auto imu\_data = imu\_->get\_data();

auto left\_vel = encoder\_1\_->get\_velocity();

auto right\_vel = encoder\_2\_->get\_velocity();

// comma separated values

// time, gyro\_x, gyro\_y, gyro\_z, acc\_x, acc\_y, acc\_z, mag\_x, mag\_y, mag\_z, left\_vel, right\_vel

std::string msg = std::to\_string(time\_us)

+ "," + std::to\_string(imu\_data.gyro[0]) + "," + std::to\_string(imu\_data.gyro[1]) + "," + std::to\_string(imu\_data.gyro[2])

+ "," + std::to\_string(imu\_data.acc[0]) + "," + std::to\_string(imu\_data.acc[1]) + "," + std::to\_string(imu\_data.acc[2])

+ "," + std::to\_string(imu\_data.mag[0]) + "," + std::to\_string(imu\_data.mag[1]) + "," + std::to\_string(imu\_data.mag[2])

+ "," + std::to\_string(left\_vel) + "," + std::to\_string(right\_vel);

send\_string\_msg(BROADCAST\_MAC, msg);