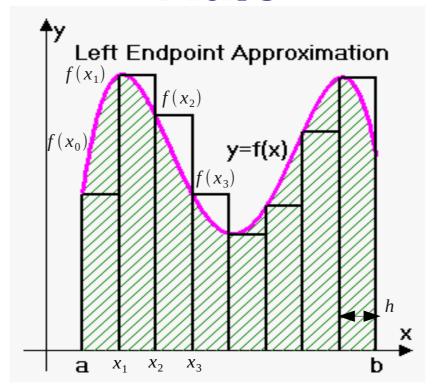
Numerical Integration

$$\int_{a}^{b} dx f(x) = \int_{a}^{b} f(x) dx$$

$$\int_{a}^{b} dx \int_{c}^{d} dy f(x,y)$$

Integrate f(x) from a to b: Elementary method: Endpoint Rule



$$\int_{a}^{b} dx f(x) = h \sum_{n=0}^{N-1} f(x_n) \qquad h = \frac{b-a}{N} \qquad x_n = a + nh$$

Endpoint rule implementation

```
function y = endpoint(f, a, b, n)
% This function implements the simple endpoint rule. Integration
% is performed over n sub-intervals on the interval a <= x < b

h = (b-a)/n; % Step size
x = a:h:(b-h); % Sample x values -- must drop point at end
s = f(x); % f(x) values
y = h*sum(s); % Perform integration
end</pre>
```

Test Endpoint Rule for Different N

- How accurate is method (error)?
- How does error scale with N?

end

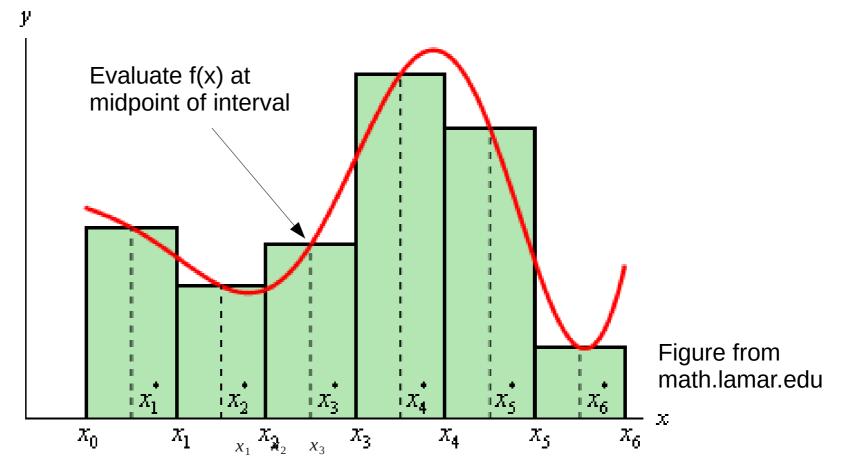
```
function test endpoint()
  % This tests the endpoint integrator by integrating
  % x^2 from 0 -> 3 for different numbers of intervals.
  % The analytic result is (1/3)x^3, which should be 9.000.
  f = Q(x) x.*x % Anonymous function
                                               f(x)=x^2
 a = 0;
  b = 3;
  true = b*b*b/3:
                                             \int_{0}^{3} x^{2} dx = \frac{1}{3} (b^{3} - a^{3})
 N = 1:
  for idx = 1:20
   N = N*2;
    act = endpoint(f, a, b, N);
    err = abs(true - act);
    printf('N = %d, true = %12.8f, act = %12.8f, err = %12.8f\n',
               N, true, act, err);
  end
```

Test results

```
octave:5> test endpoint
N = 2, true = 9.00000000, act = 3.37500000, err =
                                                    5.62500000
                                 5.90625000, err =
N = 4, true = 9.00000000, act =
                                                    3.09375000
N = 8, true =
             9.00000000, act = 7.38281250, err =
                                                   1.61718750
N = 16, true = 9.00000000, act = 8.17382812, err = 0.82617188
N = 32, true = 9.00000000, act = 8.58251953, err = 0.41748047
N = 64, true = 9.00000000, act =
                                 8.79016113, err =
                                                     0.20983887
N = 128, true = 9.00000000, act = 8.89480591, err = 0.10519409
N = 256, true = 9.00000000, act = 8.94733429, err = 0.05266571
N = 512, true =
               9.00000000, act = 8.97364998, err = 0.02635002
N = 1024, true = 9.00000000, act = 8.98682070, err = 0.01317930
               9.00000000, act = 8.99340928, err = 0.00659072
N = 2048, true =
 = 4096, true = 9.00000000, act =
                                   8.99670437. err = 0.00329563
N = 8192, true = 9.00000000, act =
                                   8.99835212, err = 0.00164788
N = 16384, true = 9.00000000, act = 8.99917604, err =
                                                       0.00082396
N = 32768. true =
                 9.00000000, act = 8.99958802, err =
                                                       0.00041198
                 9.00000000, act = 8.99979401, err =
N = 65536, true =
                                                       0.00020599
N = 131072, true = 9.00000000, act = 8.99989700, err = 0.00010300
N = 262144, true = 9.00000000, act = 8.99994850, err = 0.00005150
N = 524288, true = 9.00000000, act = 8.99997425, err = 0.00002575
N = 1048576, true = 9.00000000, act = 8.99998713, err = 0.00001287
```

