[Executive Team - Schulich Space Rover Team (weebly.com)](https://ucalgaryrover.weebly.com/executive-team.html)

[Gallery - Schulich Space Rover Team (weebly.com)](https://ucalgaryrover.weebly.com/gallery.html)

6 wheels:

* Motorized front right
* Motorized front left
* Auxiliary middle right
* Auxiliary middle left
* Motorized back right
* Motorized back left

Science arm

* Base rotation
* 2 “arm” joints
* 2 point claw

Control

* Modes:
  + Teleop
  + Autonomous get sample
* Systems
  + RPi main control
  + Multiple embedded systems to control stuff

Gameplan

* Arm
  + Design
  + Build
  + Control
* Body
  + Design
  + Build
  + Control
* Control systems
  + Arm is one embedded system
  + Body (moving) is on system
  + Sensors are anyother system
  + All controlled by central pi