Generic Bidirectional Typing for Dependent Type Theories

Thiago Felicissimo

August 21, 2024

Engenheiro pela Télécom Paris

Mestrado pelo Master Parisien de Recherche en Informatique (MPRI)

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Doutorando no final do 3o ano (defesa em menos de um mês), na Deducteam Sob a direção de Gilles Dowek e Frédéric Blanqui







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Mas antes de tudo isso...

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Estudei engenharia elétrica na UFMG, antes de ir pro duplo diploma na Télécom Fiz uma iniciação científica no DCC, no LECOM

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In dependent type theory:

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• Terms have types

[0, 1, 2] : List Nat

In dependent type theory:

• Terms have *dependent* types

[0, 1, 2] : Vec Nat 3

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$$\lambda n.[1,...,n]:?$$

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$$\lambda n.[1,...,n]: Nat \rightarrow List Nat$$

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$$\lambda n.[1,...,n]:\Pi(n:\mathsf{Nat}).\mathsf{Vec}\;\mathsf{Nat}\;n$$

In dependent type theory:

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Dependently-typed programming Dependent types allow to write both data and specification in the *same* language

```
(* pre-condition: list not empty *)

hd: List Nat \rightarrow Nat

hd (x :: l) = x

hd [] = FAIL
```

A foundation for mathematics, by the **Curry-Howard correspondence** Propositions as types, proofs as programs. Proof/type theory dictionary Used in many popular *proof assistants*, such as Coq, Lean and Agda

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hd :
$$\Pi(n : \text{Nat})$$
. Vec Nat $(n + 1) \rightarrow \text{Nat}$
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5

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Fully-annotated syntax keeps track of all annotations

$$t \otimes_{A,x.B} u \qquad \langle t,u\rangle_{A,x.B} \qquad t ::_A l \qquad \dots$$

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When defining syntax of type theories, many choices:

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$$t @_{A,x.B} u$$
 $\langle t, u \rangle_{A,x.B}$ $t ::_A l$...

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Non-annotated syntax restores usability by eliding parameter annotations

$$t u \qquad \langle t, u \rangle \qquad t :: l \qquad \dots$$

Syntax so common that many don't realize that an omission is being made

Omission has a cost Knowing annotations is needed for typing

$$\frac{\Gamma \vdash t : \Pi(x : A).B \qquad \Gamma \vdash u : A}{\Gamma \vdash t \; u : B[u/x]}$$

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$$\frac{\Gamma \vdash t:? \qquad \Gamma \vdash u:?}{\Gamma \vdash t\; u:?}$$

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$$\vdash \lambda f.\lambda x.f \ x : \alpha_0$$

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How to verify program *t u* is typed if *A* and *B* are not stored in syntax?

$$\alpha_0 = \alpha_1 \to \alpha_2 \to \alpha_3$$

$$f: \alpha_1, x: \alpha_2 \vdash f x: \alpha_3$$

$$\vdash \lambda f. \lambda x. f x: \alpha_0$$

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A solution for simple types Store the constraints on unknown types, then solve them using unification (Hindley-Milner type inference)

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$$\alpha_{0} = \alpha_{1} \rightarrow \alpha_{2} \rightarrow \alpha_{3} \frac{f : \alpha_{1}, x : \alpha_{2} \vdash f : \alpha_{4}}{f : \alpha_{1}, x : \alpha_{2} \vdash f : \alpha_{4}}$$

$$+ \lambda f. \lambda x. f : \alpha_{0}$$

Unification succeeds, with $\alpha_0 \mapsto (\alpha_5 \to \alpha_3) \to \alpha_5 \to \alpha_3$

Why does Hindley-Miler type inference works?

Simple types are 1st order

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Therefore, we would need *higher-order* unification, which is undecidable...

