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Consider the (LH) system -

$$\dot{x}(t) = A(t)x(t)$$

Suppose f_1, \dots, f_n be solns. of (LH). Consider

$$U(t) = [f_1(t), \dots, f_n(t)]$$

then $U(t)$ satisfies

$$U'(t) = A(t)U(t)$$

$$\text{Consider } (A(t)U(t))_{i,j} = \sum_{k=1}^n (A(t))_{i,k} (U(t))_{k,j}$$

$$= \sum_{k=1}^n (A(t))_{i,k} f_{j,k}(t)$$

$$\text{Here } f_j(t) = (f_{j,1}(t), \dots, f_{j,n}(t))$$

$$= (A(t)f_j(t))_{i,1} = (\dot{f}_{j,i}(t))_{i,1} = \dot{f}_{j,i}(t) = (U(t))_{i,j}$$

$U(t)$ is a solution matrix.

• Note that the principal soln. matrix at a point t_0 , $\Phi(\cdot, t_0)$ is a solution matrix.

Defⁿ: Given homogeneous system,

$$\dot{x}(t) = A(t)x(t)$$

$A: I \xrightarrow{\text{cont.}} M_n(\mathbb{R})$. A matrix valued funcⁿ $\psi: I \rightarrow M_n(\mathbb{R})$ is called a fundamental soln. matrix if $\psi(t)$ satisfies the following two conditions

$$\textcircled{1} \quad \psi'(t) = A(t)\psi(t) \quad \forall t \in I$$

\textcircled{2} the columns of ψ are linearly independent in $C(I, \mathbb{R}^n)$.

Note the principal soln. matrix is a fundamental matrix.

THEOREM: A necessary & sufficient condition that a solution matrix $\psi: I \rightarrow M_n(\mathbb{R})$ be a fundamental soln. matrix is that $\det(\psi(t)) \neq 0$ for some $t \in I$.

PROOF: First suppose $\psi: I \rightarrow M_n(\mathbb{R})$ is a fundamental soln. matrix.

$$\psi(t) = [\psi_1(t) \dots \psi_n(t)] \quad t \in I$$

Claim: Fix $t_0 \in I$ then the vector $(\psi_1(t_0), \dots, \psi_n(t_0))$ are lin. ind.

Suppose not. $\sum_{i=1}^n c_i \psi_i(t_0) = 0$, where not all c_i 's are zero.

Let $\varphi = \sum_{i=1}^n c_i \psi_i$, then φ is also a soln. of (LH).

$$\varphi(t_0) = (\sum_{i=1}^n c_i \psi_i) t_0 = \sum_{i=1}^n c_i \psi_i(t_0)$$

$$\Rightarrow \varphi \equiv 0$$

$\sum_{i=1}^n c_i \psi_i \equiv 0 \Rightarrow \{\psi_1, \dots, \psi_n\}$ are lin. dep. which is a contradicⁿ.

Now suppose $\psi'(t) = A(t)\psi(t)$

Suppose for some $t_0 \in I$, $\det(\psi(t_0)) \neq 0$

Claim: (ψ_1, \dots, ψ_n) are lin. ind.

Suppose not. Then $\sum_{i=1}^n c_i \psi_i \equiv 0$, where not all c_i 's are zero.

$$\Rightarrow \sum_{i=1}^n c_i \psi_i(t_0) = 0 \quad \text{Not all } c_i \text{'s are zero.}$$

$$\psi(t_0)C = 0 \quad C = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$$

$$\Rightarrow \det(\psi(t_0)) = 0 \quad (\text{Contradiction})$$

—X—

$U(t) \leftarrow$ Solution matrix

$$W(t) = \det(U(t)) \quad t \in I$$

\nwarrow Wronski deter.

If for some t_0 , $W(t_0) \neq 0$ then for any other t
 $W(t) \neq 0$

Exercise: $U(t) \leftarrow$ solution matrix

① $U(t)c$, $c \in M_n(\mathbb{R})$ is a soln. matrix.

② ψ_1 & ψ_2 are two FSM then for any $t_0 \in I$

$$\psi_1(t)(\psi_1(t_0))^{-1} = \psi_2(t)(\psi_2(t_0))^{-1} = \Phi(t, t_0)$$

$$\dot{x}(t) = A(t)x(t) + g(t) \quad \text{--- (1)}$$

ϕ_1, ϕ_2 then $\phi_1 - \phi_2$ is a solution of

$$\dot{x}(t) = A(t)x(t)$$

This implies that if we know a particular solution of (1), ϕ_0 then all other solns. are given by $\phi_0 + \text{soln. set of (LH)}$

$$\phi_0 + \psi$$

$$\dot{x}(t) = A(t)x(t) + g(t)$$

$$x(t_0) = x_0$$

Suppose the soln. to be of the form

$$g(t) = \Phi(t, t_0)c(t)$$

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$$\dot{x}(t) = A(t)x(t)$$

$$x(t_0) = x_0$$

Soln. is given by $x(t) = \Phi(t, t_0)x_0$

Recall $\Phi(\cdot, t_0)$ is the principal soln. matrix.

$$(1) \quad \Phi'(t, t_0) = A(t)\Phi(t, t_0)$$

$$(2) \quad \Phi(t_0, t_0) = I_n$$

Inhomogeneous System

$$\dot{x}(t) = A(t)x(t) + g(t) \quad (\text{ILS})$$

$$A: I \xrightarrow{\text{cont.}} M_n(\mathbb{R})$$

$$g: I \xrightarrow{\text{cont.}} \mathbb{R}^n$$

Let ϕ_1 & ϕ_2 be two soln. of (ILS). Then $\phi_1 - \phi_2$ is a soln. of (LH)

Hence, if we know a particular soln. ϕ of (ILS) then any other soln. is of the type $\psi + \phi$ where ψ is a soln. of (LH).

