# Generic Bidirectional Typing for Dependent Type Theories 

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Syntax so common that many don't realize that an omission is being made

## Typechecking without annotations

Omission has a cost Knowing annotations is needed for typing

$$
\begin{gathered}
\Gamma \vdash A \text { type } \quad \Gamma, x: A \vdash B \text { type } \quad \Gamma \vdash t: \Pi x: A . B \quad \Gamma \vdash u: A \\
\hline \Gamma \vdash t u: B[u / x]
\end{gathered}
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How to find $A$ and $B$ if they're not stored in syntax?

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Allow specify flow of type information in typing rules, explain how to use them

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\begin{array}{lll}
\Gamma \vdash t \Rightarrow C & C \longrightarrow{ }^{*} \Pi x: A \cdot B & \Gamma \vdash u \Leftarrow A \\
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Complements unannotated syntax, locally explains how to recover annotations

## Contribution

Bidirectional type systems have been studied and proposed for many theories
However, general guidelines have remained informal, no unified framework

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1. We give a general definition of type theories (or equivalently, a logical framework) supporting non-annotated syntaxes

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1. We give a general definition of type theories (or equivalently, a logical framework) supporting non-annotated syntaxes
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## Roadmap

1. We give a general definition of type theories (or equivalently, a logical framework) supporting non-annotated syntaxes
2. For each theory, we define declarative and bidirectional type systems
3. We show, in a theory-independent fashion, their equivalence