We need a different solution

Decompose typing judgment $\Gamma \vdash t : A$ into two modes:

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Checking \Gamma \vdash t \Leftarrow A (inputs: \Gamma, t, A) (outputs: none)
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Complements unannotated syntax, locally explains how to recover annotations

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This work *Generic* account of bidirectional typing for class of type theories

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1. We give a general definition of type theories (or equivalently, a *logical framework*) supporting non-annotated syntaxes

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- 1. We give a general definition of type theories (or equivalently, a *logical framework*) supporting non-annotated syntaxes
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- 1. We give a general definition of type theories (or equivalently, a *logical framework*) supporting non-annotated syntaxes
- 2. For each theory, we define declarative and bidirectional type systems
- 3. We show, in a theory-independent fashion, their equivalence

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Implemented in the theory-independent bidirectional type-checker BiTTs

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Can be used as independent proof verified, like in the Dedukti project But support for non-annotated syntax can allow for better performances

A theory $\mathbb T$ is made of schematic typing rules and rewrite rules.

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3 schematic typing rules: sort rules, constructor rules and destructor rules

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¹We use the name "sort" instead of "type" to avoid a name clash with the types of the theory

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Example: In MLTT, 2 judgment forms: " \Box type" and " \Box : A" for a type A.

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 $\frac{}{\text{Ty sort}} \qquad \qquad A \text{ type} \quad \rightsquigarrow \quad A : \text{Ty}$ $\frac{\text{A} : \text{Ty}}{\text{Tm(A) sort}} \qquad \qquad t : A \quad \rightsquigarrow \quad t : \text{Tm}(A)$

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Constructor rules

Constructor rules In bidirectional typing, constructors support *type-checking*

Missing information recovered from the sort given as input

The sort of the rule should be a *pattern* T^P on the missing arguments²

²Here, pattern = a *Miller* pattern that is *linear* and contains no destructors

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$$\frac{A : Ty \qquad x : Tm(A) \vdash B : Ty}{\Pi(A, x.B\{x\}) : Ty}$$

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Missing arguments are recovered by inferring the *principal argument* $t: T^P$

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Destructors written in orange, constructors written in blue

Rewrite rules

In type theory, terms should compute

Rewrite rules The computational rules of the theory

$$@(\lambda(x.t\{x\}), u) \longmapsto t\{u\}$$

In general, of the form $d(t^P, \vec{x}_1.t_1^P, ..., \vec{x}_k.t_k^P) \longmapsto r$, with left-hand-side linear

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Condition: no two left-hand sides unify

Therefore, rewrite systems are *orthogonal*, hence *confluent* by construction!

Full example, in the *formal* notation

Previous inference-rule notation can be desugared into a formal notation

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Previous inference-rule notation can be desugared into a formal notation

Theory $\mathbb{T}_{\lambda\Pi}$ A minimalistic type theory with only dependent functions

```
Tv(\cdot) sort
Tm(A : Tv) sort
\Pi(\cdot; A: Tv, B\{x: Tm(A)\}: Tv): Tv
\lambda(A : Ty, B\{x : Tm(A)\} : Ty; t\{x : Tm(A)\} : Tm(B\{x\})) : Tm(\Pi(A, x.B\{x\}))
(A : Ty, B\{x : Tm(A)\} : Ty; t : Tm(\Pi(A, x.B\{x\})); u : Tm(A)) : Tm(B\{u\})
(a)(\lambda(x,t\{x\}),u) \mapsto t\{u\}
```

Full example, in the formal notation

Previous inference-rule notation can be desugared into a formal notation

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In the rest of the talk, we use the inference-rule notation for readability ©

Each theory $\mathbb T$ defines a declarative type system, with main judgment $\Gamma \vdash t : T$

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$$A: Ty \qquad x: Tm(A) \vdash B: Ty$$

$$\frac{x: Tm(A) \vdash t: Tm(B\{x\})}{\lambda(t): Tm(\Pi(A, x.B\{x\}))} \longrightarrow$$



