

EE 603- Assignment 2

Digital Signal Processing and its applications

Assignment - 2

81) a) $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$

$$x[n] = -b^n u[-n-1] = \begin{cases} b^n, & n \leq -1 \\ 0, & n \geq 0 \end{cases}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{-1} -b^n e^{-j\omega n} \quad \begin{cases} \text{restriction on } b \\ |b| \geq 1 \end{cases}$$

$$= - \left(\frac{b e^{-j\omega}}{1 - b e^{-j\omega}} \right) \quad |b| \geq 1$$

b) $Y(e^{j\omega}) = \frac{2e^{-j\omega}}{1+2e^{-j\omega}} \quad (b=-2 \text{ from obs.})$

$$x[n] \text{ (from prev. qn)} = -(-2)^n u[-n-1]$$

82) $x[n] = \cos\left(\frac{15\pi n}{4} - \frac{\pi}{3}\right)$

$$= \cos\left(\frac{15\pi n}{4}\right) \cdot \frac{1}{2} + \frac{\sqrt{3}}{2} \sin\left(\frac{15\pi n}{4}\right)$$

$$= \frac{1}{4} \left(e^{j\frac{15\pi n}{4}} + e^{-j\frac{15\pi n}{4}} \right) + \frac{\sqrt{3}}{4} \left(e^{j\frac{15\pi n}{4}} - e^{-j\frac{15\pi n}{4}} \right)$$

Since complex exponentials are eigenfns of LTI systems

$$y[n] = \frac{1}{4} \left(H(e^{j\frac{15\pi}{4}}) e^{j\frac{15\pi n}{4}} - H(e^{-j\frac{15\pi}{4}}) e^{-j\frac{15\pi n}{4}} \right) + \frac{\sqrt{3}}{4} \left(H(e^{j\frac{15\pi}{4}}) e^{j\frac{15\pi n}{4}} + e^{-j\frac{15\pi n}{4}} H(e^{-j\frac{15\pi}{4}}) \right)$$

where,

$$H(e^{j\frac{15\pi}{4}}) = e^{-j\left[\frac{15\pi}{8} + \frac{\pi}{4}\right]} = e^{-j\frac{17\pi}{8}}$$

$$H(e^{-j\frac{15\pi}{4}}) = e^{-j\left(\frac{\pi}{4} - \frac{15\pi}{8}\right)} = e^{+j\frac{13\pi}{8}}$$

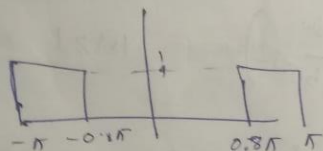
$$\Rightarrow y[n] = e^{-j\frac{\pi}{4}} \cos\left(\frac{\pi n}{4} + \frac{5\pi}{24}\right)$$

Q3)

(a) $H_1(e^{j\omega})$ is a frequency shifted form.

$$= H(e^{j(\omega-\pi)})$$

$$\Rightarrow H_1(e^{j\omega}) = \begin{cases} 0, & |\omega| < 0.8\pi \\ 1, & 0.8\pi \leq |\omega| \leq \pi \end{cases}$$

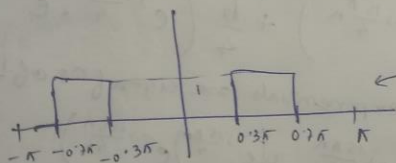


This is a high pass filter.

(b) $H_2(e^{j\omega})$ is a frequency modulated form.

$$H_2(e^{j\omega}) = H(e^{j\omega}) * (\delta(\omega - 0.5\pi) + \delta(\omega + 0.5\pi))$$

$$\rightarrow = \begin{cases} 0, & |\omega| < 0.3\pi \\ 1, & 0.3\pi \leq |\omega| \leq 0.7\pi \\ 0, & 0.7\pi < |\omega| \leq \pi \end{cases}$$



