# Adequate and Computational Encodings in the Logical Framework Dedukti 

Thiago Felicissimo

Formal Structures for Computation and Deduction 2022, Haifa
August 4, 2022

## Logical Frameworks \& Dedukti

## Logical Frameworks

Each year, more and more new type theories and systems are proposed Hard to see how they all relate

Logical Frameworks address this heterogeneity
A common foundation for defining type theories and logics
Of theoretical interest (decomposing and comparing theories) and practical one (prototyping developments, checking proofs)

## Dedukti

Edinburgh Logical Framework (LF) Historically, very influential framework It's just the $\lambda$-calculus with dependent types! (also known as $\lambda \Pi$-calculus)

Dependent types allow to express deduction!
But computation can only be expressed as deduction...

$$
\pi_{1}(M, N) \hookrightarrow_{\beta_{\pi_{1}}} M \quad \rightsquigarrow \quad \beta_{\pi_{1}}: e q\left(\pi_{1} \llbracket M \rrbracket \llbracket N \rrbracket\right) \llbracket M \rrbracket
$$

## Dedukti

Edinburgh Logical Framework (LF) Historically, very influential framework It's just the $\lambda$-calculus with dependent types! (also known as $\lambda \Pi$-calculus)
Dependent types allow to express deduction!
But computation can only be expressed as deduction...

$$
\pi_{1}(M, N) \hookrightarrow_{\beta_{\pi_{1}}} M \quad \rightsquigarrow \quad \beta_{\pi_{1}}: e q\left(\pi_{1} \llbracket M \rrbracket \llbracket N \rrbracket\right) \llbracket M \rrbracket
$$

Dedukti Extends LF with user-defined rewrite rules $\mathcal{R}$, typing modulo $\equiv_{\beta \mathcal{R}}$

$$
\pi_{1} M N \hookrightarrow \operatorname{beta}_{\pi_{1}} M \quad \in \mathcal{R}
$$

Handles both building blocks of modern logics: deduction and computation In practice, useful for rechecking and sharing proofs (see the EuroProofNet project)

## What is a Dedukti encoding?

A theory is a pair $(\Sigma, \mathcal{R})$ where

- $\Sigma=\{c: A, d: B, \ldots\}$ is a signature (constant declarations with their types)
- $\mathcal{R}=\{I \hookrightarrow r, \ldots\}$ is a set of rewrite rules

Used to represent object logics in Dedukti: $\mathcal{O}$ represented by $D[\mathcal{O}]=\left(\Sigma_{\mathcal{O}}, \mathcal{R}_{\mathcal{O}}\right)$

## What is a Dedukti encoding?

A theory is a pair $(\Sigma, \mathcal{R})$ where

- $\Sigma=\{c: A, d: B, \ldots\}$ is a signature (constant declarations with their types)
- $\mathcal{R}=\{I \hookrightarrow r, \ldots\}$ is a set of rewrite rules

Used to represent object logics in Dedukti: $\mathcal{O}$ represented by $D[\mathcal{O}]=\left(\Sigma_{\mathcal{O}}, \mathcal{R}_{\mathcal{O}}\right)$
An encoding of $\mathcal{O}$ : a theory $D[\mathcal{O}]$ and a translation function $\llbracket-\rrbracket: \Lambda_{\mathcal{O}} \rightarrow \Lambda_{\mathrm{DK}}$

## An hierarchy of encodings

An encoding is sound if:

$$
\vdash_{\mathcal{O}} M: A \quad \text { implies } \quad \vdash_{\mathrm{DK}} \llbracket M \rrbracket: E l \llbracket A \rrbracket
$$

An encoding is conservative if:

$$
\vdash_{\mathrm{DK}} M: E l \llbracket A \rrbracket \text { implies } \exists N \text { s.t. } \vdash_{\mathcal{O}} N: A
$$

An encoding is adequate if for each type $A$ :
$\llbracket-\rrbracket$ is a bijection between $A$ and $E / \llbracket A \rrbracket$


## The problem of conservativity and adequacy

Unlike with LF encodings, Dedukti encodings proposed until now are not adequate Actually, just showing conservativity of Dedukti encodings is already very hard For many recently proposed encodings, still only a conjecture...

