

## 1. Design a Low Pass Digital Filter by Windowing (M=3, rectangular window)

1a) Filter coefficients are

Coeffs = [0.8, 0.1015, 0.1611, 0.2457, 0.3363, 0.4131, 0.4589, 0.4635, 0.4251, 0.3505, 0.2530, 0.1493, 0.0554, -0.0167, -0.0671, -0.0774, -0.0727, -0.0559, -0.0364, -0.0219, -0.158];

1b)

$$H(e^{j\omega}) = \sum_{n=0}^3 \left[ 0.54 - 0.46 \cos\left(\frac{2\pi n}{M-1}\right) \right] \times \frac{\sin(\omega_c n)}{\pi n}$$

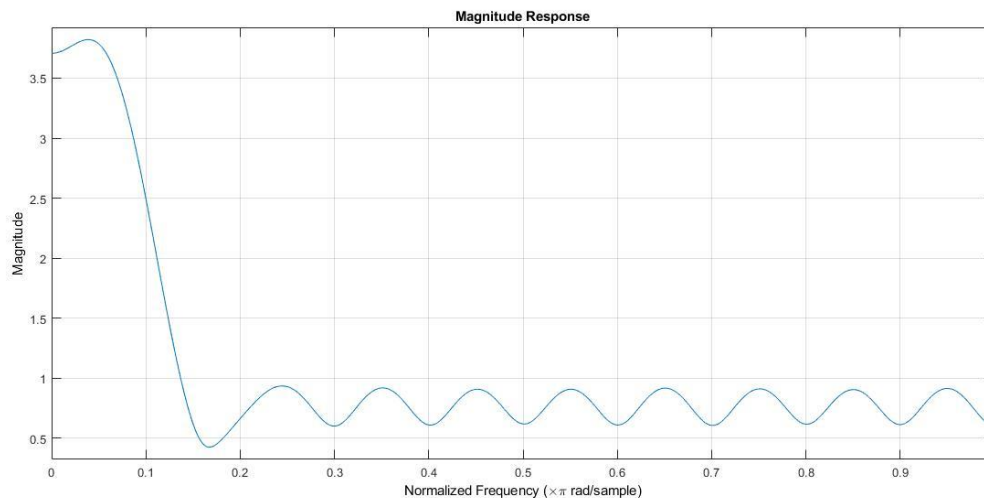
$$H(e^{j\omega}) = 0.54 \sum_{k=0}^n \delta(\omega - 2\pi k) - \sum_{n=0}^3 \left[ 0.46 \cos\left(\frac{2\pi n}{M-1}\right) \right] \times \frac{\sin(\omega_c n)}{\pi n}$$

1c) First zero occurs at 0.8.

1d) Actual cut-off frequency is 1840 Hz from the frequency response

1e) %age error =  $\frac{2000-1840}{2000} \times 100 = 0.0543\%$

1f) fvtool() frequency response plot from MatLab - linear magnitude scale



## 2. Implement a Low Pass Filter in Python (M=3, rectangular window)

```
#!/usr/bin/python
```

```
import sys
import time
import math
```

```
import base64
import random as random
```

```

import datetime
import time

from cpe367_wav import cpe367_wav
from my_fifo import my_fifo

#####
#####
# define routine for implementing a digital filter
def process_wav(fpath_wav_in,fpath_wav_out):
    """
        : this example implements a very useful system:  $y[n] = x[n]$ 
        : input and output is accomplished via WAV files
        : return: True or False
        """

    # construct objects for reading/writing WAV files
    # assign each object a name, to facilitate status and error reporting
    wav_in = cpe367_wav('wav_in',fpath_wav_in)
    wav_out = cpe367_wav('wav_out',fpath_wav_out)

    # open wave input file
    ostat = wav_in.open_wav_in()
    if ostat == False:
        print('Cant open wav file for reading')
        return False

    # setup configuration for output WAV
    # num_channels = 2
    # sample_width_8_16_bits = 16
    # sample_rate_hz = 16000
    #
    wav_out.set_wav_out_configuration(num_channels,sample_width_8_16_bits,sample_rate_hz)

    # configure wave output file, mimicking parameters of input wave (sample rate...)
    wav_out.copy_wav_out_configuration(wav_in)

    # open WAV output file
    ostat = wav_out.open_wav_out()
    if ostat == False:
        print('Cant open wav file for writing')
        return False

    # students - allocate your fifo, with an appropriate length (M)
    M = 3

