

A Variance-based Spectral Method Polynomial Chaos Expansion: Part I

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Outline

Notations & Assumptions

Why PCE? The main idea

PCE

- PCE in 1-2 dimension

- PCE in d-dimension

Notations & Assumptions

- ▶ $y = f(\mathbf{x})$ the scalar QoI
- ▶ $\mathbf{x} = (x_1, x_2, \dots, x_d) \sim p_{\mathbf{x}}$
- ▶ $x_i \sim p_{x_i} = \frac{dF_{x_i}}{dx_i}$, the marginal pdf (F_{x_i} cdf) of x_i
- ▶ $\mathcal{D} = \{0, 1, \dots, d\}$, $\mathcal{D}_{-i} \cap \{i\} = \emptyset$, $\mathcal{D}_{+i} \cap \{i\} \neq \emptyset$

Assumptions: $\mathbb{E}[f^2] = \int_{\mathbb{R}^d} f^2(\mathbf{x}) p_{\mathbf{x}} d\mathbf{x} < \infty$ and $p_{\mathbf{x}} = \prod_{i=1}^d p_{x_i}$

ANOVA HDMR

Variance-based Sensitivity Indices

Isoprobabilistic Transformation

$\mathbf{x} \sim p_{\mathbf{x}}$ can be transformed into $\mathbf{u} \sim \mathcal{U}(0,1)^d$ as follows,

$$\begin{cases} u_1 = F_{x_1}(x_1) \\ u_2 = F_{x_2}(x_2) \\ \vdots \\ u_d = F_{x_d}(x_d) \end{cases} \quad (1)$$

- ▶ The transformation is unique
- ▶ It requires the knowledge of the cdf's
- ▶ It is a special case of Rosenblatt transformations (adequate when $p_{\mathbf{x}} \neq \prod_{i=1}^d p_{x_i}$)

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As a consequence, $f(\mathbf{x}) = f(F_{x_1}^{-1}(u_1), \dots, F_{x_d}^{-1}(u_d)) = g(\mathbf{u})$

The sensitivity of $f(\mathbf{x})$ to x_i = The sensitivity of $g(\mathbf{u})$ to u_i

Sobol' HDMR

Under the previous assumptions, Sobol' (1993) shows that it is possible to cast $g(\mathbf{u})$ as follows,

$$g(\mathbf{u}) = g_0 + \sum_{i_1=1}^d g_{i_1}(u_{i_1}) + \sum_{i_2>i_1}^d g_{i_1,i_2}(u_{i_1}, u_{i_2}) \cdots + g_{1,\dots,d}(u_1, \dots, u_d) \quad (2)$$

$$= \sum_{\alpha \subseteq \mathcal{D}} g_{\alpha}(\mathbf{u}_{\alpha}) \quad (3)$$

with $g_0 = \mathbb{E}[g(\mathbf{u})]$, and, $\int_0^1 g_{\alpha}(\mathbf{u}_{\alpha}) du_k = 0, \forall k \in \alpha$

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As a result:

- ▶ **Sobol's hdmr is unique under our assumptions**
- ▶ **The g_{α} 's are pairwise \perp : $\mathbb{E}[g_{\alpha}g_{\beta}] = V_{\alpha}\delta_{\alpha\beta}$**

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Consequently, the total variance of y can be decomposed as a sum of partial variances,

$$V_y = \sum_{i_1=1}^d V_{i_1} + \sum_{i_2>i_1}^d V_{i_1,i_2} + \cdots + V_{1,\dots,d} \quad (4)$$

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which can be normalised as follows,

$$1 = \sum_{i_1=1}^d S_{i_1} + \sum_{i_2 > i_1}^d S_{i_1, i_2} + \cdots + S_{1, \dots, d}$$

introducing the so-called Sobol' indices.

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- ▶ $S_i = \frac{\mathbb{V}[\mathbb{E}[y|x_i]]}{\mathbb{V}[y]}$ is the first-order effect of x_i also called correlation ratio
- ▶ the remainders are called interaction effects.
- ▶ $T_i = \frac{\mathbb{E}[\mathbb{V}[y|\mathbf{x}_{-i}]]}{\mathbb{V}[y]} = \sum_{\alpha \subset \mathcal{D}_{+i}} S_{\alpha}$ is the total-order effect of x_i
- ▶ $Sh_i = \sum_{\alpha \subset \mathcal{D}_{+i}} \frac{S_{\alpha}}{|\alpha|}$ is called the Shapley effect of x_i

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We have the following relations:

- ▶ $T_i \geq Sh_i \geq S_i$
- ▶ $\sum_{i=1}^d S_i \leq 1, \sum_{i=1}^d T_i \geq 1, \sum_{i=1}^d Sh_i = 1$

Why PCE? The Main Idea

1D

The 1-dimensional case:

Consider the following polynomials:

$$L_0 = 1$$

$$L_1(x) = \sqrt{3}x$$

$$L_2(x) = \frac{\sqrt{5}}{2} (3x^2 - 1)$$

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known as the first three (normalised) Legendre polynomials

If $x \sim \mathcal{U}(-1, 1)$, then, we have the following properties:

$$\mathbb{E}[L_j(x)] = \frac{1}{2} \int_{-1}^1 L_j(x) dx = 0, \forall j > 0 \quad (\text{centered})$$

$$\mathbb{V}[L_j(x)] = \frac{1}{2} \int_{-1}^1 L_j^2(x) dx = 1, \forall j > 0 \quad (\text{normalised})$$

$$\text{Consequently, } \mathbb{E}[L_i(x)L_j(x)] = \delta_{ij} \quad (\text{orthonormality})$$

For convergence properties see, Cameron & Martin (1947) and Ernst et al. (2012).

