

Almgren-Chriss model and its extensions

M203 Electronic markets project

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1 Introduction

The paper aims to introduce and present enhancements to the Almgren-Chriss framework developed in [AC00]. The original model was designed to balance market risk and the costs of liquidity during significant trade executions. This research expands that model to a continuous setting and explores variations, taking inspirations from [Gué16] and [DBB22].

It examines different benchmarks beyond initial pricing, such as using the *Target Close* benchmark and the *Time-Weighted Average Price*. Further analysis includes comparing the discretized Bellman Equation's results to existing analytic solutions. Additionally, the study explores trading velocity and its impact on liquidity and execution cost efficiency, as well as strategies for liquidating a second, more liquid asset in correlation with the first. Our contribution will mostly be through the implementation of deep learning methods to find an optimal liquidation for various orders and strategies, while trying to leverage the technology into lifting some key model assumptions.

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2 Target Close and TWAP orders

2.1 Continuous Almgren-Chriss model presentation

The model first states the following dynamics on the stock inventory x_t , the spot S_t and the cash balance C_t .

$$\begin{cases} dx_t = -n_t dt \\ dS_t = \sigma dW_t - g(n_t) dt \\ dC_t = n_t(S_t - h(n_t)) dt \end{cases} \quad (1)$$

In the above system, the remaining stock inventory is diffused such as to exhibit the convexity of the execution strategy. The spot price follows an *Arithmetic Brownian* motion through the Wiener process W_t with constant volatility. The potential permanent market impact of trading is denoted $g(n_t)$, but unless stated otherwise we consider it absent for the remainder of this paper. The cash balance grows by the given traded quantity valued at the current stock price corrected of a temporary market impact written $h(n_t)$.

$$\begin{cases} x_0 = x \\ x_T = 0 \\ C_0 = 0 \end{cases} \quad (2)$$

At inception we are attributed a quantity X we want to liquidate fully at the end of the process. We also assume that the cash balance at the start is zero.

2.2 Implementation Shortfall optimal strategy

Implementation shortfall is the difference between the decision price and the execution price for a trade. We remind there is no permanent market impact.

$$\begin{aligned} C_T - x_0 S_0 &= \sigma \int_0^T x_t dW_t - \int_0^T g(n_t) x_t dt - \int_0^T n_t h(n_t) dt \\ C_T - x_0 S_0 &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt \end{aligned} \quad (3)$$

We then would like to find the optimal strategy under the *Mean-Variance* framework. This leads to solving the following optimization:

$$\min_x \lambda \mathbb{V}[C_T - x_0 S_0] - \mathbb{E}[C_T - x_0 S_0] \quad (4)$$

With λ being a risk aversion parameter. We below detail the expectation and variance for this system.

$$\mathbb{E}[C_T - x_0 S_0] = \sigma \mathbb{E} \left[\int_0^T x_t dW_t \right] - \mathbb{E} \left[\int_0^T n_t h(n_t) dt \right] = - \int_0^T n_t h(n_t) dt$$

$$\mathbb{V}[C_T - x_0 S_0] = \mathbb{V} \left[\sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt \right] = \sigma^2 \int_0^T x_t^2 dt$$

We will denote $n_t = -\frac{dx_t}{dt} = -\dot{x}_t$ by considering the Euler-Lagrange notations:

$$\frac{\partial f}{\partial x} - \frac{d}{dy} \left(\frac{\partial f}{\partial \dot{x}} \right) = 0 \quad (5)$$

This allows us to further simplify the optimization problem under (2):

$$\min_x \int_0^T [\lambda \sigma^2 x_t^2 - \dot{x}_t h(-\dot{x}_t)] dt$$

In the original model, h is assumed to be linear: the impact is directly proportional to the rate or volume of trading. We thus write $h(x) = \eta x$ and continue:

$$\min_x \int_0^T [\lambda \sigma^2 x_t^2 + \eta \dot{x}_t^2] dt \quad (6)$$

These simplifications make the model simple and tractable. Other models use more complex forms of the temporary market impact, as the accurate modelling of trade execution costs heavily rely on having chosen the right form.

At this stage, having combined Almgren-Chriss dynamics with mean-variance optimization led to a static optimization problem, with two terms appear: a *liquidation* penalty $\eta \dot{x}_t^2$ and an *inventory* penalty $\lambda \sigma^2 x_t^2$. They give us a clearer picture of how the optimal execution chronology might look like.

The liquidation penalty advises the trader not to execute too quickly, thus inferring on a lesser steep slope. Moreover, the inventory penalty term incorporates convexity in the case of a risk-averse trader. The optimal execution will then not be a straight decreasing line. Moving on with the problem, we define:

$$F(t, x_t, \dot{x}_t) = \lambda \sigma^2 x_t^2 + \eta \dot{x}_t^2 \quad (7)$$

To which we apply the predefined Euler-Lagrange equation:

$$\frac{\partial F}{\partial x_t} = 2\lambda \sigma^2 x_t; \quad \frac{\partial F}{\partial \dot{x}_t} = 2\eta \dot{x}_t;$$

Using (5) we thus obtain with $y = t$ and $f = F$:

$$\frac{\partial F}{\partial x_t} = \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}_t} \right) \implies 2\lambda \sigma^2 x_t = 2\eta \ddot{x}_t \iff \ddot{x}_t = \frac{\lambda \sigma^2}{\eta} x_t$$

The general solution to this differential equation is a linear combination of hyperbolic sine and cosine functions. We will use again (2) to conclude.

$$x(t) = A \cdot \cosh\left(\sigma t \sqrt{\frac{\lambda}{\eta}}\right) + B \cdot \sinh\left(\sigma t \sqrt{\frac{\lambda}{\eta}}\right)$$

We denote $k = \sigma \sqrt{\frac{\lambda}{\eta}}$.

$$\begin{cases} x_0 = A \\ 0 = A \cosh(kT) + B \sinh(kT) \end{cases} \implies \begin{cases} A = x_0 \\ B = -x_0 \cosh(kT) \sinh^{-1}(kT) \end{cases}$$

$$\begin{aligned} x(t) &= x_0 \left(\cosh(kt) - \frac{\cosh(kT) \sinh(kt)}{\sinh(kT)} \right) \\ &= x_0 \left(\frac{\sinh(kT) \cosh(kt) - \cosh(kT) \sinh(kt)}{\sinh(kT)} \right) \\ &= x_0 \left(\frac{\sinh(k(T-t))}{\sinh(kT)} \right) = \frac{x_0}{\sinh(kT)} \sinh(k(T-t)) \end{aligned} \quad (8)$$

We now display implementation shortfall optimal liquidation strategies for different parameters. We will initialize our market conditions at $x_0 = 100k\mathcal{L}$, $\sigma = 20\%$, $T = 1$ day and $\eta = 1.1 \times 10^{-4}$.

