#### Lecture Module - Electrical Signals

ME3023 - Measurements in Mechanical Systems

Mechanical Engineering
Tennessee Technological University

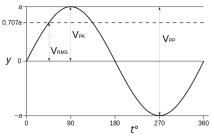
**Topic 2 - Signal Analysis** 



#### Topic 2 - Signal Analysis

- Signal Mean Value
- Power Dissipation
- Signal Root Mean Square (RMS) Value
- Discrete-Time or Digital Signals

## Signal Mean Value



#### Mean Value

$$\bar{y} \equiv \frac{\int\limits_{t_1}^{t_2} y(t)dt}{\int\limits_{t_1}^{t_2} dt}$$

#### Power Dissipation

Dissipation - Time Rate of Energy Dissipation

$$P = I^2 R$$

Total Electrical Energy

$$E = \int_{t_1}^{t_2} P dt = \int_{t_1}^{t_2} [I(t)]^2 R dt$$

# Signal Root Mean Square (RMS) Value

- For a cyclically alternating electric current, RMS is equal to the value of the direct current that would produce the same average power dissipation in a resistive load.
- In Estimation theory, the root mean square error of an estimator is a measure of the imperfection of the fit of the estimator to the data.
- The RMS value of a signal having a zero mean is a statistical measure of the magnitude of the fluctuations in the signal.

# Signal Root Mean Square (RMS) Value

$$(I_e)^2 R(t_2 - t_1) = \int_{t_1}^{t_2} [I(t)]^2 R dt$$

$$I_e = \sqrt{\frac{1}{t_2 - t_1} \int_{t_1}^{t_2} [I(t)]^2 dt}$$

$$y_{rms} = \sqrt{\frac{1}{t_2 - t_1} \int\limits_{t_1}^{t_2} [y]^2 dt}$$

Table 2.1: Theory and Design for Mechanical Measurements

## Discrete-Time or Digital Signals

$$\bar{y} = \frac{1}{N} \sum_{i=0}^{N-1} y_i$$

$$y_{RMS} = \sqrt{\frac{1}{N} \sum_{i=0}^{N-1} y_i^2}$$

Text: Theory and Design for Mechanical Measurements

Signal Mean Value Power Dissipation Signal Root Mean Square (RMS) Value Discrete-Time or Digital Signals

#### Discrete-Time or Digital Signals