Model Description and Assumptions Sketches and FBDs Kinetic and Potential Energies Apply Convervation of Energy Standard Form of FOM

Module 4 - Energy Methods

ME3050 - Dynamics Modeling and Controls

Mechanical Engineering
Tennessee Technological University

Topic 3 - Example: Swinging Pendulum

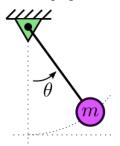
Topic 3 - Example: Swinging Pendulum

- Model Description and Assumptions
- Sketches and FBDs
- Kinetic and Potential Energies
- Apply Convervation of Energy
- Standard Form of EOM

Model Description and Assumptions

Model:

A Swinging Pendulum



Description:

A mass is suspended by a rigid link from a pin.

Assumptions:

- the mass is treated as a point mass
- the link is rigid aand mass-less
- the pin is frictionless
- the air drag is negligable

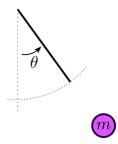


Kinetic and Potential Energies Apply Convervation of Energy Standard Form of EOM

Sketches and FBDs

First *separate* the bodies of interest to draw a **free** body diagram.





Model Description and Assumptions Sketches and FBDs Kinetic and Potential Energies Apply Convervation of Energy

Standard Form of EOM

Kinetic and Potential Energies

Model Description and Assumptions Sketches and FBDs Kinetic and Potential Energies Apply Convervation of Energy Standard Form of EOM

Apply Convervation of Energy

Model Description and Assumptions Sketches and FBDs Kinetic and Potential Energies Apply Convervation of Energy Standard Form of EOM

Standard Form of EOM