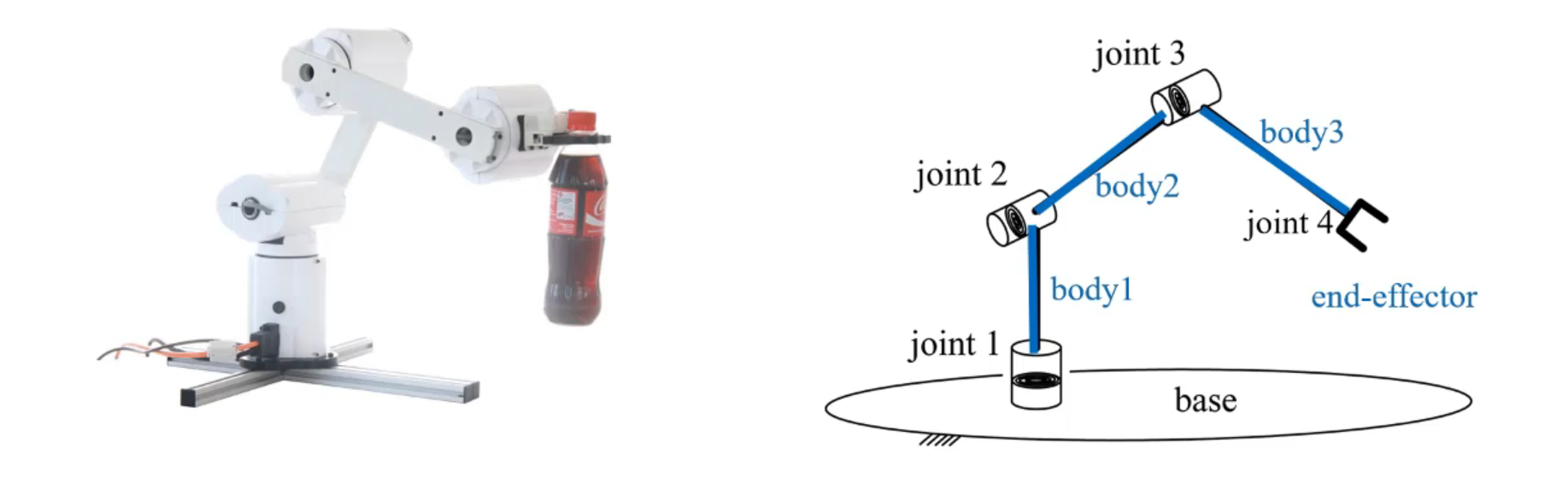
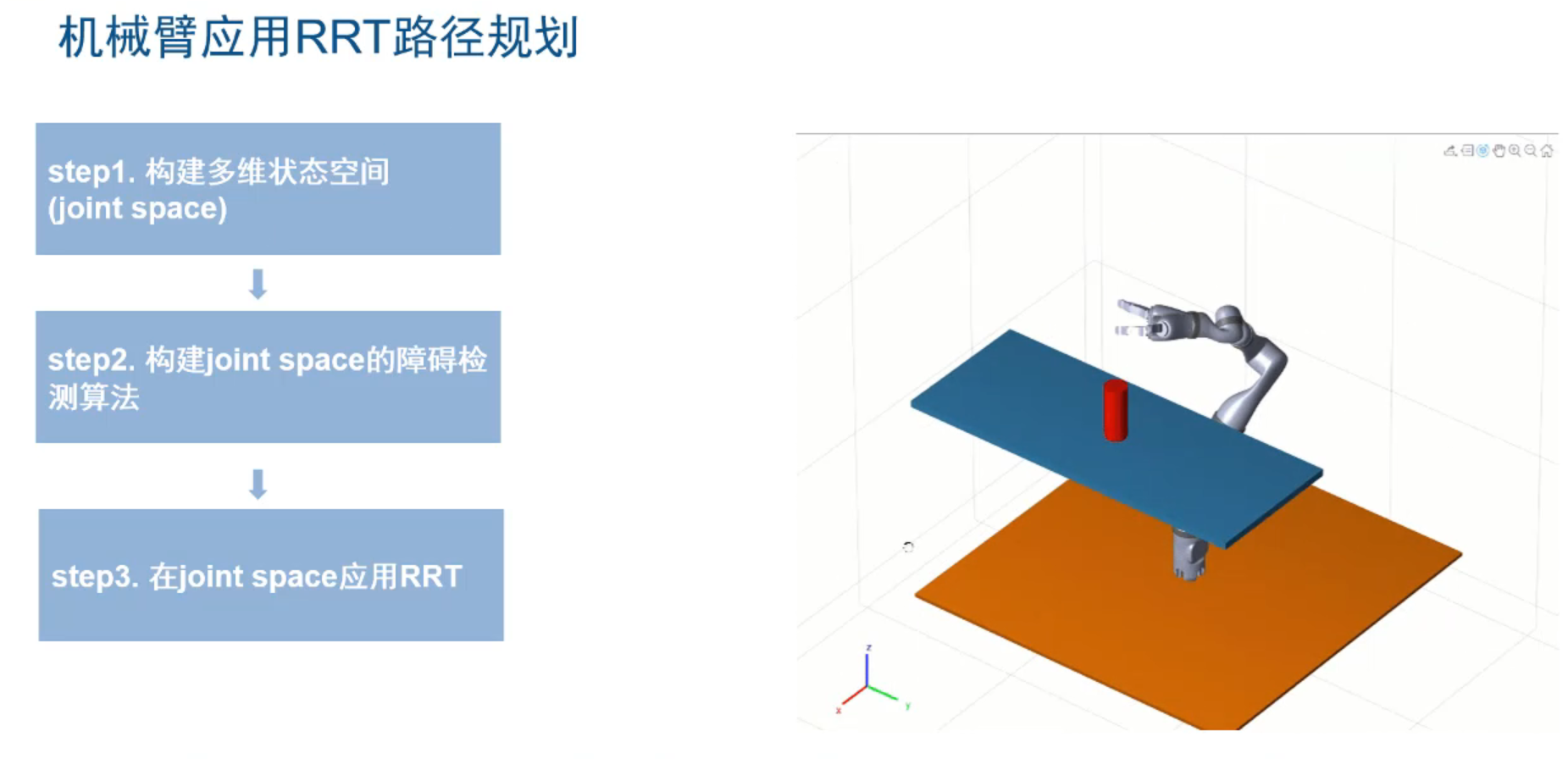
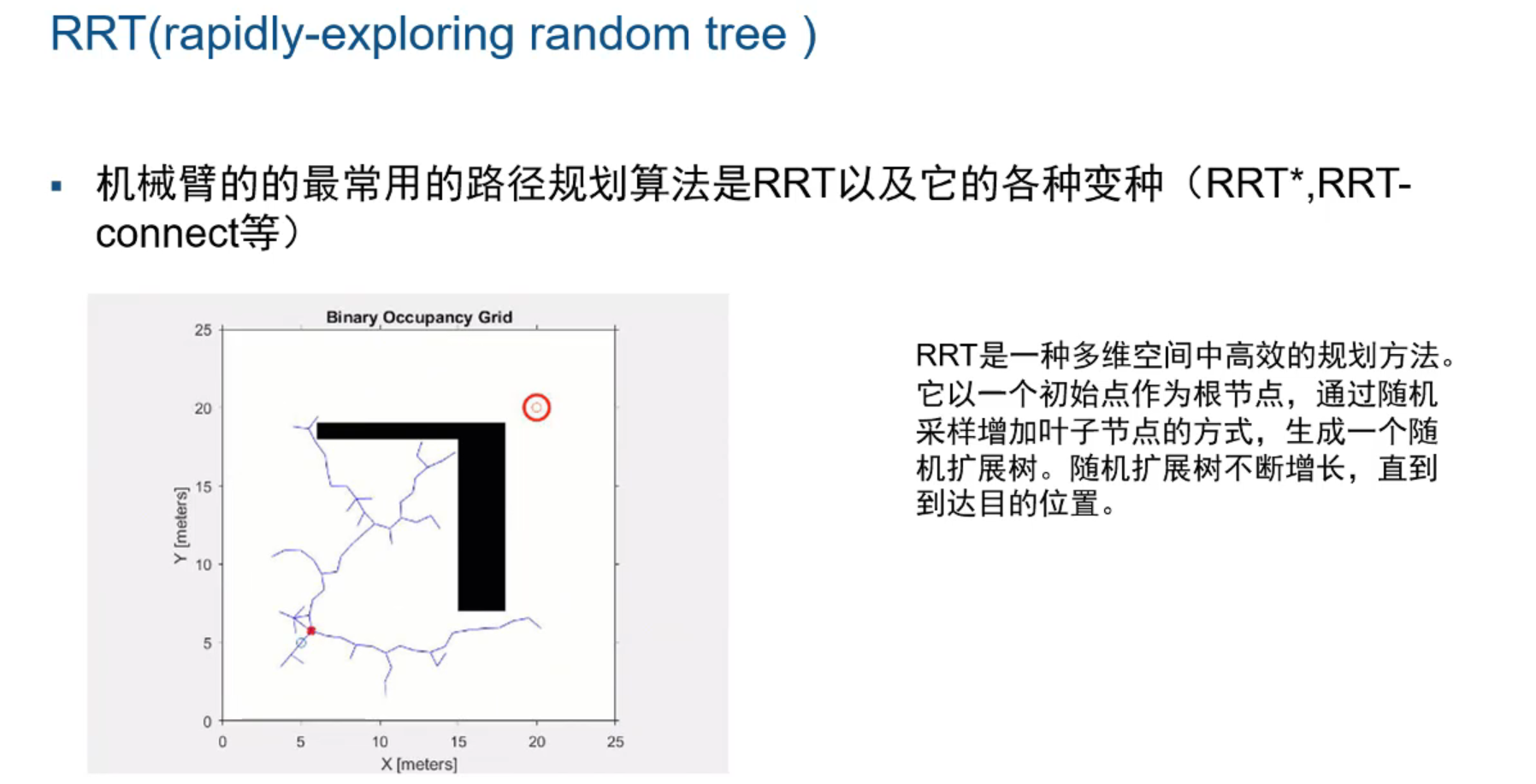
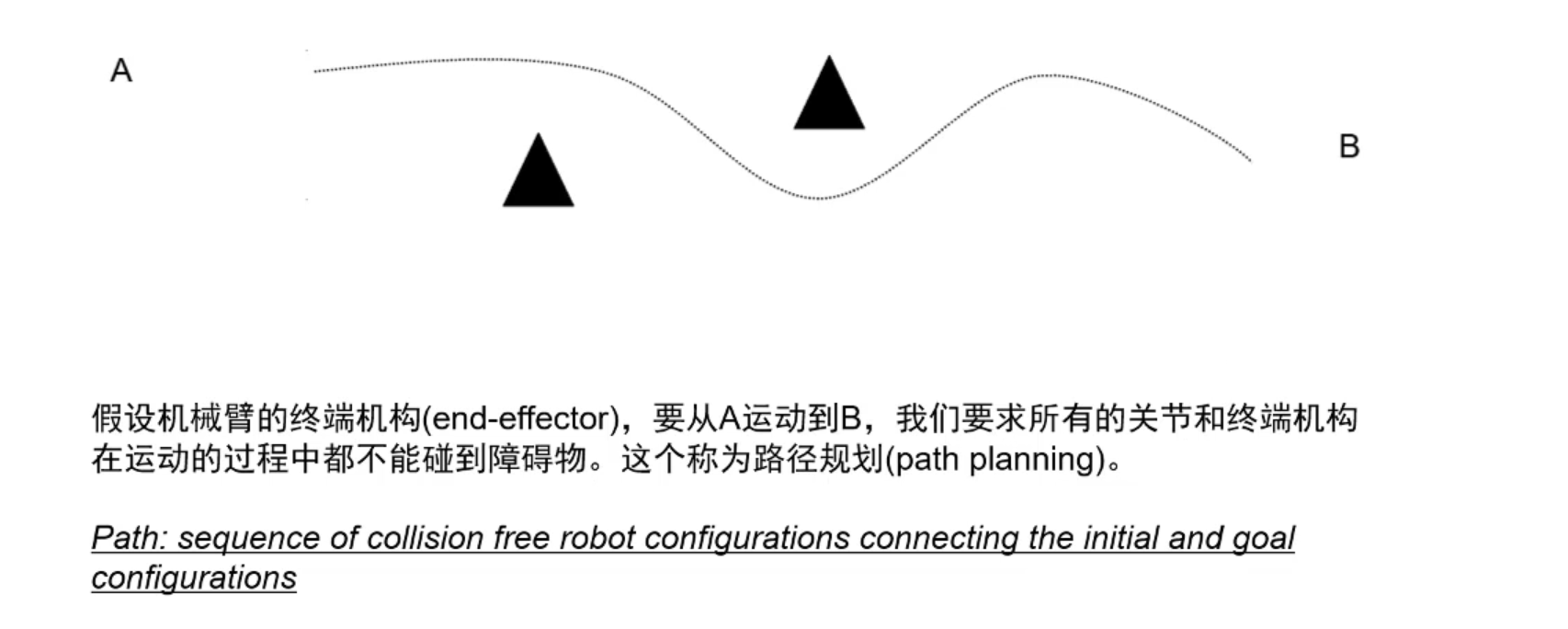
## 一、机械臂(Manipulator)组成及概览



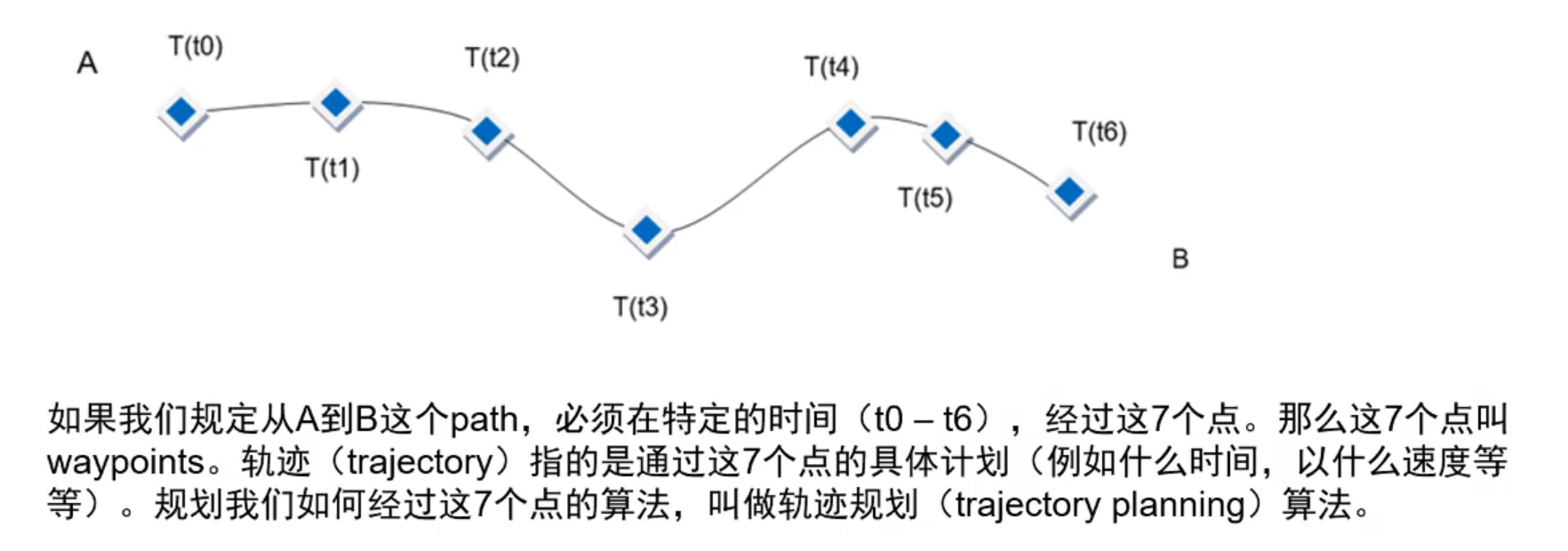


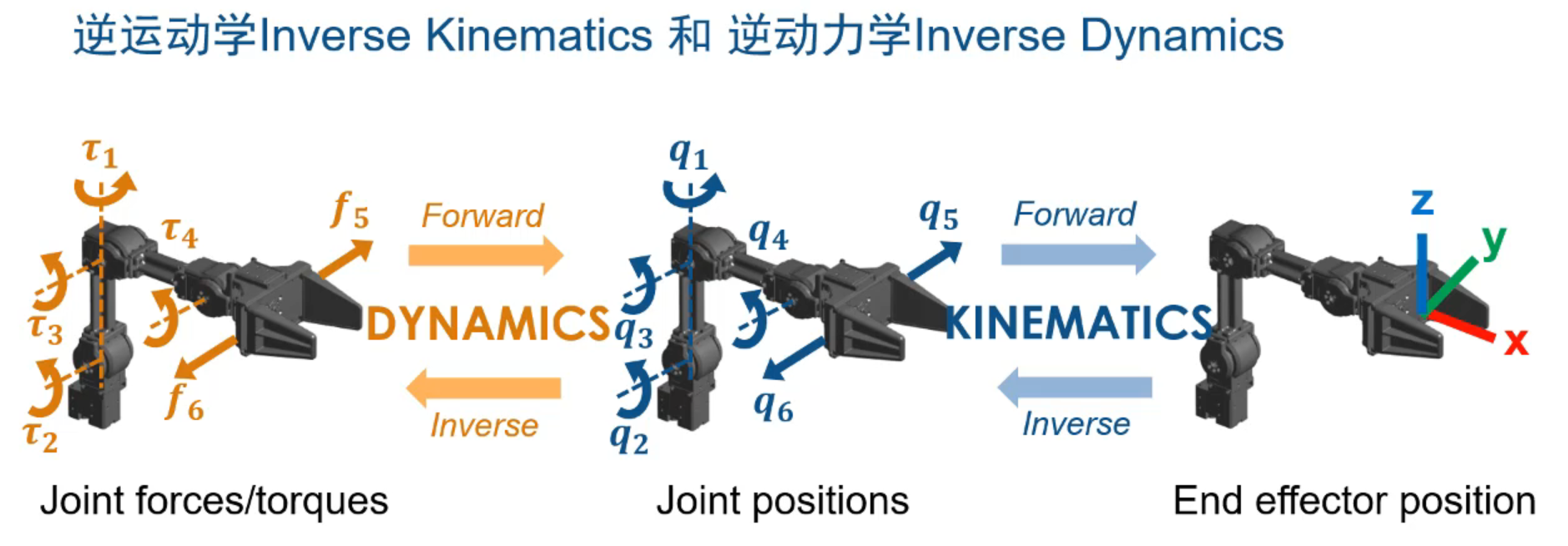
## 控制算法

