

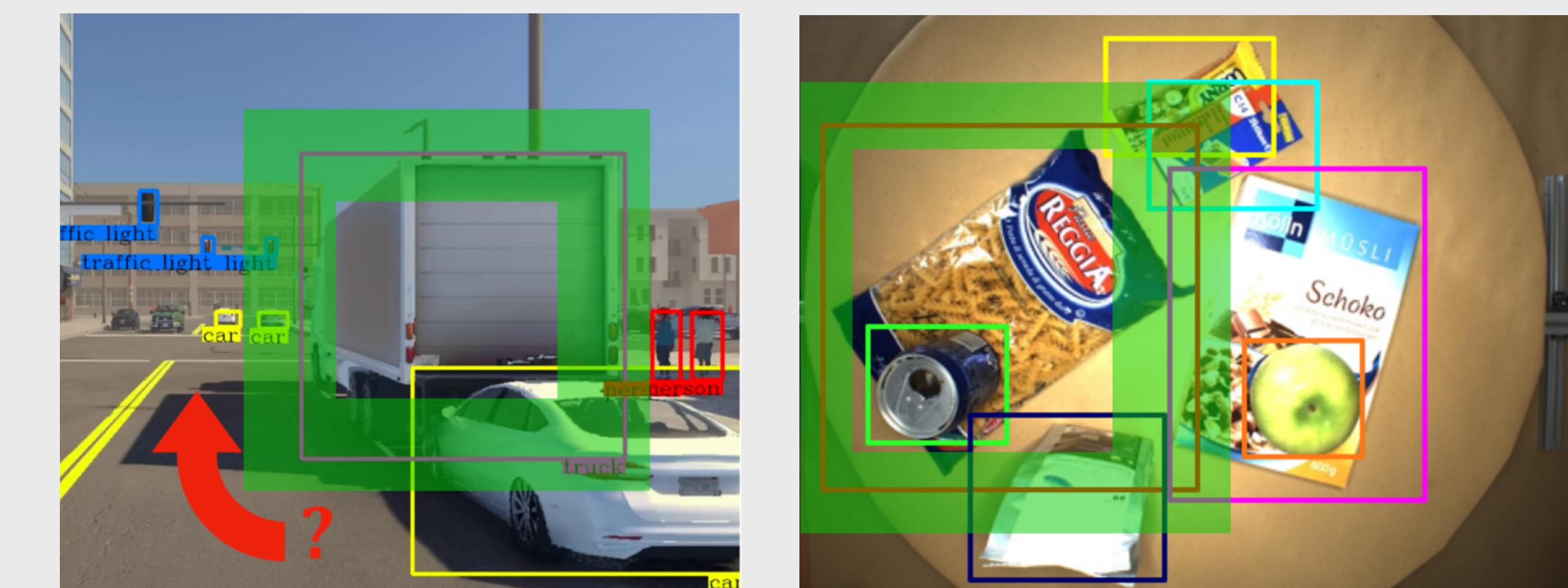
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Motivation

Autonomous agents should be able to reliably and efficiently quantify their predictive uncertainty to make safer decisions when relying on real-time bounding box predictions.

- ▶ Problem #1: How to obtain reliable bounding box uncertainties, and in what form?
- ▶ Problem #2: Object detectors predict an object's class label and its box coordinates. Both tasks exhibit uncertainty that needs to be accounted for.
- ▶ Solution (TLDR): Employ post-hoc, distribution-free conformal prediction in two steps to provide bounding box prediction intervals with coverage guarantees.



Two-Step Conformal Prediction

STEP 0

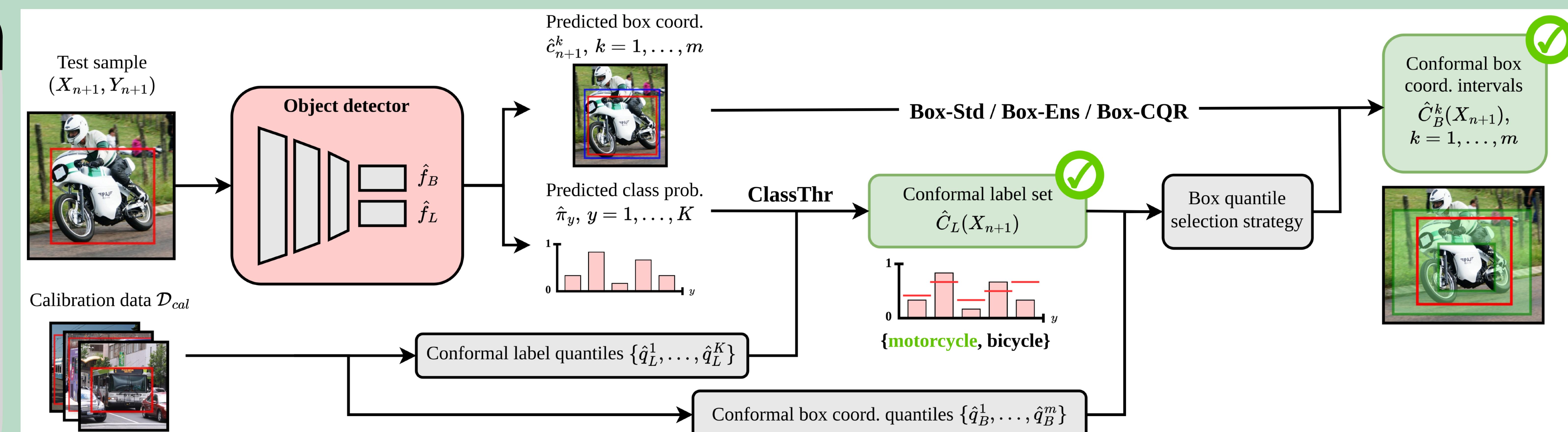
- ▶ Precompute conformal quantiles on \mathcal{D}_{cal} .
- ▶ Pass test sample through object detector.

STEP 1

- ▶ Apply conformal classification (ClassThr) to class probabilities to get a label set.