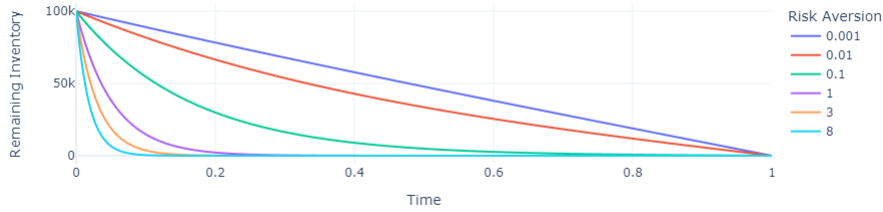


Figure 1: IS optimal liquidation for varying *risk aversion*

We observe a convex execution for well-chosen parameters. Traders with extreme risk aversion will want to liquidate as fast as possible by fear of any residual inventory at the end of the day. We now fix $\lambda = 0.1$ with varying η . For a fixed risk aversion, we notice that the bigger the temporary market impact, the smoother the execution process will be. This is quite expected: clustering orders within a restricted time frame would hurt, so the trader tries her best to proceed to an homogeneous execution.

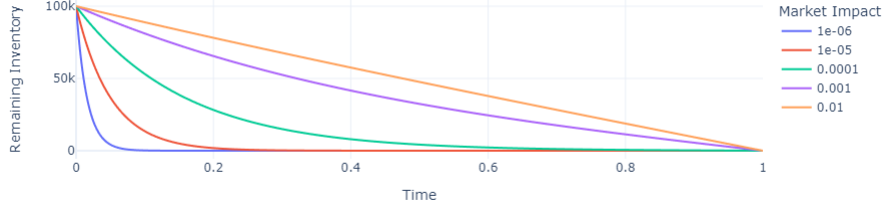


Figure 2: IS optimal liquidation for varying *temporary market impact*

2.3 Target Close optimal strategy

Target Close is when the trader aims at executing a trade at a price close to the closing price of the stock on a particular day. This approach is typically used to minimize the market impact and the transaction cost of large orders by leveraging the increased liquidity near the market's close.

$$\begin{aligned}
C_T - x_0 S_0 &= \sigma \int_0^T x_t dW_t - \int_0^T g(n_t) x_t dt - \int_0^T n_t h(n_t) dt \\
C_T - x_0 S_T &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt + x_0 (S_0 - S_T) \\
C_T - x_0 S_T &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt - x_0 \sigma W_T
\end{aligned} \tag{9}$$

We once again would like to find the optimal strategy under the *Mean-Variance* framework which gives the following, the benchmark in this case being S_T :

$$\min_x \lambda \mathbb{V}[C_T - x_0 S_T] - \mathbb{E}[C_T - x_0 S_T] \tag{10}$$

To solve the system we compute both moments $\mathbb{E}(\cdot)$ and $\mathbb{V}(\cdot)$:

$$\mathbb{E}[C_T - x_0 S_T] = \mathbb{E} \left[\int_0^T \sigma(x_t - x_0) dW_t - \int_0^T n_t h(n_t) dt \right] = - \int_0^T n_t h(n_t) dt$$

$$\mathbb{V}[C_T - x_0 S_T] = \mathbb{V} \left[\int_0^T \sigma(x_t - x_0) dW_t - \int_0^T n_t h(n_t) dt \right] = \sigma^2 \int_0^T (x_t - x_0)^2 dt$$

Continuing on the same path as for the previous problem and considering the same definitions for n_t , \dot{x}_t and h , we get the following under (2):

$$\min_x \int_0^T [\lambda \sigma^2 (x_t - x_0)^2 - \dot{x}_t h(-\dot{x}_t)] dt$$

We again write $h(x) = \eta x$ and thus have:

$$\min_x \int_0^T [\lambda \sigma^2 (x_t - x_0)^2 + \eta \dot{x}_t^2] dt \quad (11)$$

To continue, we define a functional $F(\cdot)$ to which we apply Euler-Lagrange:

$$F(t, x_t, \dot{x}_t) = \lambda \sigma^2 (x_t - x_0)^2 + \eta \dot{x}_t^2 \quad (12)$$

$$\frac{\partial F}{\partial x_t} = 2\lambda \sigma^2 (x_t - x_0); \quad \frac{\partial F}{\partial \dot{x}_t} = 2\eta \dot{x}_t;$$

Using (5) we thus obtain with $y = t$ and $f = F$:

$$\frac{\partial F}{\partial x_t} = \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}_t} \right) \implies 2\lambda \sigma^2 (x_t - x_0) = 2\eta \ddot{x}_t \iff \ddot{x}_t = \frac{\lambda \sigma^2}{\eta} (x_t - x_0)$$

The general solution to this differential equation is also a linear combination of hyperbolic sine and cosine functions. We will use again (2) to conclude.

$$x(t) - x_0 = A \cdot \cosh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) + B \cdot \sinh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right)$$

We denote $k = \sigma \sqrt{\frac{\lambda}{\eta}}$.

$$\begin{cases} A = 0 \\ B = -x_0 \sinh^{-1}(kT) \end{cases}$$

$$x(t) = x_0 - \frac{x_0}{\sinh(kT)} \sinh(k(t)) = x_0 \left(1 - \frac{\sinh(kt)}{\sinh(kT)} \right) \quad (13)$$

We now display implementation shortfall optimal liquidation strategies for different parameters. We consider the same set of base market parameters than in section 2.2 for consistency. Let us first fix all parameters but the risk aversion.

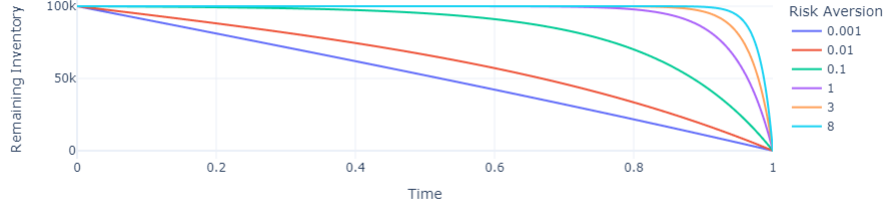


Figure 3: TC optimal liquidation for varying *risk aversion*

If a trader is heavily risk averse, she will tend to liquidate a bigger part of her inventory around the benchmark price, which in that case is S_T . This explains why the curve is skewed to the upper right part as opposed to the previous implementation where we considered S_0 as the reference. As in the previous section, let us now observe what happens when we fix all but the temporary market impact, fixing $\lambda = 0.1$ as before.

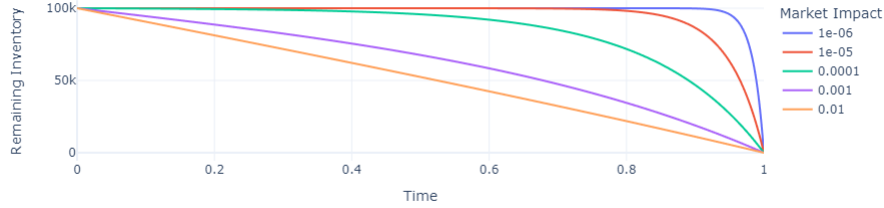


Figure 4: TC optimal liquidation for varying *temporary market impact*

Once again, the bigger the temporary market impact of an execution, the smoother the curve will be so as to spread out the impact on the timeline.

