

Module 3 - Eigenvalues and Eigenvectors

ME3001 - Mechanical Engineering Analysis

Mechanical Engineering

Tennessee Technological University

Topic 1 - What is an Eigenvalue and Eigenvector?

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- Mathematical Definition of Eigenvalue and Eigenvector
- Standard form Eigenvalue Problem
- The Geometrical Explanation
- A Simple Example by Hand

Mathematical Definition of Eigenvalue and Eigenvector

Did you study this in calculus? Differential Equations?

In linear algebra, an eigenvector or characteristic vector of a linear transformation is a non-zero vector whose direction does not change when that linear transformation is applied to it. More formally, if T is a linear transformation from a vector space V over a field F into itself and v is a vector in V that is not the zero vector, then v is an eigenvector of T if $T(v)$ is a scalar multiple of v . This condition can be written as the equation

$$T(v) = \lambda v$$

Mathematical Definition of Eigenvalue and Eigenvector

where λ is a scalar in the field F , known as the eigenvalue, characteristic value, or characteristic root associated with the eigenvector v .

If the vector space V is finite-dimensional, then the linear transformation T can be represented as a square matrix A , and the vector v by a column vector, rendering the above mapping as a matrix multiplication on the left hand side and a scaling of the column vector on the right hand side in the equation.

$$[A]v = \lambda v$$

Standard form Eigenvalue Problem

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ & \cdot & & \\ & \cdot & & \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \times \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ x_n \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ x_n \end{bmatrix}$$

$$\left(\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ & \cdot & & \\ & \cdot & & \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ 0 & 0 & 1 & 0 \\ & \cdot & & \\ 0 & 0 & \dots & 1 \end{bmatrix} \right) \times \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ x_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \cdot \\ \cdot \\ 0 \end{bmatrix}$$

Standard form Eigenvalue Problem

The Equations

$$(a_{11} - \lambda)x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0$$

$$a_{21}x_1 + (a_{22} - \lambda)x_2 + \dots + a_{2n}x_n = 0$$

.

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$$a_{n1}x_1 + a_{n2}x_2 + \dots + (a_{nn} - \lambda)x_n = 0$$

The Matrix Form

$$\begin{pmatrix} (a_{11} - \lambda) & a_{12} & \dots & a_{1n} \\ a_{21} & (a_{22} - \lambda) & \dots & a_{2n} \\ & . & & \\ & . & & \\ a_{n1} & a_{n2} & \dots & (a_{nn} - \lambda) \end{pmatrix} \times \begin{bmatrix} x_1 \\ x_2 \\ . \\ . \\ x_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ . \\ . \\ 0 \end{bmatrix}$$

The Geometrical Explanation

Let us look at the second matrix form more closely

$$([A] - \lambda[I])\{x\} = \{0\}$$

First we need to realize that this matrix system is *Homogenous*. This follows a different rule regarding the existence of a solution.

A *Homogeneous* system has a non-trivial solution if and only if the determinant of the coefficient matrix is zero.

$$|[A]| = 0$$

Therefore

$$|[A] - \lambda[I]| = 0$$

This leads to a long n^{th} order polynomial in terms of λ . This will have n roots which may be real or complex.

The Geometrical Explanation

3x3 example

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$
$$= a(ei - fh) - b(di - fg) + c(dh - eg)$$
$$= aei + bfg + cdh - ceg - bdi - afh.$$

A Simple Example by Hand

Example with 2D Vectors

The Geometrical Explanation

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