## Lecture Module - Strain Applications

ME3023 - Measurements in Mechanical Systems

Mechanical Engineering
Tennessee Technological University

Module 9 - Strain Applications



### Module 9 - Strain Applications

- Topic 1 Beam Models
- Topic 2 Multiple Gauge Bridge
- Topic 3 -

### Topic 1 - Beam Models

- Euler-Bernoulli Beam Theory
- Force-Deflection Model
- Cantilevered Beam
- Deflection and Strain





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## Euler-Bernoulli Beam Theory

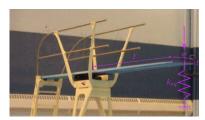
Euler-Bernoulli beam theory (also known as engineer's beam theory or classical beam theory)[1] is a simplification of the linear theory of elasticity which provides a means of calculating the load-carrying and deflection characteristics of beams. It covers the case for small deflections of a beam that are subjected to lateral loads only.

# Euler-Bernoulli Beam Theory

It is thus a special case of Timoshenko beam theory. It was first enunciated circa 1750,[2] but was not applied on a large scale until the development of the Eiffel Tower and the Ferris wheel in the late 19th century. Following these successful demonstrations, it quickly became a cornerstone of engineering and an enabler of the Second Industrial Revolution.

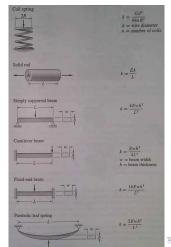
Additional mathematical models have been developed such as plate theory, but the simplicity of beam theory makes it an important tool in the sciences, especially structural and mechanical engineering.

### Force-Deflection Model



These stiffness equations come from the beam deflection equations you have and will study.

You can see them here or look in your copy of Shigleys, and here is a good section on beam analysis analysis.

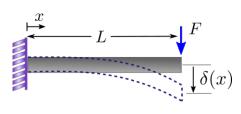


Euler-Bernoulli Beam Theory Force-Deflection Model Cantilevered Beam Deflection and Strain

### Force-Deflection Model

### Cantilevered Beam

The beam equations relate internal moment and shear as well as deflection along the length of the beam to the given beam geometry and loading.



$$\delta(x) = -\frac{Fx^2}{6EI}(3L - x)$$

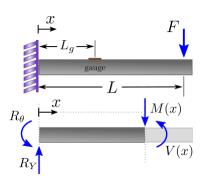
$$\delta_{\it max} = \delta|_{\it x=L} = -rac{\it FL^3}{\it 3EI}$$

$$\theta(x) = -\frac{Fx}{2EI}(2L - x)$$

$$\theta_{\it max} = \theta|_{x=\it L} = -rac{\it FL^2}{\it 2\it E\it I}$$

### Cantilevered Beam

The shear and moment are both given as a function of x, the direction along the beam.

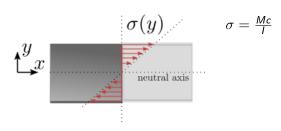


$$M(x) = -F(L - x)$$

$$M_{max} = M|_{x=0} = -FL$$

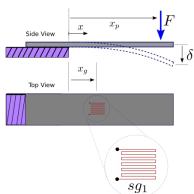
### Cantilevered Beam

The internal stress is given as a function of y, the distance from the neutral axis.



#### Deflection and Strain

Now, with the beam equations you can relate measured strain at a known location to deflection at the end of the beam. These equations are available for many different beam types and loading conditions. Beam Eq's



Euler–Bernoulli Beam Theory Force-Deflection Model Cantilevered Beam Deflection and Strain

#### Deflection and Strain

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#### Deflection and Strain

The Quarter Bridge Jsing Multiple Gauges Apparent Strain and Temperaturo Example: Digital Scale

### Topic 2 - Multiple Gauge Bridge

- The Quarter Bridge
- Using Multiple Gauges
- Apparent Strain and Temperature
- Example: Digital Scale

he Quarter Bridge

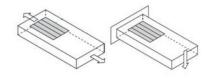
Apparent Strain and Temperature

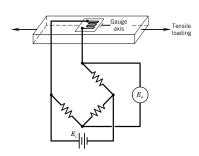
# The Quarter Bridge

Hooke's law describes the linear relationship between stress and strain of an elastic member with modulus of elasticity E.

$$\sigma = \mathbf{E}\epsilon$$

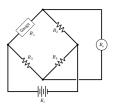
If the loading is known the beam models can be applied.