2. Consider (ILS) with the initial condition $x(t_0) = x_0$.

The idea is to guess that the soln. is of the form

$$g(t) = \Phi(t, t_0)c(t)$$

Observe that $g(t_0) = x_0 = c(t_0)$

$$g'(t) = \Phi'(t, t_0)c(t) + \Phi(t, t_0)c'(t)$$

$$= A(t)\Phi(t, t_0)c(t) + \Phi(t, t_0)c'(t)$$

$$= A(t)\phi(t) + \Phi(t, t_0)c'(t)$$

$$= A(t)\phi(t) + g(t) \quad [\text{By assumption}]$$

$$\Phi(t, t_0) c'(t) = g(t)$$

$$\Rightarrow c'(t) = \Phi(t, t_0)^{-1} g(t) = \Phi(t_0, t) g(t)$$

$$\Rightarrow c(t) - c(t_0) = \int_{t_0}^t \Phi(t_0, s) g(s) ds$$

$$c(t) = x_0 + \int_{t_0}^t \Phi(t_0, s) g(s) ds$$

$$\text{Our soln. :- } \varphi(t) = \Phi(t, t_0) x_0 + \Phi(t, t_0) \int_{t_0}^t \Phi(t_0, s) g(s) ds$$

$$\varphi(t) = \Phi(t, t_0) x_0 + \int_{t_0}^t \Phi(t, s) g(s) ds$$

1-d case :

$$\dot{x}(t) = a(t)x(t) + b(t)$$

$$\Phi'(t, t_0) = a(t)\Phi(t, t_0)$$

$$\Phi(t_0, t_0) = 1$$

$$\Phi(t, t_0) = \exp\left(\int_{t_0}^t a(s) ds\right)$$

Linear Differential Eqns. of order n:

HOMOGENEOUS CASE:

Consider a_0, a_1, \dots, a_n , cont. fnc's on I, assume $a_0(t) \neq 0$ for any $t \in I$. Consider the differential operator.

$$L_n = a_0(t) \frac{d^n}{dt^n} + a_1(t) \frac{d^{n-1}}{dt^{n-1}} + \dots + a_n(t)$$

acts on all fnc's on I that are at least n times differentiable.

$$L_n(g) = a_0(t)g^{(n)}(t) + a_1(t)g^{(n-1)}(t) + \dots + a_{n-1}(t)g^{(1)}(t) + a_n(t)g(t)$$

The linear diff. eqn. of order n is the eqn.

$$L_n x = 0 \Leftrightarrow a_0(t)x^{(n)}(t) + a_1(t)x^{(n-1)}(t) + \dots + a_{n-1}(t)x^{(1)}(t) + a_n(t)x(t) = 0$$

$$\frac{x^{(n)}(t) + a_1(t)x^{(n-1)}(t) + \dots + a_{n-1}(t)x^{(1)}(t) + a_n(t)x(t)}{a_0(t)} = 0 \quad \text{--- (1)}$$

* Introduce $(y_1, y_2, \dots, y_n) = (x(t), x^{(1)}(t), \dots, x^{(n)}(t))$

$$y_1 = y_2$$

$$y'_2 = y_3$$

$$\vdots$$

$$y_{n-1} = y_n$$

$$y_n = -\frac{a_1(t)}{a_0(t)}y_{n-1} - \frac{a_2(t)}{a_0(t)}y_{n-2} - \dots - \frac{a_n(t)}{a_0(t)}y_1$$

$$y(t) = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

$$y'(t) = A(t)y(t) \quad \text{--- (2)}$$

$$A(t) = \begin{pmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ \vdots & & & & & 1 \\ 0 & 0 & 0 & \dots & \dots & 0 \\ -\frac{a_n(t)}{a_0(t)} & -\frac{a_{n-1}(t)}{a_0(t)} & \dots & \dots & -\frac{a_1(t)}{a_0(t)} & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

1) Observe that if φ is a soln. of

$$\textcircled{1} \quad \text{i.e. } L_n \varphi = 0.$$

Then $(\varphi, \varphi', \dots, \varphi^{(n-1)})$ is a soln. of $\textcircled{2}$

2) Suppose $\varphi = \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_n \end{pmatrix}$ is a soln. of $\textcircled{2}$. Then

$$\varphi_2 = \varphi_1'$$

$$\varphi_3 = \varphi_2' = \varphi_1''$$

$$\vdots$$

$$\varphi_{n-1} = \varphi_1^{(n-2)}$$

$$\varphi_n = \varphi_1^{(n-1)} \text{ & } \varphi_1 \text{ satisfies}$$

$$L_n \varphi_1 = 0$$

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$$L_n x = 0 \quad \text{--- } \textcircled{1}$$

$$L_n = a_0 \frac{d^n}{dt^n} + a_1 \frac{d^{n-1}}{dt^{n-1}} + \dots + a_{n-1} \frac{d}{dt} + a_n$$

$$L_n x = 0 \iff y' = A(t)y \quad \text{--- } \textcircled{2}$$

$$\varphi \iff (\varphi, \varphi', \dots, \varphi^{(n-1)})$$

$$A(t) = \begin{pmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ \vdots & & \vdots & & & \\ 0 & 0 & 0 & 0 & \dots & 1 \\ -\frac{a_n(t)}{a_0(t)} & -\frac{a_{n-1}(t)}{a_0(t)} & \cdots & \cdots & \cdots & -\frac{a_1(t)}{a_0(t)} \end{pmatrix}$$

1) Notice that given $t_0 \in I$ & $y \in \mathbb{R}^n$, we know that there is a unique soln. φ of $y' = A(t)y$. WHY?

If we write $\varphi = (\varphi_1, \dots, \varphi_n)$ then

$$\varphi(t_0) = x_0 = (x_{01}, x_{02}, \dots, x_{0n})$$

$$\begin{aligned} \varphi(t_0) &= (\varphi_1(t_0), \varphi_1'(t_0), \dots, \varphi_1^{(n-1)}(t_0)) \\ &= (x_{01}, x_{02}, \dots, x_{0n}) \end{aligned}$$

$$L_n \varphi_1 = 0$$

2) Now let $\varphi_1, \dots, \varphi_n$ be soln. of

$$L_n x = 0$$

Consider the matrix

$$\Phi = \begin{pmatrix} \varphi_1 & \varphi_2 & \cdots & \varphi_n \\ \varphi_1' & \varphi_2' & \cdots & \varphi_n' \\ \vdots & \vdots & & \vdots \\ \varphi_1^{(n-1)} & \varphi_2^{(n-1)} & \cdots & \varphi_n^{(n-1)} \end{pmatrix} = [\Phi_1, \dots, \Phi_n]$$

This is a soln. matrix for the linear system

$$y' = A(t)y$$

The determinant of the soln. matrix is called the Wronskian associated to $\varphi_1, \dots, \varphi_n$ denoted by

$$W(\varphi_1, \dots, \varphi_n)(t) = |\Phi|$$

LEMMA: $x'(t) = A(t)x(t)$. Let $U(t)$ be a soln. matrix i.e.

$$U'(t) = A(t)U(t) \text{ Then}$$

$$|U(t)| = |U(t_0)| \exp\left(\int_{t_0}^t \text{trace}(A(s)) ds\right) \quad t \in I$$

← Abel's Identity

$$|U(t)|' = \text{trace}(A(t)) |U(t)|$$

THEOREM: Every soln. of $L_n x = 0$ is a linear combination of any n -linearly independent solutions. Given $\varphi_1, \dots, \varphi_n$, solution of $L_n x = 0$ they are lin. ind. iff $W(\varphi_1, \dots, \varphi_n) \neq 0$ on I

PROOF: Soln. set $L_n x = 0 \xrightarrow{\text{one-one}} \text{Soln. set of } y' = A(t)y(t)$

$$L: \varphi \xrightarrow{\text{onto}} (\varphi, \varphi^{(1)}, \dots, \varphi^{(n-1)})$$

$L(\varphi) = (\varphi, \varphi^{(1)}, \dots, \varphi^{(n-1)})$ is a vector space isomorphism i.e.

