#### Lecture Module - To Err is Human

ME3023 - Measurements in Mechanical Systems

Mechanical Engineering
Tennessee Technological University

**Topic 1 - Accuracy and Error** 



#### Topic 1 - Accuracy and Error

- Accuracy and Error
- Estimating Error
- Uncertainty Interval
- Activity with Data!

## Accuracy and Error

The exact value of a variable is called the	
The value of the variables as indicated by a	
neasurement system is called the $\_\_\_$	Γhe
of a measurement refers to the closeness of agreen	nent
petween the measured value and the true value. But the	
is rarely known, and var	rious
nfluences, called, have an effect on both of these	
values. So the concept of theof a measurement is	a
one.	

Text: Theory and Design of Mech. Meas.



# Estimating Error

		can be estimated but cannot be		
known	In practice a	value is used in		
	ue value. We will discu			
Calibration M	odule.			
2.0	f error based using this 	value is sometimes referred to		

"The	is a numerical estimate of the possible range of
the error in a	measurement. In any measurement, the
i	s not known exactly since the true value is rarely
might feel co	y. But based on available information, the operator nfident that the error is within certain bounds, a plus ge of the indicated reading. This is the assigned
	,,
We will discu	ss this again the the <i>Uncertainty Module</i> .

Text: Theory and Design of Mech. Meas.

**Experiment**: We are going to collect data with the sensor suite on our phones.

#### Sensor:

- GPS concept graphic
- info from manufacturer

#### Logger Apps:

- sensorlogger (Android) Kelvin Choi
- Sensor Logger (OSX) -Choi Tsz Hei

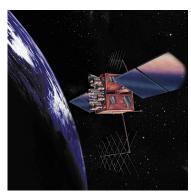
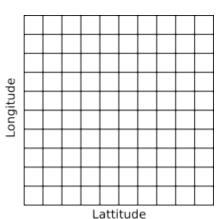


Image:Wikipedia

Part 1 - Informed Prediction: Generate data you expect the GPS in your phone to report.

i	lat;	lon;
1		
2		
3		
4		
5		
6		
7		
8		
8		
9		
10		



lmage: thill

Part 3 - Measurement: Compare and constrast the data from the two sources.

i	lat;	lon;
1		
2		
2 3 4		
4		
5 6		
7		
8		
8		
9		
10		

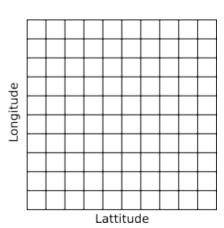


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