



LinkedIn

Integration in 2 dimensions

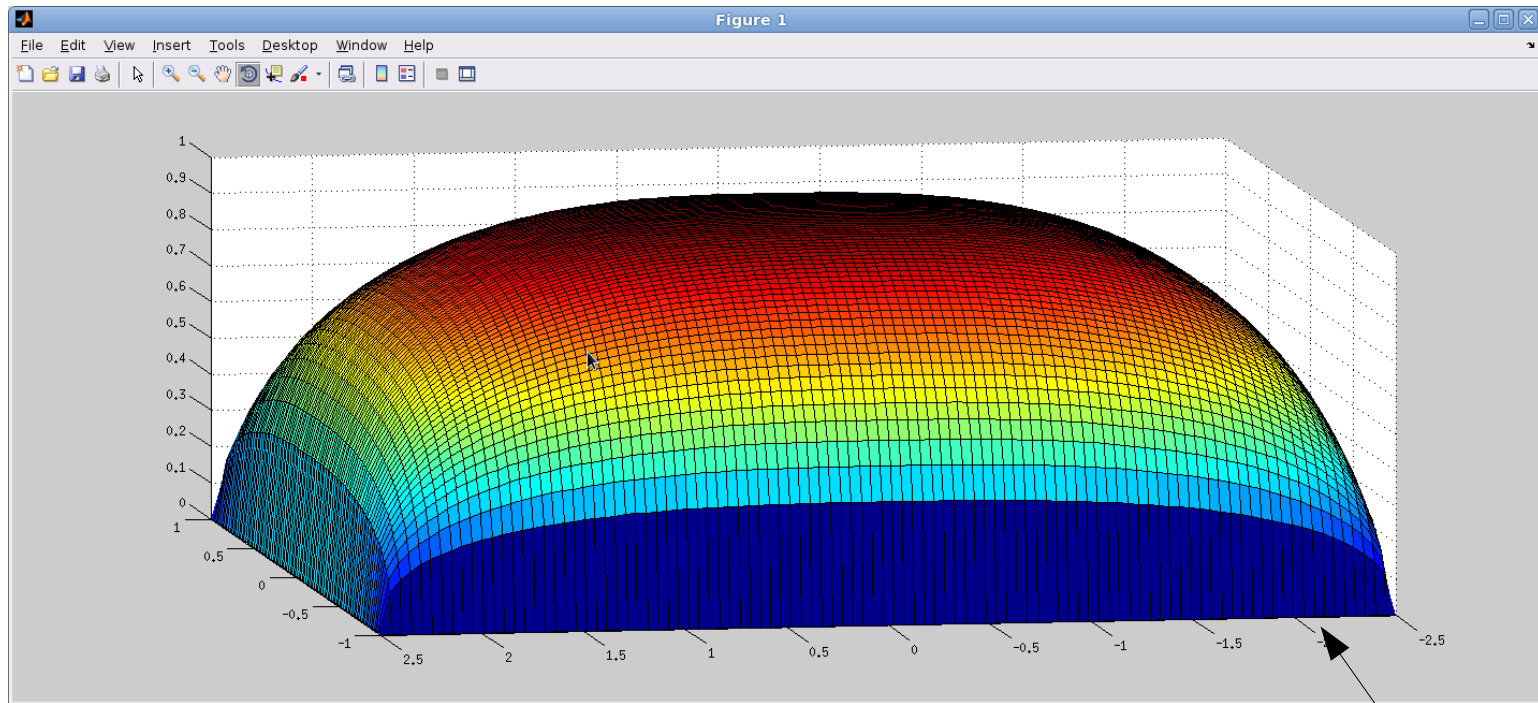
- Midpoint method in 2D
- Gaussian quadrature in 2D
- Extension to ND should be obvious after we think about 2D.

Example: Volume of tennis court



- Find volume of inflatable building.
- Useful computation for planning air conditioning (for example).

Compute volume using midpoint rule



- Model: $z(x, y) = \left(1 - \left|\frac{x}{a}\right|^p\right)^{1/p} \left(1 - \left|\frac{y}{b}\right|^p\right)^{1/p}$ $p = 2.7$
- Shape of dome depends upon parameter p .
- No closed form expression for integral?

Aside on superellipse

- Superellipse

$$\left(\left| \frac{x}{a} \right|^p + \left| \frac{y}{b} \right|^p \right)^{1/p} = c$$

- Parameter p “tunes” the shape of the superellipse.

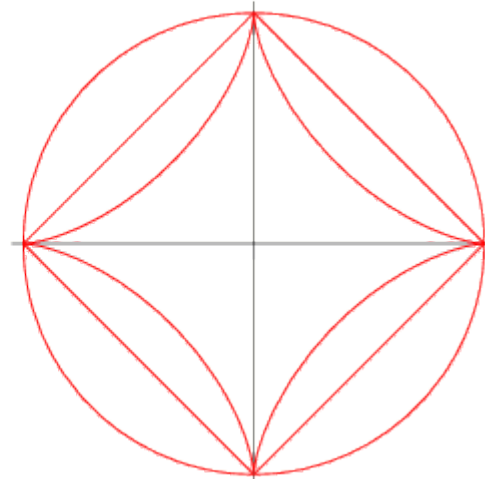
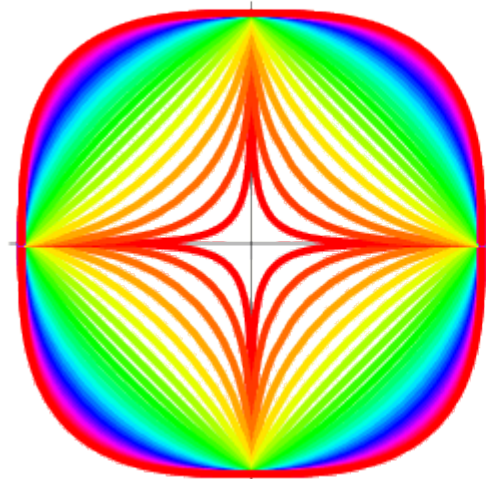
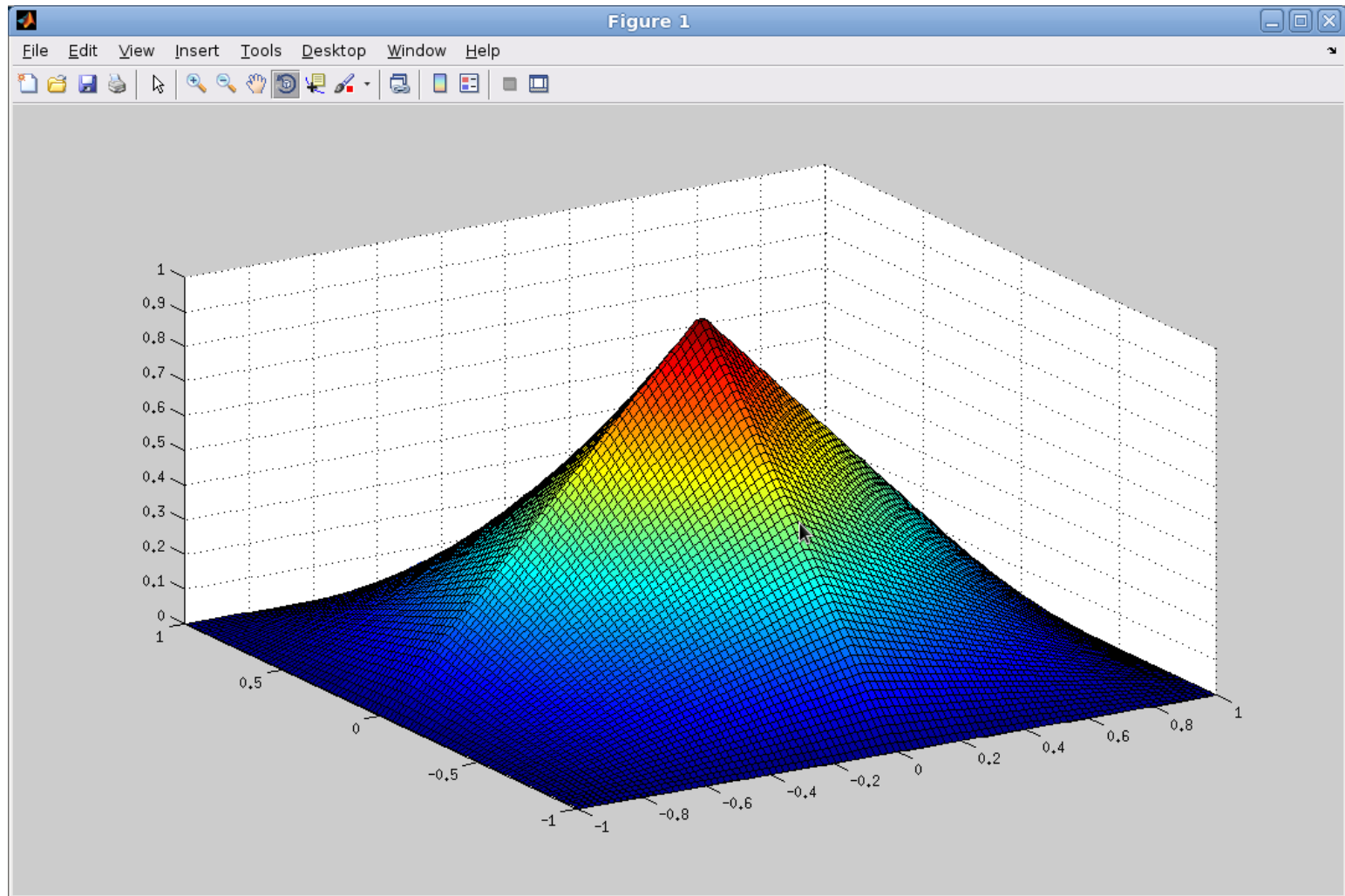


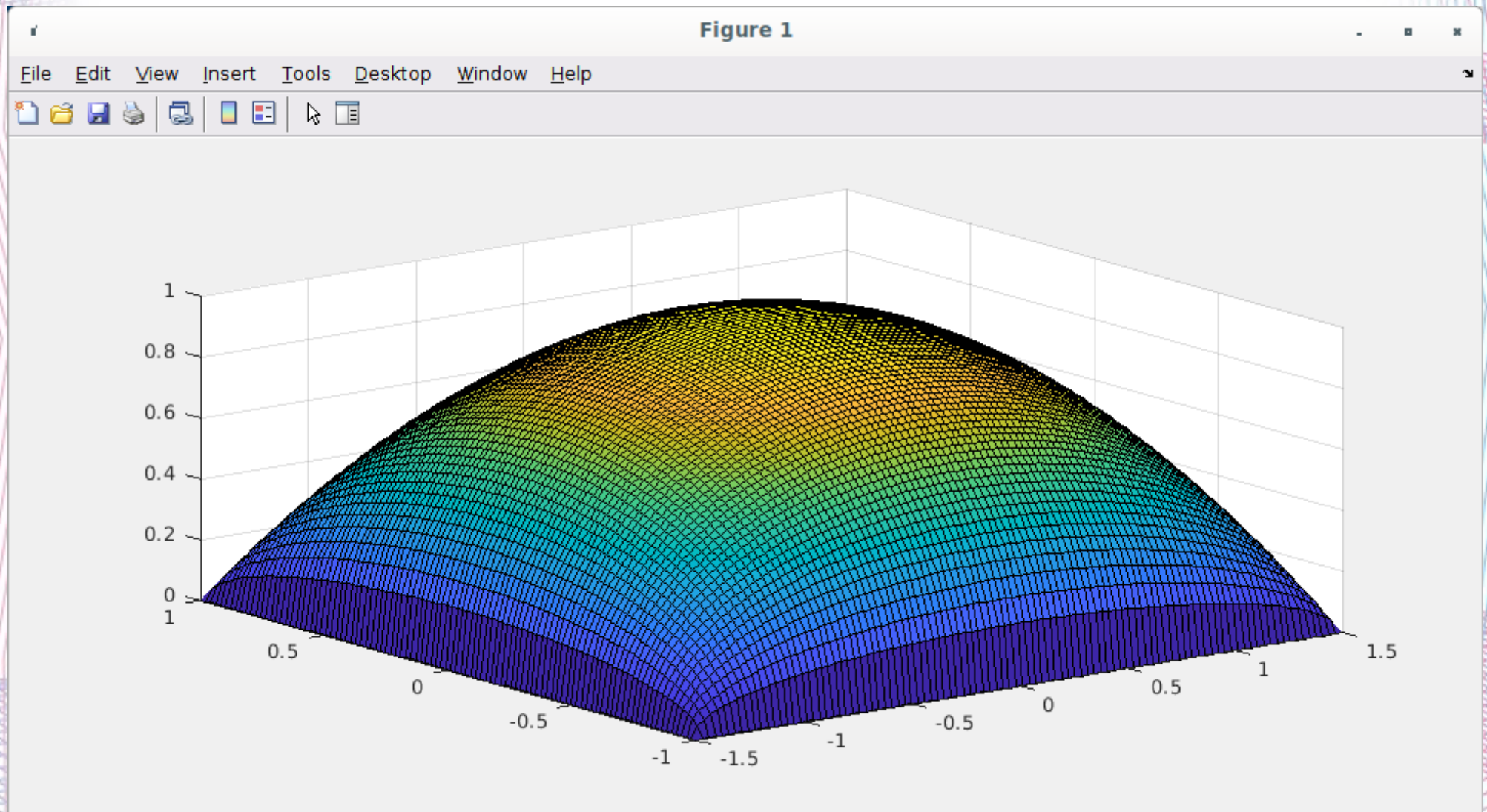
Image source:
Wolfram Math
World

- I model tennis court as superellipse in x and y directions.

