Module 10 - The Laplace Transform

ME3050 - Dynamics Modeling and Controls

Mechanical Engineering
Tennessee Technological University

Topic 1 - Definition of the Laplace Transform

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- An Integral Transform
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The Laplace Transform is an Integral Transform:

Given a function x(t) in the time domain where $t \ge 0$, the Laplace Transform is defined as follows:

$$X(s) = \mathcal{L}\{x(t)\} = \int_0^\infty x(t)e^{-st}dt$$

And its inverse is similarly defined as:

$$\mathcal{L}^{-1}\{X(s)\} = x(t)$$

The Laplace Domain variable s is a complex number:

$$s = \sigma + j\omega$$

It is useful to find the laplace transform of the derivative of a function:

$$\mathcal{L}\left\{\frac{d}{dt}(x(t))\right\} = \mathcal{L}\left\{\dot{x}(t)\right\} = s\mathcal{L}\left\{x(t)\right\} - x(t=0)$$
$$= sX(s) - x(t=0)$$
$$= sX(s) - x_0$$

$$\mathcal{L}\{\frac{d^2}{dt^2}(x(t))\} = \mathcal{L}\{\ddot{x}(t)\} = s^2 \mathcal{L}\{x(t)\} - sx(t=0) - \dot{x}(t=0)$$

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