For some probability law of x , \exists an infinite polynomial set that satisfies the previous properties called a **polynomial chaos**.

For instance, $x \sim \mathcal{N}(0, 1) \rightarrow$ (normalised) Hermite polynomials:

$$H_0 = 1$$

$$H_1(x) = x$$

$$H_2(x) = \sqrt{2} (x^2 - 1)$$

$$\vdots$$

For instance, $x \sim \Gamma(a, 1), (x, a) > 0 \rightarrow$ (normalised) Laguerre polynomials: $L_0^{(a)} = 1$

$$L_1^{(a)}(x) = \frac{1}{\sqrt{\Gamma(1+a)}} (x - a)$$

$$L_2^{(a)}(x) = \frac{1}{\sqrt{\Gamma(2+a)}} \left(\frac{1}{2}x^2 - (1+a)x - \frac{1}{2}a(1+a) \right)$$

\vdots see Xiu & Karniadakis (2002) for other RVs.

RV arbitrary distributed: If the orthogonal polynomial basis associated to p_x is unknown, then choose one of the following options,

- ▶ Transform $x \sim p_x$ into $u \sim \mathcal{U}(0, 1)$ with the integral transformation $u = F_x(x)$, and cast $y = f(x) = g(u)$ onto the shifted-Legendre polynomial
- ▶ Build the orthogonal polynomial up to degree p with the modified Gram-Schmidt transformation

In [Siml@b](#), the [second option](#) is used.

For any $f : \mathbb{E} [f^2(x)] < +\infty$, it is possible to write,

$$f(x) = \sum_{\alpha \in \mathbb{N}} a_{\alpha} \psi_{\alpha}(x)$$

where ψ_{α} denotes one possible polynomial chaos family of degree α . This is called a **polynomial chaos expansion (PCE)**.

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Advantage of such a representation: Any statistical moment of $f(x)$ can be easily computed

$$\mathbb{E} [f(x)] = a_0$$

$$\mathbb{E} [f^2(x)] = \sum_{\alpha \in \mathbb{N}} a_{\alpha}^2$$

$$\mathbb{V} [f(x)] = \sum_{\alpha \in \mathbb{N}} a_{\alpha}^2 - a_0^2$$

\vdots

2D

The 2-dimensional case:

Let $f : \mathbb{E} [f^2(x_1, x_2) < +\infty]$ with $x_1 \sim \mathcal{U}(-1, 1)$ and $x_2 \sim \mathcal{N}(0, 1)$, then, we can write

$$f(x_1, x_2) = \sum_{(\alpha_1, \alpha_2) \in \mathbb{N}^2} a_{\alpha_1 \alpha_2} \psi_{\alpha_1 \alpha_2}(x_1, x_2)$$

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that we simply write,

$$f(\mathbf{x}) = \sum_{\alpha \in \mathbb{N}^2} a_{\alpha} \psi_{\alpha}(\mathbf{x})$$

with $\mathbf{x} = (x_1, x_2)$, $\alpha = \alpha_1 \alpha_2$ and $\psi_{\alpha_1 \alpha_2}(\mathbf{x}) = L_{\alpha_1}(x_1) H_{\alpha_2}(x_2)$

L_{α_1} : α_1 -th Legendre polynomial degree

H_{α_2} : α_2 -th Hermite polynomial degree

Once again we can compute:

$$\mathbb{E}[f(\mathbf{x})] = a_{00}$$

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Further, we can show that

$$\mathbb{E}[f(\mathbf{x})|x_1] = \sum_{\alpha_1 \in \mathbb{N}} a_{\alpha_1 0} \psi_{\alpha_1 0}(x_1, x_2) = \sum_{\alpha_1 \in \mathbb{N}} a_{\alpha_1 0} L_{\alpha_1}(x_1)$$

$$\mathbb{E}[f(\mathbf{x})|x_2] = \sum_{\alpha_2 \in \mathbb{N}} a_{0 \alpha_2} \psi_{0 \alpha_2}(x_1, x_2) = \sum_{\alpha_2 \in \mathbb{N}} a_{0 \alpha_2} H_{\alpha_2}(x_2)$$

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This is important for assessing the first-order effect:

$$S_i = \frac{\mathbb{V}[\mathbb{E}[f(\mathbf{x})|x_i]]}{\mathbb{V}[f(\mathbf{x})]}$$

The ANOVA decomposition:

Recalling the ANOVA decomposition of f ,

$$f(\mathbf{x}) = f_0 + f_1(x_1) + f_2(x_2) + f_{12}(x_1, x_2)$$

with $\mathbb{E}[f(\mathbf{x})] = f_0$

$$\mathbb{E}[f(\mathbf{x})|x_1] = f_1(x_1) + f_0$$

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We see that $f_0 = a_{00}$

$$f_1(x_1) = \sum_{\alpha_1 \in \mathbb{N}^*} a_{\alpha_1 0} L_{\alpha_1}(x_1) \rightarrow \text{main effect of } x_1$$

$$f_2(x_2) = \sum_{\alpha_2 \in \mathbb{N}^*} a_{0 \alpha_2} H_{\alpha_2}(x_2) \rightarrow \text{main effect of } x_2$$

$$f_{12}(x_1, x_2) = \sum_{\alpha \in \mathbb{N}^* \times \mathbb{N}^*} a_{\alpha_1 \alpha_2} \psi_{\alpha_1 \alpha_2}(x_1, x_2) \rightarrow \text{interaction effect}$$

The Sobol' sensitivity indices:

It is straightforward to compute the Sobol' indices,

$$S_1 = \frac{\mathbb{V}[\mathbb{E}[f(\mathbf{x})|x_1]]}{\mathbb{V}[f(\mathbf{x})]} = \frac{\mathbb{V}[f_1(x_1)]}{\mathbb{V}[f(\mathbf{x})]} = \frac{\sum_{\alpha_1 \in \mathbb{N}^*} a_{\alpha_1 0}^2}{\sum_{\alpha \in \mathbb{N}^2} a_{\alpha}^2 - a_{00}^2}$$

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$$S_{12} = \frac{\mathbb{V}[f_{12}(x_1, x_2)]}{\mathbb{V}[f(\mathbf{x})]} = \frac{\sum_{\alpha \in \mathbb{N}^* \times \mathbb{N}^*} a_{\alpha_1 \alpha_2}^2}{\sum_{\alpha \in \mathbb{N}^2} a_{\alpha}^2 - a_{00}^2}$$

knowing the PCE coefficients a_{α} .

The d -dimensional PCE

d -dimension

Let $f(\mathbf{x}) \in \mathcal{L}^2$ with $\mathbf{x} = (x_1, \dots, x_d)$, its PCE writes:

$$f(\mathbf{x}) = \sum_{\alpha \in \mathbb{N}^d} a_{\alpha} \psi_{\alpha}(\mathbf{x}) \quad (5)$$

which is called the **Polynomial Chaos Expansion** of $f(\mathbf{x})$ with $\alpha = \alpha_1 \alpha_2 \dots \alpha_d$ with $\alpha_j \in \mathbb{N}$ and we denote the polynomial degree, $|\alpha| = \sum_{i=1}^d \alpha_i$.

The $|\alpha|$ -th degree multi-dimensional basis element writes:

$$\psi_{\alpha}(\mathbf{x}) = \prod_{i=1}^d \psi_{\alpha_i}(x_i)$$

d -dimension

PCE and Sobol' indices

From the PCE: $f(\mathbf{x}) = \sum_{\alpha \in \mathbb{N}^d} a_{\alpha} \psi_{\alpha}(\mathbf{x})$ it can be inferred that,

- ▶ $\mathbb{V}[f(\mathbf{x})] = \sum_{\alpha: |\alpha| > 0} a_{\alpha}^2$
- ▶ $S_i = \frac{\sum_{\alpha_i > 0} a_{0 \dots \alpha_i \dots 0}^2}{\sum_{\alpha: |\alpha| > 0} a_{\alpha}^2}$
- ▶ $S_{ij} = \frac{\sum_{\alpha_i > 0} \sum_{\alpha_j > 0} a_{0 \dots \alpha_i 0 \dots \alpha_j \dots 0}^2}{\sum_{\alpha: |\alpha| > 0} a_{\alpha}^2}$
- ▶ \vdots
- ▶ $T_i = \frac{\sum_{\alpha: \alpha_i > 0} a_{\alpha}^2}{\sum_{\alpha: |\alpha| > 0} a_{\alpha}^2}$

Conclusion: Performing GSA with PCE = Assessing the PC coefficients a_{α} .

d -dimension

Truncated PCE

In practice, only a truncated and sparse PCE is investigated:

$$f(\mathbf{x}) \simeq \sum_{\alpha \in \mathcal{A}} a_{\alpha} \psi_{\alpha}(\mathbf{x})$$

where \mathcal{A} is a non-empty **finite** subset of \mathbb{N}^d .

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If $\mathcal{A} = \{\alpha \in \mathbb{N}^d : |\alpha| \leq p\}$ then

$$\text{Card}(\mathcal{A}) = P = \frac{(p+d)!}{p!d!}, \text{ not optimal}$$

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Question 1: How to compute the PCE coefficients $a_{\mathcal{A}}$?

Question 2: How to find the optimal subset \mathcal{A} ?

Answer in Part II

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