

University of Massachusetts Lowell  
Department of Mathematical Sciences  
MATH 4750  
Senior Seminar Project Report

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**Abstract**

In this paper, I verify Newton's law of cooling by experimentation using cheap and widely available sensors and devices, and free and open source software systems, including a few short original software programs. I find that the law accurately describes this system, and I mathematically describe the particular system with a differential equation that contains a numerically calculated cooling coefficient.

## 1 Introduction

Scientists express the physical laws of the universe in the language of differential equations. The reason for this is not immediately obvious, though my personal work with differential equations has provided me with an intuition as to why. Fortunately for me, one scientist describes three necessary properties of a physical law that are satisfied by a differential equation as:

- “The mathematical relation must be sufficiently general”
- “It must define connections between neighboring points”

- “It must imply the continuity of change” [Siddiqui, 2014]

Differential equations satisfy all three of these properties since they are general enough that changes to the initial values of a system do not violate the constraints defined by a general solution and the relationship between a function and one or more of its derivatives defines the connection between points in the domain of the function and implies that change in the system is continuous due to the nature of calculus.

Newton’s law of cooling states that “the rate of heat loss of a body is directly proportional to the difference in the temperatures between the body and its surroundings” [Wikipedia, 2020].

Let  $\Delta T$  be the difference between the temperature of the body and the ambient temperature of the environment as a function of a point in time  $t$ . Then, we have that equation 1 describes Newton’s law of cooling.

$$\frac{d\Delta T}{dt} = k\Delta T(t) \text{ for some } k \in \mathbb{R} \quad (1)$$

Next, we can solve this differential equation by separating the parameters.

$$\frac{dT}{dt} \frac{1}{\Delta T(t)} = k \quad (2)$$

$$\int \frac{dT}{dt} \frac{1}{\Delta T(t)} dt = \int k dt \quad (3)$$

$$\ln |\Delta T(t)| = kt + C \text{ for some } C \in \mathbb{R} \quad (4)$$

$$e^{\ln |\Delta T(t)|} = e^{kt+C} \quad (5)$$

$$\Delta T(t) = De^{kt} \text{ where } D = e^C \quad (6)$$

In this paper, I verify the this law relative to a particular environment and calculate an approximate value of the cooling coefficient by fitting experimental data to equation 6.

## 2 Materials and Methods

I performed this experiment using using hardware sensors connected to a Raspberry Pi computer, specifically the model 4B+ with 8GB of RAM.



Figure 1: The full experimental setup

I chose the DS18D20, a waterproof temperature sensor compatible with the Raspberry Pi. These sensors are relatively inexpensive, and I purchased a 5 pack for \$12.98 on Amazon [Gikfun, 2020].

With the equipment in hand, I set up the physical system on a small table where I had previously configured my two Raspberry Pi computers. I wired the sensors to the Raspberry Pi using a breadboard.

As you can see in figure 2, the system lies under my air conditioner set to cool my room to 70 degrees Fahrenheit. Primarily, this was to keep my room comfortable, but the additional cooling source added a bit of noise to the data that made the experiment a bit more interesting.

To prepare the system, I simply filled a mug with tap water and placed it in the microwave for about a minute. Then, as shown in figure 2, I placed one of the temperature sensors inside of the water and another right next to it, hanging over the side of the mug, to measure ambient temperature.

I wrote two software programs for this experiment, the first to gather the data, and the second to perform analysis on it. For this reason, the first program is called `gather`, and the second program is called `analysis`. See sections 5 and 6 for the full code listings.