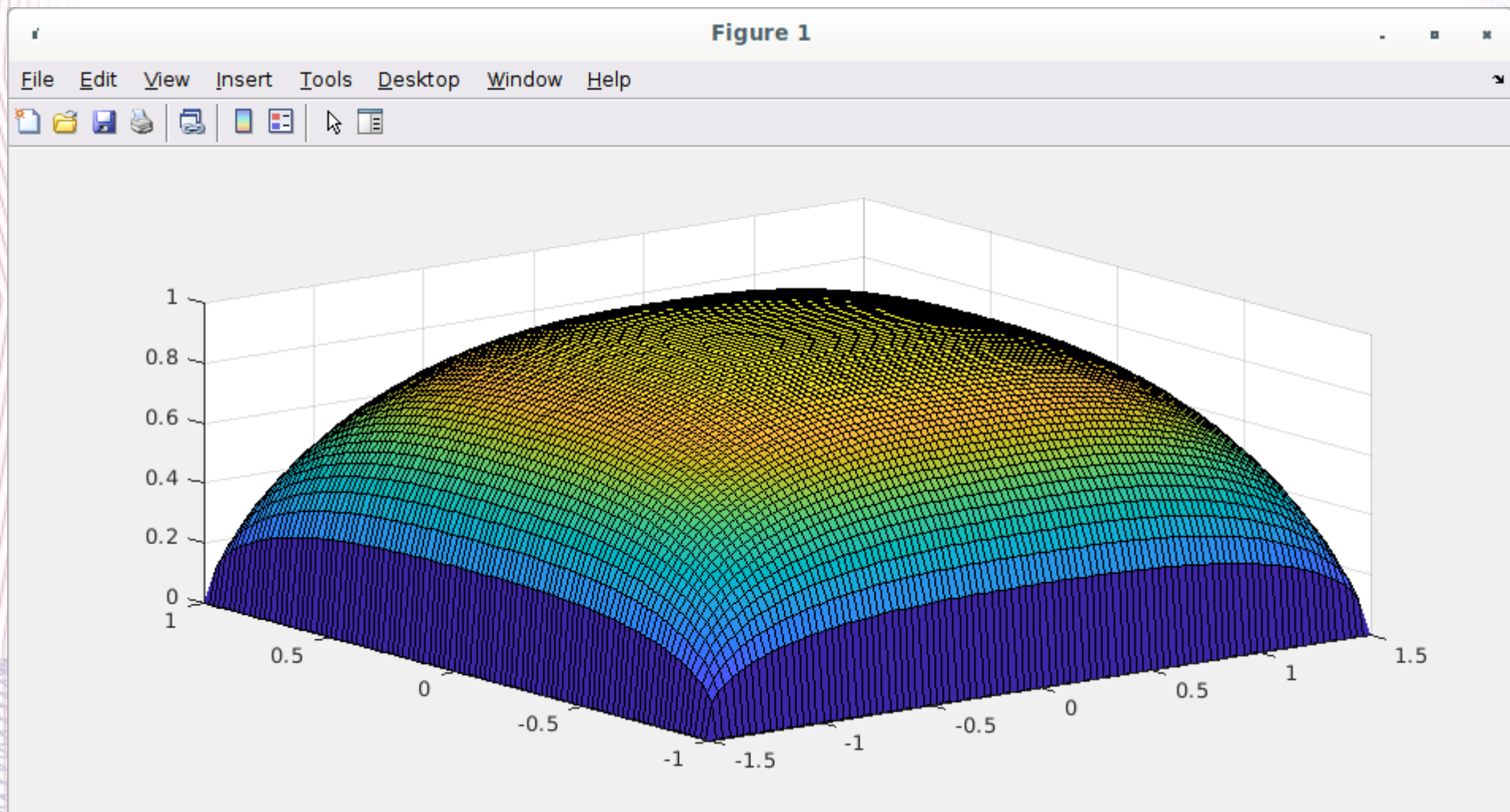
$$P = 1$$



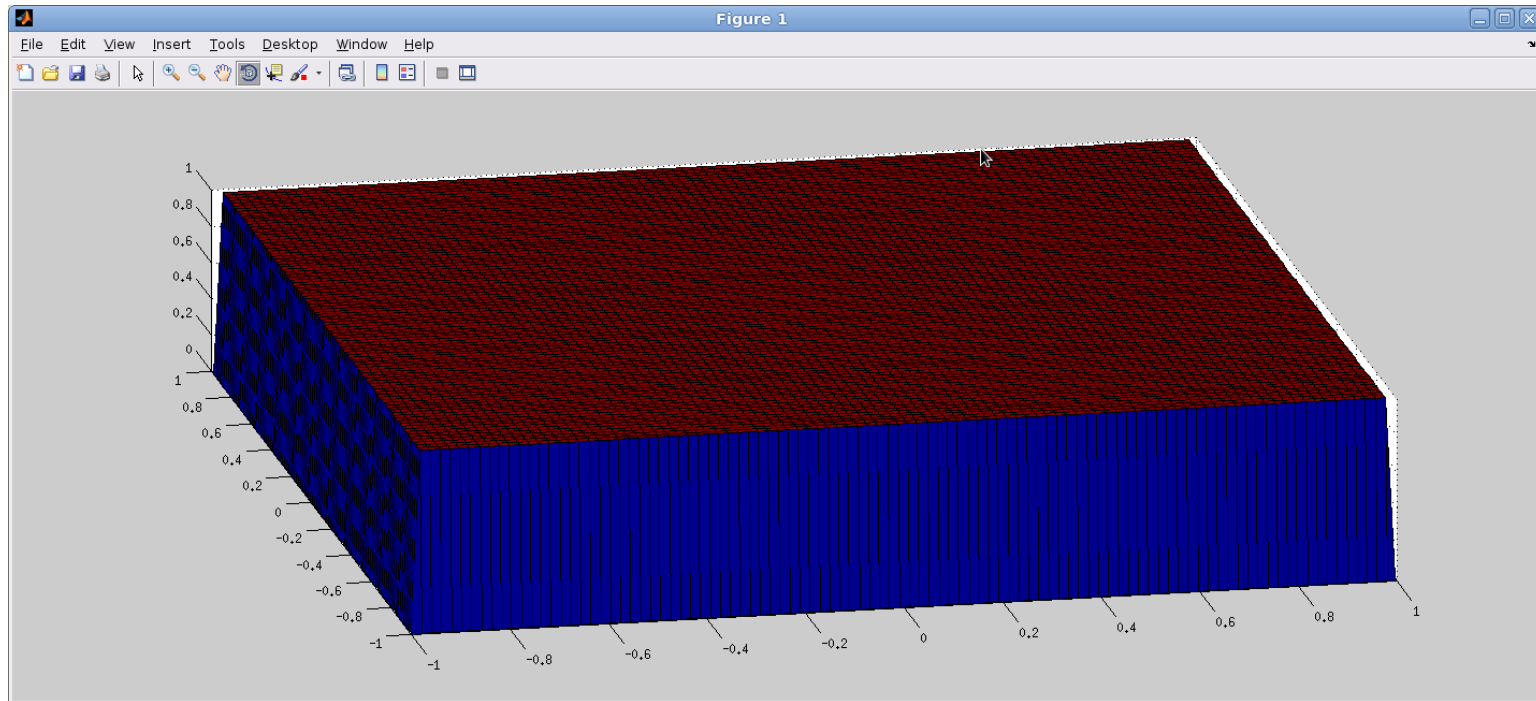
$$P = 2$$



$$P = 2.7$$



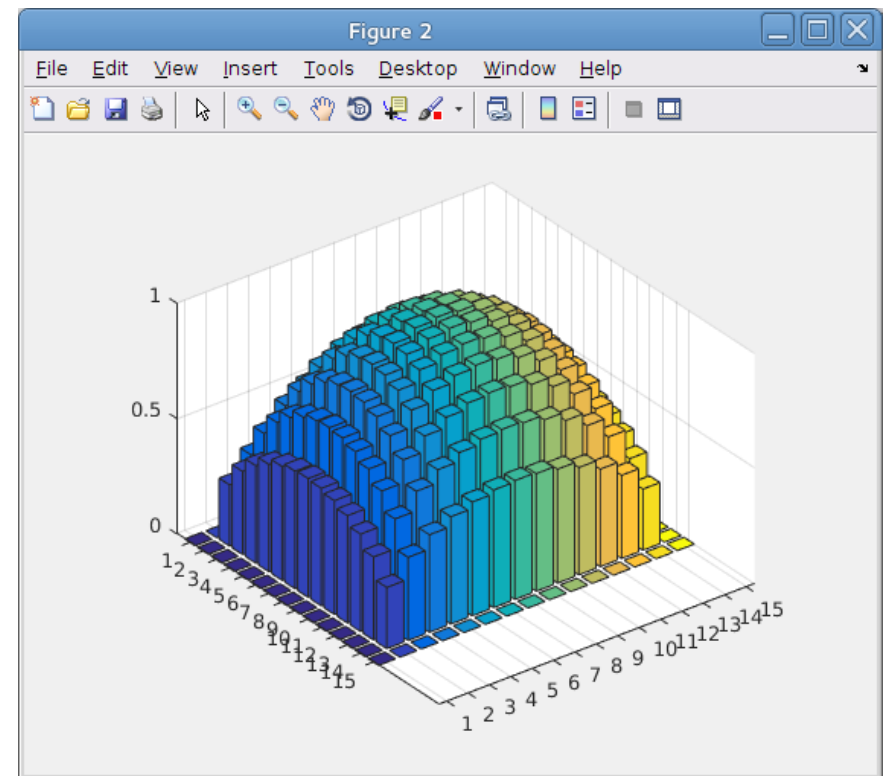
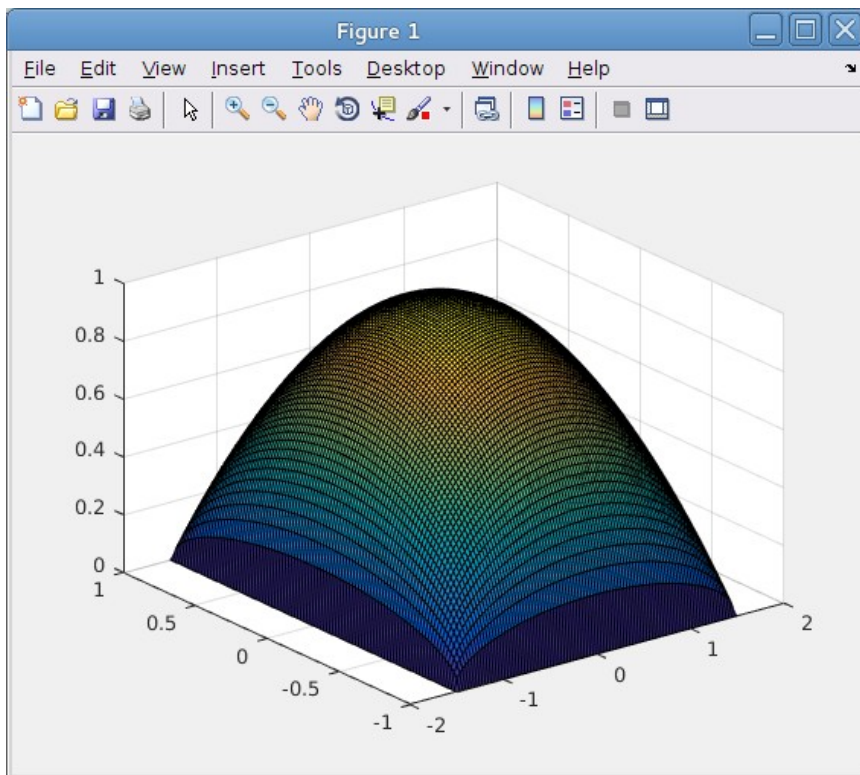
$$P = 1000$$



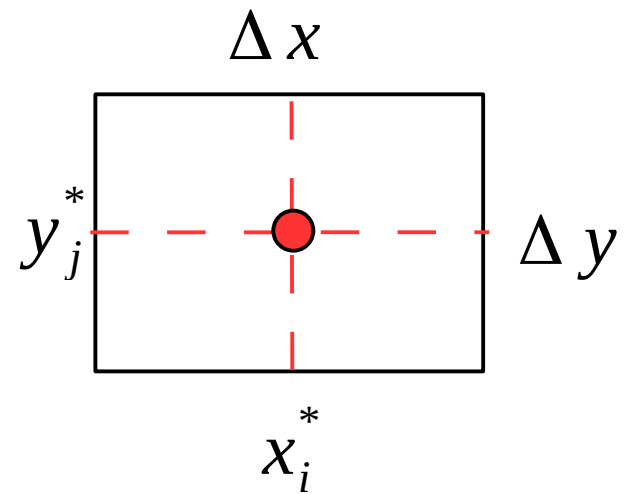
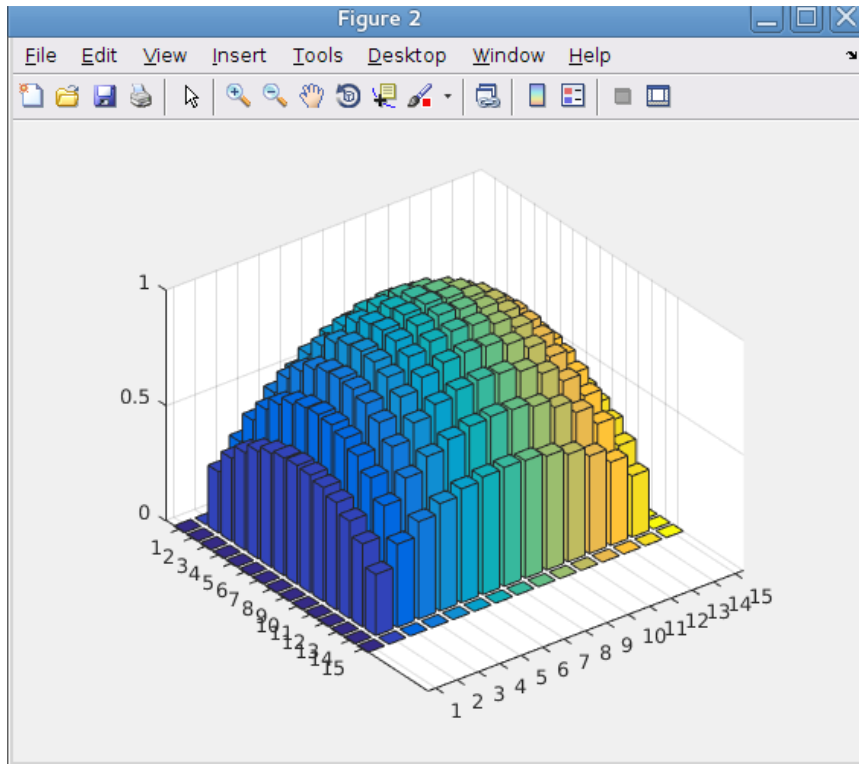
- Shape is a cuboid (rectangular cube)
- Good test case – we can easily compute the volume

Simplest idea: 2D midpoint method

1. Divide region of interest up into rectangles (cells).
2. Compute integral using sum of function values at midpoints of cells.



2D midpoint method



$$I = \iint_A dx dy f(x, y) \approx \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} f(x_i^*, y_j^*) \Delta x \Delta y$$

Star means evaluate the function at the mid point of the box.

```
% Chop up dome into smaller areas (cells)
x = linspace(-Lx/2, Lx/2, Nx);
dx = x(2) - x(1);
y = linspace(-Ly/2, Ly/2, Ny);
dy = y(2) - y(1);

% Now do midpoint-rule integration on each area
V = 0; % Volume to compute
% Loop over sample points. Don't use last one because
% it is at an edge
for xidx=1:(Nx-1)
    for yidx=1:(Ny-1)
        % Find point in middle of rectangle
        x0 = x(xidx) + dx/2;
        y0 = y(yidx) + dy/2;
        % Add value of fcn at this point to the running volume sum.
        ss = s(dome, x0, y0);
        V = V + ss*dx*dy;
    end
end
```

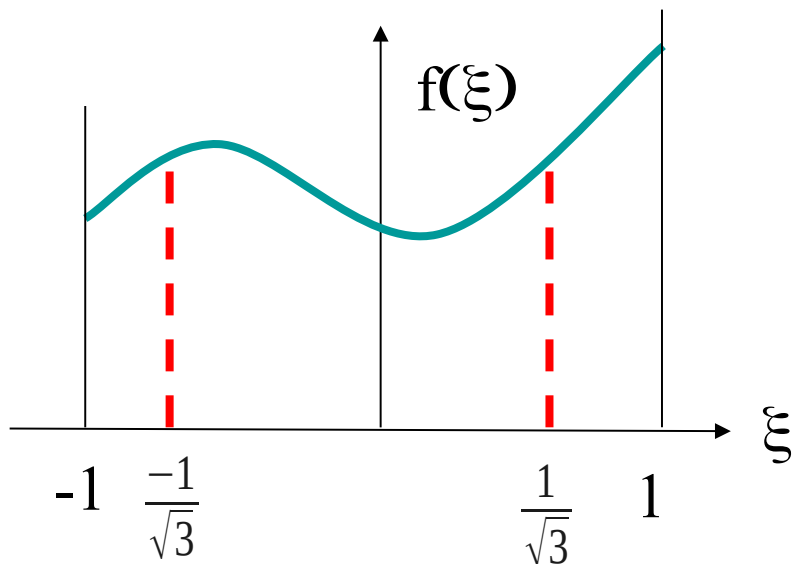

Midpoint rule in 2D

- Advantages:
 - Simple
- Disadvantages:
 - Not particularly accurate
 - Can't deal with non-rectangular domains.

