

# Your grade: 100%

Your latest: **100%** • Your highest: **100%**

To pass you need at least 80%. We keep your highest score.

Next item →

1. Which notation would you use to denote the 4th layer's activations when the input is the 7th example from the 3rd mini-batch?

1 / 1 point

- $a^{[7]\{3\}(4)}$
- $a^{[3]\{7\}(4)}$
- $a^{[4]\{3\}(7)}$

✓ **Correct**

Yes. In general  $a^{[l]\{t\}(k)}$  denotes the activation of the layer  $l$  when the input is the example  $k$  from the mini-batch  $t$ .

2. Which of these statements about mini-batch gradient descent do you agree with?

1 / 1 point

- One iteration of mini-batch gradient descent (computing on a single mini-batch) is faster than one iteration of batch gradient descent.
- Training one epoch (one pass through the training set) using mini-batch gradient descent is faster than training one epoch using batch gradient descent.
- You should implement mini-batch gradient descent without an explicit for-loop over different mini-batches, so that the algorithm processes all mini-batches at the same time (vectorization).

**Correct**

3. We usually choose a mini-batch size greater than 1 and less than  $m$ , because that way we make use of vectorization but not fall into the slower case of batch gradient descent.

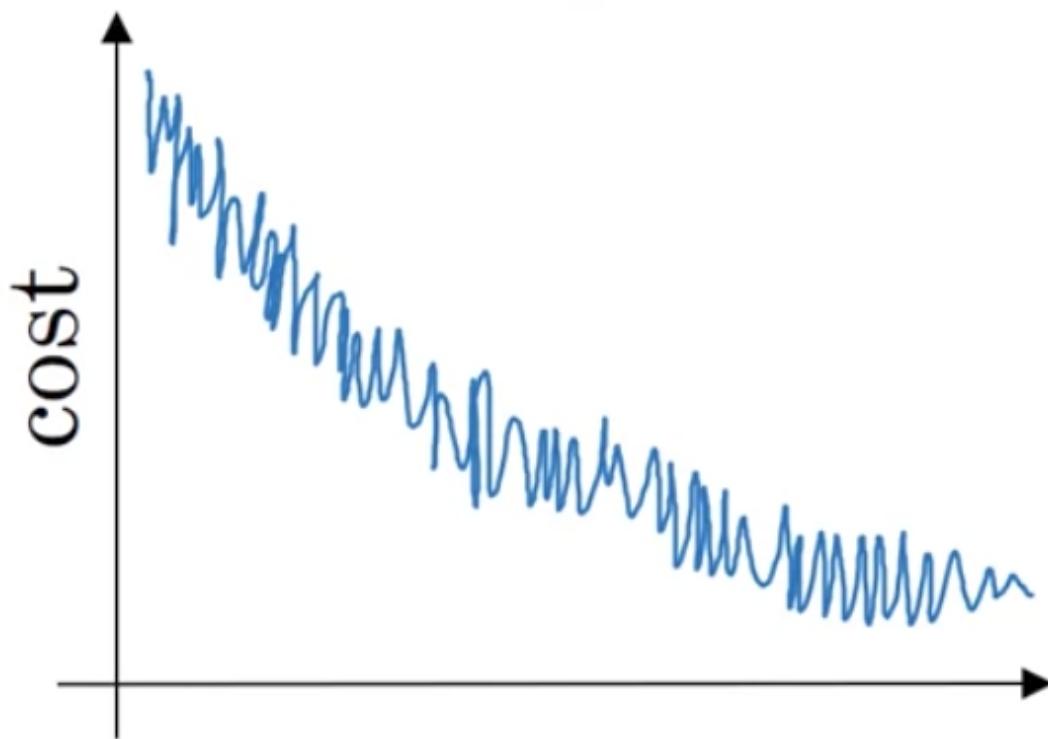
1 / 1 point

 False True **Correct**

Correct. Precisely by choosing a batch size greater than one we can use vectorization; but we choose a value less than  $m$  so we won't end up using batch gradient descent.

4. Suppose your learning algorithm's cost  $J$ , plotted as a function of the number of iterations, looks like this:

1 / 1 point



Which of the following do you agree with?

- If you're using mini-batch gradient descent, something is wrong. But if you're using batch gradient descent, this looks acceptable.
- If you're using mini-batch gradient descent, this looks acceptable. But if you're using batch gradient descent, something is wrong.
- Whether you're using batch gradient descent or mini-batch gradient descent, this looks acceptable.
- Whether you're using batch gradient descent or mini-batch gradient descent, something is wrong.