```

```

fifo = my_fifo(M)

# students - allocate filter coefficients, length (M)
# students - these are not the correct filter coefficients
bk_list = 1/M#[1/M, 1/M, 1/M]

# process entire input signal
xin = 0
while xin != None:

    # read next sample (assumes mono WAV file)
    # returns None when file is exhausted
    xin = wav_in.read_wav()
    if xin == None: break

#####
#####
# students - go to work!

# update history with most recent input
fifo.update(xin)

# evaluate your difference equation
yout = 0
h_ideal = 0
W_hamm = 0
fc=2000
for k in range(M):

    # use your fifo to access recent inputs when evaluating your diff eq
    #  $y[n] = b[k] * x[n-k]$ 
    h_ideal = math.sin(2*math.pi*fc*k)/math.pi*k
    W_hamm = 0.54-(0.46*math.cos((2*math.pi*k)/(M-1)))
    print(W_hamm*h_ideal)
    yout += W_hamm*h_ideal * fifo.get(k)

# students - well done!
#####
#####

# convert to signed int
yout = int(round(yout))

# output current sample
ostat = wav_out.write_wav(yout)
if ostat == False: break

```

```

# close input and output files
# important to close output file - header is updated (with proper file size)
wav_in.close_wav()
wav_out.close_wav()

return True
#####
#####
# define main program
def main():

    # check python version!
    major_version = int(sys.version[0])
    if major_version < 3:
        print('Sorry! must be run using python3.')
        print('Current version: ')
        print(sys.version)
        return False

    # grab file names
    fpath_wav_in = 'in_noise.wav'
    fpath_wav_out = 'out_noise.wav'

    #####
    #####
    # test signal history
    # feel free to comment this out, after verifying

    # allocate history
    M = 3
    fifo = my_fifo(M)

    # add some values to history
    fifo.update(1)
    fifo.update(2)
    fifo.update(3)
    fifo.update(4)

    # print out history in order from most recent to oldest
    print('signal history - test')
    for k in range(M):
        print('hist['+str(k)+']='+str(fifo.get(k)))

    #####
    #####

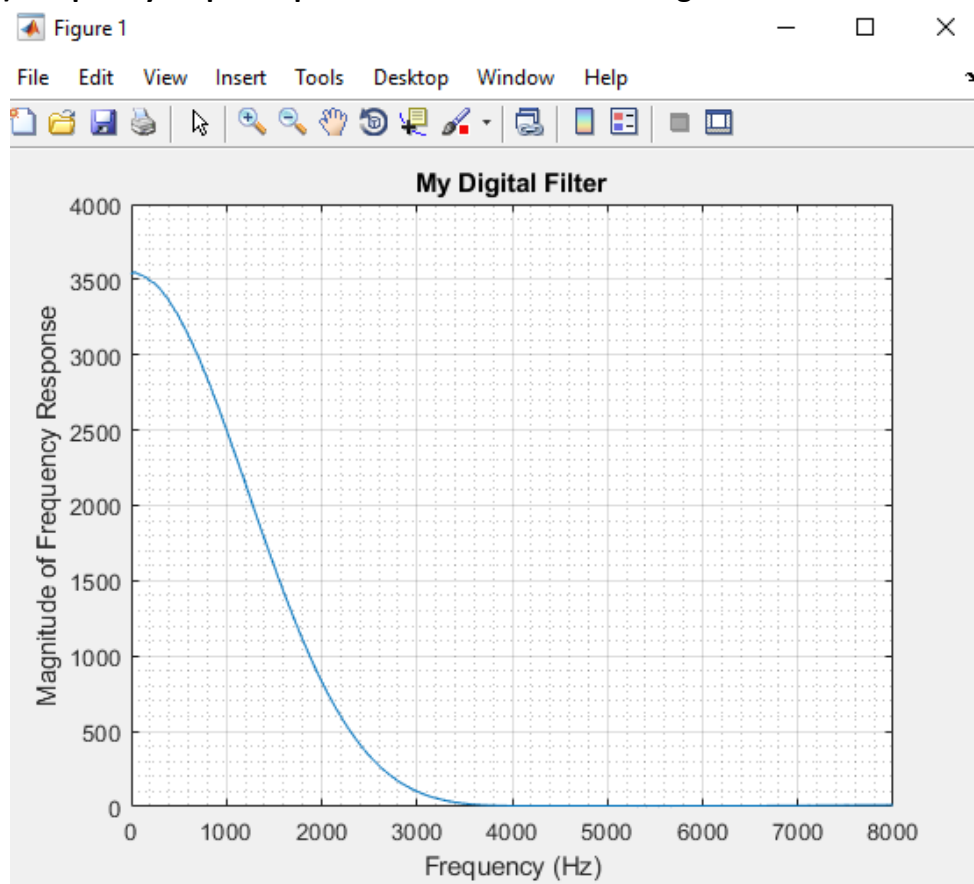
```

```
# let's do it!
return process_wav(fpath_wav_in,fpath_wav_out)
```

```
#####
#####
# call main function
if __name__ == '__main__':

    main()
    quit()
```

## 2a) Frequency response plot from MatLab - linear magnitude scale



## 3. Design a Bandpass Digital Filter and Implement in Python (M=21, Hamming window)

### 3a) What are the coefficients of your bandpass filter

|             |             |             |             |            |             |
|-------------|-------------|-------------|-------------|------------|-------------|
| 3538.778683 | 3545.872747 | 3547.401477 | 3541.588431 | 3535.44815 | 3530.302934 |
| 3528.008447 | 3515.172452 | 3514.507572 | 3498.417155 |            |             |

**3b) Upload the portion of your Python code that computes the filter coefficients and then modulates the impulse response to yield the bandpass filter**

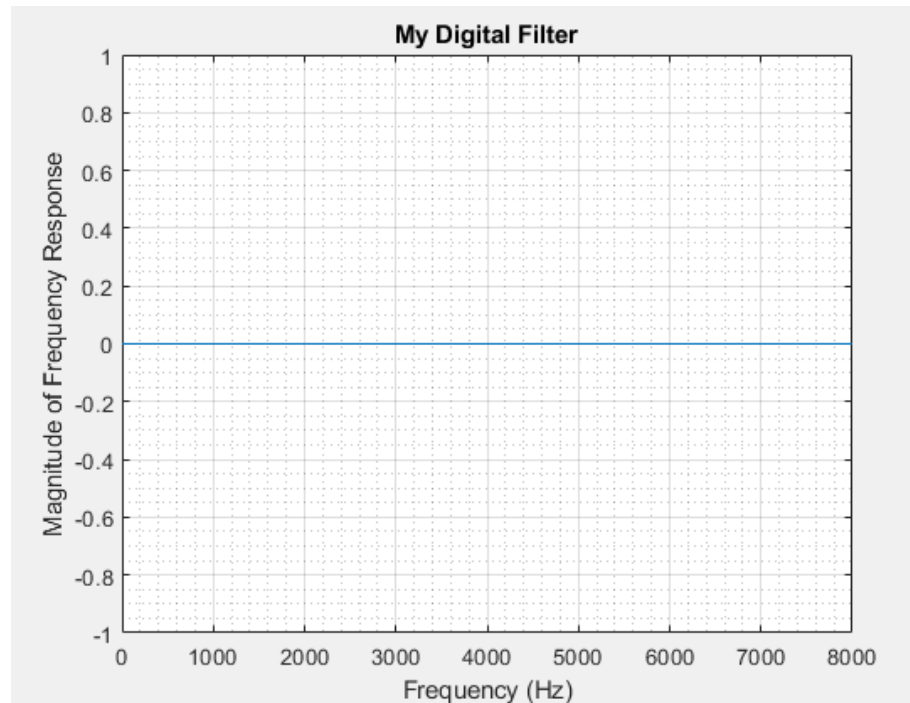
```
#####
#####
    # students - go to work!
    # update history with most recent input
    fifo.update(xin)
    # evaluate your difference equation
    yout = 0
    h_ideal = 0

    W_hamm = 0
    fc=0
    for k in range(M):

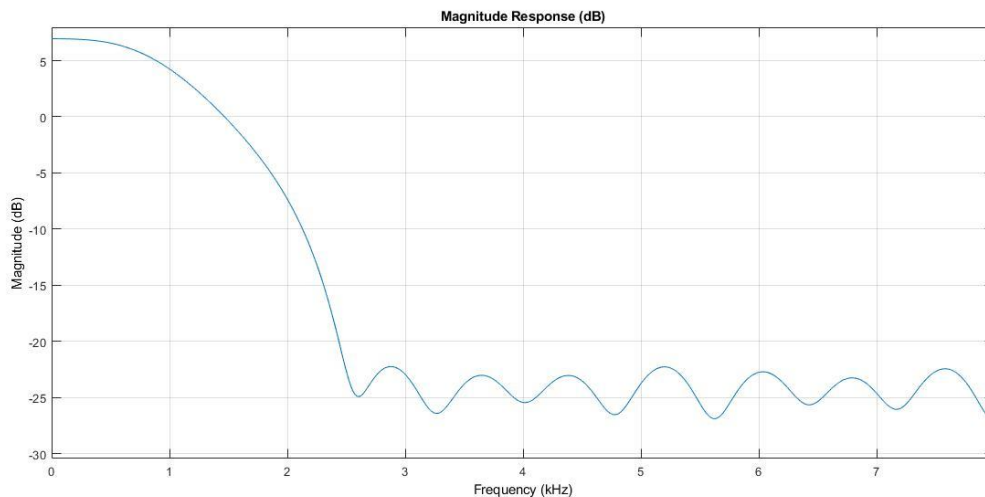
        # use your fifo to access recent inputs when evaluating your diff
eq
        #  $y[n] = b[k] * x[n-k]$ 
