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1. Diagonalization

Let D be an diagonal matrix. The power D^k is easy to calculate. For example,

$$D^k = \begin{bmatrix} d_1 & 0 & 0 & 0 \\ 0 & d_2 & 0 & 0 \\ 0 & 0 & d_3 & 0 \\ 0 & 0 & 0 & d_4 \end{bmatrix}^k = \begin{bmatrix} (d_1)^k & 0 & 0 & 0 \\ 0 & (d_2)^k & 0 & 0 \\ 0 & 0 & (d_3)^k & 0 \\ 0 & 0 & 0 & (d_4)^k \end{bmatrix}$$

Definition 1. An $n \times n$ matrix A is said to be **diagonalizable** if

Application of diagonalization:

Question:

1. Are all $n \times n$ matrices A diagonalizable?
2. If a matrix A is diagonalizable, how to find the invertible matrix P and the diagonal matrix D ? The answer for this question is called **diagonalize** matrix A .

2. Eigenvalues and Eigenvectors.

Consider a linear transformation $T : \mathbb{F}^n \rightarrow \mathbb{F}^n$ by matrix $T\vec{x} = A\vec{x}$. ($\mathbb{F} = \mathbb{R}$ or \mathbb{C} .)

Definition 2. If there exist a nonzero vector $\vec{x} \in \mathbb{F}^n$ and a number $\lambda \in F$ such that

$$A\vec{x} = \lambda\vec{x}$$

then, the vector \vec{x} is **an eigenvector corresponding to the eigenvalue λ** .

Definition 3. A basis $\vec{b}_1, \dots, \vec{b}_n$ of \mathbb{F}^n is called an **eigenbasis** for A if the vectors $\vec{b}_1, \dots, \vec{b}_n$ are eigenvectors of A .

Example 4. If \vec{v} is an eigenvector of A corresponding to λ , is \vec{v} an eigenvector of A^k ? Is λ an eigenvalue of A^k ?

Theorem 5. A is diagonalizable if and only if it has n linearly independent eigenvectors $\vec{b}_1, \dots, \vec{b}_n$ (eigenbasis).

In this case $A = PDP^{-1}$ where the columns of P are eigenvectors of A ; the diagonal entries of D are the eigenvalues of A corresponding to the eigenvectors given by the columns of P .

Proof. We already verified that system of equations $A\vec{b}_1 = \lambda_1\vec{b}_1$, $A\vec{b}_2 = \lambda_2\vec{b}_2$, \dots , $A\vec{b}_n = \lambda_n\vec{b}_n$. is equivalent to matrix equation

$$AP = PD$$

where $P = [\vec{b}_1 \ \dots \ \vec{b}_n]$ and $D = \begin{bmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{bmatrix}$.

P is invertible if and only if $\{\vec{b}_1, \dots, \vec{b}_n\}$ is a basis of \mathbb{R}^n . In this case, $A = PDP^{-1}$ and A is diagonalizable.

□

Example 6. Let T be the projection transformation onto a line $L = \text{Span}\left\{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\right\} \mathbb{R}^3$.

Find a basis $\mathcal{B} = [\vec{b}_1 \ \vec{b}_2 \ \vec{b}_3]$ for \mathbb{R}^3 such that the \mathcal{B} -matrix of the T is the diagonal matrix

$$D = \begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix}.$$

Example 7. Let T be the rotation through an angle of $\pi/2$ in the counterclock direction. So the matrix of T is $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$. Find all eigenvalues and eigenvectors of A . Is A diagonalizable?

Example 8. Which matrix has 0 as an eigenvalue?

2. Eigenvalues and Characteristic Polynomials

Let A be an $n \times n$ matrix.

Theorem 9 (The Characteristic Equation of A).

Example 10. Finding Eigenvalues for the following matrices:

$$A = \begin{bmatrix} 2 & 5 \\ 3 & 4 \end{bmatrix} \quad B = \begin{bmatrix} i & 1 \\ 2 & 3 \end{bmatrix}$$

$$\text{eig}(A) = \begin{pmatrix} -1 \\ 7 \end{pmatrix}$$

$$\text{eig}(B) = \begin{pmatrix} \frac{3}{2} - \frac{\sqrt{16-6i}}{2} + \frac{1}{2}i \\ \frac{\sqrt{16-6i}}{2} + \frac{3}{2} + \frac{1}{2}i \end{pmatrix} \approx \begin{pmatrix} -0.5337 + 0.8688i \\ 3.5337 + 0.1312i \end{pmatrix}$$

Theorem 11. *The eigenvalues of a triangular $n \times n$ matrix A equal the diagonal entries of A .*