Band pass filter

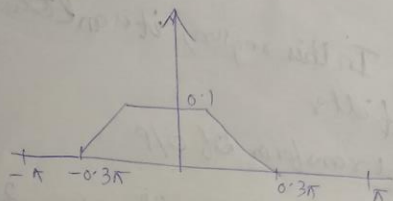
(c) $H_3(e^{j\omega})$ corresponds to a periodic convolution of $H_{lp}(e^{j\omega})$ with another low pass filter, which is

$$H_3(e^{j\omega}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_x(e^{j\eta}) H_{lp}(e^{j\omega-\eta}) d\eta$$

$$\text{where } H_x(e^{j\omega}) = \begin{cases} 1, & |\omega| < 0.1\pi \\ 0, & 0.1\pi \leq \omega \leq \pi \end{cases}$$

$$= \frac{1}{2\pi} \left[\int_{-\pi}^{-0.1\pi} H_{LP}(e^{j\omega-n}) d\omega + \int_{0.1\pi}^{\pi} H_{LP}(e^{j\omega-n}) d\omega \right]$$

$$H_3(e^{j\omega}) = \begin{cases} 0.1, & \omega < 0.1\pi \\ \frac{|\omega|}{2\pi} + 0.15, & 0.1\pi \leq |\omega| \leq 0.3\pi \\ 0, & 0.3\pi < |\omega| < \pi \end{cases}$$



Q4) $y[n] = \frac{1}{2} y[n-1] + x[n]$

Finding solution by recursion.

$$x[n] = \delta[n]$$

$$y[0] = 1 \quad y[2] = \frac{1}{4}$$

$$y[1] = \frac{1}{2} \quad y[3] = \frac{1}{8} \dots$$

$$y[n] = \left(\frac{1}{2}\right)^n u[n] \quad (\text{as } n \geq 0)$$

The system is stable, as $\left(\frac{1}{2}\right)^n u[n]$ is infinitely summable, i.e.

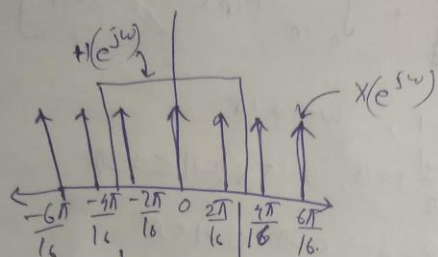
$$\sum_{-\infty}^{\infty} \left(\frac{1}{2}\right)^n u[n] = \frac{1}{1 - \frac{1}{2}} = 2.$$

Q5)
$$X(e^{j\omega}) = \sum_{-\infty}^{\infty} \sum_{(n,k)} \delta(n+16k) e^{-j\omega n}$$

$$= \frac{1}{16} \sum_{k=-\infty}^{\infty} \delta\left(\omega + \frac{2\pi k}{16}\right)$$

$X(e^{j\omega})$ is also a periodic impulse train. There

are 16 impulses in the range $-\pi \leq \omega \leq \pi$



In this region, it is an low pass filter.

~~Fourier~~ transform of o/p

$$Y(e^{j\omega}) = \frac{1}{16} \delta(\omega) + \frac{1}{16} e^{-j\frac{4\pi}{16}} \delta(\omega - \frac{2\pi}{16}) + \frac{1}{16} e^{j\frac{4\pi}{16}} \delta(\omega + \frac{2\pi}{16})$$

$$\Rightarrow y[n] = \frac{1}{16} + \frac{1}{8} \cos\left(\frac{2\pi n}{16} + \frac{3\pi}{8}\right)$$

Q6) $V(e^{j\omega}) = X(e^{j(\omega+\pi)})$

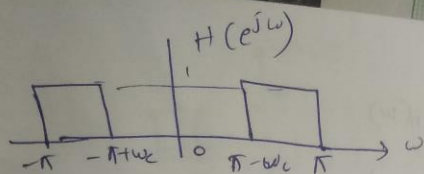
$$\begin{aligned} W(e^{j\omega}) &= H_1(e^{j\omega}) (V(e^{j\omega})) \\ &= H_1(e^{j\omega}) X(e^{j(\omega+\pi)}) \end{aligned}$$

$$\begin{aligned} Y(e^{j\omega}) &= W(e^{j(\omega-\pi)}) \\ &= H_1(e^{j(\omega-\pi)}) X(e^{j\omega}) \end{aligned}$$

$$\Rightarrow H(e^{j\omega}) = H_1(e^{j(\omega-\pi)})$$

$$H(e^{j\omega}) = H_1(e^{j(\omega-\pi)})$$

$$H(e^{j\omega}) = \begin{cases} 0, & |\omega| < \pi - \omega_c \\ 1, & \pi - \omega_c < |\omega| \leq \pi \end{cases}$$



