

Almgren-Chriss model and its extensions

M203 Electronic markets project

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1 Introduction

The paper aims to present enhancements to the Almgren-Chriss framework [AC00]. The original model by Almgren and Chriss was designed to balance market risk and the costs of liquidity during significant trade executions. This research expands that model to a continuous setting and explores variations.

It examines different benchmarks beyond initial pricing, such as using the *Target Close* benchmark and the *Time-Weighted Average Price*. Further analysis includes comparing the discretized Bellman Equation's results to existing analytic solutions. Additionally, the study explores trading velocity and its impact on liquidity and execution cost efficiency, as well as strategies for liquidating a second, more liquid asset in correlation with the first. Our contribution will mostly be through the implementation of deep learning methods to find an optimal liquidation for various orders and strategies, while observing what happens when we decide to lift some key assumptions.

2 Target Close and TWAP orders

2.1 Continuous Almgren-Chriss model presentation

The model first states the following dynamics on the stock inventory X_t , the spot S_t and the cash balance C_t .

$$\begin{cases} dX_t = -n_t dt \\ dS_t = \sigma dW_t - g(n_t) dt \\ dC_t = n_t(S_t - h(n_t)) dt \end{cases} \quad (1)$$

In the above system, the remaining stock inventory is diffused such as to exhibit the convexity of the execution strategy. The spot price follows an *Arithmetic Brownian* motion through the Wiener process W_t with constant volatility. The potential permanent market impact of trading is denoted $g(n_t)$, but unless stated otherwise we consider it absent. The cash balance grows by the given traded

quantity valued at the current stock price corrected of a temporary market impact written $h(n_t)$.

$$\begin{cases} X_0 = X \\ X_T = 0 \\ C_0 = 0 \end{cases} \quad (2)$$

At inception we are attributed a quantity X we want to liquidate fully at the end of the process. We also assume that the cash balance at the start is zero.

2.2 Implementation Shortfall optimal strategy

Implementation shortfall is the difference between the decision price and the execution price for a trade. We remind there is no permanent market impact.

$$\begin{aligned} C_T - x_0 S_0 &= \sigma \int_0^T x_t dW_t - \int_0^T g(n_t) x_t dt - \int_0^T n_t h(n_t) dt \\ C_T - x_0 S_0 &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt \end{aligned} \quad (3)$$

We then would like to find the optimal strategy under the *Mean-Variance* framework. This leads to solving the following optimization:

$$\min_x \lambda \mathbb{V}[C_T - x_0 S_0] - \mathbb{E}[C_T - x_0 S_0] \quad (4)$$

With λ being a risk aversion parameter. We below detail the expectation and variance for this system.

$$\begin{aligned} \mathbb{E}[C_T - x_0 S_0] &= \sigma \mathbb{E} \left[\int_0^T x_t dW_t \right] - \mathbb{E} \left[\int_0^T n_t h(n_t) dt \right] = - \int_0^T n_t h(n_t) dt \\ \mathbb{V}[C_T - x_0 S_0] &= \mathbb{V} \left[\sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt \right] = \sigma^2 \int_0^T x_t^2 dt \end{aligned} \quad (5)$$

We will denote $n_t = -\frac{dx_t}{dt} = -\dot{x}_t$ by considering the Euler-Lagrange notations:

$$\frac{\partial f}{\partial x} - \frac{d}{dy} \left(\frac{\partial f}{\partial \dot{x}} \right) = 0 \quad (6)$$

This allows us to further simplify the optimization problem under (2):

$$\min_x \int_0^T [\lambda \sigma^2 x_t^2 - \dot{x}_t h(-\dot{x}_t)] dt$$

In the original model, h is assumed to be linear: the impact is directly proportional to the rate or volume of trading. We thus write $h(x) = \eta x$ and continue:

$$\min_x \int_0^T [\lambda \sigma^2 x_t^2 + \eta \dot{x}_t^2] dt \quad (7)$$

These simplifications make the model simple and tractable. Other models use more complex forms of the temporary market impact, as the accurate modelling of trade execution costs heavily rely on having chosen the right form.

At this stage, having combined Almgren-Chriss dynamics with mean-variance optimization led to a static optimization problem, with two terms appear: a *liquidation* penalty $\eta \dot{x}_t^2$ and an *inventory* penalty $\lambda \sigma^2 x_t^2$. They give us a clearer picture of how the optimal execution chronology might look like.

