## Power Screws and Bolted Connections

ME4020 - Applied Machine Design

Mechanical Engineering
Tennessee Technological University

## **Motor Selection**

#### **Motor Selection**

- Overview and Classification
- Open Loop and Closed Loop Control
- Motor Torque-Speed Curves
- Motor Driver/Controller
- Analysis and Selection

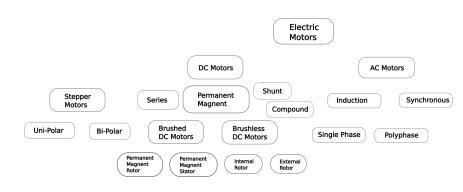
#### Overview and Classification

Open Loop and Closed Loop Control Motor Torque-Speed Curves Motor Driver/Controller **Analysis and Selection** 

## Overview and Classification



## Overview and Classification



## Overview and Classification

#### Common Electric Motor Types

— Туре —	— Example —	— Application —
	Condensor  Brush Spring Brush Wire Field Magnets  Outer Case Ball or Plain Bearing  Commutator  Shaft  Magnet Holder	

## Overview and Classification

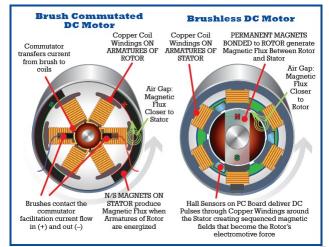
#### Common Electric Motor Types (cont.)

— Туре —	— Example —	— Applications —
	Rotor Hall Effect IC (Sensor) - Stator	
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#### Overview and Classification

Open Loop and Closed Loop Control Motor Torque-Speed Curves Motor Driver/Controller Analysis and Selection

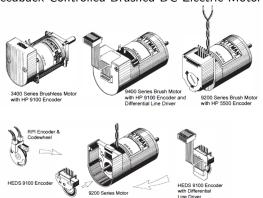
## Overview and Classification



#### Open Loop vs Closed Loop Control

- Open Loop Control
- Bang-Bang Control
- Armature Control
- Position Control
- Velocity Control

#### Feedback Controlled Brushed DC Electric Motor



Feedback Controlled Brushless DC Electric Motor Modern Case Study: Universl Robotics - Arm Joint



#### Applications:

- •
- •

#### Pros

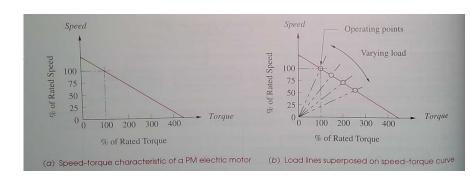
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#### Cons

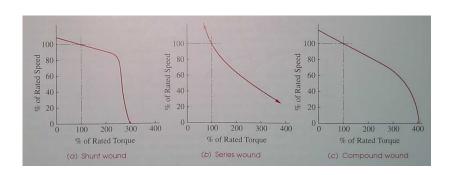
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## Open Loop and Closed Loop Control

## Motor Torque-Speed Curves



## Motor Torque-Speed Curves



## Motor Torque-Speed Curves

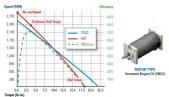


Figure 7: Speed, Torque, Efficiency Curves of a PMDC motor

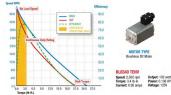


Figure 10: Speed, Torque, Efficiency Curves of a BLDC motor

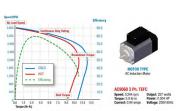


Figure 9: Speed, Torque & Efficiency Curves of an AC Induction Motor

# Motor Driver/Controller

A motor driver, aka controller, is required to operate an electric motor.

- low-level -> high-level, high-end
- open-loop, close-loop
- various signal inputs (e.g. analog, PWM, Serial, USB, etc)
- dip switches + potenionmeter configured -
- computer configuration and user interace
- feedback control integration

# Analysis and Selection

#### Considerations for Motor Selection:

- What are the torque requirements?
- What are the speed requirements?
- Does the application require a feedback control?
- What type of motor driver or controller is required?
- Does the form factor of the motor fit in the machine?

# Analysis and Selection

Haydon Kerk Pittman Ametek - Brushed DC Haydon Kerk Pittman Ametek - Brushless DC