

Lecture 15: Direct Sum of Subspaces, Fundamental Subspaces, Least Square Solutions

Let V be a vector space over K ($K = \mathbb{R}$ or \mathbb{C})
Let P and Q be two subspaces of V .

Direct Sum of P and Q , denoted by $P \oplus Q$, is the subspace $P + Q$ with $P \cap Q = \{0\}$.

Proposition: Each element x of $P \oplus Q$ can be written uniquely as $x = p + q$.

Proof: Let $x \in P \oplus Q$, then $\exists p \in P$ & $q \in Q$ such that $x = p + q$.

If $\exists p' \in P$ & $\exists q' \in Q$ such that $x = p' + q'$

$$\text{then } p + q = p' + q'$$

$$\Rightarrow p - p' = q - q' \in P \cap Q = \{0\}$$

$$\Rightarrow p = p' \text{ \& } q = q' \quad \square$$

Proposition: Let W be a subspace of an inner product space V , then $V = W \oplus W^\perp$.

Proof: We have seen $V = W + W^\perp$ & $W \cap W^\perp = \{0\}$

Fundamental Subspaces:

Let $A = (a_{ij})$ be a matrix of order $m \times n$. A induces a linear transformation

$T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $T_A(x) = Ax$, x is treated as $n \times 1$ matrix.

Notation: (i) $\ker(T_A) \equiv N(A)$, also called null space of A

(ii) Range of T_A , $R(T_A) \equiv R(A)$,

(iii) $RS(A) =$ Row space of A (subspace generated by row vectors)

(iv) $CS(A) =$ Column space of A (subspace generated by column vectors)

Note that $N(A) \subseteq \mathbb{R}^n$, $R(A) \subseteq \mathbb{R}^m$

$RS(A) \subseteq \mathbb{R}^n$, $CS(A) \subseteq \mathbb{R}^m$.

$A^T = (a_{ji})_{n \times m}$, $A^T: \mathbb{R}^m \rightarrow \mathbb{R}^n$

$N(A^T) \subseteq \mathbb{R}^m$, $R(A^T) \subseteq \mathbb{R}^n$.

Fundamental Theorem of Linear Algebra:

Theorem (i) $N(A) \oplus RS(A) = \mathbb{R}^n$

(ii) $N(A^T) \oplus CS(A) = \mathbb{R}^m$.

Proof (i) $\det w \in N(A) \iff AW = 0$

$$\Rightarrow a_{i1}w_1 + \dots + a_{in}w_n = 0 \quad \star$$

$\forall 1 \leq i \leq m.$

$\det v \in RS(A)$

$$v = \sum_{i=1}^m \lambda_i R_i, \quad \lambda_i \in \mathbb{R}$$

$$\& R_i = (a_{i1}, \dots, a_{in})$$

R_i is the row vector.

$$\star \text{ implies } \langle (a_{i1}, \dots, a_{in}), (w_1, \dots, w_n) \rangle = 0$$

$$\Rightarrow \langle R_i, w \rangle = 0$$

$$\Rightarrow \langle \sum_{i=1}^m \lambda_i R_i, w \rangle = 0$$

$$\Rightarrow \langle v, w \rangle = 0$$

Therefore, $N(A)$ is orthogonal to $RS(A)$. So, $N(A) \subseteq (RS(A))^\perp$

By Rank-Nullity theorem,

$$\dim(N(A)) + \dim(R(A)) = n$$

$$\& \dim(RS(A)) = \dim(CS(A)) = \dim(R(A))$$

$$\mathbb{R}^n = RS(A) \oplus (RS(A))^\perp$$

$$\Rightarrow n = \dim(RS(A)) + \dim(RS(A)^\perp)$$

$$\Rightarrow \dim(N(A)) = \dim(RS(A)^\perp)$$

$$\text{So, } N(A) = RS(A)^\perp$$

So, $N(A) \oplus RS(A) = \mathbb{R}^n$.

(ii) Proof of (i) is similar.

A system of linear equations $AX = B$ is said to be **consistent** if there exists a solution of $AX = B$, otherwise it is called **inconsistent**.

Let $B = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$ & $b = (b_1, b_2, \dots, b_m)$

★ If $b \in CS(A)$, then the system $AX = B$ is consistent & if $b \notin CS(A)$ then the system $AX = B$ is inconsistent. We want to find a "pseudo-solution" i.e. a point x_0 such that distance of Ax_0 and b is minimum.

Least Square Solution

Let $A = (a_{ij})$ be a matrix of order $m \times n$, it induces a linear map
 $A : \mathbb{R}^n \rightarrow \mathbb{R}^m, A(x) = AX$.