① L is one-one and onto.

② $L(\alpha\varphi + \beta\psi) = \alpha L(\varphi) + \beta L(\psi)$

$$\alpha, \beta \in \mathbb{R}, \varphi, \psi \text{ solns. of } L_n x = 0$$

The soln. space of $L_n x = 0$ is n -dim.

Suppose $\varphi_1, \dots, \varphi_n$ are lin. ind. solns. of $L_n x = 0$. Then the matrix Φ is a fundamental soln. matrix.

$$W(\varphi_1, \dots, \varphi_n)(t) \neq 0 \quad \forall t \in I$$

THEOREM: Let $\varphi_1, \dots, \varphi_n$ be functions on I such that $W(\varphi_1, \dots, \varphi_n)(t) \neq 0$ on I .

Then there exists a unique DE of order n^*

for which these functions form a fundamental set, namely:

$$\frac{W(x, \varphi_1, \dots, \varphi_n)}{W(\varphi_1, \dots, \varphi_n)} = 0$$

DEF.: A set of n lin. ind. solns. of $L_n x = 0$ is called a fundamental set for $L_n x = 0$.

* where coefficients of higher order is 1.

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EXAMPLE: Consider func's

$$f_1(t) = t, f_2(t) = te^t$$

$$W(f_1, f_2)(t) = \begin{vmatrix} f_1 & f_2 \\ f_1' & f_2' \end{vmatrix} = \begin{vmatrix} t & te^t \\ 1 & te^t + e^t \end{vmatrix} = t^2 e^t$$

$I = (a, b)$ not containing 0 then

$W(f_1, f_2)(t) \neq 0$ for any $t \in (a, b)$

$$\Rightarrow W(x, f_1, f_2) = 0$$

$$\begin{vmatrix} x & t & te^t \\ \dot{x} & 1 & te^t + e^t \\ \ddot{x} & 0 & te^t + 2e^t \end{vmatrix} = 0$$

$$x(te^t + 2e^t) - \dot{x}(t^2e^t + 2te^t) + \ddot{x}(t^2e^t) = 0$$

Reduction of order of a DE :-

$$L_n x = 0$$

$$a_0(t)x^{(n)} + a_1(t)x^{(n-1)} + \dots + a_{n-1}(t)x^{(1)} + a_n(t)x = 0 \quad \text{--- } ①$$

Say, $f(t)$ is a soln.

$$\text{We write } x(t) = f(t)y(t)$$

$$\frac{dx}{dt} = f'(t)y(t) + f(t)y'(t)$$

$$\frac{d^n x}{dt^n} = f^{(n)}(t)y(t) + C_1^n f^{(n-1)}(t)y'(t) + \dots + C_{n-1}^n f'(t)y^{(n-1)}(t) + f(t)y^{(n)}(t)$$

$$a_0(t)(f(t)y^{(n)}(t) + C_1^n f'(t)y^{(n-1)}(t) + \dots + f^{(n)}(t)y^{(1)}) + a_1(t)(f(t)y^{(n-1)}(t) + C_1^{n-1} f^{(n-1)}(t)y^{(n-2)}(t) + \dots + f^{(n-1)}(t)y^{(1)}) + \dots + a_n(t)f(t)y^{(1)} = 0$$

$$\Leftrightarrow a_0(t)f(t)y^{(n)} + (na_0(t)f^{(1)}(t) + (n-1)a_1(t)f(t))y^{(n-1)} + \dots + y(t)(a_0(t)f^{(n-1)}(t) + a_1(t)f^{(n-2)}(t) + \dots + a_{n-1}(t)f(t)) = 0 \quad \text{--- } ②$$

② reduces to

$$A_0(t)y^{(n)}(t) + A_1(t)y^{(n-1)}(t) + \dots + A_{n-1}(t)y^{(1)}(t) = 0 \quad \text{--- } ③$$

$$\text{Put } w = y'(t)$$

$$A_0(t)w^{(n-1)}(t) + A_1(t)w^{(n-2)}(t) + \dots + A_{n-1}(t)w(t) = 0 \quad \text{--- } ④$$

\Rightarrow Now suppose w_1, \dots, w_{n-1} is a known fundamental set of solutions for ④. Then $v_j(t) = \int w_j(t), j=1, \dots, n-1$

$\& v_n = 1$ is a fundamental set of solutions for ③

$$\Leftrightarrow \begin{vmatrix} 1 & v_1 & v_2 & \dots & v_{n-1} \\ 0 & w_1^{(n-1)} & w_2^{(n-1)} & \dots & w_{n-1}^{(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & w_1^{(n-1)} & w_2^{(n-1)} & \dots & w_{n-1}^{(n-1)} \end{vmatrix}$$

notice non-zero as w_1, \dots, w_{n-1} CI

Finally for fundamental set of ①, multiply by $f(t)$ by (*)

Inhomogeneous

$$\Leftrightarrow \underline{x^{(n)}(t)} + \frac{a_1(t)}{a_0(t)} \underline{x^{(n-1)}(t)} + \dots + \frac{a_n(t)}{a_0(t)} \underline{x} = \underline{g(t)}$$

$$\Leftrightarrow \underline{y'(t)} = A(t) \underline{y(t)} + \underline{\tilde{g}(t)}$$

$$\underline{\tilde{g}(t)} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \frac{g(t)}{a_0(t)} \end{pmatrix}$$

$$(y_1, \dots, y_n) = (x, x', \dots, x^{(n-1)})$$

$$y(t_0) = x_0$$

$$(x(t_0), x'(t_0), \dots, x^{(n-1)}(t_0)) = z$$

The solution is given by

$$y(t) = \Phi(t, t_0) x_0 + \int_{t_0}^t \Phi(t, s) \tilde{g}(s) ds$$

where $\Phi(t, t_0)$ is the principal solution matrix.

$$\Phi'(t, t_0) = A(t) \Phi(t, t_0) \text{ and } \Phi(t_0, t_0) = \mathbb{I}$$

$\varphi_j(t, t_0)$ is the solution of $L_n x = 0$ s.t.

$$(\varphi_j(t_0, t_0), \varphi_j^{(1)}(t_0, t_0), \dots, \varphi_j^{(n-1)}(t_0, t_0)) = e_j$$