## BiTTs: A theory-independent bidirectional type-checker

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Our framework not only of theoretic interest, can also have practical applications Implemented in the theory-independent bidirectional type-checker BiTTs

```
constructor List () (A : Ty) : Ty
constructor nil (A : Ty) () : Tm(List(A))
constructor cons (A : Ty) (a : Tm(A), l : Tm(List(A))) : Tm(List(A))
destructor ind_List (A : Ty) [l : Tm(List(A))] (P {x : Tm(List(A))} : Ty, l_nil : Tm(P{nil}),
    l_cons {a : Tm(A), l : Tm(List(A)), pl : Tm(P{l})}: Tm}(P{\operatorname{cons(a,l)}))
    : Tm(P{l})
equation ind_List(nil, l. P{l}, l_nil, a l pl. l_cons{a, l, pl}) --> l_nil
equation ind_List(cons(a, l), l. P{l}, l_nil, a l pl. l_cons{a, l, pl}) -->
    l_cons{a, l, ind_List(l, l. P{l}, l_nil, a l pl. l_cons{a, l, pl})}
let 0::1::2::3::nil : Tm(List(\mathbb{N})) := cons(0, cons(S(0), cons(S(S(0)), cons(S(S(S(0))), nil))))
let sum_of_list : Tm(\Pi(List(\mathbb{N}), _. NN)) := \lambda(l. ind_List(l, _. N, 0, x _ acc. @(@ (+, x), acc)))
assert @(sum_of_list, 0::1::2::3::nil) = S(S(S(S(S(S(0))))))
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Many theories supported: flavours of MLTT, HOL, etc (see the implementation)

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Many theories supported: flavours of MLTT, HOL, etc (see the implementation)
Compared with other theory-independent type-checkers (Dedukti, Andromeda) non-annotated syntax should allow for better performances

## The theories

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Used to represent the judgment forms of the theory (as in GATs, SOGATs, ...)

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Example: In MLTT, 2 judgment forms: $\square$ type and $\square: A$ for a type $A$
$\overline{\text { Ty sort }} \quad \frac{A: \text { Ty }}{\operatorname{Tm}(A) \text { sort }}$

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Formally, of the form $c(\Theta)$ sort, with $\Theta$ metavariable context representing premises
Example in formal notation: $\mathrm{Ty}(\cdot)$ sort and $\operatorname{Tm}(\mathrm{A}: \mathrm{Ty})$ sort

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$$

$$
\begin{gathered}
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\frac{x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{t}: \operatorname{Tm}(\mathrm{B}\{x\})}{\lambda(x . \mathrm{t}\{x\}): \operatorname{Tm}(\Pi(\mathrm{A}, x \cdot \mathrm{~B}\{x\}))}
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$$

Formally, constructor rules of the form $c\left(\Theta_{1} ; \Theta_{2}\right): U^{\mathrm{P}}$, with $U^{\mathrm{P}}$ pattern on $\Theta_{1}$
Example in formal notation: $\Pi(\cdot ; \mathrm{A}: \mathrm{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \mathrm{Ty}):$ Ty and $\lambda(A: \operatorname{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty} ; \mathrm{t}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Tm}(\mathrm{B}\{x\})): \operatorname{Tm}(\Pi(\mathrm{A}, x \cdot \mathrm{~B}\{x\}))$

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Formally, of the form $d\left(\Theta_{1} ; \mathrm{x}: T^{\mathrm{P}} ; \Theta_{2}\right): U$, with $T^{\mathrm{P}}$ a pattern on $\Theta_{1}$ Example in formal notation:
@ (A:Ty, $\mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty} ; \mathrm{t}: \operatorname{Tm}(\Pi(\mathrm{A}, x \cdot \mathrm{~B}\{x\})) ; \mathrm{u}: \operatorname{Tm}(\mathrm{A})): \operatorname{Tm}(\mathrm{B}\{\mathrm{u}\})$

## The theories

Rewrite rules Specify the definitional equality (aka conversion) $\equiv$ of the theory

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@(\lambda(x . \mathrm{t}\{x\}), \mathrm{u}) \longmapsto \mathrm{t}\{\mathrm{u}\}
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In general, of the form $d\left(\mathbf{t}^{\mathrm{P}}\right) \longmapsto r$

