train transfer learning

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[]: from keras.layers import Input, Dense, Conv2D, MaxPool2D, Flatten, Dropout,

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→BatchNormalization, Activation, Add
     from keras.optimizers import Adam
     from keras.models import Model
     from keras.callbacks import ModelCheckpoint, EarlyStopping
     import keras
     import matplotlib.pyplot as plt
     import numpy as np
     from sklearn.model_selection import train_test_split
     from keras.preprocessing.image import ImageDataGenerator
     from keras.applications.resnet50 import preprocess_input
     from keras.applications.resnet import ResNet50 as resnet50
     import os
     from tqdm import tqdm
     import json
     import glob
[]: import tensorflow as tf
     gpus= tf.config.experimental.list_physical_devices('GPU')
     tf.config.experimental.set_memory_growth(gpus[0], True)
[]: def resnet50_conv(shape):
             Load Resnet convolutional layers' and set the input image shape of \Box
      \rightarrow network.
             input: A tupe containing 3 dimensions with input shape (H, W, C) RGB.
             returns: Model with convolutional layers only.
         111
         input_tensor = Input(shape=shape)
         resnet_model_top = resnet50(include_top=True, weights='imagenet',_
      →input_tensor=input_tensor)
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resnet_model_top.summary()
        return resnet_model_top
[]: # Defines input shape and gets resnet50v1 backbone
    input\_shape = (224, 224, 3)
    (w, h, _) = input_shape
    net = resnet50_conv(input_shape)
[]: # Helps to see the name and position of each layer.
    lay_nb = 0
    for layer in net.layers:
        #print(layer)
        print(layer.name)
        #print(layer.output)
        lay nb += 1
        lay_name = layer.name
          if layer.name == 'conv4 block6 out':
              break
        if layer.name == 'avg_pool':
            break
    print(lay_nb)
    print(lay_name)
[]: def create_custom_model(net, optm, classes, questao6):
            Fine tunning implementation according to exercise 5 and 6.
           ш
     net: Resnet50 pre-trained model
            optm: Optmizer used to train the network.
            classes: Number of classes in dataset.
            questao6: If wants to implement the Exercise 5 implementation put the ∪
     \hookrightarrow flag to False. Othewise,
            It will implement exercise 6 with custom fully-connected layers and \Box
     \rightarrow another convolutional block.
            returns: Model compiled.
        111
        # Gets the average pooling layer.
        x = net.layers[-2].output
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# flatten + fully-connected + softmax activation
        if(questao6 == True):
            x = Dense(1024, activation='relu')(x)
            x = Dense(1024, activation='relu')(x)
            x = Dense(1024, activation='relu')(x)
        x = Dropout(0.25)(x)
        x = Dense(classes, activation='softmax')(x)
        custom_model = Model(net.input,x)
        # Froze layers
        for layer in custom_model.layers[:176]:
            if( "conv5_block3" in layer.name or "avg_pool" in layer.name):
               layer.trainable = True
            else:
               layer.trainable = False
            if(questao6 == True):
                if( "conv5_block2" in layer.name):
                   layer.trainable = True
        # Compile it
        custom_model.compile(loss='categorical_crossentropy',
                          optimizer=optm,
                          metrics=['accuracy'])
        return custom_model
[]: def create_custom_model_q7(net, optm, classes):
           Fine tunning implementation according to exercise 7. convolutional \sqcup
     → layer 5 is implemented from
            scratch. Other layers before convolutional layer 5 are frozen.
            Custom dense layers are implemented also.
     net: Resnet50 pre-trained model
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optm: Optmizer used to train the network.

classes: Number of classes in dataset.

returns: Model compiled.

