Lecture Module - Alternate Model Forms

ME3050 - Dynamic Modeling and Controls

Mechanical Engineering
Tennessee Technological University

Topic 1 - Equivalent Models



Alternate Model Forms

- Equivalent Model Concept
- Differential Equations
- Transfer Functions and Block Diagrams
- State-Space (Variable) Models
- Computer Models

Equivalent Model Concept

A mathematical model is an expression derived from basic principles that describes a physical or simulated system.

Models appear in different forms.

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Each form has its own advantages and disadvantages. We can convert one form into another, with differing degrees of difficulty. - Palm

Equivalent Model Concept

Standard Form of an ODE

Ordinary Differential Equations are written in the following form.

$$a_n \frac{dy^{(n)}}{d^{(n)}x} + a_{n-1} \frac{dy^{(n-1)}}{d^{(n-1)}x} + \dots + a_2 \frac{dy^2}{d^2x} + a_1 \frac{dy}{dx} + a_0 y = f(x)$$

The apostrophe is commonly used for the derivative.

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_2 y'' + a_1 y' + a_0 y = f(x)$$

The overdot notation implies that time is the independent variable.

$$a_2\ddot{y} + a_1\dot{y} + a_0y = f(t)$$

Differential Equations

Transfer Functions and Block Diagrams

The transfer function is a way of describing a system that can be used to analyze the system response to an external input with the assumption of zero intial conditions.

$$T(s) = \frac{X(s)}{F(s)}$$

Does this look familiar? How can we find the transfer function?

Transfer Functions and Block Diagrams

A block diagram is a visual representation of the transfer function concept. Here are the four basic symbols.

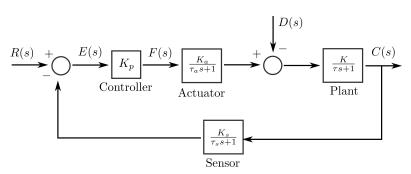
$$X(s)$$
 $Y(s)$
 $Y(s)$
 $X(s)$
 $X(s)$
 $X(s)$
 $X(s)$
 $X(s)$
 $X(s)$

Mathematical operations can be represented as block diagrams.

$$\begin{array}{c|cccc} F(s) & X(s) & F(s) & \hline & \frac{1}{s} & X(s) \\ \hline \end{array}$$

Transfer Functions and Block Diagrams

Complex systems can be desribed by block diagrams.



State-Space (Variable) Models

Computer Models