- Error decreases as 1/N
- Error decreases as h

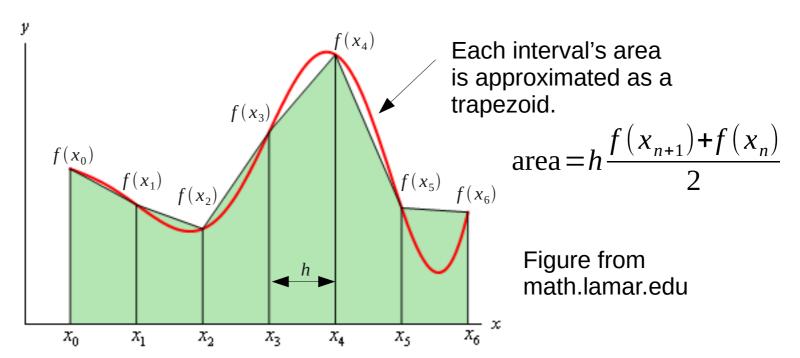
Similar method: Midpoint rule



$$\int_{a}^{b} dx f(x) = h \sum_{n=0}^{N-1} f(x_{n}^{*}) \qquad h = \frac{b-a}{N} \qquad x_{n}^{*} = a + nh + \frac{h}{2}$$

Error properties similar to endpoint rule.

Elementary method: Trapezoidal Rule



Sum up all trapezoids to get total area

$$\int_{a}^{b} dx f(x) = \frac{h}{2} \sum_{n=0}^{N-1} \left(f(x_{n+1}) + f(x_n) \right) \qquad h = \frac{b-a}{N} \qquad x_n = a + nh$$

$$= \frac{h}{2} \left(f(x_1) + 2f(x_2) + 2f(x_3) + \dots + f(x_N) \right)$$

Trapezoidal rule implementation

```
function y = trapezoid(f, a, b, n)
% This function implements the trapezoidal rule. Integration
% is performed over n points on the interval a <= x < b

h = (b-a)/n; % Step size
x = a:h:b; % Sample x values
s = f(x);
y = h*( s(1) + 2*sum( s(2:(end-1)) ) + s(end) )/2;
end</pre>
```

 Test using same test wrapper as for endpoint rule.

Test results

```
octave:7> test trapezoid
N = 2, true = 9.00000000, act = 10.12500000, err =
                                                   1.12500000
N = 4, true = 9.00000000,
                                                   0.28125000
                         act = 9.28125000, err =
             9.00000000, act = 9.07031250, err =
N = 8, true =
                                                    0.07031250
N = 16, true = 9.00000000, act = 9.01757812, err = 0.01757812
N = 32, true = 9.00000000, act = 9.00439453, err = 0.00439453
N = 64, true = 9.00000000, act = 9.00109863, err =
                                                     0.00109863
N = 128, true = 9.00000000, act = 9.00027466, err = 0.00027466
N = 256, true = 9.00000000, act = 9.00006866, err = 0.00006866
N = 512, true =
               9.000000000, act =
                                   9.00001717, err =
                                                     0.00001717
N = 1024, true =
               9.00000000, act = 9.00000429, err = 0.00000429
N = 2048, true = 9.00000000, act = 9.00000107, err = 0.00000107
N = 4096, true = 9.00000000, act = 9.00000027, err = 0.00000027
                                   9.00000007, err =
N = 8192, true = 9.00000000, act =
                                                      0.00000007
N = 16384, true = 9.00000000, act = 9.00000002, err = 0.00000002
N = 32768, true =
                 9.00000000, act = 9.00000000, err =
                                                       0.00000000
N = 65536, true =
                 9.00000000, act =
                                    9.00000000, err =
                                                       0.00000000
N = 131072, true =
                 9.00000000, act = 9.00000000, err = 0.00000000
N = 262144, true = 9.00000000, act = 9.00000000, err = 0.00000000
N = 524288, true = 9.00000000, act =
                                     9.00000000, err = 0.00000000
N = 1048576, true =
                 9.00000000, act =
                                     9.00000000. err =
                                                         0.00000000
```

- Error decreases as 1/N²
- MATLAB: trapz

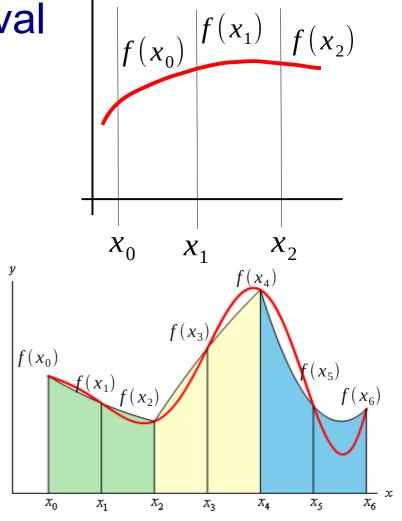
Simpson's rule

Consider only one subinterval

$$\int_{x_0}^{x_2} dx f(x) = \frac{h}{3} [f(x_0) + 4f(x_1) + f(x_2)]$$

Over many subintervals

$$\int_{x_0}^{x_2} dx f(x) = \frac{h}{3} [f(x_0) + 4f(x_1) + f(x_2)] + \frac{h}{3} [f(x_2) + 4f(x_3) + f(x_4)] + \frac{h}{3} [f(x_4) + 4f(x_5) + f(x_6)] + \cdots$$



$$= \frac{h}{3} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + 2f(x_4) + \dots + 4f(x_{n-1}) + f(x_n)]$$

Simpson's composite rule

$$\int_{x_0}^{x_2} dx f(x) = \int_{x_0}^{f(x_0)} dx f(x) = \int_{x_0}^{f(x_0)} f(x_0) + 4f(x_1) + f(x_2) \int_{x_0}^{h} dx f(x) = \int_{x_0}^{h} f(x_0) + 2 \sum_{j} f(x_{2j}) + 4 \sum_{j} f(x_{2j-1}) + f(x_n) = \frac{h}{3} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + 2f(x_4) + \dots + 4f(x_{n-1}) + f(x_n)] + \frac{b-a}{N-1}$$

$$h = \frac{b-a}{N-1} \qquad x_n = a + nh$$

Note: choose number of points N odd.

Simpson's Rule Implementation

```
function y = simpsons rule(f, a, b, n)
 % This function implements Simpson's rule. Integration
 % is performed over n points on the interval a \leq x < b
 h = (b-a)/n; % Step size
 % Compute sample points.
  x0 = a;
 x2j = (a+2*h):2*h:(b-h);
 x2jm1 = (a+h):2*h:(b-h);
 xn = b;
 % Compute partial sums.
  s0 = f(x0);
  s2j = 2*sum(f(x2j));
  s2jm1 = 4*sum(f(x2jm1));
  sn = f(xn);
 % Compute full sum.
  y = h*(s0 + s2j + s2jm1 + sn)/3;
end
```

Can you guess the convergence rate for x²?

Test results

```
octave:3> test simpsons rule
N = 2, true = 9.00000000,
                                   9.00000000,
                                                        0.0000000
                            act =
                                                err =
N = 4, true = 9.00000000,
                                   9.00000000,
                                                        0.0000000
                           act =
                                                err =
N = 8, true =
               9.000000000, act =
                                   9.00000000,
                                                        0.0000000
                                                err =
N = 16, true =
                9.00000000, act =
                                    9.00000000. err =
                                                         0.00000000
N = 32, true =
                9.00000000, act =
                                    9.00000000, err =
                                                         0.00000000
N = 64, true =
                9.00000000, act =
                                    9.00000000.
                                                         0.00000000
                                                 err =
N = 128, true =
                9.00000000. act =
                                     9.00000000.
                                                         0.00000000
                                                  err =
N = 256, true =
                9.00000000, act =
                                     9.00000000,
                                                          0.00000000
                                                  err =
N = 512, true =
                 9.00000000, act =
                                     9.00000000.
                                                          0.00000000
                                                  err =
N = 1024, true =
                  9.00000000,
                                     9.00000000, err =
                                                           0.0000000
                              act =
N = 2048, true =
                                     9.00000000, err =
                  9.00000000.
                              act =
                                                           0.00000000
N = 4096, true =
                  9.00000000,
                                      9.00000000,
                                                           0.00000000
                              act =
                                                   err =
N = 8192, true =
                  9.00000000,
                                      9.00000000.
                                                           0.0000000
                               act =
                                                   err =
N = 16384. true =
                  9.00000000, act =
                                                           0.0000000
                                       9.00000000.
                                                    err =
N = 32768, true =
                  9.00000000, act =
                                       9.00000000.
                                                           0.0000000
                                                    err =
N = 65536, true =
                   9.00000000, act =
                                       9.00000000,
                                                            0.00000000
                                                    err =
N = 131072, true =
                    9.00000000, act =
                                       9.00000000, err =
                                                             0.0000000
N = 262144, true =
                    9.00000000,
                                act =
                                       9.00000000, err =
                                                            0.00000000
N = 524288, true =
                    9.00000000.
                                act =
                                        9.00000000. err =
                                                             0.00000000
N = 1048576, true =
                    9.00000000, act =
                                         9.00000000, err =
                                                             0.00000000
```

Simpson's Rule is exact for quadratic (and cubic).

In general, these are called "Newton-Cotes" methods

- Series of formulas for integration.
- The formulas fit a series of Lagrange polynomials to the curve (Lagrange interpolation) and then report the integral of all the polynomials.
- They assume uniform step size h.
- Matlab: quad() or integral(). Uses adaptive Simpson's rule.

Newton-Cotes methods

Order Name

Formula

Formula inside one super-interval.

1 Trapezoidal method

$$\frac{h}{2}[f_1+f_2]$$

Error

 $O(h^3f^{(2)}(x))$

$$\frac{h}{3}[f_1+4f_2+f_3]$$

$$O(h^5 f^{(4)}(x))$$

$$\frac{3}{8}h[f_1+3f_2+3f_3+f_4]$$

$$O(h^5 f^{(4)}(x))$$

$$\frac{2}{45}h[7f_1+32f_2+12f_3+32f_4+7f_5]$$

$$O(h^7 f^{(6)}(x))$$

Newton-Cotes

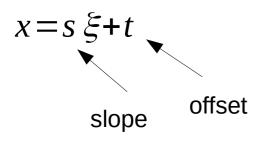
- Based on integrating sections of curve fit by Lagrange interpolation polynomial of order N.
 - Do trapezoidal method on blackboard.
- Order is degree of interpolating polynomial.
 - Recall: N points -> polynomial degree N-1.
- When order N is even, the computed result is exact for polynomials up to degree N+1.
- When order N is odd, the computed result is exact for polynomials up to degree N.

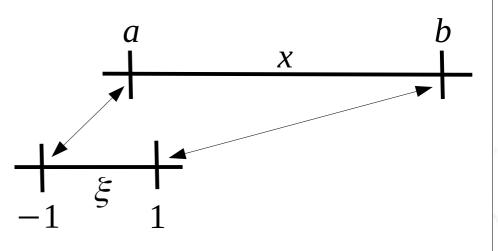
Better method: Gaussian Quadrature

- Consider integration over finite interval [-1, 1].
- Relax restriction to use uniform step size.
- By choosing the sample points you get a higher-degree polynomial fit for the same number of sample points.
 - Remember doing this for interpolation?
- Results exact for polynomials of order 2N-1.

My function lives on [a,b], Gauss quadrature works on [-1,1]

- What to do?
- Use linear map ...





Now insert info about end points and get coeffs.

$$\begin{vmatrix} a = -s + t \\ b = s + t \end{vmatrix} \Rightarrow \begin{vmatrix} t = (b+a)/2 \\ s = (b-a)/2 \end{vmatrix} \Rightarrow$$

$$x = s \, \xi + t$$

$$\xi = \frac{x - t}{s}$$

You can go back and forth

Basic Gaussian Quadrature

Approximate integral using weighted sum:

$$\int_{-1}^{1} dx f(x) \approx \sum_{i=1}^{N} w_{i} f(x_{i})$$

- Sample points: x_i
 - Non-uniform, chosen carefully.
- Summation weights: w_i
- Note you need to shift your integral's limits from [a, b] to [-1, 1].
- But what x_i and w_i to choose?