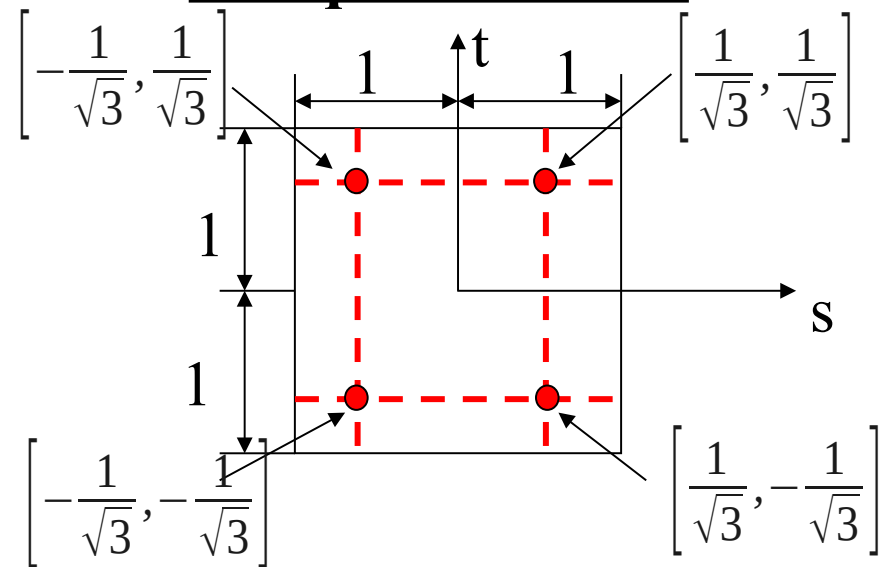
Can we use Gaussian quadrature directly in 2D?

- Yes – combine mid-point method with 2D interpolants for $f(x, y)$.

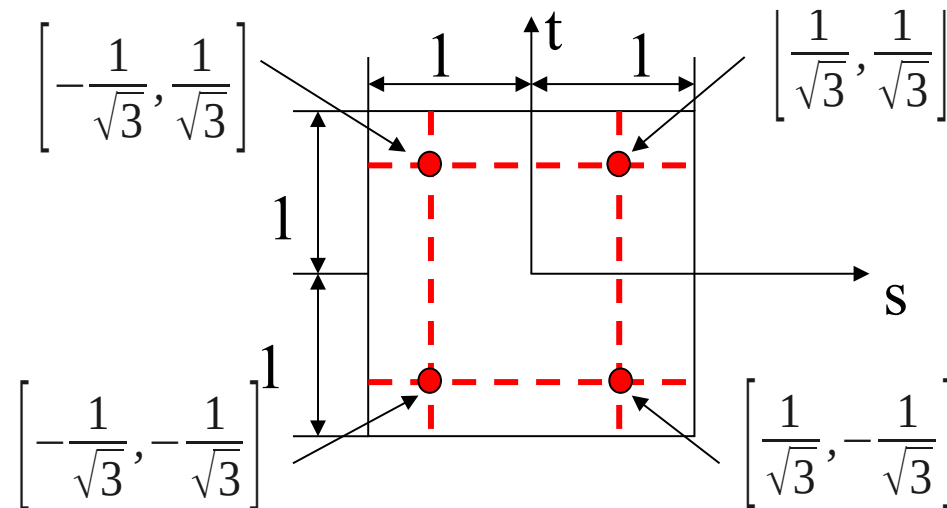
1D linear domain



2D square domain



2D Gaussian Quadrature M = 2



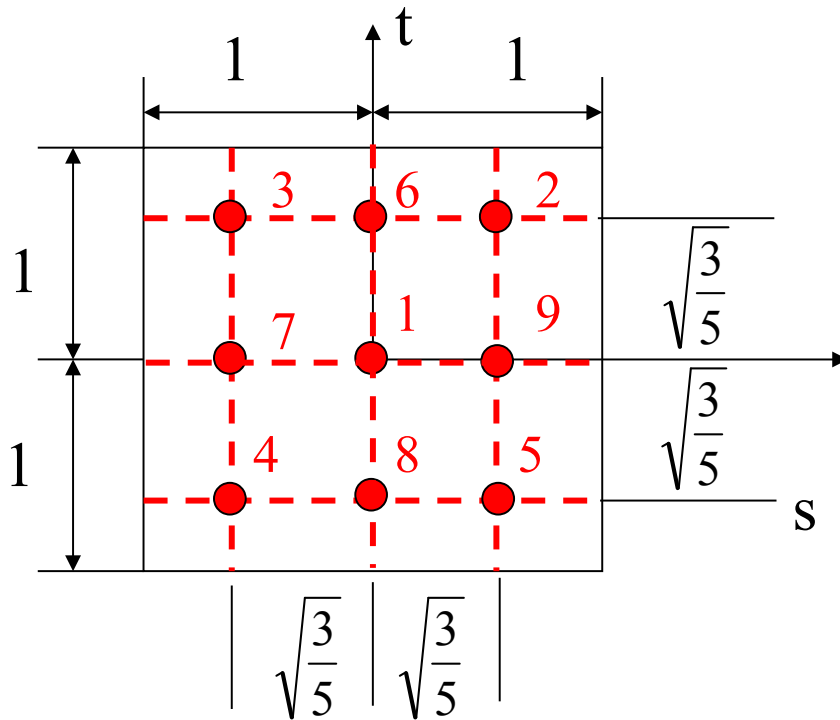
$$I = \int_{-1}^1 ds \int_{-1}^1 dt f(s, t) \approx \sum_{i=1}^2 \sum_{j=1}^2 w_{ij} f(s_i, t_j)$$

$$= f(r, r) + f(r, -r) + f(-r, r) + f(-r, -r)$$

with $r = \frac{1}{\sqrt{3}}$ and $w_{ij}^{(2)} = w_i^{(1)} w_j^{(1)} = 1$

- 2D weights are products of 1D weights
- Formula is exact for product of two cubics

2D Gaussian Quadrature M = 3



$$w^{(2)}(1) = w_i^{(1)} w_j^{(1)} = \frac{8}{9} \cdot \frac{8}{9} = \frac{64}{81}$$

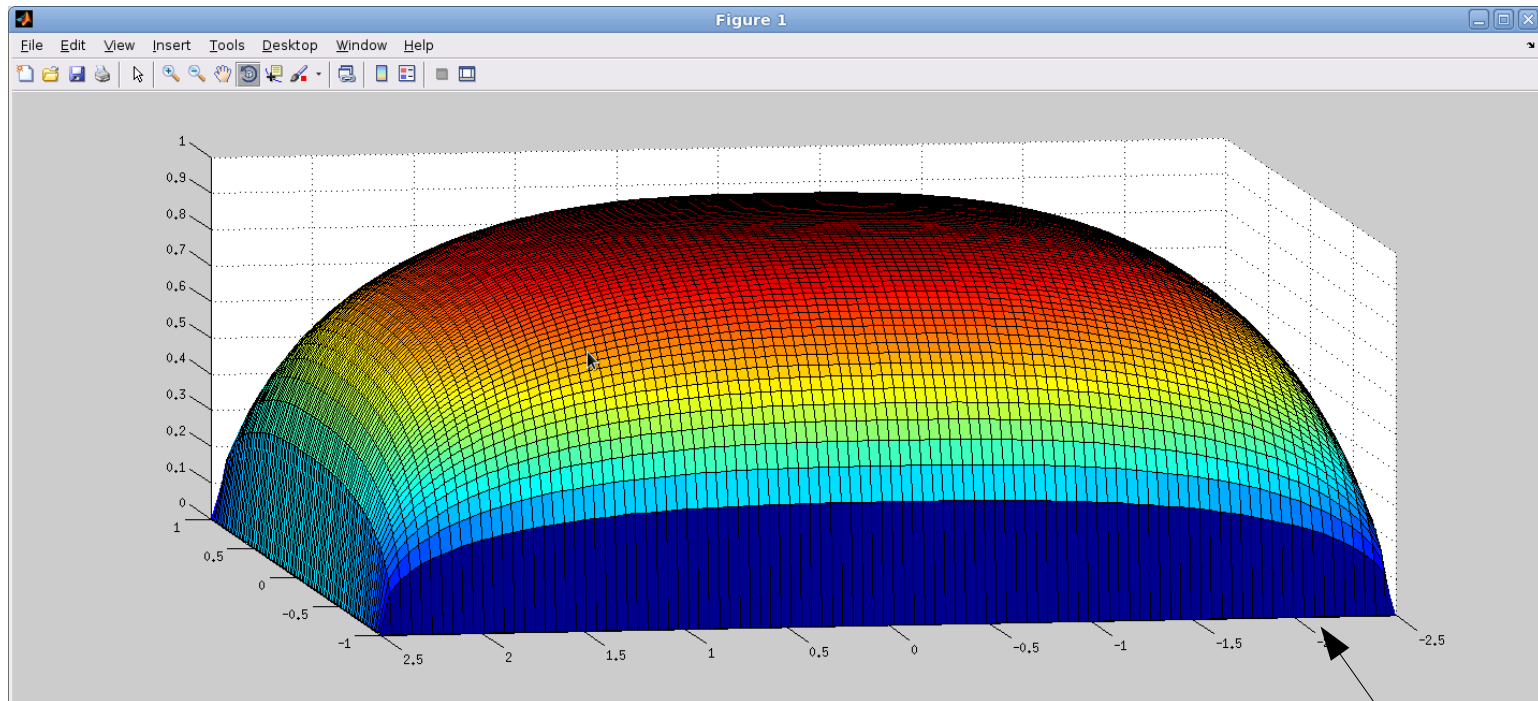
$$w^{(2)}(2,3,4,5) = \frac{5}{9} \cdot \frac{5}{9} = \frac{25}{81}$$

$$w^{(2)}(6,7,8,9) = \frac{5}{9} \cdot \frac{8}{9} = \frac{40}{81}$$

$$I = \int_{-1}^1 ds \int_{-1}^1 dt f(s, t) \approx \sum_{i=1}^3 \sum_{j=1}^3 w_{ij} f(s_i, t_j)$$

- 2D weights are products of 1D weights
- Method is exact for product of two 5th degree polynomials

Compute volume using Gaussian quadrature

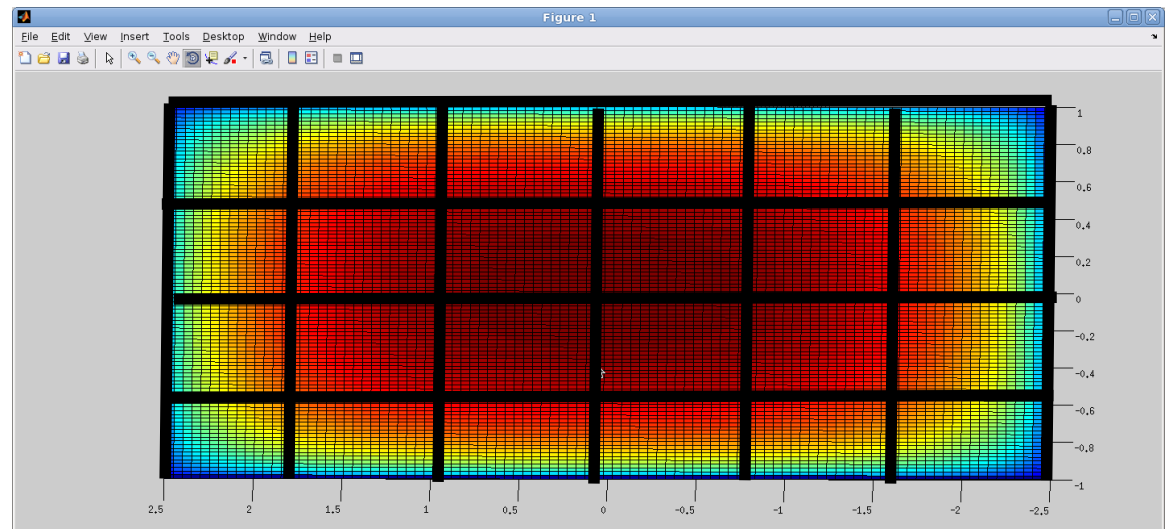


- Model: $z(x, y) = \left(1 - \left|\frac{x}{a}\right|^p\right)^{1/p} \left(1 - \left|\frac{y}{b}\right|^p\right)^{1/p}$ $p = 2.7$
- Shape of dome depends upon parameter p .
- No closed form expression for integral?

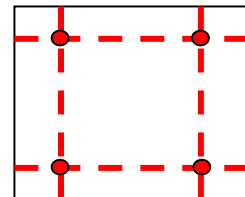
Compute integral using M=2 Gaussian Quadrature

$$V = \int_{-L_x/2}^{L_x/2} dx \int_{-L_y/2}^{L_y/2} dy \left(1 - \left(\frac{x}{a} \right)^p \right)^{1/p} \left(1 - \left(\frac{y}{b} \right)^p \right)^{1/p}$$

- Chop domain into boxes:



- Do M=2 Gaussian quadrature on each box:




```

% Chop up dome into smaller areas
x = linspace(-Lx/2, Lx/2, Nx);
dx = x(2) - x(1);
y = linspace(-Ly/2, Ly/2, Ny);
dy = y(2) - y(1);

% Now do Gaussian quadrature integration on each area
V = 0; % Volume to compute
hx = dx/(2*sqrt(3)); % Define convenience variable.
hy = dy/(2*sqrt(3)); % Define convenience variable.
% Loop over sample points. Don't use last one because
% it is at an edge
for xidx=1:(Nx-1)
    for yidx=1:(Ny-1)
        % Find point in middle of rectangle
        x0 = x(xidx) + dx/2;
        y0 = y(yidx) + dy/2;

        % Now compute value of fcn at quadrature points
        spp = s(dome, x0 + hx, y0 + hy);
        spm = s(dome, x0 + hx, y0 - hy);
        smp = s(dome, x0 - hx, y0 + hy);
        smm = s(dome, x0 - hx, y0 - hy);
        V = V + (spp+spm+smp+smm)*dx*dy/4;
    end
end
end

```

Test integration for different p

Integrating dome with p=1. Answer should be 1.500000

Testing accuracy of 2D Gaussian quadrature

p = 1.000000, Vgauss = 1.500000, Vtrue = 1.500000, diff = 4.440892e-16 ... Passed!

Testing accuracy of 2D midpoint rule

p = 1.000000, Vmid = 1.500000, Vtrue = 1.500000, diff = 2.220446e-16 ... Passed!

Integrating dome with p=2. Answer should be 3.701102

Testing accuracy of 2D Gaussian quadrature

p = 2.000000, Vgauss = 3.701735, Vtrue = 3.701102, diff = -6.328837e-04 ... Passed!

Testing accuracy of 2D midpoint rule

p = 2.000000, Vmid = 3.855406, Vtrue = 3.701102, diff = -1.543042e-01 ... Failed

Integrating dome with p=4. Answer should be 5.156389

Testing accuracy of 2D Gaussian quadrature

p = 4.000000, Vgauss = 5.158872, Vtrue = 5.156389, diff = -2.482626e-03 ... Failed

Testing accuracy of 2D midpoint rule

p = 4.000000, Vmid = 5.347053, Vtrue = 5.156389, diff = -1.906632e-01 ... Failed

Integrating dome with p=10000. Answer should be 6.000000

Testing accuracy of 2D Gaussian quadrature

p = 10000.000000, Vgauss = 6.000000, Vtrue = 6.000000, diff = -1.776357e-15 ...
Passed!

Testing accuracy of 2D midpoint rule

p = 10000.000000, Vmid = 6.000000, Vtrue = 6.000000, diff = -1.776357e-15 ... Passed!