The liquidation penalty advises the trader not to execute too quickly, thus inferring on a lesser steep slope. Moreover, the inventory penalty term incorporates convexity in the case of a risk-averse trader. The optimal execution will then not be a straight decreasing line. Moving on with the problem, we define:

$$F(t, x_t, \dot{x}_t) = \lambda \sigma^2 x_t^2 + \eta \dot{x}_t^2 \quad (8)$$

To which we apply the predefined Euler-Lagrange equation:

$$\frac{\partial F}{\partial x_t} = 2\lambda \sigma^2 x_t; \quad \frac{\partial F}{\partial \dot{x}_t} = 2\eta \dot{x}_t;$$

Using (6) we thus obtain with $y = t$ and $f = F$:

$$\frac{\partial F}{\partial x_t} = \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}_t} \right) \implies 2\lambda \sigma^2 x_t = 2\eta \ddot{x}_t \iff \ddot{x}_t = \frac{\lambda \sigma^2}{\eta} x_t$$

The general solution to this differential equation is a linear combination of hyperbolic sine and cosine functions. We will use again (2) to conclude.

$$x(t) = A \cdot \cosh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) + B \cdot \sinh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right)$$

We denote $k = \sigma \sqrt{\frac{\lambda}{\eta}}$.

$$\left\{ \begin{array}{l} x_0 = A \\ 0 = A \cosh(kT) + B \sinh(kT) \end{array} \right\} \implies \left\{ \begin{array}{l} A = x_0 \\ B = -x_0 \cosh(kT) \sinh^{-1}(kT) \end{array} \right.$$

$$\begin{aligned}
x(t) &= x_0 \left(\cosh(kt) - \frac{\cosh(kT) \sinh(kt)}{\sinh(kT)} \right) \\
&= x_0 \left(\frac{\sinh(kT) \cosh(kt) - \cosh(kT) \sinh(kt)}{\sinh(kT)} \right) \\
&= x_0 \left(\frac{\sinh(k(T-t))}{\sinh(kT)} \right) = \frac{x_0}{\sinh(kT)} \sinh(k(T-t)) \tag{9}
\end{aligned}$$

We now display implementation shortfall optimal liquidation strategies for different parameters. We will observe a convex execution for well-chosen values.

2.3 Target Close optimal strategy

Target Close is when the trader aims at executing a trade at a price close to the closing price of the stock on a particular day. This approach is typically used to minimize the market impact and the transaction cost of large orders by leveraging the increased liquidity near the market's close.

$$\begin{aligned}
C_T - x_0 S_0 &= \sigma \int_0^T x_t dW_t - \int_0^T g(n_t) x_t dt - \int_0^T n_t h(n_t) dt \\
C_T - x_0 S_T &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt + x_0 (S_0 - S_T) \\
C_T - x_0 S_T &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt - x_0 \sigma W_T \tag{10}
\end{aligned}$$

We once again would like to find the optimal strategy under the *Mean-Variance* framework which gives the following, the benchmark in this case being S_T :

$$\min_x \lambda \mathbb{V}[C_T - x_0 S_T] - \mathbb{E}[C_T - x_0 S_T] \tag{11}$$

To solve the system we compute both moments $\mathbb{E}(\cdot)$ and $\mathbb{V}(\cdot)$:

$$\begin{aligned}
\mathbb{E}[C_T - x_0 S_T] &= \mathbb{E} \left[\int_0^T \sigma (x_t - x_0) dW_t - \int_0^T n_t h(n_t) dt \right] = - \int_0^T n_t h(n_t) dt \\
\mathbb{V}[C_T - x_0 S_T] &= \mathbb{V} \left[\int_0^T \sigma (x_t - x_0) dW_t - \int_0^T n_t h(n_t) dt \right] = \sigma^2 \int_0^T (x_t - x_0)^2 dt
\end{aligned}$$

Continuing on the same path as for the previous problem and considering the same definitions for n_t , \dot{x}_t and h , we get the following under (2):

$$\min_x \int_0^T [\lambda \sigma^2 (x_t - x_0)^2 - \dot{x}_t h(-\dot{x}_t)] dt$$

We again write $h(x) = \eta x$ and thus have:

$$\min_x \int_0^T [\lambda \sigma^2 (x_t - x_0)^2 + \eta \dot{x}_t^2] dt \quad (12)$$

To continue, we define a functional $F(\cdot)$ to which we apply Euler-Lagrange:

$$F(t, x_t, \dot{x}_t) = \lambda \sigma^2 (x_t - x_0)^2 + \eta \dot{x}_t^2 \quad (13)$$

$$\frac{\partial F}{\partial x_t} = 2\lambda \sigma^2 (x_t - x_0); \quad \frac{\partial F}{\partial \dot{x}_t} = 2\eta \dot{x}_t;$$

Using (6) we thus obtain with $y = t$ and $f = F$:

$$\frac{\partial F}{\partial x_t} = \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}_t} \right) \implies 2\lambda \sigma^2 (x_t - x_0) = 2\eta \ddot{x}_t \iff \ddot{x}_t = \frac{\lambda \sigma^2}{\eta} (x_t - x_0)$$