Consider integrating powers

General Gauss quadrature formula

$$\int_{-1}^{1} dx f(x) \approx a_0 f(x_0) + a_1 f(x_1) + a_2 f(x_2) + a_3 f(x_3) + \cdots$$

$$x_i = \text{Sample point(s)}$$

$$a_i = \text{Weights}$$

Concept:

- Interpolate on N points.
- That gives 2N free variables we can adjust:
 a_i, x_i.
- Find a_i , x_i to make integration exact for all powers up to 2N-1.

Example

• Example: choose n = 2, and see what makes the 2nd order Gauss quadrature formula **exact** for f(x) = 1, x, x^2 , x^3

$$\int_{-1}^{1} dx f(x) \approx a_0 f(x_0) + a_1 f(x_1)$$

- 4 unknowns: a_0 , x_0 , a_1 , x_1
- 4 equations 1 each for 1, x, x^2 , x^3 .

Goal: Find a_i and x_i to make Gauss quadrature formula exact for powers 0, 1, 2, 3

$$\int_{-1}^{1} dx \, 1 = 2 = a_1 + a_2 \tag{1}$$

$$\int_{1}^{1} dx \, x = 0 = a_1 x_1 + a_2 x_2 \tag{2}$$

$$\int_{-1}^{1} dx \, x^2 = \frac{2}{3} = a_1 x_1^2 + a_2 x_2^2 \tag{3}$$

$$\int_{1}^{1} dx \, x^{3} = 0 = a_{1} x_{1}^{3} + a_{2} x_{2}^{3}$$
 (4)

- By symmetry, $a_1 = a_2 = a$.
- From (1), $2a = 2 \Rightarrow a_1 = a_2 = 1$.
- Therefore, from (2), $x_1 = -x_2 = x$

From last slide:

$$\int_{-1}^{1} dx \, x^2 = \frac{2}{3} = a_1 x_1^2 + a_2 x_2^2 \qquad (3)$$

$$a_1 = a_2 = 1$$

$$x_1 = -x_2 = x$$

- Solve for x: $x = \pm \frac{1}{\sqrt{3}}$
- Therefore, the following formula is exact for all polynomials up to (including) degree 3:

$$\int_{-1}^{1} dx f(x) \approx f(-\frac{1}{\sqrt{3}}) + f(\frac{1}{\sqrt{3}})$$

 This is 2nd order Gaussian quadrature. Highly accurate for integrating any function.

Gauss quadrature

Number of sample points

Sample points
$$x_i$$

Weights a_{i}

Exact to degree

1

0

2

1

2

$$-\frac{1}{\sqrt{3}}, +\frac{1}{\sqrt{3}}$$

1

3

3

$$-\sqrt{\frac{3}{5}},0,+\sqrt{\frac{3}{5}}$$

$$\frac{5}{9}, \frac{8}{9}, \frac{5}{9}$$

5

- General rule: N points => exact for polys up to degree 2N-1.
- Recall Newton-Cotes was exact for polys up to degree N.
- But where to get sample pts and weights for arbitrary degree?

Detour: Legendre Polynomials

 Consider expanding a function f(x) on the interval [-1, 1].

$$f(x) = \sum_{n=0}^{\infty} c_n \phi_n(x)$$

 Many ways to do it – Fourier series, Taylor's series, etc. Consider Taylor's series:

$$f(x) = \sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + c_3 x^3 + \cdots$$

 We can consider the powers of x to be a basis set of functions useful for creating a series expansion of f(x)

Taylor's series expansion

 Take basis set for expansion as powers of x:

$$f(x) = \sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + c_3 x^3 + \cdots$$

- Problem with Taylor's series expansion:
 Basis set is not orthogonal.
- What if we applied the Gram-Schmidt procedure to the basis vectors $[1, x, x^2, x^3, x^4, \cdots]$?
- Answer: Legendre polynomials.

Legendre Polynomials

• Legendre polynomials $P_n(x)$: Another set of orthogonal polynomials.

$$\int_{-1}^{1} dx P_n(x) P_m(x) = 0 \quad \text{if} \quad n \neq m$$

 Useful for series expansions of functions on interval [-1, 1]:

$$f(x) = \sum_{n=0}^{\infty} c_n P_n(x)$$
, where $-1 \le x \le 1$

 Legendre polynomials show up in quantum mechanics, electromagnetism, and other places where wave equations are solved in systems with spherical symmetry.