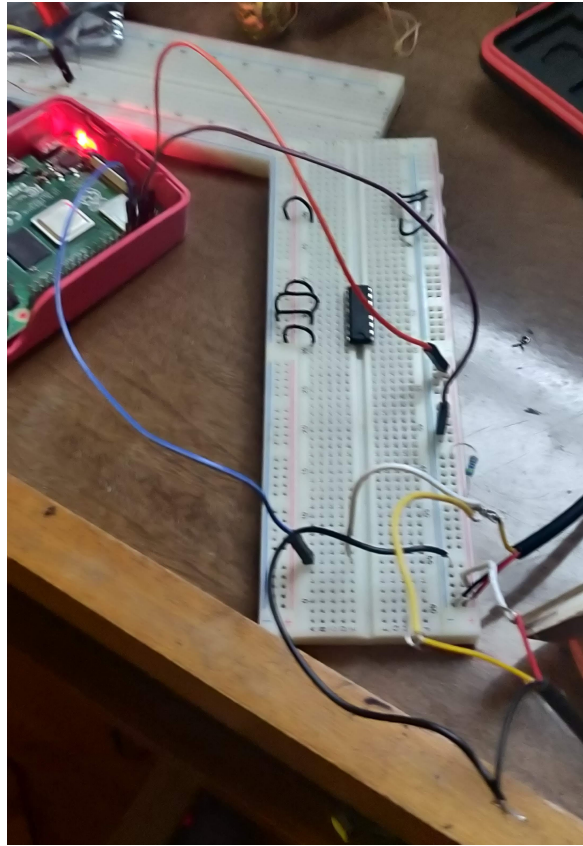


Figure 2: A close up of the wiring

### 3 Results

The sensors gathered the data for just over 4 hours. The full dataset is accessible in the project git repository as the file `gather/data2` [Savitz, 2020]. As seen in figure 3, the raw data contained a sharp oscillating pattern as the difference between the temperature of the body and the ambient temperature of the surrounding environment decayed towards zero. I suspect this was due to the thermostat of the nearby air conditioner turning off and on in order to maintain the room temperature. Regardless of this fluctuation, the data displayed a clear trend of exponential decay, validating and confirming Newton’s law of cooling.

Using non-linear least squares regression, courtesy of the `scipy` python library, I was able to find a curve of best fit, and approximate the following equation for this system:

$$\Delta T(t) = 26.31e^{-3.658 \times 10^{-4}t} - 0.4938 \quad (7)$$

Thus the approximate value of the cooling coefficient, denoted  $k$  in equation 6, is  $3.658 \times 10^{-4}$ , and we can write the following differential equation to approximate this system:

$$\frac{d\Delta T}{dt} = -3.658 \times 10^{-4}\Delta T(t) \quad (8)$$

### 4 Discussion

For this relatively small difference between the temperature of a cup of hot water and my room with a running and fairly powerful 10,000 BTU air conditioner, Newton’s law of cooling approximates the rate at which the temperature of the body of concern decays to the temperature of its environment. This is a testament to the genius of Isaac Newton, whose scientific articulation was able to describe the behavior of a cup of water in my room several hundred years in advance.

Using my small software suite and relatively inexpensive equipment, I could replicate this experiment on a wide variety of systems, given that the temperatures of concern are within the detection range of the sensors and

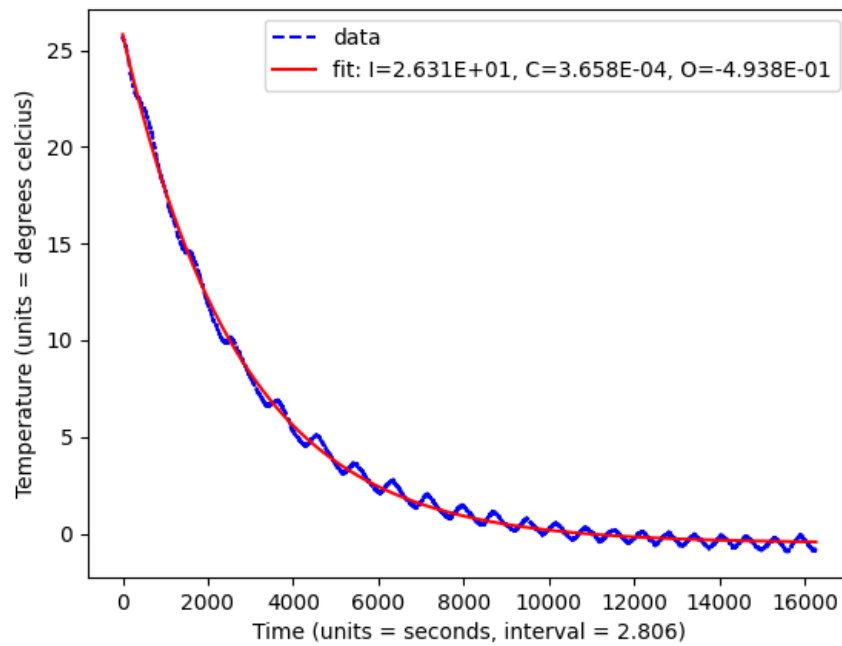


Figure 3: A plot of the data and the fitted curve

the operating temperature of the nearby Raspberry Pi computer. In a small but significant sense, this experiment demonstrates the democratization of the scientific process, for almost anyone could acquire the same equipment, and perhaps using my freely available software, replicate my experiment and validate Newton's law for themselves. The beauty of scientific and mathematical progress and discovery lies in its objective nature. This physical law describes the behavior of physical systems whether a person believes in their validity or not, and a skeptical mind may take matters into their own hands and validate this equation as I have, with no need to appeal any authority other than nature itself.

The code listings of my `gather` and `analysis` programs follow as appendices.