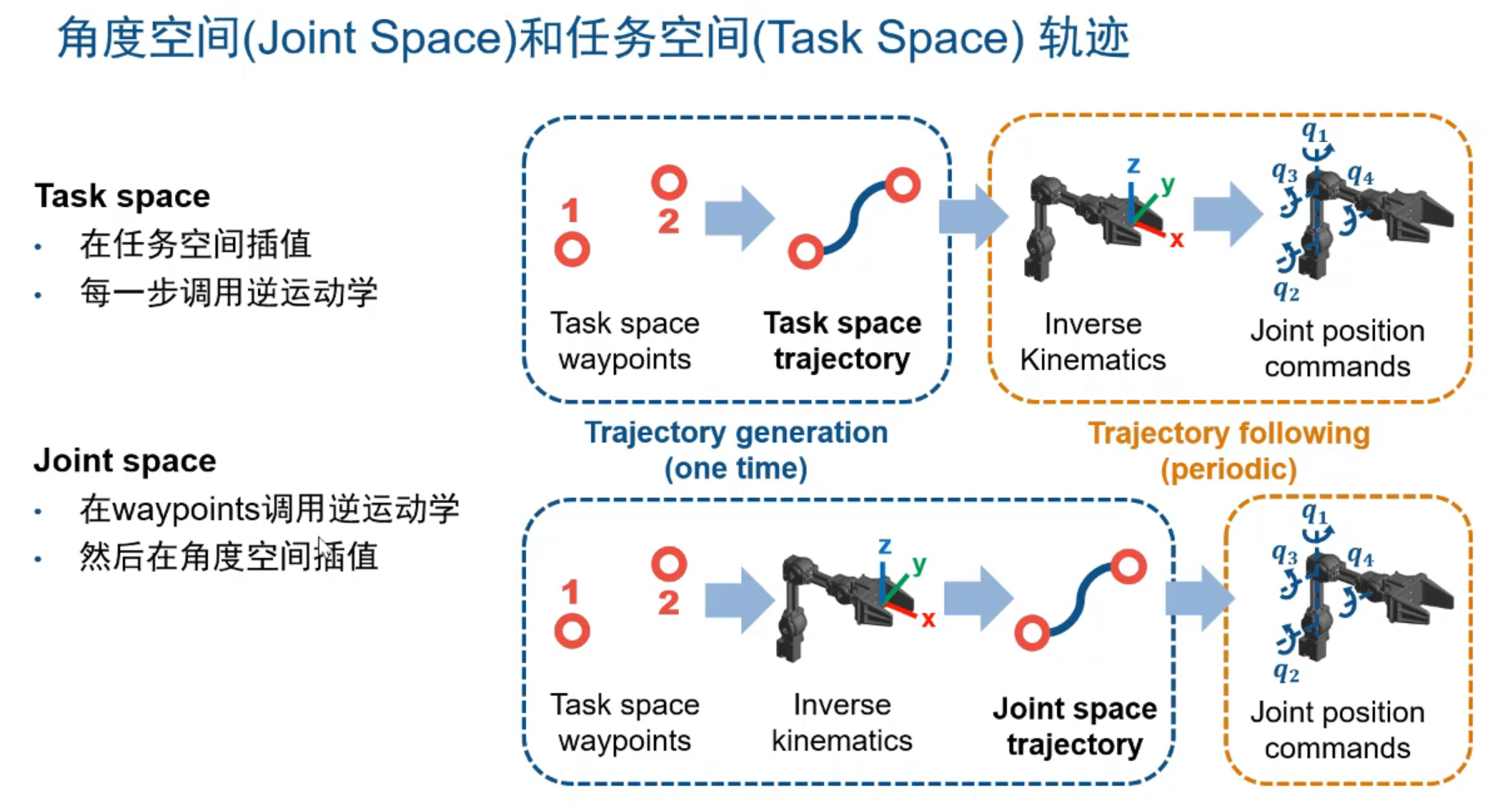
### 2.1 路径规划(Path Planning)



### 2.2 轨迹规划(Trajectory Planning)







### 2.3 轨迹跟随(Trajectory Following)