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$$\begin{array}{c} \mathsf{A}: \mathsf{Ty} \qquad x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B}: \mathsf{Ty} \\ \hline x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{t}: \mathsf{Tm}(\mathsf{B}\{x\}) \\ \hline \lambda(\mathsf{t}): \mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \end{array} \sim \begin{array}{c} \Gamma \vdash A: \mathsf{Ty} \qquad \Gamma, x: \mathsf{Tm}(A) \vdash B: \mathsf{Ty} \\ \hline \Gamma, x: \mathsf{Tm}(A) \vdash t: \mathsf{Tm}(B) \\ \hline \Gamma \vdash \lambda(x.t): \mathsf{Tm}(\Pi(A, x.B)) \end{array} \\ \hline \\ \mathsf{A}: \mathsf{Ty} \qquad x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B}: \mathsf{Ty} \\ \hline \underbrace{\mathsf{t}: \mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \quad \mathsf{u}: \mathsf{Tm}(\mathsf{A})}_{\bigoplus (\mathsf{t}, \mathsf{u}): \mathsf{Tm}(\mathsf{B}\{\mathsf{u}\})} \end{array} \sim \begin{array}{c} \Gamma \vdash A: \mathsf{Ty} \qquad \Gamma, x: \mathsf{Tm}(A) \vdash B: \mathsf{Ty} \\ \hline \\ \Gamma \vdash \lambda(x.t): \mathsf{Tm}(\Pi(A, x.B)) \end{array}$$

Each theory \mathbb{T} defines a declarative type system, with main judgment $\Gamma \vdash t : T$

$$\begin{array}{lll} {\rm A:Ty} & x: {\rm Tm}({\rm A}) \vdash {\rm B:Ty} \\ & x: {\rm Tm}({\rm A}) \vdash {\rm t:Tm}({\rm B}\{x\}) \\ \hline & \lambda({\rm t}): {\rm Tm}(\Pi({\rm A},x.{\rm B}\{x\})) \end{array} \\ & \overset{\Gamma \vdash A: {\rm Ty}}{\longrightarrow} \frac{\Gamma, x: {\rm Tm}(A) \vdash B: {\rm Ty}}{\Gamma, x: {\rm Tm}(A) \vdash t: {\rm Tm}(B)} \\ & \overset{\Gamma \vdash A: {\rm Ty}}{\longrightarrow} \frac{\Gamma \vdash \lambda(x.t): {\rm Tm}(\Pi(A,x.B))}{\Gamma \vdash \lambda(x.t): {\rm Tm}(\Pi(A,x.B))} \\ & \overset{\Gamma \vdash A: {\rm Ty}}{\longrightarrow} \frac{\Gamma \vdash A: {\rm Ty}}{\Gamma, x: {\rm Tm}(A) \vdash B: {\rm Ty}} \\ & \overset{\Gamma \vdash A: {\rm Ty}}{\longrightarrow} \frac{\Gamma \vdash A: {\rm Ty}}{\Gamma, x: {\rm Tm}(A) \vdash B: {\rm Ty}} \\ & \overset{\Gamma \vdash t: {\rm Tm}(\Pi(A,x.B))}{\longrightarrow} \frac{\Gamma \vdash t: {\rm Tm}(\Pi(A,x.B)) \quad \Gamma \vdash u: {\rm Tm}(A)}{\Gamma \vdash (0,t) : {\rm Tm}(B[u/x])} \end{array}$$

Each theory \mathbb{T} defines a declarative type system, with main judgment $\Gamma \vdash t : T$

Main typing rules instantiate the schematic rules of \mathbb{T} :

Note that typing terms bottom-up requires guessing *A* and *B*

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Note that typing terms bottom-up requires guessing *A* and *B*

Properties of the declarative system Weakening, substitution property, ...

Bidirectional type system

Matching modulo for recovering arguments

In bidirectional typing, we need matching modulo to recover missing arguments

$$\frac{\Gamma \vdash t \Rightarrow U \quad \dots}{\Gamma \vdash \mathbf{@}(t, u) \Rightarrow}$$

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If $\underline{\omega}(t, u)$ is well-typed (in the declarative system), for some A, B we have

$$U \equiv \operatorname{Tm}(\Pi(A, x.B\{x\}))[A/A, x.B/B]$$

but how to recover *A* and *B* from *U*?

