

## Module 2A

Vector mathematics, great circles, and latitude/longitude



### In this module

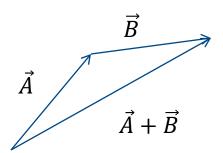
- We review
  - o Vector sums
  - The vector dot product
  - ECEF and ECI coordinate systems
  - The use of the vector dot product to compute great circle distances on the surface of a sphere

### Vector sums

$$\vec{A} = A_x \hat{x} + A_y \hat{y} + A_z \hat{z}$$

$$\vec{B} = B_x \hat{x} + B_y \hat{y} + B_z \hat{z}$$

$$\vec{A} + \vec{B} = (A_x + B_x)\hat{x} + (A_y + B_y)\hat{y} + (A_z + B_z)\hat{z}$$



# Vector dot product

Vector dot product, also known as scalar product, or inner product

$$\overrightarrow{A} \cdot \overrightarrow{B} = A_{x}B_{x} + A_{y}B_{y} + A_{z}B_{z}$$

Meaning of the vector dot product:

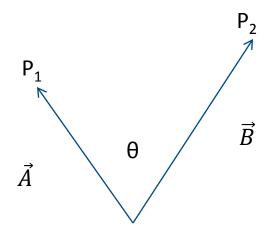
$$\overrightarrow{A} \cdot \overrightarrow{B} = A_x B_x + A_y B_y + A_z B_z = |A||B|\cos\theta$$

where  $\theta$  is the angle between the two vectors.

Note that the vector dot product produces a scalar, not a vector.

### **JOHNS HOPKINS**

### The vector dot product, cont'd.



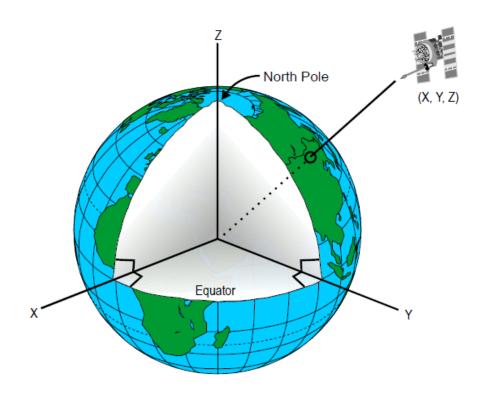
The dot product is particularly useful for computing great circle distances on the surface of a sphere. If the vectors **A** and **B** point from the center of the earth to its surface, and each have magnitude r<sub>e</sub>, the radius of the earth, then the dot product divided by r<sub>e</sub><sup>2</sup> yields a value for  $\cos \theta$ . Taking the inverse cosine to obtain a value for  $\theta$ , then Multiplying  $r_e\theta$  yields the great circle distance between points P<sub>1</sub> and P<sub>2</sub> on the surface of a sphere, in this case the earth. The angle must be specified in *radians*.

# The lat/long/alt ECEF coordinate system

- ECEF means earth centered earth fixed. It is the coordinate system in which the earth does not appear to be moving with respect to a position on the surface of the earth.
- In the ECEF frame, the concepts of latitude, longitude, and altitude are welldefined.

# ECI, or Earth Centered Inertial Frame

- The ECI frame rotates with respect to the ECEF frame
- The rotation period is called a sidereal day, and is 23 hours, 56 minutes, 4.0916 seconds
  - This is the time it takes the earth to rotate 360 degrees
- The solar day
  - 24 hours is the times it takes from noon to noon
  - The solar day is longer than a sidereal day because of the earth's motion in its orbit around the sun
- This topic will be discussed in more detail in a later module



#### Latitude and longitude

This Wikipedia page excerpt shows the earth with respect to the Cartesian ECEF and/or ECI coordinate systems. In the ECEF system, the Cartesian axes rotate in synchrony with the earth. From:

http://upload.wikimedia.org/wikipedia/commons/3/32/Earth\_Centered\_Inertial\_Coordinate\_System.png (accessed Oct 16, 2014).

#### Vector representation of Latitude and Longitude

- A position x, y, z on the surface of the earth can be written as the vector
  - $\circ A_x = r_e \cos (lat) \cos (long)$
  - $\circ A_v = r_e \cos (lat) \sin (long)$
  - $\circ A_z = r_e \sin(lat)$



# Two points on the surface of the earth

- Two points on the surface of the earth can be represented as vectors **A** and **B**.
- The great circle distance can be determined from the dot product of A and **B**, as discussed earlier.

# Radio waves, light, and great circles

- Electromagnetic waves travel between two points by the shortest possible path
  - This is Fermat's principle or the principle of least time
- This means that radio signals and light waves travel in great circles at the surface of the earth



# Assignment 2.1

- Look up the latitude and longitude of San Francisco and Washington, D.C., and compute the great circle distance between the two cities.
- 2.1.2 Derive equation 2.20 in the text.



#### End of Mod 2A