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Cancelled

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Order n differential equation

$$L_n = a_0(t) \frac{d^n}{dt^n} + a_1(t) \frac{d^{n-1}}{dt^{n-1}} + \cdots + a_{n-1}(t) \frac{d}{dt} + a_n(t)$$

$$L_n x = g(t)$$

a_0, a_1, \dots, a_n are cts. fncⁿ on $I \subset \mathbb{R}$

HOMOGENEOUS CASE

$$L_n x = 0 \Leftrightarrow y'(t) = A(t)y(t)$$

INHOMOGENEOUS CASE

$$a_0(t) \frac{d^n x}{dt^n} + a_1(t) \frac{d^{n-1} x}{dt^{n-1}} + \cdots + a_{n-1}(t) \frac{dx}{dt} + a_n(t) x(t) = g(t)$$

By considering the change of variable

$$y = (y_1, \dots, y_n) = (x, x', \dots, x^{(n-1)})$$

The associated linear system is given by

$$y'(t) = \begin{pmatrix} y'_1 \\ \vdots \\ y'_n \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 \\ \vdots & & & & & \\ 0 & 0 & 0 & 0 & \cdots & 0 \\ \frac{a_n}{a_0} & -\frac{a_{n-1}}{a_0} & \cdots & -\frac{a_1}{a_0} & & \end{pmatrix} \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} + \begin{pmatrix} \tilde{g}(t) \\ 0 \\ 0 \\ \vdots \\ 0 \\ a_0(t) \end{pmatrix}$$

This linear system has a unique soln., given $y(t_0) = y_0 \in \mathbb{R}^n$
 \Rightarrow This implies that given $t_0 \in I$, $y_0 \in \mathbb{R}^n \exists$ unique soln. with
 $(x(t_0), x'(t_0), \dots, x^{(n-1)}(t_0)) = y_0$

The unique soln. of $(**)$ is given by

$$y(t) = \underbrace{\Phi(t, t_0)}_{\downarrow} y_0 + \int_{t_0}^t \Phi(t, s) \tilde{g}(s) ds$$

Principal soln. matrix

First coordinate of ① given by

$$x(t) = \sum_{j=1}^n \Phi_{1j}(t, t_0) y_{0j} + \int_{t_0}^t \Phi_{1n}(t, s) \frac{g(s)}{a_n(s)} ds$$

$$\Phi(t, s) = [\Phi_1(t, s) \dots \dots \Phi_n(t, s)]$$

$$\Phi'_1(t, s) = A(t) \Phi_1(t, s)$$

$$\Phi_1(s, s) = (1, 0, \dots, 0)$$

$$(\Phi_{ij}(t_0, t_0), \Phi'_{ij}(t_0, t_0), \dots, \Phi_{ij}^{(n-1)}(t_0, t_0)) = (0, \dots, 1, \dots, 0)$$

Linear Equations of order n with constant coefficients :-

$$x^{(n)} + a_1 x^{(n-1)} + \dots + a_n x = g(t)$$

Here a_1, \dots, a_n are constants

HOMOGENEOUS CASE

$$x^{(n)} + a_1 x^{(n-1)} + \dots + a_n x = 0 \quad \text{--- ①}$$

$y' = Ay$ Associated linear system

LEMMA: The characteristic polynomial of matrix A is given by :

$$f(\lambda) = \lambda^n + a_1 \lambda^{n-1} + \dots + a_n$$

THEOREM:

Consider ①. Let $\lambda_1, \dots, \lambda_s$ be distinct eigenvalues of matrix A. Let m_i be the multiplicity of λ_i as a zero of $f(\lambda)$. Then the set of functions $t^k e^{t\lambda_i}$, $k=0, \dots, m_i - 1$ form a fundamental set of solns.

PROOF: $L_n(e^{t\lambda}) = f(\lambda) e^{t\lambda} \quad \text{--- ①}$

$$L_n(t^k e^{t\lambda}) = L_n\left(\frac{\partial^k}{\partial \lambda^k} e^{t\lambda}\right)$$

$$= \frac{\partial^k}{\partial \lambda^k} (L_n(e^{t\lambda})) = \frac{\partial^k}{\partial \lambda^k} (f(\lambda) e^{t\lambda})$$

$$= (f^{(k)}(\lambda) + k f^{(k-1)}(\lambda)t + \frac{k(k-1)}{2} f^{(k-2)}(\lambda)t^2$$

$$+ \dots + f(\lambda)t^k) e^{t\lambda} \quad \text{--- ②}$$

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Ordinary differential equation of order n with constant coefficients

$$L_n x = x^{(n)} + a_1 x^{(n-1)} + \dots + a_n x = 0$$

$$f(\lambda) = \lambda^n + a_1 \lambda^{n-1} + \dots + a_n$$

$$L_n = \frac{d^n}{dt^n} + a_1 \frac{d^{n-1}}{dt^{n-1}} + \dots + a_n$$

THEOREM: Let $\lambda_1, \dots, \lambda_s$ be distinct zeros of the polynomial $f(\lambda)$. Also let m_i be the multiplicity of λ_i as a zero of f .

$$(f(\lambda) = (\lambda - \lambda_i)^{m_i} g(\lambda))$$

Then $t^k e^{t\lambda_i}$, $k=0, \dots, m_i - 1$ are fundamental solutions of ①.

FACT: λ_i has multiplicity m_i if the derivatives of f at λ_i vanish upto order $m_i - 1$.

PROOF: $\frac{d^k}{dt^k}(e^{t\lambda}) = \lambda^k e^{t\lambda}$

$$L_n(e^{t\lambda}) = f(\lambda)e^{t\lambda} \quad \text{--- ①}$$

$$L_n(t^k e^{t\lambda}) = L_n\left(\frac{\partial^k}{\partial \lambda^k} e^{t\lambda}\right) = \frac{\partial^k}{\partial \lambda^k} L_n(e^{t\lambda}) = \frac{\partial^k}{\partial \lambda^k} (f(\lambda)e^{t\lambda})$$

Periodic Linear Systems :-

$$\begin{aligned} \dot{x}(t) &= A(t)x(t) \\ A(t+\omega) &= A(t) \quad \forall t \in \mathbb{R}, \omega > 0 \end{aligned}$$

$$\frac{d^2\theta}{dt^2} = -\frac{g}{L} \sin \theta$$

$$\begin{aligned} \text{EXAMPLE: } \dot{x} &= \sin^2 t x \\ A(t) &= \sin^2 t \\ A(t+\pi) &= A(t) \end{aligned} \quad \begin{aligned} x(t) &= c \exp\left(t/2\right) \exp\left(-\frac{\sin 2t}{4}\right) \\ c &\neq 0 \\ \dot{x} &= \sin t x(t) \end{aligned}$$

THEOREM (FLOQUET) :- Consider the linear system

$$\dot{x}(t) = A(t)x(t) \quad \text{--- ①}$$

where $A: \mathbb{R} \rightarrow M_n(\mathbb{R})$ continuous with the least positive period ω , i.e.,
 $A(t) = A(t+\omega) \quad \forall t \in \mathbb{R}$.