Q7)

$$y[n] = \nabla(x[n]) = x[n] - x[n-1]$$

(a) linear & time invariant

$$\begin{aligned} \hookrightarrow y[ax_1[n] + bx_2[n]] &= ax_1[n] + bx_2[n] - ax_1[n-1] - bx_2[n-1] \\ &= a(x_1[n] - x_1[n-1]) + b(x_2[n] - x_2[n-1]) \\ &= ay_1[n] + by_2[n] \\ &\therefore \text{linear} \end{aligned}$$

$$\begin{aligned} y(x[n-1]) &= x[n-1] - x[n-2] \\ &= y[n-1] \end{aligned}$$

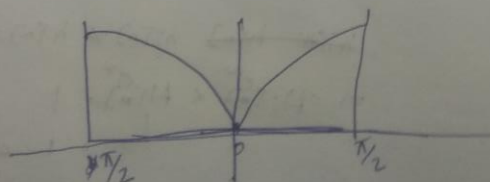
\therefore Time invariant

(b) $x[n] = \delta[n]$

$$y[n] = \delta[n] - \delta[n-1]$$

(c) $H(e^{j\omega}) = 1 - e^{-j\omega}$

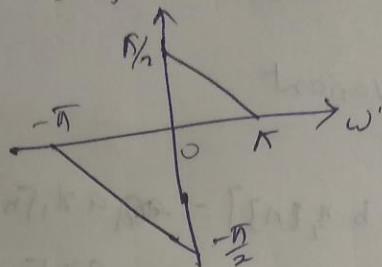
$$\begin{aligned} |H(e^{j\omega})| &= \sqrt{(1 - e^{-j\omega})(1 - e^{+j\omega})} \\ &= \sqrt{(1 + 1 - e^{-j\omega} - e^{j\omega})} \\ &= \sqrt{(2 - 2\cos\omega)} \end{aligned}$$



phase

$$H(e^{j\omega}) = (1 - \cos\omega) + j\sin\omega$$

$$\angle H(e^{j\omega}) = \tan^{-1} \left(\frac{\sin\omega}{1 - \cos\omega} \right)$$



(d) : $y[n] = f[n] * g[n]$

$$\downarrow$$

$$x[n] - x[n-1] = \underbrace{x[n]}_{f[n] * g[n]} * \underbrace{(\delta[n] - \delta[n-1])}_{t[n]}$$

$$\Rightarrow y[n] = f[n] * g[n] * t[n]$$

$$= f[n] * g[n] * (\delta[n] - \delta[n-1])$$

$$\downarrow$$

$$= [f[n] * (\delta[n] - \delta[n-1])] * g[n] = f[n] * (g[n] * (\delta[n] - \delta[n-1]))$$

$$= (\nabla f[n]) * g[n] = f[n] * \nabla(g[n])$$

(e)