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$$\frac{\Gamma \vdash t \Rightarrow U \quad \dots}{\Gamma \vdash \mathbf{@}(t,u) \Rightarrow}$$

If @(t, u) is well-typed (in the declarative system), for some A, B we have

$$U \equiv \operatorname{Tm}(\Pi(A, x.B\{x\}))[A/A, x.B/B]$$

but how to recover A and B from U?

Solution Given T^{P} and U, we define an algorithmic³ matching judgment

$$T^{\mathsf{P}} \prec U \leadsto \vec{x}_1.t_1/\mathsf{x}_1,...,\vec{x}_k.t_k/\mathsf{x}_k$$

that tries to compute t_1, \ldots, t_k s.t. $T^{\mathsf{P}}[\vec{x}_1.t_1/\mathsf{x}_1, \ldots, \vec{x}_k.t_k/\mathsf{x}_k] \equiv U$

 $^{^{3}}$ Decidable when U is normalizing

Not all unannotated terms can be algorithmically typed

$$\frac{?}{\Gamma \vdash \lambda(x.t) \Rightarrow ?} \dots$$

$$\frac{\Gamma \vdash \lambda(x.t) \Rightarrow ?}{\Gamma \vdash \mathbf{@}(\lambda(x.t), u) \Rightarrow ?}$$

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Limitation not specific to bidirectional typing, undecidable in general!

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Limitation not specific to bidirectional typing, undecidable in general!

Avoided by defining bidirectional typing only for *inferrable* and *checkable* terms.

$$t^{i}, u^{i} ::= x \mid d(t^{i}, \vec{x}_{1}.u_{1}^{c}, ..., \vec{x}_{k}.u_{k}^{c})$$

$$t^{c}, u^{c} ::= c(\vec{x}_{1}.u_{1}^{c}, ..., \vec{x}_{k}.u_{k}^{c}) \mid \underline{t}^{i}$$

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Avoided by defining bidirectional typing only for *inferrable* and *checkable* terms.

$$\begin{split} t^{\mathsf{i}}, u^{\mathsf{i}} &::= x \mid d(t^{\mathsf{i}}, \vec{x}_1.u_1^{\mathsf{c}}, ..., \vec{x}_k.u_k^{\mathsf{c}}) \\ t^{\mathsf{c}}, u^{\mathsf{c}} &::= c(\vec{x}_1.u_1^{\mathsf{c}}, ..., \vec{x}_k.u_k^{\mathsf{c}}) \mid \underline{t}^{\mathsf{i}} \end{split}$$

Principal argument of a destructor can only be variable or another destructor.

Not all unannotated terms can be algorithmically typed

$$\frac{?}{\Gamma \vdash \lambda(x.t) \Rightarrow ?} \dots$$

$$\frac{\Gamma \vdash \lambda(x.t) \Rightarrow ?}{\Gamma \vdash (\partial \lambda(x.t), u) \Rightarrow ?}$$

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$$t^{i}, u^{i} ::= x \mid d(t^{i}, \vec{x}_{1}.u_{1}^{c}, ..., \vec{x}_{k}.u_{k}^{c})$$

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Principal argument of a destructor can only be variable or another destructor.

For most theories: t^c , u^c , ... = normal forms

Each \mathbb{T} defines a bidirectional system. Main judgments: $\Gamma \vdash t^c \Leftarrow T$ and $\Gamma \vdash t^i \Rightarrow T$

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⁴Given t^i or u^c , I write $\lceil t^i \rceil$ or $\lceil u^c \rceil$ for the underlying regular term.

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The main typing rules instantiate the schematic rules of \mathbb{T} :⁴

$$A: Ty \qquad x: Tm(A) \vdash B: Ty$$

$$\frac{x: Tm(A) \vdash t: Tm(B\{x\})}{\lambda(x.t\{x\}): Tm(\Pi(A, x.B\{x\}))} \sim$$