## The problem of conservativity and adequacy

Unlike with LF encodings, Dedukti encodings proposed until now are not adequate Actually, just showing conservativity of Dedukti encodings is already very hard For many recently proposed encodings, still only a conjecture...

Where does this problem come from?
The cause can actually be traced back to the first Dedukti encoding, 2007 Cousineau \& Dowek's encoding of (functional) Pure Type Systems

## The cause of the problem, in a nutshell

Cousineau \& Dowek's idea is to represent object functions by framework's functions

$$
\text { (*) EI (Prod A B) } \hookrightarrow \Pi x: E I A \cdot E I(B x)
$$

Problem To show conservativity, we need to assume that $\beta$ terminates
But because of ( $\star$ ), $\beta$ might not terminate (when it does, proof is non trivial)

## The cause of the problem, in a nutshell

Cousineau \& Dowek's idea is to represent object functions by framework's functions

$$
(\star) \quad E I(\operatorname{Prod} A B) \hookrightarrow \Pi x: E I A \cdot E I(B x)
$$

Problem To show conservativity, we need to assume that $\beta$ terminates
But because of ( $\star$ ), $\beta$ might not terminate (when it does, proof is non trivial)
This work A different encoding of (functional) Pure Type Systems, without ( $\star$ ), where $\beta$ always normalizes

Easy conservative proof and an adequacy theorem
An encoding both adequate (like in LF) and computational (like in Dedukti)

## Encoding Pure Type Systems in Dedukti

## Pure Type Systems

Pure Type Systems (or PTSs) is a class of type theories with two forms of types: dependent functions ( $\Pi x: A . B$ ) and universes (or sorts, written as $s_{1}, s_{2}, \ldots$ )

$$
\begin{aligned}
M, N, A, B::= & x \in \mathcal{V}|s \in \mathcal{S}| \Pi x: A \cdot B|\lambda x: A \cdot M| M N \\
& (\lambda x: A \cdot M) N \hookrightarrow_{\beta} M\{N / x\}
\end{aligned}
$$

Each PTS described by a specification $(\mathcal{S}, \mathcal{A}, \mathcal{R})$, where $\mathcal{S}$ is a set of sorts and $\mathcal{A} \subseteq \mathcal{S}^{2}, \mathcal{R} \subseteq \mathcal{S}^{3}$

$$
\frac{\Gamma \vdash s_{1}: s_{2}}{\Gamma}\left(s_{1}, s_{2}\right) \in \mathcal{A} \quad \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2}}{\Gamma \vdash \Pi x: A \cdot B: s_{3}}\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R}
$$

For the rest of this talk, we assume $\mathcal{A}, \mathcal{R}$ are functional

## The theory $\left(\Sigma_{P T S}, \mathcal{R}_{P T S}\right)$

## Universes

$$
\begin{array}{llr}
\Sigma_{\text {PTS }} \ni & U_{s}: \text { Type } & \text { for } s \in \mathcal{S} \\
\Sigma_{P T S} \ni & E l_{s}\left(A: U_{s}\right): \text { Type } & \text { for } s \in \mathcal{S} \\
\Sigma_{\text {PTS }} \ni & u_{s_{1}}: U_{s_{2}} & \text { for }\left(s_{1}, s_{2}\right) \in \mathcal{A} \\
\mathcal{R}_{P T S} \ni & \left.E\right|_{s_{2}} u_{s_{1}} \hookrightarrow U_{s_{1}} & \text { for }\left(s_{1}, s_{2}\right) \in \mathcal{A}
\end{array}
$$

Dependent functions (Cousineau \& Dowek)

$$
\begin{aligned}
& \Sigma_{P T S} \ni \operatorname{Prod}_{s_{1}, s_{2}}\left(A: U_{s_{1}}\right)\left(B: E I_{s_{1}} A \rightarrow U_{s_{2}}\right): U_{s_{3}} \\
& \mathcal{R}_{\text {PTS }} \ni E I_{s_{3}}\left(\operatorname{Prod}_{s_{1}, s_{2}} A B\right) \hookrightarrow \Pi x: E I_{s_{1}} A \cdot E I_{s_{2}}(B x)
\end{aligned} \quad \text { for }\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R}
$$