2.4 TWAP optimal strategy

Time Weighted Average Price aims to minimize the market impact of large trades by spreading the order out over a specific time period. Its main goal is to execute the trade as close to the average price of the security as possible, within the chosen time frame.

$$C_T - x_0 S_0 = \sigma \int_0^T x_t dW_t - \int_0^T g(n_t) x_t dt - \int_0^T n_t h(n_t) dt$$

$$C_T - \frac{x_0}{T} \int_0^T S_t dt = \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt + x_0 \left(S_0 - \frac{1}{T} \int_0^T S_t dt \right)$$

However we do know from (1) that:

$$S_t = S_0 + \sigma W_t \implies S_0 - \frac{1}{T} \int_0^T S_t dt = S_0 - \frac{1}{T} S_0 T - \frac{\sigma}{T} \int_0^T W_t dt = -\frac{\sigma}{T} \int_0^T W_t dt$$

Hence we further simplify our equation:

$$\begin{aligned} C_T - \frac{x_0}{T} \int_0^T S_t dt &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt - \frac{x_0 \sigma}{T} \int_0^T W_t dt \\ C_T - \frac{x_0}{T} \int_0^T S_t dt &= \sigma \int_0^T x_t dW_t - \int_0^T n_t h(n_t) dt - \frac{x_0 \sigma}{T} \int_0^T (T-t) dW_t \\ C_T - \frac{x_0}{T} \int_0^T S_t dt &= \sigma \int_0^T x_t - x_0 \left(1 - \frac{t}{T} \right) dW_t - \int_0^T n_t h(n_t) dt \end{aligned} \quad (14)$$

The optimal strategy is found by solving the following optimization system:

$$\min_x \lambda \mathbb{V} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] - \mathbb{E} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] \quad (15)$$

Let us compute both moments $\mathbb{E}(\cdot)$ and $\mathbb{V}(\cdot)$:

$$\begin{aligned} \mathbb{E} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] &= -\mathbb{E} \left[\int_0^T n_t h(n_t) dt \right] = -\int_0^T n_t h(n_t) dt \\ \mathbb{V} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] &= \mathbb{V} \left[\sigma \int_0^T x_t - x_0 \left(1 - \frac{t}{T} \right) dW_t \right] \\ &= \sigma^2 \int_0^T \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 dt \end{aligned}$$

Again following the same path as for the previous two systems and considering the same definitions for n_t , \dot{x}_t and h , we get the following under (2):

$$\min_x \int_0^T \left[\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 - \dot{x}_t h(-\dot{x}_t) \right] dt$$

We again write $h(x) = \eta x$ and thus have:

$$\min_x \int_0^T \left[\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 + \eta \dot{x}_t^2 \right] dt \quad (16)$$

To continue, we define a functional $F(\cdot)$ to which we apply Euler-Lagrange:

$$\begin{aligned} F(t, x_t, \dot{x}_t) &= \lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 + \eta \dot{x}_t^2 \\ \frac{\partial F}{\partial x_t} &= 2\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right); \quad \frac{\partial F}{\partial \dot{x}_t} = 2\eta \dot{x}_t; \end{aligned} \quad (17)$$

Using (5) we thus obtain with $y = t$ and $f = F$:

$$\begin{aligned} \frac{\partial F}{\partial x_t} &= \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}_t} \right) \implies 2\lambda \sigma^2 \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right) = 2\eta \ddot{x}_t \\ \ddot{x}_t &= \frac{\lambda \sigma^2}{\eta} \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right) \end{aligned}$$

The general solution to this differential equation is again a linear combination of hyperbolic sine and cosine functions, that we use with (2) to conclude.

$$\begin{aligned} x(t) - x_0 \left(1 - \frac{t}{T} \right) &= A \cdot \cosh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) + B \cdot \sinh \left(\sigma t \sqrt{\frac{\lambda}{\eta}} \right) \\ \begin{cases} A = 0 \\ B = 0 \end{cases} &\implies x(t) = x_0 \left(1 - \frac{t}{T} \right) \end{aligned} \quad (18)$$

The liquidation strategy is smooth and does not account for any of the two risks defined above in section 2.2. The plot would only be a straight decreasing curve, regardless of the market parameters.

2.5 Implementation Shortfall efficient frontier

The efficient frontier represents a set of optimal portfolios that offer the highest expected return for a defined level of risk. Given the optimal deterministic strategy obtained in (8):

$$x(t) = \frac{x_0}{\sinh(kT)} \sinh(k(T - t))$$

We thus express our moments as functions of (8). Thus we will be able to plot each portfolio on a graph of axes $(\mathbb{E}[\cdot], \mathbb{V}[\cdot])$.

$$\begin{aligned}\mathbb{V}[C_T - x_0 S_0] &= \sigma^2 \int_0^T x_t^2 dt = \sigma^2 \int_0^T \left(\frac{x_0}{\sinh(kT)} \sinh(k(T-t)) \right)^2 dt \\ \mathbb{V}[C_T - x_0 S_0] &= \left(\frac{x_0 \sigma}{\sinh(kT)} \right)^2 \int_0^T \sinh(k(T-t))^2 dt\end{aligned}$$

We focus on solving the remaining integral through the change of variable:

$$t^* = T - t \implies \int_0^T \sinh(k(T-t))^2 dt = - \int_T^0 \sinh(kt^*)^2 dt^*$$

Using some trigonometry rules to move forward we obtain:

$$\begin{aligned}\sinh(kt^*)^2 &= \cosh(2kt^*) - \cosh(kt^*)^2 = \cosh(2kt^*) - \sinh(kt^*)^2 - 1 \\ \sinh(kt^*)^2 &= \frac{\cosh(2kt^*) - 1}{2}\end{aligned}$$

So that we can further write the variance as the following:

$$\begin{aligned}- \int_T^0 \sinh(kt^*)^2 dt^* &= \frac{1}{2} \int_0^T \cosh(2kt^*) dt^* - \frac{T}{2} = \frac{1}{4} \left(\frac{\sinh(2kT)}{k} - 2T \right) \\ \mathbb{V}[C_T - x_0 S_0] &= \left(\frac{x_0 \sigma}{\sinh(kT)} \right)^2 \left(\frac{\sinh(2kT) - 2kT}{4k} \right)\end{aligned}$$

We can then write $\mathbb{E}[C_T - x_0 S_0]$ knowing $n_t = -\frac{\partial x_t}{\partial t}$, which we first develop:

$$\begin{aligned}\frac{\partial}{\partial t} x_t &= - \frac{x_0 k \cosh(k(T-t))}{\sinh(kT)} \\ \mathbb{E}[C_T - x_0 S_0] &= - \int_0^T \eta n_t^2 dt = -\eta \left(\frac{x_0 k}{\sinh(kT)} \right)^2 \int_0^T \cosh(kt^*)^2 dt^*\end{aligned}$$

Again using some hyperbolic trigonometry tricks we have:

$$\begin{aligned}\cosh(kt^*)^2 &= \cosh(2kt^*) - \sinh(kt^*)^2 = \cosh(2kt^*) - \cosh(kt^*)^2 + 1 \\ \cosh(kt^*)^2 &= \frac{\cosh(2kt^*) + 1}{2}\end{aligned}$$

So that simplifying forward becomes easy:

$$\int_0^T \cosh(kt^*)^2 dt^* = \frac{1}{2} \int_0^T \cosh(2kt^*) dt^* + \frac{T}{2} = \frac{1}{4} \left(\frac{\sinh(2kT)}{k} + 2T \right)$$

$$\mathbb{E}[C_T - x_0 S_0] = -\eta \left(\frac{x_0 k}{\sinh(kT)} \right)^2 \left(\frac{\sinh(2kT) + 2kT}{4k} \right)$$

We can then plot the frontier efficient for different values of λ in (4).

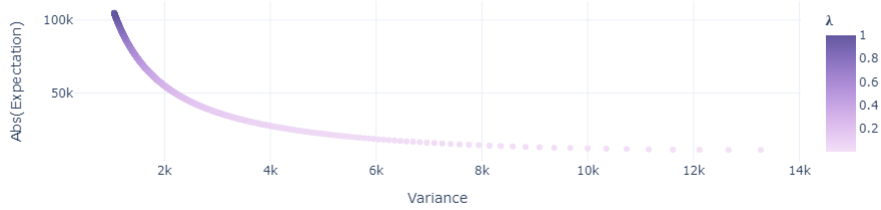


Figure 5: IS efficient frontier for varying *risk aversion*

We considered the same set of parameters as in section 2.2. The *y-axis* represents the absolute loss in cash. We observe that for a maximum λ , the trader is willing to bear a maximal loss exposure, which is in line with what is expected.

2.6 Target Close efficient frontier

We again derive hyperbolic functions to define the moments defined in (10). Given the optimal strategy computed in (13):

$$x(t) = x_0 \left(1 - \frac{\sinh(kt)}{\sinh(kT)} \right)$$

$$\mathbb{V}[C_T - x_0 S_T] = \sigma^2 \int_0^T (x_t - x_0)^2 dt = \left(\frac{\sigma x_0}{\sinh(kT)} \right)^2 \int_0^T \sinh(kt)^2 dt$$

$$\mathbb{V}[C_T - x_0 S_T] = \left(\frac{\sigma x_0}{\sinh(kT)} \right)^2 \left(\frac{\sinh(2kT) - 2T}{4k} \right)$$

We heavily relied on the mathematical developments from section 2.5 to integrate. We can then write $\mathbb{E}[C_T - x_0 S_0]$ knowing $n_t = -\frac{\partial x_t}{\partial t}$, which gives:

$$\frac{\partial}{\partial t} x_t = -\frac{x_0 k \cosh(kt)}{\sinh(kT)}$$

$$\mathbb{E}[C_T - x_0 S_0] = -\int_0^T \eta n_t^2 dt = -\eta \left(\frac{x_0 k}{\sinh(kT)} \right)^2 \int_0^T \cosh(kt)^2 dt$$

$$\mathbb{E}[C_T - x_0 S_0] = -\eta \left(\frac{x_0 k}{\sinh(kT)} \right)^2 \left(\frac{\sinh(2kT) + 2kT}{4k} \right)$$

For which we also plot the optimal portfolios following the system in (10).

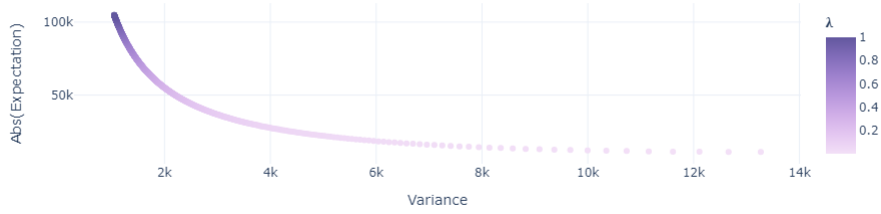


Figure 6: TC efficient frontier for varying *risk aversion*

Here we remark the graph is exactly the same as in 2.5. Mathematically it is because the formulas for $\mathbb{E}[\cdot]$ and $\mathbb{V}[\cdot]$ are equal.

2.7 TWAP efficient frontier

The efficient frontier for the TWAP is derived from its problem in (15). Given the closed-form optimal strategy in (18) we compute both moments:

$$x(t) = x_0 \left(1 - \frac{t}{T} \right)$$

$$\mathbb{V} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] = \sigma^2 \int_0^T \left(x_t - x_0 \left(1 - \frac{t}{T} \right) \right)^2 dt = 0$$

We can then write the expectancy knowing $n_t = -\frac{\partial x_t}{\partial t} = -\frac{x_0}{T}$, which gives:

$$\mathbb{E} \left[C_T - \frac{x_0}{T} \int_0^T S_t dt \right] = - \int_0^T n_t h(n_t) dt = -\eta \left(\frac{x_0}{T} \right)^2 \int_0^T dt = -\frac{\eta x_0^2}{T}$$

The inventory is liquidated with constant speed and thus no variance. The expected loss is independent of the risk aversion coefficient λ and the efficient frontier is represented as a single dot.

2.8 Bellman findings within expected utility framework

Here we will first aim at expressing the liquidation strategy within the expected utility framework, using CARA utility functions. We will then show that this framework yields equivalent results than the Hamilton-Jacobi-Bellman framework, and we will solve for both strategies given their Mean-Variance problem.

Let us first derive the HJB equation within the Markovian framework, which characterizes the optimal value function associated with the problem and provides optimal control strategies. We consider a utility function of the form:

$$u : x \rightarrow \exp(-\gamma x) \quad (19)$$

The *Bellman* value function of our problem is such that the very next iteration value comes from the action that maximizes an expected utility for a game:

$$v(t, x_{t+dt}, S_{t+dt}, C_{t+dt}) = \sup_{\psi} \mathbb{E} (u(C_T) | S_t = S, x_t = x, C_t = C) \quad (20)$$

We now want to derive an expression for $v(t + dt, x_{t+dt}, S_{t+dt}, C_{t+dt}) = v_{t+dt}$:

$$\begin{aligned} v_{t+dt} &= v_t + \frac{\partial v_t}{\partial t} dt + \frac{\partial v_t}{\partial S} dS_t - \frac{\partial v_t}{\partial x} dx_t + \frac{\partial v_t}{\partial C} dC_t + \frac{1}{2} \frac{\partial^2 v_t}{\partial S^2} (dS_t)^2 \\ dv &= \frac{\partial v_t}{\partial t} dt + \frac{\partial v_t}{\partial S} \sigma dW_t - \frac{\partial v_t}{\partial x} \psi dt + \frac{\partial v_t}{\partial C} \psi (S_t - h(\psi)) dt + \frac{\partial^2 v_t}{\partial S^2} \frac{\sigma^2}{2} dt \end{aligned}$$

Next we compute the expectation of the above to average out stochastic terms:

$$\mathbb{E}[dv] = \mathbb{E} \left[\frac{\partial v_t}{\partial t} dt - \frac{\partial v_t}{\partial x} \psi dt + \frac{\partial v_t}{\partial C} \psi (S_t - h(\psi)) dt + \frac{\partial^2 v_t}{\partial S^2} \frac{\sigma^2}{2} dt \right]$$

$$\mathbb{E}[dv] = \psi \left[-\frac{\partial v_t}{\partial x} dt + \frac{\partial v_t}{\partial C} (S - h(\psi)) \right] dt + \left[\frac{\partial v_t}{\partial t} + \frac{\partial^2 v_t}{\partial S^2} \frac{\sigma^2}{2} \right] dt$$