Let ψ be a fundamental solution matrix of ① then

$$\psi_\omega(t) = \psi(t+\omega)$$

is a fundamental solution matrix. Furthermore,

$$\psi(t) = P(t) e^{Bt}$$

where $P: \mathbb{R} \rightarrow M_n(\mathbb{R})$ is a continuously differentiable periodic function with period ω and B is a complex matrix (constant).

THEOREM: Let C be a nonsingular matrix. Then $\exists B \in M_n(\mathbb{C})$ s.t.
 $e^B = C$

PROOF $n=2$

Case 1: Say, C diagonalisable; $J = \begin{pmatrix} \mu_1 & 0 \\ 0 & \mu_2 \end{pmatrix}$

Take $B = \begin{pmatrix} \log \mu_1 & 0 \\ 0 & \log \mu_2 \end{pmatrix}$

$$\text{also } P^{-1} e^B P = e^{P^{-1} B P}$$

$$C = PJP^{-1}$$

$$C = Pe^K P^{-1} = e^{PKP^{-1}}$$

$$C = PJP^{-1}$$

$$J = \begin{pmatrix} \mu_1 & 0 \\ 0 & \mu_2 \end{pmatrix}$$

or

$$J = \begin{pmatrix} \mu_1 & 1 \\ 0 & \mu_2 \end{pmatrix}$$

$$\text{take } \tilde{B} = P^{-1}BP$$

$$B = PKP^{-1} = P \begin{pmatrix} \log \mu_1 & 0 \\ 0 & \log \mu_2 \end{pmatrix} P^{-1}$$

Case 2: $J = \begin{pmatrix} \mu & 1 \\ 0 & \mu \end{pmatrix}$

$$K = \begin{pmatrix} a_1 & a_2 \\ 0 & a_1 \end{pmatrix}$$

$$e^K = \begin{pmatrix} e^{a_1} & a_2 e^{a_1} \\ 0 & e^{a_1} \end{pmatrix}$$

$$K = \begin{pmatrix} \log \mu & 1/\mu \\ 0 & \log \mu \end{pmatrix} \quad \mu \neq 0$$

$$B = PKP^{-1}$$

Jordan Canonical Form

$$J = \begin{bmatrix} J_1 & 0 & & \\ 0 & J_2 & & \\ & \ddots & \ddots & 0 \\ & & 0 & J_k \end{bmatrix}$$

where for each i

$$① J_i = [\lambda]$$

$$② J_i = \begin{bmatrix} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_2 & 1 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & \lambda_n \end{bmatrix}$$

$$J = \bigoplus_{i=1}^k J_i$$

$$K = \bigoplus_{i=1}^k K_i$$

$$\exp \begin{bmatrix} K_1 & & & \\ & K_2 & & \\ & & \ddots & \\ & & & K_k \end{bmatrix} = \begin{bmatrix} \exp(K_1) & 0 & 0 & 0 \\ 0 & \exp(K_2) & 0 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & \exp(K_k) \end{bmatrix}$$

PROOF OF FLOQUET'S THEOREM:-

$$\begin{aligned} \psi_\omega'(t) &= \psi'(t+\omega) = A(t+\omega)\psi(t+\omega) \\ &= A(t)\psi(t+\omega) = A(t)\psi_\omega(t) \end{aligned}$$

$\Rightarrow \psi_\omega$ is a soln. matrix

$$\det(\psi_\omega(t)) = \det(\psi(t+\omega)) \neq 0$$

$\Rightarrow \psi(t+\omega)$ is a FSM.

Fix a point $t_0 \in \mathbb{R}$.

$$c_0 = \psi^{-1}(t_0) \psi_\omega(t_0)$$

Note c_0 is a non-singular matrix.

$$\psi_\omega(t_0) = \psi(t_0) c$$

Now observe $\psi(t)c$ is a FSM and agrees with $\psi_\omega(t)$ at t_0 . Hence,

$$\psi_\omega(t) = \psi(t)c$$

$$\psi(t+\omega) = \psi(t)c \quad \forall t \in \mathbb{R}$$

By the existence of \log for $M \in GL_n(\mathbb{R})$

$$\exists B \in M_n(\mathbb{R}) \text{ s.t. } c = \exp(B\omega)$$

$$\text{Consider } P(t) = \psi(t) \exp(-Bt) \quad \psi(t) = P(t) \exp(Bt)$$

$$P(t+\omega) = \psi(t+\omega) \exp(-B(t+\omega)) = \psi(t) \exp(-Bt) \exp(-B\omega) \subset$$

$$= \psi(t) \exp(-Bt) = P(t)$$

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Stability of LHS:-

$$\dot{x}(t) = A(t)x(t)$$

In the 2×2 case, A is a constant matrix.

$$\dot{x}(t) = A(t)x(t)$$

Case 1. A is diagonalizable with eigenvalues α_1 & α_2 .

$$x(t) = ae^{\alpha_1 t} u_1 + be^{\alpha_2 t} u_2$$

$$\|x(t)\|^2 = e^{2\alpha_1 t} \|u_1\|^2 a^2 + e^{2\alpha_2 t} \|u_2\|^2 b^2 + 2e^{(\alpha_1 + \alpha_2)t} ab \langle u_1, u_2 \rangle$$

$$\leq (e^{\alpha_1 t} |a| \|u_1\| + e^{\alpha_2 t} |b| \|u_2\|)^2 < \epsilon$$

$$e^{\alpha_1 t} |a| \|u_1\| + e^{\alpha_2 t} |b| \|u_2\| < \sqrt{\epsilon}$$

Suppose $\alpha_1, \alpha_2 < 0$,

$$\text{then } |a| \|u_1\| + |b| \|u_2\| < \sqrt{\epsilon}$$

THEOREM: Consider $\dot{x}(t) = A(t)x(t)$ where A is an $n \times n$ real matrix. Then

- Suppose $\exists \lambda$, an eigenvalue of A such that $\operatorname{Re}(\lambda) > 0$ then the trivial soln. is unstable
- Suppose all the eigenvalues with zero real part are simple, and all other eigenvalues have negative real part, then the solution is stable.
- If all eigenvalues of A have negative real part then the solution is asymptotically stable.

Periodic System :-

$$\dot{x}(t) = A(t)x(t) \quad A(t+\omega) = A(t)$$

THEOREM: Let u_1, \dots, u_n be the Floquet multipliers of the system. Then the following holds true.

- If $|u_i| < 1 \forall i \leq i \leq n$ then the trivial soln. is asymptotically stable.
- Stable if $\forall i, |u_i| \leq 1$
- Unstable if $\exists i, |u_i| > 1$

Kellert & Peterson

Boundary Value Problems:

$$\frac{\partial^2 u(t, x)}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 u(t, x)}{\partial t^2}$$

One-dim. wave
eqn.