## The theory $\left(\Sigma_{P T S}, \mathcal{R}_{P T S}\right)$

## Universes

$$
\begin{array}{llr}
\Sigma_{\text {PTS }} \ni & U_{s}: \text { Type } & \text { for } s \in \mathcal{S} \\
\Sigma_{\text {PTS }} \ni & E I_{s}\left(A: U_{s}\right): \text { Type } & \text { for } s \in \mathcal{S} \\
\Sigma_{P T S} \ni & u_{s_{1}}: U_{s_{2}} & \text { for }\left(s_{1}, s_{2}\right) \in \mathcal{A} \\
\mathcal{R}_{P T S} \ni & E I_{s_{2}} u_{s_{1}} \longrightarrow U_{s_{1}} & \text { for }\left(s_{1}, s_{2}\right) \in \mathcal{A}
\end{array}
$$

## Dependent functions

$$
\begin{aligned}
& \Sigma_{P T S} \ni \operatorname{Prod}_{s_{1}, s_{2}}\left(A: U_{s_{1}}\right)\left(B: E I_{s_{1}} A \rightarrow U_{s_{2}}\right): U_{s_{3}} \quad \text { for }\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \\
& \Sigma_{\text {PTS }} \ni \operatorname{abs}_{s_{1}, s_{2}}\left(A: U_{s_{1}}\right)\left(B: E l_{s_{1}} A \rightarrow U_{s_{2}}\right)\left(M: \Pi x: E I_{s_{1}} A \cdot E l_{s_{2}}(B x)\right): E l_{s_{3}}\left(\operatorname{Prod}_{s_{1}, s_{2}} A B\right) \\
& \Sigma_{P T S} \ni \operatorname{app}_{s_{1}, s_{2}}\left(A: U_{s_{1}}\right)\left(B: E l_{s_{1}} A \rightarrow U_{s_{2}}\right)\left(M: E I_{s_{3}}\left(\operatorname{Prod}_{s_{1}, s_{2}} A B\right)\right)\left(N: E l_{s_{1}} A\right): E l_{s_{2}}(B N) \\
& \mathcal{R}_{P T S} \ni \operatorname{app}_{s_{1}, s_{2}} A B\left(a b s_{s_{1}, s_{2}} A^{\prime} B^{\prime} M\right) N \longrightarrow \text { beta }_{s_{1}, s_{2}} M N
\end{aligned}
$$

## Defining the translation function

$$
\begin{aligned}
& \llbracket x \rrbracket=x \\
& \llbracket s \rrbracket=u_{s} \\
& \llbracket \Pi x: A \cdot B \rrbracket=? \\
& \llbracket \lambda x: A \cdot M \rrbracket=? \\
& \llbracket M N \rrbracket=?
\end{aligned}
$$

## Defining the translation function

$$
\begin{aligned}
& \llbracket x \rrbracket=x \\
& \llbracket s \rrbracket=u_{s} \\
& \llbracket \sqcap x: A \cdot B \rrbracket=P r o d_{?, ?} \llbracket A \rrbracket(\lambda x \cdot \llbracket B \rrbracket) \\
& \llbracket \lambda x: A \cdot M \rrbracket=a b s_{?, ?} \llbracket A \rrbracket ?(\lambda x \cdot \llbracket M \rrbracket) \\
& \llbracket M N \rrbracket=a p p_{?, ?} ? ? \llbracket M \rrbracket \llbracket N \rrbracket
\end{aligned}
$$

## Defining the translation function

$$
\begin{aligned}
& \llbracket x \rrbracket_{\Gamma}=x \\
& \llbracket s \rrbracket_{\Gamma}=u_{s}
\end{aligned}
$$

