$, $A \rightarrow G = 4$, $B \rightarrow G = 6$, $A \rightarrow B = 2$

Heuristic values:
$$S = 5$$
, $A = 2$, $B = 4$, $G = 0$







#Q. In an A* search problem, if the cost to move from node A to B is 6, and the heuristic from B to the goal is 4, what is the evaluation function f(B) for node B if g(A) = 3?



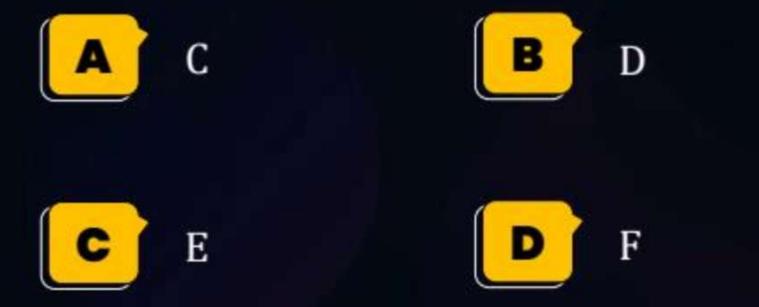


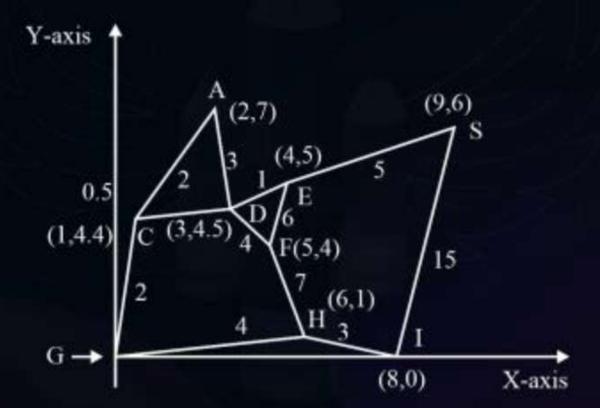
#Q. In a GBFS search, the heuristic from node X to the goal is 6, and from node Y to the goal is 4. Which node will GBFS prioritize for expansion, and what is the heuristic value of the prioritized node?





#Q. Consider the below undirected graph with cartesian coordinate in which G is the "Goal" node with coordinate (0,0) and S is the starting node with coordinate (9,6). Apply the A* algorithm on the below graph and find the node that is not generated as neighbor (except S) in searching for the shortest path from S to G with Euclidean distance from G node as heuristic value and edge cost is given on the edge. Note – If two nodes have same cost then for tie-breaker use alphabetical order.









#Q. Consider a graph having nodes y1, y2, y3, y4, y5, S (starting node) and G (goal node). It uses GBFS algorithm.

The heuristic function h(n) is defined as follows:

$$h(v_i) = \begin{cases} i^2 - 2, & i \text{ is even} \\ 2i, & i \text{ is odd} \end{cases}$$

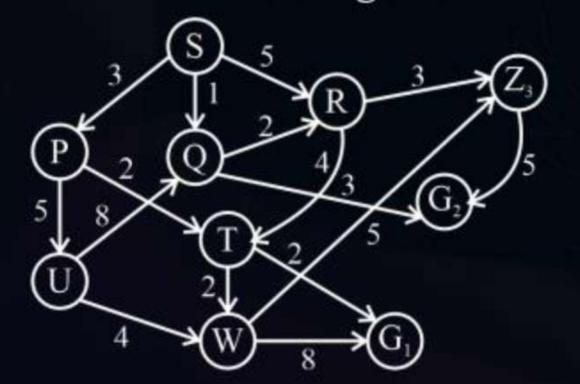
The value of $\Sigma h(v_i)$ where v_i is not expanded is _____. Node: the tie breaker will be the vertex with highest order.







#Q. Consider the search space depicted in the figure below. S is the initial state. G1 and G2 are two states that satisfy the goal test. The cost of traversing from one state to another is depicted by the numerical value close to the edge connecting the two states. The estimated cost to the goal is reported inside the states. Use alphabetical order of nodes to break ties. Which goal state is reached if you perform A* (graph) search?
What is the number of nodes failing the admissibility condition?





THANK - YOU