Let $b \in \mathbb{R}^m$, we want to find $x_0 \in \mathbb{R}^n$ such that

$$\|Ax_0 - b\|^2 = \min_{x \in \mathbb{R}^n} \|Ax - b\|^2.$$

Existence of x_0 :

Let $W = \text{CS}(A)$.

Take orthogonal

projection $P_W(b)$ of b

on W . $P_W(b) \in \text{CS}(A)$

$\Rightarrow \exists x_0 \in \mathbb{R}^n$ s.t

$P_W(b) = Ax_0$ & we know

that $\|b - P_W(b)\| \leq \|b - y\| \forall y \in W$.

Such a solution x_0 need not be unique,

if we take $z \in N(A)$ then $A(x_0 + z) = Ax_0$

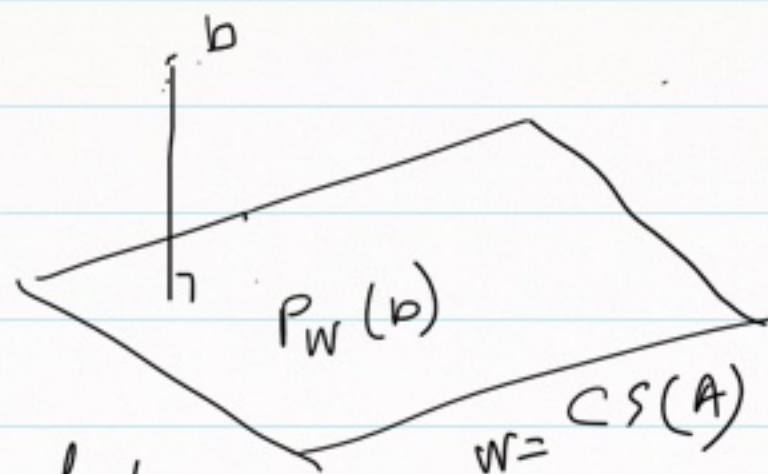
hence $x_0 + z$ is also a solution.

So, any element of $x_0 + N(A)$ is a

solution. As $P_W(b)$ is unique such

point on W , the solution set is

$x_0 + N(A)$.



What is x_0 ? To find $P_W(b)$, we need to find an orthonormal basis of $CS(A)$ & then find the point x_0 . The whole process may be cumbersome. We will use fundamental theorem of linear algebra to avoid it.

$$\mathbb{R}^m = N(A^T) \oplus CS(A) \quad , \quad W = CS(A)$$

$$b \in \mathbb{R}^m, \quad b = (b - P_W(b)) + P_W(b)$$

$$P_W(b) \in CS(A)$$

$$\Rightarrow b - P_W(b) \in N(A^T)$$

$$\Rightarrow A^T(b - P_W(b)) = 0$$

$$\Rightarrow A^T(P_W(b) - b) = 0$$

$$\Rightarrow A^T(Ax_0 - b) = 0$$

$$\Rightarrow A^T A x_0 = A^T b$$

$$\Rightarrow x_0 \text{ is a solution of } A^T A x = A^T b.$$

Conversely, if y_0 is a solution of $A^T A x = A^T b$

$$\Rightarrow A^T(Ay_0 - b) = 0$$

$$\Rightarrow Ay_0 - b \in N(A^T), \quad Ay_0 \in CS(A)$$

$$\& \quad b = (b - Ay_0) + Ay_0$$

b can be written uniquely as $x + y$, where

$$x \in N(A^T) \text{ \& } y \in CS(A).$$

$$\text{So, } Ay_0 = P_W(L)$$

Thus, we have the following theorem

Theorem: x_0 is a solution of $A^T A x = A^T b$ if and only if $\|Ax_0 - b\|^2 = \min_{x \in \mathbb{R}^n} \|Ax - b\|^2$