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Full example Theory $\mathbb{T}_{\lambda \Pi}$

$$
\begin{aligned}
& \operatorname{Ty}(\cdot) \text { sort } \quad \operatorname{Tm}(A: \operatorname{Ty}) \text { sort } \quad \Pi(\cdot ; \mathrm{A}: \operatorname{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty}): \operatorname{Ty} \\
& \lambda(\mathrm{A}: \operatorname{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty} ; \mathrm{t}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Tm}(\mathrm{B}\{x\})): \operatorname{Tm}(\Pi(\mathrm{A}, x \cdot \mathrm{~B}\{x\})) \\
& @(\mathrm{~A}: \operatorname{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty} ; \mathrm{t}: \operatorname{Tm}(\Pi(\mathrm{A}, x \cdot \mathrm{~B}\{x\})) ; \mathrm{u}: \operatorname{Tm}(\mathrm{A})): \operatorname{Tm}(\mathrm{B}\{\mathrm{u}\}) \\
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\begin{aligned}
& \text { Dest } \\
& d\left(\Xi_{1} ; \mathrm{x}: T ; \Xi_{2}\right): U \in \mathbb{T} \frac{\Theta ; \Gamma \vdash \mathbf{t}, t, \mathbf{u}: \Xi_{1} \cdot(\mathrm{x}: T) \cdot \Xi_{2}}{\Theta ; \Gamma \vdash d(t, \mathbf{u}): U[\mathbf{t}, t, \mathbf{u}]}
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\Theta ; \Gamma \vdash \quad \Theta ; \Gamma \vdash A: \operatorname{Ty} \quad \Theta ; \Gamma, x: \operatorname{Tm}(A) \vdash B: \operatorname{Ty} \\
\begin{array}{c}
\Theta ; \Gamma \vdash t: \operatorname{Tm}(\Pi(A, x . B)) \quad \Theta ; \Gamma \vdash u: \operatorname{Tm}(A) \\
\Theta ; \Gamma \vdash @(t, u): \operatorname{Tm}(B[u / x])
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\end{gathered}
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(for @(A: $\left.\operatorname{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty} ; \mathrm{t}: \operatorname{Tm}(\Pi(\mathrm{A}, x . \mathrm{B}\{x\})) ; \mathrm{u}: \operatorname{Tm}(\mathrm{A})): \operatorname{Tm}(\mathrm{B}\{\mathrm{u}\}) \in \mathbb{T}_{\text {又 }}\right)$

## Declarative type system

Each theory $\mathbb{T}$ defines a declarative type system, with main judgment $\Theta ; \Gamma \vdash t: T$ Main typing rules instantiate the schematic rules of $\mathbb{T}$ :

$$
\begin{array}{cc}
\Theta ; \Gamma \vdash & \Theta ; \Gamma \vdash A: \operatorname{Ty}
\end{array} \quad \Theta ; \Gamma, x: \operatorname{Tm}(A) \vdash B: \operatorname{Ty} .
$$

$$
\Theta ; \Gamma \vdash @(t, u): \operatorname{Tm}(B[u / x])
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\Theta ; \Gamma \vdash t: \operatorname{Tm}(\Pi(A, x \cdot B)) \quad \Theta ; \Gamma \vdash u: \operatorname{Tm}(A) \\
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Reading bottom-up, requires guessing $A$ and $B$

Properties of the declarative system Weakening, substitution property, sorts are well-typed, subject reduction, etc (see the paper)

Bidirectional typing system

## Matching modulo rewriting

In bidirectional typing, we need matching modulo to recover missing arguments.

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If @ $(t, u)$ is well-typed (in the declarative system), for some $A, B$ we have

$$
U \equiv \operatorname{Tm}(\Pi(\mathrm{~A}, x \cdot \mathrm{~B}\{x\}))[A / \mathrm{A}, x . B / \mathrm{B}]
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Solution We define an algorithmic ${ }^{2}$ matching judgment $T^{P}<U \leadsto \mathbf{v}$
We have $T^{\mathrm{P}}[\mathbf{v}] \equiv U$ iff $T^{\mathrm{P}}<U \leadsto \mathbf{v}^{\prime}$ for some $\mathbf{v}^{\prime} \equiv \mathbf{v}$

[^3]
## Bidirectional syntax

Not all unannotated terms can be algorithmically typed

$$
\frac{?}{\Gamma \vdash \lambda(x . t) \Rightarrow ?} \frac{\ldots}{\Gamma \vdash @(\lambda(x . t), u) \Rightarrow ?}
$$

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$$

Avoided by defining bidirectional system only for inferrable and checkable terms

$$
\begin{array}{ll}