 **Correct**

5. Suppose the temperature in Casablanca over the first two days of March are the following:

1 / 1 point

March 1st:  $\theta_1 = 10^\circ \text{ C}$

March 2nd:  $\theta_2 = 25^\circ \text{ C}$

Say you use an exponentially weighted average with  $\beta = 0.5$  to track the temperature:  $v_0 = 0$ ,  $v_t = \beta v_{t-1} + (1 - \beta) \theta_t$ . If  $v_2$  is the value computed after day 2 without bias correction, and  $v_2^{\text{corrected}}$  is the value you compute with bias correction. What are these values?

- $v_2 = 20$ ,  $v_2^{\text{corrected}} = 15$ .

- $v_2 = 15$ ,  $v_2^{\text{corrected}} = 20$ .

- $v_2 = 20$ ,  $v_2^{\text{corrected}} = 20$ .

- $v_2 = 15$ ,  $v_2^{\text{corrected}} = 15$ .

(✓) Correct

Correct.  $v_2 = \beta v_{t-1} + (1 - \beta) \theta_t$  thus  $v_1 = 5, v_2 = 15$ . Using the bias correction  $\frac{v_t}{1-\beta^t}$  we get  $\frac{15}{1-(0.5)^2} = 20$ .

6. Which of these is NOT a good learning rate decay scheme? Here,  $t$  is the epoch number.

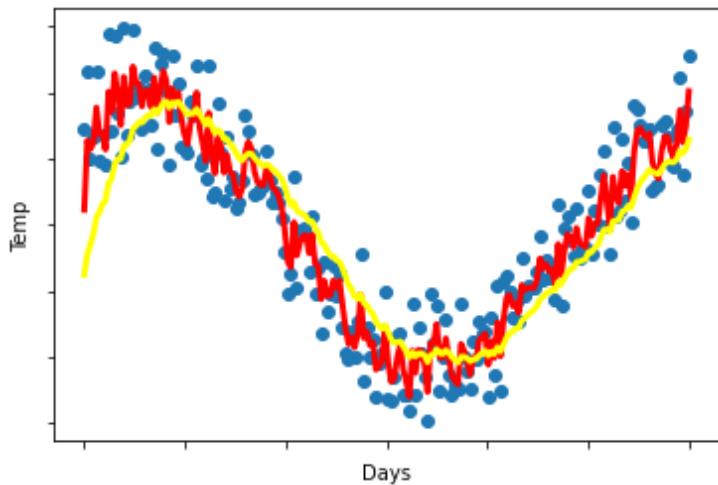
1 / 1 point

- $\alpha = 0.95^t \alpha_0$
- $\alpha = \frac{1}{\sqrt{t}} \alpha_0$
- $\alpha = \frac{1}{1+2*t} \alpha_0$
- $\alpha = e^t \alpha_0$

(✓) Correct

7. You use an exponentially weighted average on the London temperature dataset. You use the following to track the temperature:  
 $v_t = \beta v_{t-1} + (1 - \beta) \theta_t$ . The yellow and red lines were computed using values  $\beta_1$  and  $\beta_2$  respectively. Which of the following are true?

1 / 1 point



- $\beta_1 > \beta_2$ .
- $\beta_1 = 0, \beta_2 > 0$ .
- $\beta_1 = \beta_2$ .
- $\beta_1 < \beta_2$ .

**Correct**

Correct.  $\beta_1 > \beta_2$  since the red curve is noisier.

8. Which of the following are true about gradient descent with momentum? 1 / 1 point

- It generates faster learning by reducing the oscillation of the gradient descent process.

**Correct**

Correct. The use of momentum makes each step of the gradient descent more efficient by reducing oscillations.

- Gradient descent with momentum makes use of moving averages.

**Correct**

Correct. Gradient descent with momentum makes use of moving averages, which smooths out the gradient descent process.

- Increasing the hyperparameter  $\beta$  smooths out the process of gradient descent.

**Correct**

Correct. Gradient descent with momentum makes use of moving averages, which smooths out the gradient descent process.

- It decreases the learning rate as the number of epochs increases.

9. Suppose batch gradient descent in a deep network is taking excessively long to find a value of the parameters that achieves a small value for the cost function  $J(W^{[1]}, b^{[1]}, \dots, W^{[L]}, b^{[L]})$ . Which of the following techniques could help find parameter values that attain a small value for  $J$ ? (Check all that apply)

- Try tuning the learning rate  $\alpha$

 **Correct**

- Try using Adam

 **Correct**

- Try initializing all the weights to zero

- Try better random initialization for the weights

 **Correct**

- Try mini-batch gradient descent

 **Correct**

10. Which of the following are true about Adam?

- The most important hyperparameter on Adam is  $\epsilon$  and should be carefully tuned.
- Adam combines the advantages of RMSProp and momentum.
- Adam can only be used with batch gradient descent and not with mini-batch gradient descent.
- Adam automatically tunes the hyperparameter  $\alpha$ .

**Correct**

True. Precisely Adam combines the features of RMSProp and momentum that is why we use two-parameter  $\beta_1$  and  $\beta_2$ , besides  $\epsilon$ .