## 5 Appendix A: The gather program

### 5.1 Main program

```
#!/usr/bin/python3
# Based on code from https://learn.adafruit.com/
#   adafruits-raspberry-pi-lesson-11-ds18b20-temperature
#   -sensing/software

import glob
import time
import datetime
import sys
import signal

BASE_DIR = '/sys/bus/w1/devices/'
SENSOR_DIRS = glob.glob(BASE_DIR + '28*')
NUM_SRCS = len(SENSOR_DIRS)
DATA_SRCS = [SENSOR_DIRS[i] + '/w1_slave' for i in
              range(NUM_SRCS)]

# Print the date on receipt of SIGINT
def print_date_on_sigint(sig, frame):
    print("End sensor reading at {}".format(str(
        datetime.datetime.now())))
```

```

sys.exit(0)

# Get the pure, raw, uncensored sensor data
def read_temp_raw(index):
    srcfile = open(DATA_SRCS[i], 'r')
    lines = srcfile.readlines()
    srcfile.close()
    return lines

# Extract the actual temperature value from the raw data
def read_temp(index):
    lines = read_temp_raw(index)
    while lines[0].strip()[-3:] != 'YES':
        time.sleep(0.2)
        lines = read_temp_raw()
    equals_pos = lines[1].find('t=')
    if equals_pos != -1:
        temp_string = lines[1][equals_pos+2:]
        temp_c = format(float(temp_string) / 1000.0, '.2f')
        return temp_c

# Register the signal handler and read on loop until forcibly stopped
signal.signal(signal.SIGINT, print_date_on_sigint)
print("Begin sensor reading at {}".format(str(datetime.datetime.now())))
while True:
    for i in range(NUM_SRCS):
        print(read_temp(i), end=' ' if i < NUM_SRCS - 1 else '\n')
    time.sleep(1)

```

## 5.2 Wrapper shell script

```
#!/bin/bash
```



```

usage() {
echo << DELIMITER
Usage: gather.sh [-o] [-f <output_filename>

-f: specify output filename (defaults to 'data')
-o: overwrite file instead of append

DELIMITER
}

FILENAME="data"
TEE_ARGS="-a"

while getopts "f:o" OPTION; do
    case ${OPTION} in
        f)
            FILENAME="${OPTARG}"
            ;;
        o)
            TEE_ARGS=""
            ;;
        *)
            echo "Unknown option ${OPTION},
                ignoring"
            shift
            ;; esac
    done
shift $((OPTIND -1))

# Gather buffered input (instead of using python -u) to
allow for Ctl+C
script -qc 'python3 gather.py' | tee ${TEE_ARGS} ${
    FILENAME}

# We don't actually need this lol
rm -rf "typescript"

```

```
# Remove the ugly ^C from the logfile
sed -i 's/\^C//g' ${FILENAME}
```

## 6 Appendix B: The analysis program

```
#!/usr/bin/python3
import sys
import datetime
import re
import matplotlib.pyplot as plt
from scipy.optimize import curve_fit
import numpy

def getlines(filename):
    f = open(filename)
    lines = f.readlines()
    f.close()
    return lines

def stamp_stripper(unstripped_stamp):
    res = re.search(r'(?<=reading at ).* ',
        unstripped_stamp)
    return res.group(0)

# Get total reading duration
def calculate_duration(start_datetime_str,
    end_datetime_str):
    start_datetime = datetime.datetime.strptime(
        start_datetime_str, "%Y-%m-%d %H:%M:%S.%f")
    end_datetime = datetime.datetime.strptime(
        end_datetime_str, "%Y-%m-%d %H:%M:%S.%f")
    return end_datetime - start_datetime

# paramaters: t(ime), I(nitial), C(ooling coefficient),
O(ffset)
def exponential_decay(t, I, C, O):
    return I * numpy.exp(-C * t) + O
```

```

# If we don't have datafile, we can't do anything
if len(sys.argv) < 2:
    print("usage: analysis.py <datafile>")
    sys.exit(0)

# Get the raw data from the datafile
datafile = sys.argv[1]
lines = getlines(datafile)

# Calculate the duration of the sensor reading
duration = calculate_duration(stamp_stripper(lines[0]),
    stamp_stripper(lines[-1]))

# Turn temperature readings into differences of type
float
y_data = [nums[1] - nums[0] for nums in [list(map(numpy
    .float64, s[0:-1].split(' '))) for s in lines
    [1:-1]]]

# Calculate the time interval by dividing the total
duration by the number of data points
x_range = len(y_data)
x_units = (duration / x_range).total_seconds()
x_data = numpy.array([numpy.float64(i * x_units) for i
    in range(x_range)])

# Perform non-linear least squares curve fitting using
the scipy library
popt, pcov = curve_fit(exponential_decay, x_data,
    y_data)

# Plot the raw data in blue dashed lines
plt.plot(x_data, y_data, 'b--', label='data')

# Plot the curve we fitted to the data
plt.plot(x_data, exponential_decay(x_data, *popt), 'r--'

```

```

,
    label='fit: I=%0.3E, C=%0.3E, O=%0.3E' % tuple(
        popt))

plt.xlabel('Time (units = seconds, interval = %0.3f)' %
    x_units)
plt.ylabel('Temperature (units = degrees celcius)')
plt.legend()

# The result :)
plt.show()

```

## References

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