

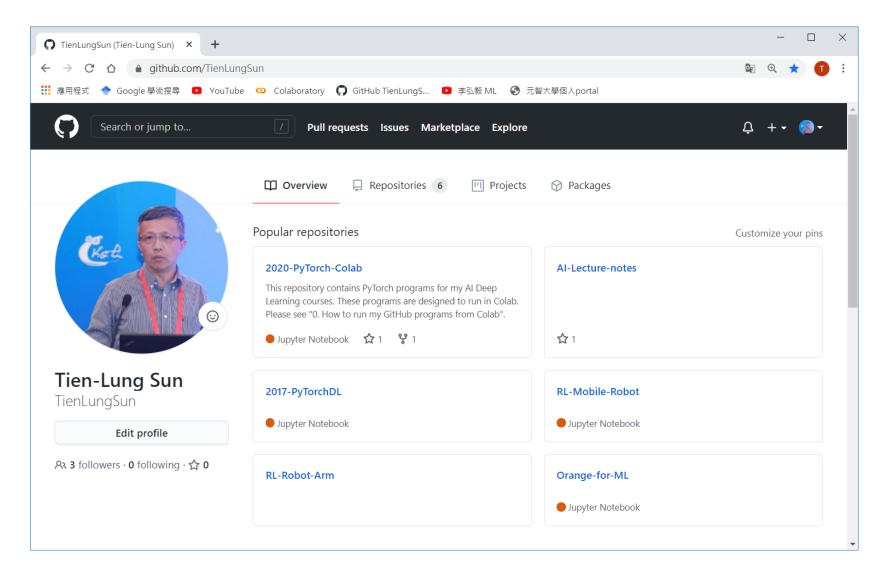
### 元智大學 卓越·務實·宏觀·圓融



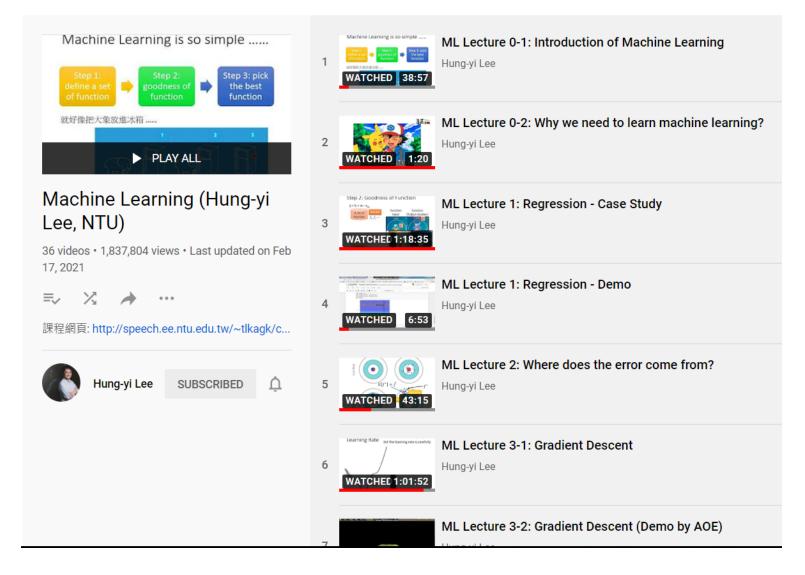
### Deep Learning – Concepts and PyTorch Development

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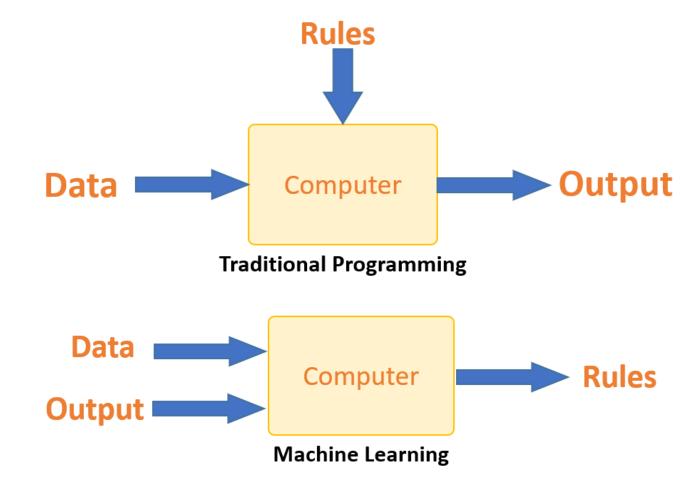
#### My GitHub