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$$\frac{\mathsf{A}: \mathsf{Ty} \qquad x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B}: \mathsf{Ty}}{x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{t}: \mathsf{Tm}(\mathsf{B}\{x\})}$$
$$\frac{\lambda(x.\mathsf{t}\{x\}): \mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\}))}{\lambda(x.\mathsf{t}\{x\}): \mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\}))}$$

$$\frac{\operatorname{Tm}(\Pi(A, x.B\{x\})) < T \leadsto A/A, \ x.B/B}{\Gamma, x : \operatorname{Tm}(A) \vdash t^{c} \Leftarrow \operatorname{Tm}(B)}$$
$$\Gamma \vdash \lambda(x.t^{c}) \Leftarrow T$$

 $[\]sim$

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$$A: Ty \qquad x: Tm(A) \vdash B: Ty \\ \frac{x: Tm(A) \vdash t: Tm(B\{x\})}{\lambda(x.t\{x\}): Tm(\Pi(A, x.B\{x\}))} \qquad \sim \qquad \frac{Tm(\Pi(A, x.B\{x\})) < T \leadsto A/A, \ x.B/B}{\Gamma, x: Tm(A) \vdash t^c \Leftarrow Tm(B)} \\ \frac{\Gamma, x: Tm(A) \vdash t^c \Leftarrow Tm(B)}{\Gamma \vdash \lambda(x.t^c) \Leftarrow T}$$

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$$\begin{array}{lll} \mathsf{A}: \mathsf{Ty} & x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B}: \mathsf{Ty} \\ & \frac{x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{t}: \mathsf{Tm}(\mathsf{B}\{x\})}{\lambda(x.\mathsf{t}\{x\}): \mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\}))} & \leadsto & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma, x: \mathsf{Tm}(A) \vdash t^c \Leftarrow \mathsf{Tm}(B)} \\ & \frac{\Gamma, x: \mathsf{Tm}(A) \vdash t^c \Leftarrow \mathsf{Tm}(B)}{\Gamma \vdash \lambda(x.t^c) \Leftarrow T} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{t}^i \Rightarrow T} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec \mathsf{Tm}(\mathsf{B}\{\mathsf{u}\})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(A)} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec \mathsf{Tm}(\mathsf{B}\{\mathsf{u}\})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \dashv \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \dashv \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \dashv \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \dashv \mathsf{Tm}(\mathsf{A})}{\Gamma \vdash \mathsf{u}^c \Leftrightarrow \mathsf{Tm}(\mathsf{A})} \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{$$

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Each \mathbb{T} defines a bidirectional system. Main judgments: $\Gamma \vdash t^c \Leftarrow T$ and $\Gamma \vdash t^i \Rightarrow T$

The main typing rules instantiate the schematic rules of \mathbb{T}^{4} :

$$\begin{array}{ll} \mathsf{A}: \mathsf{Ty} & x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B}: \mathsf{Ty} \\ \hline x: \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{t}: \mathsf{Tm}(\mathsf{B}\{x\}) \\ \hline \lambda(x.\mathsf{t}\{x\}): \mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \end{array} \sim \\ & \frac{\mathsf{Tm}(\Pi(\mathsf{A}, x.\mathsf{B}\{x\})) \prec T \leadsto A/\mathsf{A}, \ x.B/\mathsf{B}}{\Gamma, x: \mathsf{Tm}(A) \vdash t^{\mathsf{c}} \Leftarrow \mathsf{Tm}(B)} \\ \hline \Gamma \vdash \lambda(x.t^{\mathsf{c}}) \Leftarrow T \\ \hline \end{array}$$

$$\Gamma \vdash t^{i} \Rightarrow T$$

$$A : Ty \qquad x : Tm(A) \vdash B : Ty$$

$$t : Tm(\Pi(A, x.B\{x\})) \quad u : Tm(A)$$

$$@(t, u) : Tm(B\{u\})$$

$$Tm(\Pi(A, x.B\{x\})) < T \Rightarrow A/A, x.B/B$$

$$\Gamma \vdash u^{c} \Leftarrow Tm(A)$$

$$\Gamma \vdash @(t^{i}, u^{c}) \Rightarrow Tm(B[\Gamma u^{c} \Gamma / x])$$

Note that no more need to guess *A* and *B*!

⁴Given t^{\dagger} or u^{c} , I write $^{\dagger}t^{\dagger}$ or $^{\dagger}u^{c}$ for the underlying regular term.