\operatorname{Tm}^{\mathrm{i}} \ni & t^{\mathrm{i}}, u^{\mathrm{i}}::=x \mid d\left(t^{\mathrm{i}}, \mathbf{t}^{\mathrm{c}}\right) \\
\mathrm{Tm}^{\mathrm{c}} \ni & t^{\mathrm{c}}, u^{\mathrm{c}}::=c\left(\mathbf{t}^{\mathrm{c}}\right) \mid t^{\mathrm{i}} \\
\text { MSub }^{\mathrm{c}} \ni & \mathbf{t}^{\mathrm{c}}, \mathbf{u}^{\mathrm{c}}::=\epsilon \mid \mathbf{t}^{\mathrm{c}}, \vec{x} \cdot t^{\mathrm{c}}
\end{array}
$$

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\end{array}
$$

Principal argument of a destructor can only be variable or another destructor For most theories, $t^{c}, u^{c}, \ldots$ are the normal forms

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Each $\mathbb{T}$ defines a bidirectional system. Main judgments: $\Gamma \vdash t^{c} \Leftarrow T$ and $\Gamma \vdash t^{i} \Rightarrow T$

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$$
\begin{gathered}
\begin{array}{c}
\text { DeST } \\
\Gamma \vdash t^{\mathrm{i}} \Rightarrow T^{\prime} \\
d \prec T^{\prime} \leadsto \mathbf{v} \\
d\left(\Xi_{1} ; \mathrm{t}: T ; \Xi_{2}\right): U \in \mathbb{T} \frac{\Gamma \mid\left(\mathbf{v},\left\ulcorner t^{\mathrm{i}}\right\urcorner\right):\left(\Xi_{1}, \mathrm{x}: T\right) \vdash \mathbf{u}^{\mathrm{c}} \Leftarrow \Xi_{2}}{\Gamma \vdash d\left(t^{\mathrm{i}}, \mathbf{u}^{\mathrm{c}}\right) \Rightarrow U\left[\mathbf{v},\left\ulcorner t^{\mathrm{i}}\right\urcorner,\left\ulcorner\mathbf{u}^{\mathrm{c}}\right\urcorner\right]}
\end{array} . \begin{array}{c} 
\\
\Gamma
\end{array}
\end{gathered}
$$

${ }^{3}$ Given $t^{i}$ or $u^{c}$, I write $\left\ulcorner t^{i}\right\urcorner$ or $\left\ulcorner u^{c}\right\urcorner$ for the underlying regular term.

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$$
\frac{\Gamma \vdash t^{\mathrm{i}} \Rightarrow T^{\prime} \quad \operatorname{Tm}(\Pi(\mathrm{A}, x . \mathrm{B}\{x\}))<T^{\prime} \leadsto A / \mathrm{A}, x \cdot B / \mathrm{B} \quad \Gamma \vdash u^{\mathrm{c}} \Leftarrow \operatorname{Tm}(A)}{\Gamma \vdash @\left(t^{\mathrm{i}}, u^{\mathrm{c}}\right) \Rightarrow \operatorname{Tm}\left(B\left[\left\ulcorner u^{\mathrm{c}}\right\urcorner / x\right]\right)}
$$



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(for @ $(\mathrm{A}: \operatorname{Ty}, \mathrm{B}\{x: \operatorname{Tm}(\mathrm{A})\}: \operatorname{Ty} ; \mathrm{t}: \operatorname{Tm}(\Pi(\mathrm{A}, x \cdot \mathrm{~B}\{x\})) ; \mathrm{u}: \operatorname{Tm}(\mathrm{A})): \operatorname{Tm}(\mathrm{B}\{\mathrm{u}\}) \in \mathbb{T}_{\lambda}$ )
Reading bottom-up, no more need to guess $A$ and $B$ !
${ }^{3}$ Given $t^{i}$ or $u^{c}$, I write $\left\ulcorner t^{i}\right\urcorner$ or $\left\ulcorner u^{c}\right\urcorner$ for the underlying regular term.

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Suppose underlying theory $\mathbb{T}$ is valid

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Completeness If $\Gamma \vdash\left\ulcorner t^{i}\right\urcorner: T$ then $\Gamma \vdash t^{i} \Rightarrow T^{\prime}$ with $T^{\prime} \equiv T$
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If $\Gamma \vdash\left\ulcorner t^{c}\right\urcorner: T$ then $\Gamma \vdash t^{c} \Leftarrow T$
Decidability If $\mathbb{T}$ normalizing, then inference is decidable for inferable terms, and checking is decidable for checkable terms

## More examples

## Dependent sums

Extends $\mathbb{T}_{\lambda \Pi}$ with

$$
\begin{gathered}
\frac{\mathrm{A}: \operatorname{Ty} \quad x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{B}: \operatorname{Ty}}{\sum(\mathrm{A}, x \cdot \mathrm{~B}\{x\}): \operatorname{Ty}} \\
\frac{\mathrm{A}: \operatorname{Ty} \quad x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{B}: \operatorname{Ty}}{\mathrm{t}: \operatorname{Tm}(\Sigma(\mathrm{A}, x \cdot \mathrm{~B}\{x\}))} \\
\operatorname{proj}_{1}(\mathrm{t}): \operatorname{Tm}(\mathrm{A}) \\