Using Gaussian quadrature, with p = 2.700000, tennis court volume = 4.463983

Using 2D midpoint rule, with p = 2.700000, tennis court volume = 4.652684

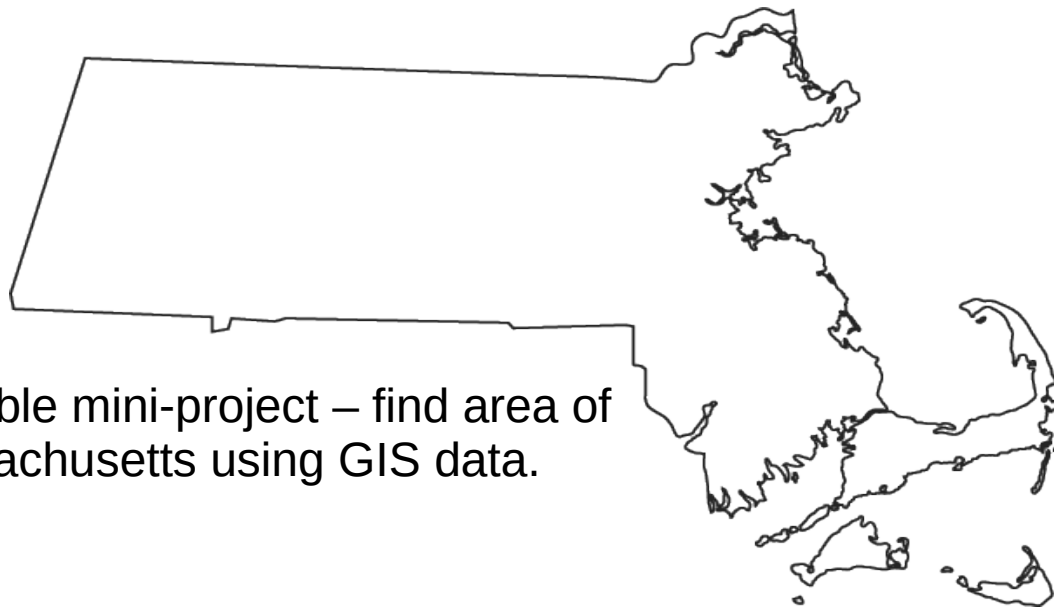
Remarks

- Accuracy will increase with:
 - Increased quadrature order (M)
 - Increased number of integration cells
- Extension to higher dimensions obvious.
- We still have not solved the problem of integration over irregular domains.

Integrating over odd-shaped boundaries

- Example: Find area of Massachusetts

Possible mini-project – find area of Massachusetts using GIS data.



A note on integration

- Find surface area of a domain

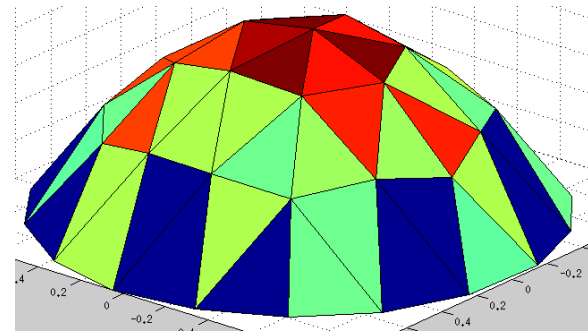
$$\iint_{(x,y) \in A} dx dy 1$$

Possible mini-project – find area of Massachusetts using GIS data.



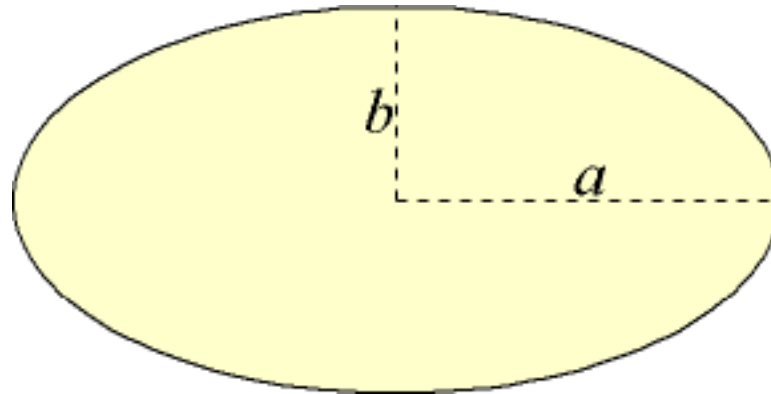
- Integrate function over a domain

$$\iint_{(x,y) \in A} dx dy f(x, y)$$



Simple example: Area of Ellipse

- Classical formula: $A = \pi a b$



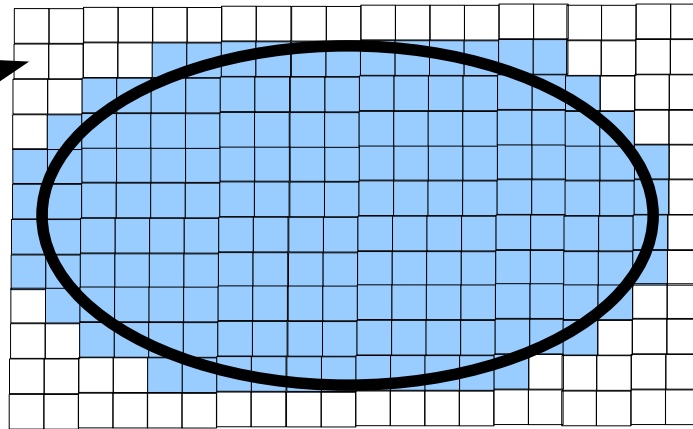
- Points inside ellipse satisfy:

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} < 1$$

- Finding area is same as integrating over domain of function $f(x, y) = 1$.

Area of ellipse: count boxes

Area of little box
= $dx \, dy$



- Algorithm:

1. Initialize: $A = 0$

2. Loop over all boxes

3. For each box, if $\frac{x^2}{a^2} + \frac{y^2}{b^2} < 1$ then
 $A = A + dx \, dy$

4. End loop

5. Return A

The core of this algorithm involves knowing when we're inside or outside the boundary

If box is inside, add in area of small box.

Matlab code

```
function A = box_count_ellipse(a, b)
% This fcn uses box counting to get the area of an
% ellipse whose semi-major/minor axes are a, b.
```

```
N = 10000;
x = linspace(-a, a, N);
y = linspace(-b, b, N);
dx = x(2) - x(1);
dy = y(2) - y(1);
```

```
% Convenience definitions.
a2 = a*a;
b2 = b*b;
```

```
A = 0;           % Initialize A
for ix = 1:N
    for iy = 1:N
        p = x(ix)*x(ix)/a2 + y(iy)*y(iy)/b2;
        if (p < 1)
            A = A + dx*dy;
        end
    end
end
```

```
end
```

Include $f(x, y)$ here if integrating a more complicated function than $f(x, y) = 1$.

Box counting results

- $N = 100$

```
>> test_ellipse_area_boxcount
```

```
Ellipse a, b = 1.000000, 1.000000 ...
```

```
Acomputed = 3.129477, Atrue = 3.141593, relldiff = -3.856665e-03
```

```
Ellipse a, b = 3.672186, 1.130595 ...
```

```
Acomputed = 12.992818, Atrue = 13.043121, relldiff = -3.856665e-03
```

- $N = 10000$

```
>> test_ellipse_area_boxcount
```

```
Ellipse a, b = 1.000000, 1.000000 ...
```

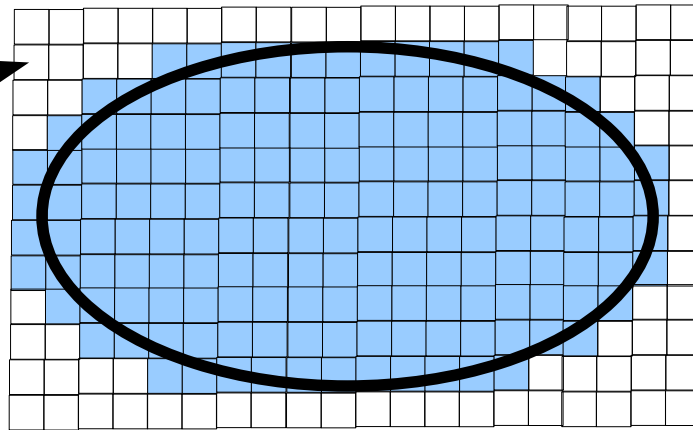
```
Acomputed = 3.141583, Atrue = 3.141593, relldiff = -3.172019e-06
```

```
Ellipse a, b = 1.952509, 0.541740 ...
```

```
Acomputed = 3.323019, Atrue = 3.323029, relldiff = -3.172641e-06
```


Box counting for ellipse....

Area of little box
= $dx \, dy$



1. Initialize: $A = 0$
2. Loop over all boxes
3. For each box, if
 $A = A + dx \, dy$
4. End loop
5. Return A

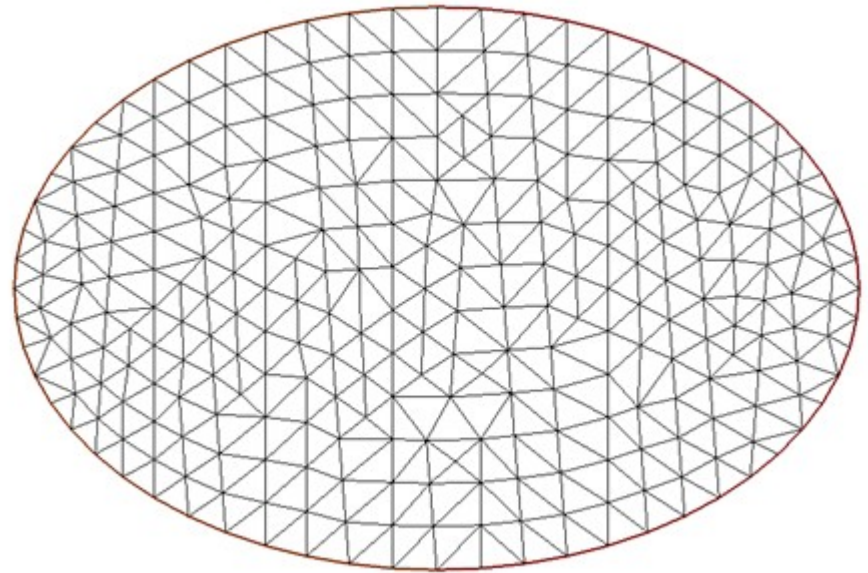
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} < 1 \text{ then}$$

The core of this algorithm involves knowing when we're inside or outside the boundary

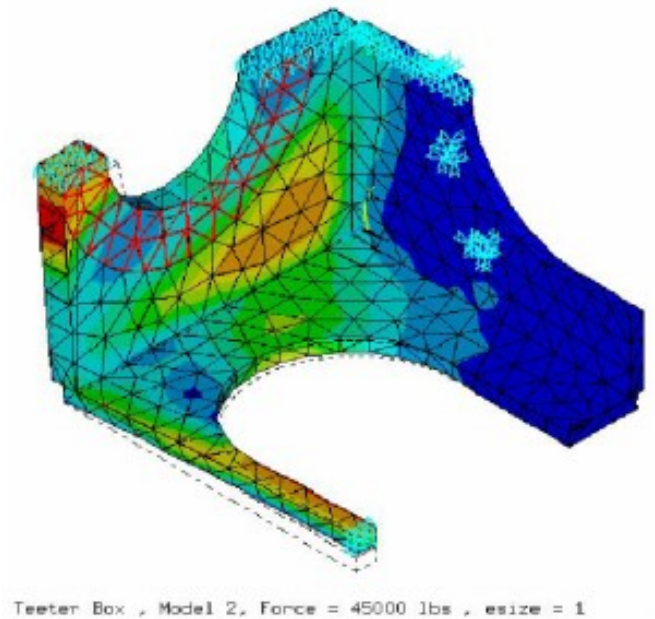
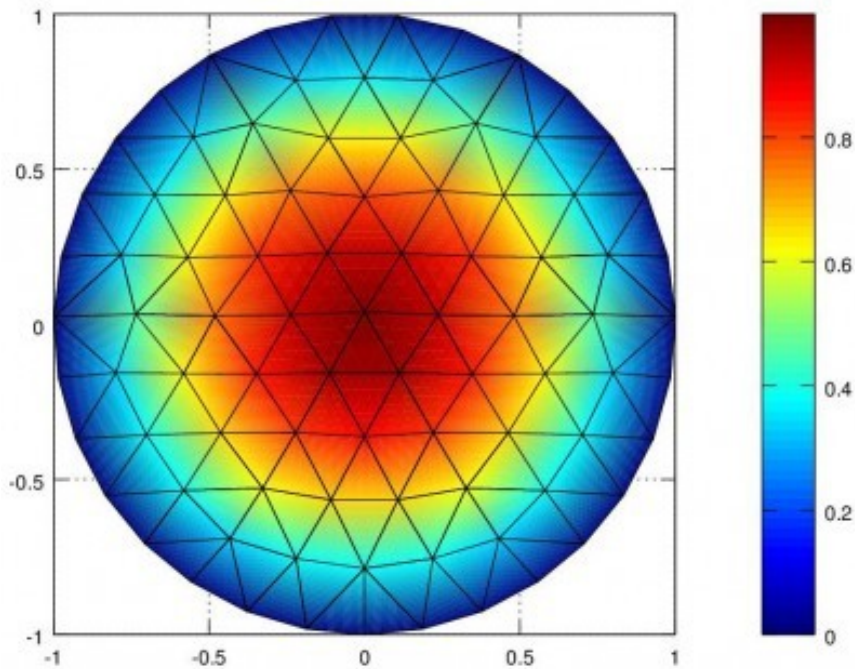
But accuracy stinks because boundaries are not well handled

A different method

- Mesh your object, then compute area of each triangle.
- More accurate than counting boxes – computation is 2D trapezoidal method.
- Boundaries are handled better.
- Method fits nicely with data structures and concepts used in FEA analysis.



Concept: mesh



Teeter Box , Model 2, Force = 45000 lbs , esize = 1

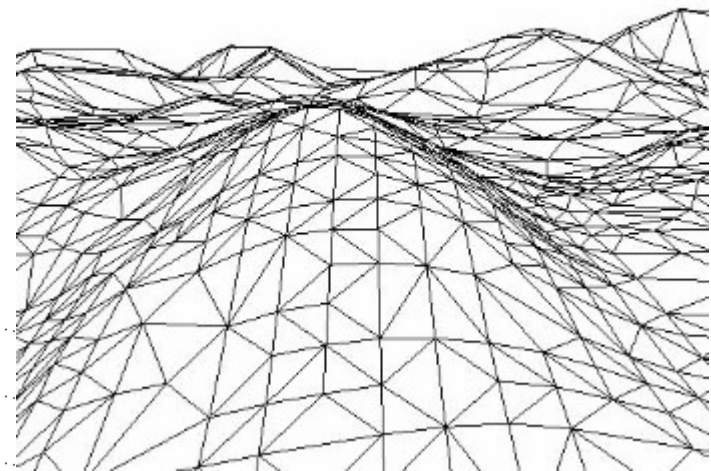
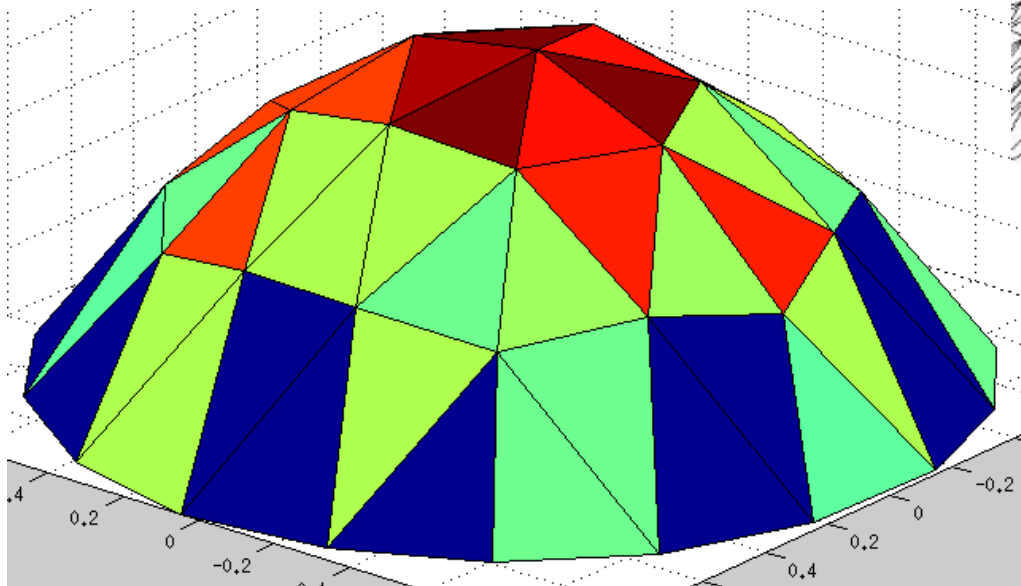
Figure 3

<http://www.umass.edu/mie/labs/mda/fea/fealib/goldstein/PROJECT.html>

- Cover domain with triangles.
- Triangles follow boundaries much better than simple squares.

