

# Furkan Mert Algan

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CONTACT INFORMATION	<b>Address:</b> Arcisstrasse 21 80333, Munich, Germany	<b>Website:</b> <a href="https://theycallmefm.github.io">theycallmefm.github.io</a> <b>Phone:</b> +49 152 371 709 65 <b>E-mail:</b> <a href="mailto:fmertalgan@gmail.com">fmertalgan@gmail.com</a>
RESEARCH INTERESTS	<b>Machine Learning:</b> Deep Learning, Convolutional Neural Networks, Transformers <b>Computer Vision:</b> 3D Vision, Scene Understanding, Motion Estimation, Diffusion Models <b>Computer Graphics:</b> 3D Reconstruction, Neural Rendering	
EDUCATION	<b>Technical University of Munich</b> , Munich, Germany Ph.D.in Chair of Media Technology Advisor: Prof. Steinbach Eckehard	2021–2026 (expected)
	<b>Technical University of Munich</b> , Munich, Germany M.Sc.in Informatics Thesis: <i>3D Motion Estimation on Point Clouds using Deep Learning</i>	2017–2021
	<b>Sabanci University</b> , Istanbul, Turkey. B.Sc.in Computer Science and Engineering Minor in Mathematics Graduation Project: <i>Sensitivity Time Control Function on Marine Radar Videos</i>	2013–2017
RESEARCH EXPERIENCE	<b>Technical University of Munich</b> , Munich, Germany <i>Research Associate</i> in the Chair of Media Technology <ul style="list-style-type: none"><li>Currently in 6G Digital Twin project.</li><li>Working for the realization of a continuously updated digital twin for objects, spatial geometry, surface properties, sensors, actuators and network.</li><li>Research focusing on 3D model editing, generation and completion</li><li>Working closely with Chair of Communication Networks to create a real-time application.</li></ul> <b>Supervisor:</b> Eckehard Steinbach	Dec 2021 - Present
	<b>Harvard University</b> , Cambridge, MA, USA <i>Graduate Research Fellow</i> in the Visual Computing Group <ul style="list-style-type: none"><li>Master's thesis about 3D motion estimation on point clouds using deep learning.</li><li>Achieved state-of-the-art results using sparse convolutions and transformers.</li><li>Paper submission is expected.</li></ul> <b>Supervisors:</b> Prof. Hanspeter Pfister, Prof. Donglai Wei, Prof. Matthias Niessner	Aug 2020 - June 2021
	<b>Technical University of Munich</b> , Munich, Germany <i>Graduate Research Intern</i> in the Visual Computing Lab <ul style="list-style-type: none"><li>Combined Scan2CAD and VoxelHashing research projects</li><li>Implemented a real-time 3D reconstruction framework that replaces incomplete model by a CAD model in a 3D scene</li></ul> <b>Supervisor:</b> Prof. Matthias Niessner	Sept 2019 - June 2020
	<i>Research Intern</i> in the Chair of Robotics, AI and Real-time Systems <ul style="list-style-type: none"><li>Contributed to a task-driven algorithm for configuration synthesis of the modular robot project.</li><li>Gathered sample data in MATLAB and created data structures in C++</li></ul> <b>Supervisor:</b> Prof. Matthias Althoff	Aug 2016 - Oct 2016
PROFESSIONAL EXPERIENCE	<b>Roboy</b> , Munich, Germany <i>Practical Project Student</i> <ul style="list-style-type: none"><li>Worked in a multidisciplinary team to build ice cream selling Roboy</li><li>Contributed to Ravestate, a reactive library for real-time natural language dialog systems and created ice cream selling dialogue.</li><li>Implemented a Telegrambot to call Roboy to a remote location.</li></ul> <b>HAVELSAN</b> , Istanbul, Turkey <i>Graduation Project Student</i>	May 2019 - Sept 2019 Nov 2016 - June 2017
	<ul style="list-style-type: none"><li>Implemented the Sensitivity Time Control Function on Marine Radar Videos on FPGA.</li><li>Gathered sea clutter data using K-distribution in MATLAB.</li></ul>	

TECHNICAL SKILLS	<p><b>Programming Languages:</b> C++, Python</p> <p><b>Deep Learning:</b> PyTorch, Scikit-learn</p> <p><b>Miscellaneous:</b> Git, OpenGL, CUDA, ROS, Blender</p> <p><b>Editing Softwares:</b> Adobe Premiere, Adobe Photoshop.</p>
NOTABLE PROJECTS	<p><b>Augmentation for Scene Flow Estimation</b> This project aims to create a new augmentation technique for scene flow estimation using differentiable rendering.</p> <p><b>A KinectFusion Reimplementation on CUDA</b> This project aims to implement a system for accurate real-time mapping of complex and arbitrary indoor scenes in variable lighting conditions, using only a low cost Kinect camera. A coarse-to-fine iterative closest point (ICP) algorithm has been implemented for point cloud registration using CUDA library in C++.</p> <p><b>Exploring the Relationship between Design Metrics and Software Diagnosability using Machine Learning</b> The purpose of the project was to find best software metrics for fault localization using machine learning methods. A dataset has been created using Eclipse Plugin CodePro and it has been analyzed using Scikit-Learn library in Python.</p>
TEACHING EXPERIENCE	<p><b>Technical University of Munich</b> <i>Teaching Assistant</i></p> <ul style="list-style-type: none"> <li>Software Engineering Lab Winter 2023, Summer 2024, Winter 2024</li> <li>Techniques in Artificial Intelligence Winter 2018</li> </ul> <p><b>Sabanci University</b> <i>Undergraduate Teaching Assistant</i></p> <ul style="list-style-type: none"> <li>Introduction to Programming Spring 2017</li> <li>Calculus Spring 2015, Fall 2015, Fall 2016</li> </ul>
HONORS AND AWARDS	<p><b>TEV-DAAD Master's Scholarship</b> Awarded by Turkish Education Foundation and German Academic Exchange service due to success in undergraduate studies</p> <p><b>Sabanci University Merit Scholarship</b> Awarded by Sabanci University due to success in national university entrance exam.</p>
LANGUAGES	Turkish (native), English (fluent), German (limited).
SELECTED PUBLICATIONS	<ol style="list-style-type: none"> <li><b>F Mert Algan</b> <i>et al.</i>, "LEMON: Localized Editing with Mesh Optimization and Neural Shaders" <i>arXiv preprint</i>, arXiv:2409.12024, 2024. [Online]. Available: <a href="https://arxiv.org/abs/2409.12024">https://arxiv.org/abs/2409.12024</a> Website</li> </ol>
REFERENCES	Available upon request.