(Suppose underlying theory \mathbb{T} is *valid*)

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Soundness If $\Gamma \vdash$ and $\Gamma \vdash t^{\mathsf{i}} \Rightarrow T$ then $\Gamma \vdash \ulcorner t^{\mathsf{i}} \urcorner : T$ If $\Gamma \vdash T$ sort and $\Gamma \vdash t^{\mathsf{c}} \Leftarrow T$ then $\Gamma \vdash \ulcorner t^{\mathsf{c}} \urcorner : T$

(Suppose underlying theory \mathbb{T} is *valid*)

Soundness If
$$\Gamma \vdash$$
 and $\Gamma \vdash t^{\mathsf{i}} \Rightarrow T$ then $\Gamma \vdash \ulcorner t^{\mathsf{i}} \urcorner : T$
If $\Gamma \vdash T$ sort and $\Gamma \vdash t^{\mathsf{c}} \Leftarrow T$ then $\Gamma \vdash \ulcorner t^{\mathsf{c}} \urcorner : T$

Completeness If
$$\Gamma \vdash \lceil t^{i} \rceil : T$$
 then $\Gamma \vdash t^{i} \Rightarrow U$ with $T \equiv U$ If $\Gamma \vdash \lceil t^{c} \rceil : T$ then $\Gamma \vdash t^{c} \Leftarrow T$

(Suppose underlying theory \mathbb{T} is *valid*)

Soundness If
$$\Gamma \vdash$$
 and $\Gamma \vdash t^{\mathsf{i}} \Rightarrow T$ then $\Gamma \vdash {}^{\mathsf{r}}t^{\mathsf{i}} \urcorner : T$ If $\Gamma \vdash T$ sort and $\Gamma \vdash t^{\mathsf{c}} \Leftarrow T$ then $\Gamma \vdash {}^{\mathsf{r}}t^{\mathsf{c}} \urcorner : T$

Completeness If
$$\Gamma \vdash \lceil t^{i} \rceil : T$$
 then $\Gamma \vdash t^{i} \Rightarrow U$ with $T \equiv U$ If $\Gamma \vdash \lceil t^{c} \rceil : T$ then $\Gamma \vdash t^{c} \Leftarrow T$

Decidability If $\mathbb T$ normalizing, then inference is decidable for inferable terms, and checking is decidable for checkable terms

(Suppose underlying theory \mathbb{T} is *valid*)

Soundness If
$$\Gamma \vdash$$
 and $\Gamma \vdash t^{\mathsf{i}} \Rightarrow T$ then $\Gamma \vdash {}^{\mathsf{r}}t^{\mathsf{i}} \urcorner : T$ If $\Gamma \vdash T$ sort and $\Gamma \vdash t^{\mathsf{c}} \Leftarrow T$ then $\Gamma \vdash {}^{\mathsf{r}}t^{\mathsf{c}} \urcorner : T$

Completeness If
$$\Gamma \vdash \lceil t^{i} \rceil : T$$
 then $\Gamma \vdash t^{i} \Rightarrow U$ with $T \equiv U$ If $\Gamma \vdash \lceil t^{c} \rceil : T$ then $\Gamma \vdash t^{c} \Leftarrow T$

Decidability If $\mathbb T$ normalizing, then inference is decidable for inferable terms, and checking is decidable for checkable terms