Representing a function using a mesh

- Assemble individual triangles into function defined over domain

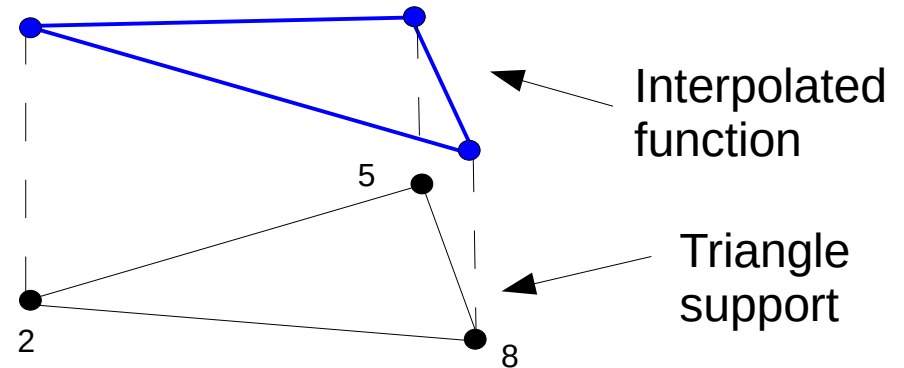
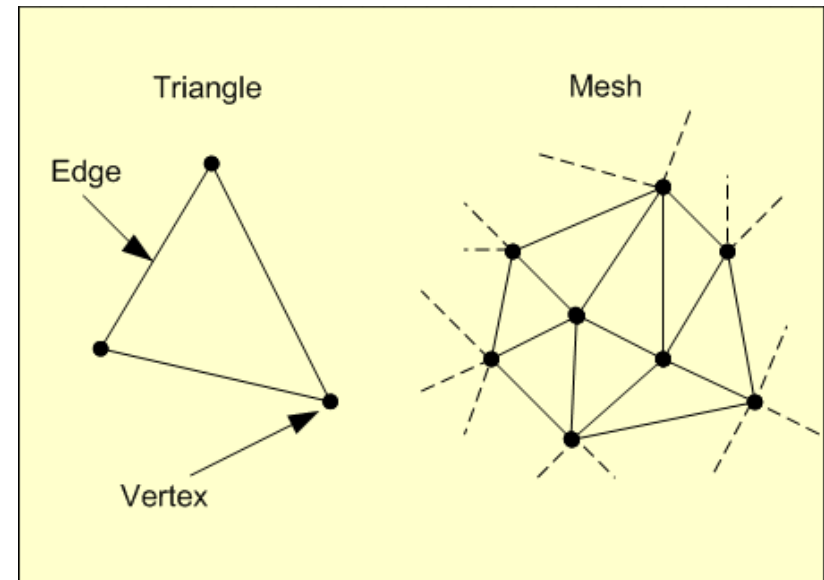


Arbitrary function

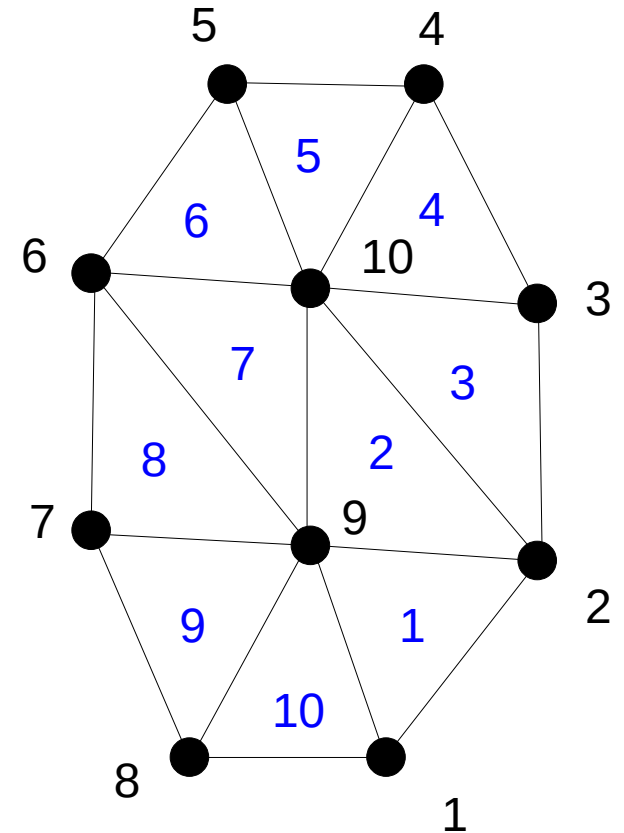
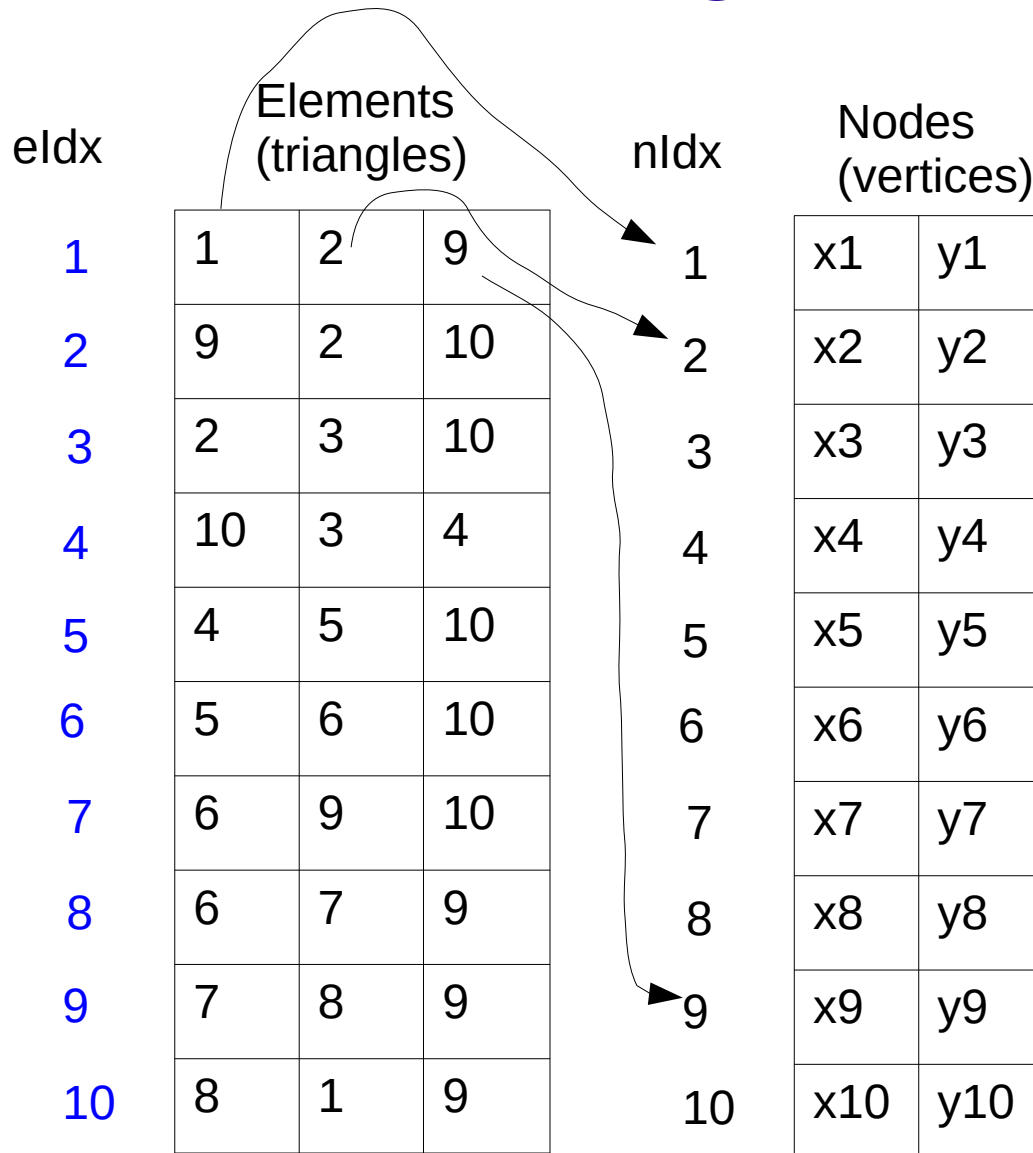
$1 - (x^2 + y^2)$

Using a mesh to represent a 2D function

- Cover domain with triangles.
- Triangles have vertices (points).
- Triangles have edges (line segments).
- Use linear interpolation to find value of function inside triangle



Representing a mesh in Matlab

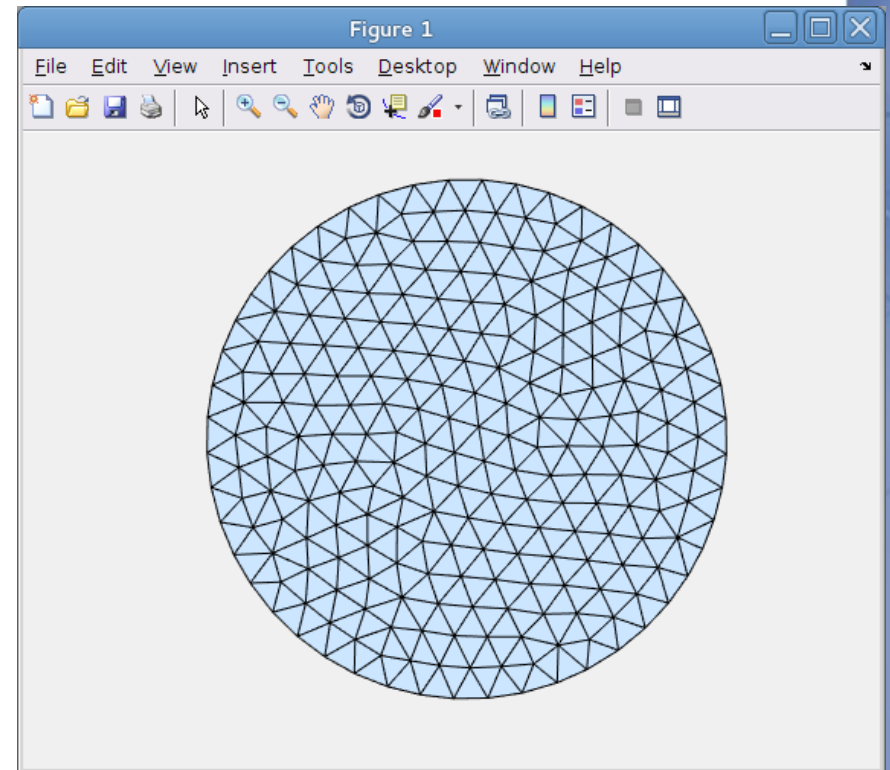


Nodes are black
Triangles (elements) are blue

Note all nodes listed
in CCW order.

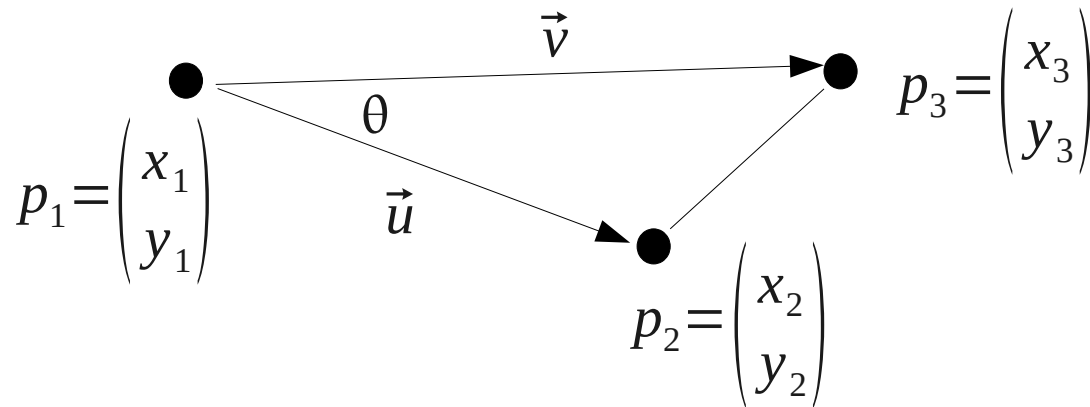
Example: Find area of circle in 2D

- Inputs:
 - Meshed circle (P and T matrices)
- Desired output:
 - Sum of areas of all triangles
- Question:
 - How to compute area of each triangle?



Area of triangle

- Triangle is defined by three vertex points.



