

## Module 3 - Newton's Approach

ME3050 - Dynamics Modeling and Controls

Mechanical Engineering

Tennessee Technological University

### Topic 3 - The Velocity Model

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- Example Problem - Quadcopter Model
- Mathematical Modeling
- Newton's Second Law Approach
- Derived Equations of Motion

## Example Problem - Quadcopter Model



Problem Statement - Derive the [equations of motion](#) using Newton's Second Law for the quadcopter velocity model.

Image: source needed

# Mathematical Modeling

First, consider the physical problem and list all simplifying assumptions necessary or desired. In general, the designed should start simple and add complexity incrementally.

## Quadcopter Model Assumptions:

- 1
- 2
- 3

# Newton's Second Law Approach

## Newton's Second Law Approach

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- 1 Draw a **Free Body Diagram**
- 2 Make an **assumption of motion**
- 3 Determine all **forces** acting on the system and their **directions**.
- 4 Write **Newton's second law** for the appropriate DOF.
- 5 Re-write the ODE in the **standard form** of a system equation.

# Newton's Second Law Approach - Steps 1,2 and 3

## Newton's Second Law Approach - Steps 4,5

Translation:  $\Sigma \mathbf{F} = m\mathbf{a}$      $\Sigma F_x = ma_x$   
 $\Sigma F_y = ma_y$   
 $\Sigma F_z = ma_z$

Rotation:  $\Sigma \mathbf{M} = I_o \alpha$      $\Sigma M_o = I_o \alpha_z$

# Derived Equations of Motion