Module 13 - Higher Order Systems

ME3050 - Dynamics Modeling and Controls

Mechanical Engineering
Tennessee Technological University

Topic 2 - State Space Representations

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- State Space Models
- The State Space Equation
- The Output Equation
- Simulation and Control Applications

State Space Models

- commonly used for system models
- useful for numerical simulation
- used in the area of automatic control
- an ODE system has an equivalent State Space Model representation

State Space Models

Higher Order Differential Equations - An N^{th} order differential equation can be decomposed into a system of N first order differential equations. The resulting system is equivalent to the original equation.

The State Space Equation

The State Equation After the system of differential equations consists of first order equations only, these equations form the state equation.

The State Space Equation

The State Equation

$$\dot{x} = Ax + Bu$$

- there are n state variables or states called $x_1 x_n$
- there are m inputs called $u_1 u_m$
- the state vector **x** is a collumn vector with *n* rows
- the system matrix \mathbf{A} is a square matrix n rows and n columns.
- the *input vector* **u** is a column vector with *m* rows.
- the control or input matrix B is a matrix with n rows and m columns.

The Output Equation

The Output Equation

$$y = Cx + Du$$

- the *output vector* **y** is a collumn vector with **p** rows
- the output matrix C is a square matrix p rows and n columns.
- the control matrix D is a matrix with p rows and m columns.

The designer chooses any combination of dependent variables or derived quantities for the output equation for your individual purposes. The number of outputs is flexible.

The Output Equation

Simulation and Control Applications

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References

• System Dynamics, Palm III, Third Edition - Chapter 4 - Spring and Damper Elements in Mechanical Systems - pg. 208