        #  $y_{out} += b_k_{list} * \text{fifo.get}(k)$ 
         $h_{ideal} = \sin(2 * \pi * fc * k) / \pi * k$ 
         $W_{hamm} = 0.54 - (0.46 * \cos((2 * \pi * k) / (M - 1)))$ 
         $yout = W_{hamm} * h_{ideal}$ 

    # students - well done!
#####
#####
```

**3c) Upload Welch Periodogram from MatLab**



#### 4. Use MatLab's DSP Toolbox to Find an Optimized Filter (M=21)



**4a) How much can the stopband attenuation be increased while maintaining a filter length of M=21 or less (dB)? (2) Keep  $F_p = 1\text{kHz}$ ,  $F_{st} = 3.5\text{kHz}$  and increase  $A_{st}$ .**

As we increase the dBs with the increment of 5 dB, it was observed the dBs can be increased upto 65 dB. Above this value, and the filter length increases than 21.

**4b) How much can the stopband frequency be reduced while maintaining a filter length of M=21 or less (Hz)? (2) Keep  $A_{st} = 50$ ,  $F_p = 1\text{kHz}$ , and decrease  $F_{st}$**

As we decrease the  $F_{st}$  with the decrement of 100 Hz, it was observed that it can be decreased up to 3100 Hz. Below this value, the filter length increases more than 21.