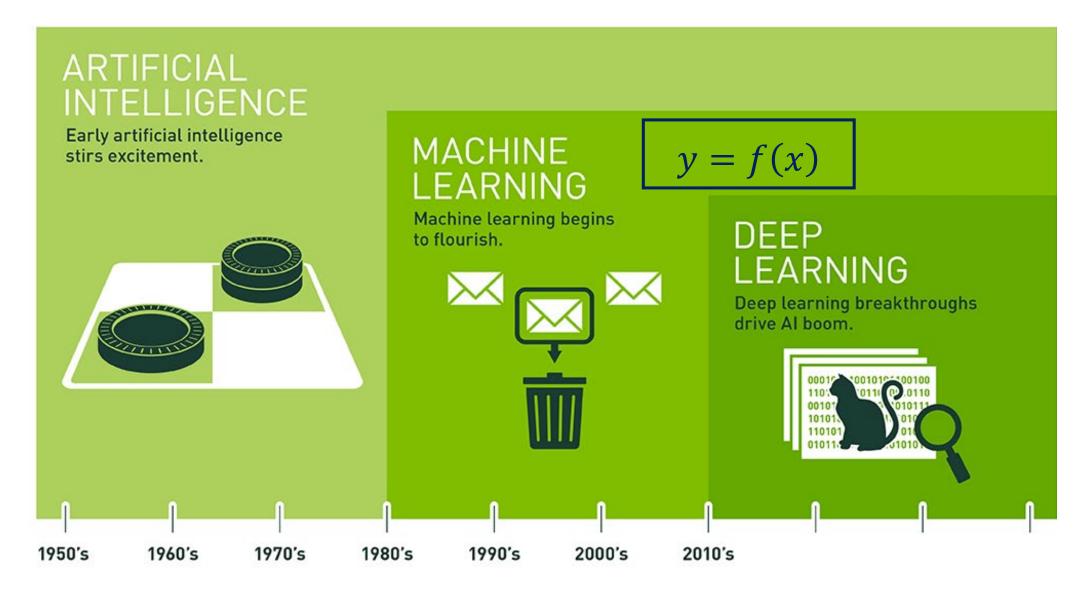
#### Acknowledgement



### ML vs programming approach to let computer have intelligence



#### AI, ML and DL



#### Deep Learning - Machine learns a connected network



Geoffrey Hinton spent 30 years hammering away at an idea most other scientists dismissed as nonsense. Then, one day in 2012, he was proven right. Canada's most influential thinker in the field of artificial intelligence is far too classy to say I told you so

https://torontolife.com/tech/ai-superstars-google-facebook-apple-studied-guy/

For more than 30 years , Geoffrey Hinton hovered at the edges of artificial intelligence research , an outsider clinging to a simple proposition: that computers could think like humans do—using intuition rather than rules.

Geoffrey Hinton 多年來堅持着一個簡單的觀點:電腦可以像人類一樣思考-用直覺而不是規則。 Hinton 一直好奇的是,電腦能不能像人類大腦一樣的工作:信息通過一個巨大的,由神經元圖譜連接 起來的細胞網絡傳播,在多達十億條的路徑上發射、連接和傳輸。

#### Machine learning mechanism

- Define a function to be learned:  $y^n = f(x^n)$
- Define a loss function  $\mathcal{L}(f)$  to describe the error between  $y^n$  and  $\hat{y}^n$
- Find the optimal parameters that minimize  $\mathcal{L}(f)$

#### Machine learning mechanism – SL, SSL and RL

	Supervised Learning	Self-supervised Learning	Reinforcement Learning							
1. Function to be	MLP, CNN families	AE/VAE, GAN	Actor							
learned	y = f(x)	$\hat{x} = f(x)$	a = f(s)							
2. Loss function $\mathcal{L}(f)$	MSE, CE	MSE, CE, KLD, JSD	MSE, KLD							
3. Minimize $\mathcal{L}(f)$	Gradient decent, Maximum Likelihood									

#### After learned, what tasks can Al do?

	Supervised Learning	Self-supervised Learning	Reinforcement Learning				
Function learned	MLP, CNN families	AE/VAE, GAN	Actor				
	y = f(x)	$\hat{x} = f(x)$	a = f(s)				
Intelligence	Recognitic	Interact with dynamic, adversial environment					
Tasks	<ul> <li>Regression</li> <li>Classification</li> <li>CV tasks, image classification, object detection, instance segmentation, subject tracking</li> </ul>	<ul><li>Feature extraction</li><li>Image generation</li><li>Anomaly detection</li></ul>	<ul> <li>Play chess</li> <li>Play video game</li> <li>Mobile robot that can play with elderly</li> <li>Robot arm that can play with elderly</li> </ul>				

#### Challenges in learning a=f(s)

- Define a function to be learned: a = f(s)
- Define a loss function  $\mathcal{L}(f)$  to describe the error between  $y^n$  and

Time-delayed answer – If at time t we perform action  $a_t$  under state  $s_t$ , we only know the immediate reward  $r_t$  and there is a time delay to know the total accumulated reward  $\hat{y}$ .

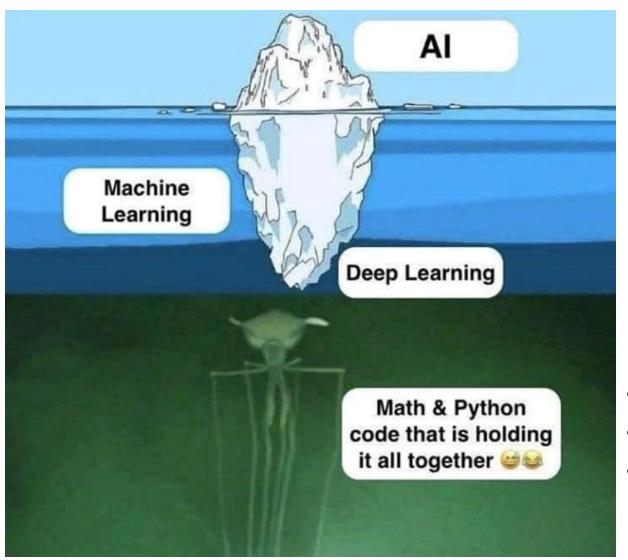
Adversial interaction – After preforming  $a_t$  at state  $s_t$ , there are infinite number of possibilities for following state- actions  $s_{t+1}$ ,  $a_{t+1}$ ,  $s_{t+2}$ ,  $a_{t+2}$ ,  $\cdots$   $s_{t+T}$ ,  $a_{t+T}$ . It is difficult to estimate the true answer y (the true final reward).

• Find the optimal parameters that minimize  $\mathcal{L}(f)$ 

### Development

	Supervised Learning	Self-supervised Learning	Reinforcement Learning
Function	MLP, CNN families	AE/VAE, GAN	Actor
learned	y = f(x)	$\hat{x} = f(x)$	a = f(s)
Training concern	<ul> <li>Labelling cost</li> </ul>	<ul><li>Long training time (? epochs)</li><li>Difficult to train</li></ul>	<ul> <li>Long training time (1M ~5M steps)</li> <li>Difficult to train</li> </ul>
Development	<ul> <li>Integrate pretrained models with application software, e.g., flask, app</li> <li>Deployed to edge computing devices (Jetson Nano, Xavier)</li> </ul>		<ul> <li>Virtual training environment development (Unity, ML Agent)</li> <li>Reward engineering</li> <li>Engineering of other training settings</li> <li>Deploy to edge computing devices (Jetson Nano, Xavier)</li> <li>Mobile robot and robot arm</li> </ul>

#### Math and coding



- Probability and statistics
- Non-linear optimization
- Linear algebra

#### Python

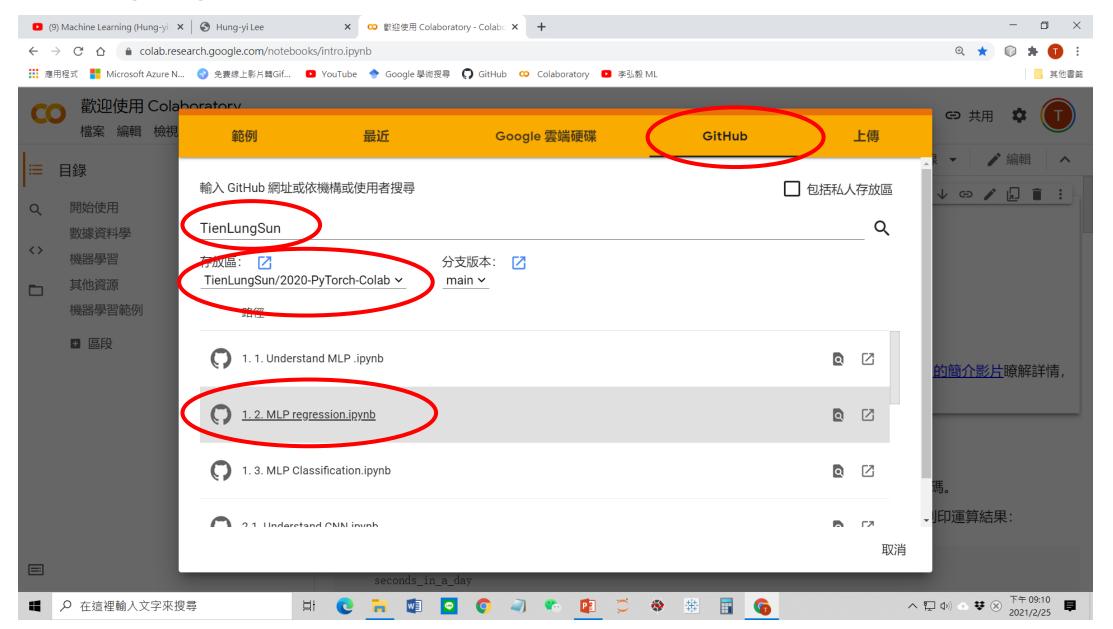








#### Run my PyTorch code in GitHub from Colab



#### Notations

 $x_i$ 

No	age	t1	t2	t3	t4	t5	t6	time	Step frequency	n1	n2	n3	n4	n5	пб	рх	ру	pz	Steps Gende:	r TUG y	<i>y</i> 1	BBS	y2
1	70	1.76	2.64	6.24	7.02	10	12.8	11	2.285	80	120	282	317	453	575	11.67	1.809	-1.99	13 F	11	0	26	0
2	86	1.64	2.6	5.82	7.27	10.4	12.6	11	1.934	75	118	263	328	470	570	11.14	2.302	4.651	12 F	11	0	24	0
3	76	1.76	2.93	6.27	7.04	10.3	12.8	11	2.109	80	133	283	318	465	575	11.53	2.169	-3.253	14 F	11	0	22	1
4	70	2.38	3.29	5.58	6.47	9.02	10.4	8	2.461	108	149	252	292	407	468	11.6	1.838	-3.138	12 F	8	0	24	0
5	66	3.09	4.07	6.6	7.4	10.2	12.1	9	2.461	140	184	298	334	462	545	11.55	2.531	-2.742	12 F	9	0	26	0
6	79	1.76	2.91	5.87	6.6	10.2	12.8	11	2.109	80	132	265	298	462	575	$_{\mathbf{x}}n$	1.788	-1.349	13 F	11	0	26	0
7	85	1.2	2.33	5.42	8.31	12.1	17.2	16	2.988	55	106	245	375	545	775	$\lambda_i$	2.203	4.89	17 M	16	1	18	1
8	81	1.64	2.93	5.98	7.47	10.9	13.6	12	1.758	75	133	270	337	493	615	11.1	2.667	<b>-4.</b> 594	10 F	12	0	24	0
9	82	0.64	1.47	4.76	5.76	9.36	11.6	11	2.109	30	67	215	260	422	525	11.26	4.1	-2.693	14 M	11	0	24	0
10	69	1.64	2.49	5.02	5.98	9.82	12.6	11	2.637	75	113	227	270	443	570	11.27	3.292	-3.522	13 F	11	0	20	1
11	84	0.64	1.4	5.67	7.29	11.5	14.6	14	1.934	30	64	256	329	520	660	11.53	2.335	-2.999	15 M	14	1	26	0
12	69	1.09	1.98	5	5.62	8.38	10.1	9	2.109	50	90	226	254	378	455	11.15	1.919	4.608	11 M	9	0	26	0
13	73	1.09	2.13	6.78	8.38	12.4	17.1	16	3.691	50	97	306	378	558	770	11.46	2.264	-3.333	16 F	16	1	14	1
14	81	0.64	1.87	9.24	11.2	19	22.6	22	1.934	30	85	417	507	857	1020	11.58	2.511	-2.157	27 M	22	1	24	0
15	80	0.76	1.71	3.98	5	7.58	9.76	9	2.109	35	78	180	226	342	440	11.33	2.821	-3.595	10 M	9	0	26	0
16	88	0.98	2.13	6.31	7.44	11.5	14	13	1.934	45	97	285	336	518	630	11.38	2.498	-3.702	16 M	14	1	26	0
17	81	1.09	2.09	4.18	5.16	7.76	10.1	9	2.285	50	95	189	233	350	455	11.21	2.241	4.337	10 M	9	0	28	0
18	76	1.76	2.64	5.87	6.98	9.98	12.8	11	1.406	80	120	265	315	450	575	11.33	2.679	-3.736	10 M	11	0	26	0
19	69	0.36	3.76	13.3	16.7	24.2	29.4	29	3.691	17	170	598	753	1090	1322	11.31	1.361	4.171	28 F	29	1	10	1
20	75	1.98	2.93	5.98	7.91	12.2	15	13	1.934	90	133	270	357	551	675	11.5	2.202	-1.495	14 M	13	0	28	0
21	87	1.53	3.2	10.9	13.8	21.3	26.5	25	2.9	70	145	492	624	960	1195	11.6	2.199	-2.54	19 F	25	1	16	1
22	72	0.2	1.02	3.36	4.11	7.42	10.2	10	1.758	10	47	152	186	335	460	11.52	2.658	-2.081	9 M	10	0	28	0
23	109	0.64	1.93	5.04	5.71	9.13	10.6	10	2.285	30	88	228	258	412	480	11.51	2.056	-3.158	15 F	10	0	28	0 15

 $x^n$ 

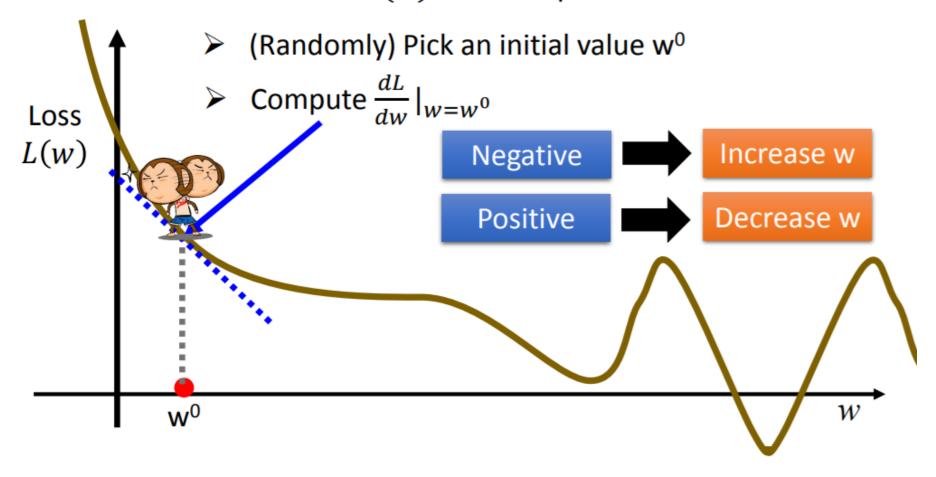
#### ML model (1) – Linear regression

- Linear model:  $y^n = \sum_i (w_i x_i^n) + b$
- Loss function:  $L(w \cdot b) = \sum_{n=1}^{N} (\hat{y}^n y^n)^2 = \sum_{n=1}^{N} (\hat{y}^n (\sum_i (w_i x_i^n) + b))^2$
- Find the optimal parameters that minimize loss: arg min  $L(w \cdot b)$

#### Use gradient decent to find optimal parameters

$$w^* = arg \min_{w} L(w)$$

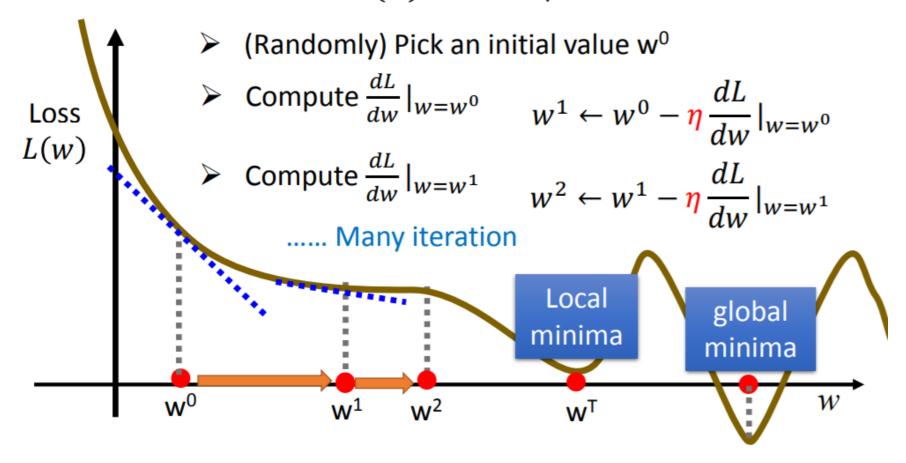
• Consider loss function L(w) with one parameter w:



#### Gradient decent

$$w^* = arg \min_{w} L(w)$$

• Consider loss function L(w) with one parameter w:



# Gradient decent to find two parameters $w^*$ and $b^*$

- How about two parameters?  $w^*, b^* = arg \min_{w,b} L(w,b)$ 
  - > (Randomly) Pick an initial value w<sup>0</sup>, b<sup>0</sup>
  - ightharpoonup Compute  $\frac{\partial L}{\partial w}|_{w=w^0,b=b^0}$ ,  $\frac{\partial L}{\partial b}|_{w=w^0,b=b^0}$

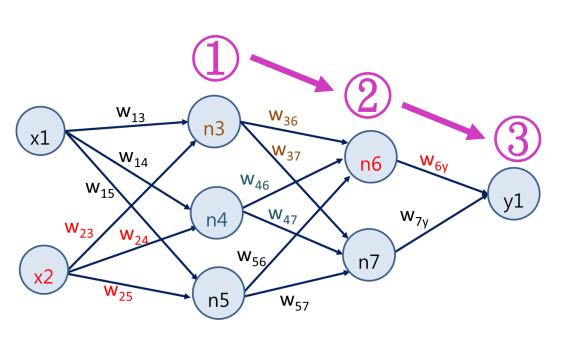
$$w^1 \leftarrow w^0 - \frac{\partial L}{\partial w}|_{w=w^0,b=b^0}$$
  $b^1 \leftarrow b^0 - \frac{\partial L}{\partial b}|_{w=w^0,b=b^0}$ 

$$ightharpoonup$$
 Compute  $\frac{\partial L}{\partial w}|_{w=w^1,b=b^1}$ ,  $\frac{\partial L}{\partial b}|_{w=w^1,b=b^1}$ 

$$w^2 \leftarrow w^1 - \eta \frac{\partial L}{\partial w}|_{w=w^1,b=b^1} \qquad b^2 \leftarrow b^1 - \eta \frac{\partial L}{\partial b}|_{w=w^1,b=b^1}$$

#### Machine learning model (2) – Deep learning

Define a function to be learned:  $y^n = f(x^n)$ 



$$n_3 = \sigma(x_1 * w_{13} + x_2 * w_{23} + b_3)$$

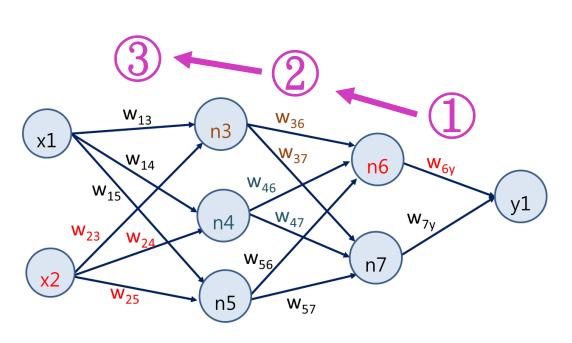
$$1 n_4 = \sigma(x_1 * w_{14} + x_2 * w_{24} + b_4)$$

$$n_5 = \sigma(x_1 * w_{15} + x_2 * w_{25} + b_5)$$

3 
$$y_1 = \sigma (n_6 * w_{6y} + n_7 * w_{7y} + b_y)$$

#### Machine learning model (2) – Deep learning

Use gradient decent to find optimal parameters



$$L = g(y - \hat{y})$$
  $y = \sigma(n_6 * w_{6y} + n_7 * w_{7y} + b_y)$ 

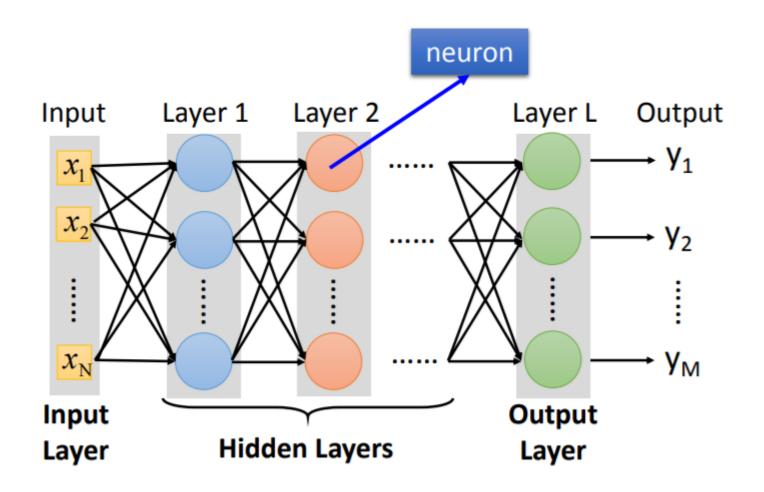
$$\mathbf{w}_{6y} \leftarrow \mathbf{w}_{6y} - \eta \frac{\partial L}{\partial \mathbf{w}_{6y}} \qquad \frac{\partial L}{\partial \mathbf{w}_{6y}} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial \mathbf{w}_{6y}}$$

$$w_{7y} \leftarrow w_{7y} - \eta \frac{\partial L}{\partial w_{7y}} \frac{\partial L}{\partial w_{7y}} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial w_{7y}}$$

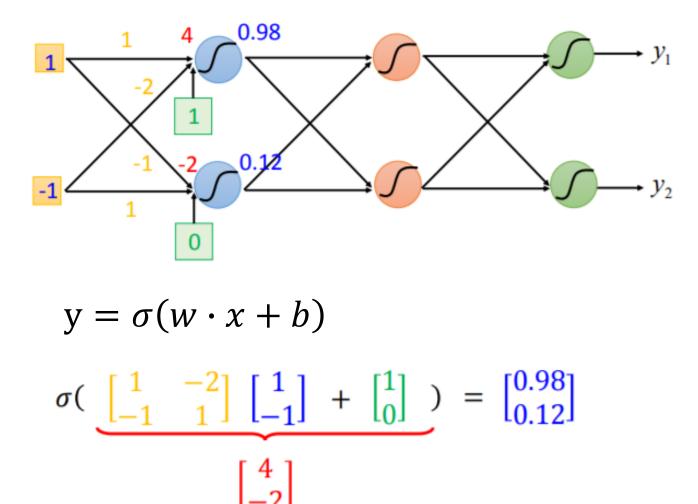
$$\mathbf{w}_{i} \leftarrow \mathbf{w}_{i} - \eta \frac{\partial e}{\partial \mathbf{w}_{i}}$$

2 
$$w_{57} \leftarrow w_{57} - \eta \frac{\partial L}{\partial w_{57}} \frac{\partial L}{\partial w_{57}} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial n_7} \frac{\partial n_7}{\partial w_{57}}$$
  
 $n_7 = f(n_3 * w_{37} + n_4 * w_{47} + n_5 * w_{57} + b_7)$ 

#### MLP is a fully connected feedforward network



# Fully connected feed forward network is implemented as matrix operation



Reference: 李弘毅 ML Lecture 6 <a href="https://youtu.be/Dr-WRIEFefw">https://youtu.be/Dr-WRIEFefw</a>

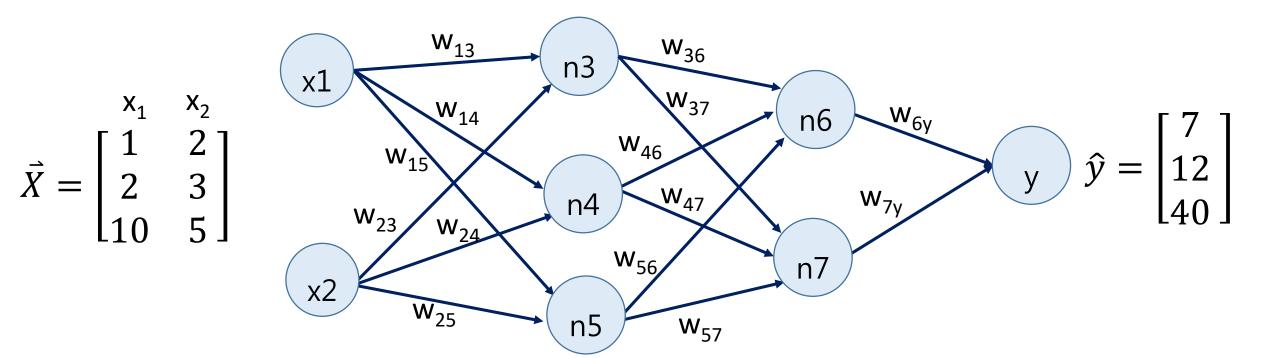
#### Practice

Run "1.1 Matrix operation.ipynb"



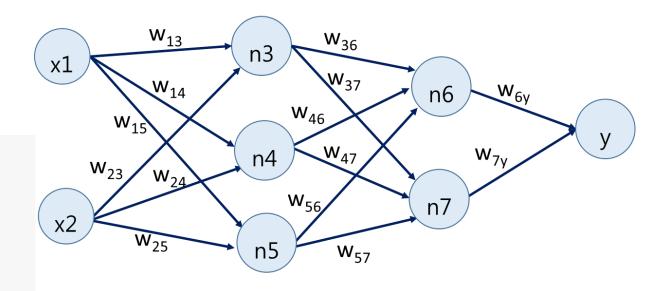
#### Matrix operation

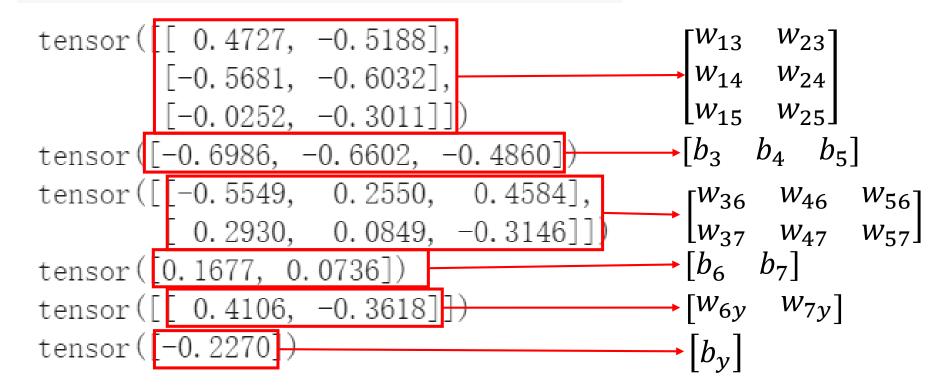
```
MyNet = nn. Sequential(
    nn. Linear(2, 3),
    nn. Linear(3, 2),
    nn. Linear(2, 1)
)
```



#### Matrix operation

```
for param in MyNet.parameters():
    if param.requires_grad:
        print(param.data)
```





$$\vec{X} = \begin{bmatrix} x_1 & x_2 \\ 1 & 2 \\ 2 & 3 \\ 10 & 5 \end{bmatrix} \qquad \begin{array}{c} w_{13} \\ w_{14} \\ w_{23} \\ w_{24} \end{array}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \\ 10 & 5 \end{bmatrix} \begin{bmatrix} w_{13} & w_{14} & w_{15} \\ w_{23} & w_{24} & w_{25} \end{bmatrix} + [b_3 \quad b_4 \quad b_5]$$

$$\begin{bmatrix} k_3^1 & k_4^1 & k_5^1 \\ k_3^2 & k_4^2 & k_5^2 \\ k_3^3 & k_4^3 & k_5^3 \end{bmatrix} + \begin{bmatrix} b_3 & b_4 & b_5 \\ b_3 & b_4 & b_5 \\ b_3 & b_4 & b_5 \end{bmatrix}$$

$$\begin{bmatrix} n_3^1 & n_4^1 & n_5^1 \\ n_3^2 & n_4^2 & n_5^2 \\ n_3^3 & n_4^3 & n_5^3 \end{bmatrix}$$

Use Excel to verify

n3

n4

n5

```
#Calculate n3, n4, n5
HiddenLayer1 = MyNet[0](tensorX)
print(HiddenLayer1)
```

```
tensor([[-1.2635, -2.4348, -1.1135], [-1.3097, -3.6061, -1.4398], [ 1.4340, -9.3577, -2.2441]],
```

```
#Calculate n3, n4, n5 using Pytorch matrix operation

HiddenLayer1 = tensorX.mm(torch.transpose(W1, 1, 0)) + b1

print(HiddenLayer1)
```

```
tensor ([[-1.2635, -2.4348, -1.1135],

[-1.3097, -3.6061, -1.4398],

[ 1.4340, -9.3577, -2.2441]], grad_fn=<AddBackward0>)
```

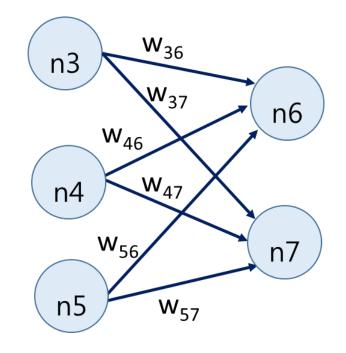
```
#Calculate n6, n7 using PyTorch matrix operation
W2 = MyNet[1].weight
b2 = MyNet[1].bias
HiddenLayer2 = HiddenLayer1. mm(torch. transpose(W2, 1, 0)) +b2
print(HiddenLayer2)
```

$$\begin{bmatrix} n_3^1 & n_4^1 & n_5^1 \\ n_3^2 & n_4^2 & n_5^2 \\ n_3^3 & n_4^3 & n_5^3 \end{bmatrix}$$

[-4.0429, 0.4054]], grad\_fn=<AddBackward0>)

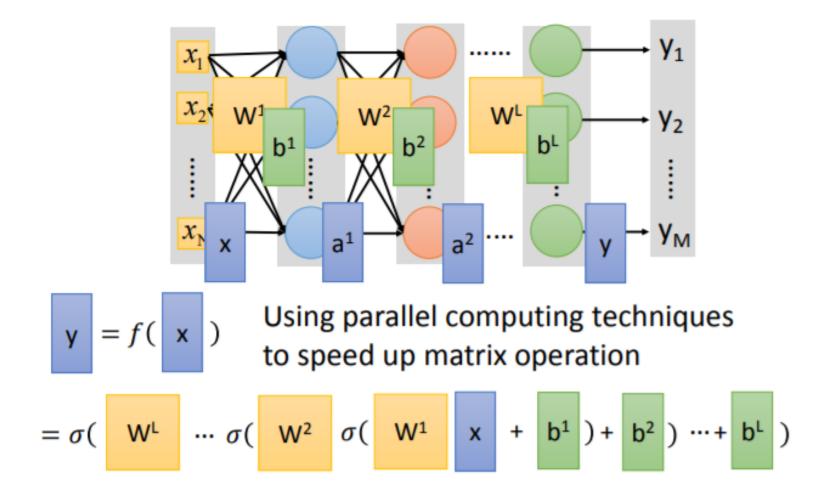
$$\begin{bmatrix} -1.2635 & -2.4348 & -1.1135 \\ -1.3097 & -3.6061 & -1.4398 \\ 1.4340 & -9.3577 & -2.2441 \end{bmatrix} \begin{bmatrix} w_{36} & w_{37} \\ w_{46} & w_{47} \\ w_{56} & w_{57} \end{bmatrix} + \begin{bmatrix} b_6 & b_7 \end{bmatrix}$$

$$egin{bmatrix} k_6^1 & k_7^1 \ k_6^2 & k_7^2 \ k_6^3 & k_7^3 \end{bmatrix} & + egin{bmatrix} b_6 & b_7 \ b_6 & b_7 \ b_6 & b_7 \end{bmatrix}$$



$$\begin{bmatrix} n_6^1 & n_7^1 \\ n_6^2 & n_7^2 \\ n_6^3 & n_7^3 \end{bmatrix} \quad \begin{array}{c} \text{Use Excel to} \\ \text{verify} \end{array}$$

# Use parallel computing to speed up matrix operation



# Use parallel computing to speed up matrix operation

```
In [2]: if(torch.cuda.is_available()):
    device = torch.device("cuda")
    print(device, torch.cuda.get_device_name(0))
else:
    device= torch.device("cpu")
    print(device)
```

```
tensorX = torch.FloatTensor(trainX).to(device)
tensorY_hat = torch.FloatTensor(trainY_hat).to(device)
print(tensorX.shape, tensorY_hat.shape)
```

```
torch.Size([128, 2]) torch.Size([128, 1])
```

```
conv1_out = conv1(imageTensor.to(device))
conv1_out.shape
#output image (feature map) has 64 channels
torch.Size([1, 64, 55, 55])
```