to find $h_i[n]$ where

$$h_i[n] * \nabla(x[n]) = x[n]$$

$$\text{if } x[n] = \delta[n]$$

$$\cancel{h_i[n]} \quad h_i[n] * h[n] = \delta[n]$$

$$\Rightarrow H_i(e^{j\omega}) \times H(e^{j\omega}) = 1$$

$$\hookrightarrow 1 - e^{-j\omega}$$

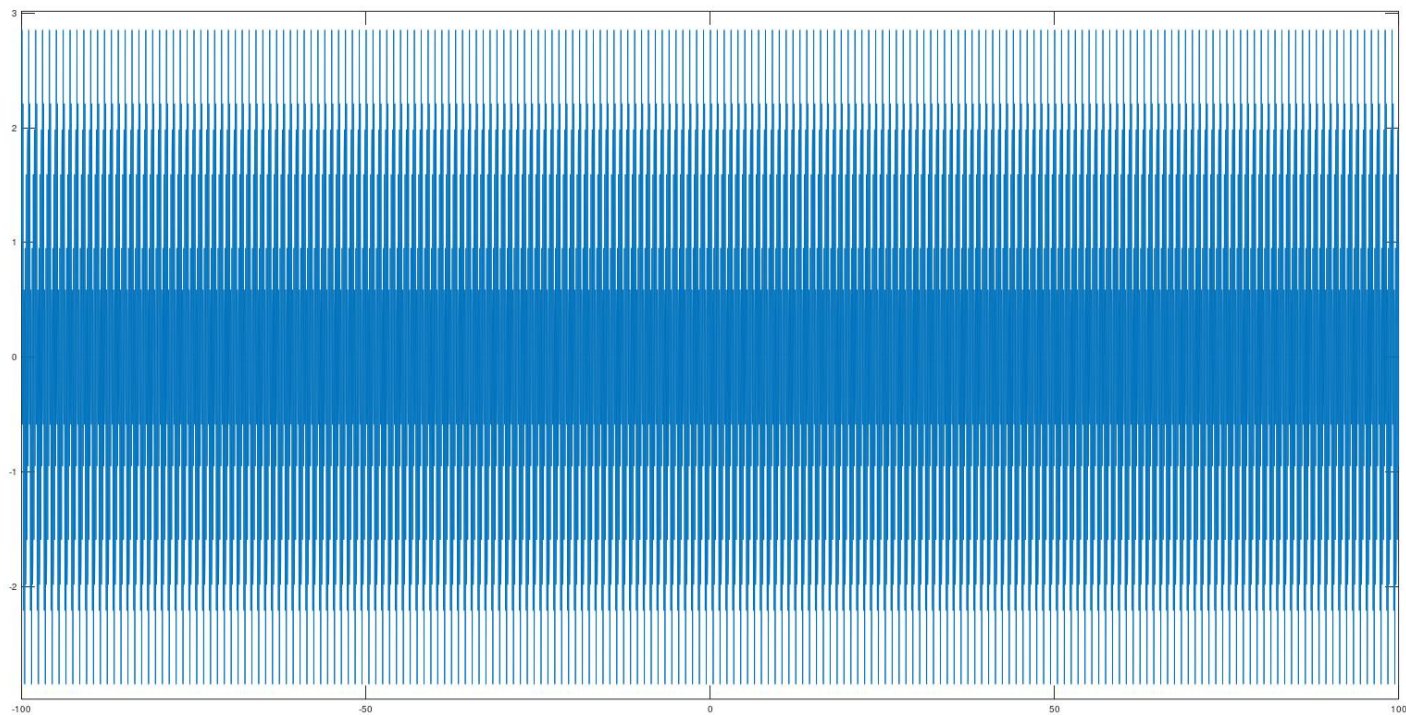
$$\Rightarrow H_i(e^{j\omega}) = \frac{1}{1 - e^{-j\omega}} \Rightarrow \underline{\underline{h_i[n] = u[n]}}$$

Question 8

a. Code:

```
n=-100:100;  
Fs= 20;  
t=-100:1/Fs:100;  
x=cos(2*pi*t)+2*sin(12*pi*t);  
plot(t,x);
```