$\llbracket \Pi x: A \cdot B \rrbracket_{\Gamma}=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma \vdash A: s_{1}$ and $\Gamma, x: A \vdash B: s_{2}$
$\llbracket \lambda x: A \cdot M \rrbracket_{\Gamma}=a b s_{?, ?} \llbracket A \rrbracket_{\Gamma} ?\left(\lambda x \cdot \llbracket M \rrbracket_{\Gamma, x: A}\right)$
$\llbracket M N \rrbracket_{\Gamma}=a p p_{?, ?} ? ? \quad \llbracket M \rrbracket_{\Gamma} \llbracket N \rrbracket_{\Gamma}$

## Defining the translation function

$$
\begin{aligned}
& \llbracket x \rrbracket_{\ulcorner }=x \\
& \llbracket s \rrbracket_{\Gamma}=u_{s}
\end{aligned}
$$

$\llbracket \Pi x: A \cdot B \rrbracket_{\Gamma}=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma \vdash A: s_{1}$ and $\Gamma, x: A \vdash B: s_{2}$
$\llbracket \lambda x: A \cdot M \rrbracket_{\Gamma}=a b s_{?, ?} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right)\left(\lambda x \cdot \llbracket M \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma, x: A \vdash M: B$
$\llbracket M N \rrbracket_{\Gamma}=a p p_{?, ?} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \llbracket M \rrbracket_{\ulcorner } \llbracket N \rrbracket_{\Gamma} \quad$ where $\Gamma \vdash M: \Pi x: A \cdot B$

## Defining the translation function

$$
\llbracket x \rrbracket_{\Gamma}=x
$$

$$
\llbracket s \rrbracket_{\Gamma}=u_{s}
$$

$\llbracket \Pi x: A \cdot B \rrbracket_{\Gamma}=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma \vdash A: s_{1}$ and $\Gamma, x: A \vdash B: s_{2}$
$\llbracket \lambda x: A \cdot M \rrbracket_{\Gamma}=a b s_{?, ?} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right)\left(\lambda x \cdot \llbracket M \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma, x: A \vdash M: B$ $\llbracket M N \rrbracket_{\Gamma}=a p p_{?, ?} \llbracket A \rrbracket_{\ulcorner }\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \llbracket M \rrbracket_{\ulcorner } \llbracket N \rrbracket_{\Gamma} \quad$ where $\Gamma \vdash M: \Pi x: A \cdot B$

Problem 1: $A, B$ not syntactically unique, thus $\llbracket M \rrbracket \subseteq \Lambda_{D K}$ instead of $\llbracket M \rrbracket \in \Lambda_{D K}$
Problem 2: Not a valid structural recursion: $A, B$ are not subterms

## Defining the translation function

$$
\llbracket x \rrbracket_{\Gamma}=x
$$

$$
\llbracket s \rrbracket_{\Gamma}=u_{s}
$$

$\llbracket \Pi x: A \cdot B \rrbracket_{\Gamma}=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma \vdash A: s_{1}$ and $\Gamma, x: A \vdash B: s_{2}$
$\llbracket \lambda x: A \cdot M \rrbracket_{\Gamma}=a b s_{?, ?} \llbracket A \rrbracket_{\Gamma}\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right)\left(\lambda x \cdot \llbracket M \rrbracket_{\Gamma, x: A}\right) \quad$ where $\Gamma, x: A \vdash M: B$
$\llbracket M N \rrbracket_{\Gamma}=a p p_{?, ?} \llbracket A \rrbracket_{\ulcorner }\left(\lambda x \cdot \llbracket B \rrbracket_{\Gamma, x: A}\right) \llbracket M \rrbracket_{\ulcorner } \llbracket N \rrbracket_{\Gamma} \quad$ where $\Gamma \vdash M: \Pi x: A \cdot B$
Problem 1: $A, B$ not syntactically unique, thus $\llbracket M \rrbracket \subseteq \Lambda_{D K}$ instead of $\llbracket M \rrbracket \in \Lambda_{D K}$
Problem 2: Not a valid structural recursion: $A, B$ are not subterms
Solution: Add the necessary data to the syntax