The system of linear equation

$$A^T A x = A^T b \quad \text{is called}$$

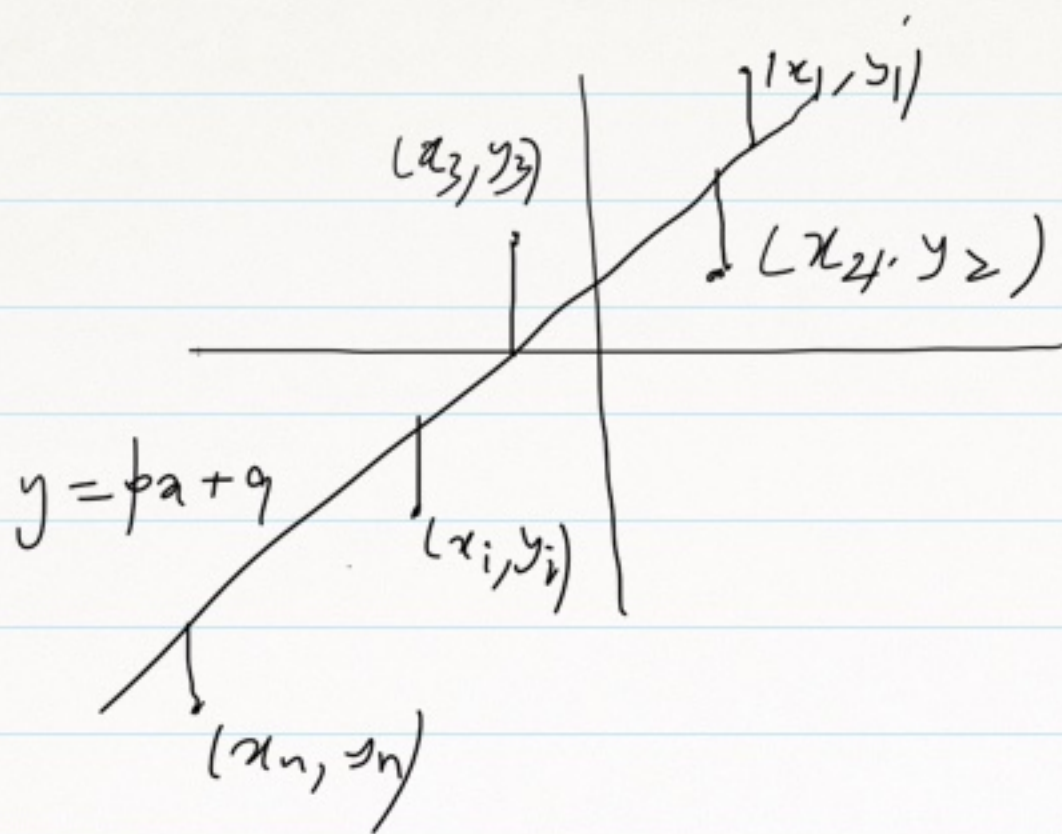
Normal system of equations.

Least square fittings:

Suppose $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ are finitely many points in \mathbb{R}^2 . Least square fittings is to find a straight line $y = px + q$ such that

$$\sum_{i=1}^n |y_i - (px_i + q)|^2 \text{ is}$$

minimum. We will apply least square solution to find the straight line $y = px + q$.



Consider

$$A = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix}, \quad X = \begin{pmatrix} q \\ p \end{pmatrix}, \quad B = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

The least square fittings is to find $X_0 = \begin{pmatrix} q_0 \\ p_0 \end{pmatrix}$ such that,

$$\|AX_0 - b\|^2 = \min_{X \in \mathbb{R}^2} \|AX - b\|^2 \quad \star$$

Where $b = (y_1, \dots, y_n)$. $X \in \mathbb{R}^2$

By least square solution, solution of \star exists & it is a solution of

$$A^T A X = A^T B$$

Example : $(x_1, y_1) = (1, 0)$, $(x_2, y_2) = (2, 3)$,
 $(x_3, y_3) = (3, 4)$, $(x_4, y_4) = (4, 4)$

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{pmatrix}, \quad X = \begin{pmatrix} q \\ p \end{pmatrix}, \quad B = \begin{pmatrix} 0 \\ 3 \\ 4 \\ 4 \end{pmatrix}$$

$$A^T A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{pmatrix}$$

$$(A^T A)^{-1} = \frac{1}{20} \begin{pmatrix} 4 & 10 \\ 10 & 30 \end{pmatrix} = \begin{pmatrix} 3/2 & -1/2 \\ -1/2 & 1/5 \end{pmatrix}$$

$$A^T B = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 0 \\ 3 \\ 4 \\ 4 \end{pmatrix}$$

$$= \begin{pmatrix} 11 \\ 34 \end{pmatrix}$$

$$A^T A X = A^T B$$

$$\rightarrow X = \begin{pmatrix} q \\ p \end{pmatrix} = (A^T A)^{-1} A^T B = \begin{pmatrix} 3/2 & -1/2 \\ -1/2 & 1/5 \end{pmatrix} \begin{pmatrix} 11 \\ 34 \end{pmatrix}$$

$$= \begin{pmatrix} -1/2 \\ 13/10 \end{pmatrix}$$

$y = \frac{13}{10}x - \frac{1}{2}$ is the required

straight line.