# The Quarter Bridge

Consider the quarter bridge case in which the gauge is  $R_1$  and  $R_1 = R_2 = R_3 = R_4$  in a condition of zero strain.



$$E_{out} = E_{in} \times \left( \frac{R_1}{R_1 + R_2} - \frac{R_3}{R_3 + R_4} \right) \implies E_{out} = E_{in} \frac{(R_1 R_4 - R_2 R_3)}{(R_1 + R_2)(R_3 + R_4)}$$

Now,  $R_1$  changes by  $\delta R$  causing  $E_{out}$  to change by  $\delta E_{out}$ 

$$E_{out} + \delta E_{out} = E_{in} \frac{((R_1 + \delta R)R_4 - R_2R_3)}{((R_1 + \delta R) + R_2)(R_3 + R_4)}$$

# The Quarter Bridge

In practice the bridge is balanced in a condition of zero strain which gives an output voltage of  $E_{out} = 0v$ . Then any additional strain causes a  $\delta E_{out}$  which is measured.

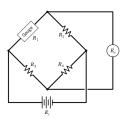
The previous equation is commonly written in the following practical form.

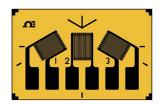
$$\frac{\delta E_{out}}{E_{in}} = \frac{\delta R/R}{4 + 2(\delta R/R)} \approx \frac{\delta R/R}{4} \quad \text{or} \quad \frac{\delta E_{out}}{E_{in}} = \frac{GF\epsilon}{4 + 2GF\epsilon} \approx \frac{GF\epsilon}{4}$$

with Gage Factor defined as 
$$GF \equiv \frac{\delta R/R}{\delta L/L} = \frac{\delta R/R}{\epsilon}$$

## Using Multiple Gauges

An improved system uses a set of gauges known as a rosette with the wheatstone bridge in a half or full bridge configuration.





















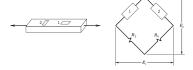






# Using Multiple Gauges

If multiple gauges are used the relationship between strain and output voltage is derived with a similar process (see page 479).



The result gives an expression relating the output voltage, the gauge factor, and all four measured strains.

$$rac{\delta E_{out}}{E_{in}} = rac{GF}{4} \left( \epsilon_1 - \epsilon_2 + \epsilon_4 - \epsilon_3 
ight)$$

## Apparent Strain and Temperature

Equation 11.22 shows that for a bridge containing one or more strain gauges, equal strains on opposite bridge arms sum, whereas equal strains on adjacent arms of the bridge cancel. These characteristics can be used to increase the output of the bridge, to provide temperature compensation, or to cancel unwanted components of strain.

Text: Theory and Design of Mechanical Measurements

This summarizes the reasons to use a wheatstone instead of a operational amplifier when measuring strain with a metallic strain gauge.

## Apparent Strain and Temperature

	Arrangement	Compensation Provided	Bridge Constant κ
	Single gauge in uniaxial stress	None	κ = 1
	Two gauges sensing equal and opposite strain—typical bending arrangement	Temperature	κ = 2
<u>↓</u> 1	Two gauges in uniaxial stress	Bending only	$\kappa = 2$
4 3	Four gauges with pairs sensing equal and opposite strains	Temperature and bending	к=4
Shaft Q-G	One axial gauge and one Poisson gauge		κ= 1 +ν
Shall — E	Four gauges with pairs sensing equal and opposite strains—sensitive to torsion only; typical shaft arrangement.	Temperature and axial	κ = 4

The Quarter Bridge
Using Multiple Gauges
Apparent Strain and Temperature

## Apparent Strain and Temperature

The Quarter Bridge
Using Multiple Gauges
Apparent Strain and Temperature
Example: Digital Scale

## Example: Digital Scale

Have you ever wondered how a digital scale works?

Does it matter where you place item? Why or why not?



The Quarter Bridge
Using Multiple Gauges
Apparent Strain and Temperature
Example: Digital Scale

# Example: Digital Scale

### Topic 3 -

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