We separated the static elements to the right for convenience. We go further by reducing the number of variables of this problem by guessing the form of their solutions. We propose the following ansatz, using a negative utility:

$$v : t, x, S, C \rightarrow -\exp(-\gamma(Sx + C - \theta_{t,x})) \quad (21)$$

Such exponential utility is common as it ensures smoothness and can help ensure that the value function is well-defined. We can thus simplify further:

$$\begin{aligned} \frac{\partial v_t}{\partial t} + \frac{\partial^2 v_t}{\partial S^2} \frac{\sigma^2}{2} &= \left[\frac{\partial v}{\partial t} + \frac{\gamma(\sigma x)^2}{2} \right] \gamma v \\ -\frac{\partial v_t}{\partial x} dt + \frac{\partial v_t}{\partial C} (S - h(\psi)) &= \left[-\frac{\partial v}{\partial x} + h(\psi) \right] \gamma v \end{aligned}$$

The problem is unchanged if we divide by γv , and can be easily inverted if we consider negative utility (21). Thus we have the following optimization problem:

$$\frac{\partial v}{\partial t} + \frac{\gamma}{2}(\sigma x)^2 + \inf_{\psi} \psi \left[h(\psi) - \frac{\partial v}{\partial x} \right] = 0 \quad (22)$$

2.9 Implementation Shortfall discrete Bellman resolution

Let us try this from the *mean variance* optimization problem introduced in (4).

$$v_{t,x} = \min_x \int_t^T [\lambda \sigma^2 x_s^2 + \eta x_s'^2] ds$$

We know from Bellman theory that the current state value is the supremum of the expectation for the very next state. Thus we solve:

$$\begin{aligned} v_{t,x} &= \inf_{\psi} [v(t+dt, x - \psi dt) + (\lambda \sigma^2 x^2 + \eta \psi^2) dt] \\ v_{t,x} &= \inf_{\psi} \left[v(t, x) + \frac{\partial v}{\partial t} dt - \psi \frac{\partial v}{\partial x} dt + (\lambda \sigma^2 x^2 + \eta \psi^2) dt \right] \end{aligned}$$

Which later gives the following HJB optimization problem:

$$\frac{\partial v_t}{\partial t} + \lambda (\sigma x)^2 + \inf_{\psi} \left[\eta \psi - \frac{\partial v}{\partial x} \right] = 0 \quad (23)$$

We notice that we retrieve the same expression as in 22, with $\lambda = \frac{\gamma}{2}$ as expected, and $h(\psi) = \eta \psi$ as defined, where ψ represents the quantity liquidated at a given time. Bellman backward resolution will then advise at every step what is the optimal share of inventory ψ that needs to be sold on the market. The value x is still considered as the remaining inventory.

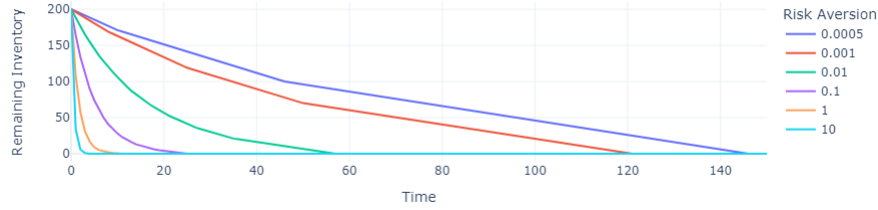


Figure 7: IS Bellman liquidation for varying *risk aversion*

This graph above was diffused using slightly different parameters to fit a nice curve: η is now much bigger at 0.5 with a smaller portfolio of value $200\mathcal{L}$, reduced for more adequate computation time. We chose a grid of 150 time steps. We therefore confirm that for a sufficiently fine grid, the optimal liquidation strategy is resembling what we theoretically found on graph (2).

2.10 Target Close discrete Bellman resolution

Let us also proceed from the *mean variance* optimization problem introduced above (10) and its subsequent value function:

$$v_{t,x} = \min_x \int_t^T [\lambda \sigma^2 (x_s - x_0)^2 + \eta x_s^2] ds$$

We continue to solve following Bellman theory by finding optimal action ψ :

$$v_{t,x} = \inf_{\psi} [v(t+dt, x - \psi dt) + (\lambda \sigma^2 (x - x_0)^2 + \eta \psi^2) dt]$$

$$v_{t,x} = \inf_{\psi} \left[v(t, x) + \frac{\partial v}{\partial t} dt - \psi \frac{\partial v}{\partial x} dt + (\lambda \sigma^2 (x - x_0)^2 + \eta \psi^2) dt \right]$$

Hence the resulting HJB equation, with once again the expected format of (22):

$$\frac{\partial v_t}{\partial t} + \lambda \sigma^2 (x - x_0)^2 + \inf_{\psi} \left[\eta \psi - \frac{\partial v}{\partial x} \right] = 0 \quad (24)$$

The below implementation shows the liquidation strategy found through backward solving Bellman, with the same parameters as in the previous subsection.

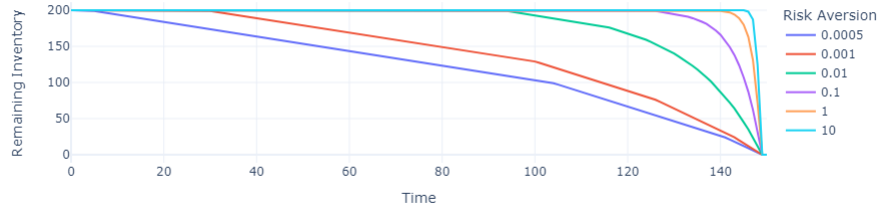


Figure 8: TC Bellman liquidation for varying *risk aversion*

We observe that the obtained optimal liquidation through Bellman is the symmetrical of the one following *implementation shortfall*, and this as to do with how the inventory costs are accounted for in both cases.

3 Optimal POV

In this exercise we restrict the set of strategies to *Percentage of Volume* orders, where the execution of the trade is contingent upon a specified percentage of the total trading volume of the security at the time. We assume constant market volume and constant liquidation speed $\dot{x}_t = -n_t = -v$ until portfolio emptiness.

