

## Lecture Module - Introduction

ME3023 - Measurements in Mechanical Systems

Mechanical Engineering

Tennessee Technological University

### Topic 1 - General Measurement System

## Topic 1 - General Measurement System

- Welcome Back!
- Definition of a Measurement
- Measurement System Stages
- Examples in Mechanical Engineering

# Welcome Back!

Notes about class:

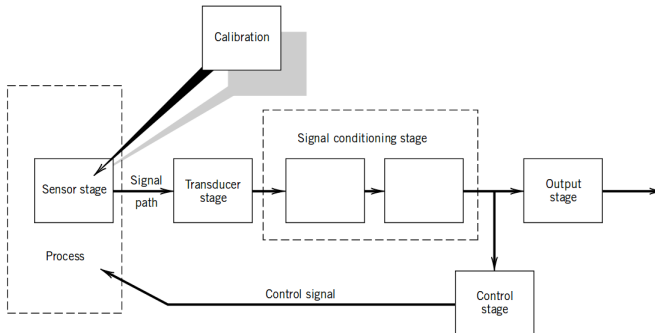
- The material will be organized in 10 to 15 min lectures. You are encouraged to ask questions.
- The lectures and most discussions will be recorded. You can watch them at anytime.

# Definition of a Measurement

“A **measurement** is an act of assigning a specific value to a physical variable.”

Text: Theory and Design of Mech. Meas.

# Measurement System Stages

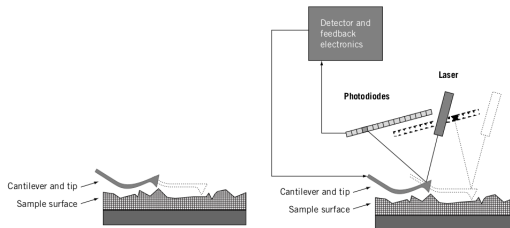


**Figure 1.5** Components of a general measurement system.

Image: Theory and Design of Mech. Meas.

# Sensor-Transducer Stage

a **sensor**, a physical element that employs some natural phenomenon... ..to sense the variable being measured

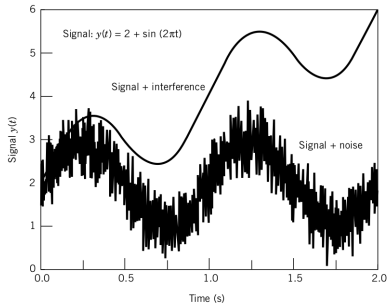


A **transducer** converts the sensed information into a detectable signal

Text, Image: Theory and Design of Mech. Meas.

# Signal Conditioning Stage

What is the the definition of **signal**?



- Filtering
- Amplification
- Attenuation
- Excitation
- Linearization
- Electrical Isolation
- Surge Protection

Image: Theory and Design of Mech. Meas.

# Output Stage

The **output stage** indicates or records the value measured. This might be a simple readout display, a marked scale, or even a recording device such as a computer disk drive.

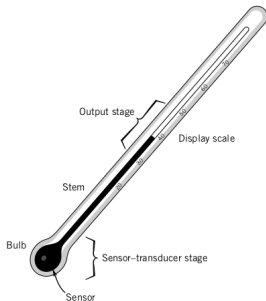


Image: Theory and Design of Mech. Meas.

Image: [Wikipedia](#)



# Examples in Mechanical Engineering

IDETC2022-96785: Development of an Instrumented Rear Suspension to Measure the Tire Forces of a Race Car During Track Driving



# Examples in Mechanical Engineering

IDETC2022-91154: Photometric Stereo Enhanced Light Sectioning  
Measurement for Microtexture Road Profiling



# Examples in Mechanical Engineering

IDETC2022-90082: Automated Weld Path Generation Using  
Random Sample Consensus and Iterative Closest Point Workpiece  
Localization