## Explicitly-typed Pure Type Systems (EPTS)

$$
\begin{gathered}
\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2}}{\Gamma \vdash \Pi x: A \cdot B: s_{3}} \text { Prod } \\
\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2} \quad \Gamma, x: A \vdash M: B}{\Gamma \vdash \lambda x: A \cdot M: \Pi x: A \cdot B} \text { Abs } \\
\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2} \quad \Gamma \vdash M: \Pi x: A \cdot B \quad \Gamma \vdash N: A}{\Gamma \vdash M N: B\{N / x\}} \mathrm{App}
\end{gathered}
$$

## Explicitly-typed Pure Type Systems (EPTS)

$$
\begin{gathered}
\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2}}{\Gamma \vdash \Pi_{s_{1}, s_{2}}(A,[x] B): s_{3}} \text { Prod } \\
\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2} \quad \Gamma, x: A \vdash M: B}{\Gamma \vdash \lambda_{s_{1}, s_{2}}(A,[x] B,[x] M): \Pi_{s_{1}, s_{2}}(A,[x] B)} \text { Abs } \\
\left(s_{1}, s_{2}, s_{3}\right) \in \mathcal{R} \frac{\Gamma \vdash A: s_{1} \quad \Gamma, x: A \vdash B: s_{2} \quad \Gamma \vdash M: \Pi_{s_{1}, s_{2}}(A,[x] B) \quad \Gamma \vdash N: A}{\Gamma \vdash @_{s_{1}, s_{2}}(A,[x] B, M, N): B\{N / x\}} \text { App }
\end{gathered}
$$

Theorem $\Gamma \vdash_{P T S} M: A$ iff there are $\Gamma^{\prime}, M^{\prime}, A^{\prime}$ with $\Gamma^{\prime} \vdash_{E P T S} M^{\prime}: A^{\prime}$, where $\Gamma^{\prime}, M^{\prime}, A^{\prime}$ are erased to $\Gamma, M, A$

## Defining the translation function

$$
\begin{aligned}
& \llbracket x \rrbracket=x \\
& \llbracket s \rrbracket=u_{s} \\
& \llbracket \Pi_{s_{1}, s_{2}}(A,\lceil x] B) \rrbracket=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A \rrbracket(\lambda x \cdot \llbracket B \rrbracket) \\
& \left.\left.\llbracket \lambda_{s_{1}, s_{2}}(A, \llbracket x] B, \llbracket x\right] M\right) \rrbracket=a b s_{s_{1}, s_{2}} \llbracket A \rrbracket(\lambda x \cdot \llbracket B \rrbracket)(\lambda x . \llbracket M \rrbracket) \\
& \left.\llbracket \varrho_{s_{1}, s_{2}}(A, \llbracket \times] B, M, N\right) \rrbracket=a p p_{s_{1}, s_{2}} \llbracket A \rrbracket(\lambda x \cdot \llbracket B \rrbracket) \llbracket M \rrbracket \llbracket N \rrbracket
\end{aligned}
$$

Very natural definition
Does not need to prove that $M$ is typed on 「 to apply $\llbracket-\rrbracket$

## Soundness, Conservativity and

 Adequacy
## The easy bit: soundness

Before soundness, show that the encoding is computational

$$
M \hookrightarrow N \quad \text { implies } \quad \llbracket M \rrbracket \hookrightarrow \hookrightarrow^{+} \llbracket N \rrbracket
$$

Not satisfied by LF encodings, but here Dedukti shines!

Soundness If $\Gamma \vdash_{\text {EPTS }} M: A$ then $\llbracket \Gamma \rrbracket \vdash_{D K} \llbracket M \rrbracket: E I_{S_{A}} \llbracket A \rrbracket$
Simple proof by induction on the derivation

## Conservativity, first try

If $\llbracket\left\ulcorner\rrbracket \vdash_{\mathrm{DK}} M: E I_{S_{A}} \llbracket A \rrbracket\right.$ we would like to show $\Gamma \vdash_{E P T S} \llbracket M \rrbracket^{-1}: A$
Problem If $M$ not in $\beta$-normal form, no way to inverse it. What is $\llbracket N \rrbracket^{-1}$ of

$$
N=\left(\lambda x \cdot\left(\lambda z \cdot z\left(\lambda y \cdot \llbracket A_{2} \rrbracket\right)\right)\left(\operatorname{Prod}_{s_{1}, s_{2}} x\right)\right) \llbracket A_{1} \rrbracket \quad ?
$$