3.1 IS optimal speed of liquidation in MV framework

We already worked on *Implementation Shortfall* orders within the *mean-variance* framework in section 2.2. The optimal pace of liquidation v can be found as a closed-form solution following the proof below, first using (1):

$$dC_t = n_t(S_t - h(n_t)) dt = v(S_t - \eta v) dt$$

$$\int_0^T dC_t = v \left(\int_0^T S_t dt - \eta v T \right) = -\eta v^2 T + v \left(\int_0^T S_0 + \sigma W_t dt \right)$$

$$\begin{aligned}
C_T - C_0 &= -\eta v^2 T + v \left(T S_0 + \sigma \int_0^T (T-t) dW_t \right) \\
C_T - x_0 S_0 &= -\eta v^2 T + S_0(vT - x_0) + \sigma v \int_0^T (T-t) dW_t \quad (25)
\end{aligned}$$

We will thus compute $\mathbb{E}[\cdot]$ and $\mathbb{V}[\cdot]$ to arrive at an optimization problem under the MV framework. Then we will derive the analytical solution and conclude.

$$\begin{aligned}
\mathbb{V}(C_T - x_0 S_0) &= (\sigma v)^2 \mathbb{V} \left[\int_0^T (T-t) dW_t \right] = (\sigma v)^2 \int_0^T (T-t)^2 dt \\
\mathbb{V}(C_T - x_0 S_0) &= (\sigma v)^2 \int_0^T (T^2 - 2Tt + t^2) dt = (\sigma v)^2 \frac{T^3}{3} = (\sigma v)^2 \frac{T^3}{3} \\
\mathbb{V}(C_T - x_0 S_0) &= \sigma^2 \frac{x_0^3}{3v} \text{ because } \dot{x}_t = -v \implies x_0 = v \int_0^T dt = vT
\end{aligned}$$

The variance was easy to compute, most of the terms being constants. The first moment will also be straightforward as the Weiner process has mean 0.

$$\begin{aligned}
\mathbb{E}(C_T - x_0 S_0) &= -\eta v^2 T + S_0(vT - x_0) + \sigma v \mathbb{E} \left[\int_0^T (T-t) dW_t \right] \\
\mathbb{E}(C_T - x_0 S_0) &= -\eta v^2 T + S_0(vT - x_0) = -\eta v x_0
\end{aligned}$$

We now plug both moments in the MV problem (4) under the constraints (2):

$$\begin{aligned}
\min_v \left[\lambda \sigma^2 \frac{x_0^3}{3v} + \eta v x_0 \right] &= \min_v x_0 \left[\lambda \sigma^2 \frac{x_0^2}{3v} + \eta v \right] = \min_v x_0 F(v) \\
F(v) = \lambda \sigma^2 \frac{x_0^2}{3v} + \eta v &\implies \frac{\partial F}{\partial v} = \eta - \lambda \sigma^2 \frac{x_0^2}{3v^2} \\
\frac{\partial F}{\partial v} = 0 &\implies v = \sqrt{\frac{x_0^2 \lambda \sigma^2}{3\eta}} \quad (26)
\end{aligned}$$

3.2 Visualizing optimal POV strategies

Given our constant liquidation speed computed in (26), we can now study the POV strategy under different sets of market parameters. We will thus be able to compare them to IS curves. Let us first write the analytical formula of liquidation for POV order given v :

$$dx_t = -vdt \implies x(t) = x_o - vt \quad (27)$$

We will try two sets of parameters and compare to the IS method already studied in section 2.2. We will observe high similarity in intuition.

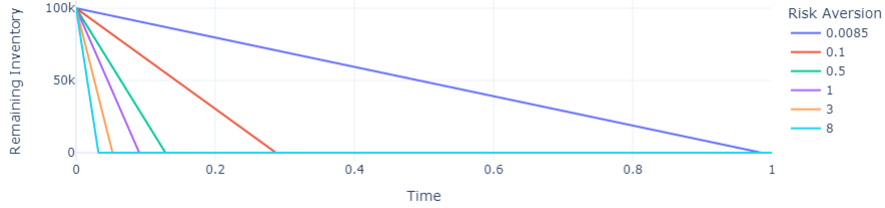


Figure 9: POV optimal liquidation for varying *risk aversion*

This figure shows as expected the constant pace of liquidation, through an execution scheme following a straight line. Very risk averse traders will also prefer to empty their inventory as fast as possible, with no particular degree of smoothness that was however observed in section 2.2 for the IS liquidation. Therefore, some might find themselves in a situation where they finished execution before the end of the day.

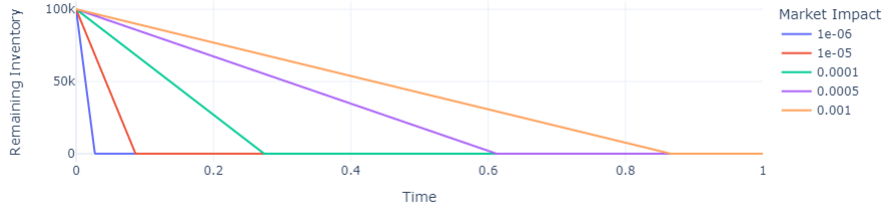


Figure 10: POV optimal liquidation for varying *temporary market impact*

As was observed in (2), the bigger the temporary market impact η and the more dispersed will the execution scheme be. This still makes sense as traders in both scenarios have high incentives to be prudent within an unstable market. Overall, POV and IS are highly similar in their intuition, only the IS incorporates a convexity in the pace of liquidation, generally spreading the execution process until the very end of the day.

3.3 POV efficient frontier

Given the closed-form liquidation in (26) we simplify both moments:

$$\mathbb{V}(C_T - x_0 S_0) = \sigma^2 \frac{x_0^3}{3v}$$

$$\mathbb{E}(C_T - x_0 S_0) = -\mu \sqrt{\frac{\lambda \sigma^2}{3\eta}} x_0^2$$

The plot is thus straightforward. By comparing to our IS resulting efficient frontier in (5), we notice that the POV frontier is slightly higher, especially at the curvature. This means that for each expected level of variance, the trader is willing to be exposed to more losses under the POV liquidation strategy.

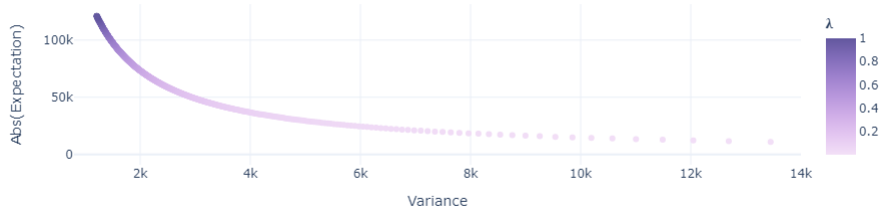


Figure 11: POV efficient frontier for varying *risk aversion*

We plotted below the difference between the two efficient frontier to provide a straightforward visual representation of this difference. We notice this difference is rather significant towards extreme cases, but remains existent for more regular couples.

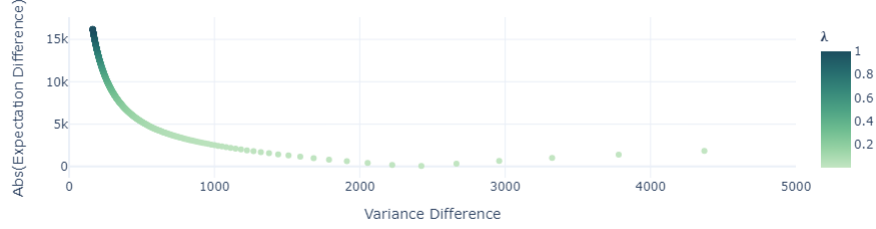


Figure 12: IS and POV efficient frontier differential for varying *risk aversion*

The reason why (12) shows POV is more efficient than IS is mainly explained by the inherent convex nature of IS. We observed earlier that for most risk averse traders, the liquidation under IS goes on until the very end of the period T , whereas the scheme might be done earlier when following a POV strategy. This gives the trader going through IS a longer exposure to market, where she has to bear inventory risk for the entire duration.