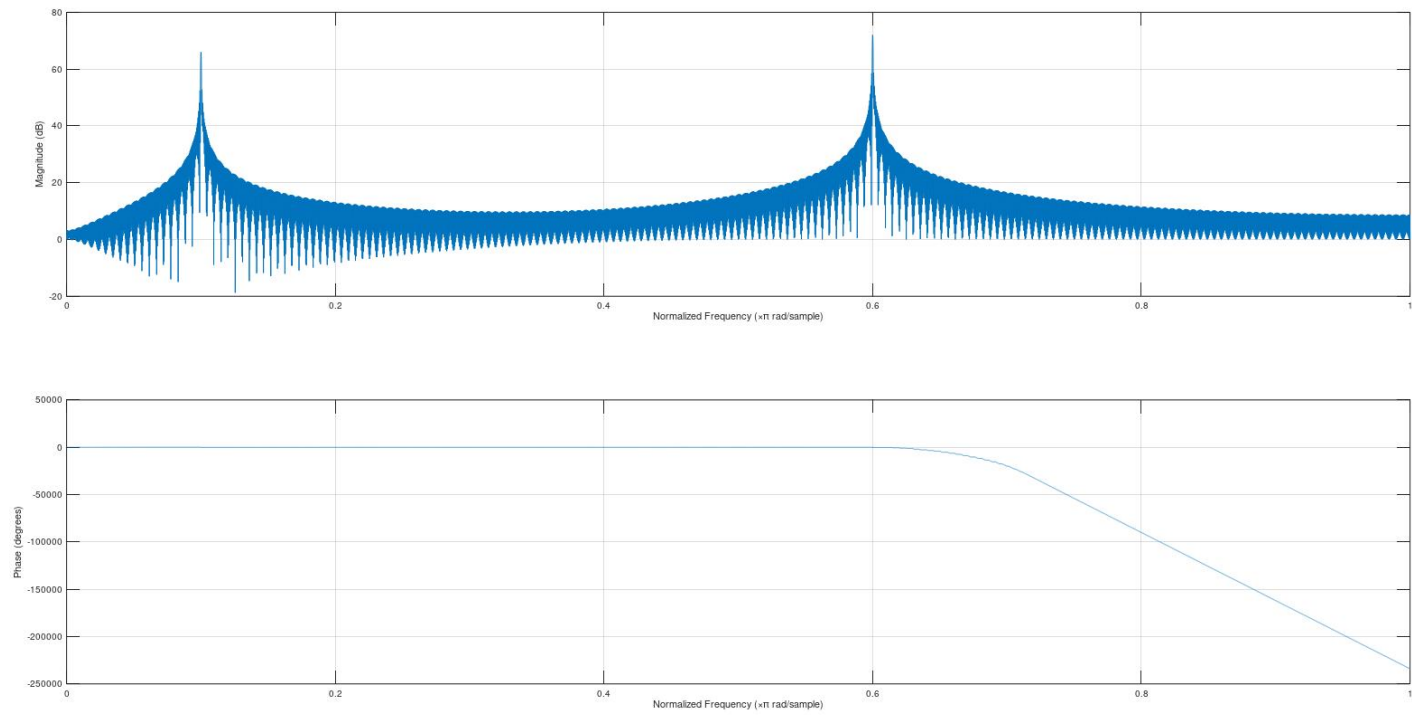
Plot:



b. Code:

```
n=-100:100;  
Fs= 20;  
t=-100:1/Fs:100;  
x=cos(2*pi*t)+2*sin(12*pi*t);  
freqz(x);
```

Plot:



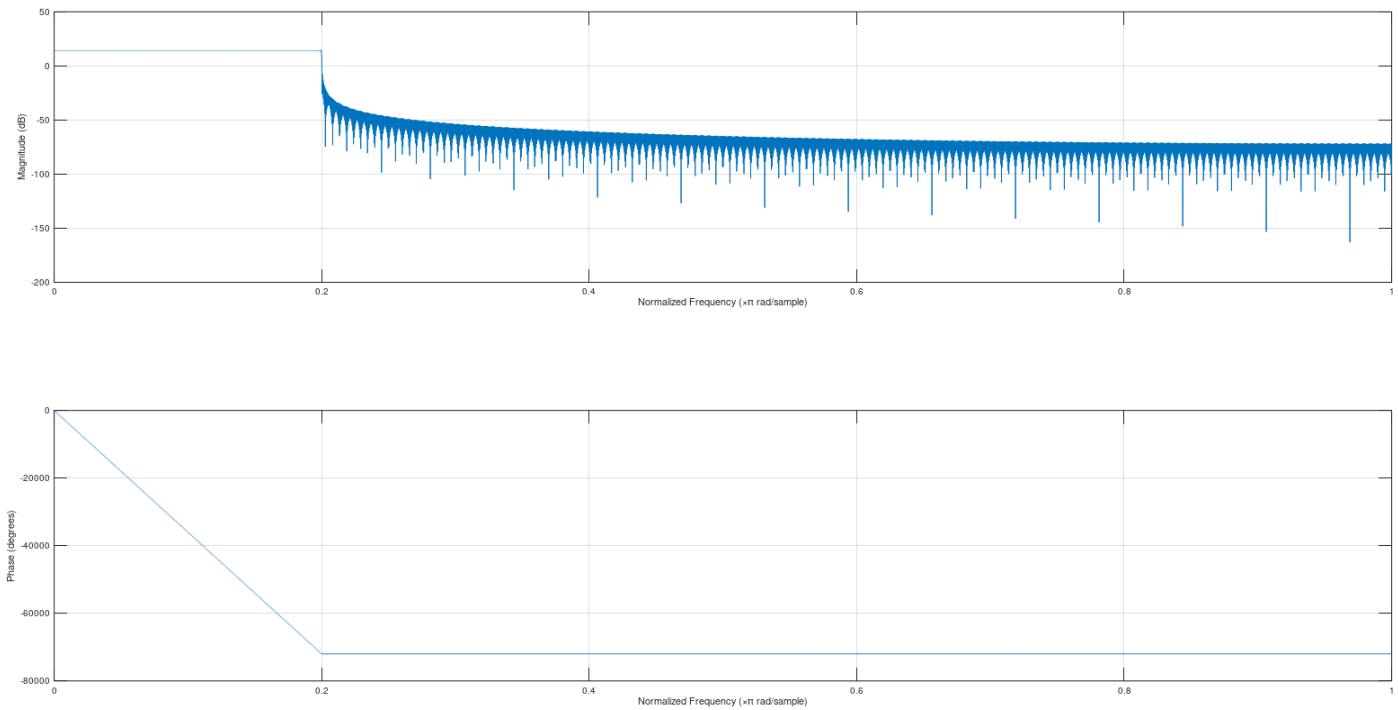
c. Code:

```

Fs= 20;
t=-100:1/Fs:100;
myfilter=sinc(4*t);
freqz(myfilter);

```

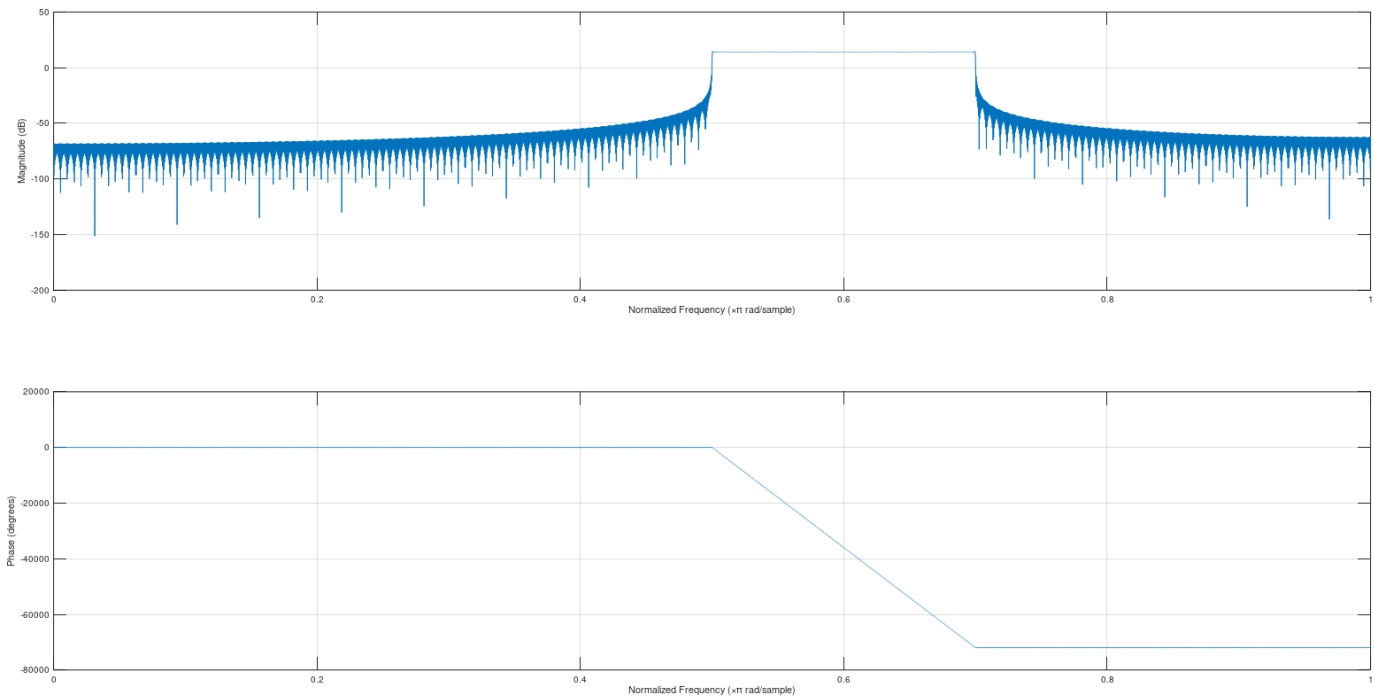
Plot:



d. Code:

```
Fs= 20;  
t=-100:1/Fs:100;  
myfilter=sinc(2*t);  
myfilter2=myfilter.*cos(12*pi*t);  
freqz(myfilter2);
```

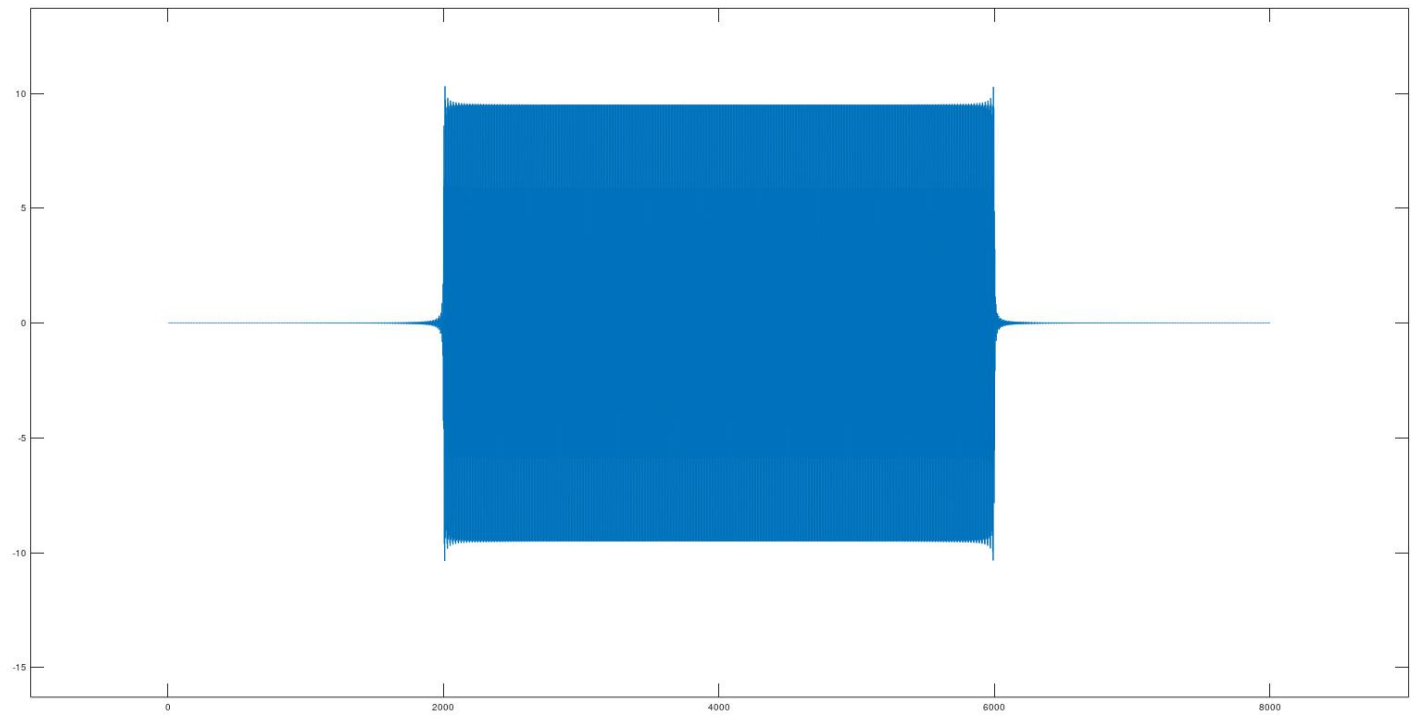
Plot:



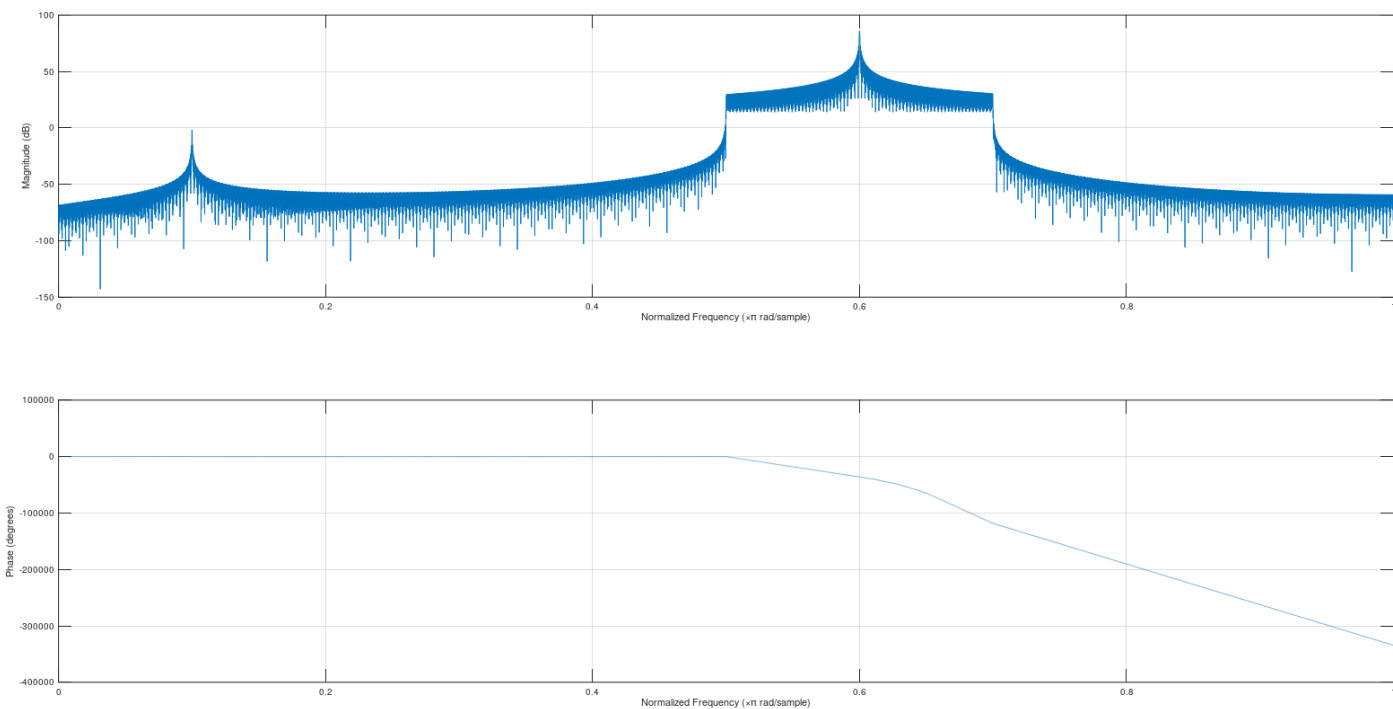
e. Code:

```
Fs= 20;  
t=-100:1/Fs:100;  
x=cos(2*pi*t)+2*sin(12*pi*t);  
myfilter=sinc(2*t);  
myfilter2=myfilter.*cos(12*pi*t);  
plot(conv(x,myfilter2));
```

Plot:



Freqz:



We observe a high varying output between 5 Hz and 7 Hz, and on the plot we see a box like figure. This is because the filter filtered out all frequencies in the input signal $x(t)$, except for the frequencies 5 to 7 Hz. This means that the sine wave is passed (the peak at 0.6) but the cos wave is blocked.