## Conservativity, first try

If $\llbracket\left\ulcorner\rrbracket \vdash_{\mathrm{DK}} M: E I_{S_{A}} \llbracket A \rrbracket\right.$ we would like to show $\Gamma \vdash_{\text {EPTS }} \llbracket M \rrbracket^{-1}: A$
Problem If $M$ not in $\beta$-normal form, no way to inverse it. What is $\llbracket N \rrbracket^{-1}$ of

$$
N=\left(\lambda x \cdot\left(\lambda z \cdot z\left(\lambda y \cdot \llbracket A_{2} \rrbracket\right)\right)\left(\operatorname{Prod}_{s_{1}, s_{2}} x\right)\right) \llbracket A_{1} \rrbracket \quad ?
$$

Solution Take the $\beta$-normal form!

$$
N F_{\beta}(N)=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A_{1} \rrbracket\left(\lambda y \cdot \llbracket A_{2} \rrbracket\right) \text {, thus } \llbracket N F_{\beta}(N) \rrbracket^{-1}=\Pi_{s_{1}, s_{2}}\left(A_{1},[y] A_{2}\right)
$$

## Conservativity, first try

If $\llbracket\left\ulcorner\rrbracket \vdash_{D K} M: E I_{S_{A}} \llbracket A \rrbracket\right.$ we would like to show $\Gamma \vdash_{E P T S} \llbracket M \rrbracket^{-1}: A$
Problem If $M$ not in $\beta$-normal form, no way to inverse it. What is $\llbracket N \rrbracket^{-1}$ of

$$
N=\left(\lambda x \cdot\left(\lambda z \cdot z\left(\lambda y \cdot \llbracket A_{2} \rrbracket\right)\right)\left(\operatorname{Prod}_{s_{1}, s_{2}} x\right)\right) \llbracket A_{1} \rrbracket \quad ?
$$

Solution Take the $\beta$-normal form!
$N F_{\beta}(N)=\operatorname{Prod}_{s_{1}, s_{2}} \llbracket A_{1} \rrbracket\left(\lambda y \cdot \llbracket A_{2} \rrbracket\right)$, thus $\llbracket N F_{\beta}(N) \rrbracket^{-1}=\Pi_{s_{1}, s_{2}}\left(A_{1},[y] A_{2}\right)$
Solution also used in LF, where $\beta$ is known to be SN (strongly normalizing)
But in Dedukti, rewrite rules extend the typing relation of the $\lambda \Pi$-calculus Is $\beta$ still $S N$ in Dedukti?

## A simple proof that $\beta$ is SN

$\mathcal{R}$ is arity preserving if (roughly) no $\Pi$ appears at right-hand sides of rules in $\mathcal{R}$
Theorem If $\mathcal{R}$ is arity preserving and $\beta \mathcal{R}$ is confluent, then $\beta$ is $S N$ in Dedukti
Proof by erasure into the simply-typed $\lambda$-calculus

## A simple proof that $\beta$ is SN

$\mathcal{R}$ is arity preserving if (roughly) no $\Pi$ appears at right-hand sides of rules in $\mathcal{R}$
Theorem If $\mathcal{R}$ is arity preserving and $\beta \mathcal{R}$ is confluent, then $\beta$ is $S N$ in Dedukti
Proof by erasure into the simply-typed $\lambda$-calculus

Example The rewrite rule used by Cousineau \& Dowek to encode PTS

$$
(\star) \quad E I_{s_{3}}\left(\operatorname{Prod}_{s_{1}, s_{2}} A B\right) \hookrightarrow \Pi x: E I_{s_{1}} A \cdot E I_{s_{2}}(B x)
$$

is not arity preserving
Expected, since we know ( $\star$ ) can break SN of $\beta$