4 Liquidating two assets

In this exercise we consider two risky assets S_1 and S_2 . We complete the initial set (1) with ρ the correlation of both Brownian motions. For $j = \{1, 2\}$:

$$\begin{cases} dx_t^{(j)} = \sigma_j dW_t^{(j)} \\ dS_t^{(j)} = \sigma_j dW_t^{(j)} \\ dC_t = \sum_{j=1}^2 \left[n_t^{(j)} \left(S_t^{(j)} - h^{(j)} \left(n_t^{(j)} \right) \right) \right] dt \end{cases}$$

Boundary conditions are essentially the same as in (2), with $x_0 = (x_0^1, 0)$. As a first step we will draw upon our previous developments of the mean-variance framework. As in previous sections, we will compute $\mathbb{E}[\cdot]$ and $\mathbb{V}[\cdot]$ to thus solve the MV optimization problem under modified constraints (2). We then will do some stochastic control under HJM to retrieve the Bellman equation.

$$\begin{aligned} \int_0^T n_t^{(1)} h^{(1)} \left(n_t^{(1)} \right) + n_t^{(2)} h^{(2)} \left(n_t^{(2)} \right) dt &= \int_0^T N_t dt \\ C_T - x_0^{(1)} S_0^{(1)} &= \sigma_1 \int_0^T x_t^{(1)} dW_t^{(1)} + \sigma_2 \int_0^T x_t^{(2)} dW_t^{(2)} - \int_0^T N_t dt \end{aligned} \quad (28)$$

We thus compute both moments, supposing an execution following IS:

$$\mathbb{E} \left(C_T - x_0^{(1)} S_0^{(1)} \right) = \sigma_1 \mathbb{E} \left[\int_0^T x_t^{(1)} dW_t^{(1)} \right] + \sigma_2 \mathbb{E} \left[\int_0^T x_t^{(2)} dW_t^{(2)} \right] - \int_0^T N_t dt$$

$$\mathbb{E} \left(C_T - x_0^{(1)} S_0^{(1)} \right) = - \int_0^T N_t dt$$

The first moment was almost as straightforward as the single asset models. The variance will however exhibit a covariance term:

$$\begin{aligned} \mathbb{V} \left(C_T - x_0^{(1)} S_0^{(1)} \right) &= \mathbb{V} \left[\sigma_1 \int_0^T x_t^{(1)} dW_t^{(1)} + \sigma_2 \int_0^T x_t^{(2)} dW_t^{(2)} \right] \\ \mathbb{V} \left(C_T - x_0^{(1)} S_0^{(1)} \right) &= \int_0^T \left[\sigma_1^2 \left(x_t^{(1)} \right)^2 + \sigma_2^2 \left(x_t^{(2)} \right)^2 + 2 \sigma_1 \sigma_2 x_t^{(1)} x_t^{(2)} \rho \right] dt \end{aligned}$$

Solving for the optimal strategy within MV, starting with (4). We assume:

$$\int_0^T N_t dt = \int_0^T \eta^{(1)} \left(\dot{x}_t^{(1)} \right)^2 + \eta^{(2)} \left(\dot{x}_t^{(2)} \right)^2 dt \quad (29)$$

We again assumed linearity of the temporary market impact. Going further:

$$\begin{aligned} \min_x \lambda \mathbb{V} \left[C_T - x_0^{(1)} S_0^{(1)} \right] - \mathbb{E} \left[C_T - x_0^{(1)} S_0^{(1)} \right] \\ \min_x \lambda \left[\int_0^T \left[\sigma_1^2 \left(x_t^{(1)} \right)^2 + \sigma_2^2 \left(x_t^{(2)} \right)^2 + 2 \sigma_1 \sigma_2 x_t^{(1)} x_t^{(2)} \rho \right] dt \right] + \int_0^T N_t dt \\ \min_x \int_0^T \left(\lambda \left[\sigma_1^2 \left(x_t^{(1)} \right)^2 + \sigma_2^2 \left(x_t^{(2)} \right)^2 + 2 \sigma_1 \sigma_2 x_t^{(1)} x_t^{(2)} \rho \right] + N_t \right) dt \end{aligned}$$

We assume this system is equivalent to solving the below:

$$\min_x \int_0^T F \left(t, x_t^{(1)}, \dot{x}_t^{(1)}, x_t^{(2)}, \dot{x}_t^{(2)} \right) dt \quad (30)$$

4.1 Bellman equation on discretized grid

Based on the system in (30) we solve the Bellman value function, $x = (x^{(1)}, x^{(2)})$:

$$v_{t,x} = \min_x \int_0^T \left(\lambda \left[\sigma_1^2 \left(x_t^{(1)} \right)^2 + \sigma_2^2 \left(x_t^{(2)} \right)^2 + 2 \sigma_1 \sigma_2 x_t^{(1)} x_t^{(2)} \rho \right] + N_t \right) dt$$

We continue to solve by finding optimal action $\psi = (\psi^{(1)}, \psi^{(2)})$:

$$\int_0^T N_t dt = \int_0^T \eta^{(1)} \left(\psi_t^{(1)} \right)^2 + \eta^{(2)} \left(\psi_t^{(2)} \right)^2 dt \quad (31)$$

$$v \left(t + dt, x^{(1)} - \psi^{(1)} dt, x^{(2)} - \psi^{(1)} dt \right) = v_{t+dt, x-\psi dt}$$

$$v_{t,x} = \inf_{\psi} \left[v_{t+dt, x-\psi dt} + \left(\lambda \left[\sigma_1^2 \left(x_t^{(1)} \right)^2 + \sigma_2^2 \left(x_t^{(2)} \right)^2 + 2 \sigma_1 \sigma_2 x_t^{(1)} x_t^{(2)} \rho \right] + N_t \right) \right]$$

We simplify using Taylor expansion:

$$v_{t+dt, x-\psi dt} = v_{t,x} + \left(\frac{\partial v_t}{\partial t} - \psi^{(1)} \frac{\partial v_x}{\partial x^{(1)}} - \psi^{(2)} \frac{\partial v_x}{\partial x^{(2)}} \right) dt$$

$$\inf_{\psi} \frac{\partial v_t}{\partial t} - \psi^{(1)} \frac{\partial v_x}{\partial x^{(1)}} - \psi^{(2)} \frac{\partial v_x}{\partial x^{(2)}} + \lambda \left[\sum_{i=1}^2 \sum_{j=1}^2 \sigma_i \sigma_j x_t^{(i)} x_t^{(j)} \rho_{i,j} \right] + N_t = 0$$

$$\frac{\partial v_t}{\partial t} + \lambda \left[\sum_{i=1}^2 \sum_{j=1}^2 \sigma_i \sigma_j x_t^{(i)} x_t^{(j)} \rho_{i,j} \right] + \inf_{\psi} \left(N_t - \psi^{(1)} \frac{\partial v_x}{\partial x^{(1)}} - \psi^{(2)} \frac{\partial v_x}{\partial x^{(2)}} \right) = 0$$

We will thus have to implement the above, which we notice once again resembles our previous results formulated in (22), the only difference here being that this Bellman resolution will involve a two-dimensional policy.