The general solution to this differential equation is also a linear combination of hyperbolic sine and cosine functions. We will use again (2) to conclude.

$$x(t) - x_0 = A \cdot \cosh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) + B \cdot \sinh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right)$$

We denote $k = \sigma \sqrt{\frac{\lambda}{\eta}}$.

$$\begin{cases} A = 0 \\ B = -x_0 \sinh^{-1}(kT) \end{cases}$$

$$x(t) = x_0 - \frac{x_0}{\sinh(kT)} \sinh(k(t)) = x_0 \left(1 - \frac{\sinh(k(t))}{\sinh(kT)} \right) \quad (14)$$

We now implement implementation shortfall optimal liquidation strategies for different parameters. We will observe a convex execution for well-chosen values.

2.4 TWAP optimal strategy

Time Weighted Average Price aims to minimize the market impact of large trades by spreading the order out over a specific time period. Its main goal is to execute the trade as close to the average price of the security as possible, within the chosen time frame.

$$C_T - x_0 S_0 = \sigma \int_0^T x_t dW_t - \int_0^T g(n_t) x_t dt - \int_0^T n_t h(n_t) dt$$

$$C_T - \frac{x_0}{T} \int_0^T S_t dt = \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt + x_0 \left(S_0 - \frac{1}{T} \int_0^T S_t dt \right)$$

However we do know from (1) that:

$$S_t = S_0 + \sigma W_t \implies S_0 - \frac{1}{T} \int_0^T S_t dt = S_0 - \frac{1}{T} S_0 T - \frac{\sigma}{T} \int_0^T W_t dt = -\frac{\sigma}{T} \int_0^T W_t dt$$

Hence we further simplify our equation:

$$C_T - \frac{x_0}{T} \int_0^T S_t dt = \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt - \frac{x_0 \sigma}{T} \int_0^T W_t dt$$

$$C_T - \frac{x_0}{T} \int_0^T S_t dt = \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt - \frac{x_0 \sigma}{T} \int_0^T (T - t) dW_t$$

$$C_T - \frac{x_0}{T} \int_0^T S_t dt = \sigma \int_0^T x_t - x_0 \left(1 - \frac{t}{T} \right) dW_t - \int_0^T n_t h(n_t) dt \quad (15)$$

The optimal strategy is found by solving the following optimization system:

$$\min_x \lambda \mathbb{V} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] - \mathbb{E} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] \quad (16)$$

Let us compute both moments $\mathbb{E}(\cdot)$ and $\mathbb{V}(\cdot)$:

$$\mathbb{E} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] = -\mathbb{E} \left[\int_0^T n_t h(n_t) dt \right] = -\int_0^T n_t h(n_t) dt$$

$$\mathbb{V} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] = \mathbb{V} \left[\sigma \int_0^T x_t - x_0 \left(1 - \frac{t}{T} \right) dW_t \right]$$

$$= \sigma^2 \int_0^T \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 dt$$

Again following the same path as for the previous two systems and considering the same definitions for n_t , \dot{x}_t and h , we get the following under (2):

$$\min_x \int_0^T \left[\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 - \dot{x}_t h(-\dot{x}_t) \right] dt$$

We again write $h(x) = \eta x$ and thus have:

$$\min_x \int_0^T \left[\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 + \eta \dot{x}_t^2 \right] dt \quad (17)$$

To continue, we define a functional $F(\cdot)$ to which we apply Euler-Lagrange:

$$\begin{aligned} F(t, x_t, \dot{x}_t) &= \lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 + \eta \dot{x}_t^2 \\ \frac{\partial F}{\partial x_t} &= 2\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right); \quad \frac{\partial F}{\partial \dot{x}_t} = 2\eta \dot{x}_t; \end{aligned} \quad (18)$$

Using (6) we thus obtain with $y = t$ and $f = F$:

$$\begin{aligned} \frac{\partial F}{\partial x_t} &= \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}_t} \right) \implies 2\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right) = 2\eta \ddot{x}_t \\ \ddot{x}_t &= \frac{\lambda \sigma^2}{\eta} \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right) \end{aligned}$$

The general solution to this differential equation is again a linear combination of hyperbolic sine and cosine functions, that we use with (2) to conclude.

$$\begin{aligned} x(t) - x_0 \left(1 - \frac{t}{T} \right) &= A \cdot \cosh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) + B \cdot \sinh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) \\ \begin{cases} A = 0 \\ B = 0 \end{cases} &\implies x(t) = x_0 \left(1 - \frac{t}{T} \right) \end{aligned} \quad (19)$$

The liquidation strategy is smooth and does not account for any of the two risks defined above in section 2.2.