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Identifier	Description
va_list	A type suitable for holding information needed by macros <b>va_start</b> , <b>va_arg</b> , and <b>va_end</b> . To access the arguments in a variable-length argument list, an object of type <b>va_list</b> must be declared.
va_start	A macro that is invoked before the arguments of a variable-length argument list can be accessed. The macro initializes the object declared with <b>va_list</b> for use by the <b>va_arg</b> and <b>va_end</b> macros.
va_arg	A macro that expands to an expression of the value and type of the next argument in the variable-length argument list. Each invocation of <b>va_arg</b> modifies the object declared with <b>va_list</b> so that the object points to the next argument in the list.
va_end	A macro that facilitates a normal return from a function whose variable-length argument list was referred to by the <b>va_start</b> macro.

Fig. 18.1 The type and the macros defined in header **stdarg.h**.

```
// Fig. 18.2: fig18_02.cpp
    // Using variable-length argument lists
    #include <iostream.h>
    #include <iomanip.h>
    #include <stdarg.h>
 6
    double average( int, ... );
8
9
    int main()
10
11
       double w = 37.5, x = 22.5, y = 1.7, z = 10.2;
12
13
       cout << setiosflags( ios::fixed | ios::showpoint )</pre>
14
            << setprecision( 1 ) << "w = " << w << "\nx = " << x
15
            << "\ny = " << y << "\nz = " << z << endl;
       cout << setprecision( 3 ) << "\nThe average of w and x is "
16
17
            << average( 2, w, x )
            << "\nThe average of w, x, and y is "
18
19
            << average( 3, w, x, y )
20
            << "\nThe average of w, x, y, and z is "
21
22
23
            << average( 4, w, x, y, z ) << endl;
       return 0;
    }
24
25
    double average( int i, ... )
26
27
       double total = 0;
```

Fig. 18.2 Using variable-length argument lists (part 1 of 2).

```
32
       for ( int j = 1; j <= i; j++ )
33
          total += va_arg( ap, double );
34
35
       va_end( ap );
36
37
       return total / i;
38
   }
         w = 37.5
         x = 22.5
        y = 1.7
         z = 10.2
        The average of w and x is 30.000
        The average of w, x, and y is 20.567
         The average of w, x, y, and z is 17.975
```

Fig. 18.2 Using variable-length argument lists (part 2 of 2).

```
// Fig. 18.3: fig18_03.cpp
   // Using command-line arguments
    #include <iostream.h>
    #include <fstream.h>
6
   int main( int argc, char *argv[] )
7
8
       if ( argc != 3 )
9
          cout << "Usage: copy infile outfile" << endl;</pre>
10
       else {
11
          ifstream inFile( argv[ 1 ], ios::in );
12
          if (!inFile)
13
             cout << argv[ 1 ] << " could not be opened" << endl;</pre>
14
15
          ofstream outFile( argv[ 2 ], ios::out );
16
          if ( !outFile )
17
             cout << argv[ 2 ] << " could not be opened" << endl;</pre>
18
19
          while ( !inFile.eof() )
20
             outFile.put( static_cast< char >( inFile.get() ) );
21
       }
       return 0;
24
    }
```

Fig. 18.3 Using command-line arguments.

```
// Fig. 18.4: fig18_04.cpp
   // Using the exit and atexit functions
   #include <iostream.h>
   #include <stdlib.h>
6
   void print( void );
8
   int main()
9
10
       atexit( print );
                              // register function print
11
       cout << "Enter 1 to terminate program with function exit"</pre>
12
            << "\nEnter 2 to terminate program normally\n";
```

```
13
14
        int answer;
15
        cin >> answer;
16
17
        if ( answer == 1 ) {
18
           cout << "\nTerminating program with function exit\n";</pre>
19
           exit( EXIT_SUCCESS );
20
21
22
23
24
25
26
27
28
29
        cout << "\nTerminating program by reaching the of main"</pre>
              << endl;
        return 0;
    }
    void print( void )
30
        cout << "Executing function print at program termination\n"</pre>
31
             << "Program terminated" << endl;
32
    }
```

Fig. 18.4 Using functions exit and atexit (part 1 of 2).

```
Enter 1 to terminate program with function exit
Enter 2 to terminate program normally
: 1

Terminating program with function exit
Executing function print at program termination
Program terminated

Enter 1 to terminate program with function exit
Enter 2 to terminate program normally
: 2

Terminating program by reaching end of main
Executing function print at program termination
Program terminated
```

Fig. 18.4 Using functions exit and atexit (part 2 of 2).

Signal	Explanation
SIGABRT	Abnormal termination of the program (such as a call to abort).
SIGFPE	An erroneous arithmetic operation, such as a divide-by-zero or an operation resulting in overflow.
SIGILL	Detection of an illegal instruction.
SIGINT	Receipt of an interactive attention signal.
SIGSEGV	An invalid access to storage.
SIGTERM	A termination request sent to the program.

Fig. 18.5 The signals defined in header **signal.h**.

```
// Fig. 18.6: fig18_06.cpp
    // Using signal handling
    #include <iostream.h>
    #include <iomanip.h>
    #include <signal.h>
    #include <stdlib.h>
    #include <time.h>
    void signal_handler( int );
10
11
    int main()
12
13
       signal( SIGINT, signal_handler );
14
       srand( time( 0 ) );
15
16
       for ( int i = 1; i < 101; i++ ) {
17
          int x = 1 + rand() % 50;
18
19
           if (x == 25)
20
              raise( SIGINT );
21
22
23
           cout << setw( 4 ) << i;
24
           if ( i % 10 == 0 )
25
              cout << endl;</pre>
26
       }
27
28
29
30
31
32
33
34
       return 0;
    }
    void signal_handler( int signalValue )
       cout << "\nInterrupt signal (" << signalValue</pre>
             << ") received.\n"
35
             << "Do you wish to continue (1 = yes or 2 = no)? ";
36
37
       int response;
38
       cin >> response;
39
40
       while ( response != 1 && response != 2 ) {
41
           cout << "(1 = yes or 2 = no)? ";
42
           cin >> response;
43
       }
44
45
       if ( response == 1 )
46
           signal( SIGINT, signal_handler );
47
       else
48
           exit( EXIT_SUCCESS );
49
    }
```

Fig. 18.6 Using signal handling (part 1 of 2)

```
10
         23
                               29
                                   30
         33
            34 35
                    36
                           38
                               39
                                   40
         43
                    46
                        47
                           48
                               49
                                   50
        53
                    56
                        57
                               59
                                   60
 61
     62
            64
               65
                        67
        63
                    66
                           68
                               69
                                   70
                        77
 71
        73
            74
                    76
                           78
                               79 80
        83
 81 82
            84
                85
                    86
                        87
Interrupt signal (4) received.
Do you wish to continue (1 = yes or 2 = no)? 1
 91 92 93 94 95 96 97 98 99 100
```

Fig. 18.6 Using signal handling (part 2 of 2)

```
// Fig. 18.7: fig18_07.cpp
    // Using goto
   #include <iostream.h>
5
    int main()
6
    {
7
       int count = 1;
8
9
       start:
                                  // label
10
         if ( count > 10 )
11
             goto end;
12
13
          cout << count << " ";
14
          ++count;
15
          goto start;
16
17
                                  // label
       end:
18
          cout << endl;</pre>
19
20
       return 0;
    }
           2 3 4 5 6 7 8 9 10
```

Fig. 18.7 Using goto.

```
// Fig. 18.8: fig18_08.cpp
// An example of a union
#include <iostream.h>

union Number {
   int x;
   float y;
};
```

Fig. 18.8 Printing the value of a **union** in both member data types (part 1 of 2).

```
9
10
    int main()
11
12
       Number value;
13
14
       value.x = 100;
15
       cout << "Put a value in the integer member\n"</pre>
16
             << "and print both members.\nint:
17
             << value.x << "\nfloat: " << value.y << "\n\n";
18
19
       value.y = 100.0;
       cout << "Put a value in the floating member \n"
20
21
             << "and print both members.\nint:
             << value.x << "\nfloat: " << value.y << endl;
23
24
       return 0;
    }
         Put a value in the integer member
         and print both members.
         int: 100
float: 3.504168e-16
         Put a value in the floating member
         and print both members.
         int: 0
         float: 100
```

Fig. 18.8 Printing the value of a **union** in both member data types (part 2 of 2).

```
// Fig. 18.9: fig18_09.cpp
    // Using an anonymous union
    #include <iostream.h>
 5
    int main()
 6
       // Declare an anonymous union.
Fig. 18.9
        Using an anonymous union (part 1 of 2).
 8
       // Note that members b, d, and f share the same space.
 9
       union {
10
           int b;
11
           double d;
12
           char *f;
13
       };
14
15
       // Declare conventional local variables
16
       int a = 1;
17
       double c = 3.3;
18
       char *e = "Anonymous";
19
20
       // Assign a value to each union member
21
22
       // successively and print each.
       cout << a << ' ';
23
       b = 2;
24
25
       cout << b << endl;</pre>
26
       cout << c << ' ';
       d = 4.4;
       cout << d << endl;</pre>
```

```
29
30     cout << e << ' ';
31     f = "union";
32     cout << f << endl;
33
34     return 0;
35 }

1 2
3.3 4.4
Anonymous union</pre>
```

Fig. 18.9 Using an anonymous union (part 2 of 2).