Module 11 - First Order Time Response

ME3050 - Dynamics Modeling and Controls

Mechanical Engineering
Tennessee Technological University

Topic 1 - First Order Free Response

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- Model and EOM
- Solution with Laplace Transforms Method
- The Critically Damped Case
- The Underdamped Case

Model and EOM

Consider the model of the moving mass we derived.



The EOM is:

$$m\dot{v} + cv = 0$$

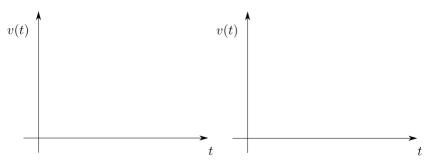
Solution with Laplace Transforms Method

$$\mathcal{L}\{m\dot{v}+cv=0\} \implies$$

We can find the expected result from the table.

Sketch Response Equation

Sketch the System Response in the time Domain.



Is this a stable system? What does that mean?

Step Input Function

Consider the model subject to a Step Input, f(t).



$$m\dot{v} + cv = f(t)$$

$$f(t) = \begin{cases} 0 & t < 0 \\ F & t \ge 0 \end{cases}$$

Solution with Laplace Transforms Method - Step 1

The method of Laplace Transforms is shown.

Solve for V(s).

Solution with Laplace Transforms Method - Step 2

Expand V(s) as a partial fraction.

'Cover up' to find the coefficients.

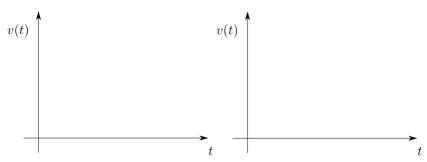
This leads to a form that can be inverted with the table.

Solution with Laplace Transforms Method - Step 3

Can you find these terms in the Table of Laplace Transforms? The inverse Laplace transform of V(s) gives the time response.

Sketch Response Equation

Sketch the System Response in the time Domain.



Is this a stable system?

Components of the Response

In these forms we can see the different components of the response.

$$v(t) = \frac{F}{C} \{ 1 - e^{-\frac{t}{\tau}} \} + v(0)e^{-\frac{t}{\tau}} = \{ v(0) - \frac{F}{c} \} e^{-\frac{t}{\tau}} + \frac{F}{c}$$

- Forced Response
- Free Response
- Transient Response
- Steady-State Response

References

 System Dynamics, Palm III, Third Edition - Section 8.1 -Response of First Order Systems - pg. 475