## Conservativity, finally

$\mathcal{R}_{\text {PTS }}$ is arity preserving and $\beta \mathcal{R}_{\text {PTS }}$ is confluent (can be seen as orthogonal CRS)

$$
\begin{aligned}
& E l_{s_{2}} u_{s_{1}} \hookrightarrow U_{s_{1}} \\
& a p p_{s_{1}, s_{2}} A B\left(a b s_{s_{1}, s_{2}} A^{\prime} B^{\prime} M\right) N \hookrightarrow{\text { betas } s_{1}, s_{2}} M N
\end{aligned}
$$

Thus, to show conservativity it suffices to consider $\beta$-normal forms

## Conservativity, finally

$\mathcal{R}_{\text {PTS }}$ is arity preserving and $\beta \mathcal{R}_{\text {PTS }}$ is confluent (can be seen as orthogonal CRS)

$$
\begin{aligned}
& E l_{s_{2}} u_{s_{1}} \hookrightarrow U_{s_{1}} \\
& a p p_{s_{1}, s_{2}} A B\left(a b s_{s_{1}, s_{2}} A^{\prime} B^{\prime} M\right) N \hookrightarrow{\text { beta } s_{1}, s_{2}} M N
\end{aligned}
$$

Thus, to show conservativity it suffices to consider $\beta$-normal forms
Theorem If $\llbracket\left\ulcorner\rrbracket \vdash_{\mathrm{DK}} M: E I_{S_{A}} \llbracket A \rrbracket\right.$ and $M$ in $\beta$-normal form then $\Gamma \vdash_{E P T S} \llbracket M \rrbracket^{-1}: A$
Proof by induction on $M$, some work but not hard

## Adequacy, a simple corollary

Let $\Gamma \vdash_{\text {EPTS }} A: s_{A}$
Theorem $\llbracket-\rrbracket$ and $\llbracket-\rrbracket^{-1}$ form a bijection $A \simeq N F_{\beta}\left(E I_{s_{A}} \llbracket A \rrbracket\right)$
Consequence of soundness and conservativity

## Conclusion

## Takeaway lesson

Cousineau \& Dowek's encoding represents object $\beta$ by Dedukti's $\beta$
SN of $\beta$ becomes property of the theory
Conservativity needs $S N$ of $\beta$, and thus is made dependent on the encoded system
But logical frameworks should be agnostic to such properties

## Takeaway lesson

Cousineau \& Dowek's encoding represents object $\beta$ by Dedukti's $\beta$
SN of $\beta$ becomes property of the theory
Conservativity needs $S N$ of $\beta$, and thus is made dependent on the encoded system But logical frameworks should be agnostic to such properties

In our encoding, beta separated from $\beta$. Here, $\beta$ represents pending substitution

$$
\operatorname{app}(\text { abs }(\lambda x \cdot M)) N \hookrightarrow_{\text {beta }}(\lambda x \cdot M) N \hookrightarrow_{\beta} M\{N / x\}
$$

Suggests that $S N$ of $\beta$ should be a property of the framework It is $S N$ of $\beta \mathcal{R}$ which is a property of the theory: if we instantiate our encoding with non-normalizing PTS, $\beta \mathcal{R}$ will not be SN , but $\beta$ will always be SN

## Future work

What about systems that are not Pure Type Systems?
Future work Encoding can be probably extended to general definition of purely computational type theories

## Future work

What about systems that are not Pure Type Systems?
Future work Encoding can be probably extended to general definition of purely computational type theories

Elephant in the room $a p p_{s_{1}, s_{2}} A(\lambda x . B) M N$ much bigger then $M N$, benchmarks show 16 times performance loss when checking Fermat's Little Theorem

Future work Explore extensions of Dedukti with erased (not implicit!) arguments Improve performance, but also make $\llbracket-\rrbracket$ easy to define

## Future work

What about systems that are not Pure Type Systems?
Future work Encoding can be probably extended to general definition of purely computational type theories

Elephant in the room $a p p_{s_{1}, s_{2}} A(\lambda x . B) M N$ much bigger then $M N$, benchmarks show 16 times performance loss when checking Fermat's Little Theorem

Future work Explore extensions of Dedukti with erased (not implicit!) arguments Improve performance, but also make $\llbracket-\rrbracket$ easy to define

Thank you!