$u(t, x) :=$ disp. of the start at x , and time t ,
 $c :=$ propagation speed

$$u(t, 0) = 0, \quad u(t, 1) = 0$$

$$u(0, x) = u(x), \quad \frac{\partial u}{\partial t}(0, x) = v(x)$$

$$u(t, x) = w(t)y(x)$$

$$\frac{1}{c^2} \frac{w''(t)}{w(t)} = \frac{y''(x)}{y(x)} = -\lambda$$

$$\Rightarrow \begin{aligned} y''(x) &= -\lambda y(x) - \textcircled{1} & y(0) &= 0, \quad y(1) = 0 \\ w''(t) &= -c^2 \lambda w(t) - \textcircled{2} \end{aligned}$$

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Stability of Autonomous System

THEOREM: Consider $\dot{x}(t) = Ax(t)$. Then the trivial soln.

Stable \Leftrightarrow for any $\lambda \in \sigma(A)$, $\operatorname{Re}(\lambda) \leq 0$ and $m_g(\lambda) = m_a(\lambda) \neq 0$
 with $\operatorname{Re}(\lambda) = 0$.

Unstable $\Leftrightarrow \exists \lambda \in \sigma(A)$ s.t. $\operatorname{Re}(\lambda) > 0$ or $\exists \lambda \in \sigma(A)$ s.t. $\operatorname{Re}(\lambda) = 0$
 & $m_a(\lambda) > m_g(\lambda) \geq 1$

Asymptotic Stable $\Leftrightarrow \operatorname{Re}(\lambda) < 0 \nabla \lambda \in \sigma(A)$

Here, $A \in M_n(\mathbb{R})$

$\sigma(A) :=$ the set of all eigenvalues of A
 $\lambda \in \sigma(A)$

$m_g(\lambda) :=$ the geometric multiplicity of λ
 $= \dim(\ker A - \lambda \mathbb{I})$

$m_a(\lambda) :=$ algebraic multiplicity of λ

Sturm Boundary Value Problems :-

$$\frac{\partial^2 u(t, x)}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 u(t, x)}{\partial t^2}$$

$$u(0, x) = u(x)$$

$$\frac{\partial}{\partial x} u(0, x) = v(x)$$

One-dim.

$$u(t, x) = w(t)y(x)$$

$$\Rightarrow \frac{1}{c^2} \frac{w''(t)}{w(t)} = \frac{y''(x)}{y(x)} = -\lambda \text{ (a constant)}$$

$$u(t, 0) = 0, \quad u(t, 1) = 0$$

$$\Rightarrow W''(t) + c^2 \lambda W(t) = 0$$

$$y''(x) + \lambda y(x) = 0, y(0) = 0, y(1) = 0 \quad \text{--- (1)}$$

$$c^2 + c^2 \lambda = 0$$

Case ①: $\lambda > 0$

$$\pm i c \sqrt{\lambda}$$

$$\alpha e^{ic\sqrt{\lambda}x} + \beta e^{-ic\sqrt{\lambda}x}$$

$$W(t) = \alpha \cos c\sqrt{\lambda}t + \beta \sin c\sqrt{\lambda}t$$

$$c^2 + \lambda = 0$$

$$y(x) = \gamma \cos \sqrt{\lambda}x + \delta \sin \sqrt{\lambda}x$$

$$y(0) = 0 \Rightarrow \gamma = 0$$

$$y(1) = 0$$

$$\delta \sin \sqrt{\lambda} = 0$$

$$\delta = 0 \text{ or } \sin \sqrt{\lambda} = 0$$

$$\Rightarrow \sqrt{\lambda} = n\pi \Rightarrow \lambda = n^2\pi^2$$

$$U_n(t, x) = (\alpha \cos cn\pi t + \beta \sin cn\pi t) \sin n\pi x$$

DEFINITION (ADJOINT) :-

Consider second order ODE,

$$a_0(t) \frac{d^2 x}{dt^2} + a_1(t) \frac{dx}{dt} + a_2(t) x(t) = 0 \quad \text{--- (1)}$$

Here: a_0 is twice continuously differentiable & $a_0(t) \neq 0$ on I.
 a_1 is continuously differentiable.
 a_2 is continuous.

The adjoint of (1) is the differential equation :

$$\frac{d^2}{dt^2} (a_0(t) x(t)) - \frac{d}{dt} (a_1(t) x(t)) + a_2(t) x(t) = 0$$

$$\Leftrightarrow a_0(t) \frac{d^2 x}{dt^2} + [2a_0'(t) - a_1(t)] \frac{dx}{dt} + (a_0''(t) - a_1'(t) + a_2(t)) x(t) = 0$$

DEFINITION : ① is called self-adjoint if ① and its adjoint eqn. are identical $\Leftrightarrow 2a_0'(t) - a_1(t) = a_1(t)$
 $\Leftrightarrow a_0'(t) = a_1(t)$
 \Leftrightarrow ① can be written in the following form :-

$$\frac{d}{dt} \left(a_0(t) \frac{dx}{dt} \right) + a_2(t) x(t) = 0$$

EXAMPLE : $(1-t^2) \frac{d^2 x}{dt^2} - 2t \frac{dx}{dt} + n(n+1)x(t) = 0$

HOMEWORK :

$$a_0(t) \frac{d^2x}{dt^2} + a_1(t) \frac{dx}{dt} + a_0(t)x(t) = 0 \quad (*)$$

$\frac{d}{dt} \left(P(t) \frac{dx}{dt} \right) + Q(t)x(t) = 0$ by multiplying (*) by

$$\frac{1}{a_0(t)} \exp \int \frac{a_1(t)}{a_0(t)} dt$$

$$P(t) = \exp \left(\int \frac{a_1(t)}{a_0(t)} dt \right)$$

$$Q(t) = \frac{a_2(t)}{a_0(t)} \exp \left(\int \frac{a_1(t)}{a_0(t)} dt \right)$$

From now on the general, second-order, self-adjoint ordinary DE that we will consider:

$$(p(t)x')' + q(t)x(t) = h(t)$$

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Consider the self-adjoint equation:

$$(p(t)x')' + q(t)x(t) = h(t)$$

Assuming that $p(t), q(t), h(t)$ are continuous on I .

$$\mathcal{D} := \{x \in C(I) : \dots\}$$

DEFINITION: $x(t)$ & $y(t)$ are differentiable fncs, then we define

$$W(x(t), y(t)) = \det \begin{pmatrix} x(t) & y(t) \\ x'(t) & y'(t) \end{pmatrix}$$