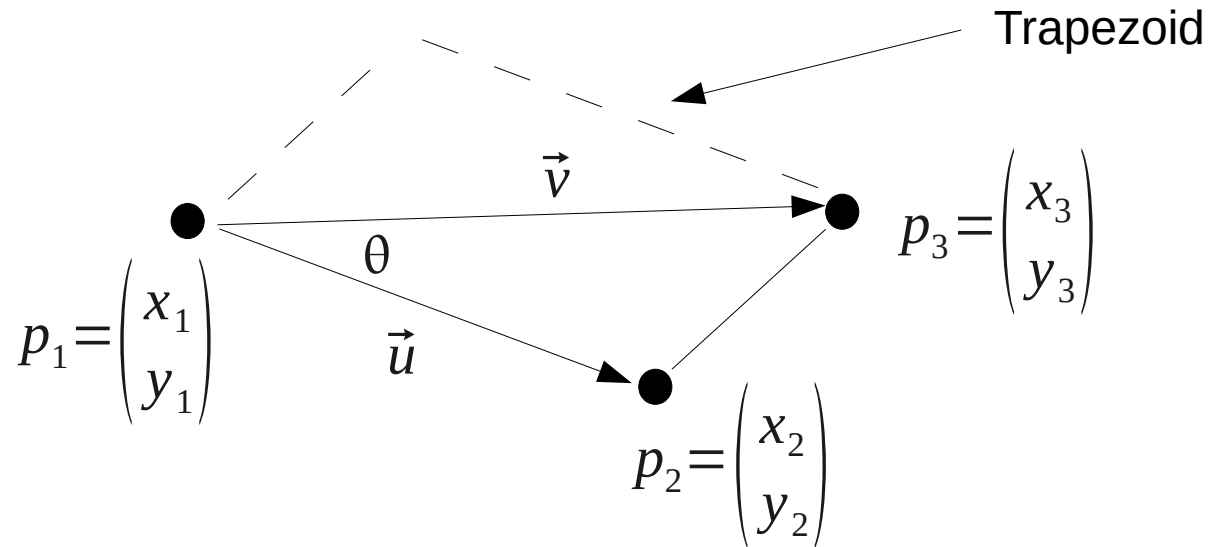
- Consider vectors u , v , defined by

$$\vec{u} = \vec{p}_2 - \vec{p}_1 \quad \vec{v} = \vec{p}_3 - \vec{p}_1$$

- Recall formula for vector cross product:

$$\vec{u} \times \vec{v} = |\vec{u}| |\vec{v}| \sin(\theta) \hat{z}$$

Triangle area



- Area of trapezoid

$$A_{trap} = \vec{u} \times \vec{v} = |u||v|\sin(\theta)$$

- Area of triangle:

$$A_{Tri} = \frac{1}{2} |u||v|\sin(\theta)$$

Cross product

- Recall another definition:

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ u_x & u_y & u_z \\ v_x & v_y & v_z \end{vmatrix} \quad \leftarrow \text{Evaluate this like a determinant}$$

- From last slide we have

$$\vec{u} = \begin{pmatrix} x_2 - x_1 \\ y_2 - y_1 \end{pmatrix} \quad \vec{v} = \begin{pmatrix} x_3 - x_1 \\ y_3 - y_1 \end{pmatrix}$$

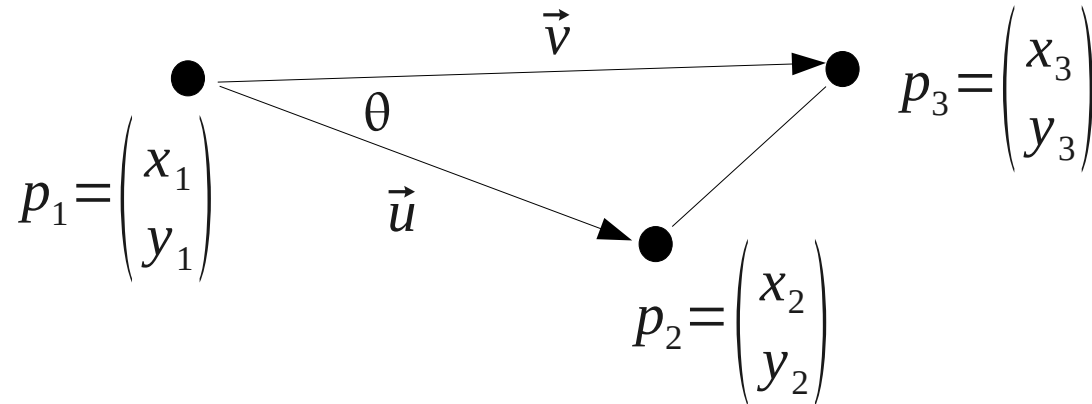
- Insert into det:

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ x_2 - x_1 & y_2 - y_1 & 0 \\ x_3 - x_1 & y_3 - y_1 & 0 \end{vmatrix}$$

- We care about \hat{z} component:

$$= (x_2 - x_1)(y_3 - y_1) - (y_2 - y_1)(x_3 - x_1)$$

Area of triangle



$$A_{Tri} = \frac{1}{2} \left((x_2 - x_1)(y_3 - y_1) - (y_2 - y_1)(x_3 - x_1) \right)$$

$$= \frac{1}{2} \begin{vmatrix} (x_2 - x_1) & (x_3 - x_1) \\ (y_2 - y_1) & (y_3 - y_1) \end{vmatrix} \quad \text{"Surveyor's area formula"}$$

Area-finding algorithm

1. Initialize $A_{tot} = 0$.
2. Loop over all triangles.
3. For each triangle t , use surveyer's area formula to compute area A_{tri}
4. $A_{tot} = A_{tot} + A_{tri}$
5. Continue looping -- go back to 2
6. At end of looping, return A_{tot} .


```

% Perform integration by summing over triangles
s = 0;
for idx = 1:size(T, 1)
    p1 = P(T(idx, 1), :)' ;
    p2 = P(T(idx, 2), :)' ;
    p3 = P(T(idx, 3), :)' ;
    s = s + tri_area_surveyers(p1, p2, p3);
end

```

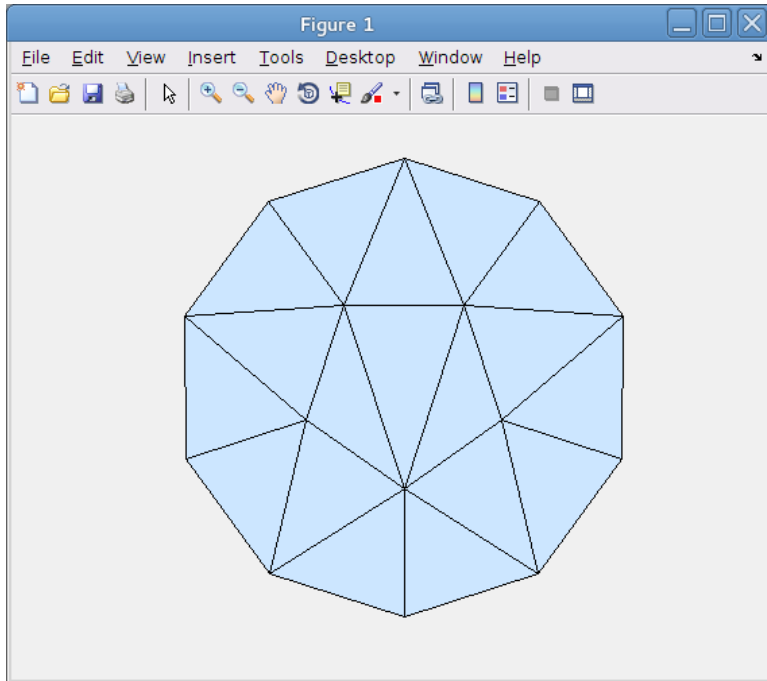
```

function A = tri_area_surveyers(p1, p2, p3)
% Inputs:
% p1, p2, p3 = vertices of triangle as 2D vectors [x, y]'
%
% Outputs:
% A = computed area of triangle [p1, p2, p3]
%
% Area is computed using the Surveyor's triangle
% area formula  $A = (1/2) * \det([u \ v; v \ w])$  where
%  $u = p2 - p1$ , and  $v = p3 - p1$ .

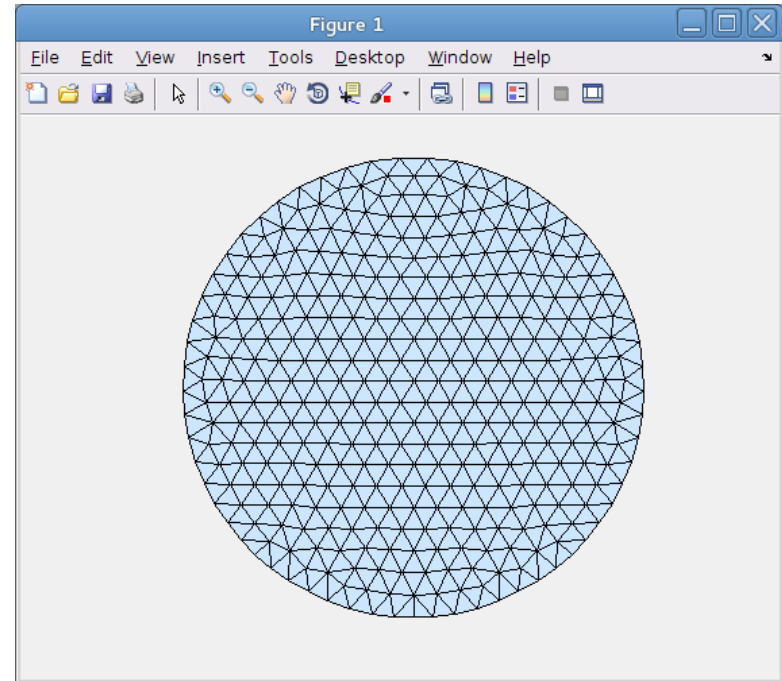
u = p2 - p1;
v = p3 - p1;
S = [u(1) v(1); u(2) v(2)];
A = abs(det(S))/2;
end

```

Area of unit circle

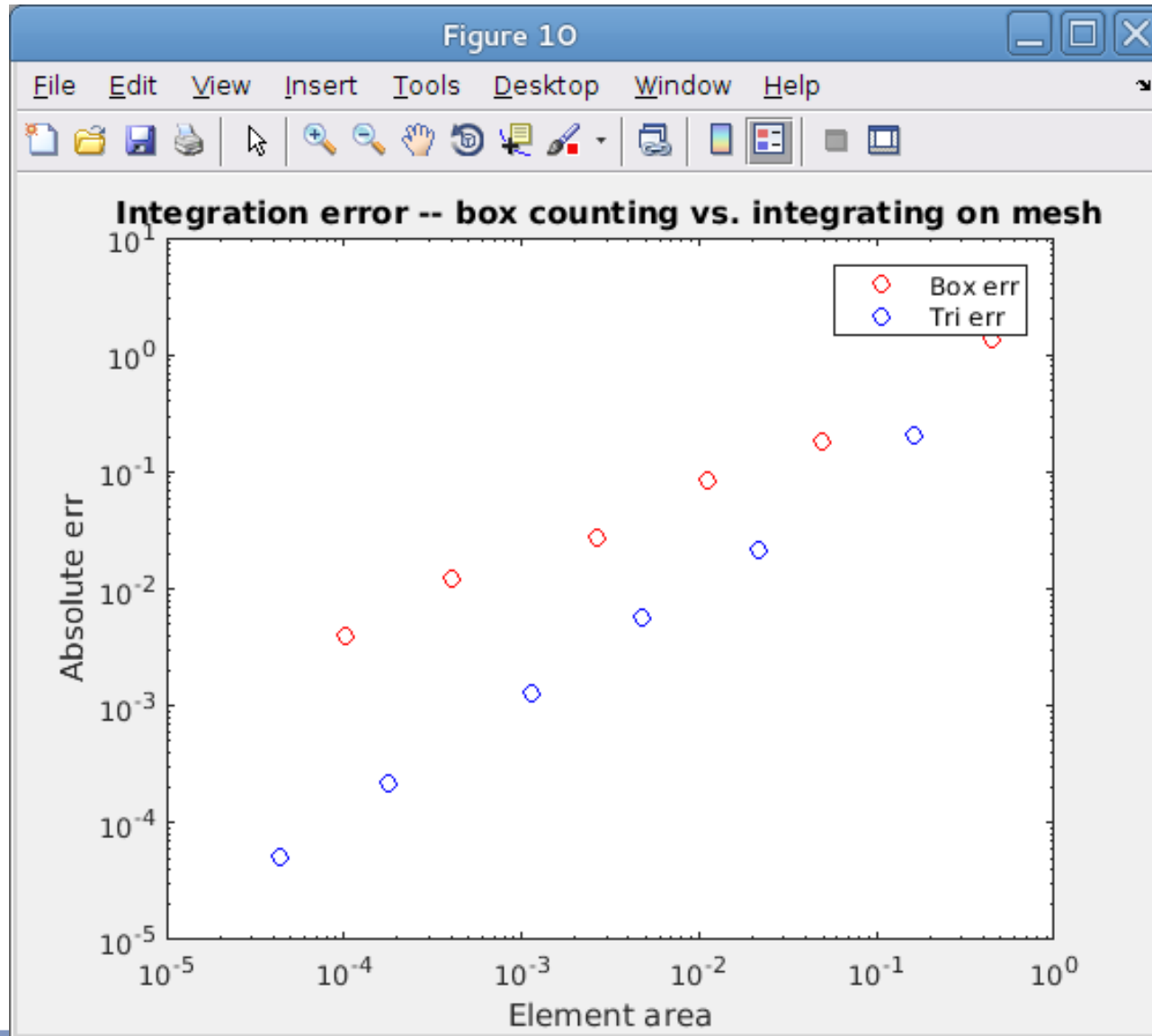


tri size param = 0.500000,
Atrue = 3.141593,
Asurveyors = 2.938924,
abs error = 2.026682e-01



tri size param = 0.100000,
Atrue = 3.141593,
Asurveyors = 3.135911,
abs error = 5.681554e-03

Compare box counting to integration on triangular mesh

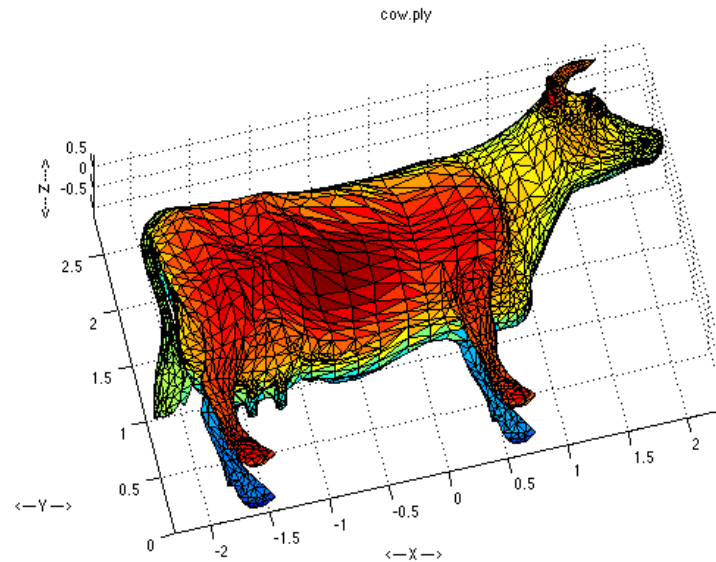


$$err(box) \sim \sqrt{A}$$

$$err(tri) \sim A$$

More complicated shapes?

- Usually, the mesh is given to you.
- Use a program to create a suitable mesh for your problem.
- Many file formats:
 - STL
 - PLY
 - Etc...
- If mesh is regular enough, you can make it yourself.



Next: integrating the volume under a surface

- Find surface area of a domain

$$\iint_{(x,y) \in A} dx dy 1$$

← We just did this

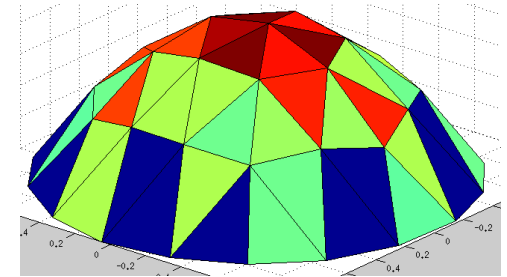
- Integrate function over a domain

$$\iint_{(x,y) \in A} dx dy f(x, y)$$

← What about doing this?