Proof. Suppose A is an upper triangular matrix.

$$\det(A - \lambda I) = \begin{vmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ 0 & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} - \lambda \end{vmatrix} = (a_{11} - \lambda)(a_{22} - \lambda) \cdots (a_{nn} - \lambda) = 0$$

Hence, the eigenvalues of A are a_{ii} for $i = 1, \dots, n$. □

Practice: Finding Eigenvalues for the following matrices:

$$A = \begin{bmatrix} 2 & 5 & \sqrt{2} \\ 3 & 4 & 7 \\ 0 & 0 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 2 & 1 & 0 \\ -1 & 4 & 0 \\ 3 & 5 & 7 \end{bmatrix}$$

In general for a $n \times n$ matrix A ,

$$\begin{aligned} \det(A - \lambda I) &= \begin{vmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} - \lambda \end{vmatrix} \\ &= (a_{11} - \lambda)(a_{22} - \lambda) \cdots (a_{nn} - \lambda) + \sum (\text{terms of degree} \leq (n-2)) \\ &= (-\lambda)^n - (a_{11} + a_{22} + \cdots + a_{nn})(-\lambda)^{n-1} + \sum (\text{terms of degree} \leq (n-2)) \end{aligned}$$

Definition 12 (Characteristic Polynomial). If A is an $n \times n$ matrix, the **characteristic polynomial** of A is

Example 13. Find the characteristic polynomial for a 2×2 arbitrary matrix.

Definition 14. The sum of the diagonal entries of a square matrix is called the **trace** of A ,

The characteristic polynomial for a 2×2 matrix A :

More generally,

Theorem 15. *Let A be an $n \times n$ matrix. Then the characteristic polynomial of A is*

More properties on Characteristic Polynomials

Definition 16 (Algebraic Multiplicity).

An eigenvalue λ_0 of A is said to have **algebraic multiplicity** k if it has multiplicity k as a root of the characteristic polynomial $f_A(t)$. Equivalently,

$$f_A(\lambda) = (\lambda_0 - \lambda)^k g(\lambda)$$

such that $g(\lambda_0) \neq 0$.

Theorem 17. *An $n \times n$ matrix has at most n eigenvalues, even counted with algebraic multiplicities.*

Example 18. Find all eigenvalues and their algebraic multiplicities of $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

Example 19. Find the characteristic polynomial of $A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}$. Which of the following numbers 1, -1 , 4 are eigenvalues of A ?

Example 20. Find the characteristic polynomial of $A = \begin{bmatrix} 2 & 1 & 2 \\ -1 & 4 & 2 \\ -1 & 1 & 5 \end{bmatrix}$. Verify that 3 and 5 are eigenvalues.

Theorem 21. *Let A be an $n \times n$ matrix. Suppose A has n eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$, (listed with algebraic multiplicities.) Then*

Theorem 22 (On Eigenvalues of Similar Matrices). *If A and B are similar,*

The converse of the preceding theorem is not generally true. There do exist matrices with the same characteristic polynomial that are not similar matrices. See example later.

Proposition 23. *If A and B are similar, then*

Proposition 24. *If A and B are similar, then*

Example 25. $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ are not similar, but they have the same rank, the same determinant, the same trace, the same eigenvalues.

Example 26. Are the following two matrices similar to each other? $A = \begin{bmatrix} 2 & 4 \\ 1 & 3 \end{bmatrix}$, $B =$

$$\begin{bmatrix} 3 & 5 \\ 2 & 3 \end{bmatrix}$$

Warning: Similar matrices may have **different** eigenvectors.

3. Eigenvectors and Eigenspaces

Theorem 27. Let A be an $n \times n$ matrix. A scalar λ is an eigenvalue for A if and only if the matrix equation

$$(A - \lambda I_n)\vec{x} = \vec{0}$$

has a nontrivial solution \vec{x} .

Said differently, λ is an eigenvalue for A if and only if

$$\text{Nul}(A - \lambda I_n) \neq \{\vec{0}\}.$$

Definition 28. Let A be an $n \times n$ matrix and λ be an eigenvalue of A . The set of all eigenvectors of A corresponding to λ together with the zero vector, is called the **eigenspace** of A corresponding to λ , and it equals the subspace

$$\text{Nul}(A - \lambda I_n).$$

The dimension of the eigenspace $\text{Nul}(A - \lambda I_n)$ is called the **geometric multiplicity** of λ .

Proposition 29.

$$1 \leq \text{Geometric multiplicity of } \lambda \leq \text{Algebraic multiplicity of } \lambda \leq n .$$

Example 30. Let T be the projection transformation onto a line $L = \text{Span}\left\{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\right\} \mathbb{R}^3$.
Explain the geometric meaning of the eigenvalues and eigenspaces.

Lemma 31. Let A be an $n \times n$ matrix and let $\vec{v}_1, \dots, \vec{v}_p$ be eigenvectors of A that correspond to distinct eigenvalues $\lambda_1, \dots, \lambda_p$ respectively. Then $\{\vec{v}_1, \dots, \vec{v}_p\}$ is a linearly independent set of vectors.

Proof. We prove this by induction on p . If $p = 1$, it is clear. Suppose this is true for $p - 1$ vectors.

□

Lemma 32. *Let A be an $n \times n$ matrix and let $\lambda_1, \dots, \lambda_p$ be distinct eigenvalues with corresponding independent set of eigenvectors V_1, \dots, V_p . Then $V_1 \cup \dots \cup V_p$ is a linearly independent set of vectors.*

Recall that an $n \times n$ matrix A is diagonalizable if and only if it has n linearly independent eigenvectors.

Proposition 33 (Case of Distinct Eigenvalues). *If an $n \times n$ matrix A has n **distinct** eigenvalues, then its corresponding eigenvectors are linearly independent and A is diagonalizable.*

Theorem 34. *Let $\lambda_1, \dots, \lambda_p$ be **distinct** eigenvalues of A such that*

$$f_A(\lambda) = \det(A - \lambda I) = (\lambda_1 - \lambda)^{k_1} (\lambda_2 - \lambda)^{k_2} \cdots (\lambda_p - \lambda)^{k_p}.$$

Suppose $k_1 + k_2 + \dots + k_p = n$. Let E_k be the eigenspace of λ_k .

Proof. A is diagonalizable if and only if it has n linearly independent eigenvectors.

□

Another point of view of the eigenspaces is the invariant subspace.

Definition 35. Let $T : V \rightarrow V$ be a linear transformation on a vector space V . A subspace $W \subseteq V$ is said to be **invariant** under T if

Proposition 36. A one-dimensional subspace is invariant under the linear transformation T_A if and only if it is an eigenspace spanned by an eigenvector of A .

Theorem 37. An $n \times n$ matrix A is similar to a diagonal matrix D , (i.e., $A = PDP^{-1}$) if and only if there exists a decomposition of

$$\mathbb{F}^n = V_1 \oplus V_2 \oplus \cdots \oplus V_n$$

such that each V_i is one dimensional and invariant under T_A .

In Matlab, $[P, D] = \text{eig}(A)$ returns diagonal matrix D of eigenvalues and matrix P whose columns are the corresponding right eigenvectors, such that $AP = PD$.

Example 38. Diagonalizing Matrices

$$A = \begin{bmatrix} 4 & -1 & 0 \\ 2 & 1 & 0 \\ 2 & -1 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} 5 & 1 & 0 \\ 2 & 4 & 0 \\ 2 & 1 & 3 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}, \quad M = \begin{bmatrix} 2 & 1 & 2 \\ -1 & 4 & 2 \\ -1 & 1 & 5 \end{bmatrix}.$$

Remark[Non Diagonalizing Result] For any $n > 1$ there exist examples of $n \times n$ matrices that are not diagonalizable.

Real Matrices Acting on \mathbb{C}^n

Let A be a real $n \times n$ matrix and λ be an eigenvalue of A .

- If λ is a real number, then there exist real eigenvectors associate to λ , as well as complex eigenvector.
- If λ is a complex (non-real) eigenvalue of A , then every eigenvector \vec{x} associated to λ is a complex (non-real) vector.

Suppose A is an $n \times n$ matrix with real number entries so that $\overline{A} = A$. Let λ be a complex eigenvalue of A with associated eigenvector \vec{x} . Then

$$\begin{aligned}\overline{A \cdot \vec{x}} &= \overline{A} \cdot \overline{\vec{x}} = A \cdot \overline{\vec{x}} \\ \overline{A \cdot \vec{x}} &= \overline{\lambda \cdot \vec{x}} = \overline{\lambda} \cdot \overline{\vec{x}}\end{aligned}$$

Combining the two we obtain

$$A \cdot \overline{\vec{x}} = \overline{\lambda} \cdot \overline{\vec{x}}.$$

Theorem 39. *Let A be an $n \times n$ matrix with real number entries and let λ be an eigenvalue of A with associated eigenvector \vec{x} . Then $\overline{\lambda}$ is also an eigenvalue of A with associated eigenvector $\overline{\vec{x}}$.*