STEP 2

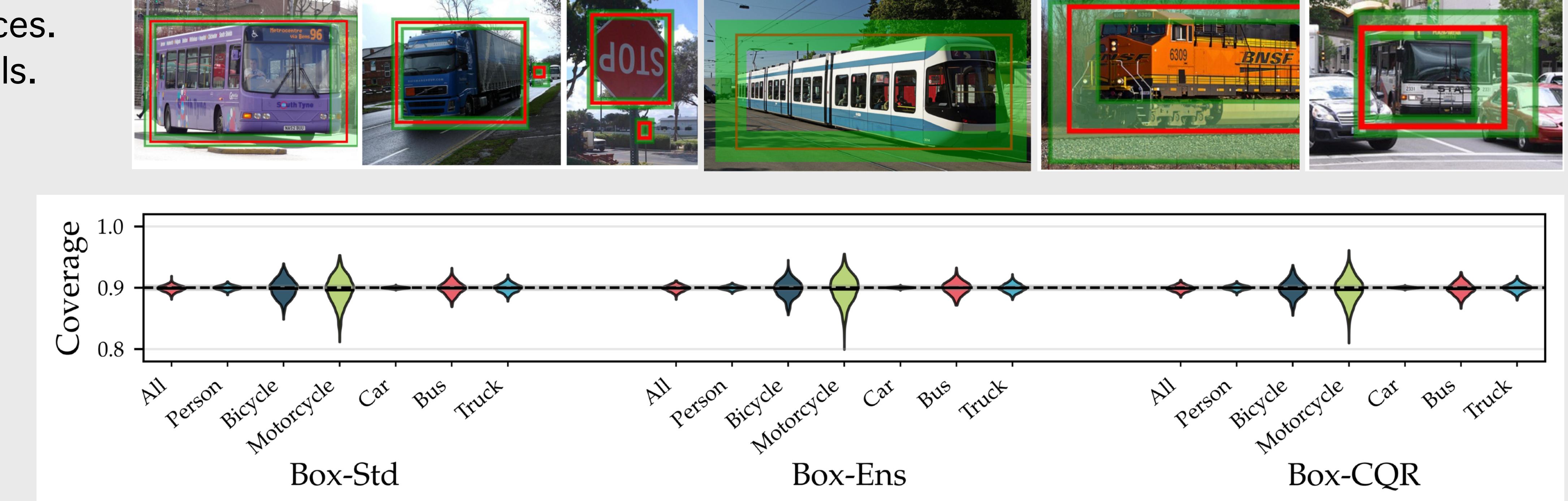
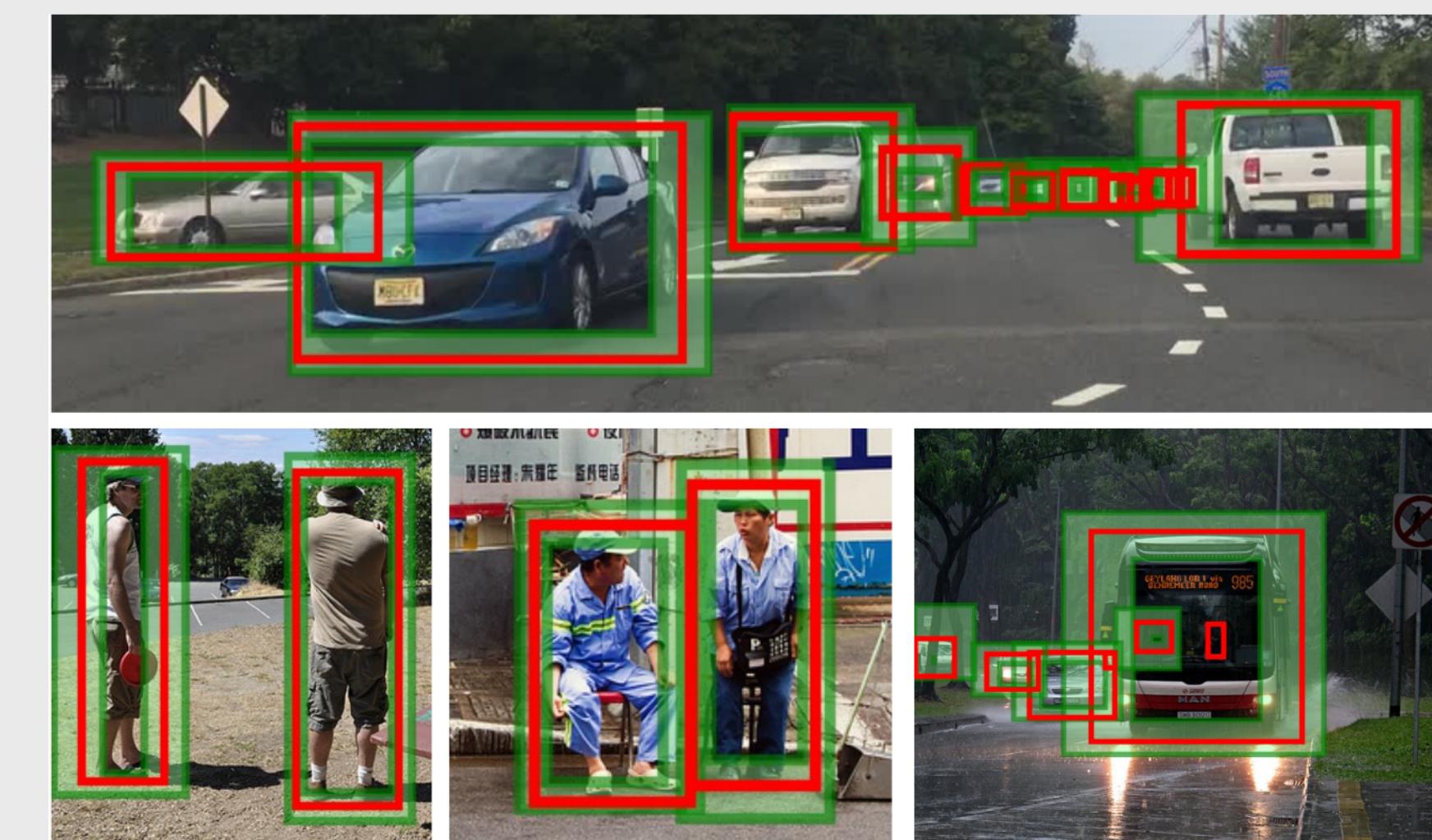
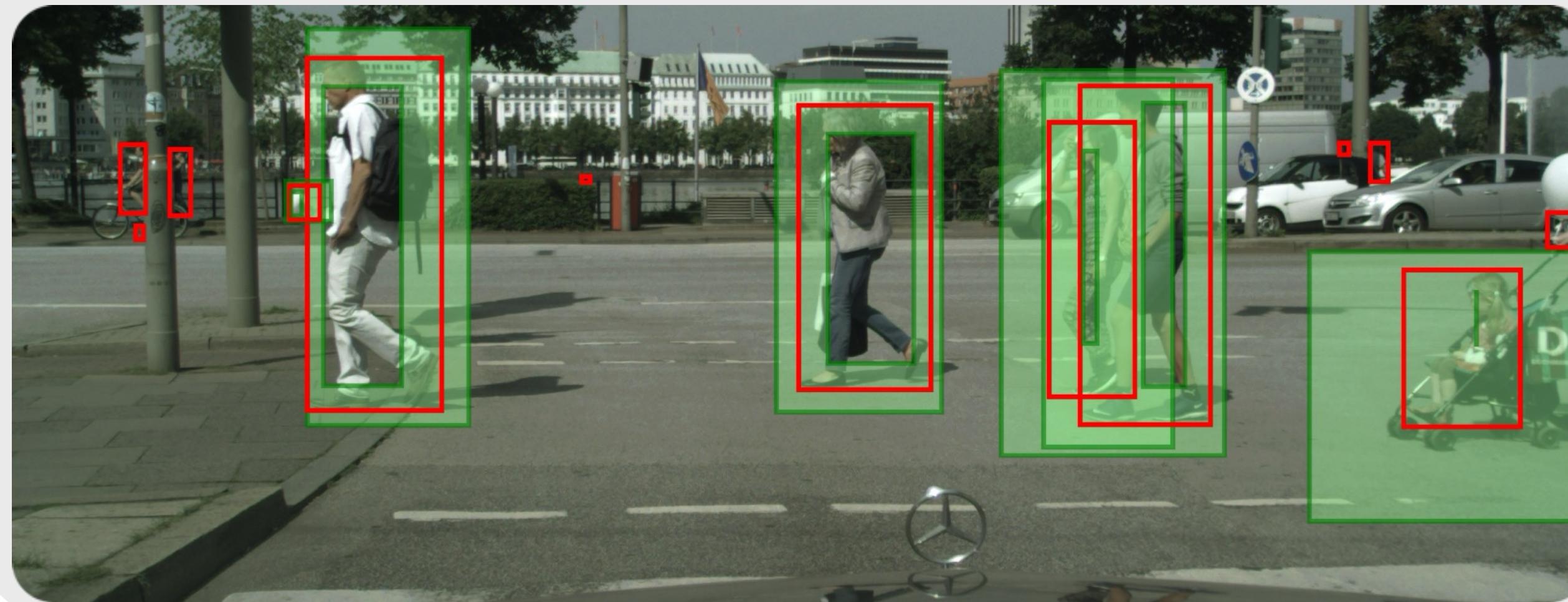
- ▶ Apply conformal regression and use label set from Step 1 to build final prediction intervals for bounding box coordinates.



Our coverage guarantee: For exchangeable (iid) calibration data \mathcal{D}_{cal} and test sample (X_{n+1}, Y_{n+1}) where $Y = (c^1, c^2, c^3, c^4, l)$, it holds that: $\mathbb{P}\left(l_{n+1} \in \hat{C}_L(X_{n+1}) \wedge \bigcap_{k=1}^m \left(c_{n+1}^k \in \hat{C}_B^k(X_{n+1})\right) \mid l_{n+1} = y\right) \geq (1 - \alpha_L)(1 - \alpha_B) \approx (1 - \alpha_B) \quad \forall y \in \mathcal{Y}$

Results

- ▶ Bounding box intervals are tight and scale adaptively with class instances.
- ▶ Guarantees hold across object classes, datasets, and 'black-box' models.



References

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- ▶ Lei et al. (2018). Distribution-free Predictive Inference (JASA)
- ▶ Angelopoulos & Bates (2023). Conformal prediction: A gentle introduction (F&T in ML)
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