

Lecture Module - ODE Review

ME3050 - Dynamics Modeling and Controls

Mechanical Engineering

Tennessee Technological University

Topic 1 - —



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We have previously derived the accepted equation of motion for this simple but fundamental system.

$$m\ddot{x} + kx = 0$$

Dynamic Simulation

A simulation is an approximate imitation of the operation of a process or system;[1] that represents its operation over time. definition [Wikipedia](#)

System Analysis in the Time Domain

We study the motion and forces in the system as they change over time in response to various initial conditions and external forces.

This idea is known as the [time response](#) and we will discuss the derivations and resulting [response equations](#) for a generalized system model as we proceed (System Dynamics, Ch. 8).

Imagine you displaced the mass,
and then released it from rest.

Equation of Motion:

$$m\ddot{x} + kx = 0$$

Initial Position:

$$x(t = 0) = x(0) = x_0$$

Initial Velocity:


$$\dot{x}(t = 0) = v(0) = v_0$$

The **free response** is found as the *solution the differential equation* subject to known initial conditions with zero external forced applied.

$$m\ddot{x} + kx = 0 \quad , \quad x(0) = x_0 \quad , \quad \dot{x}(0) = v_0$$




$$x(t) =$$



Look at the system response subject to various initial conditions.
What determines the amplitude and frequency of oscillation?