We were not successful in implementing the two-asset policy in *Python*.

5 Deep learning approach to optimal liquidation

In this section, we try using artificial neural networks to find the optimal liquidation strategies for several orders studied in sections 2.2, 2.3 and 3. Let us first theoretically introduce deep learning, and how we could set up an architecture to attain our objective.

5.1 Neural nets theoretical foreword

In the context of optimizing a liquidation strategy, the neural network acts as a function approximator that learns to map the state of a trading system to the most profitable actions by modelling complex nonlinear relationships between inputs and outputs. For a liquidation strategy, the inputs are the time itself, the current inventory level and the current price of the asset. The output is the action, here being the quantity to sell at each time step.

The net is structured as a succession of connected layers, which allow the network to capture the complexities of the market and the relationship between inventory levels, time, and price impact. Each neuron in these layers can be thought of as learning a specific aspect of the trading strategy. Thus, a neuron weighs the importance of the specific aspect it measures, and the weights are iteratively adjusted through *backwardation* such as to optimize the trade-off between execution pace and market impact, hence minimizing liquidation cost.

The mapping is learned during the *training* phase, during which the neural network uses generated spot trajectories to learn the mapping between state variables and optimal action. The policy gradient method allows the network to improve its strategy iteratively by increasing the probability of actions that lead to lower liquidation costs.

5.2 Optimal liquidation application procedure

Here, we will expose the steps we will take to structure our deep learning model. Since the rest of this exercise will be focused on applying this method to three types of orders, a common approach will be beneficial for comparison purposes.

Each net will differ in the expression of *liquidation* and *inventory* costs. They were theoretically found in previous sections for each order type. All nets will share the same architecture and initial market parameters. Spot dynamics are simulated following (1) and will be used for orders that consider future spot values as benchmark.

We also incorporate a synthetic infinite loss if any positive inventory is observed at maturity, so that the model can imply after a few episodes that it must liquidate all before the end of the day. We will plot our model for different values of λ and study consistency with theory.

We will be implementing a feedforward neural network with *three* hidden layers of *decreasing* number of neurons, enhanced with *dropout* layers to prevent overfitting during the procedure. The *ReLU* activation function is used to account for nonlinear relationships in the data. Our learning rate within this *Adam* optimizer will be 0.1%, a popular choice for regression tasks.

5.3 IS neural nets optimal liquidation

We first decide to apply this new method to the *implementation shortfall* strategy (8). We notice that the model learns sufficiently fast the convexity inherent to the liquidation. The model also fails to capture the influences of the risk aversion, which tends to accelerates the liquidation at inception if high.

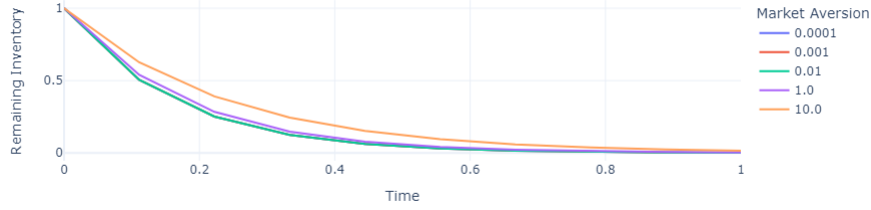


Figure 13: Neural net optimal IS liquidation for varying *risk aversion*

The model was trained considering a floating λ , so that we were able to plot different trajectories for different traders using a same trained model. We had to reduce the portfolio to $10\mathcal{L}$ to avoid further loss explosion issues. This result was observed for a total number of 250 episodes. The curve appears scattered because we highly reduced the time steps to accelerate the computation process.

5.4 POV neural nets optimal liquidation

The neural net was not at all successful at isolating an optimal liquidation strategy resembling our theoretical results. Let us now implement this algorithm for POV orders, considering the same model architecture with inventory and liquidation losses computed in (26).

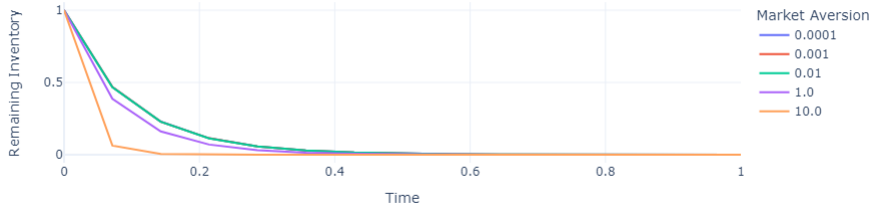


Figure 14: Neural net optimal POV liquidation for varying *risk aversion*

5.5 Introducing stochastic volatility dynamics

This final subsection will explore the addition of stochastic dynamics for the volatility of the traded asset. We will use a discretized *Cox-Ingersoll-Ross* process and observe how different the optimal liquidation strategy looks. We will model an optimal liquidation strategy for IS with one asset.

This model was originally designed to describe the evolution of interest rates [CIR85], but can be adapted to model the stochastic volatility. It can be defined using the following SDE, with σ the *vol of vol* and κ a fixed parameter on the *pace of reversion* to mean θ :

$$dV_t = \kappa(\theta - V_t) dt + \sigma\sqrt{V_t}dW_t \quad (32)$$

We can see that this model includes mean-reversion as well as non-negativity, which are natural and realistic attributes for the volatility of a stock. Since we use a discretized grid within the deep learning framework, let us provide with a discrete version of this process:

$$V_{t+\Delta t} = V_t + \kappa(\theta - V_t)\Delta t + \sigma\sqrt{V_t}\Delta t Z_t \quad (33)$$

The replacement will be rather straightforward, we will first diffuse our volatility, and at each iteration let the volatility be dynamically updated. We will thus compare to our previous liquidation strategy and comment on the changes. For comparative purposes, we use the same parameters as in the previous section.

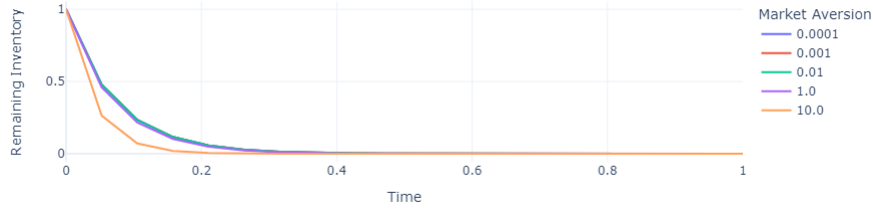


Figure 15: Neural net optimal IS liquidation with stochastic volatility

We observe that the algorithm seems to differentiate better between different levels of *risk aversion* given a stochastic volatility for the stock.

6 Conclusion and remarks

In this project, we leveraged the knowledge advanced in [AC00] to implement optimal liquidation strategies for different types of orders, while proposing some

modest contributions through the use of neural nets. We finally tried to leverage the use of deep learning into lifting some key yet highly penalizing assumptions of the model, such as the static nature of the volatility of the traded stock.

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