Lagrange's Identity: Suppose $x, y \in \mathcal{D}$ then

$$x(t)L(y(t)) - y(t)L(x(t)) = [p(t)W(x(t), y(t))]_{t \in I}$$

Corollary: If x, y are solns of $L(x(t)) = 0$

$$\text{then } W(x(t), y(t)) = \frac{C}{p(t)}, \text{ where } C \text{ is a constant } \forall t \in I.$$

Sturm-Liouville Boundary Problems :-

$$(p(t)x')' + (\lambda \sigma(t) + q(t))x(t) = 0$$

together with boundary conditions

$$\left. \begin{array}{l} \alpha x(a) - \beta x'(a) = 0 \\ \gamma x(b) - \delta x'(b) = 0 \end{array} \right\} \text{(SLP)} \quad \begin{array}{l} p(t) > 0 \\ \alpha^2 + \beta^2 > 0 \end{array} \quad \begin{array}{l} y(t) \geq 0 \\ \gamma^2 + \delta^2 > 0 \end{array}$$

$$I = [a, b]$$

$$L(x(t)) = (p(t)x')' + q(t)x(t)$$

DEFINITION: $\lambda_0 \in \mathbb{R}$ is called an eigenvalue of (SLP) if $\exists x_0$, a nontrivial funcⁿs.t.

$$Lx_0(t) = -\lambda_0 y(t)x_0(t)$$

satisfying the boundary condition.

(λ_0, x_0) an eigenpair, x_0 is called the eigen function corresponding to λ_0 .

Suppose, given a λ_0 an eigenvalue of (SLP) if any two eigenfuncⁿs corresponding to λ_0 are lin. dependent, then λ_0 is called simple.

EXAMPLE: $x'' = -\lambda x$, $x(0) = 0$, $x(\pi) = 0$

Case I: $\lambda > 0$, $\lambda = \mu^2$

$$x'' + \mu^2 x = 0$$

$$t^2 + \mu^2 = 0 \quad t = \pm \mu$$

$$x(t) = \alpha e^{i\mu t} + \beta e^{-i\mu t}$$

$$= \alpha \cos \mu t + \beta \sin \mu t$$

$$\alpha = \alpha, \beta = \beta \sin \pi \mu$$

$$\beta \neq 0, \sin \pi \mu = 0 \quad \pi \mu = \pm n\pi$$

$$\mu = \pm n$$

$$\lambda = \mu^2 = n^2$$

$$\lambda = n^2, n_\lambda(t) = \pm \sin nt$$

Case II: $\lambda = 0$.

$$x'' = 0 \quad x(t) = \alpha + \beta t$$

$$x(0) = 0 \Rightarrow \alpha = 0$$

$$x(\pi) = 0, \beta \pi = 0, \beta = 0$$

Case III: $\lambda = -\mu^2$

$$x'' - \mu^2 x = 0$$

$$x(t) = \alpha e^{\mu t} + \beta e^{-\mu t}$$

$$\begin{pmatrix} 1 & 1 \\ e^{\pi \mu} & e^{-\pi \mu} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = 0$$

$$x(0) = 0$$

$$\alpha + \beta = 0$$

$$\alpha e^{\pi \mu} + \beta e^{-\pi \mu} = 0$$

DEFINITION: Let $y \in C([a, b], \mathbb{R})$ & assume $y \geq 0$ & not identically equal to zero.

Then on $C([a, b], \mathbb{R})$, we introduce the inner product, defined by

$$\langle x(t), y(t) \rangle_y = \int_a^b x(t)y(t)r(t)dt$$

x & y are orthogonal w.r.t. r if $\langle x(t), y(t) \rangle_y = 0$

THEOREM: $Lx(t) = -\lambda y(t)x(t)$

$$\alpha x(a) - \beta x'(a) = 0$$

$$\alpha^2 + \beta$$

$$\gamma x(b) - \delta x'(b) = 0$$

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THEOREM: Consider the (SLP)

$$\begin{aligned} (px')' + (\lambda f(t) + g(t))x &= 0 \\ \alpha x(a) - \beta x'(a) &= 0 \\ \delta x(b) - \gamma x'(b) &= 0 \end{aligned} \quad \left. \right\} \text{(BV)}$$

When $p > 0$, $\alpha \geq 0$ and $g \in C[a, b]$

The eigenfunctions corresponding to distinct eigen values are orthogonal.
Each eigen value is simple.

PROOF: (λ_1, x_1) (λ_2, x_2)

$$\begin{aligned} (\lambda_1 - \lambda_2) \langle x_1, x_2 \rangle_g &= [p(t)W(x_1(t), x_2(t))]_a^b \\ W(x_1(t), x_2(t)) \Big|_{t=a} &= x_1(a)x_2'(a) - x_2(a)x_1'(a) \\ &= x_1(a) \cancel{\alpha x_2(a)} - x_2(a) \cancel{\alpha x_1(a)} = 0 \end{aligned}$$

$$\alpha x_j(a) - \beta x_j'(a) = 0$$
$$\beta = 0, W(x_1(t), x_2(t)) \Big|_{t=a} = 0$$

$$(\lambda_1 - \lambda_2) \langle x_1, x_2 \rangle_g = 0$$

$$\lambda_1 \neq \lambda_2 \Rightarrow \langle x_1, x_2 \rangle_g = 0$$

$$(\lambda_1, x_1), (\lambda_2, x_2)$$

$$(\lambda_1 - \lambda_2) p(t)x_1(t)x_2(t) = [p(t)W(x_1, x_2)]$$

$$\Rightarrow p(t)W(x_1, x_2) = 0$$

From boundary condit., $C=0 \Rightarrow W(x_1, x_2) = 0$

$\Rightarrow x_1, x_2$ are l.d.

STRUM-LOUVILLE THEOREM:

Then the (SLP) has an infinite seq. of eigenvalues (λ_n) with $\lambda_n < \lambda_{n+1}$ & $\lim_{n \rightarrow \infty} \lambda_n = \infty$. The eigenfuncⁿ corresponding to each λ_n has precisely $(n-1)$ zeros in $[a, b]$.