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layer_dict = dict([(layer.name, layer) for layer in net.layers])
   conv4_block6_out = layer_dict['conv4_block6_out'].output
   # Custom Convolutional layers
   # custom_conv_block1
   momemtum=0.8
   activation f = 'relu'
   # conv block 1 1
   x = Conv2D(512, (1,1), strides=1, activation='linear', __
→padding='same')(conv4_block6_out)
   x = BatchNormalization(momentum=momentum)(x)
   x = Activation(activation f)(x)
   # conv_block_1_2
   x = Conv2D(512, (3,3), strides=1, activation='linear', padding='same')(x)
   x = BatchNormalization(momentum=momentum)(x)
   x = Activation(activation f)(x)
   # conv_block_1_0
   y = Conv2D(2048, (1,1), strides=1, activation='linear', __
→padding='same')(conv4_block6_out)
   y = BatchNormalization(momentum=momentum)(y)
   # conv_block_1_3
   x = Conv2D(2048, (1,1), strides=1, activation='linear', padding='same')(x)
   x = BatchNormalization(momentum=momentum)(x)
   x = Add()([y, x])
   custom_conv_block1_out = Activation(activation_f)(x)
   # custom_conv_block2
   x = Conv2D(512, (1,1), strides=1, activation='linear', __
→padding='same')(custom_conv_block1_out)
   x = BatchNormalization(momentum=momentum)(x)
   x = Activation(activation f)(x)
   x = Conv2D(512, (3,3), strides=1, activation='linear', padding='same')(x)
   x = BatchNormalization(momentum=momemtum)(x)
   x = Activation(activation_f)(x)
   x = Conv2D(2048, (1,1), strides=1, activation='linear', padding='same')(x)
   x = BatchNormalization(momentum=momentum)(x)
   x = Add()([custom_conv_block1_out, x])
   custom_conv_block2_out = Activation(activation_f)(x)
   # custom_conv_block3
   x = Conv2D(512, (1,1), strides=1, activation='linear',
→padding='same')(custom_conv_block2_out)
   x = BatchNormalization(momentum=momentum)(x)
   x = Activation(activation_f)(x)
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x = Conv2D(512, (3,3), strides=1, activation='linear', padding='same')(x)
         x = BatchNormalization(momentum=momentum)(x)
         x = Activation(activation_f)(x)
         x = Conv2D(2048, (1,1), strides=1, activation='linear', padding='same')(x)
         x = BatchNormalization(momentum=momemtum)(x)
         x = Add()([custom_conv_block2_out, x])
         custom_conv_block3_out = Activation(activation_f)(x)
         #Global Aerage Pooling
         x = layer_dict['avg_pool'](custom_conv_block3_out)
         # custom fully-connected + softmax activation
         x = Dense(1024, activation='relu')(x)
         x = Dense(1024, activation='relu')(x)
         x = Dense(1024, activation='relu')(x)
         x = Dropout(0.25)(x)
         x = Dense(classes, activation='softmax')(x)
         custom_model = Model(net.input,x)
         # Froze layers
         for layer in custom_model.layers[:143]:
                 layer.trainable = False
         # Compile it
         custom_model.compile(loss='categorical_crossentropy',
                            optimizer=optm,
                            metrics=['accuracy'])
         return custom_model
[]: lr = 0.5e-5
     optm = Adam(learning_rate = lr, decay=0.001)
     classes = 5
     #custom_resnet =
     → create_custom_model(net,optm,lay_name,lay_nb,classes,questao6=False)
     custom_resnet = create_custom_model_q7(net,optm,lay_name,lay_nb,classes)
[]: custom_resnet.summary()
[]: train_datagen = ImageDataGenerator(validation_split=0.2,__
      →preprocessing_function=preprocess_input) # set validation split
[]: #Defines the batch-size and keras generators
     batch_size = 32
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train_data_dir = 'Dataset/flower_photos/all'
     train_generator = train_datagen.flow_from_directory(
         train_data_dir,
         target_size=(w,h),
         batch_size=batch_size,
         class_mode='categorical',
         shuffle=True, seed=42,
         subset='training') # set as training data
     val_generator = train_datagen.flow_from_directory(
         train_data_dir, # same directory as training data
         target_size=(w,h),
         batch_size=batch_size,
         class_mode='categorical',
         shuffle=True, seed=42,
         subset='validation') # set as validation data
[]: # Gets the total number of images in dataset
     filenames = train_generator.filenames
     samples = len(filenames)
     print(samples)
[]: | # Defines Early Stopping and sabe the best model during training before
     \rightarrow overfitting.
     file_name = 'best_model.h5'
     checkpointer = ModelCheckpoint(file name, monitor='val accuracy', __
     →save_best_only=True)
     early_stop = EarlyStopping(monitor = 'val_accuracy', min_delta = 0.001,
     mode = 'max', patience = 10)
     callbacks=[checkpointer,early_stop]
[]: # Defines number of epochs and train the model
     epochs = 100
     steps_in_epoch = samples // batch_size
     history = custom_resnet.fit_generator(train_generator,_
     →steps_per_epoch=steps_in_epoch, epochs=epochs,
                                   validation_data=val_generator, __
      →validation_steps=1,
                                   verbose=1,callbacks=callbacks)
[]: def graph_training_history(history):
         acc_train = history['accuracy']
         acc_test = history['val_accuracy']
         loss_train = history['loss']
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loss_test = history['val_loss']
plt.rcParams['axes.facecolor']='white'
fig = plt.figure(1)
# summarize history for accuracy
plt.subplot(121)
plt.plot(acc_train)
plt.plot(acc_test)
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.tight_layout()
# summarize history for loss
plt.subplot(122)
plt.plot(loss_train)
plt.plot(loss_test)
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper right')
plt.tight_layout()
plt.show()
fig.savefig('weights/history.png', dpi=fig.dpi)
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[]: graph_training_history(history.history)
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[]: # Saving history
    with open('weights/history_model.json', 'w') as f:
         json.dump(str(custom resnet.history.history), f)
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[]: