Fine tune FasterRCNN to detect our own objects

pip install labelme in your Anaconda environment

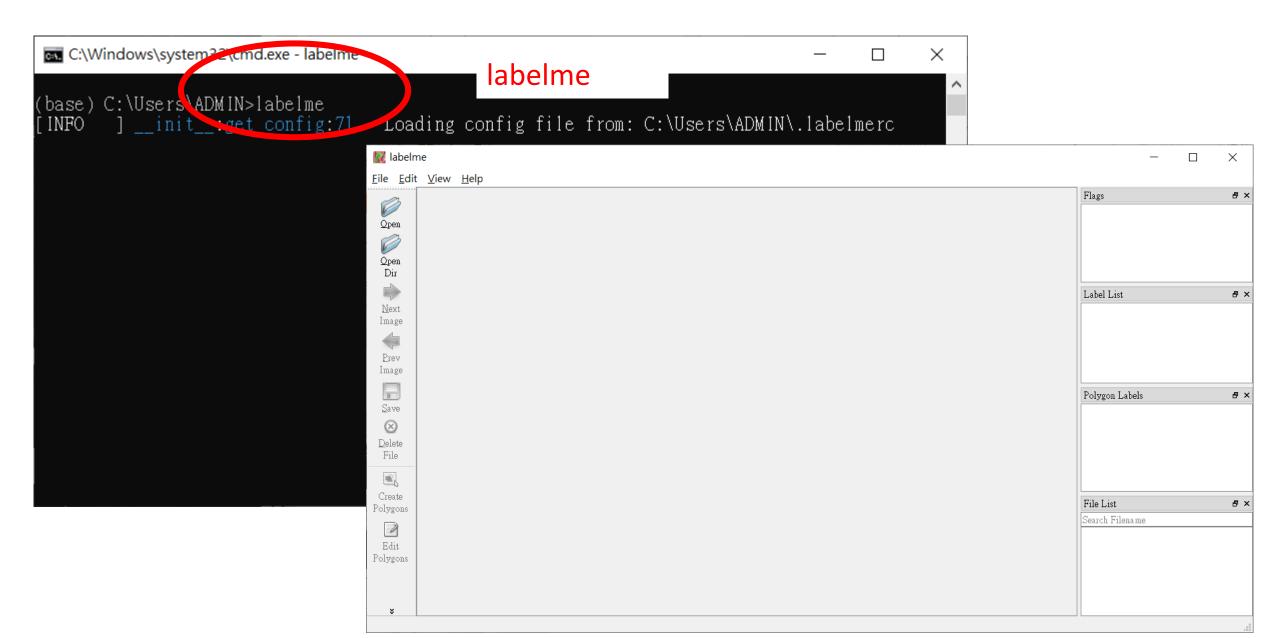
```
C:\Windows\system32\cmd.exe in instanta
                                                                                                                                                                                X
                                                                                              pip install labelme
(base) C:\Users\ADY<mark>(</mark>IN>pip install labelme
Collecting labelme
Downloading labelme 4 5.7.tar.gz (1.5 MB)
                                                       1.5 MB 1.7 MB/s
Collecting imgviz>=0.11.0
Downloading imgviz-1.2.6.tar.gz (7.7 MB)
                                                           7.7 MB 6.8 MB/s
Installing build dependencies ... done

Getting requirements to build wheel ... done

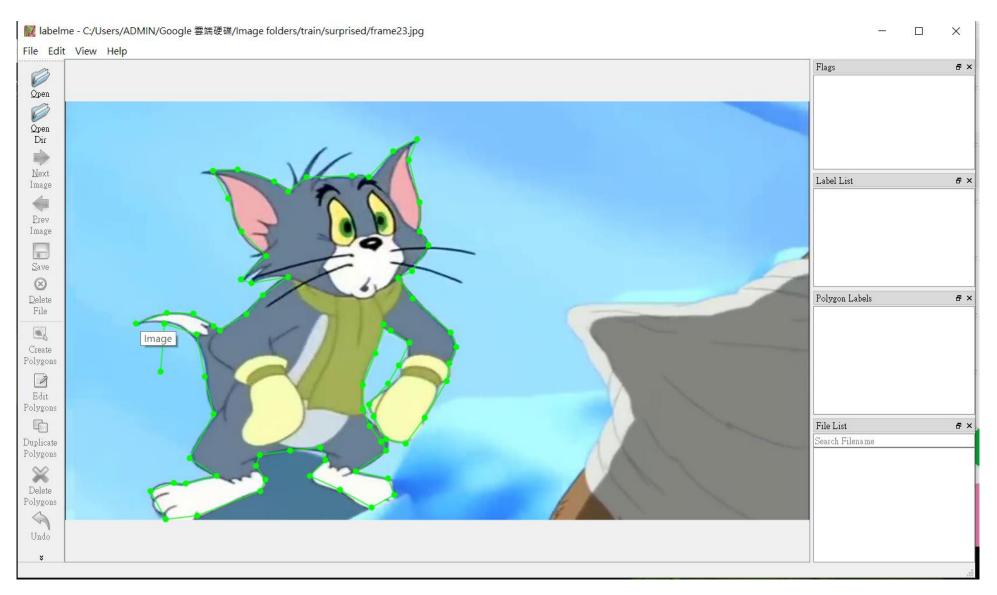
Preparing wheel metadata ... done

Requirement already satisfied: matplotlib<3.3 in c:\users\admin\anaconda3\lib\site-packages (from labelme) (3.1.3)
```

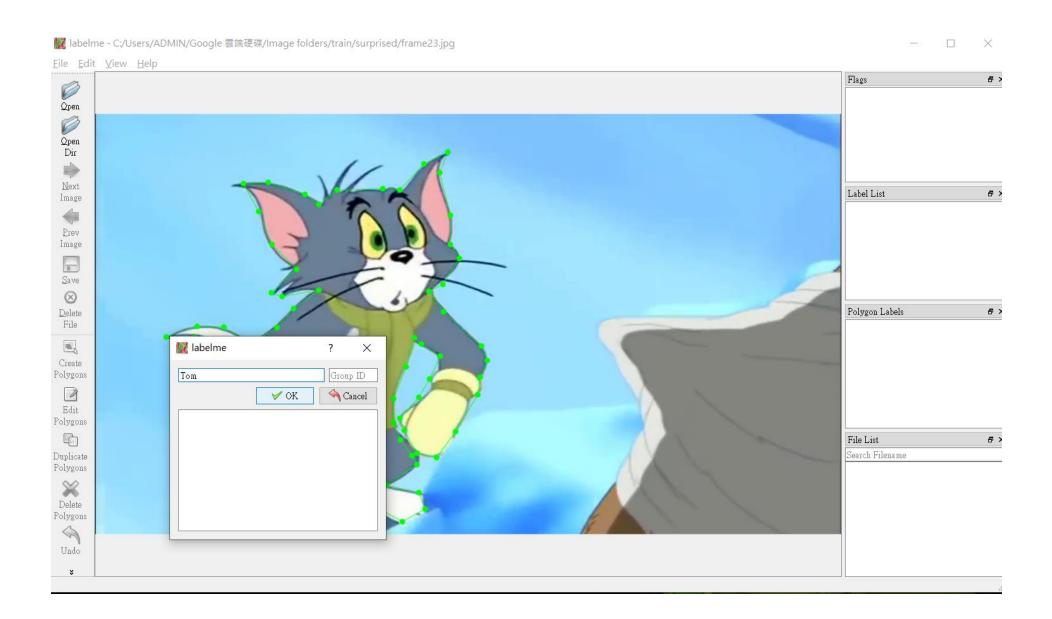
Run labelme



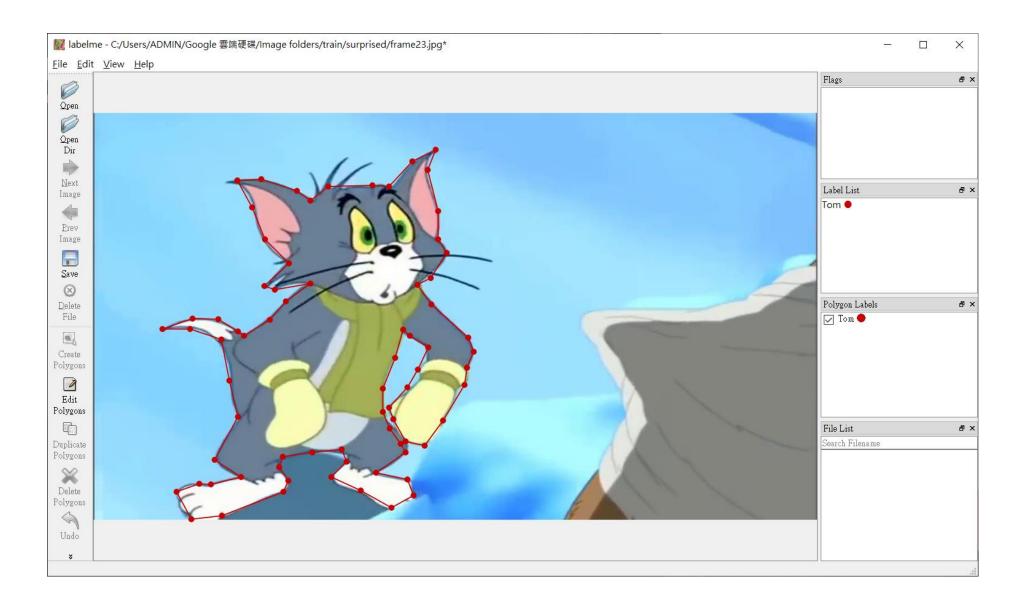
Load an image and draw boundary



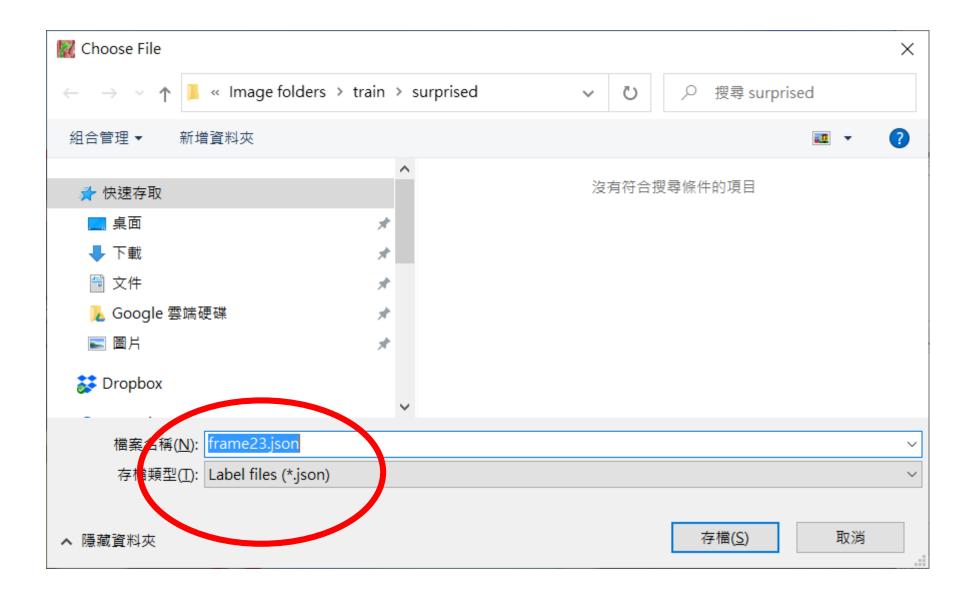
Save label



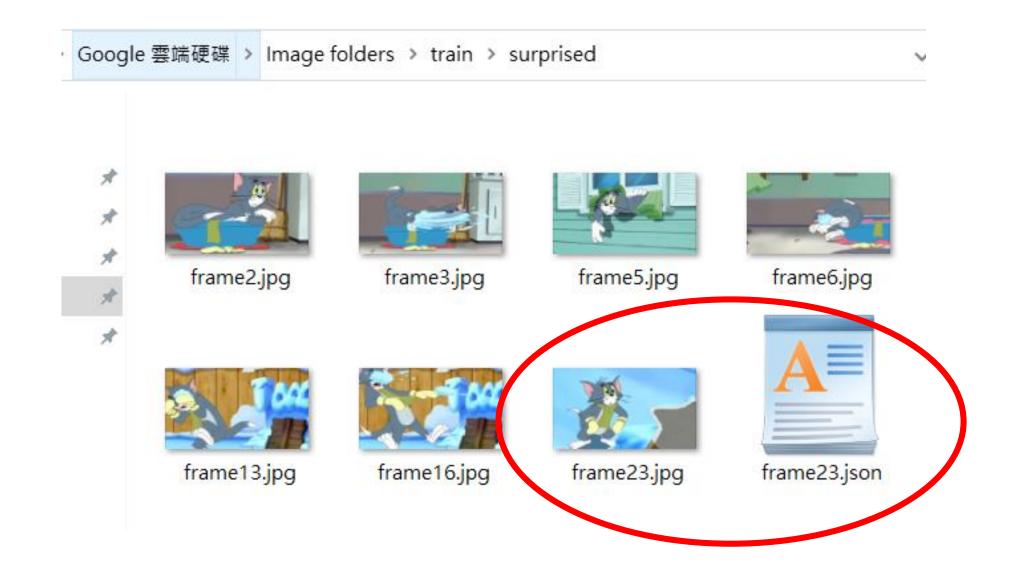
Saved label



Save boundary to json file



Saved json file

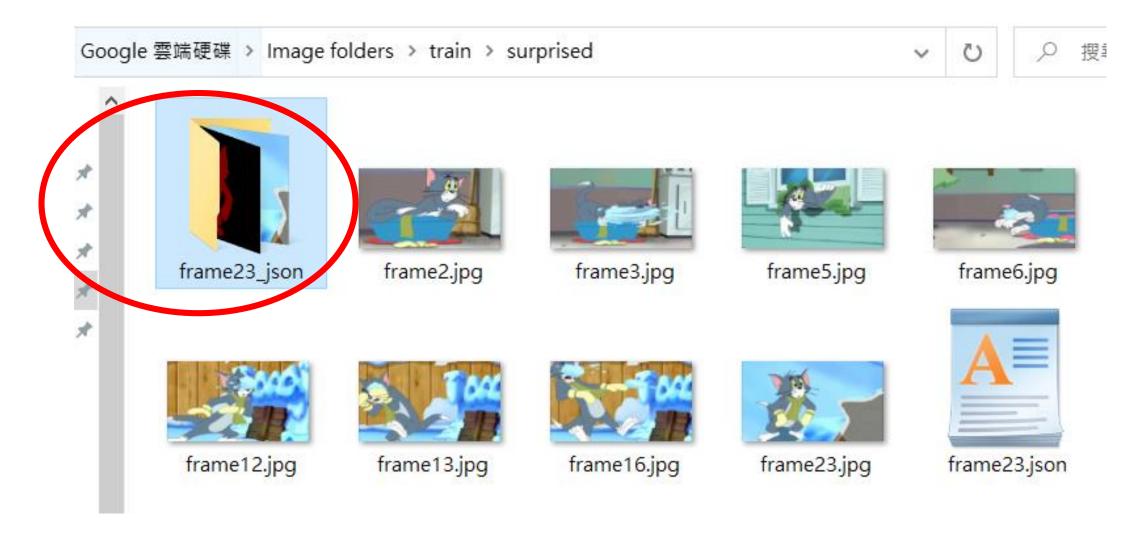


Convert json file to mask image

cd to the folder where you save the *.json file Labelme_json_to_dataset *.json

```
(base) C:\Users\ADMIN\coogle 雲端硬碟\Image folders\train\surprised
(base) C:\Users\ADMIN\coogle 雲端硬碟\Image folders\train\surprised>labelme_json_to_dataset frame23.json
[WARNING] json_to_dataset;main:16 - This script is aimed to demonstrate how to convert the JSON file to a sin gle image dataset.
[WARNING] json_to_dataset:main:20 - It won't handle multiple JSON files to generate a real-use dataset.
[INFO ] json_to_dataset:main:77 - Saved to: irame23_json
(base) C:\Users\ADMIN\Google 雲端硬碟\Image folders\train\surprised>
```

Mask images are saved in a folder

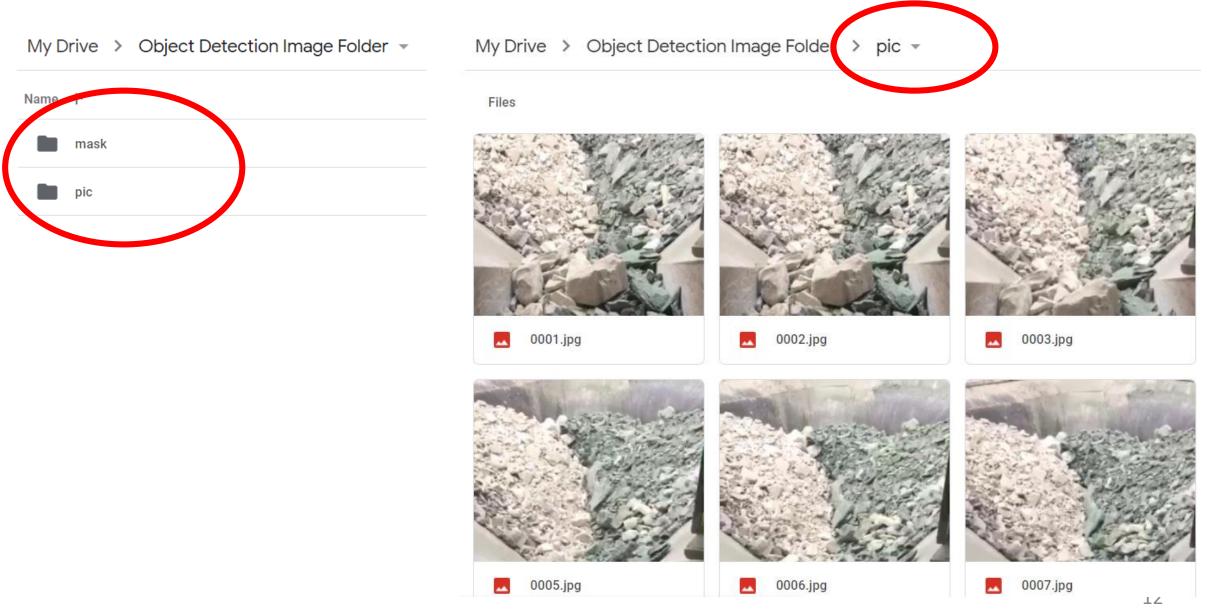


Mask image

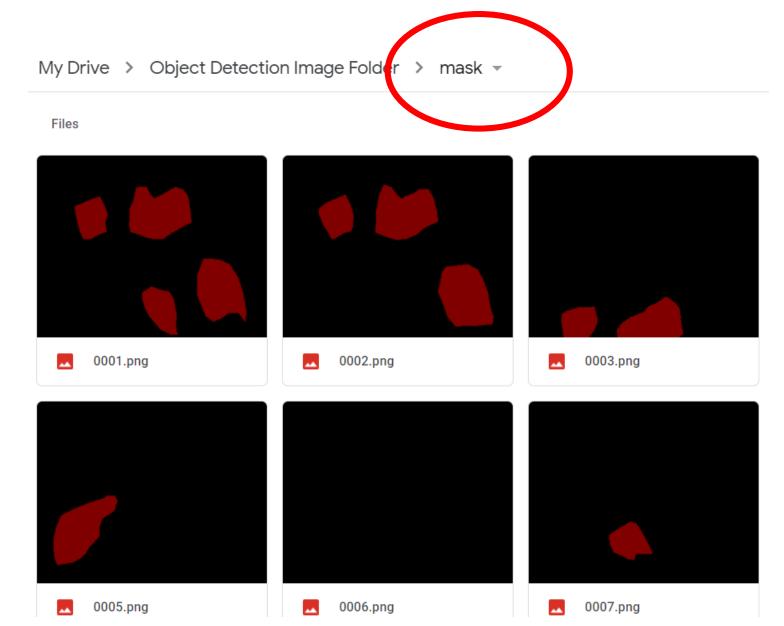
|le 雲端硬碟 > Image folders > train > surprised > frame23_json



Save RGB and mask images on your Google drive



Save RGB and mask images on your Google drive



Fine tune FasterRCNN

FasterRCNN(3) Fine_tune.ipynb

HW4 – Object detector

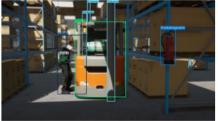
Fine-tune pre-trained FasterRCNN to detect your own objects.

Automatically labelled photo-realistic images

Accelerate computer vision model training with the synthetic image data generated using Unity's perception package

2D bounding boxes







3D bounding boxes



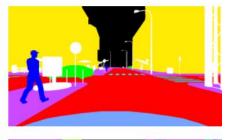




Class segmentation



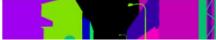




Instance segmentation







Unity perception package



https://github.com/Unity-Technologies/com.unity.perception