Integrate a function over a meshed domain

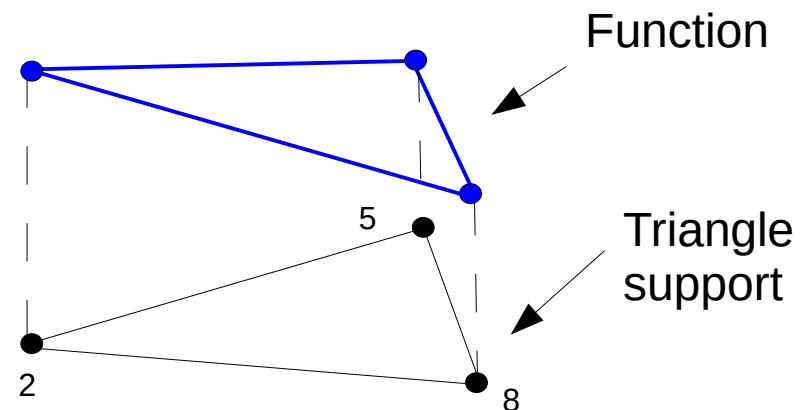
- Global integral is found as sum of integrals over triangles



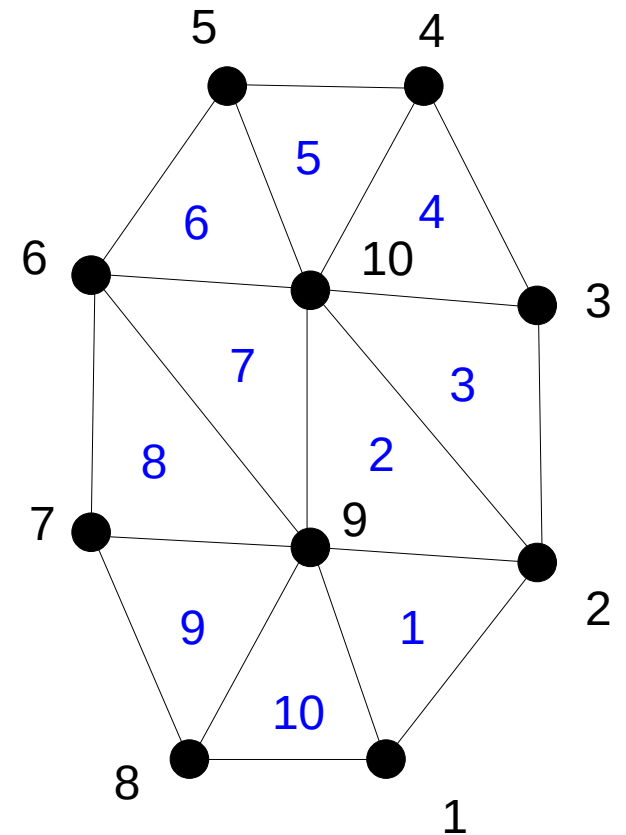
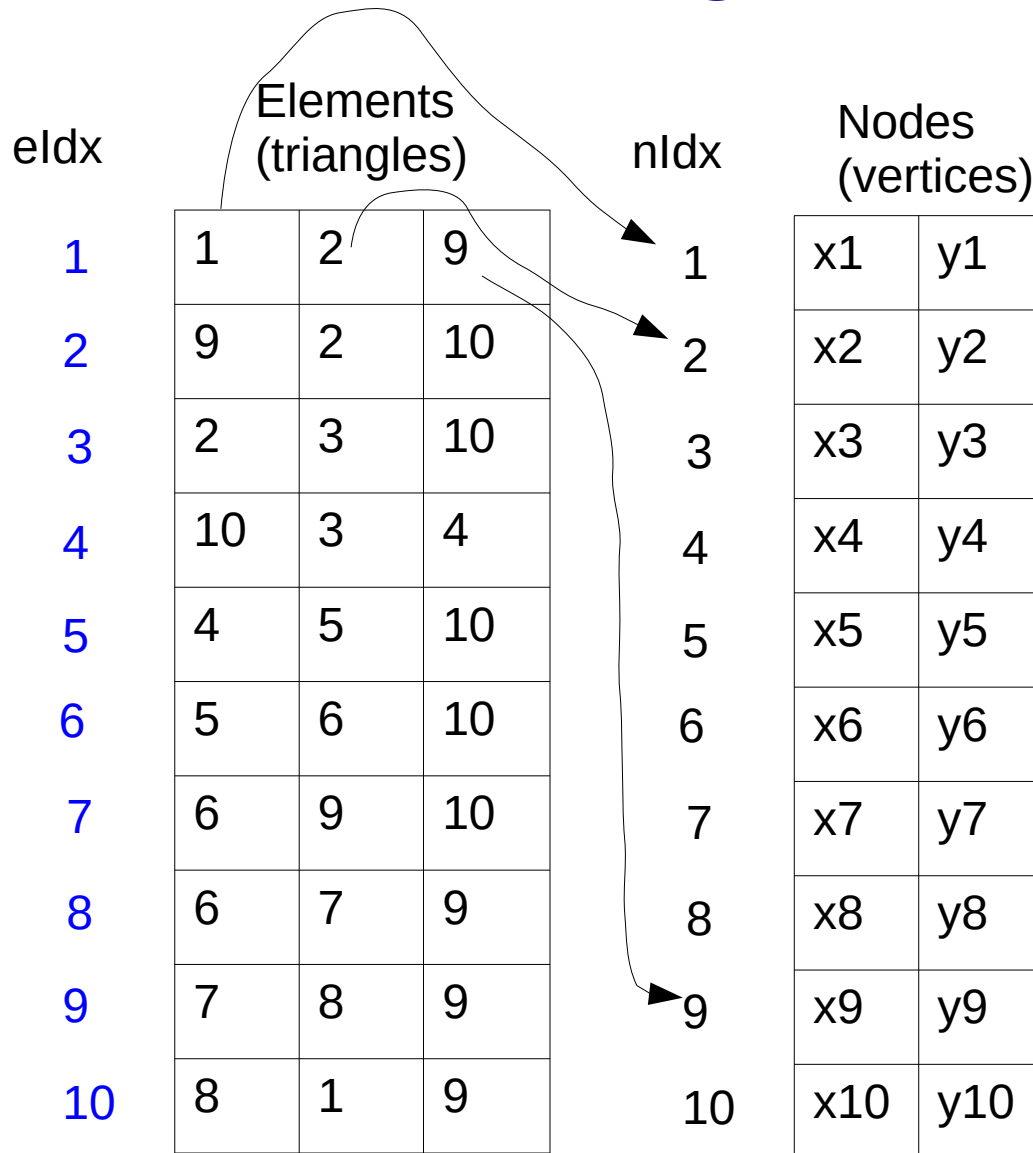
$$\iint_{(x,y) \in A} dx dy f(x,y) = \sum_i \iint_{(x,y) \in A_i} dx dy f(x,y)$$

- Question: How to compute integral over each triangle?

$$\iint_{(x,y) \in A_i} dx dy f(x,y)$$



Representing a mesh in Matlab



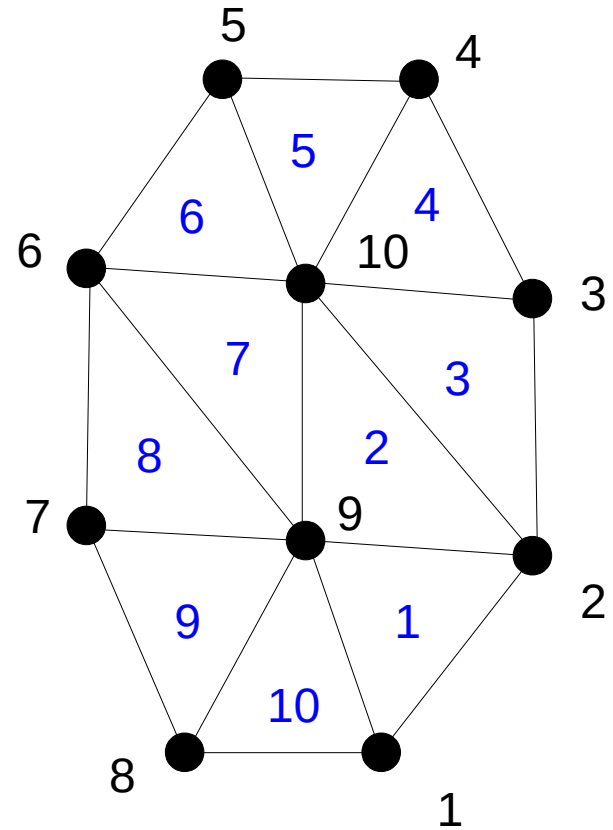
Nodes are black
Triangles (elements) are blue

Note all nodes listed
in CCW order.

New: Function vector

nldx $f(x, y)$

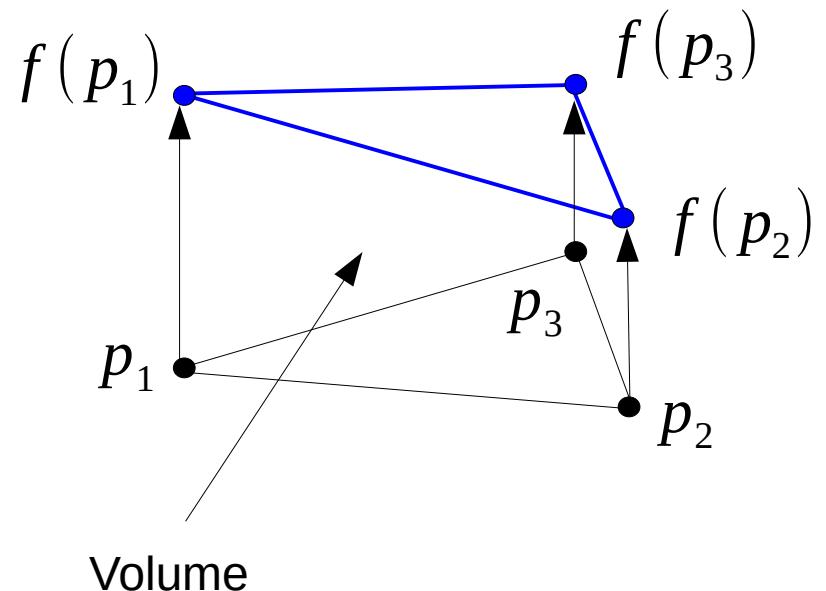
1	U1
2	U2
3	U3
4	U4
5	U5
6	U6
7	U7
8	U8
9	U8
10	U10



Function vector $f(x, y)$ is defined on the mesh nodes (vertices).

Inputs and outputs

- Inputs at each triangle:
 - Locations of vertices p_1 , p_2 , p_3 .
 - Function value at vertices, $f(p_1)$, $f(p_2)$, $f(p_3)$.
- Assumption:
 - Blue triangle is planar.
- Desired output:
 - Volume underneath top triangle

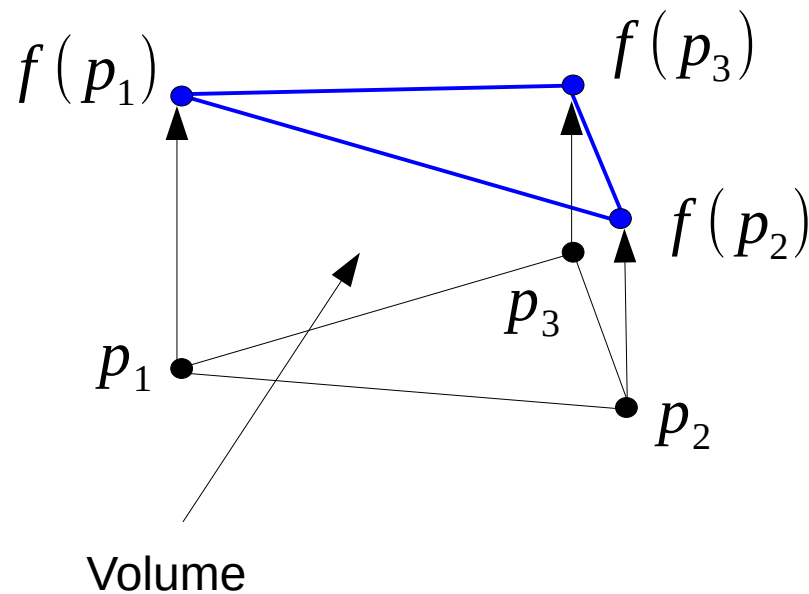


Big problem

- If vertices are at arbitrary positions in plane, how to set limits of integration?

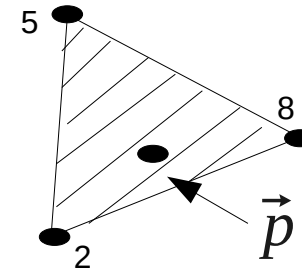
$$V = \int_{x_0}^{x_1} \int_{y_0}^{y_1} f(x, y) dy dx$$

- It's not obvious ...

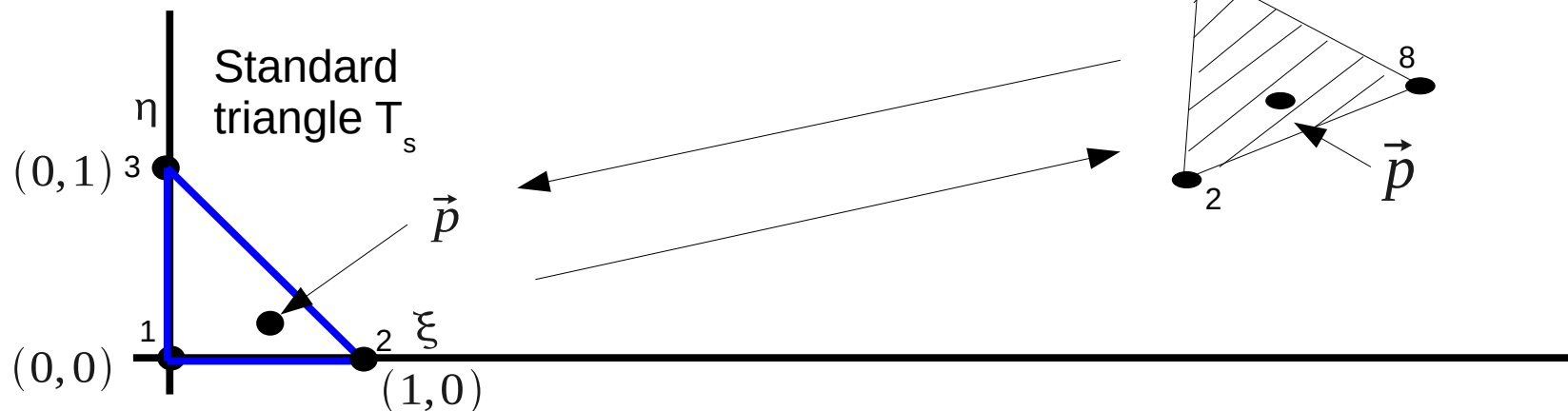


Concept: standard triangle

- How to perform integral of function over some arbitrary triangular patch?



- Map triangle back to “standard triangle”, do integration, then map back result.