Some Legendre Polynomials

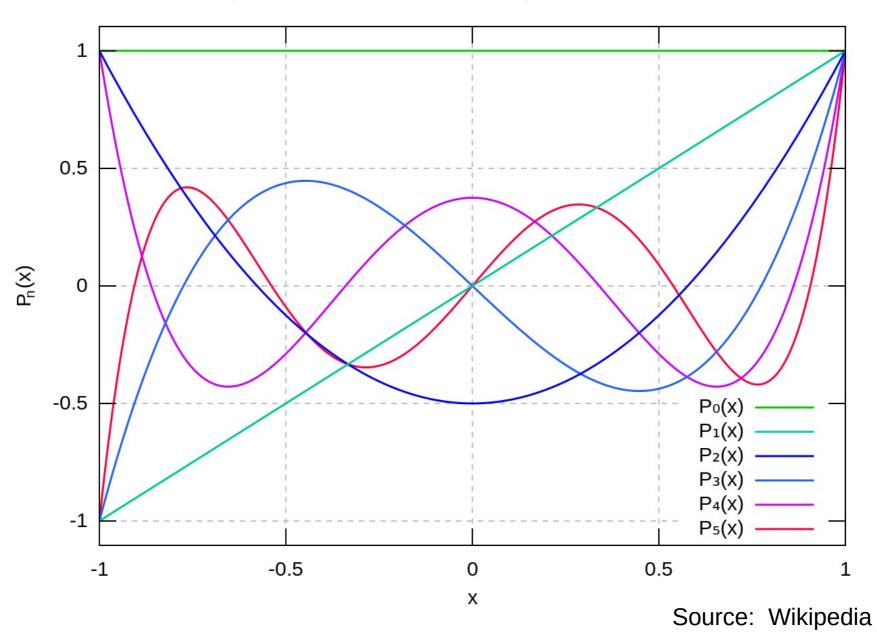
$$n=0 P_0(x)=1$$

$$n=1 P_1(x)=x$$

$$n=2 P_2(x)=\frac{1}{2}(3x^2-1)$$

$$n=3 P_3(x)=\frac{1}{2}(5x^3-3x)$$

Legendre Polynomials



Back to Gaussian Quadrature: Connection to Legendre Polynomials

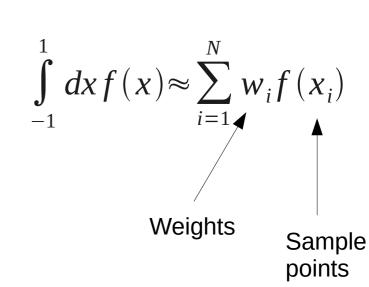
• For *n* point Gaussian quadrature, sample points x_i are roots of Legendre polynomial $P_n(x)$.

n=1
$$P_1(x)=x$$

n=2 $P_2(x)=\frac{1}{2}(3x^2-1)$
n=3 $P_3(x)=\frac{1}{2}(5x^3-3x)$

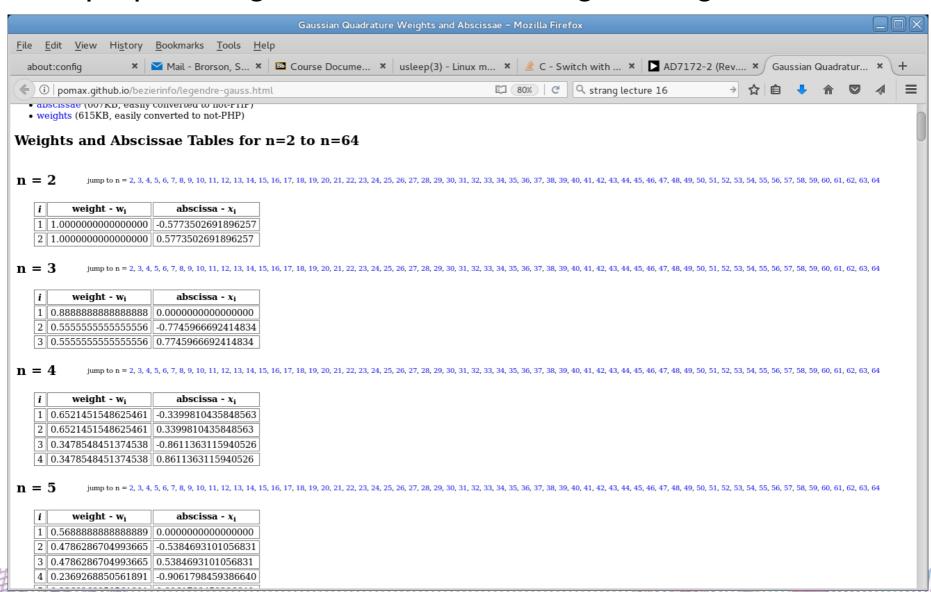
• And weights are given by:

$$w_i = \frac{2}{(1-x_i^2)[P'_n(x_i)]^2}$$



Gaussian quadrature points and weights (numeric)

http://pomax.github.io/bezierinfo/legendre-gauss.html



Gauss-Legendre quadrature demo

```
function ret = gauss quadrature(f, a, b, N)
  % Sample points and weights on [-1, 1] interval
  [xi, omega]=lgwt(N, -1, 1); % lgwt is from Mathworks file share
  % Sample pts on [a, b] interval
 x = ((b-a)/2).*xi + (b+a)/2; % x is a vector.
 % Weights
 w = ((b-a)/2)*omega; % w is a vector.
 % Now sample fcn at Gauss points
 y = f(x); % f(x) must be constructed to return a vector
 % Do sum to compute integral
  ret = dot(w,y);
end
```

Class11/CompareMethods

Gauss-Legendre quadrature demo

Clenshaw-Curtis Quadrature

 Similar to Gauss-Legendre, you must use prescribed sample points and weights.

$$\int_{-1}^{1} dx f(x) \approx \sum_{i=1}^{N} w_{i} f(x_{i})$$

Sample points

$$x_i = -\cos(k\pi/N)$$
 $k = 0, 1, \dots, N$

• Weights
$$w_{i} = \begin{cases} \frac{1}{N^{2}-1} & k=0 \text{ or } k=N \\ \frac{4}{N} \sum_{j=0}^{N/2} \frac{\cos(2\pi j k/N)}{\gamma_{j}(1-4j^{2})} & k=1, \dots N-1 \\ \gamma_{j} = \begin{cases} 2 \text{ for } j=0 \text{ or } j=N/2 \\ 1 \text{ for } j=1,2, \dots N/2-1 \end{cases}$$

$$k=0$$
 or $k=N$

$$k=1,\dots N-1$$

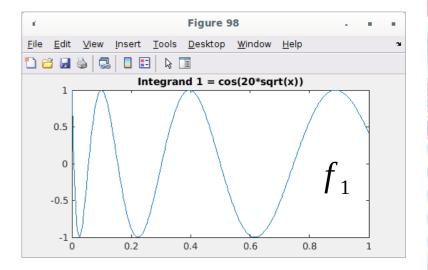
$$\gamma_{j} = \begin{cases} 2 \text{ for } j=0 \text{ or } j=N/2\\ 1 \text{ for } j=1,2,\dots N/2-1 \end{cases}$$

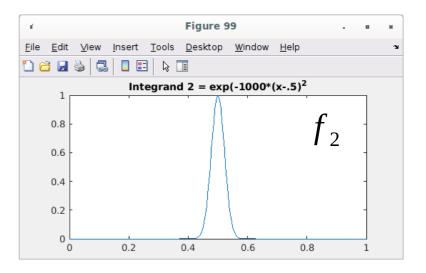
Comparison of methods

- Comparison:
 - Simpson's 1/3 rule
 - Gauss-Legendre
 - Clenshaw-Curtis
- Two difficult test functions:

$$I_{1} = \int_{0}^{1} f_{1}(x) dx \qquad f_{1}(x) = \cos(20\sqrt{x})$$

$$I_{2} = \int_{0}^{1} f_{2}(x) dx \qquad f_{2}(x) = e^{-1000(x-1/2)^{2}}$$

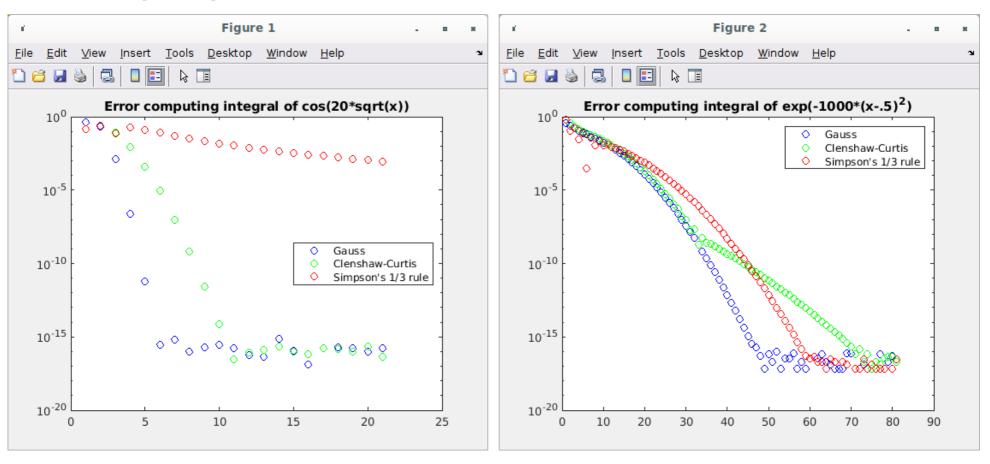




Examine error for increasing N.

Comparison of methods

 Plots show error vs. increasing number of sample points N.



Reference: "Improving the Accuracy of the Trapezoidal Rule", Bengt Fornberg, SIAM Rev., 63(1), 167–180.

Different integrands, different polynomials

 Gauss-Legendre quadrature – simplest method which we just looked at. Integrals of form:

$$\int_{-1}^{1} dx f(x) \approx \sum_{i=1}^{N} w_i f(x_i)$$

Gauss-Chebyshev quadrature. Integrals of form:

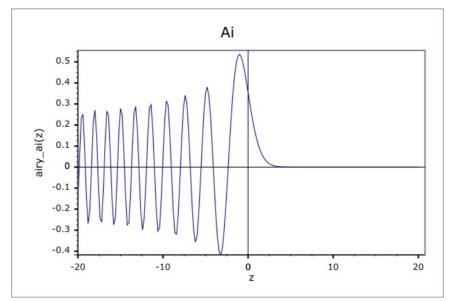
$$\int_{1}^{1} dx \frac{f(x)}{\sqrt{1-x^2}} \approx \sum_{i=1}^{N} w_i f(x_i)$$
 Homework problem

Gauss-Hermite quadrature. Integrals of form:

$$\int_{-\infty}^{\infty} dx f(x) e^{-x^2} \approx \sum_{i=1}^{N} w_i f(x_i)$$

- Many others...
- Many not in Matlab. You must roll your own.

Next topic: Adaptive quadrature



$$\frac{d^2y}{dx^2} = xy$$

$$y = Ai(x)$$

- Consider integrating Ai(x) from -20 to 20.
 - Mesh points on left must be closely spaced.
 - Mesh points on right don't need close spacing.
- Integration needs different h values over different intervals for low error.
- Matlab quad: "Adaptive Simpson Quadrature".

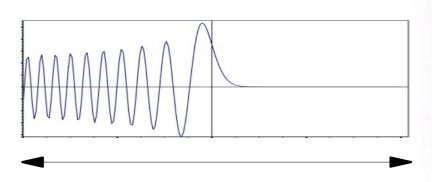
Adaptive quadrature algorithm

- Get error estimate for integral over full interval
 - Get error estimate by doing integral twice:
 once with h, then with h/2.
- If error estimate too high, then sub-divide interval.
- Do integral over each sub-interval separately, and get error estimates over sub-intervals.
- If error estimate too high in one or more subintervals, divide them again and recurse.

Example

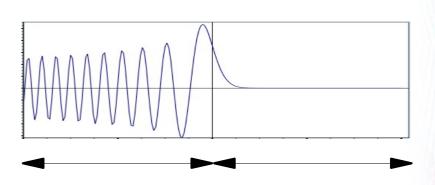
First attempt

 Do quad twice with different h to estimate error



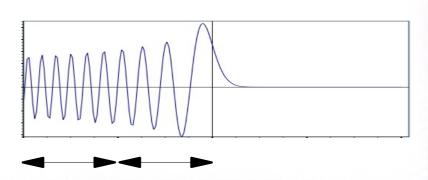
Second attempt

 Do quad twice with different h to estimate error



Third attempt

 Do quad twice with different h to estimate error



Library you should know: QUADPACK

- Another public-domain numerical analysis package available on www.netlib.org.
- Numerical integration library (Fortran).
- Bindings to Octave, NumPy/SciPy, etc.
- Clones for C/C++, etc.
- Similar integration routines for C++ also available in GSL (Gnu Scientific Library).

Numerical Integration: Summary

- 1D integration:
 - Endpoint & trapezoidal rules
 - Newton-Cotes (evenly spaced x axis points)
 - Gaussian-Legendre quadrature (choose sample points and weights using Legendre polynomials).
 - Clenshaw-Curtis
- Comparison of methods