\operatorname{proj}_{1}(\operatorname{pair}(\mathrm{t}, \mathrm{u})) \longmapsto \mathrm{t}
\end{gathered}
$$

$$
\begin{aligned}
& \mathrm{A}: \operatorname{Ty} \quad x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{B}: \operatorname{Ty} \\
& \mathrm{t}: \operatorname{Tm}(\mathrm{A}) \quad \mathrm{u}: \operatorname{Tm}(\mathrm{B}\{\mathrm{t}\}) \\
& \hline \operatorname{pair}(\mathrm{t}, \mathrm{u}): \operatorname{Tm}(\Sigma(\mathrm{A}, x \cdot \mathrm{~B}\{x\}))
\end{aligned}
$$

## Lists

Extends $\mathbb{T}_{\lambda \Pi}$ with


## W types

Extends $\mathbb{T}_{\lambda \Pi}$ with

$$
\begin{aligned}
& \text { A: Ty } \quad x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{B}: \operatorname{Ty} \\
& \mathrm{A}: \operatorname{Ty} \quad x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{B}: \operatorname{Ty} \quad \mathrm{a}: \operatorname{Tm}(\mathrm{A}) \quad \mathrm{f}: \operatorname{Tm}\left(\Pi\left(\mathrm{B}\{\mathrm{a}\},{ }_{-} . \mathrm{W}(\mathrm{~A}, x . \mathrm{B}\{x\})\right)\right) \\
& \mathrm{W}(\mathrm{~A}, x . \mathrm{B}\{x\}): \mathrm{Ty} \\
& \sup (\mathrm{a}, \mathrm{f}): \operatorname{Tm}(\mathrm{W}(\mathrm{~A}, x . \mathrm{B}\{x\})) \\
& \mathrm{A}: \operatorname{Ty} \quad x: \operatorname{Tm}(\mathrm{A}) \vdash \mathrm{B}: \operatorname{Ty} \quad \mathrm{t}: \operatorname{Tm}(\mathrm{W}(\mathrm{~A}, x \cdot \mathrm{~B}\{x\})) \quad x: \operatorname{Tm}(\mathrm{W}(\mathrm{~A}, x . \mathrm{B}\{x\}))+\mathrm{P}: \operatorname{Ty} \\
& x: \operatorname{Tm}(\mathrm{A}), y: \operatorname{Tm}\left(\Pi\left(\mathrm{B}\{x\}, x^{\prime} \cdot \mathrm{W}(\mathrm{~A}, x \cdot \mathrm{~B}\{x\})\right)\right), z: \operatorname{Tm}\left(\Pi\left(\mathrm{B}\{x\}, x^{\prime} . \mathrm{P}\left\{@\left(y, x^{\prime}\right)\right\}\right)\right) \vdash \mathrm{p}: \operatorname{Tm}(\mathrm{P}\{\sup (x, y)\}) \\
& \operatorname{WRec}(\mathrm{t}, x . \mathrm{P}\{x\}, x y z . \mathrm{p}\{x, y, z\}): \operatorname{Tm}(\mathrm{P}\{\mathrm{t}\})
\end{aligned}
$$

$\operatorname{WRec}(\sup (\mathrm{a}, \mathrm{f}), x . \mathrm{P}\{x\}, x y z . \mathrm{p}\{x, y, z\}) \longmapsto \mathrm{p}\{\mathrm{a}, \mathrm{f}, \lambda(x . \mathrm{WRec}(@(\mathrm{f}, x), x . \mathrm{P}\{x\}, x y z . \mathrm{p}\{x, y, z\}))\}$

## Universes

Extends $\mathbb{T}_{\lambda \Pi}$ with
$\overline{U: T y} \quad \frac{a: \operatorname{Tm}(\mathrm{U})}{\mathrm{El}(\mathrm{a}): \mathrm{Ty}}$

## (Weak) Coquand-style

Tarski-style Adds codes for all types

$$
\overline{\mathrm{u}: \operatorname{Tm}(\mathrm{U})} \quad \mathrm{El}(\mathrm{u}) \longmapsto \mathrm{U}
$$

$$
\begin{aligned}
& \frac{\mathrm{a}: \operatorname{Tm}(\mathrm{U}) \quad x: \operatorname{Tm}(\mathrm{El}(\mathrm{a})) \vdash \mathrm{b}: \operatorname{Tm}(\mathrm{U})}{\pi(\mathrm{a}, x \cdot \mathrm{~b}\{x\}): \operatorname{Tm}(\mathrm{U})} \\
& \mathrm{El}(\pi(\mathrm{a}, x \cdot \mathrm{~b}\{x\})) \longmapsto \Pi(\mathrm{El}(\mathrm{a}), x \cdot \mathrm{El}(\mathrm{~b}\{x\}))
\end{aligned}
$$

$$
\frac{A: \operatorname{Ty}}{c(A): \operatorname{Tm}(U)}
$$

$$
\mathrm{El}(\mathrm{c}(\mathrm{~A})) \longmapsto \mathrm{A}
$$

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1. Support ascriptions in the bidirectional system

$$
@(\lambda(x . t):: T, u)
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2. Handling indexed inductive types

$$
\frac{\mathrm{A}: \operatorname{Ty} \quad \mathrm{t}: \operatorname{Tm}(\mathrm{A})}{\text { refl }: \operatorname{Tm}(\mathrm{Eq}(\mathrm{~A}, \mathrm{t}, \mathrm{t}))}
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$$

3. Type-directed equalities ( $\eta$-rules, proof irrelevance), generically? Alternatively, treat conversion with a black-box approach

Thank you for your attention!


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[^3]:    ${ }^{2}$ Decidable when $U$ is normalizing

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