Not shown for one particular theory, but for all instances of our framework

More examples

Dependent sums

Extends $\mathbb{T}_{\lambda\Pi}$ with

$$\begin{array}{lll} & \text{A}: \text{Ty} & x: \text{Tm}(A) \vdash B: \text{Ty} \\ \hline & \Sigma(A, x.B\{x\}): \text{Ty} & \frac{\text{t}: \text{Tm}(A) & \text{u}: \text{Tm}(B\{t\})}{\text{pair}(\texttt{t}, \texttt{u}): \text{Tm}(\Sigma(A, x.B\{x\}))} \\ & \text{A}: \text{Ty} & x: \text{Tm}(A) \vdash B: \text{Ty} \\ & \text{t}: \text{Tm}(\Sigma(A, x.B\{x\})) & \text{t}: \text{Tm}(\Sigma(A, x.B\{x\})) \\ \hline & \text{proj}_1(\texttt{t}): \text{Tm}(A) & \text{proj}_2(\texttt{t}): \text{Tm}(B\{\text{proj}_1(\texttt{t})\}) \\ & \text{proj}_1(\text{pair}(\texttt{t}, \texttt{u})) \longmapsto \texttt{t} & \text{proj}_2(\text{pair}(\texttt{t}, \texttt{u})) \longmapsto \texttt{u} \end{array}$$

Lists

Extends $\mathbb{T}_{\lambda\Pi}$ with

```
A : Tv
                             A : Tv
                                                      1: Tm(List(A))
   List(A) : Tv
                       nil : Tm(List(A))
                                                 cons(x, 1) : Tm(List(A))
         1: Tm(List(A)) x: Tm(List(A)) \vdash P: Ty pnil: Tm(P\{nil\})
A : Tv
  x : Tm(A), y : Tm(List(A)), z : Tm(P\{y\}) \vdash pcons : Tm(P\{cons(x, y)\})
          ListRec(1, x.P\{x\}, pnil, xyz.pcons\{x, y, z\}) : Tm(P\{1\})
       ListRec(nil, x.P{x}, pnil, xyz.pcons{x, y, z}) \longmapsto pnil
       ListRec(cons(x, 1), x.P{x}, pnil, xyz.pcons{x, y, z}) \longmapsto
            pcons\{x, 1, ListRec(1; x.P\{x\}, pnil, xyz.pcons\{x, y, z\})\}
```

W types

W types capture a class of inductive types

Extends $\mathbb{T}_{\lambda\Pi}$ with

$$\frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{W}(\mathsf{A}, x.\mathsf{B}\{x\}) : \mathsf{Ty}} \qquad \frac{\mathsf{a} : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{sup}(\mathsf{a}, \mathsf{f}) : \mathsf{Tm}(\mathsf{\Pi}(\mathsf{B}\{\mathsf{a}\}, _.\mathsf{W}(\mathsf{A}, x.\mathsf{B}\{x\})))} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{sup}(\mathsf{a}, \mathsf{f}) : \mathsf{Tm}(\mathsf{W}(\mathsf{A}, x.\mathsf{B}\{x\}))} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{sup}(\mathsf{a}, \mathsf{f}) : \mathsf{Tm}(\mathsf{W}(\mathsf{A}, x.\mathsf{B}\{x\}))} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{a}, \mathsf{f}) : \mathsf{Tm}(\mathsf{W}(\mathsf{A}, x.\mathsf{B}\{x\}))} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\}))} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{A}) \vdash \mathsf{B} : \mathsf{Ty}}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})} \\ = \frac{\mathsf{A} : \mathsf{Ty} \qquad x : \mathsf{Tm}(\mathsf{M}(\mathsf{A}, x.\mathsf{B}\{x\}))}{\mathsf{sup}(\mathsf{A}, x.\mathsf{B}\{x\})}$$

WRec(sup(a, f), x.P{x}, xyz.p{x, y, z}) \longmapsto p{a, f, λ (x.WRec(\emptyset (f, x), x.P{x}, xyz.p{x, y, z}))}

24

Higher-Order Logic

Extends $\mathbb{T}_{\lambda\Pi}$ with

$$\frac{t : Tm(Prop)}{Prop : Ty}$$

$$\frac{t : Tm(Prop)}{Prf(t) sort}$$

We can then add, for instance, universal quantification:

Other examples

In the implementation at

https://github.com/thiagofelicissimo/BiTTs

you can also find:

- Indexed types: Equality, Vectors, etc
- Tarski-, Russell- and Coquand-style universes, with/without cumulativity and universe polymorphism
- Flavous of Observational Type Theory
- A variant of Exceptional Type Theory (type theory with exceptions)



We have given a generic account of bidirectional typing for a class of type theories

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Thank you for your attention!

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