Lecture Module - Sensors

ME3023 - Measurements in Mechanical Systems

Mechanical Engineering
Tennessee Technological University

Module 4 - Sensors



Module 4 - Sensors

- Topic 1 Introduction and Overview
- Topic 2 IC and MEMS based Sensors

Topic 1 - Introduction and Overview

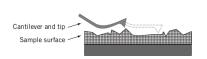
- Analog and Digital Sensors
- Example 1: Distance or Range
- Example 2: Rotation
- Example 3: Orientation

Analog and Digital Sensors

Example 1: Distance or Range Example 2: Rotation

Analog and Digital Sensors

a sensor, a physical element that employs some natural phenomenon... ...to sense the variable being measured



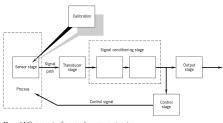


Figure 1.5 Components of a general measurement system.

Analog and Digital Sensors

Example 1: Distance or Ra Example 2: Rotation

Analog and Digital Sensors

Sensors are typically classified as either **analog** or **digital** based on the type of signal that is output from the sensor.

However, this can be a misleading term. Many digital sensors operate based on analog circuit principles but require a digital circuit or MCU to operate or comminicate.

Analog	Digital	Both?

Analog and Digital Sensors

Example 1: Distance or Ra

Example 3: Orientatio

Analog and Digital Sensors

Other Classifications:

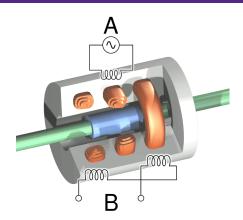
- Contact vs Non-Contact
- Programmable (Configurable) vs Non-Programmable
- By Measured Variable

Example 1: Distance or Range

Thought Exercise: How do we measure distance (aka range)?

- What variable or quantity is used to describe distance?
- What type of sensor is used to measure this?
 - •
 - •
 - •

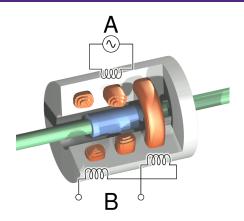
Example 1: Distance or Range



LVDTs with NI LVDT Animation



Example 1: Distance or Range



Example 3: Orientation

• What applications require this type of sensor?

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Example 3: Orientation

• How does this type of sensor work?

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Example 2: Rotation

Thought Exercise: How do we measure rotation?

- What variable or quantity is used to describe rotation?
 - •
 - •

- What type of sensor is used to measure this?
 - •
 - •
 - •

Example 2: Rotation

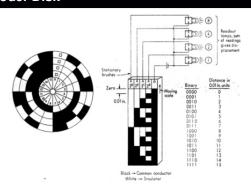
Rotational Potentiometer



Example 2: Rotation

Absolute Encoder

4-Bit Binary Optical Absolute Encoder Disk



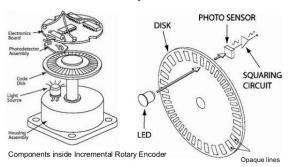




Incremental Encoder

2. Types of Rotary Encoder - Incremental

Construction of Incremental Rotary Encoder



Example 2: Rotation

• What applications require this type of sensor?

•

•

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Example 2: Rotation

• How does this type of sensor work?

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•

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Example 3: Orientation

Thought Exercise: How do we measure orientation?

- What variable or quantity is used to describe orientation?
 - •
 - •
 - •
- What type of sensor is used to measure this?
 - •
 - •
 - •

Example 3: Orientation

ADD EXAMPLE ORIENTATION SENSOR HERE

Example 3: Orientation

• What applications require this type of sensor?

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Example 3: Orientation

• How does this type of sensor work?

•

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Topic 2 - IC and MEMS based Sensors

- Integrated Circuits
- Micro Electro-Mechanical Devices
- Example 1: Accelerometer
- Example 2: Magnometer and Digital Compass

Integrated Circuits

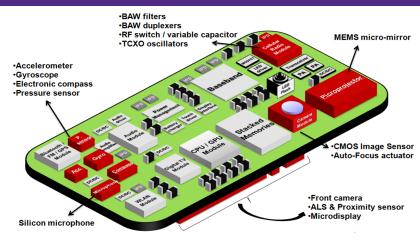
An integrated circuit (also known as an IC, a chip, or a microchip) is a set of electronic circuits on one small flat piece[a] of semiconductor material, usually silicon. Large numbers of miniaturized transistors and other electronic components are integrated together on the chip.

Integrated Circuits

Actvitity: Group Brainstorming List three applications or devices that use ICs and or IC based sensors.

- •
- •
- •

Integrated Circuits



Micro Electro-Mechanical Devices

MEMS (micro-electromechanical systems) is the technology of microscopic devices incorporating both electronic and moving parts. MEMS are made up of components between 1 and 100 micrometres in size (i.e., 0.001 to 0.1 mm), and MEMS devices generally range in size from 20 micrometres to a millimetre (i.e., 0.02 to 1.0 mm), although components arranged in arrays (e.g., digital micromirror devices) can be more than 1000 mm2.[1] They usually consist of a central unit that processes data (an integrated circuit chip such as microprocessor) and several components that interact with the surroundings (such as microsensors)

Micro Electro-Mechanical Devices



Activitity: Group Brainstorming List three sensors that are found on a high performance quadcopter or drone.

- •
- •
- •

Example 1: Accelerometer

An accelerometer is a tool that measures proper acceleration, which is the acceleration of a body in its own instantaneous frame. Applications:

- Navigation Systems Robotics Aircraft Missiles
- Personal Devices Phones Tablets
- Others:

Example 1: Accelerometer

Thought Exercise: How do we measure acceleration?

Activitity: Group Brainstorming

Explain one method for measuring acceleration of a body.

Example 1: Accelerometer

Mechanical Accelerometers Consist of a damped mass spring system and a sensing device.

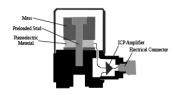
Types of accelerometers:

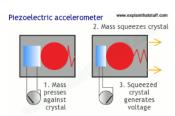
- Seismometer or Seismograph
- piezoelectric charge in material resulting from mechanical stress
- piezoresistive change in resistance resulting from mechanical stress
- capacitive

Integrated Circuits
Micro Electro-Mechanical Devices
Example 1: Accelerometer

Example 1: Accelerometer

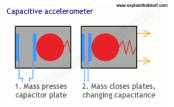
piezoelectric accelerometer





Example 1: Accelerometer

capacitive accelerometer



Example 2: Magnometer and Digital Compass

Thought Exercise: How do we measure orientation?

- What variable or quantity is used to describe motion?
 - •
 - •
 - •
- What type of sensor is used to measure this?
 - -
 - •
 - •

Example 2: Magnometer and Digital Compass

• What applications require this type of sensor?

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Example 2: Magnometer and Digital Compass

A magnetometer is a device that measures magnetic field or magnetic dipole moment. Different types of magnetometers measure the direction, strength, or relative change of a magnetic field at a particular location. A compass is one such device, one that measures the direction of an ambient magnetic field, in this case, the Earth's magnetic field. Other magnetometers measure the magnetic dipole moment of a magnetic material such as a ferromagnet, for example by recording the effect of this magnetic dipole on the induced current in a coil.