Mapping between triangles

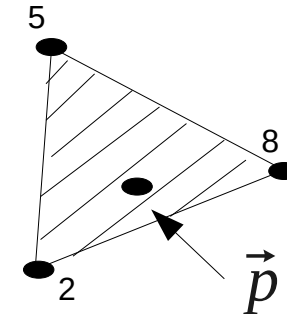
- Note any point in T may be written using barycentric coordinates:

$$\vec{p} = (1 - \xi - \eta) \vec{p}_2 + \xi \vec{p}_8 + \eta \vec{p}_5$$

$$\text{With } \eta \in [0, 1] \quad \xi \in [0, 1 - \eta]$$

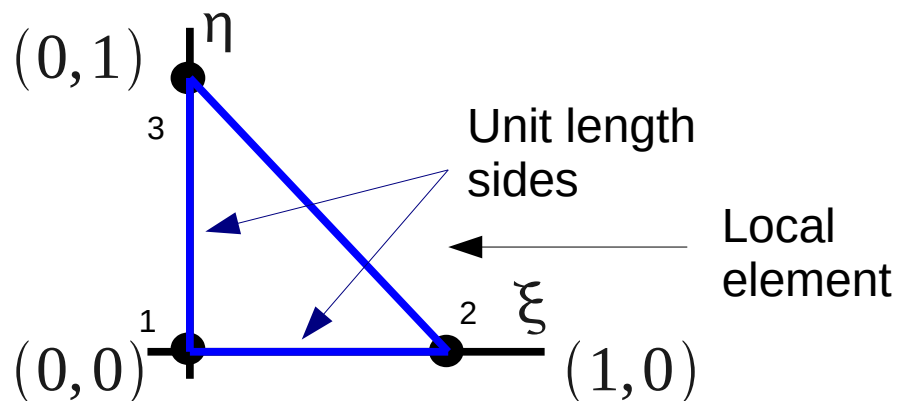
Eta

Xi



Point in global mesh

- This induces a mapping to the “standard” triangle T_s :



Local vertex \Leftrightarrow Global vertex

$1 \Leftrightarrow 2$

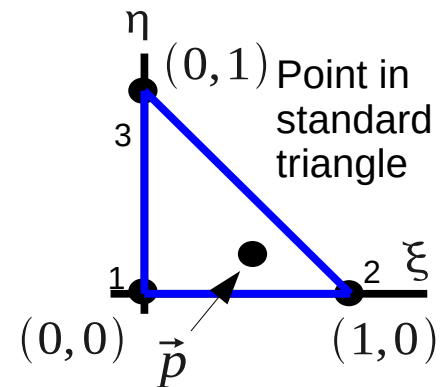
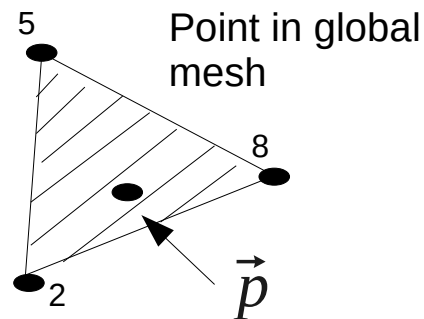
$2 \Leftrightarrow 8$

$3 \Leftrightarrow 5$

Mapping between triangles

- Jacobian matrix associated with coordinate change encodes scale change

$$\begin{aligned}\vec{p} &= (1 - \xi - \eta) \vec{p}_2 + \xi \vec{p}_8 + \eta \vec{p}_5 \\ &= \vec{p}_1 + \xi(\vec{p}_2 - \vec{p}_1) + \eta(\vec{p}_3 - \vec{p}_1)\end{aligned}$$



$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} p_{1x} \\ p_{1y} \end{pmatrix} + \xi \begin{pmatrix} p_{2x} - p_{1x} \\ p_{2y} - p_{1y} \end{pmatrix} + \eta \begin{pmatrix} p_{3x} - p_{1x} \\ p_{3y} - p_{1y} \end{pmatrix}$$

- Jacobian

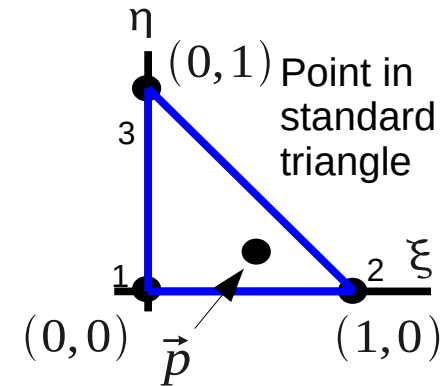
$$J = \left| \frac{\partial(x, y)}{\partial(\xi, \eta)} \right| = \det \begin{vmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial x}{\partial \eta} \\ \frac{\partial y}{\partial \xi} & \frac{\partial y}{\partial \eta} \end{vmatrix}$$

Handles scale change due to coordinate change

Evaluate integral

- Compute integral on standard triangle:

$$\iint_{(x,y) \in A_i} dx dy f(x,y) = \int_0^1 d\eta \int_0^{(1-\eta)} d\xi \left| \frac{\partial(x,y)}{\partial(\xi,\eta)} \right| f(\eta,\xi)$$



- Determinant is a constant scale factor:

$$J = (p_{2x} - p_{1x})(p_{3y} - p_{1y}) - (p_{3x} - p_{1x})(p_{2y} - p_{1y})$$

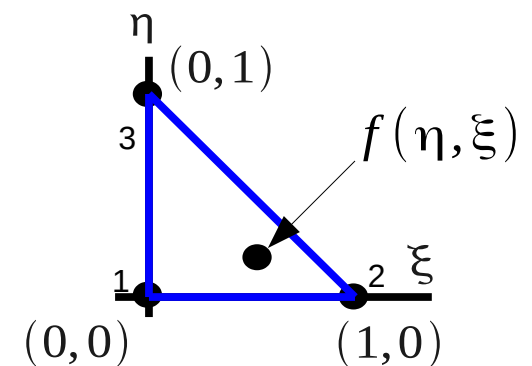
- Look familiar? This is 2x area of original triangle. That is,

$$J = \left| \frac{\partial(x,y)}{\partial(\xi,\eta)} \right| = 2 A_T$$

Computing area under triangle

- From knowing the Jacobian, we have

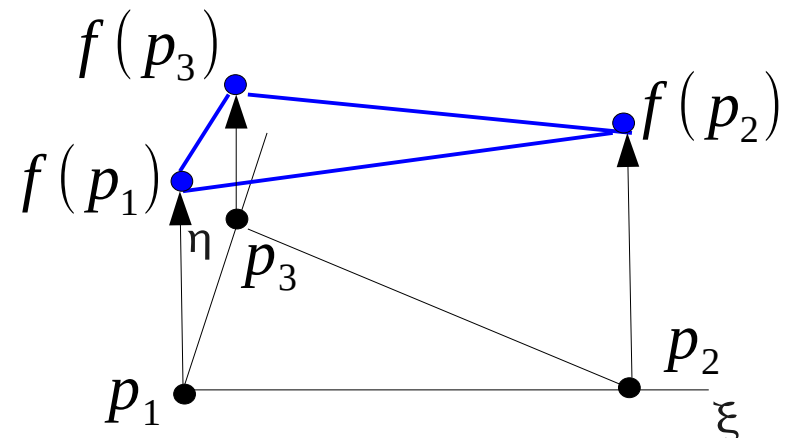
$$\begin{aligned}
 \iint_{(x,y) \in A_i} dx dy f(x,y) &= \int_0^1 d\eta \int_0^{(1-\eta)} d\xi \left| \frac{\partial(x,y)}{\partial(\xi,\eta)} \right| f(\eta,\xi) \\
 &= 2 A_i \int_0^1 d\eta \int_0^{(1-\eta)} d\xi f(\eta,\xi)
 \end{aligned}$$



- What is $f(\eta,\xi)$? Since function is a plane,

$$f(\eta,\xi) = a\xi + b\eta + c$$

Recall interpolation on a triangle from class 9



- Function is a plane

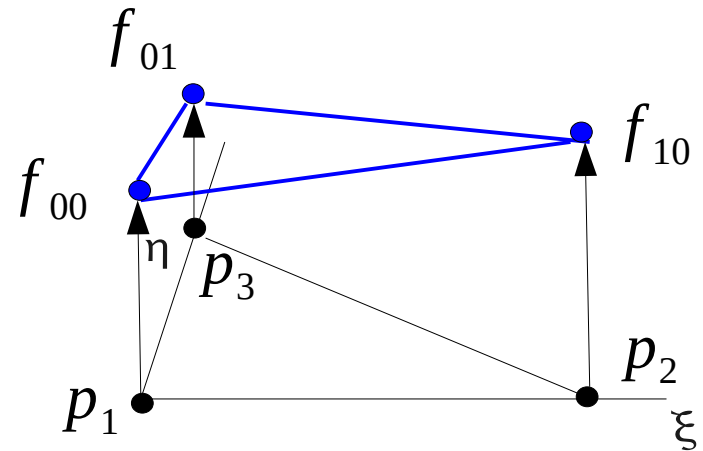
$$f(\eta, \xi) = a\xi + b\eta + c$$

- We know the function values at the vertices:

$$f_{00} = a \cdot 0 + b \cdot 0 + c$$

$$f_{10} = a \cdot 1 + b \cdot 0 + c$$

$$f_{01} = a \cdot 0 + b \cdot 1 + c$$



- Written in matrix form:

$$\begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} f_{00} \\ f_{10} \\ f_{01} \end{pmatrix}$$

Since we know the matrix, and we know f , we can get $[a, b, c]$ using a matrix solve operation.

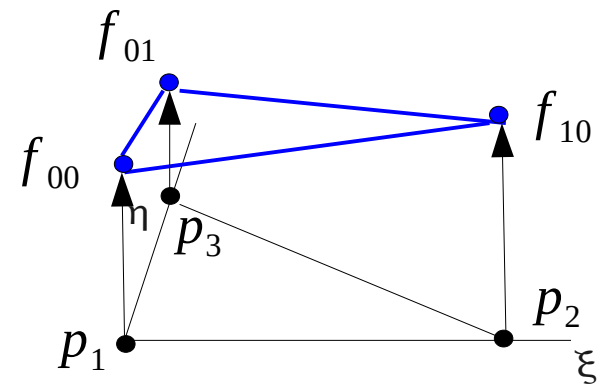
Next, perform integration on standard triangle

$$\iint_{(x,y) \in A_i} dx dy f(x,y)$$

$$= 2 A_i \int_0^1 d\eta \int_0^{(1-\eta)} d\xi (a\xi + b\eta + c)$$

$$= 2 A_i \int_0^1 d\eta \left(\frac{a}{2} \xi^2 + b\eta\xi + c\xi \right) \Big|_0^{1-\eta}$$

$$= 2 A_i \int_0^1 d\eta \left(\frac{a}{2} (1-\eta)^2 + b\eta(1-\eta) + c(1-\eta) \right)$$



Split into three pieces

$$2 A_i \int_0^1 d\eta \left(\frac{a}{2} (1-\eta)^2 + b\eta(1-\eta) + c(1-\eta) \right)$$

$$2 A_i \int_0^1 d\eta \left(\frac{a}{2} (1-\eta)^2 \right)$$

Substitute:

$$s = 1 - \eta \quad ds = -d\eta$$

Integral becomes:

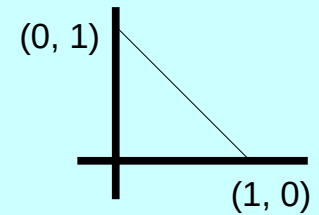
$$\begin{aligned} & -2 A_i \int_1^0 ds \left(\frac{a}{2} s^2 \right) \\ & = 2 A_i \left(\frac{a}{6} \right) \end{aligned}$$

$$2 A_i \int_0^1 d\eta (b\eta(1-\eta))$$

$$= 2 A_i \left(\frac{1}{2} \eta^2 - \frac{1}{3} \eta^3 \right) \Big|_0^1$$

$$= 2 A_i b \left(\frac{1}{2} \eta^2 - \frac{1}{3} \eta^3 \right) \Big|_0^1$$

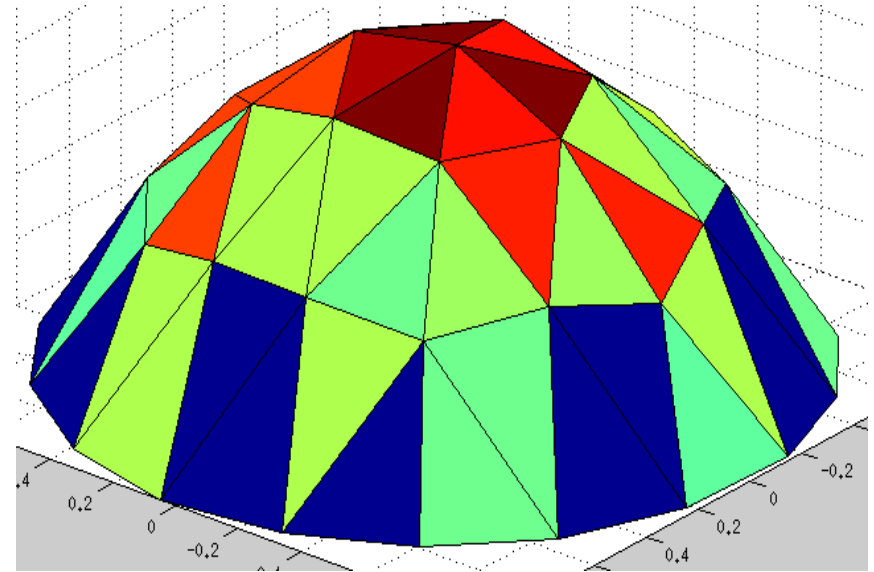
$$= 2 A_i \left(\frac{b}{6} \right)$$



$$= 2 A_i \left(\frac{c}{2} \right)$$

Integrating over meshed domain: Putting it all together...

1. Loop over all triangles.
2. For each triangle, send $p_1, p_2, p_3, f_1, f_2, f_3$ to sub-fcn.
3. Compute Jacobian



$$J = 2A_T = (p_{2x} - p_{1x})(p_{3y} - p_{1y}) - (p_{3x} - p_{1x})(p_{2y} - p_{1y})$$

4. Compute [a, b, c] using linear solve for a, b, c coeffs:

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \setminus \begin{pmatrix} f_{00} \\ f_{10} \\ f_{01} \end{pmatrix}$$

$$f(\eta, \xi) = a\xi + b\eta + c$$

Recall interpolation on a triangle from class 9

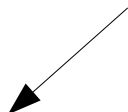
5. Compute integral on standard triangle:

$$\text{Integral} = \left(\frac{a}{6}\right) + \left(\frac{b}{6}\right) + \left(\frac{c}{2}\right)$$

6. Multiply by Jacobian, then return.

$$\iint_{(x,y) \in A_i} dx dy f(x,y) = J \left[\left(\frac{a}{6}\right) + \left(\frac{b}{6}\right) + \left(\frac{c}{2}\right) \right]$$

Result is
integral over
one triangle
in mesh.



7. Add returned integral over single triangle to global sum.

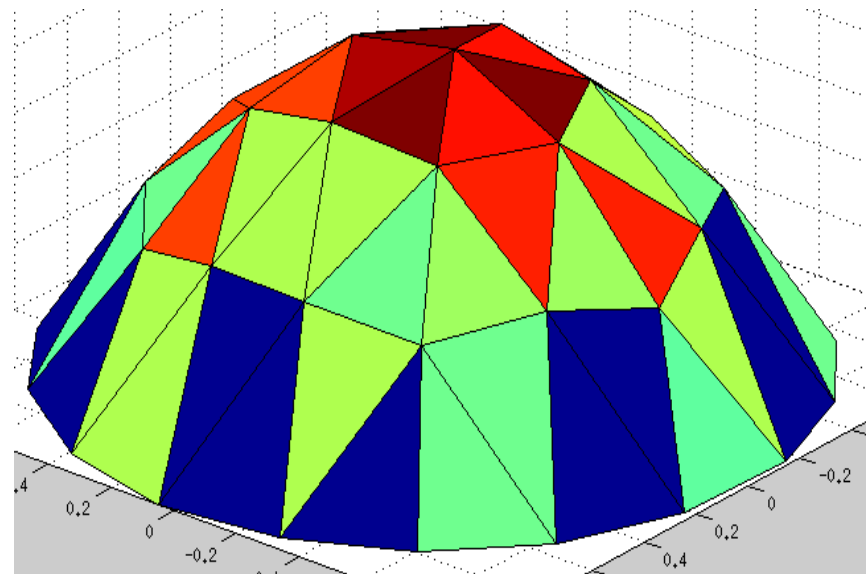
$$\iint_{(x,y) \in A} dx dy f(x,y) = \sum_i \iint_{(x,y) \in A_i} dx dy f(x,y)$$

8. When done looping, the global sum is the integral of the function over the triangulated domain.

Summary: Integrating meshed function over irregular domain

$$\iint_{(x,y) \in A} dx dy f(x,y) = \sum_i \iint_{(x,y) \in A_i} dx dy f(x,y)$$

- Multi-step process
- Sum volumes of triangular domains.
- Replace function over patch with interpolant.



Comments

- The classical methods involving sampling at a few points (Gauss quadrature) reflect their time period.
 - Hand computation was very expensive.
- The computer allows us to use meshing/triangulation as a better way to integrate over irregular domains.



Session summary

- Integration in 2 dimensions
 - Box counting.
 - 2D Gaussian quadrature.
- Integrating shapes over odd boundaries
 - Box counting.
 - Meshing using triangles.
 - Integrating over a triangle mesh.