Oscillation Theory:

Consider

$$(Px')' + Q(t)x = 0$$

Prüfer Substitution:

We write

$$px' = r(t) \cos \theta(t)$$

$$x = r(t) \sin \theta(t)$$

$$(rx')^2 + x^2 = (r(t))^2$$

$$\tan \theta(t) = \frac{x}{px'}$$

$$\cot \theta(t) = \frac{px'}{x}$$

$$-\operatorname{cosec}^2 \theta(t) \frac{d\theta}{dt} = \frac{(Px')'}{x} - \frac{Px'^2}{x^2}$$

$$= -Q(t) - \frac{1}{P} \frac{r(t)^2 \cos^2 \theta(t)}{r(t)^2 \sin^2 \theta(t)}$$

$$2r(t)r'(t) = 2Px'(Px')' + 2xx'$$

$$= 2Px'(-Q(t)x(t)) + 2xx'$$

$$= 2r^2(t) \cos \theta(t) - Q(t) \sin \theta(t)$$

$$+ \frac{2r^2(t) \sin \theta(t) \cos \theta(t)}{P}$$

$$\frac{d\theta}{dt} = Q(t) \sin^2 \theta + \frac{1}{P} \cos^2 \theta$$

$$= F(t, \theta) \quad \text{--- ①}$$

$$\frac{dr}{dt} = \frac{1}{2} r \sin 2\theta \left(\frac{1}{P(t)} - Q(t) \right) \quad \text{--- ②}$$

PRÜFER
SYSTEM

LEMMA: If (SLP) has non-trivial soln., $\theta(t)$ never vanishes

Consider the self-adjoint equation

$$(Px')' + Q(t)x(t) = 0 \quad (\text{SA})$$

We say (SA) is oscillatory if it admits a soln. that has more than one zero.

OBSERVATION: If x is a soln. of (SA) on $[a, b]$ and let $t_0 \in [a, b]$ s.t.

$$x(t_0) = 0 \text{ then } \theta(t_0) = m\pi, m \in \mathbb{Z}$$

PROPOSITION: For each $m \in \mathbb{Z}$, \exists atmost one point $t_m \in [a, b]$ s.t. $\theta(t_m) = m\pi$

Moreover if $t < t_m$ then $\theta(t) < m\pi$ and if $t > t_m$, $\theta(t) > m\pi$

PROOF: Consider the constant funcⁿ

$$y(t) = m\pi$$

$$y'(t) = 0 \quad F(t, m\pi) = \frac{1}{P(t)} > 0 = y'(t)$$

Suppose $t_m \in [a, b]$ is such that

$$\theta(t_m) = m\pi = y(t_m)$$

$$\theta(t) > m\pi \forall t > t_m$$

Say, \tilde{t}_m s.t. $\theta(\tilde{t}_m) = m\pi$, $\tilde{t}_m < t_m \Rightarrow \theta(t_m) > m\pi (*)$

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Consider θ -equations corresponding to two Brüfer systems:

$$\hat{\theta} = \hat{Q} \sin^2 \hat{\theta} + \frac{1}{\hat{P}} \cos^2 \hat{\theta} \quad \hat{\theta}(a) = \hat{\theta}_0$$

$$\theta' = Q \sin^2 \theta + \frac{1}{P} \cos^2 \theta = F(t, \theta) \quad \theta(a) = \theta_0$$

PROPOSITION 1: Suppose $Q(t) \geq \hat{Q}(t) \forall t \in (a, b)$ and $\frac{1}{P(t)} \geq \frac{1}{\hat{P}(t)} \forall t \in (a, b)$ and assume that $\theta_0 \geq \hat{\theta}_0$. Then $\theta(t) \geq \hat{\theta}(t) \forall t \in [a, b]$. Moreover, if $\exists t_* \in (a, b)$ s.t. $\theta(t_*) = \hat{\theta}(t_*)$ then $\theta(t) = \hat{\theta}(t) \forall t \in [a, t_*]$

$$\text{PROOF: } \hat{\theta}' - F(t, \hat{\theta}) = \hat{Q} \sin^2 \hat{\theta} + \frac{1}{\hat{P}} \cos^2 \hat{\theta} - \left(Q \sin^2 \hat{\theta} + \frac{1}{P} \cos^2 \hat{\theta} \right)$$

$$= \sin^2 \hat{\theta} (\hat{Q} - Q) + \cos^2 \hat{\theta} \left(\frac{1}{\hat{P}} - \frac{1}{P} \right) \leq 0 = \theta' - F(t, \theta)$$

Since $\hat{\theta}(a) \leq \theta(a) \Rightarrow \theta(t) \geq \hat{\theta}(t) \forall t \in [a, b]$

COROLLARY: Suppose in Proposition 1, we have either $Q(t) > \hat{Q}(t) \forall t \in (a, b)$ or

$$\frac{1}{P(t)} > \frac{1}{\hat{P}(t)} \quad \forall t \in (a, b). \text{ Then } \theta(t) > \hat{\theta}(t) \forall t \in (a, b)$$

PROOF: Suppose $Q(t) > \hat{Q}(t) \forall t \in (a, b)$. Suppose $\exists t_* \in (a, b)$ s.t. $\theta(t_*) = \hat{\theta}(t_*)$

$$\theta(t) = \hat{\theta}(t) \quad \forall t \in [a, t_*],$$

$$(Q - \hat{Q}) \sin^2 \theta + \left(\frac{1}{P} - \frac{1}{\hat{P}} \right) \cos^2 \theta = 0$$

$$\Rightarrow \sin^2 \theta(t) = 0, \quad \cos^2 \theta(t) = 1$$

≥ 0 on $[a, t_*]$

$\Rightarrow \theta$ is constant

$$\theta' = \frac{1}{P}, \quad \theta \text{ is strictly increasing} \quad (*)$$

STURM COMPARISON THEOREM:-

$$\left(\frac{\hat{P} d\hat{x}}{dt} \right)' + \hat{Q} \hat{x} = 0 \quad \text{I}$$

$$\left(\frac{P dx}{dt} \right)' + Q x = 0 \quad \text{II}$$

Suppose $Q(t) \geq \hat{Q}(t)$ & $P(t) \leq \hat{P}(t) \quad \forall t \in [a, b]$. Now, let \hat{x} be a nontrivial soln. of I that has zeros at $c, d \in [a, b]$. Let x be a soln. of II then x has a zero in the interval $[c, d]$. This implies if \hat{x} has n zeros in $[a, b]$ then x has at least $(n-1)$ zeros in the interval $[a, b]$.

$$\hat{x}(c) = 0 = \hat{x}'(t) \sin \hat{\theta}(c) \Rightarrow \hat{\theta}(c) = m\pi, m \in \mathbb{Z}$$

$$\hat{x}(d) = 0 = \hat{x}'(t) \cos \hat{\theta}(d) \Rightarrow \hat{\theta}(d) = n\pi, n \in \mathbb{Z}$$

We will assume $\hat{\theta}(c) = 0, \hat{\theta}(d) = n\pi, n \in \mathbb{Z}_+$.

Consider the $\hat{\theta}$ and θ eqns. with initial condns.

$$\hat{\theta}(c) = 0$$

$$\theta(c) \in [0, \pi)$$

Then by Proposition 1, $\theta(t) \geq \hat{\theta}(t) \quad \forall t \in [c, b]$

$$\theta(d) \geq \hat{\theta}(d) = n\pi, n \in \mathbb{Z}^+$$

$$\Rightarrow \exists t \in [c, d] \text{ s.t. } \theta(t) = n\pi$$

$$x(t) = \sin \theta(t) = 0$$

First part