

# Lab - Stability Problems

MATH 5110: Applied Linear Algebra and Matrix Analysis

Northeastern University

Author: Chris King

## 1 Background

Let  $A$  be a real  $n \times n$  matrix, and consider the  $n$ -dimensional linear dynamical system described by the update equation

$$\vec{x}(1) = A \vec{x}(0)$$

By iterating this equation we obtain the sequence of vectors  $\vec{x}(0), \vec{x}(1), \vec{x}(2), \dots$ , where

$$\vec{x}(k) = A^k \vec{x}(0), \quad k = 1, 2, 3, \dots$$

The system is said to be *asymptotically stable* if for every initial vector  $\vec{x}(0)$  we have

$$\vec{x}(k) = A^k \vec{x}(0) \rightarrow \vec{0} \quad \text{as } k \rightarrow \infty$$

For example, suppose  $n = 2$  and

$$A = \begin{pmatrix} 0.5 & 0 \\ 0 & -0.2 \end{pmatrix}, \quad \vec{x}(0) = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

Then for every integer  $k$  we have

$$\vec{x}(k) = A^k \vec{x}(0) = \begin{pmatrix} (0.5)^k x_1 \\ (-0.2)^k x_2 \end{pmatrix}$$

Since  $r^k \rightarrow 0$  for every  $|r| < 1$  this shows that  $(0.5)^k x_1 \rightarrow 0$  and  $(-0.2)^k x_2 \rightarrow 0$ , hence the system is asymptotically stable.

Now suppose that  $A$  is diagonalizable and consider the factorization

$$A = S D S^{-1}$$

where  $D = \text{diag}(\lambda_1, \dots, \lambda_n)$ . Then

$$A^k = S D^k S^{-1}, \quad k = 1, 2, 3, \dots$$

where  $D^k = \text{diag}(\lambda_1^k, \dots, \lambda_n^k)$ . We see that  $\lambda_1^k \rightarrow 0$  if  $|\lambda_1| < 1$ , and similarly for the other eigenvalues. Thus the necessary and sufficient condition for asymptotic stability is that all eigenvalues of  $A$  have absolute value less than 1.

## 2 Computation

Consider the 3-dimensional dynamical system with matrix

$$A = \frac{1}{8} \begin{pmatrix} 1 & 2 & 1 \\ 3 & 4 & 1 \\ 2 & 3 & 4 \end{pmatrix}$$

### 2.1 Task 1

Show that the system with matrix  $A$  is asymptotically stable.

### 2.2 Task 2

Let  $\vec{u}, \vec{w}$  be vectors given by

$$\vec{u} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \quad \vec{w} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$$

and define the matrix

$$B = \frac{1}{5} \vec{u} \vec{w}^T$$

We suppose that the original system with matrix  $A$  is perturbed by the addition of matrix  $B$ : the perturbed system has matrix

$$A(s) = A + s B$$

where  $s$  is a real number. So for example  $A(0) = A$ , and  $A(1) = A + B$ . From Task 1 we know that the matrix  $A(s)$  is stable at  $s = 0$ . Use Matlab to show that the system is unstable at  $s = 1$ . Use Matlab to find the smallest integer  $m$  such that the matrix  $A(s)$  is unstable at  $s = -m$ .

### 2.3 Task 3

The matrix  $A(s)$  is stable for all  $s$  in an open interval  $(-a, b)$  where  $a, b$  are real positive numbers, and it is unstable for  $s$  outside this interval. Use Matlab to compute the numbers  $a$  and  $b$  to 2 decimal places.